

Developing an automatic differentiation and parameter optimisation pipeline for the particle shower model

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Stochastic program $f: \mathcal{X} \times \Omega \times \Theta \rightarrow \mathcal{Y}$

\mathcal{X} is the input and \mathcal{Y} is the program's output space

$\Omega \ni \omega$ is a random element drawn from a distribution $P(\cdot; \theta)$

samples of uniform (pseudo) random numbers in $[0, 1]$ + inversion of CDF (in practice)

Θ is the set of parameters on which f depends either explicitly
or implicitly via the probability distribution on Ω

Basic examples

```
function f_0( $\theta$ )  
    return rand(Bernoulli( $\theta$ ))  
end
```

```
function f_1( $\theta$ )  
    p =  $\theta^2 / (1 + \theta^2)$   
    return rand(Bernoulli(p))  
end
```

```
function f_2(x,  $\theta$ )  
    a =  $\theta^2$   
    m = x * 3 + 11  
    return rand(Normal(m, a))  
end
```

```
function f_3(x,  $\theta$ )  
    a =  $\theta^2$   
    b = rand(Binomial(10,  $\theta$ ))  
    c = 2 * b + 3 * rand(Bernoulli( $\theta$ ))  
    return x * a * c * rand(Normal(b, a))  
end
```

What unbiased estimate to put inside the expectation?

$$\frac{\partial}{\partial \theta} \mathbb{E}_{\theta} [f(x, \theta)] = \mathbb{E} [?]$$

everything depends on smoothness (differentiability properties)

of $f(x, \theta)$ and $P(\cdot; \theta)$ with respect to θ

Gradient Estimation Using Stochastic Computation Graphs

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- Finally θ might appear both in the probability distribution and inside the expectation, e.g., in $\frac{\partial}{\partial \theta} \mathbb{E}_{z \sim p(\cdot; \theta)} [f(x(z, \theta))]$. Then the gradient estimator has two terms:

$$\frac{\partial}{\partial \theta} \mathbb{E}_{z \sim p(\cdot; \theta)} [f(x(z, \theta))] = \mathbb{E}_{z \sim p(\cdot; \theta)} \left[\frac{\partial}{\partial \theta} f(x(z, \theta)) + \left(\frac{\partial}{\partial \theta} \log p(z; \theta) \right) f(x(z, \theta)) \right]. \quad (4)$$

When $f(x, \theta)$ and $P(\cdot; \theta)$ are both smooth with respect to θ

Condition 1 (Differentiability Requirements). *Given input node $\theta \in \Theta$, for all edges (v, w) which satisfy $\theta \prec^D v$ and $\theta \prec^D w$, then the following condition holds: if w is deterministic, Jacobian $\frac{\partial w}{\partial v}$ exists, and if w is stochastic, then the derivative of the probability mass function $\frac{\partial}{\partial v} p(w \mid \text{PARENTS}_w)$ exists.*

Theorem 1. *Suppose that $\theta \in \Theta$ satisfies 1. Then the following two equivalent equations hold:*

$$\frac{\partial}{\partial \theta} \mathbb{E} \left[\sum_{c \in \mathcal{C}} c \right] = \mathbb{E} \left[\sum_{\substack{w \in \mathcal{S}, \\ \theta \prec^D w}} \left(\frac{\partial}{\partial \theta} \log p(w \mid \text{DEPS}_w) \right) \hat{Q}_w + \sum_{\substack{c \in \mathcal{C} \\ \theta \prec^D c}} \frac{\partial}{\partial \theta} c(\text{DEPS}_c) \right] \quad (5)$$

$$= \mathbb{E} \left[\sum_{c \in \mathcal{C}} \hat{c} \sum_{\substack{w \prec c, \\ \theta \prec^D w}} \frac{\partial}{\partial \theta} \log p(w \mid \text{DEPS}_w) + \sum_{\substack{c \in \mathcal{C}, \\ \theta \prec^D c}} \frac{\partial}{\partial \theta} c(\text{DEPS}_c) \right]. \quad (6)$$

Corollary 1. *Let $L(\Theta, \mathcal{S}) := \sum_w \log p(w \mid \text{DEPS}_w) \hat{Q}_w + \sum_{c \in \mathcal{C}} c(\text{DEPS}_c)$. Then differentiation of L gives us an unbiased gradient estimate: $\frac{\partial}{\partial \theta} \mathbb{E} [\sum_{c \in \mathcal{C}} c] = \mathbb{E} [\frac{\partial}{\partial \theta} L(\Theta, \mathcal{S})]$.*

One practical consequence of this result is that we can apply a standard automatic differentiation procedure to L to obtain an unbiased gradient estimator. In other words, we convert the stochastic computation graph into a deterministic computation graph, to which we can apply the backpropagation algorithm.

And what if the differentiability requirements are not satisfied?

What if the differentiability requirements are not satisfied?

```
function f_0(θ)
    return rand(Bernoulli(θ))
end
```

```
function f_1(θ)
    p = θ2 / (1 + θ2)
    return rand(Bernoulli(p))
end
```

```
function f_2(x, θ)
    a = θ2
    m = x * 3 + 11
    return rand(Normal(m, a))
end
```

```
function f_3(x, θ)
    a = θ2
    b = rand(Binomial(10, θ))
    c = 2 * b + 3 * rand(Bernoulli(θ))
    return x * a * c * rand(Normal(b, a))
end
```


More advanced examples

```
function p_interact_material(x, y, θ)
    par_radial = 10
    par_azimutal = 10
    r = sqrt(x^2 + y^2)

    alpha = atan2(x, y)

    sampling1 = 1 / (1 + exp(10*sin(par_radial*(alpha + 2*r))))
    sampling2 = 1 / (1 + exp(10*sin(par_azimutal*(r-2))))

    start = 1 / (1 + exp(-10*(r - θ)))
    tail = 1 / (1 + exp(10*(r - (θ + 10))))

    return 0.5 * start * sampling1 * sampling2 * tail
end
```

```
function simulate(T, θ)
    T_new = propagate(T)

    dointeract = rand(Binomial(p_interact_material(x, y, θ)))

    if dointeract
        push!(hits, (x, y))

        dosplit = rand(Binomial(p_split(T)))

        if dointeract
            T_1, T_2 = split(T_new)

            simulate(T_1, θ)
            simulate(T_2, θ)

        else
            simulate(T_new, θ)
        end
    end
end
```

It is still possible to obtain meaningful estimates

```
samples = [derivative_estimate(f_0, 0.6) for i in 1:1000]
println("d/dθ of E[f_0(θ)]: $(mean(samples)) ± $(std(samples) / sqrt(1000))")

samples = [derivative_estimate(f_1, 0.6) for i in 1:1000]
println("d/dθ of E[f_1(θ)]: $(mean(samples)) ± $(std(samples) / sqrt(1000))")

samples = [derivative_estimate(θ -> f_2(5, θ), -20) for i in 1:1000]
println("d/dθ of E[f_2(θ)]: $(mean(samples)) ± $(std(samples) / sqrt(1000))")

samples = [derivative_estimate(θ -> f_3(1, θ), 0.6) for i in 1:1000]
println("d/dθ of E[f_3(θ)]: $(mean(samples)) ± $(std(samples) / sqrt(1000))")
```

```
d/dθ of E[f_0(θ)]: 1.0025 ± 0.038765274363745904
d/dθ of E[f_1(θ)]: 0.6529411764705884 ± 0.012245094114506663
d/dθ of E[f_2(θ)]: 2.476388047193479 ± 1.2892228953295273
d/dθ of E[f_3(θ)]: 202.98243353789118 ± 1.2607083445925458
```

How?

$$\frac{d\mathbb{E}[X(p)]}{dp} = \mathbb{E}[\delta + w(Y - X(p))].$$

Automatic Differentiation of Programs with Discrete Randomness

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Definition 2.2 (Stochastic derivative). Suppose $X(p) \in E$ is a stochastic program with index set I a closed real interval. We say that the triple of random variables (δ, w, Y) , with $w \in \mathbb{R}$ and $Y \in E$, is a right (left) *stochastic derivative* of X at the input $p \in I$ if $dX(\varepsilon)/\varepsilon \rightarrow \delta$ almost surely as $\varepsilon \rightarrow 0$, and there is an integrable (i.e. of bounded expectation) random variable $B > |\delta|$ such that for all bounded functions $f: E \rightarrow \mathbb{R}$ with bounded derivative it holds almost surely that

$$\mathbb{E}[w(f(Y) - f(X(p))) \mid X(p)] = \lim_{\varepsilon \rightarrow 0^{+/-}} \mathbb{E} \left[\frac{f(X(p + \varepsilon)) - f(X(p))}{\varepsilon} \mathbf{1}_{A_B(\varepsilon)} \mid X(p) \right], \quad (2.4)$$

with limit taken from above (below), where $\mathbb{P}(A_B(\varepsilon) \mid X(p)) / \varepsilon$ is dominated by an integrable random variable for all $\varepsilon > 0$ ($\varepsilon < 0$).

```

1 struct StochasticTriple
2     value # primal evaluation
3     δ # "infinitesimal" component
4     Δs # component of discrete change
5         # with "infinitesimal"
6         # probability
7 end

```

```

1 using Distributions
2 function X(p) p = 0.6 + ε
3     a = p^2 0.36 + 1.2ε
4     b = rand(Binomial(10, p))
5     6 + (1 with probability 10.0ε)
6     c = 2 * b + 3 * rand(Bernoulli(p))
7     12 + (3 with probability 12.5ε)
8     return a * c * rand(Normal(b, a))
9 end

```

Thanks for attention!