# $\mathbb{C}$ irfu

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Model-assisted measurement of dE/dx in T2K's near detector High-Angle TPCs

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Context
 Modelization
 Results with data

## The T2K experiment





#### Goals

- Study v<sub>e</sub> appearance in v<sub>µ</sub> beam => need e/µ separation
- Measurement of  $\Delta m_{23}^2$ ,  $\theta_{23}$  &  $\delta_{CP}$  from PMNS matrix

#### How?

- Far detector:
  - Cherenkov effect
  - 50 ktons of water
- Near detectors:
  - characterize beam
  - constrain systematics
- Upgrade ND280:
  - more active target (Super FGD)
  - 2 High-Angle TPCs (HATPCs)



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### Encapsulated Resistive Anode bulk Micromegas (ERAM)



- Spatial constraints to avoid sparks
- Precision ~ pad size
- Implemented in vertical TPCs in ND280



- Prevents sparks & protects the electronics
- Charge spreading gives more precise information about the charge position
- Sub-pad precision tracking

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#### Converting an electronic response to a real charge





Signal in a pad:

$$S(t) = Q_{
m pad}(t) \otimes rac{{
m d}}{{
m d}t}\,f_{
m electronics}(t)$$

- If the charge escapes the pad during the integration, it is not fully reconstructed by the recorded signal
- But we want the charge to escape, to have a better precision on the position!
- How to meet these contradictory conditions?
  - Integrate over a larger surface

#### Converting an electronic response to a real charge







- 3 pads => good
- 5 pads => excellent

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# dE/dx by summing waveforms: $WF_{sum}$ method





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# dE/dx by summing waveforms: $WF_{sum}$ method

Diagonal

cluster





30

25

20

15

10

- Charge Q spreads as a wavefront  $\perp$  to the track
- Regroup pads into diagonal clusters

10

5

15

20

25

Poor Q reconstruction because of improper clustering



n



# Problem:

 Clustering is not trustworthy for inclined tracks (relies on too many approximations)

# Solution:

- Modelize the detector's response
- Rely on this modelization to reconstruct the
  - deposited charge <u>without clusters</u>



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A modelization of the charge spreading allows to:

- Simulate every track configuration
- Retrieve the deposited charge in a pad just with its waveform & the track fit
- Overlook neighbour pads (i.e. not crossed by the track)

- dE/dx can be obtained without clusters
- > Only needs  $A_{max}$ ,  $T_{max}$  & track information

#### What was known:

Linear charge spread for horizontal track: 1.

modelization: the mathematics

$$Q_{pad}(t) = rac{\lambda}{2} [x_{ ext{right}} - x_{ ext{left}}] \Bigg[ ext{erf} \Bigg( rac{y_{ ext{high}} - y_c}{\sqrt{2} \sigma(t)} \Bigg) - ext{erf} \Bigg( rac{y_{ ext{low}} - y_c}{\sqrt{2} \sigma(t)} \Bigg) \Bigg]$$

2. Pad signal depending on Q(t) and the electronics:

$$S(t) = Q_{
m pad}(t) \otimes rac{{
m d}}{{
m d} t} \, f_{
m electronics}(t) \, .$$



What is new: Linear charge spread for inclined tracks

$$Q_{pad}(t) = \frac{\lambda\sqrt{1+m^{2}}}{2m} \left( \sqrt{\frac{2(1+m^{2})}{\pi}} \sigma \left( -e^{-\frac{(-c+am+q)^{2}}{2(1+m^{2})\sigma^{2}}} + e^{-\frac{(-d+am+q)^{2}}{2(1+m^{2})\sigma^{2}}} - e^{-\frac{(-d+bm+q)^{2}}{2(1+m^{2})\sigma^{2}}} \right) + (c-am-q) \operatorname{Erf}\left[\frac{-c+am+q}{\sqrt{2(1+m^{2})\sigma^{2}}}\right] - (d-am-q) \operatorname{Erf}\left[\frac{-d+am+q}{\sqrt{2(1+m^{2})\sigma}}\right] + (c-am+q) \operatorname{Erf}\left[\frac{-c+bm+q}{\sqrt{2(1+m^{2})\sigma}}\right] + (d-bm-q) \operatorname{Erf}\left[\frac{-d+bm+q}{\sqrt{2(1+m^{2})\sigma}}\right] \right)$$

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#### modelization: the simulation

modelization depends on:

- $\blacksquare$  Track angle  $\phi$
- Impact parameter d
- Drift distance Z<sub>drift</sub>
- Diffusion coefficient of the pad 1/RC

#### For a given configuration, a pad has:

- a real charge deposited Q<sub>anode</sub>
- which corresponds to a waveform with a maximum amplitude A<sub>max</sub>



 Store in Look-Up Tables (LUT) a scaling factor for all track configurations to retrieve Q<sub>anode</sub>

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#### modelization: the Crossed Pads (XP) method





## modelization: the Crossed Pads (XP) method





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#### Drift distance scan (test beam e<sup>-</sup> 4 GeV @ DESY)



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## Angle scan (test beam e<sup>-</sup> 4 GeV @ DESY)



#### Separation power with 1 detector (1.5 GeV @ CERN)



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#### Separation power with 4 detectors (1.5 GeV @ CERN)



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#### dE/dx & Bethe-Bloch curve with 4 detectors (@ CERN)

Mean vs energy with XP method Bethe-Bloch for different particles nean (keV/cm) nean (keV/cm)  $\circ \pi^+$ Fitting range фр 1.5 0.5 0.8 1.2 0.6 1.4 10 Energy (GeV) Energy (GeV)  $\left\langle -rac{dE}{dx} 
ight
angle = rac{\mathrm{P1}}{eta^{\mathrm{P4}}} \Big[ \mathrm{P2} \ - \ eta^{\mathrm{P4}} - \ln\left(\mathrm{P3} + \left[eta\gamma
ight]^{\mathrm{P5}}
ight) \Big] \quad rac{\mathrm{https://doi.org/10.1007}}{/978-3-540-76684-1}$ 

- Particles datasets are coherent with each other
- Values (keV/cm) & fit extrapolation match expectations





# CONCLUSIONS

- A new dE/dx method to overcome clustering issues in presence of charge sharing has been developed
  - Based on a modelization of the ERAM response
  - Demonstrates our complete understanding of the detector
- dE/dx:
  - Resolution as good as the previous method
  - More consistent values for inclined tracks
- XP will now be implemented in the ND280 reconstruction software

## Current dE/dx method: sum of waveforms in a cluster WF<sub>sum</sub>



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# WF<sub>sum</sub> ad hoc mean correction



cea-

#### modelization: complete mathematics



1) 1D linear charge function in a pad for a linear track, parametrized with an angle  $\phi$  & an impact parameter d:

2) Electronics function depending on two parameters Q & w<sub>s</sub>:

$$ADC_{\text{Dirac}}\left(t\right) = \frac{4096}{120fC} \frac{F(t)}{F^{Max}} \text{ with } F(t) = e^{-w_s t} + e^{-\frac{w_s t}{2Q}} \left(\sqrt{\frac{2Q-1}{2Q+1}} \sin\left(\frac{w_s t}{2}\sqrt{4-\frac{1}{Q^2}}\right) - \cos\left(\frac{w_s t}{2}\sqrt{4-\frac{1}{Q^2}}\right)\right)$$

3) Finally, do the **convolution** of the derivative of the charge & the electronics:

$$ADC(t) = rac{dQ}{dt} \otimes ADC_{ ext{Dirac}}$$

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### modelization: filling the LUTs



- Physical characteristics: RC, transverse diffusion, charge sharing

#### **Goal:** Resolution < 10% & stable mean

- Angle **φ**: 200 steps [0°, 90°]
- Impact parameter: 200 steps [-7.3, +7.3] mm
- Drift distance: 21 steps [0, 1] m
- RC: 21 steps [50, 150] ns/mm<sup>2</sup>

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## Row scan (test beam e<sup>-</sup> 4 GeV @ DESY)







## Theta angle (test beam e<sup>-</sup> 4 GeV @ DESY)



- Tracks inclined towards the ERAMs
- Resolution σ/μ ~ 8%
- Similar results with XP or WF<sub>sum</sub>



- WF<sub>sum</sub> has no procedure to handle such tracks
- XP does not directly include theta dependency either
- Can do a reasonable approximation for XP with a "staircase" description

#### CERN22: Mockup gain maps





- Truncation across 4 ERAMs requires gain equalisation.
  - Especially because of ERAM23.
- Equalisation done by getting the average gain value across the 4 ERAMs and use it as a scaling factor.

#### Energy scan with 4 detectors (CERN22)



#### XP systematics - drift distance scan - resolution



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#### XP systematics - $\phi$ scan - resolution



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#### XP systematics - drift distance scan - mean plots





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#### XP systematics - $\phi$ scan - mean plots



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## Error propagation for impact parameter



 Parabola parameters are correlated

 Can express the error on d with respect to a, b & c

Local straight approximation

$$egin{aligned} d&=rac{mx_c-y_c+q}{\sqrt{m^2+1}} & y_{curve}\ &=\ a+bx+cx^2\ &=rac{(b+c(x_{out}+x_{in}))x_c-y_c+a-cx_{out}x_{in}}{\sqrt{(b+c(x_{out}+x_{in}))^2+1}} & y_{line}\ &=\ mx+q \ \end{aligned}$$

$$(x_{c}, y_{c}) \stackrel{(x_{c}, y_{c})}{\longrightarrow} \stackrel{(x_{out}, y_{out})}{\bigwedge} \partial_{a}d = \frac{1}{\sqrt{(c(x_{out} - x_{in}) + b)^{2} + 1}} \\ \partial_{b}d \quad \frac{x_{c}}{\sqrt{(b + c(x_{out} + x_{in}))^{2} + 1}} - \frac{(b + c(x_{out} + x_{in}))(x_{c}b - y_{c} + c(x_{c}(x_{out} + x_{in}) - x_{in}x_{out}) + a)}{((b + c(x_{out} + x_{in}))^{2} + 1)^{3/2}} \\ \partial_{c}d = \frac{x_{c}(x_{out} + x_{in}) - x_{in}x_{out}}{\sqrt{((x_{out} + x_{in}) - x_{in}x_{out})}} - \frac{(x_{out} + x_{in})((x_{out} + x_{in}) - x_{in}x_{out}) + a)}{(((x_{out} + x_{in})c + b)((x_{c}(x_{out} + x_{in}) - x_{in}x_{out})c - y_{c} + bx_{c} + a)} \\ ((x_{out} + x_{in})c + b)^{2} + 1)^{3/2}$$

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