

Optimising Resonance Driving Terms Using MAD-NG Parametric Differential Maps.

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MAD-NG's Features



• Integrated platform designed for Methodical Accelerators Design (optics).

- Flexible language is fast, simple, and general purpose scripting language.
 - ▶ ~70% of the code is written in the Lua(JIT) scripting language, ~30% in C and C++.
- Flexible technologies self-contained, all-in-one and modular application.
 - Single "copy & run" application, no dependencies (requires Gnuplot installed for plotting).
- Efficient & Portable technologies in embeds a Tracing Just in Time compiler.
 - Same results everywhere (LNX, OSX, WIN), extensive unit tests (>8000) and examples.
 - Extremely simple and fast Foreign Function Interface to external libraries in C, C++, Fortran, etc...
- Easy to extend & support me embeds an online profiler and debugger.
 - Adding new elements with new physics takes a day (assuming known explicit exact equations).

• 5D and 6D physics using high-order differential algebra and symplectic integrators.

- Combined physics, combined elements, misalignments & errors, local & global frames, all elements fringe fields, forward, backward and reverse tracking.
- Physics & Maths in Lua and C/C++, performance is x10-x70 faster than MADX-PTC.
- Support and development for new physics extensions is extremely easy...

• Development open source.

- ➡ License GPL V3, Manual (~200p, covers <25%), Lua Manual (30p).</p>
- Sources <u>https://github.com/MethodicalAcceleratorDesign/MAD</u>
- Releases & Manual <u>https://cern.ch/mad/releases/madng/</u>
- Online Manual <u>https://cern.ch/mad/releases/madng/html/</u>
- Learn Lua in 15 min: <u>https://www.youtube.com/watch?v=REReUFgii5A</u>





Track a high-order differential algebra (DA) map on the closed orbit (optionally) equipped with parameters (knobs) to obtain the one-turn map m, then compute the closed nonlinear normal form $m = a \circ r \circ a^{-1}$ and track the normalising map a to extract the optical functions (α , β , μ , etc.) and the resonant driving terms (RDTs) along the lattice.





MAD-NG studies: RDTs for HL-LHC







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MAD-NG studies: Parametric RDTs for HL-LHC













MAD-NG studies: DA increase for LHC@injection



Dynamic Aperture Improvements

Dynamic aperture for beam 1 (top) and beam 2 (bottom) with old (left) and new (right) injection optics for LHC. Lowering the octupolar RDTs has significantly improved the dynamic aperture at injection.







- HB2023 papers
 - L. Deniau et al., "Optimising Resonance Driving Terms Using MAD-NG Parametric Differential Maps".
 - R. Tomás et al., "Optics for Landau Damping with Minimised Octupolar Resonances in the LHC".
 - ➡ K. Paraschou et al., "Emittance Growth from Electron Clouds Forming in the LHC Arc Quadrupoles".
- Papers and books on Differential Algebra, Nonlinear Normal Forms and RDTs.
 - E. Forest, M. Berz and J. Irwin, "Normal Form Methods for Complicated Periodic Systems using Differential Algebra and Lie Operators", Particle Accelerators, Vol. 24, pp. 91-107, 1989.
 - E. Forest, "From Tracking Code to Analysis, Generalised Courant-Snyder Theory for Any Accelerator Model", Springer, 2016.
 - A. Franchi, "Studies and Measurements of Linear Coupling and Nonlinearities in Hadron Circular Accelerators", PhD Thesis, 2006.
 - R. Bartolini and F. Schmidt, "Normal Form via Tracking or Beam Data", Particle Accelerators, Vol. 59, pp. 93-106, 1998.
 - T. Pugnat, R. Tomás, A. Franchi and B. Dalena, "Non-linear Variation of the Beta-beating Measured from Amplitude", 12th Int. Particle Acc. Conf., 2021.
 - L. Deniau and C.I. Tomoiaga, "Generalised Truncated Power Series Algebra for Fast Particle Accelerator Transport Maps", 6th Int. Particle Acc. Conf., 2015.





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Extra Slides



MAD-NG's Physics I



- 5D and 6D physics using differential algebra and symplectic integrators.
 - combined physics & elements, slicing & frames, easy to extend, etc...
 - **x10-30** faster than MADX-PTC for TPSA tracking (Multivariate Taylor Series).
- **Survey**: geometrical tracking (global frame, linear algebra)
 - Survey supports multi-turns, ranged and step-by-step forward, backward and reverse tracking. Return a Survey table and a Survey map flow (tracked context).
 - fully compatible with Track for superposition and observable points (e.g. table output, smooth plots, slicing, actions, sub-elements, **local in global frame**, etc...)
 - support exact misalignments, permanent misalignments, and patches.
- **Track**: dynamical tracking (*local mobile frame, differential algebra*)
 - Track supports multi-particles or multi-damaps, multi-turns, ranged and step-bystep forward, backward and reverse tracking of charged particles to arbitrary DA order with an arbitrary number of parameters (few hundreds). Return a Track table and a Track map flow (tracked context).
 - fully compatible with Survey for superposition and observable points.
 - support exact misalignments, permanent misalignments, multipoles & field errors for all elements. Can be combined freely with patches.
 - symplectic tracking with integrators up to 8th order on 5D (delta-p) and 6D (delta-rf) phase space (exact=true, time=true, totalpath e.g. for thick RF).
 - provides true thick lens and thin lens tracking model, radiation with photons tracking (disabled in twiss), fringe fields (hard edge for all elements, including quads, solenoid, RFs), mutable particles (multiple beams), exact patches (translations, rotations & time-energy), 4D weak-strong beam-beam (sixtracklib), apertures (all kinds).
 - can search for the closed orbit to support relative initial coordinates.





• Cofind: fix point search

- Newton-based optimiser running Track with 1st order DA map or 7 particles (F-Diff).
- extend Track with actions.

• Twiss: optics tracking

- runs Cofind (closed orbit) Track (one-turn map) Normal Track (optics, RDTs).
- extend Track with actions to compute on-the-fly optics and fill twiss table (extended track table).
- support strongly coupled optics, linear and non-linear dispersions, tunes, and chromaticities, RDTs, synchrotron integrals, compaction factor, phase slip factor, gamma transition, Montaigue functions, etc...

Match: highly configurable optimiser

- on the model of MAD-X use_macro approach, i.e. arbitrary user's setups & runs.
- provides all kinds of local & global, linear & non-linear, optimiser (~20 algorithms).
- very flexible, highly configurable with many physics-oriented setups (not just a penalty-function to minimise).

• Correct: orbit correction

 provides few algorithms (e.g. SVD, Micado) to correct orbit using BPMs and Kickers. Supports many options.

• Normal: parametric normal forms & analysis

 provides linear and non-linear parametric normal forms on DA map (used by twiss) to extract RDTs. Can also be applied at observable points in Track to track RDTs, either on-the-fly with actions or through post processing of DA maps saved in Track table.



MAD-NG's Ecosystem

Legend

202x?



Objects Commands Geo/LinAlg Dyn/DiffAlg A exposes B A uses B A is-a B Done Dev Todo \rightarrow B A \longrightarrow B A \longrightarrow B Algorithms MAD-NG Solvers, Eigen, **Unit Tests** Core FFT, Optimisers (LuaJIT+FFI) Plot Table Linear ToolBox Match Real & Complex Vector & Matrix Survey **MADX Env** Object Model Correct Commands Geometric **Elements 3D Maps** Beam CoFind Symplectic Sequence Integrators **DA** Toolbox Twiss Real & Complex Track Dynamic 6D Maps **GTPSA** Radiation Parametric DA Map Aperture Spin Normal forms

Optical Funs



GTPSA in a nutshell

- Generalised Truncated Power Series Algebra [IPAC 2015 \bigcirc
 - → Multivariate Taylor polynomials of order n in $\mathbb{R} \& \mathbb{C}$. 2017-2018
 - Powerful tool for solving differential equations (e.g. motion equations).
 - **TPSA coefficients** 1 variable x at order n in the *neighbourhood* of the point a in the domain of the function f:

Beams

Github MAD

Department

$$T_f^n(x;a) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots + \frac{f^{(n)}(a)}{n!}(x-a)^n = \sum_{k=0}^n \frac{f^{(k)}_a}{k!}(x-a)^k$$

convergence of the remainder (i.e. truncation error):

$$\lim_{n \to \infty} R_f^n(x; a) = \lim_{n \to \infty} f(x) - T_f^n(x; a) = 0$$

$$f(x) \text{ is an analytic function, } T_f^n(x; a) \text{ is a polynomial approximation nearby } a \text{ with radius of convergence } h: \min_{h > 0} \lim_{n \to \infty} R_f^n(a \pm h; a) \neq 0.$$
2 variables (x,y) at order 2 nearby (a,b) :
$$T_f^2(x, y; a, b) = f(a, b) + \left(\frac{\partial f}{\partial x}\left((x - a) + \frac{\partial f}{\partial y}\right)(y - b) + \dots\right) + \frac{\partial f}{(a,b)}(x - a, y - b)$$

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$$T_f^2(x, y; a, b) = f(a, b) + \left(\frac{\partial f}{\partial x}\left((x - a) + \frac{\partial f}{\partial y}\right)(y - b) + \dots\right) + \frac{\partial f}{\partial x}\left((x - a)(y - b) + \frac{\partial^2 f}{\partial y^2}\right)(y - b)^2\right)$$

$$v \text{ variables } X \text{ at order } n \text{ nearby } A:$$

$$T_f^n(X; A) = \sum_{k=0}^n \frac{f_A^{(k)}}{k!}(X; A)^k = \sum_{k=0}^n \frac{1}{k!} \sum_{|\overline{m}|=k} \left(\frac{k}{m}\right) \frac{\partial^k f}{\partial x^{\overline{m}}}_A(X; A)^{\overline{m}} \text{ with } \left(\frac{k}{m}\right) = \frac{k!}{c_1! c_2! \dots c_v!}$$

$$monomials of order k$$





- GTPSA are **exact** to machine precision, **no** approximation for orders 0...n
 - derivatives are computed using automatic differentiation (AD).

from Wikipedia

AD exploits the fact that every computer program, no matter how complicated, executes a sequence of elementary arithmetic operations (addition, subtraction, multiplication, division, etc.) and elementary functions (exp, log, sin, cos, etc.). By applying the chain rule repeatedly to these operations, **derivatives of arbitrary order can be computed automatically, accurately to working precision**, and using at most a small constant factor more arithmetic operations than the original program.

Symbolic differentiation can lead to inefficient code and faces the d program into a single expression, while numerical differentiation can i discretization process and cancellation. Both classical methods have problems with calculating higher derivatives, where complexity and errors increase.

- MAD-NG includes a complete toolbox (i.e. module) to handle DA using AD...
 - users have full access to GTPSA and DAmaps from the scripting language.
 - users can manipulate DAmaps stored in the MTable or the MFlow returned by Track.
- So when DAmap/TPSA introduce errors? (Something that we never do...)
 - ➡ If they are used as *functions* (e.g. evaluated), instead of DA (e.g. track, twiss).
 - High orders of $T_f^n(x; a)$ are used to interpolate at the new position by substitution, e.g. MADX.

$$T_{f}^{n}(x;a+h) = \sum_{k=0}^{n} \frac{f_{a+h}^{(k)}}{k!} (x-a-h)^{k}; \quad f(a+h) \approx \sum_{k=0}^{n} \frac{f_{a}^{(k)}}{k!} h^{k}; \quad f_{a+h}^{(k)} \approx \frac{\mathsf{d}^{k} T_{f}^{n}(x;a)}{\mathsf{d} x^{k}} (a+h) \frac{\mathsf{d} x^{k}}{\mathsf{d} x^{k}} (a+h) \frac{\mathsf{d} x^{k$$