



Wire-Cell: A High Quality Automated LArTPC Reconstruction for Neutrino Experiments

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ACAT24

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2024-03-11

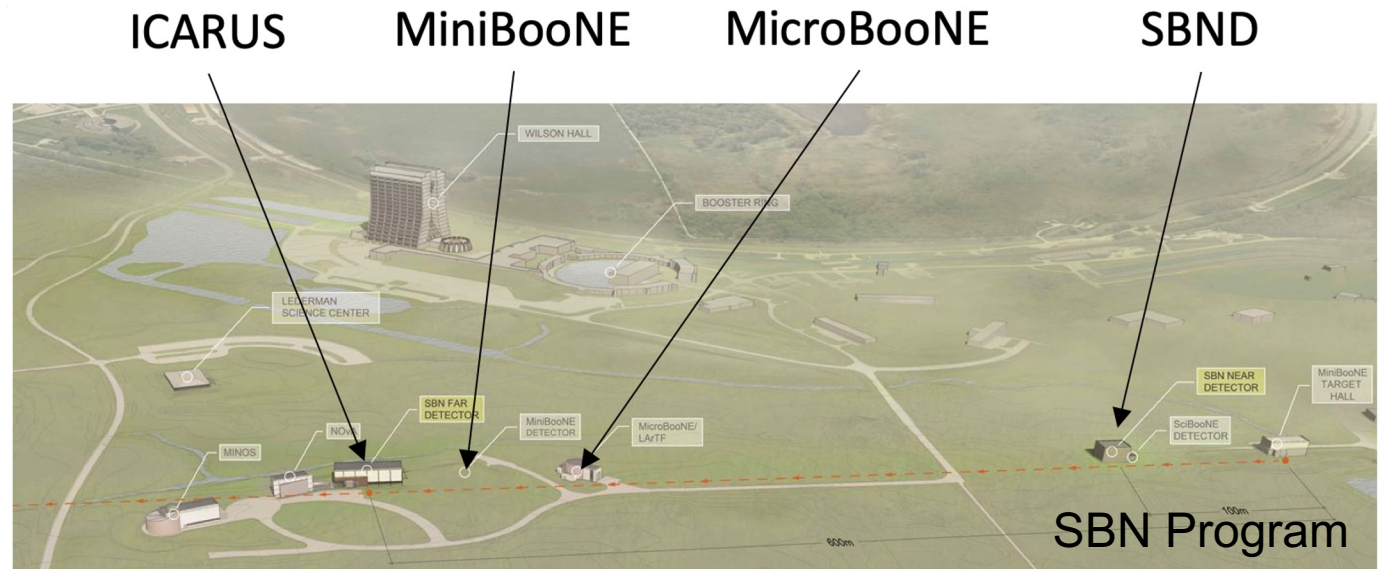
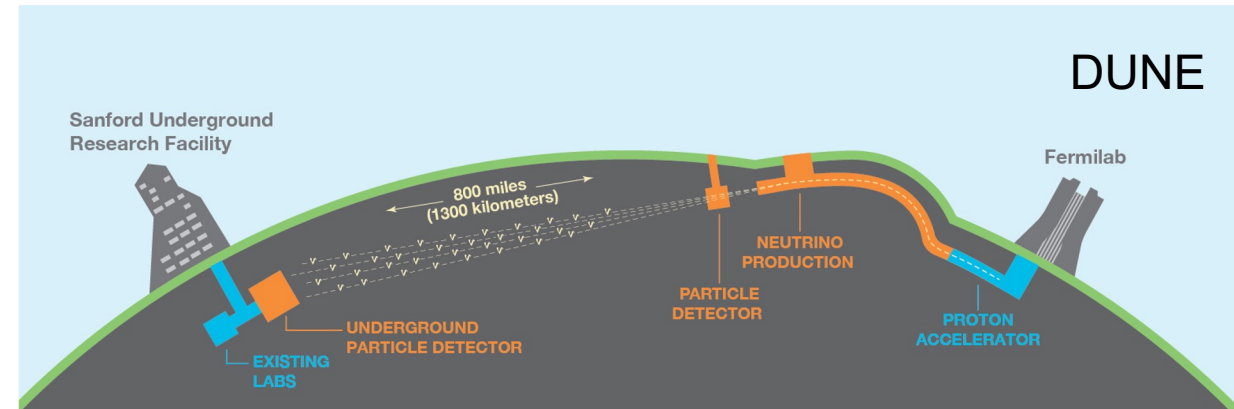
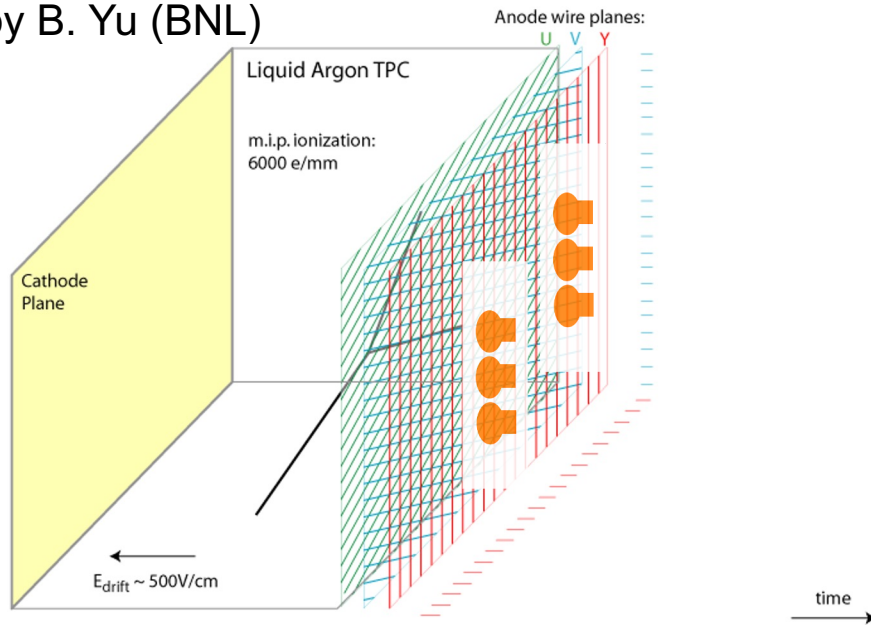


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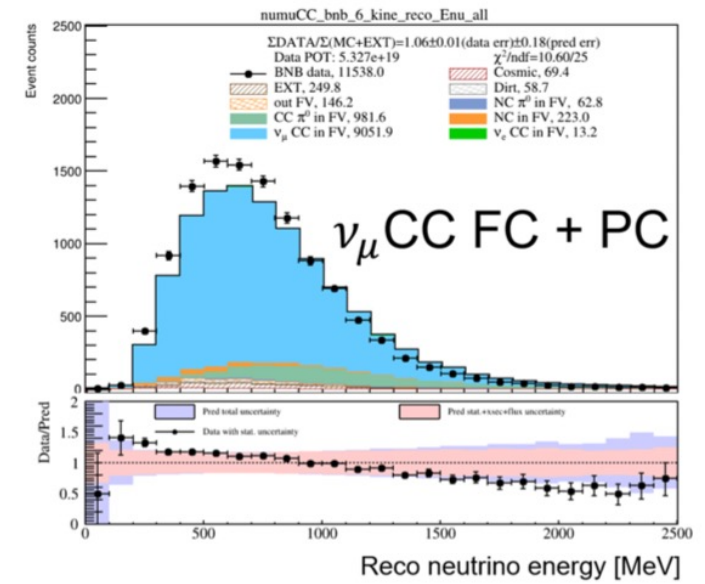
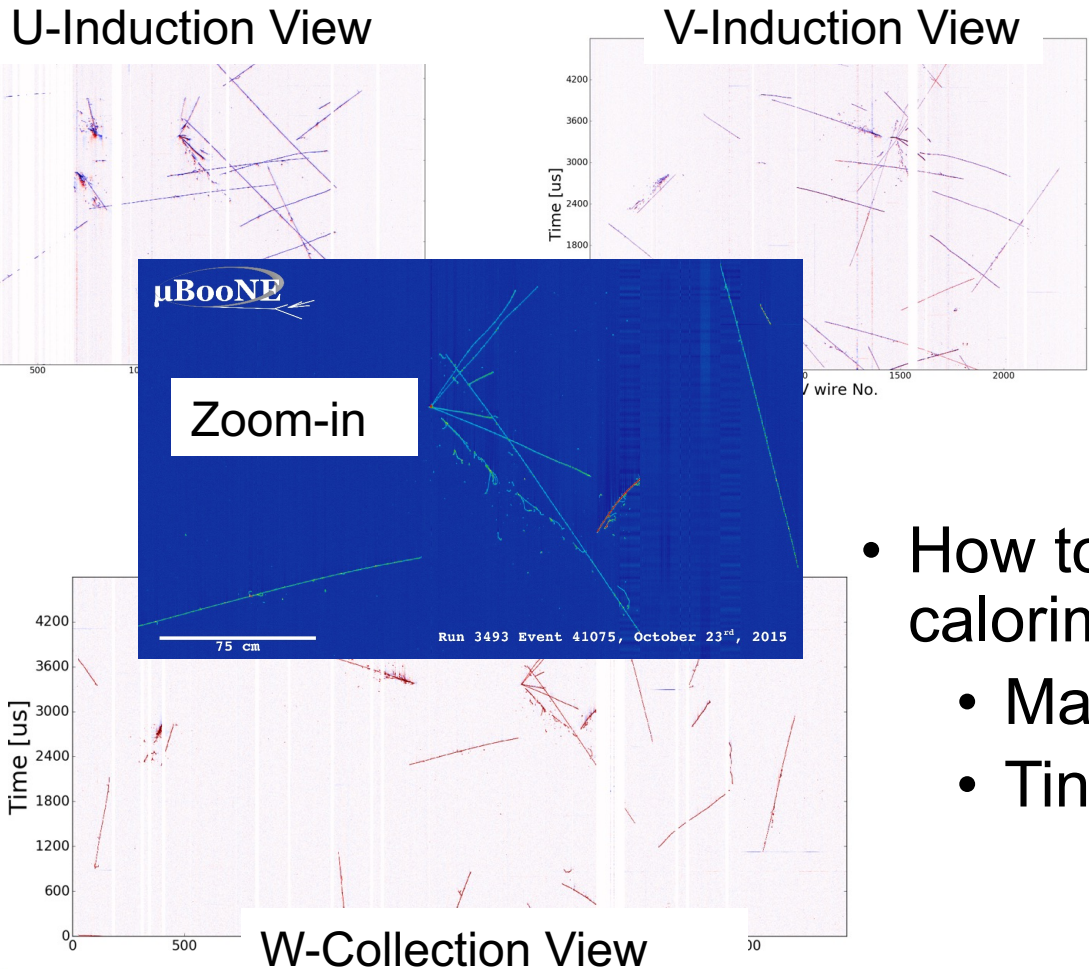
Liquid Argon TPC

- ~mm scale position resolution with multiple 1D wire readouts
- Particle identification (PID) with energy depositions and topologies

LArTPC Signal Formation Illustration
by B. Yu (BNL)



Challenge in Automated Event Reconstruction



- How to convert the excellent resolution and calorimetry to rigorous physics results?
 - Massive amount of information across multi-scales
 - Tiny signal to background ratio

Wire-Cell Event Reconstruction

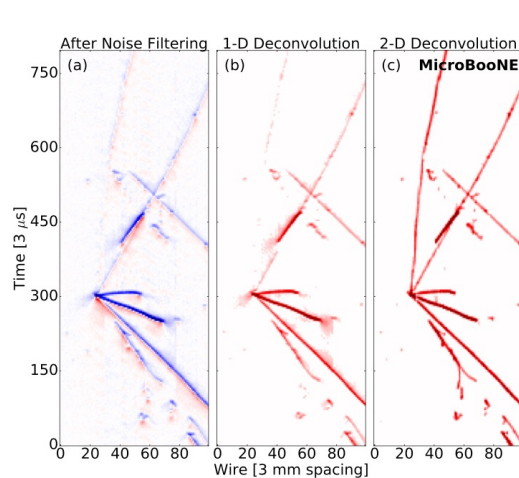


TPC simulation
noise filtering
signal processing

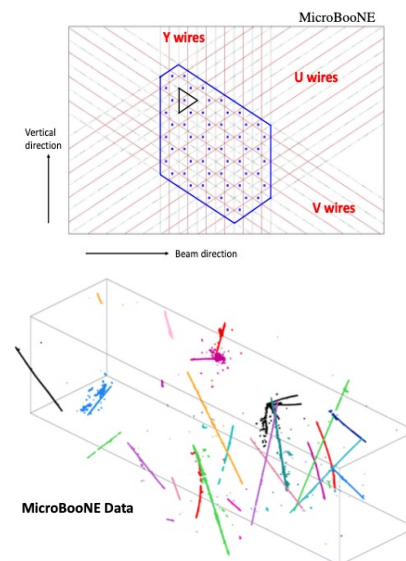
3D imaging
clustering
charge-light matching

3D trajectory & dQ/dx fitting
cosmic muon tagger

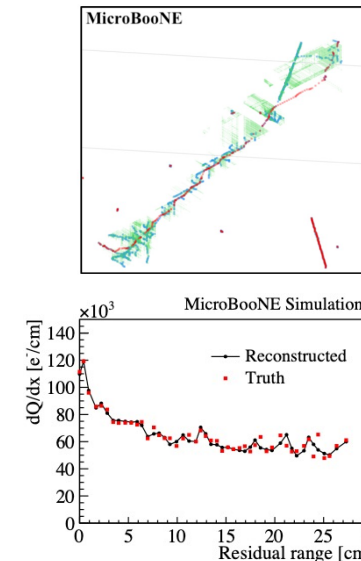
multi-track fitting
DL-3D vertexing
particle identification



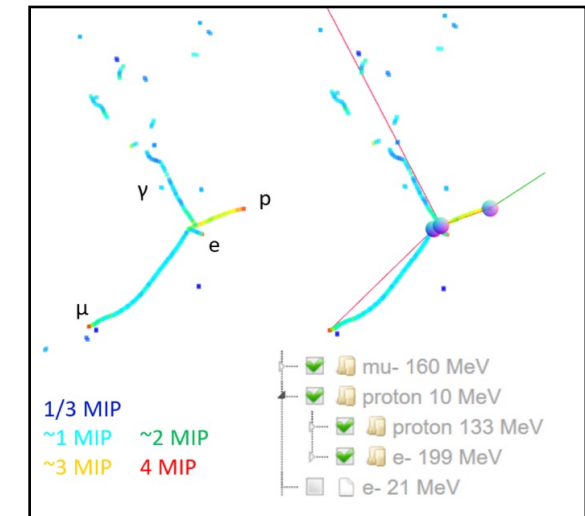
[JINST 12 P08003 \(2017\)](#)
[JINST 13 P07006 \(2018\)](#)
[JINST 13 P07007 \(2018\)](#)
[JINST 16 P01036 \(2020\)](#)



[JINST 13 P05032 \(2018\)](#)
[JINST 16 P06043 \(2021\)](#)



[Phys. Rev. Applied 15, 064071 \(2021\)](#)



[JINST 17 P01037 \(2022\)](#)

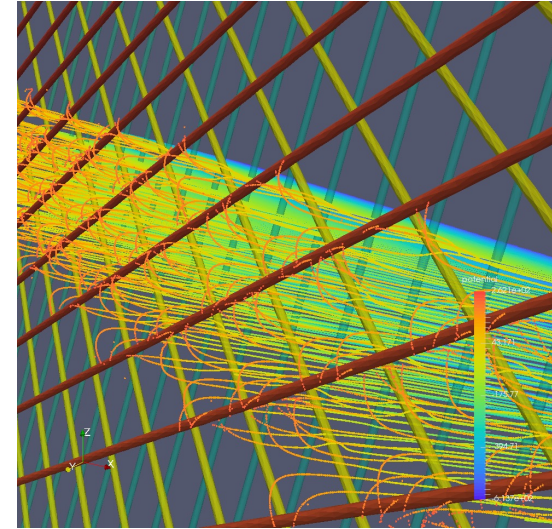
2D-Convolution based LArTPC Simulation

$$\text{Ramo's theorem: } i = -q \vec{E}_w \cdot \vec{v}_q$$

2D: approximate translational symmetry along the wire direction

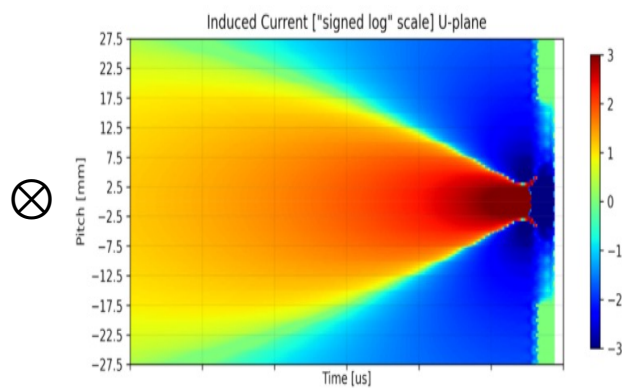
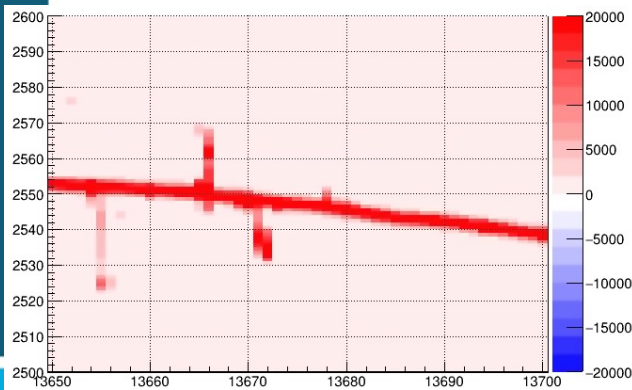
LArTPC wire-readout measures induced charge \otimes response

$$M(t', x') = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} R(t, t', x, x') \cdot S(t, x) dt dx + N(t', x')$$

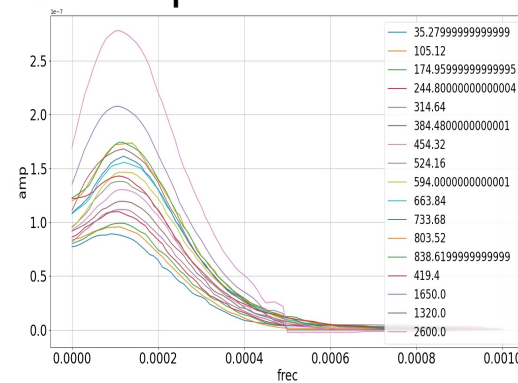


Energy depo + diffusion
+ rasterization

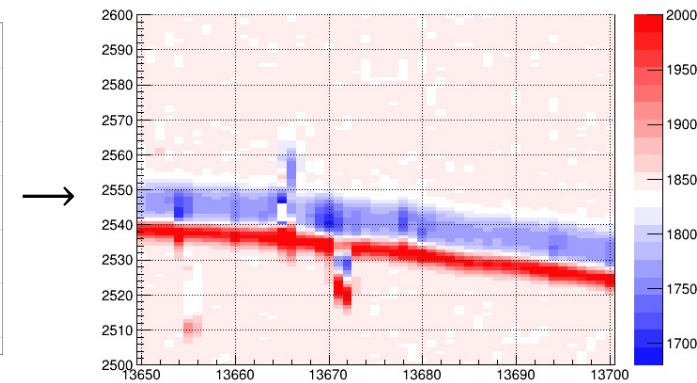
Long-range and
position-dependent field



Noise
Spectrum



Final Signal

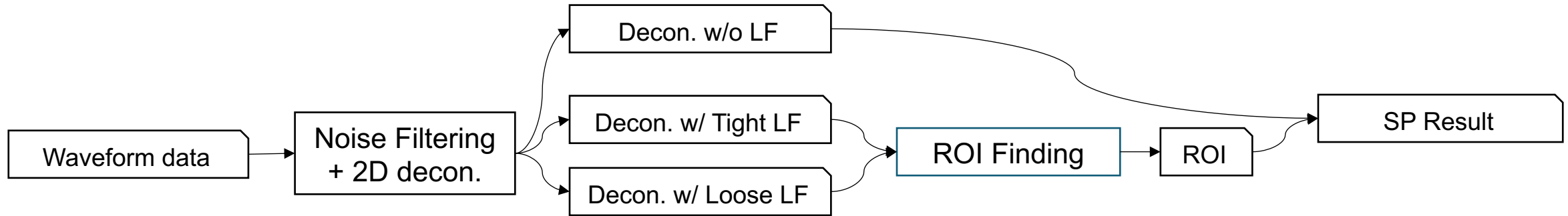


2D-Convolution based Signal Processing

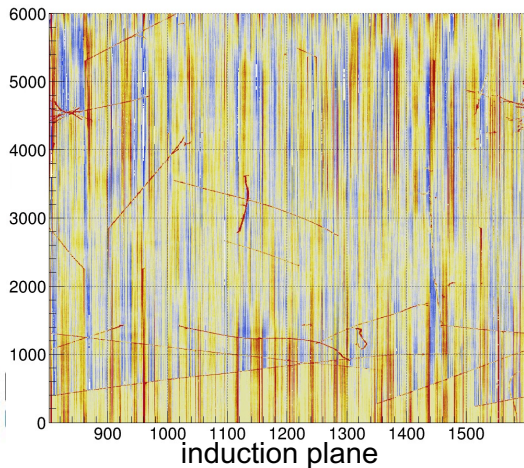
Signal Processing (SP) of LArTPC resolves charge from the original measurement:

$$S(\omega_t, \omega_x) \sim \frac{F(\omega_t, \omega_x) \cdot M(\omega_t, \omega_x)}{R(\omega_t, \omega_x)} \xrightarrow{IFT} S(t, x)$$

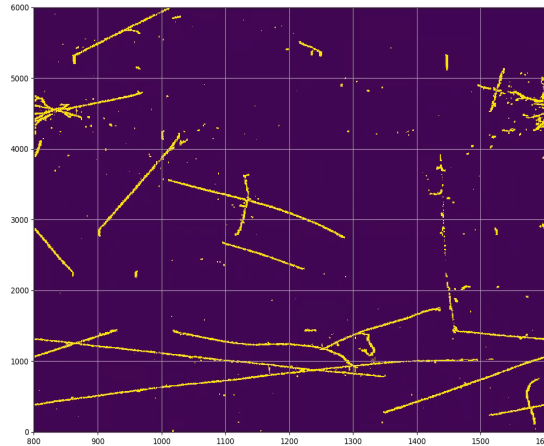
- “2D deconvolution”: assuming translational symmetry in the third dimension
- Utilize the signal/noise separation in both frequency and time domain



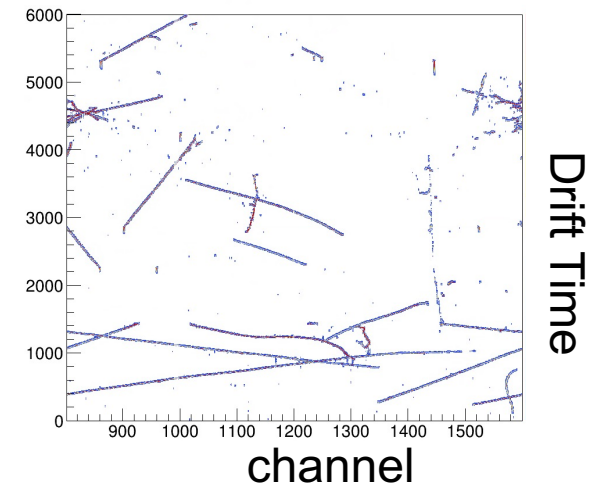
Decon. w/o LF (low frequency) filter
Waveform \rightarrow charge, dense



ROI (region of interest):
Hit finding, sparsify

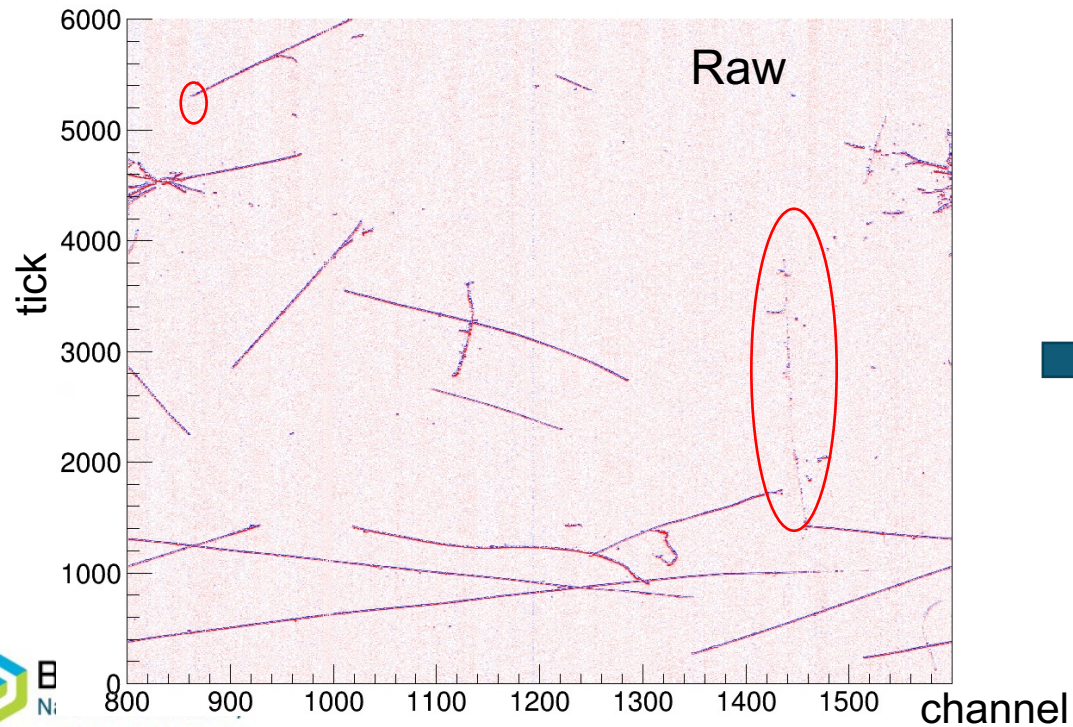
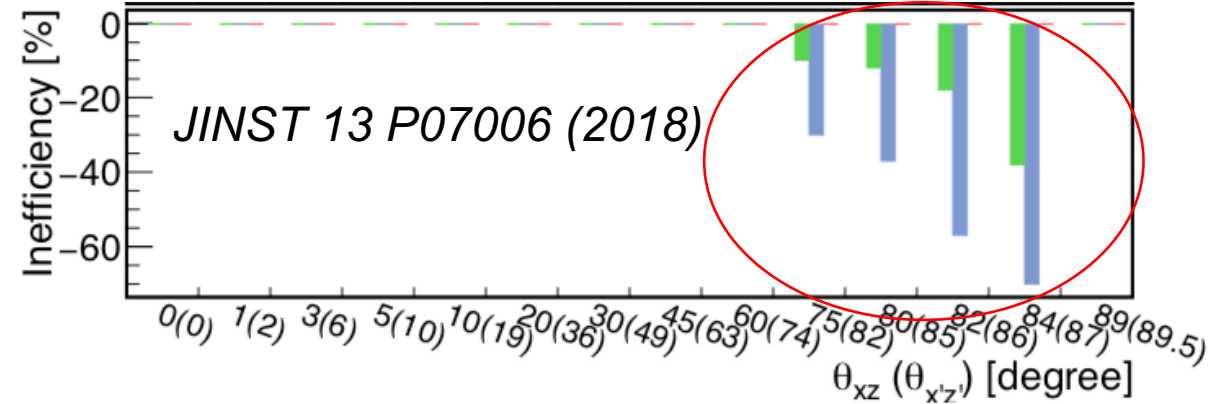
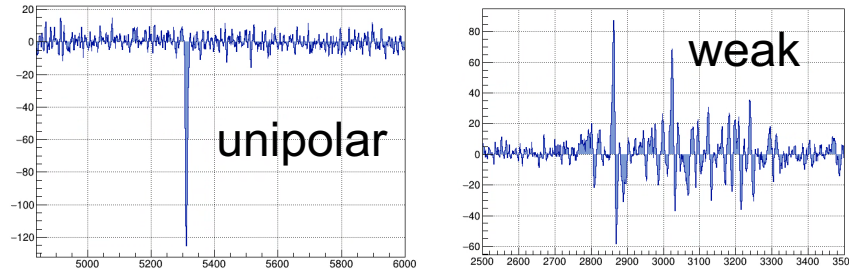


SP (signal processing) result:
Sparse, ionization charge

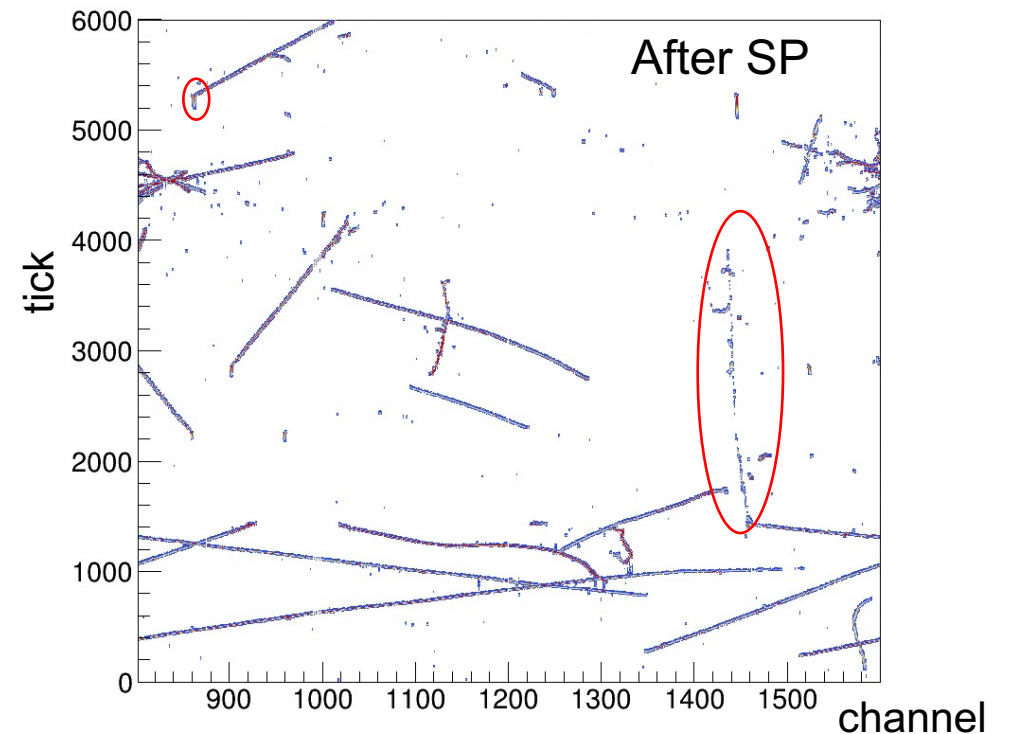


DNN ROI finding to improve LArTPC Signal Processing

- “Prolonged Track” – weak signal
- “Tear Drop” - distorted waveform
- Noisy dots - noise



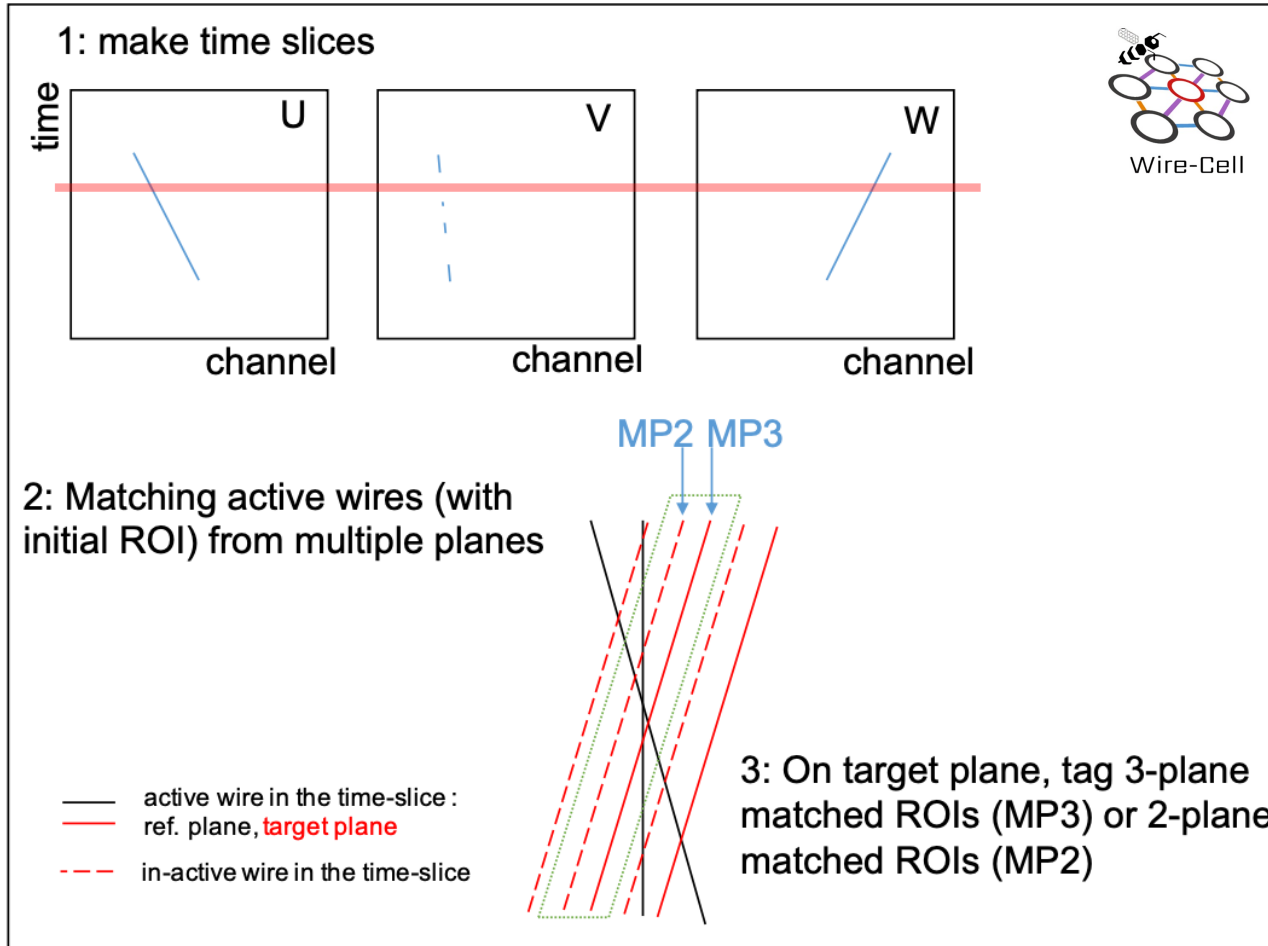
SP



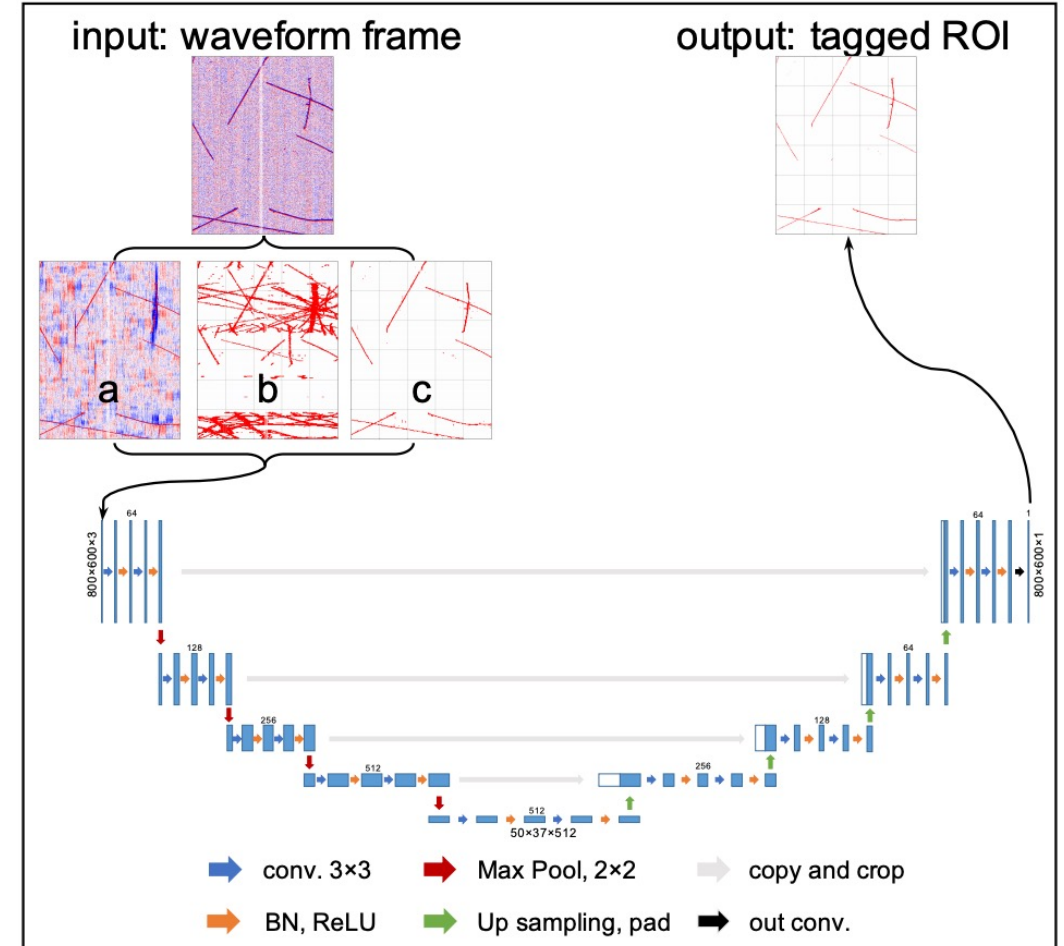
DNN ROI finding with multi-plane information

JINST 16 P01036 (2021)

Multi-plane information in Signal Processing

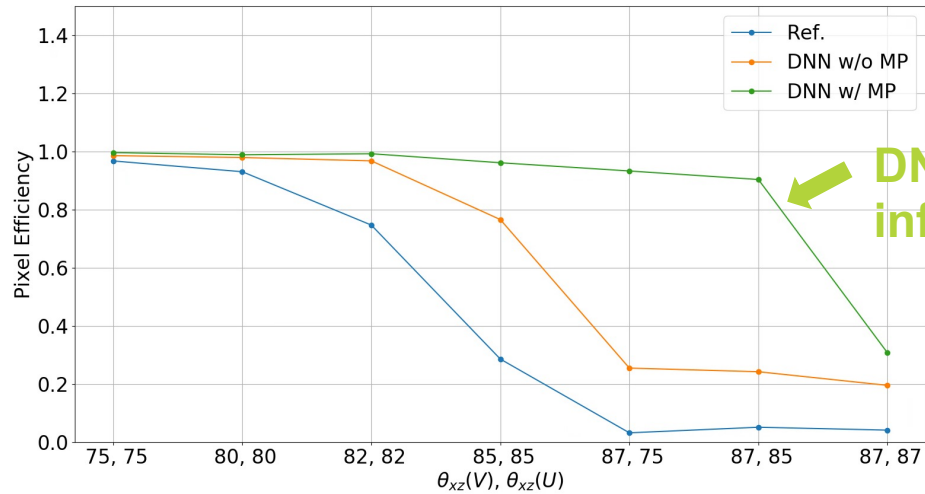


DNN ROI finding with multiple input channel

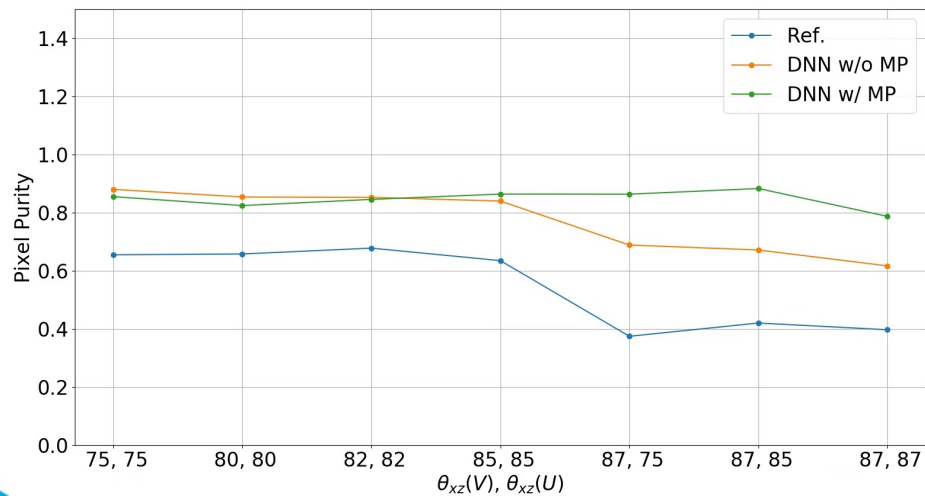


Trained using 450 images

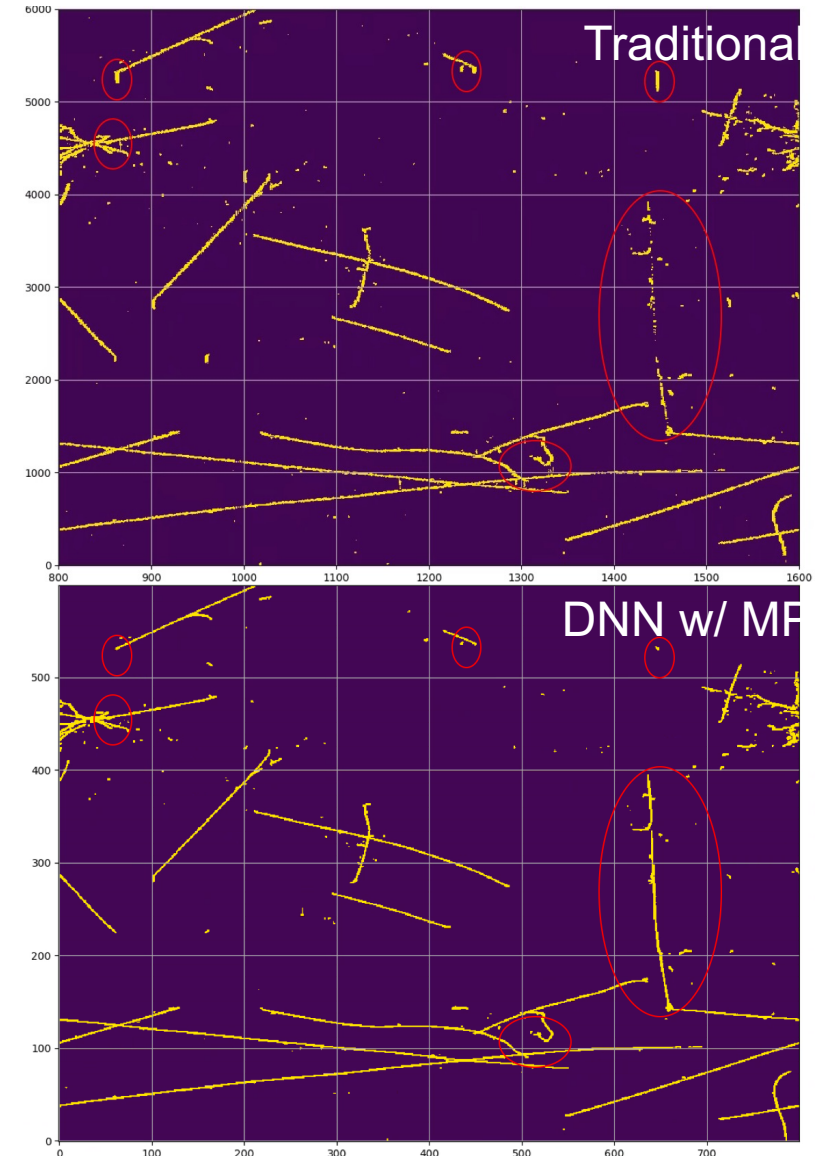
ProtoDUNE simulation
ROI finding on V plane (2nd induction)



DNN With 3-plane information



tested on ProtoDUNE data



Wire-Cell Tomographic Event Reconstruction

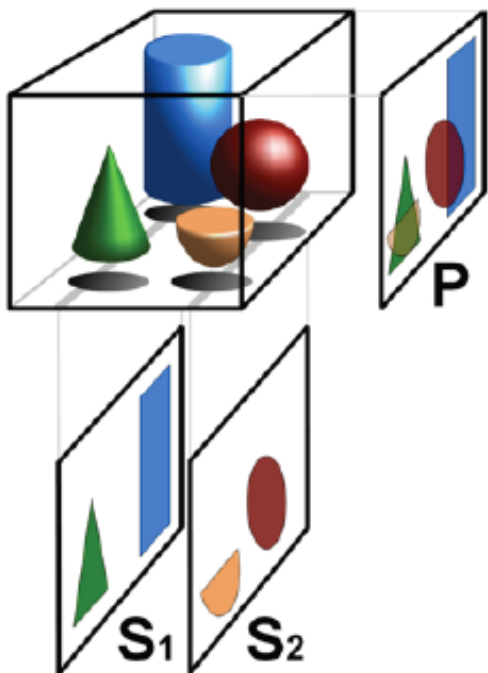
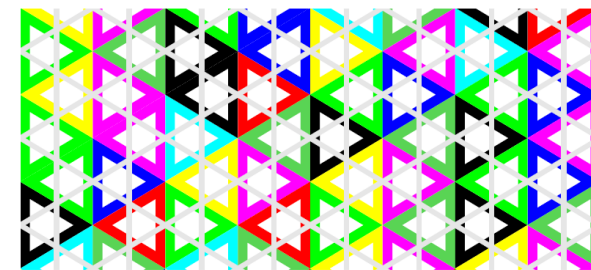
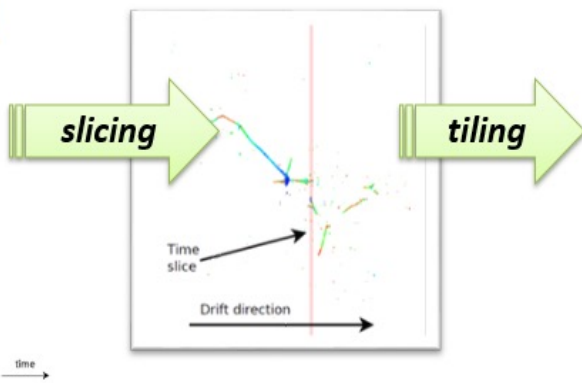
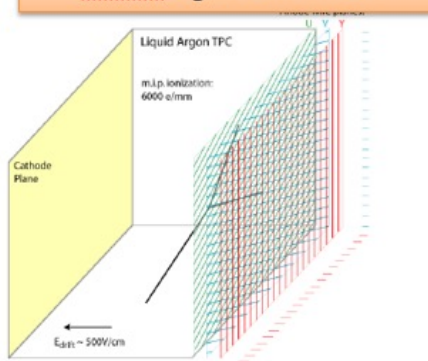


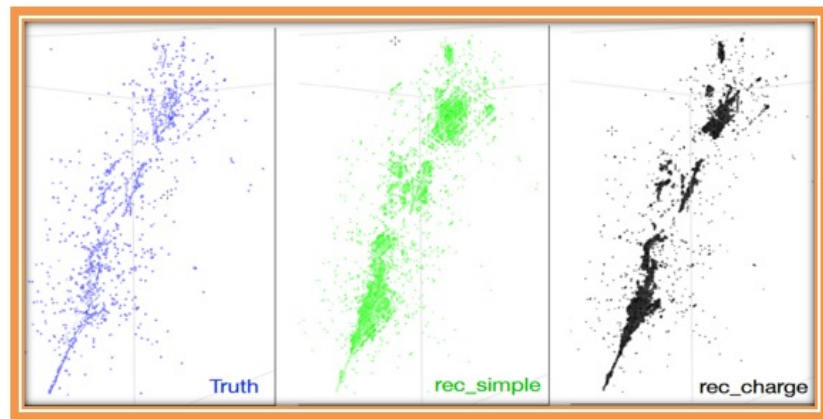
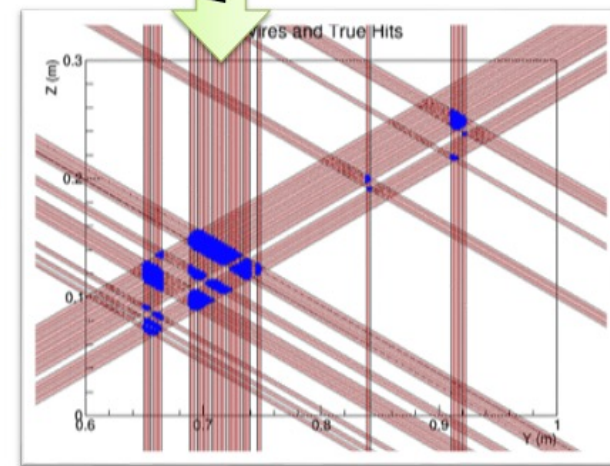
Fig.1: Basic principle of **tomography**: superposition free tomographic cross sections S1 and S2 compared with the projected image P

<https://en.wikipedia.org/wiki/Tomography>

LArTPC Signal Formation

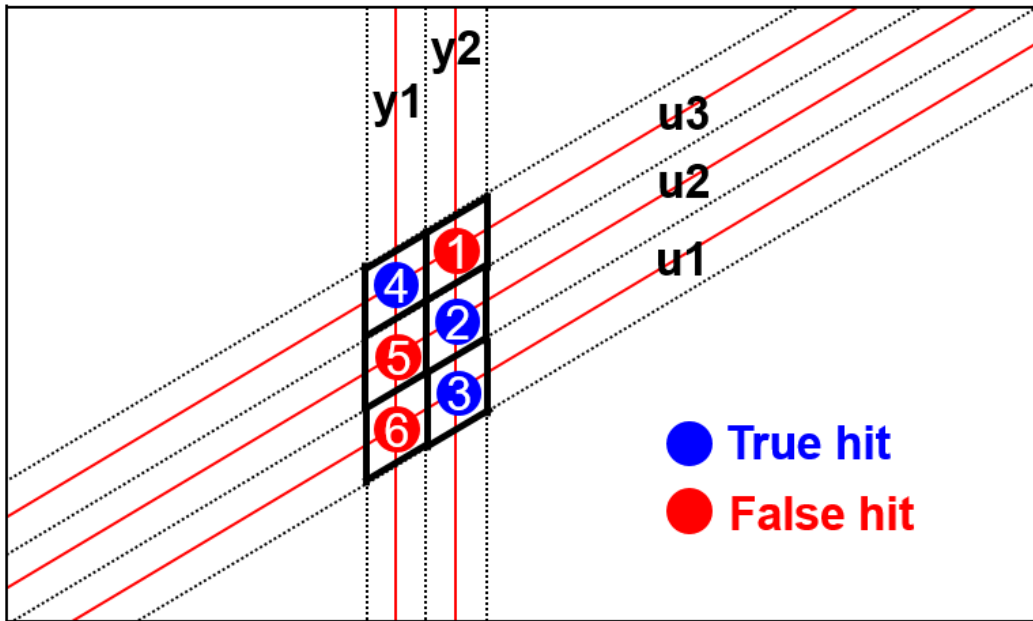


merging



“Three-dimensional Imaging for Large LArTPCs”,
[JINST 13, P05032 \(2018\)](#)

Solving: usage of Charge, Sparsity, Positivity, Proximity



measured charges on Wires

$$y = A \cdot X$$

true charge to be resolved

$$\begin{pmatrix} y1 \\ y2 \\ u1 \\ u2 \\ u3 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & a & a & a \\ a & a & a & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 & a \\ 0 & a & 0 & 0 & a & 0 \\ a & 0 & 0 & a & 0 & 0 \end{pmatrix} \begin{pmatrix} H1 \\ H2 \\ H3 \\ H4 \\ H5 \\ H6 \end{pmatrix}$$

matrix determined by geometry, $a=1$

- The goal is to differentiate the true hits from fake ones by using the charge information
 - ~ large charge \rightarrow true hits
 - ~ zero charge \rightarrow fake hits
- Sparsity, positivity, and proximity information are added through compressed sensing (L1 regularization)

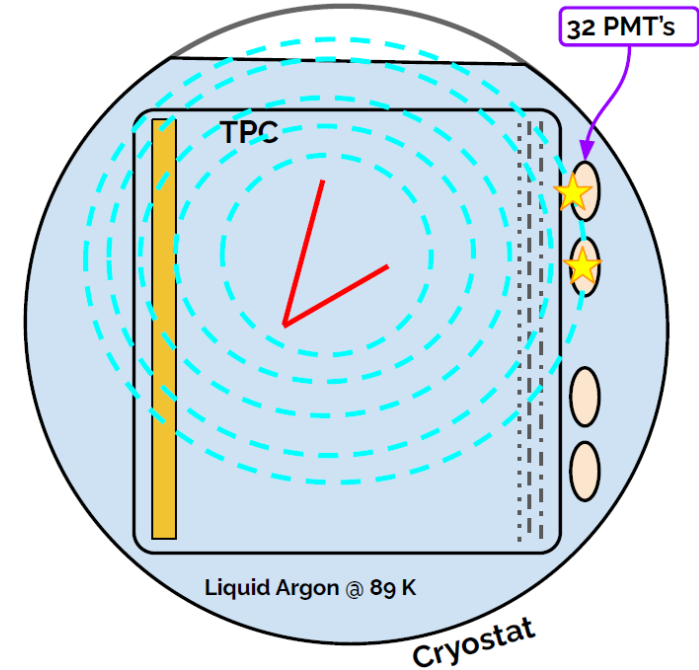
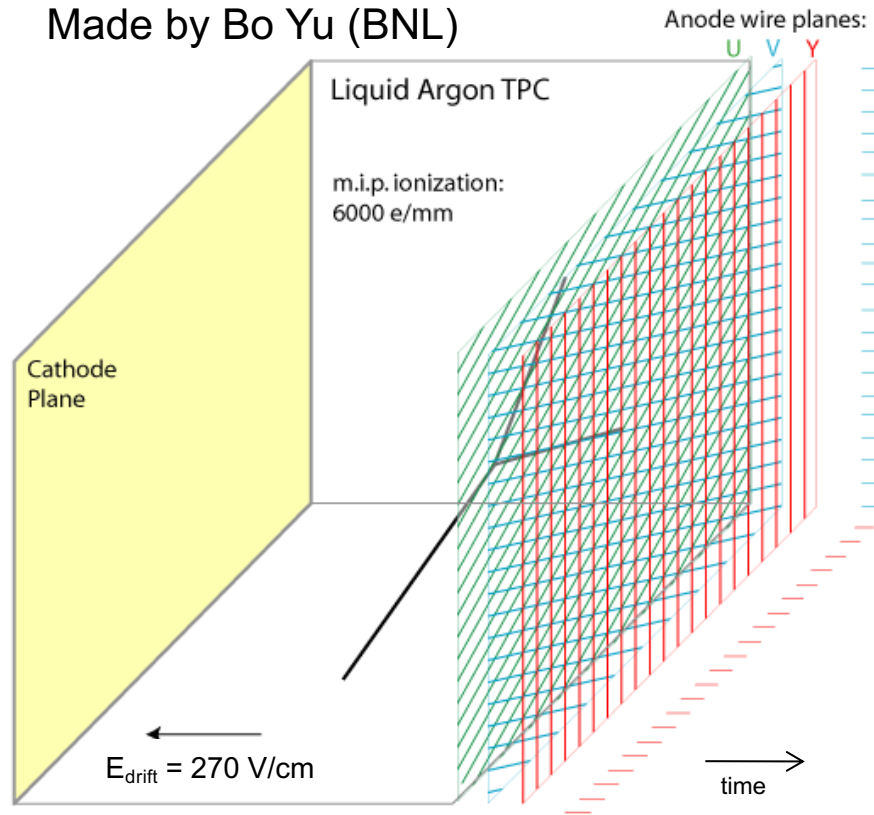
$$\text{L1 reg. } O(N!) \rightarrow O(m \times N)$$

$$\chi^2 = (y - A \cdot x)^2 + \lambda \cdot \sum_i |x_i|$$

E. Candes, J. Romberg, T. Taoⁱ
arXiv-math/0503066

Cluster-flash (light) Matching

Made by Bo Yu (BNL)



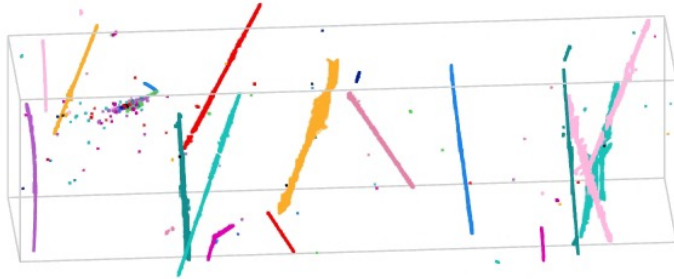
PMTs detect the scintillation light, time \sim ns

Drift velocity $1.1 \text{ mm}/\mu\text{s}$ \rightarrow several ms drift time

- In LArTPC, the light (PMT) readout and charge (TPC) readout systems are decoupled
- The identification of neutrino interaction candidate requires matching the charge signal with the light signal in order to obtain the event time

Matching Principle

[JINST 16 P06043 \(2021\)](#)



Core Charge-Light Matching Algorithm

$$\chi^2 = \sum_i \sum_j \chi_{ij}^2 + \chi_{p1}^2 + \chi_{p2}^2 + \chi_{p3}^2$$

Overall test statistics to be minimized

$$\chi_{ij}^2 = \frac{(M_{ij} - \sum_k a_{ik} \cdot P_{ikj} - b_i \cdot M_{ij})^2}{\delta M_{ij}^2}$$

Comparison of the measured and predicted light pattern

Rule 1st

$$\chi_{p1}^2 = \sum_i \frac{(\sum_k a_{ik} - 1)^2}{c_1^2}$$

Each charge cluster can only be used once

Rule 2nd

$$\chi_{p2}^2 = \sum_i \frac{b_i^2}{c_2^2}$$

Observed light flash may not correspond to any charge cluster

$$\chi_{p3}^2 = \lambda \cdot \sum_i \sum_k a_{ik}$$

Compressed sensing to select the best pairs

M : Measured Light Pattern

P : Predicted Light Pattern

δ : Uncertainty

i : i th Light Flash

j : j th PMT

k : k th Charge Cluster

Aggressively pursue charge-light matching

Additional cuts to examine the "light mismatch" events

Hypotheses Selection

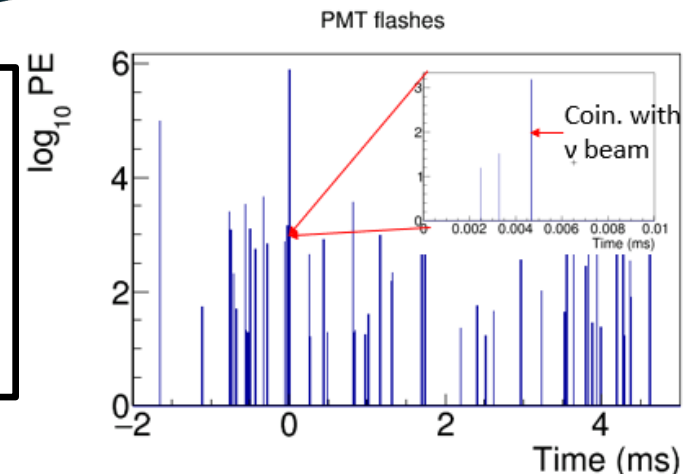
Match Hypotheses

Reconstruct

- Light signal proportional to (reconstructed 3D) charge
- Known light acceptance given position
- Predicted vs. Measured light pattern with Compressed Sensing

All possible hypotheses

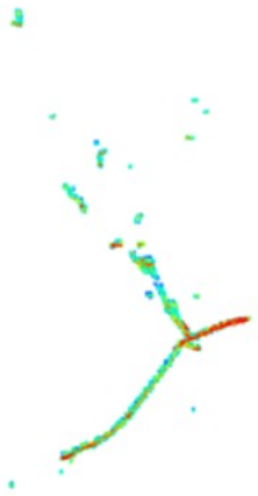
- One cluster → at most one flash (inefficiency in the light system)
- One flash → many or zero TPC clusters within corresponding active volume (activities in inactive volume)



40-50 PMT activities

3D Pattern Recognition

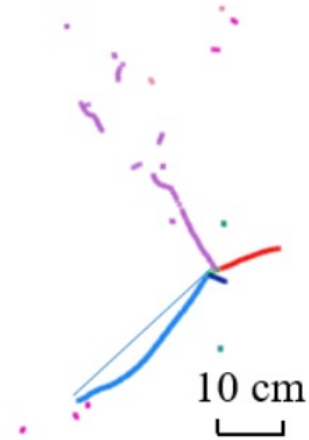
(a) Selected neutrino activity



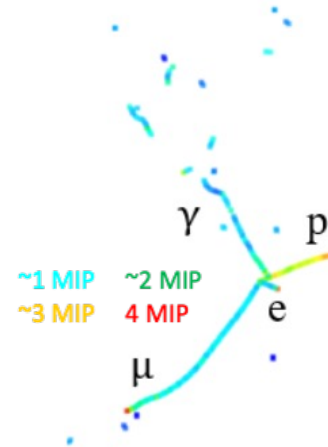
(b) Track/Shower separation



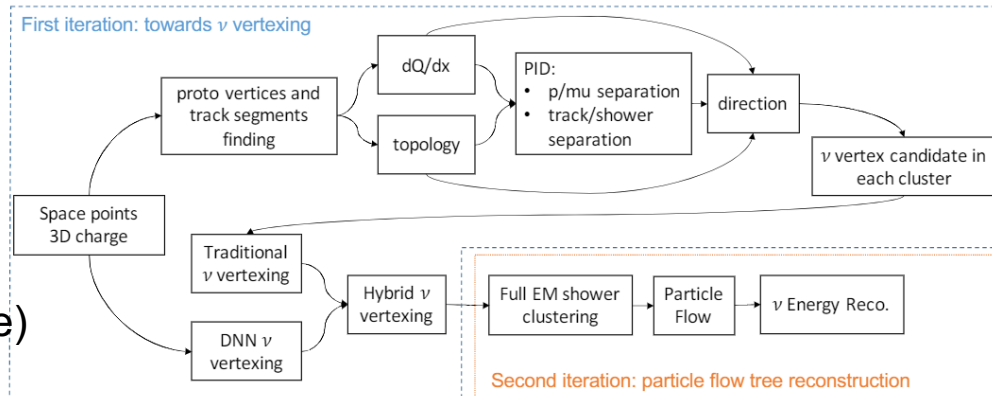
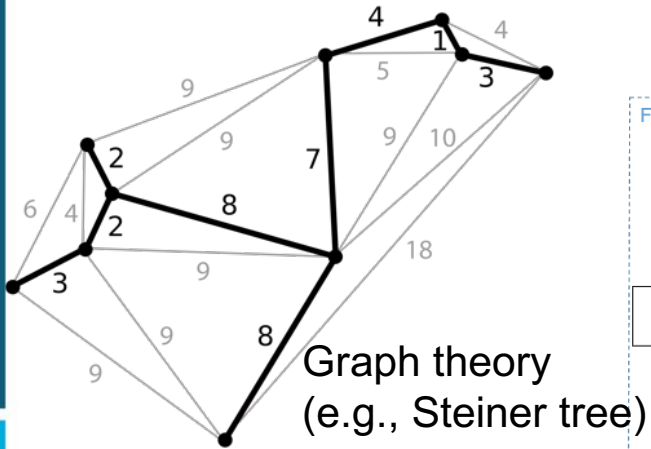
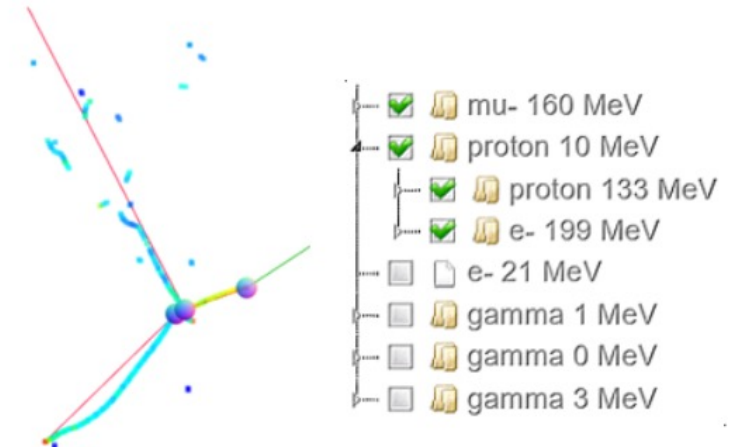
(c) Particle-level sub-clustering



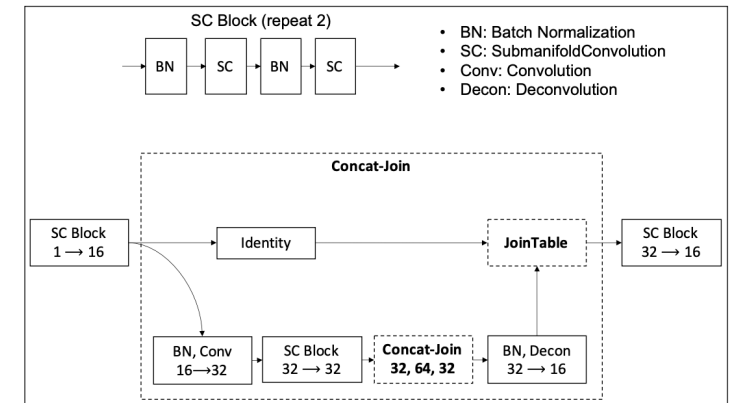
(d) 3D dQ/dx displayed with PID capability



(e) Particle flow starting from neutrino vertex



Sparse Regression U-Net

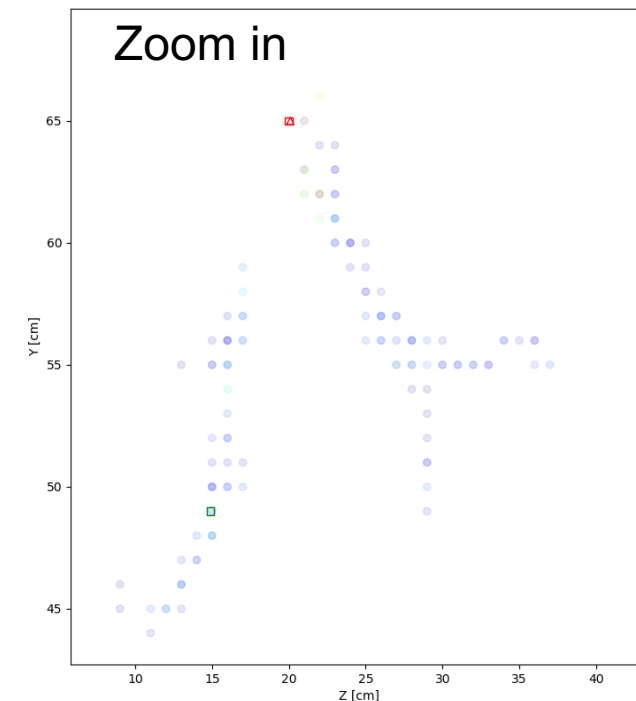
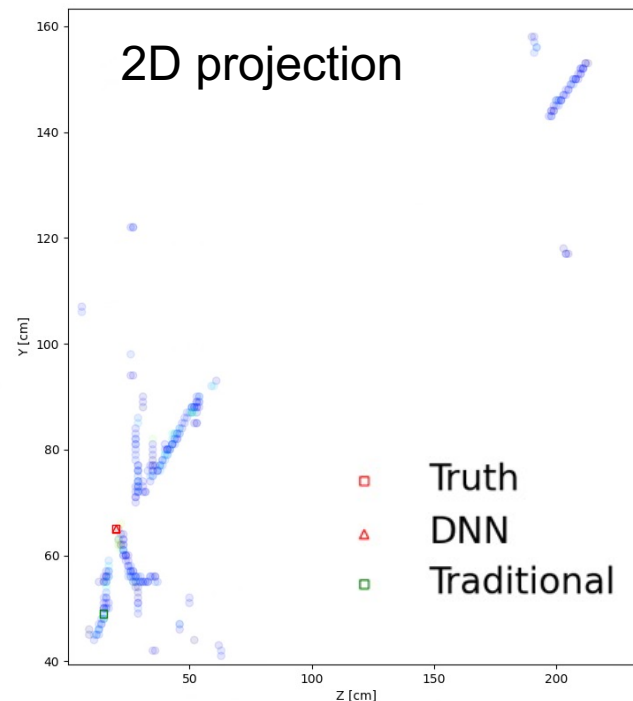
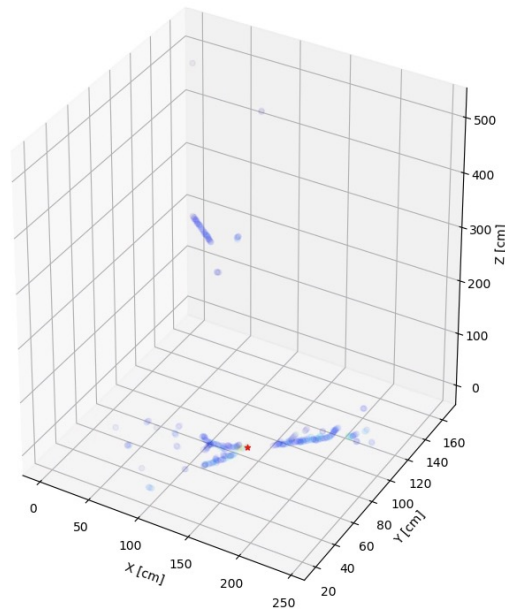


Deep Learning based Neutrino Interaction Vertex Finding

Regression segmentation with a sparse U-Net

- U-Net: efficiently use geometry info which is critical
 - compared to graph networks
- Regression loss on distance based “confidence map” to use a region of points instead of only one
 - otherwise, data is highly imbalanced (Z. Cao etc, arXiv:1812.08008)
- Sparse: boosted computing efficiency with our sparse 3D data
 - Submanifold Sparse Convolutional Networks (B. Graham etc, arXiv:1706.01307)

3D points from Wire-Cell



Regression segmentation

Initially we used Cross Entropy loss

- effectively only use the vertex information for one space point
- doesn't care about the distance between the prediction and the target.
 - while our main metric is this distance.

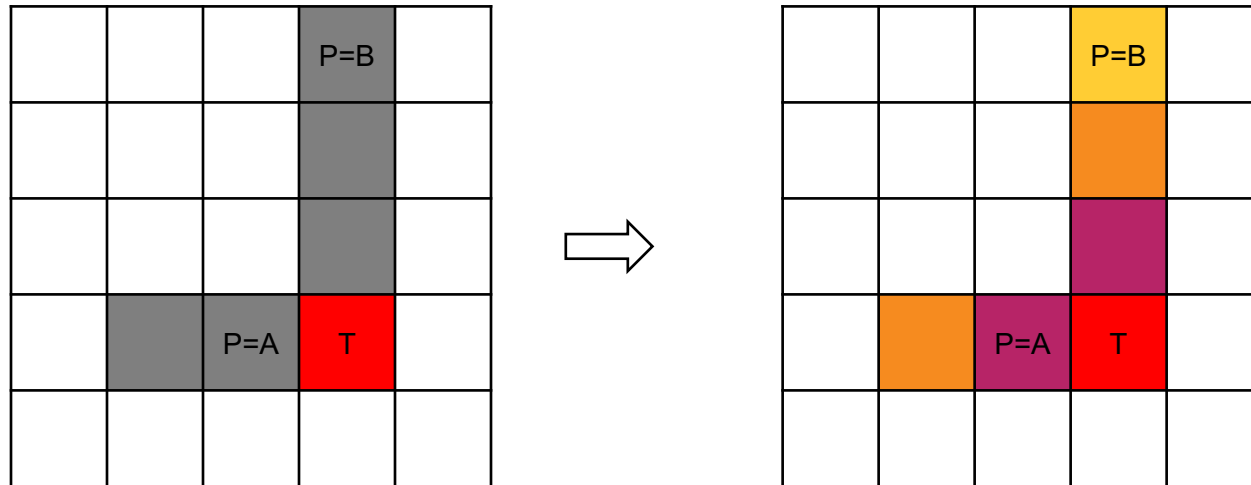
→ encode the distance information for a region of points

- predicting the full “confidence map” instead of only one point

- current mapping: $\text{Conf}_{\text{truth}} = \exp\left(-\frac{\|\vec{x} - \vec{v}_{\text{truth}}\|^2}{2\sigma^2}\right)$

OpenPose:

<https://arxiv.org/pdf/1812.08008.pdf>

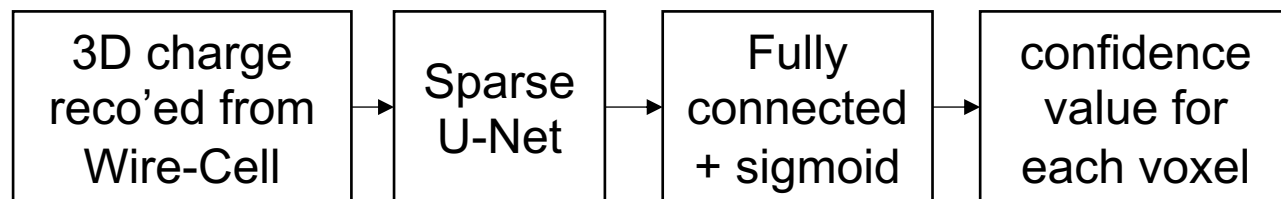


Network structure and improvements

Used *SparseConvNet* to realized 3D sparse conv. DNN

<https://github.com/facebookresearch/SparseConvNet>

This work: [github](#), [paper](#)



[SparseConvNet](#)

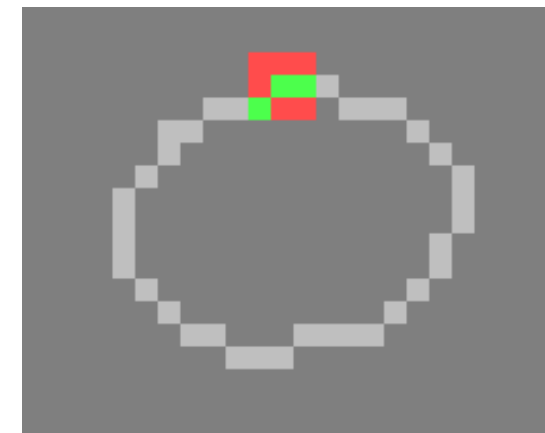
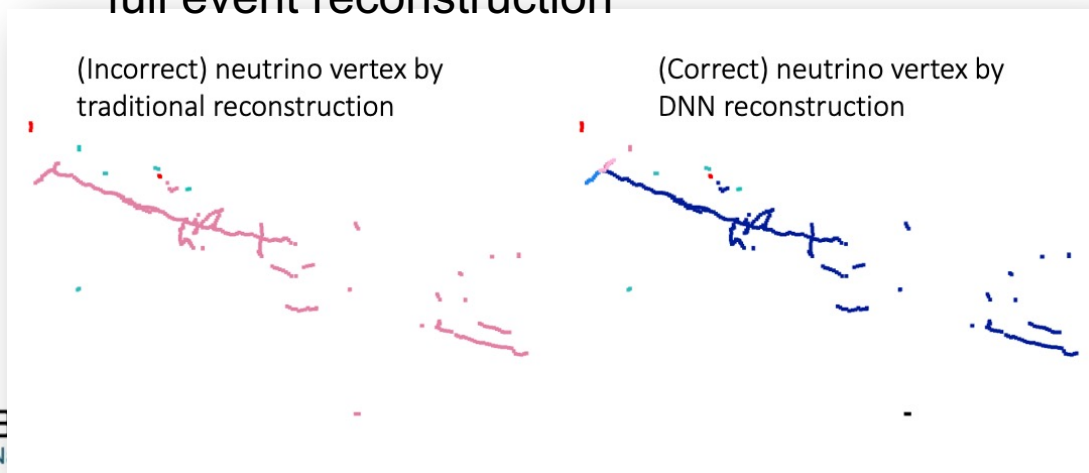
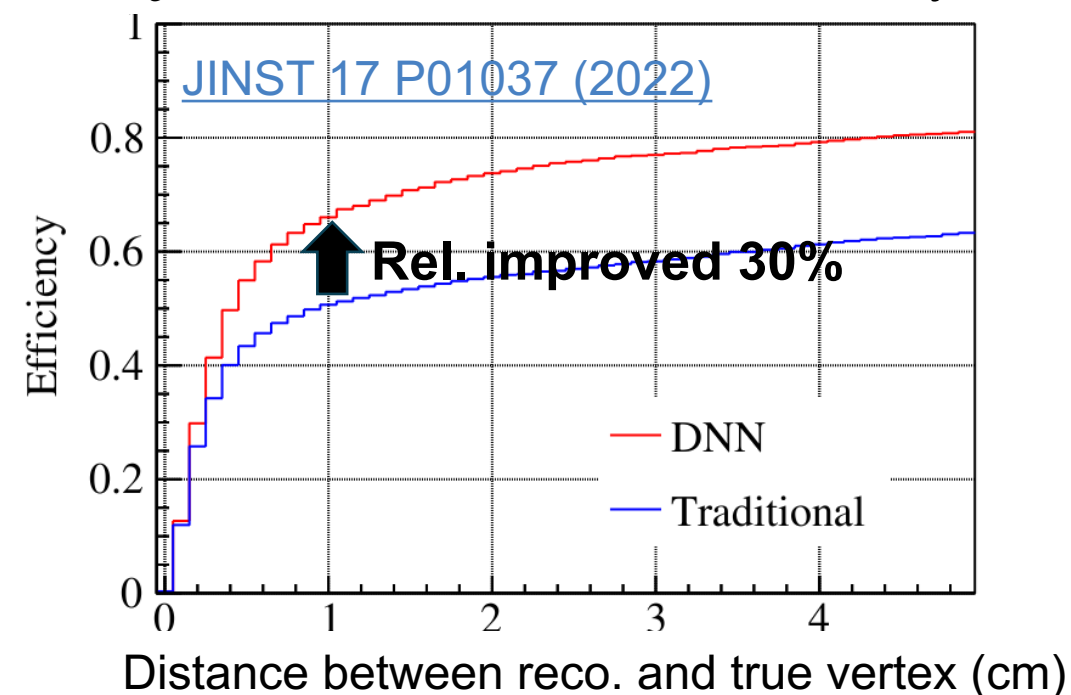


Illustration of impact of vertex ID on the full event reconstruction

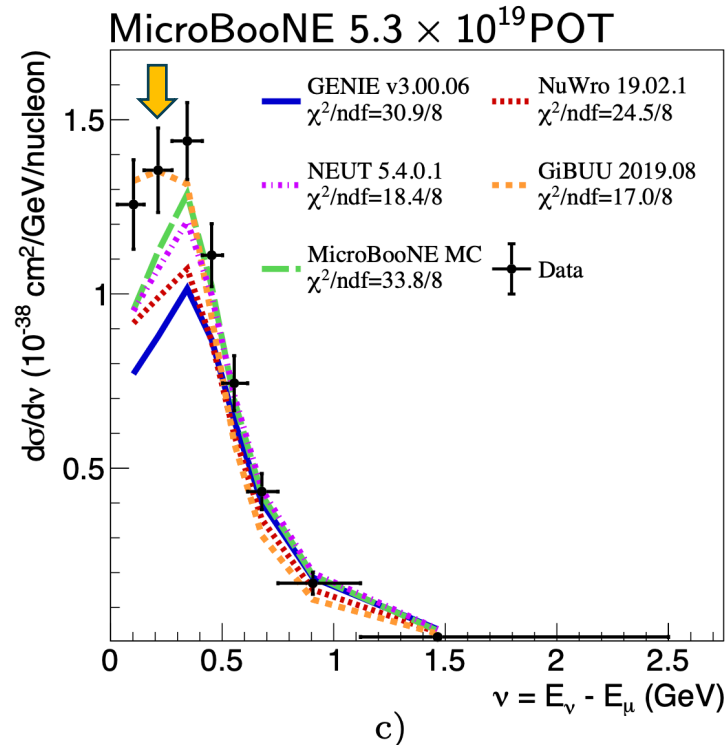


ν_e CC vertex identification efficiency



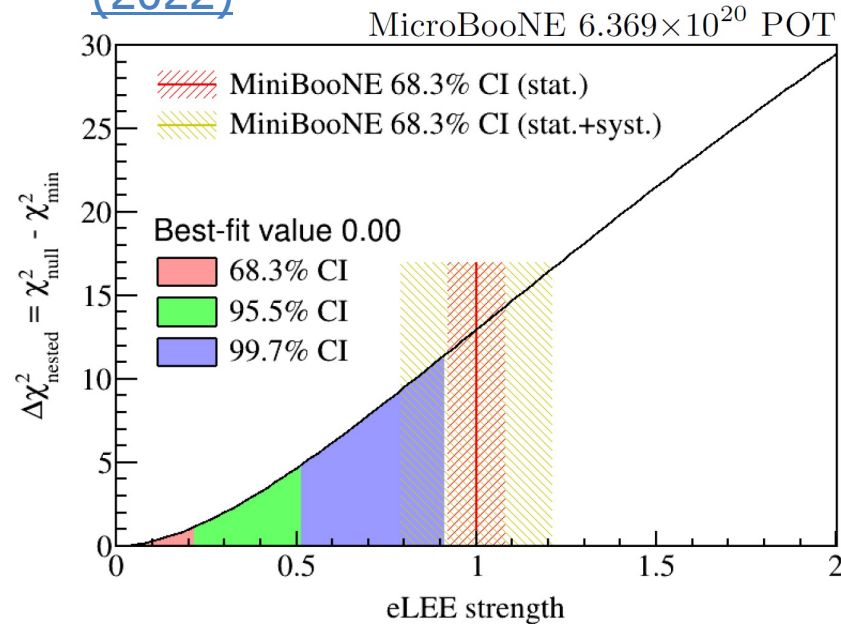
Application of Wire-Cell in Physics Analyses

Energy-dependent Cross Section
[Phys. Rev. Lett. 128, 151801 \(2022\)](#)



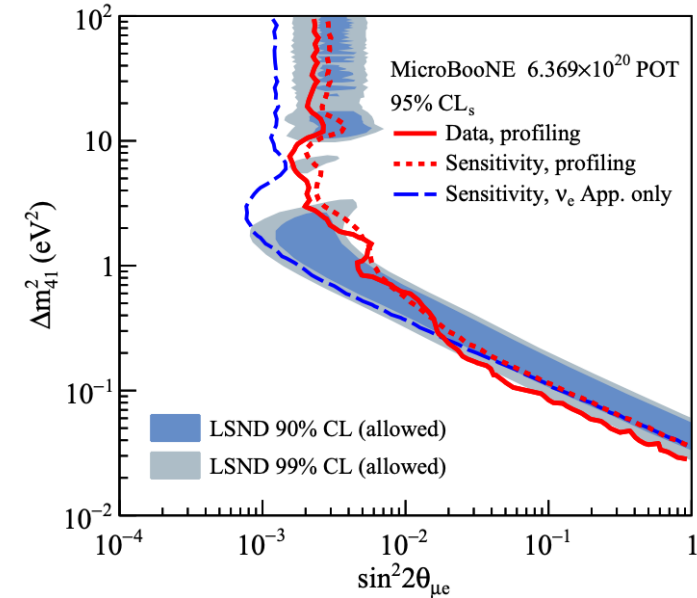
- Good separation power of model predictions from different generators
- GiBUU's central prediction gives best agreement at low energy transfer for Ar \Rightarrow more contribution of 2p2h

Search for ν_e Low Energy Excess
[Phys. Rev. D 105, 112005 \(2022\)](#)
[Phys. Rev. Lett. 128, 241801 \(2022\)](#)



- 68% stat-only (full) uncer. MiniBooNE CI is disfavored at over 3σ (2.6σ)
- ν_e cannot be the sole explanation of MiniBooNE LEE!

Constraints on light Sterile neutrino oscillations, [Phys. Rev. Lett. 130, 011801 \(2023\)](#), submitted to PRL



- No hint of light sterile neutrino oscillations has been found yet, and so we set exclusion contours (plotted at the 95% confidence level)

Outlook

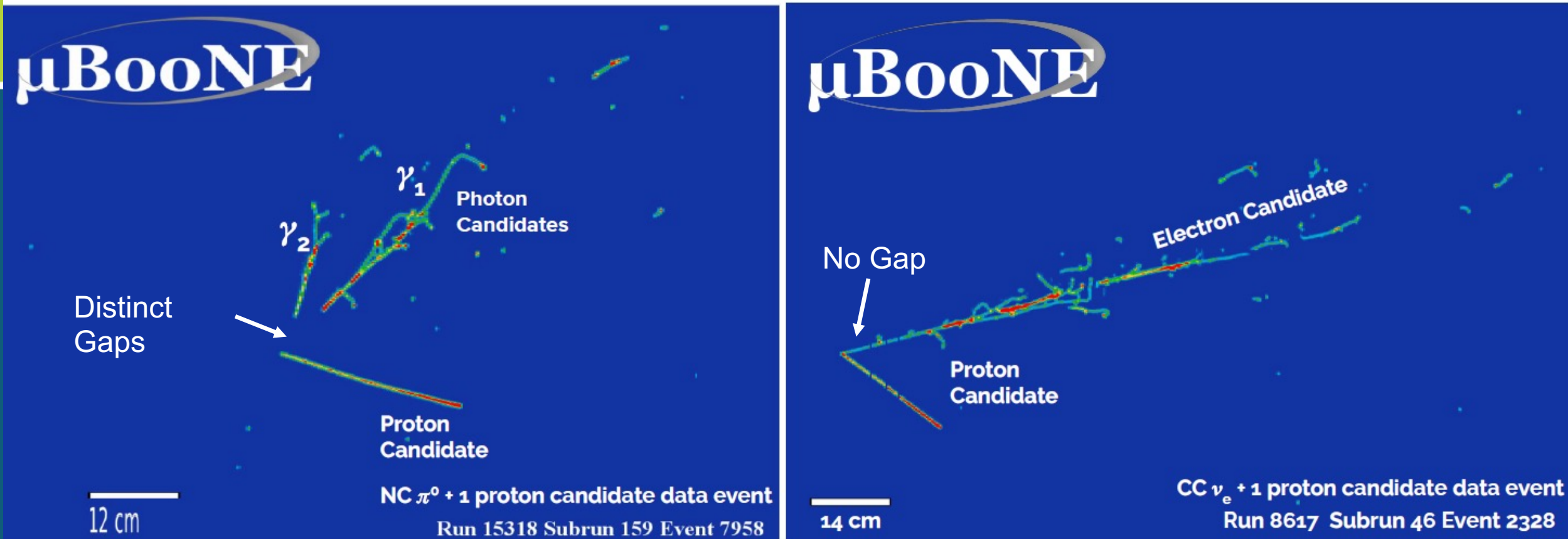
- The Wire-Cell team has developed a fully automated reconstruction chain for LArTPC reconstruction for neutrino experiments
- Its good performance was demonstrated in MicroBooNE analyses
- <https://www.bnl.gov/wirecellsummit/>

The Second Wire-Cell Reconstruction Summit

Hosted by Brookhaven National Laboratory
The workshop will held as a hybrid event on April 10–12, 2024

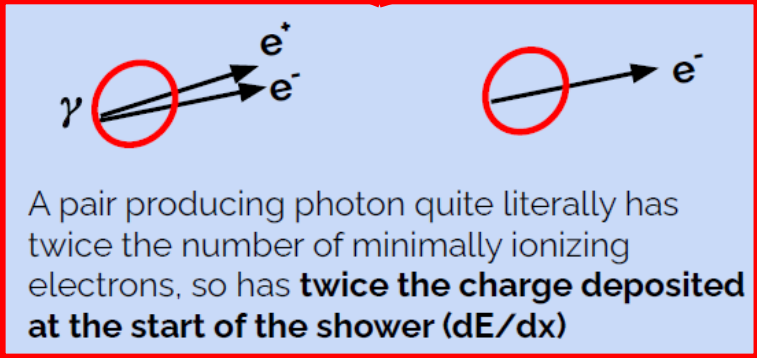
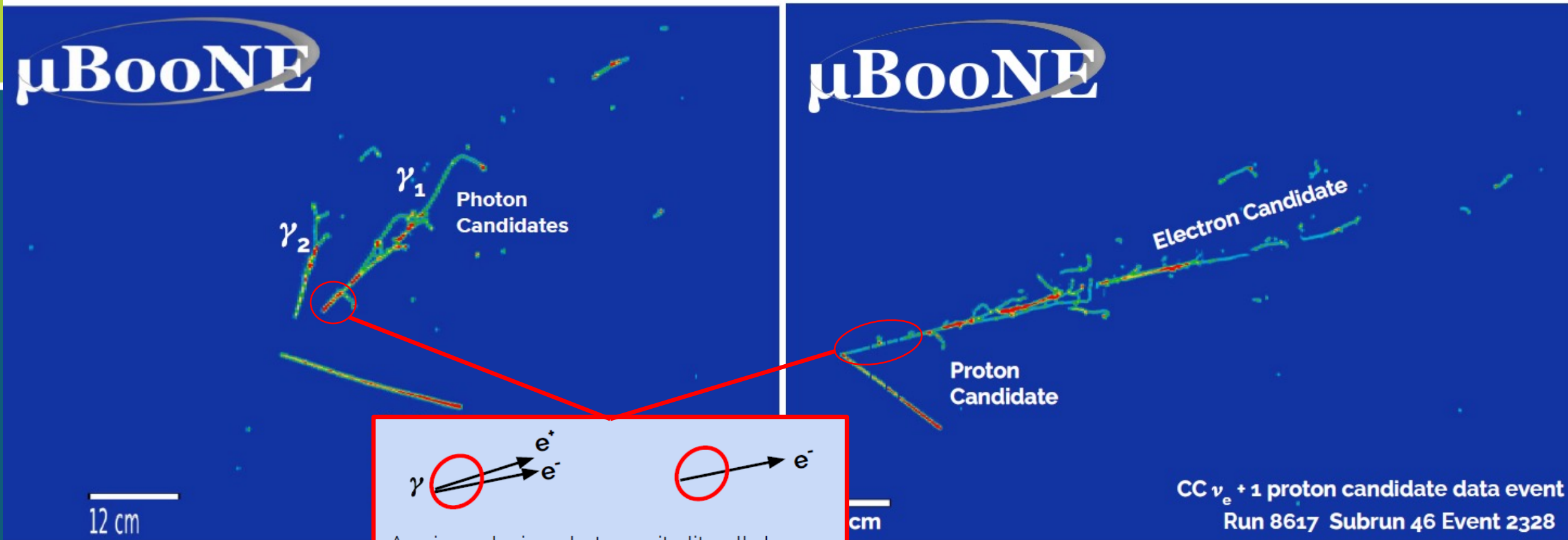
Thanks!

Separation of e and γ in LArTPC



- Event topology to separate EM showers (e/ γ) from tracks (proton, muon)
- Separation of e and γ : Gap Identification

Separation of e and γ in LArTPC

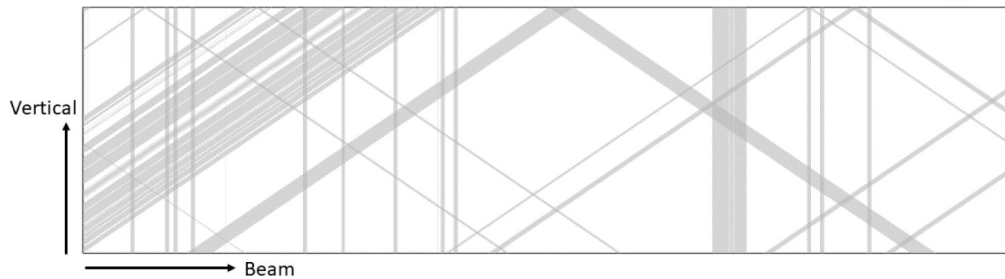


- Event topology to identify ν_e (e/ γ) from tracks (proton, muon)
- Separation of e and γ : Gap Identification + dE/dx
- Unique capability to identify ν_e charge-current (CC) interactions in LArTPC

Overcome Challenges of 10% non-functional channels

- Impact of 10% non-functional channels is reduced from **~30%** → **~3% dead volume** by requiring only 2 out of 3 wire planes in reconstruction when necessary
 - Utilizing coverage of 3 planes, but generating a lot of fake 3D activities (ghosts)
 - Dedicated algorithm in deghosting, clustering, charge solving etc. have to be developed

Active detector if three live wires are required prior to tiling



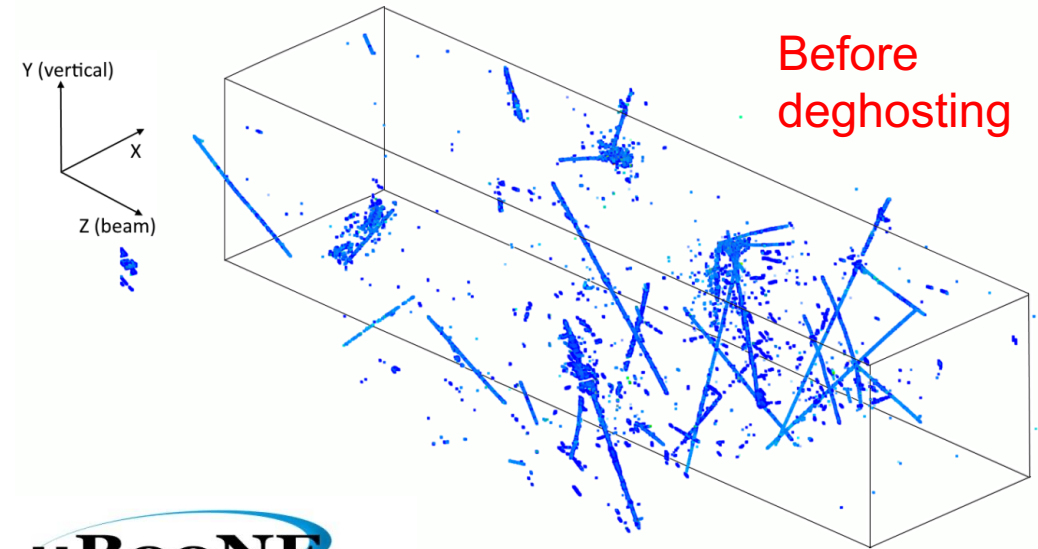
30% dead volume

Active detector if two live wires are required to tile

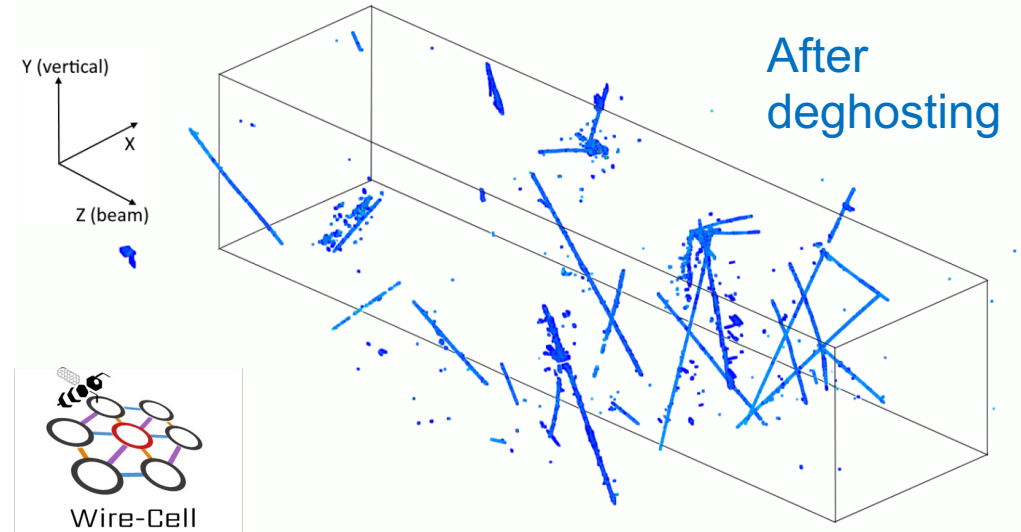


3% dead volume

MicroBooNE



JINST 16, P06043



Human to machine

- We learned that some tasks in the chain fit better for conventional alg. while some others fit better for ML alg.
- I believe combining both would give us the best performance with limited data and computing resources

