

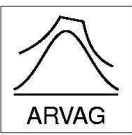
UNU.RAN

A library for Universal Non-Uniform RANdom variate generators

Concepts and Implementation

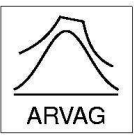
Josef Leydold (WU Wien), Wolfgang Hörmann (BU Istanbul)

Lorenzo Moneta (CERN)



Learning Objectives

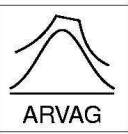
- Some remarks on uniform random numbers
- General Principles:
Inversion, Rejection, and Composition
- Special Algorithms vs. Universal Methods
- Random Vectors
- Implementation: UNU.RAN



Non-Uniform Random Variate Generation

Purpose:

Generate a sequence X_i of IID random variates with given distribution.



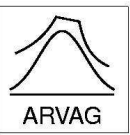
Non-Uniform Random Variate Generation

Purpose:

Generate a sequence X_i of IID random variates with given distribution.

Independent and **I**dentically **D**istributed

Independence can be dropped for some applications (MCMC).



Non-Uniform Random Variate Generation

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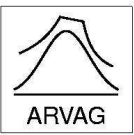
Generate a sequence X_i of IID random variates with given distribution.

Solution:

Transform sequence U_i of IID $U(0, 1)$ random numbers into sequence X_i .

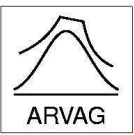
$$U_1, U_2, U_3, U_4, \dots \longrightarrow X_1, X_2, X_3, \dots$$

This transformation needs not to be one-to-one.



Assumptions

- Have a source of **perfect** (truely) uniform random numbers.
- Real numbers.



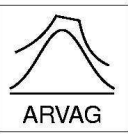
Assumptions

- Have a source of **perfect** (truly) uniform random numbers.

Not possible in practice!

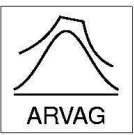
- Real numbers.

Computer uses **Floating Point Arithmetic!**

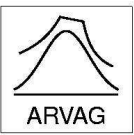


Uniform Random Numbers Generators

- Pseudo-random numbers.
Physical devices are slow, simulations not reproducible.
- Have restricted resolution.
Typically 10^{-9} .
- Always use generators designed by experts.
No self-made combined generators!
- Test generator, if possible.
Use a test similar to application.
E.g. TestU01 (L'Ecuyer), DIEHARD (Marsaglia),
NIST test-suite.
- PRNG in libraries usually not state-of-the-art.
Never use standard libraries for serious computations
(e.g. Visual Basic).

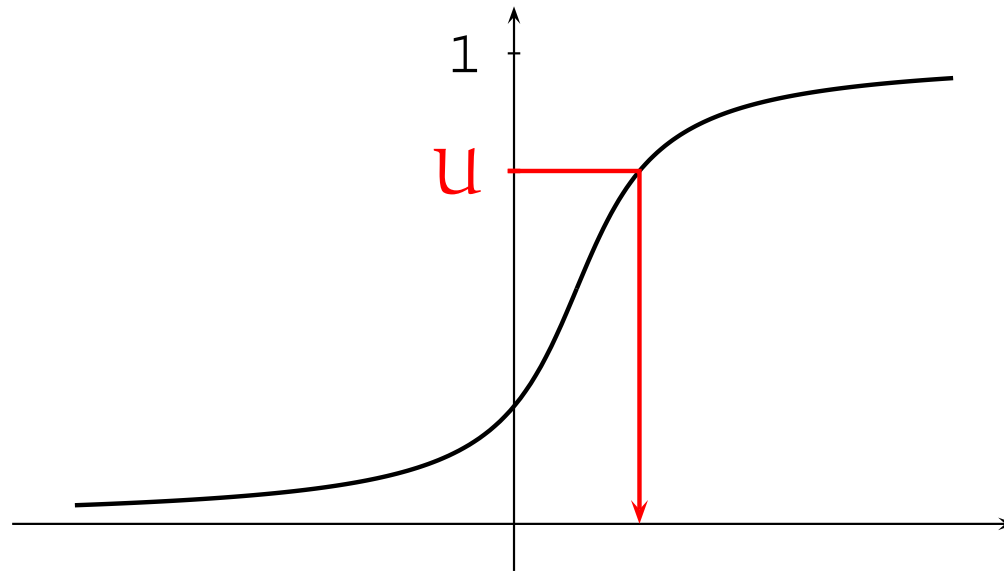


General Principles: Inversion, Rejection, and Composition



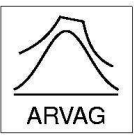
Inversion Method

Required: (Inverse of) **CDF** F of Distribution.



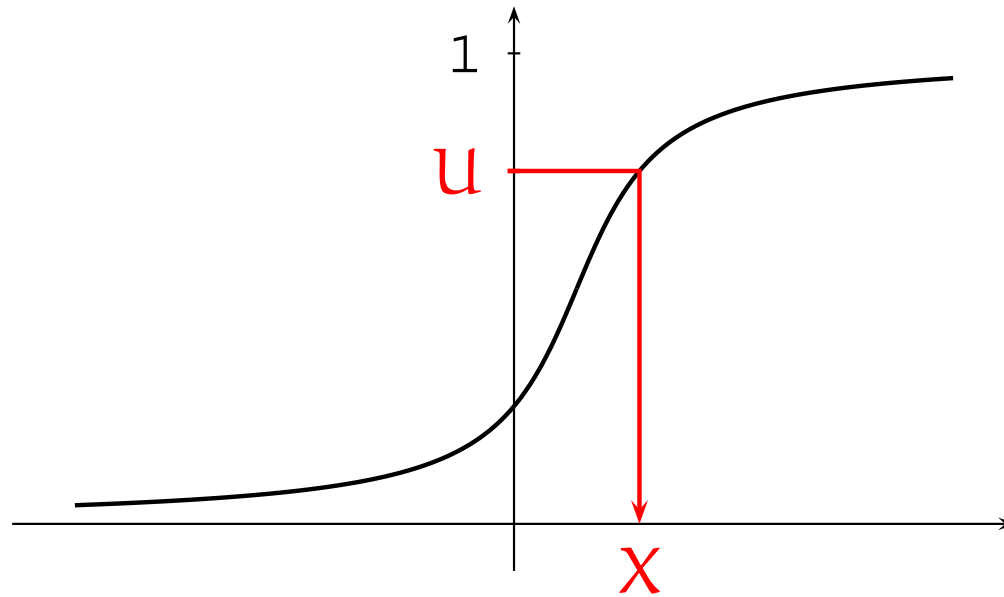
$$U \sim U(0, 1) \longrightarrow X = F^{-1}(U)$$

Exponential distribution: $F^{-1}(u) = -\log(1 - u)$

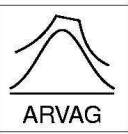


Inversion Method

Required: (Inverse of) **CDF** F of Distribution.



$$U \sim U(0, 1) \longrightarrow X = F^{-1}(U) \Leftarrow \text{Problem (?)}$$

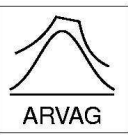


Inversion Method // Properties

- The most **general** method for generating non-uniform random variates.
Works for all distributions provided that the inverse CDF is given.
- Get **one** random variate X for each uniform U .
- **Preserves** the structural properties of the underlying uniform PRNG.

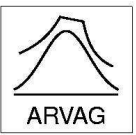
However:

- CDF and its inverse often not given in closed form.
- Need slow and/or **approximate** numerical methods.

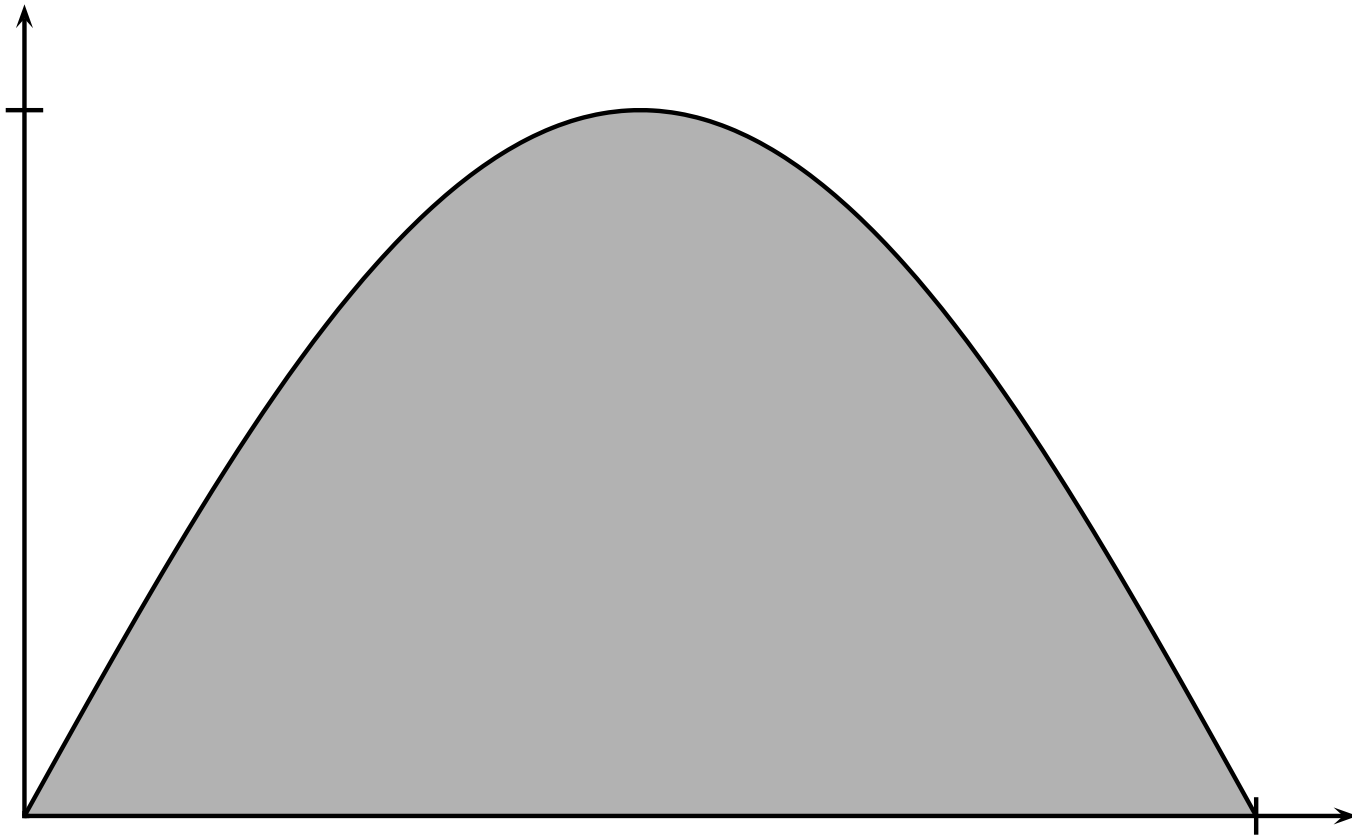


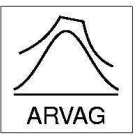
Inversion Method // Application

- Sampling from **truncated** distributions.
- Can be used for **variance reduction** techniques.
(common / antithetic variates, stratified sampling, ...)
- **Quality** of generated random numbers depends only on the underlying uniform PRNG, not on distribution.
- Applicable for **copula** methods and in the framework of **Quasi-Monte Carlo** methods (HUPS).

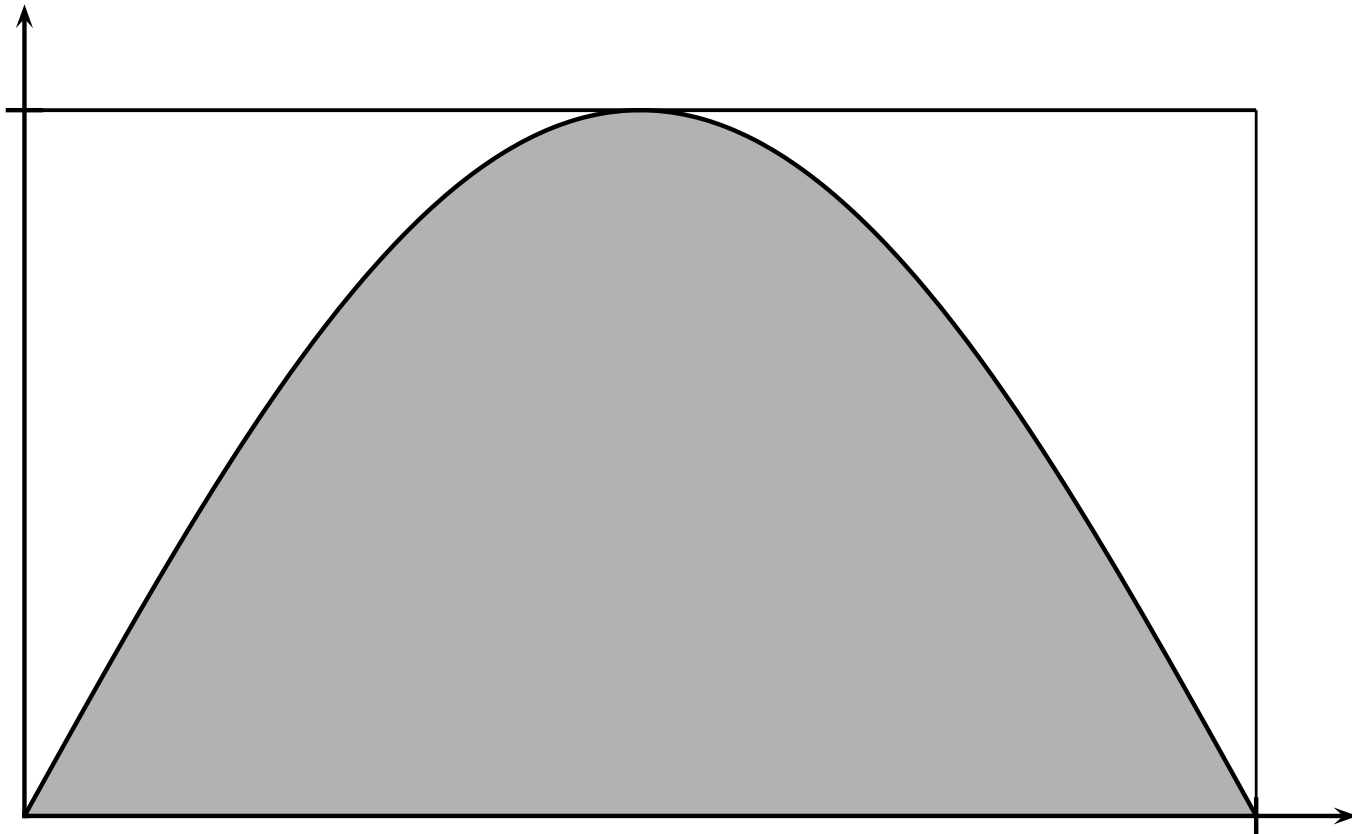


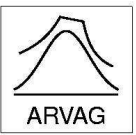
Rejection Method // Idea



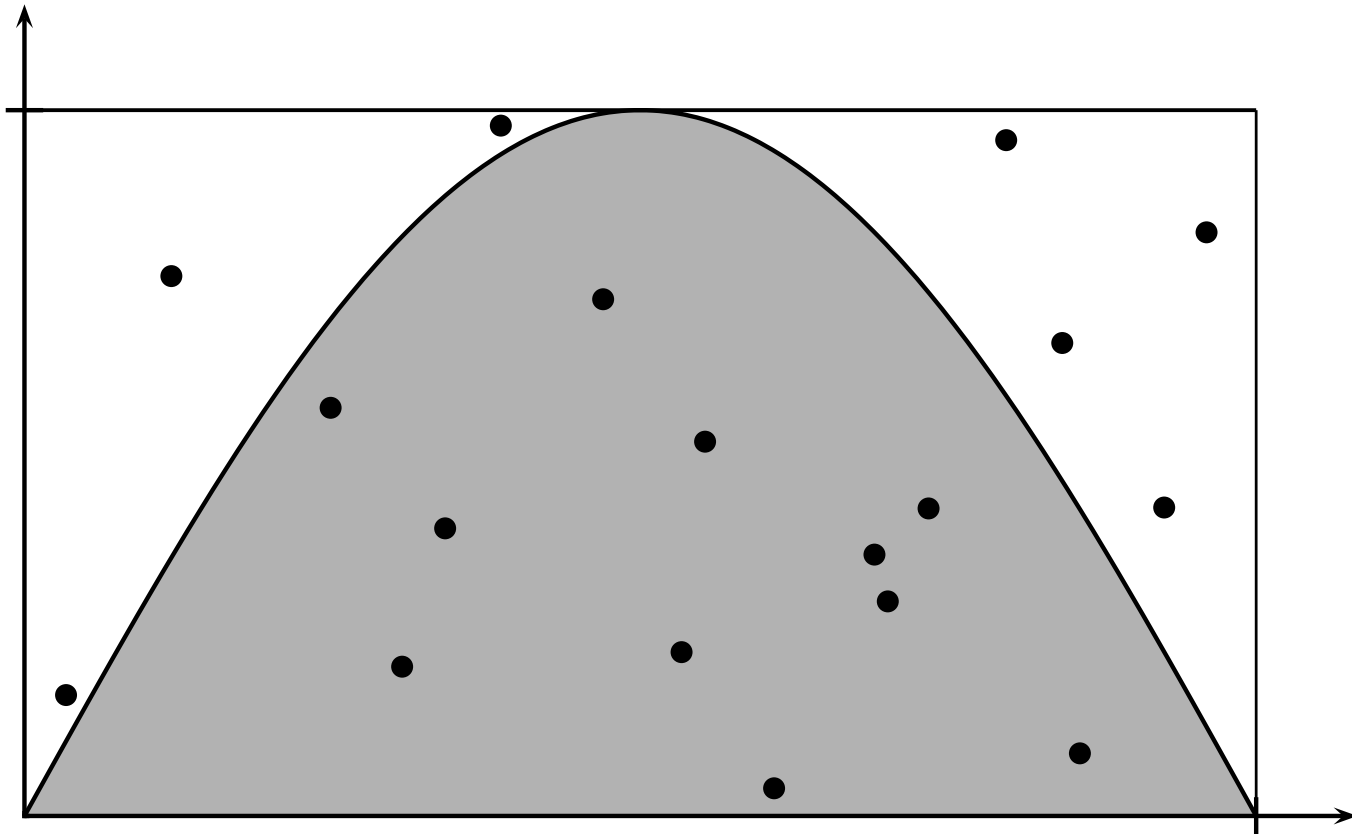


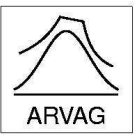
Rejection Method // Idea



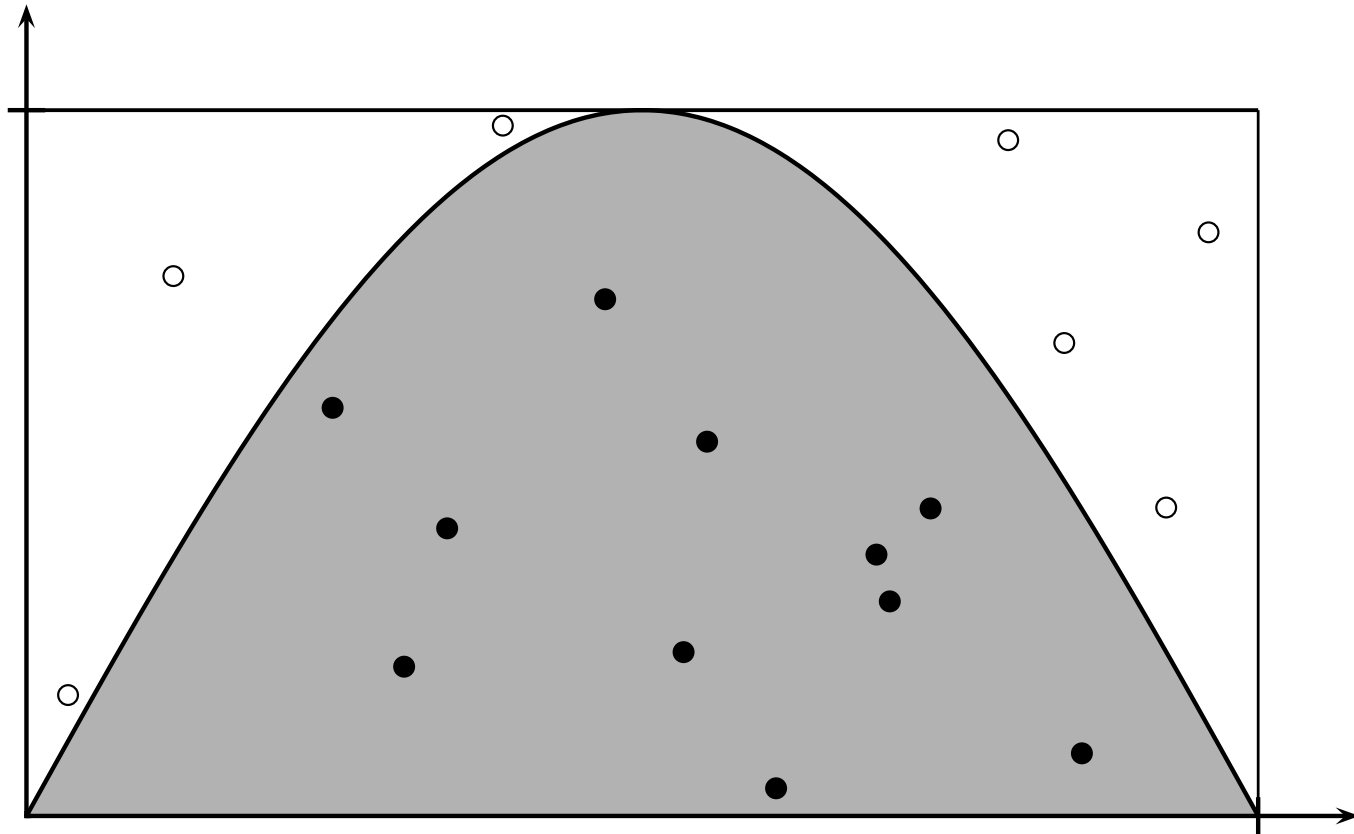


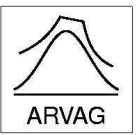
Rejection Method // Idea



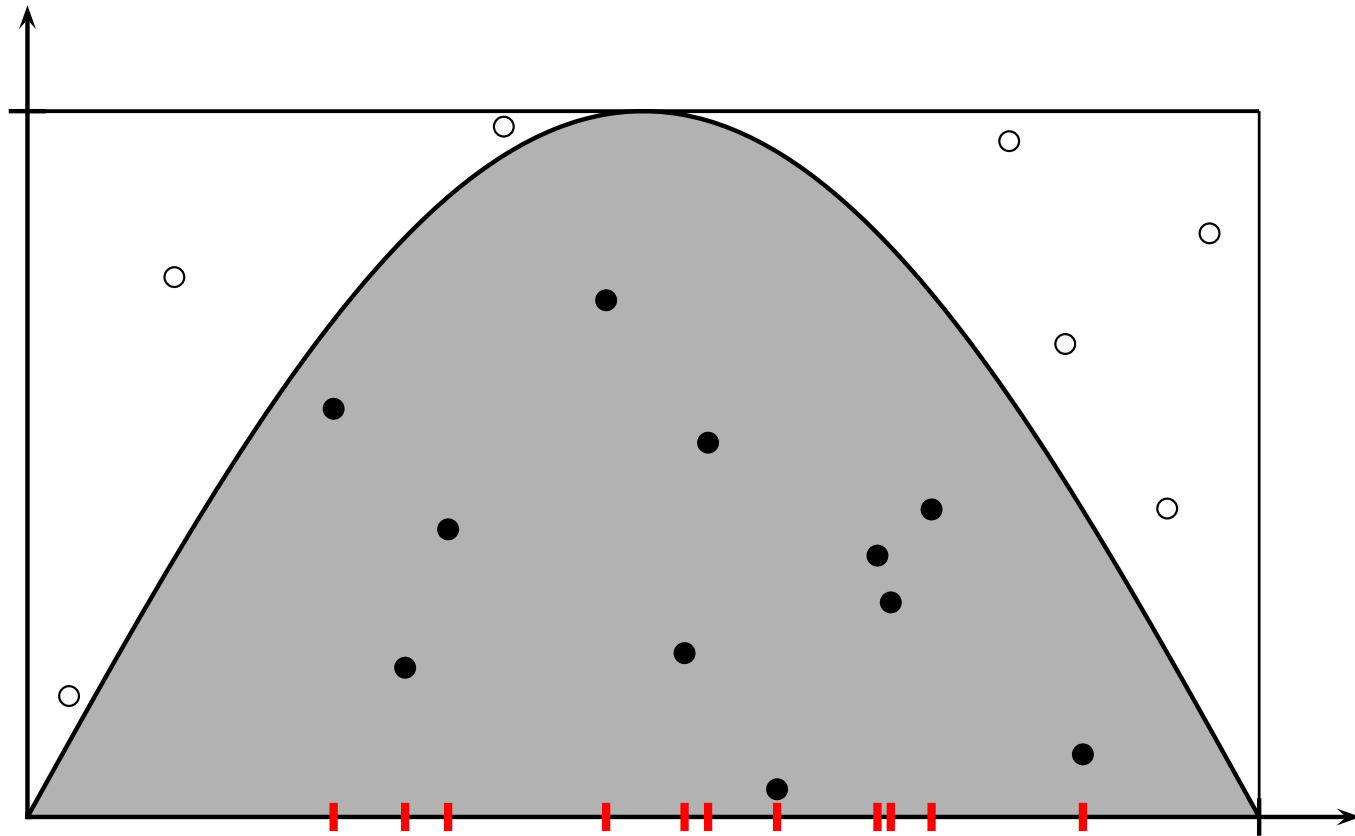


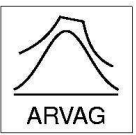
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Rejection Method // Idea

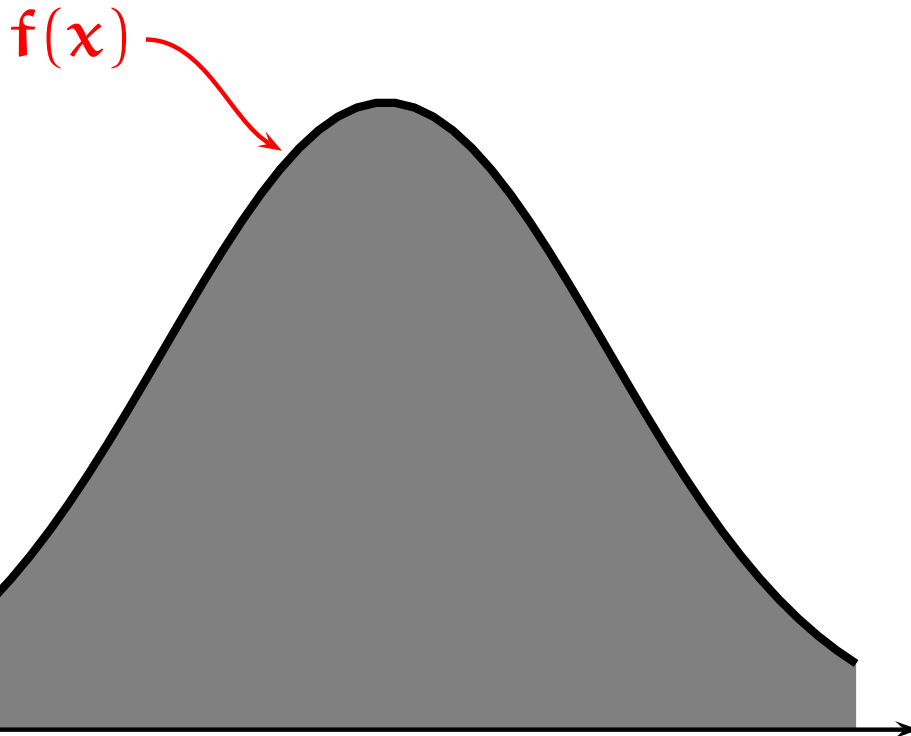


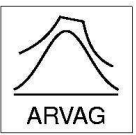


Rejection Method

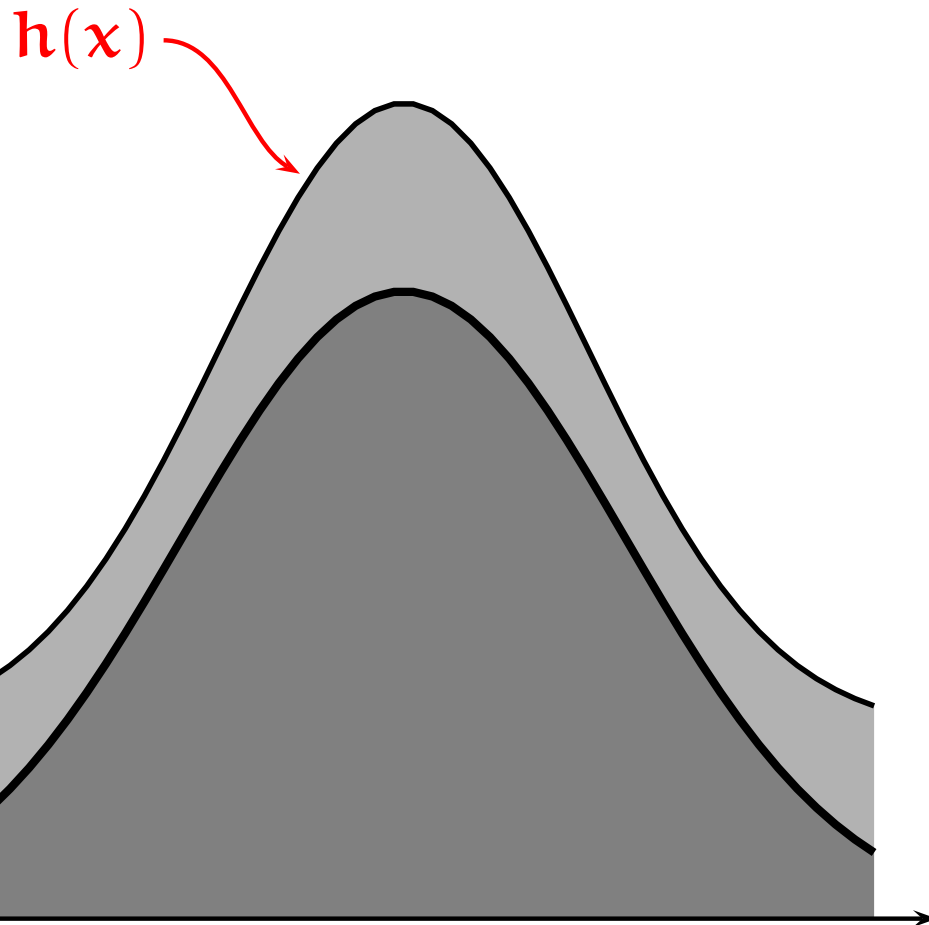
Required:

- density $f(x)$



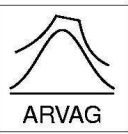


Rejection Method

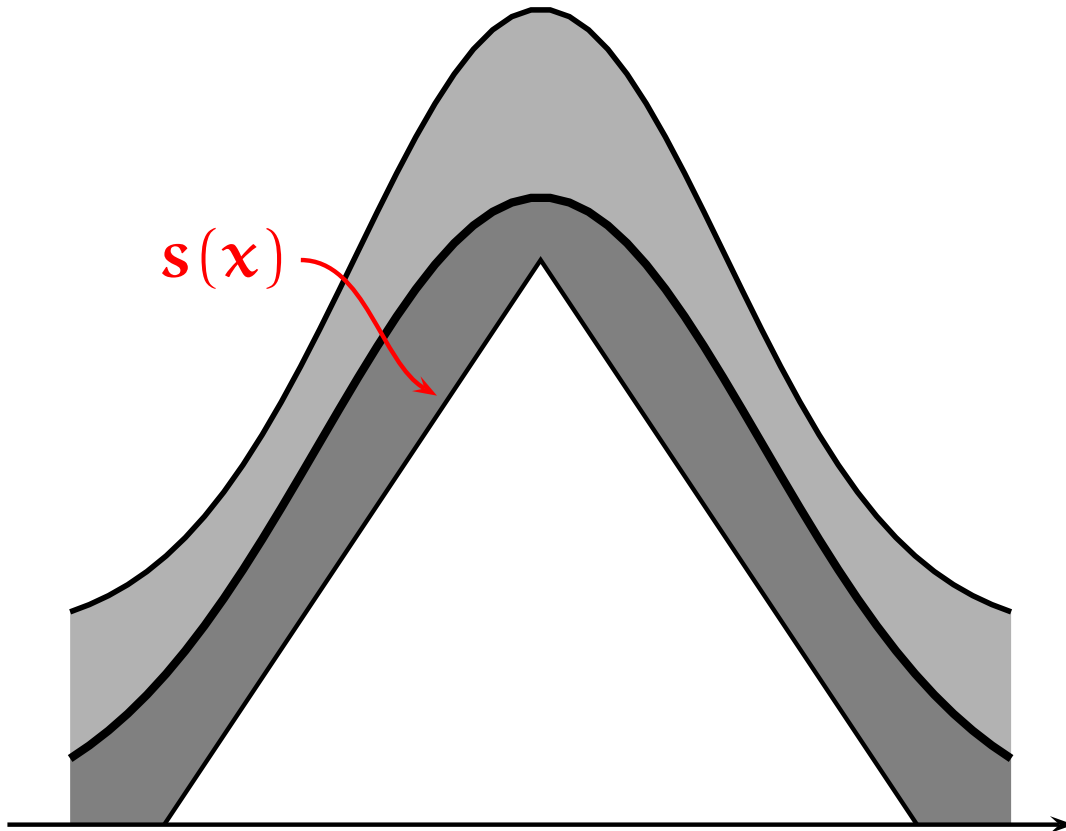


Required:

- density $f(x)$
- $\hat{h}(x) \geq f(x)$



Rejection Method

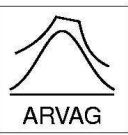


Required:

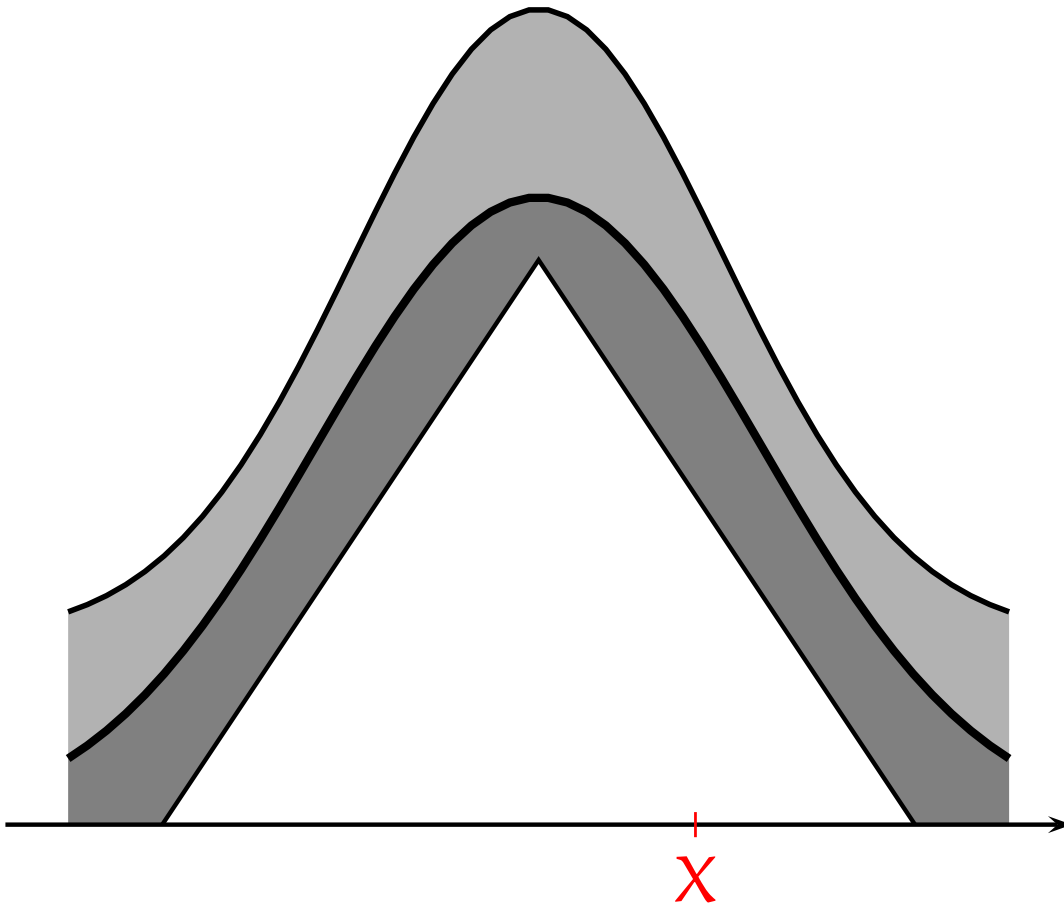
- density $f(x)$
- $\hat{h}(x) \geq f(x)$

Optional:

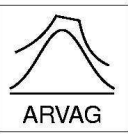
- squeeze $s(x) \leq f(x)$



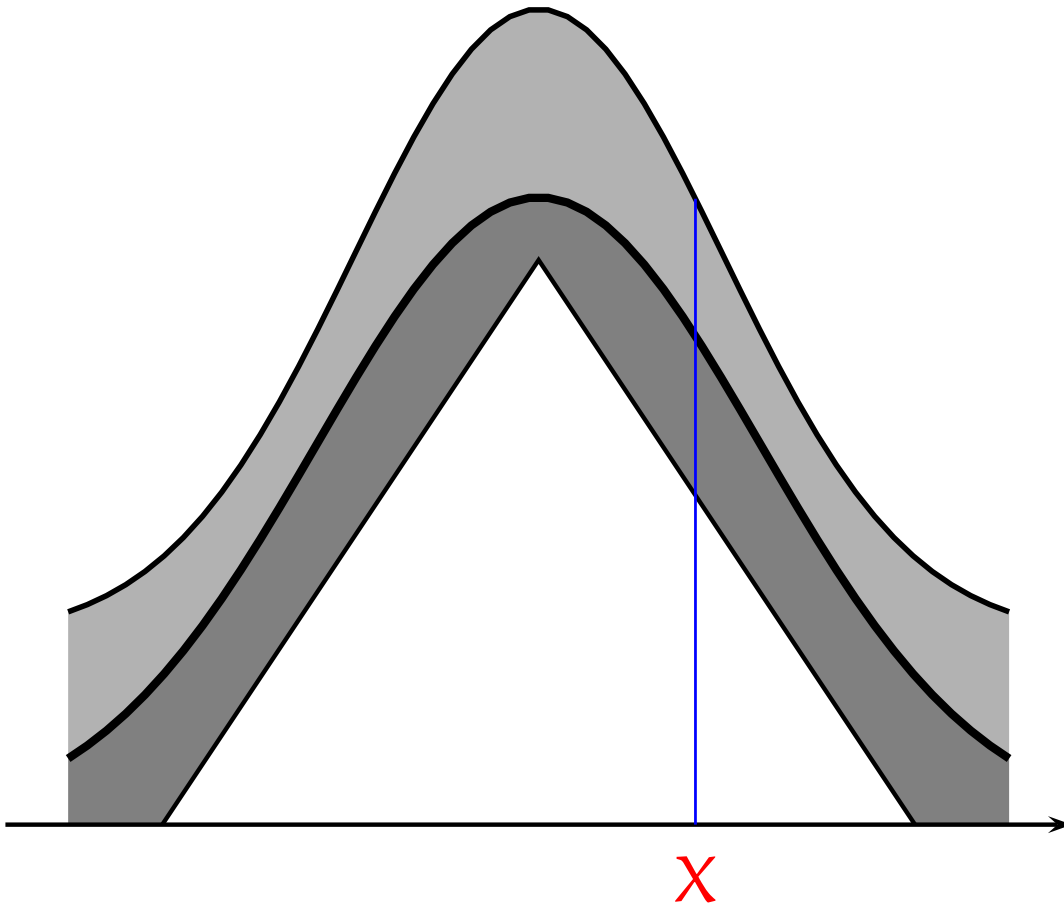
Rejection Method // Algorithm



- Generate $X \sim \text{hat}$.
Generate $U \sim U(0, 1)$.
If $U \cdot h(X) \leq s(X)$,
Return X .
If $U \cdot h(X) \leq f(X)$,
Return X .
Else try again.



Rejection Method // Algorithm



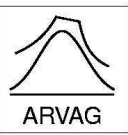
Generate $X \sim \text{hat}$.

● Generate $U \sim U(0, 1)$.

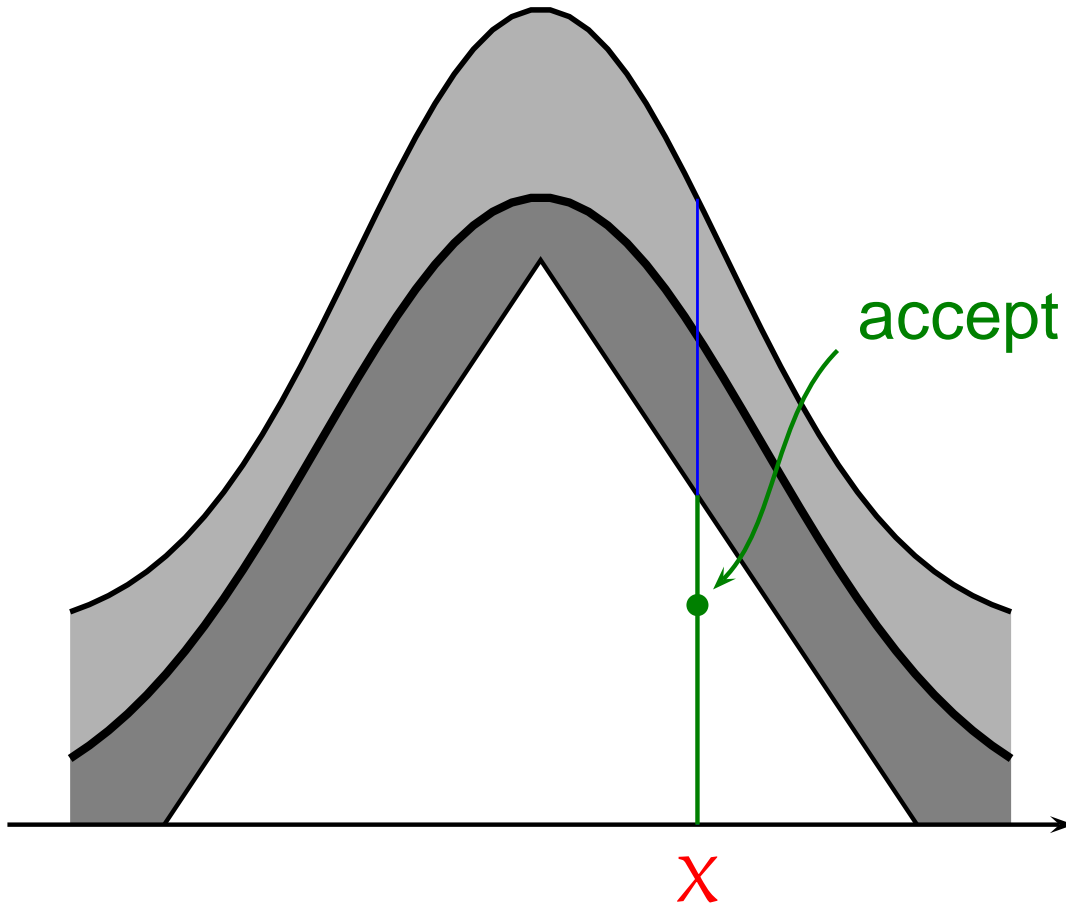
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Rejection Method // Algorithm



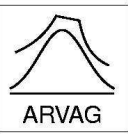
Generate $X \sim \hat{h}$.

Generate $U \sim U(0, 1)$.

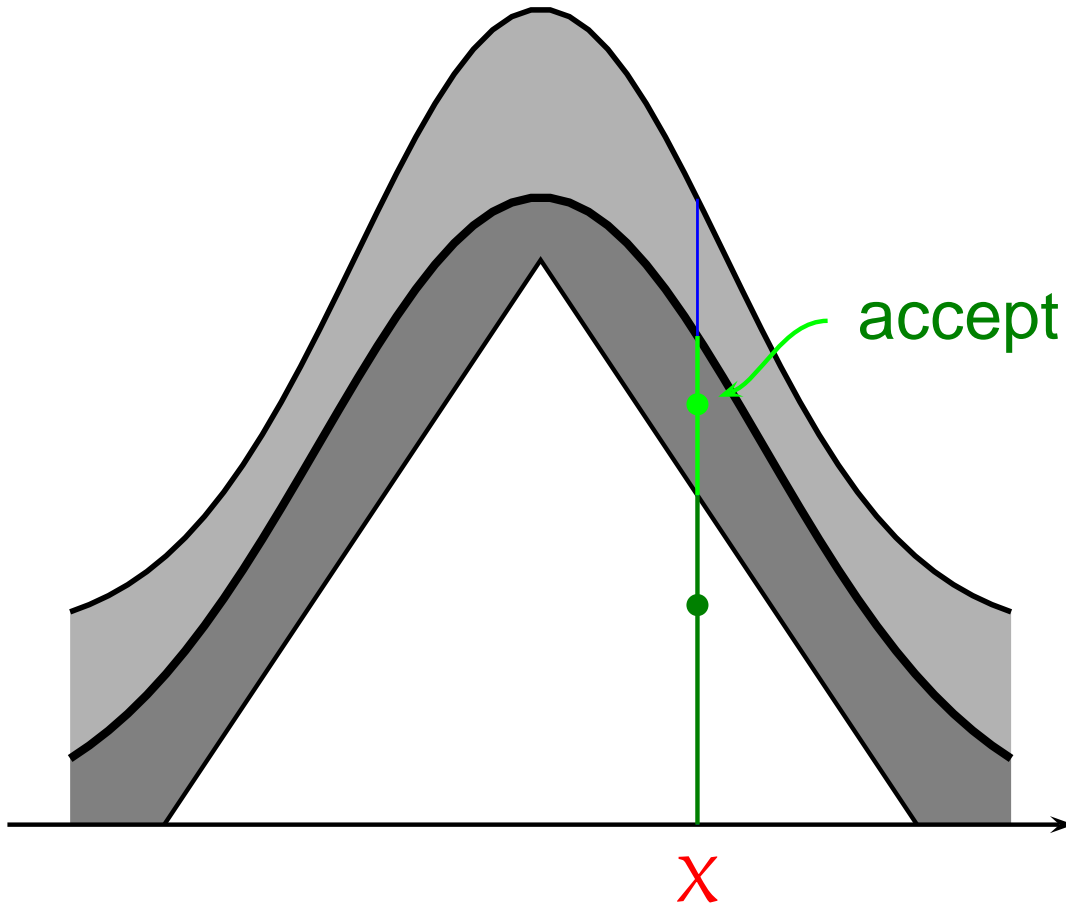
• If $U \cdot h(X) \leq s(X)$,
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Rejection Method // Algorithm



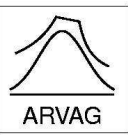
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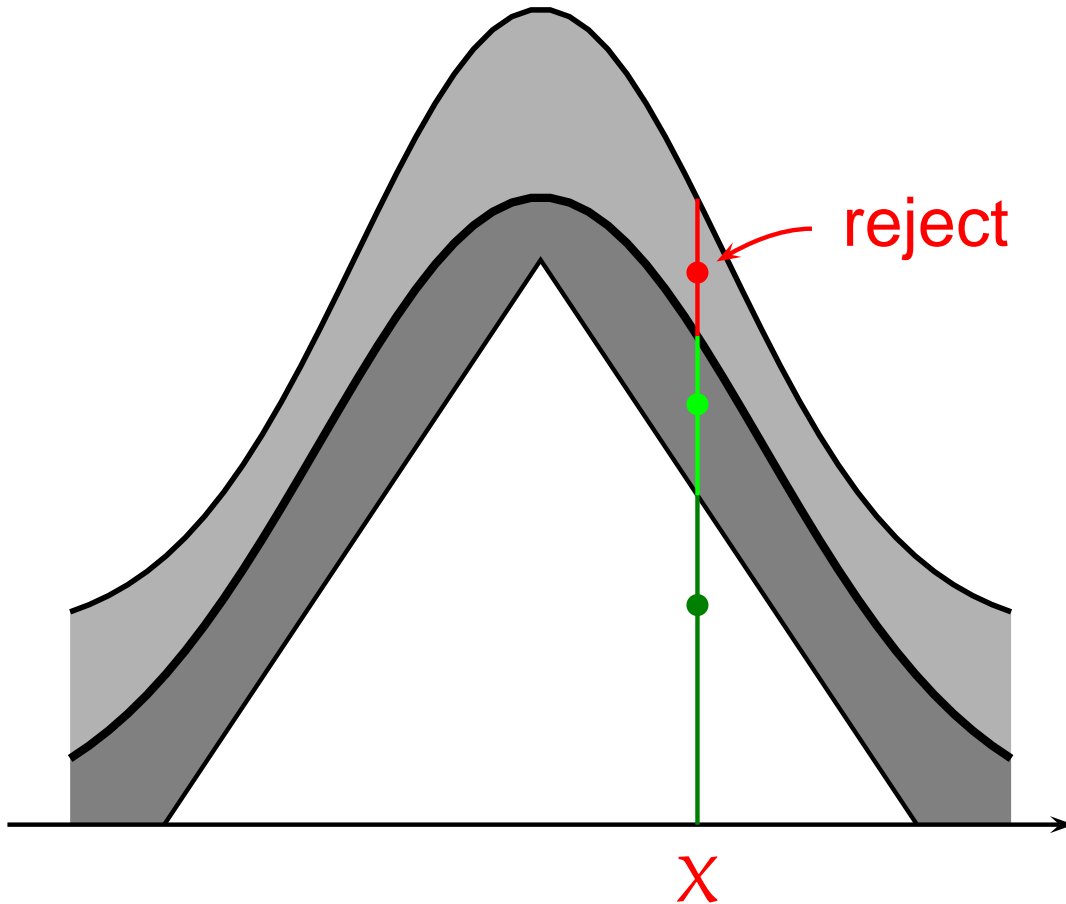
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Rejection Method // Algorithm



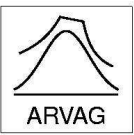
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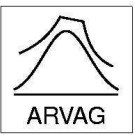
● Else try again.



Rejection Constant

$$\alpha = \frac{\int h(x) dx}{\int f(x) dx} = \frac{\text{area below hat}}{\text{area below density}}$$

is called the **rejection constant** and gives the expected number of iterations to get one random variate.



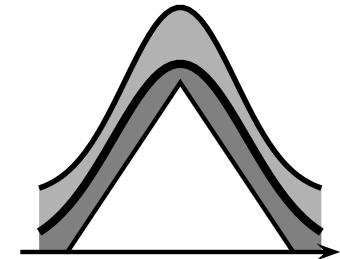
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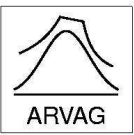
is called the **rejection constant** and gives the expected number of iterations to get one random variate.

In practice more useful:

$$\rho = \frac{\int h(x) dx}{\int s(x) dx} = \frac{\text{area below hat}}{\text{area below squeeze}}$$

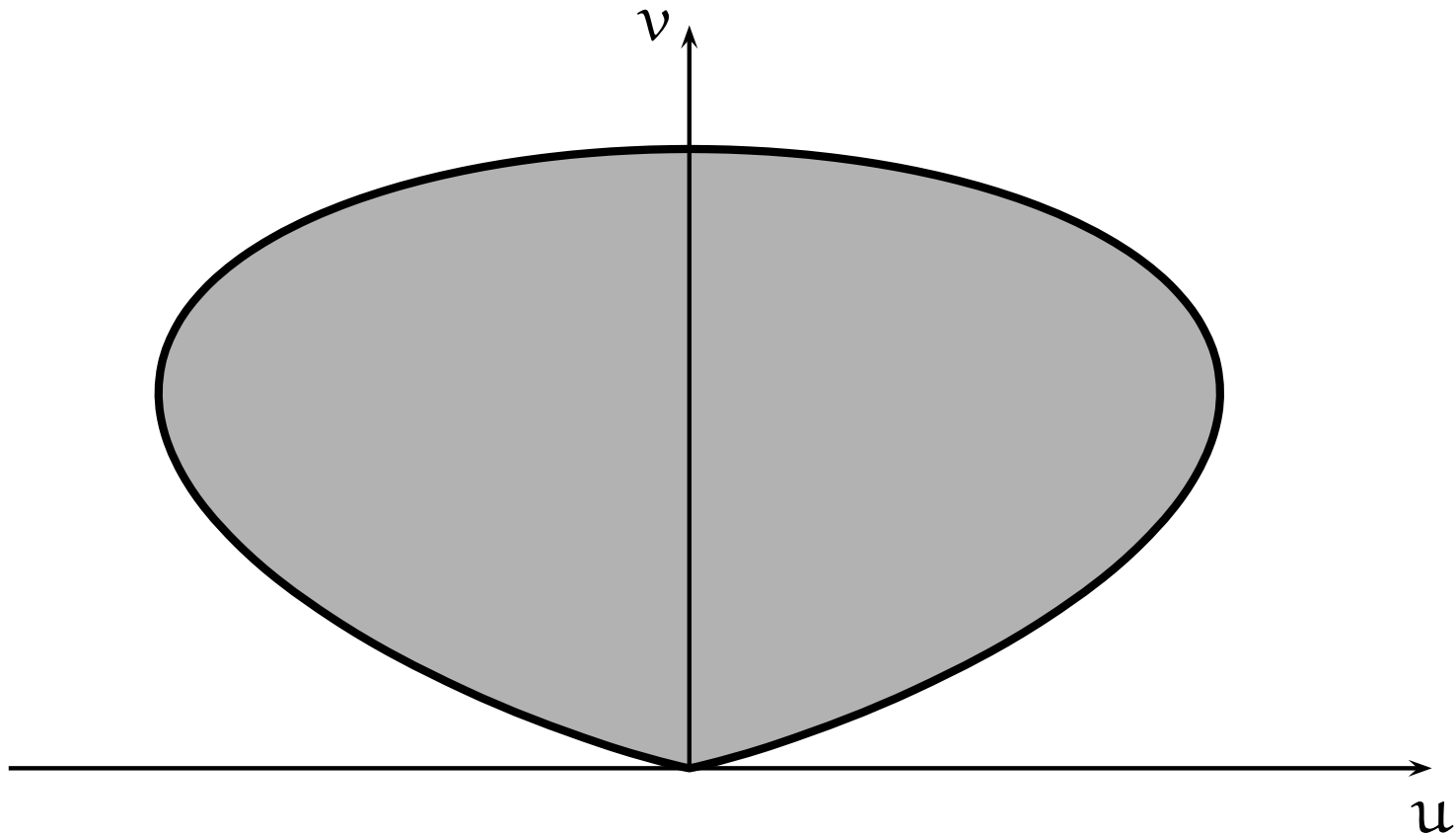


Notice that f need not integrate to 1 and $\int f$ need not be known.

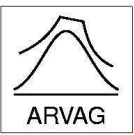


Ratio-of-Uniforms

Transform acceptance region: $(x, y) \mapsto (u, v) = (x\sqrt{y}, \sqrt{y})$



Normal distribution



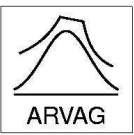
Composition Method

Required: Composition $f(x) = \sum p_i f_i(x)$

- Generate random variate $J \in \mathbb{Z}$ with prob. vector (p_i) .

Generate random variate X with density f_J .

Return X .



Composition Method

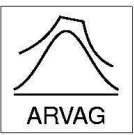
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Can be done in constant time (independent of N) by means of *Indexed Search* (Chen and Asau, 1974).



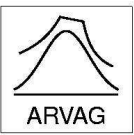
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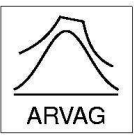
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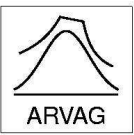
● Return X .



Special Algorithms

vs.

Universal Methods

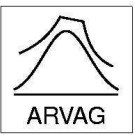


Algorithms for Particular Distributions

Goal for design:

- **fast** generator and/or
- **simple** code and/or
- little storage requirements
- **Structural** properties are hardly investigated.
(In opposition to uniform random number generators.)
- Expert required for making generator for new distribution.

Vast literature on generation methods for standard distributions; eg. Book: Devroye (1986),



Universal Methods

Universal algorithms have been developed for non-standard distributions.

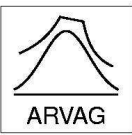
Also called **black-box** or **automatic** methods.

Idea:

One algorithm works for a large class of distributions.

Today these algorithms have properties that makes them also attractive for generating from standard distributions. Even for sampling from Gaussian distributions.

E.g., their structural properties are known.



Universal Methods // Design Goals

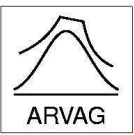
Need a procedure that adjusts **parameters** of universal algorithm to the given distribution.

Obvious **costs**:

- Higher storage requirements, /or
- Expensive setup, /or
- Slower marginal generation times.

Modern algorithms give the freedom of **choice**.

- **Control** over structural properties of generated random variates.



Two Examples

We make a glimpse at two such algorithms:

(TDR)

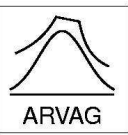
Transformed density rejection.

Gilks and Wild (1992), and Hörmann (1995)

(HINV)

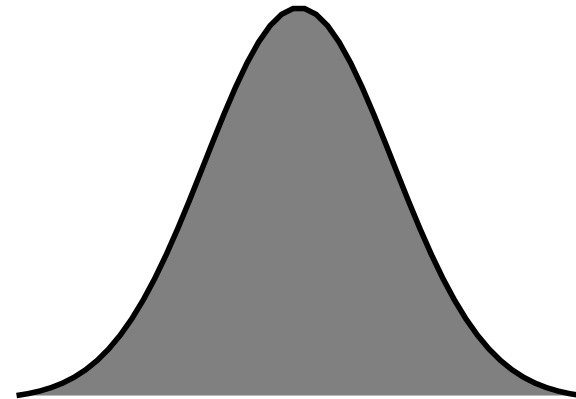
A numerical *inversion* method using Hermite interpolation. (Hörmann and Leydold, 2003)

All respective constants for hat, squeeze or interpolating polynome are computed automatically.

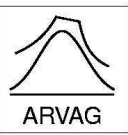


Transformed Density Rejection

Gaussian distribution, $T(x) = \log(x)$

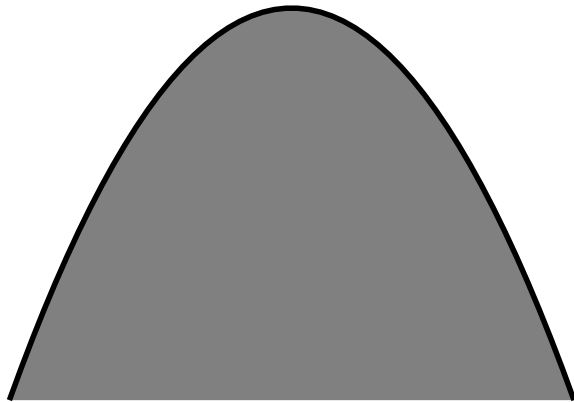


Density with hat and squeeze



Transformed Density Rejection

Gaussian distribution, $T(x) = \log(x)$

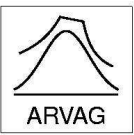


Transformed density



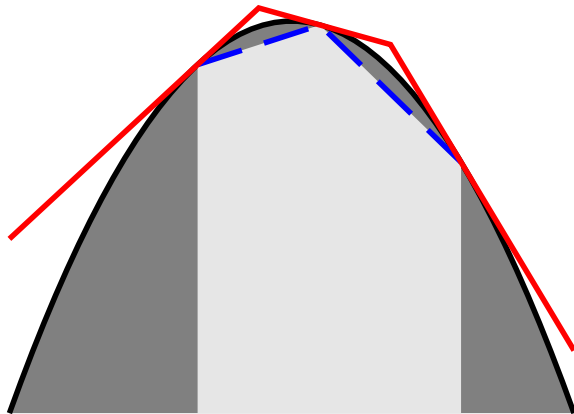
Density with hat and squeeze

Find a monotone differentiable transformation T , such that the transformed density $T(f(x))$ is concave.

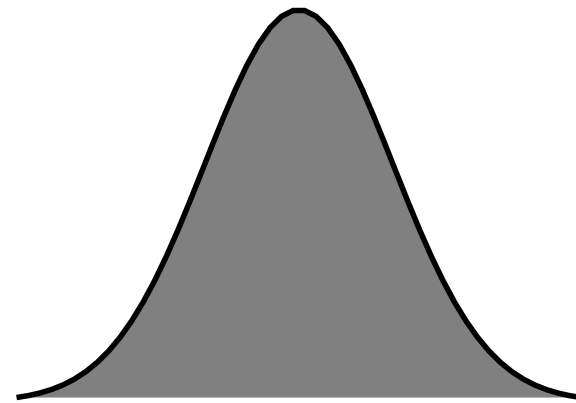


Transformed Density Rejection

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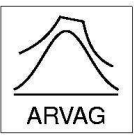


Transformed density



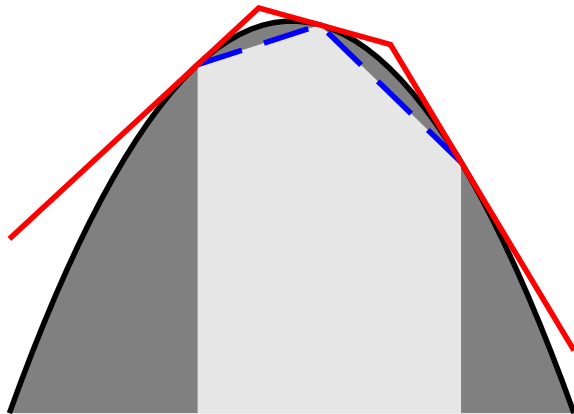
Density with hat and squeeze

Use tangents and secants to construct hat and squeeze for the transformed density.

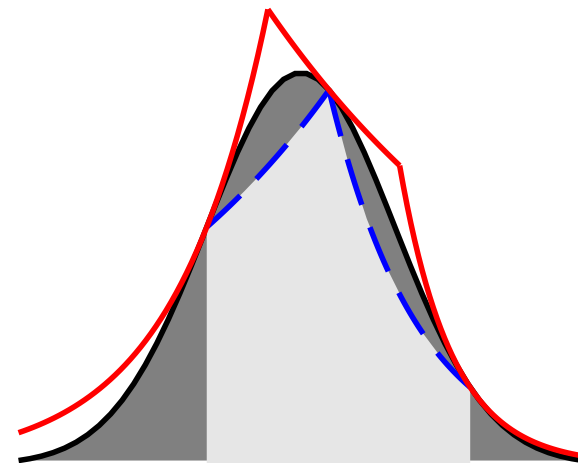


Transformed Density Rejection

Gaussian distribution, $T(x) = \log(x)$

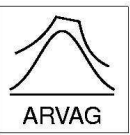


Transformed density



Density with hat and squeeze

By transforming back into the original scale using T^{-1} we get hat $h(x)$ and squeeze $s(x)$ for the density.



Hermite Interpolation

Idea:

Approximate function $g(x)$ on some interval $[b_0, b_1]$ by polynomial $h(x)$ of order $2n + 1$ such that

$$g^{(k)}(b_i) = h^{(k)}(b_i) \quad \text{for } k = 0, \dots, n \text{ and } i = 0, 1$$

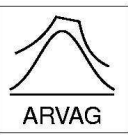
Approximation error is $O(\|g^{2n+2}(x)\|_\infty \cdot (b_1 - b_0)^{2k+2})$.

Consequently, we can make approximation error as small as desired by splitting interval in shorter subintervals.

$n = 0 \rightarrow$ linear interpolation

$n = 1 \rightarrow$ cubic interpolation

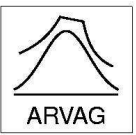
$n = 2 \rightarrow$ quintic interpolation



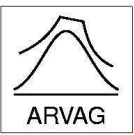
A First Conclusion

The given algorithms have advantages which make their usage attractive even for standard distributions.

- Only one piece of code.
- Performance controlled by a simple parameter.
- Sampling from truncated distributions.
- The marginal generation time does not depend on the density.
- They can be used for variance reduction techniques.
- The quality of the generated random numbers only depends on the underlying uniform random number generator.



Random Vectors



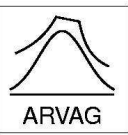
Random Vector Generation

Exact methods

- Conditional distribution method (Generalized inversion)
- Rejection Method

Markov chain sampler

- Metropolis-Hastings algorithm
- Gibbs sampler, Hit-and-Run sampler
- HITRO algorithm



Multivariate Rejection Method

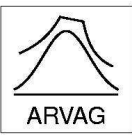
Rejection principle exactly the same as for univariate distributions.

Problems:

- Construction of hat functions much more difficult.
- Curse of Dimensionality: Acceptance probability deteriorates quickly with dimension.

Example: Rejection from hypercube to generate uniform vectors in a ball:

| | | | | |
|-------------|-------|-------|--------|------------|
| dimension | 2 | 3 | 10 | 50 |
| probability | 0.785 | 0.524 | 0.0025 | 10^{-28} |



Markov Chain Sampler

Run a Markov chain whose stationary distribution is the required distribution.

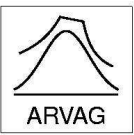
Advantages:

- Algorithms are much simpler.
- More generally applicable.

Disadvantages:

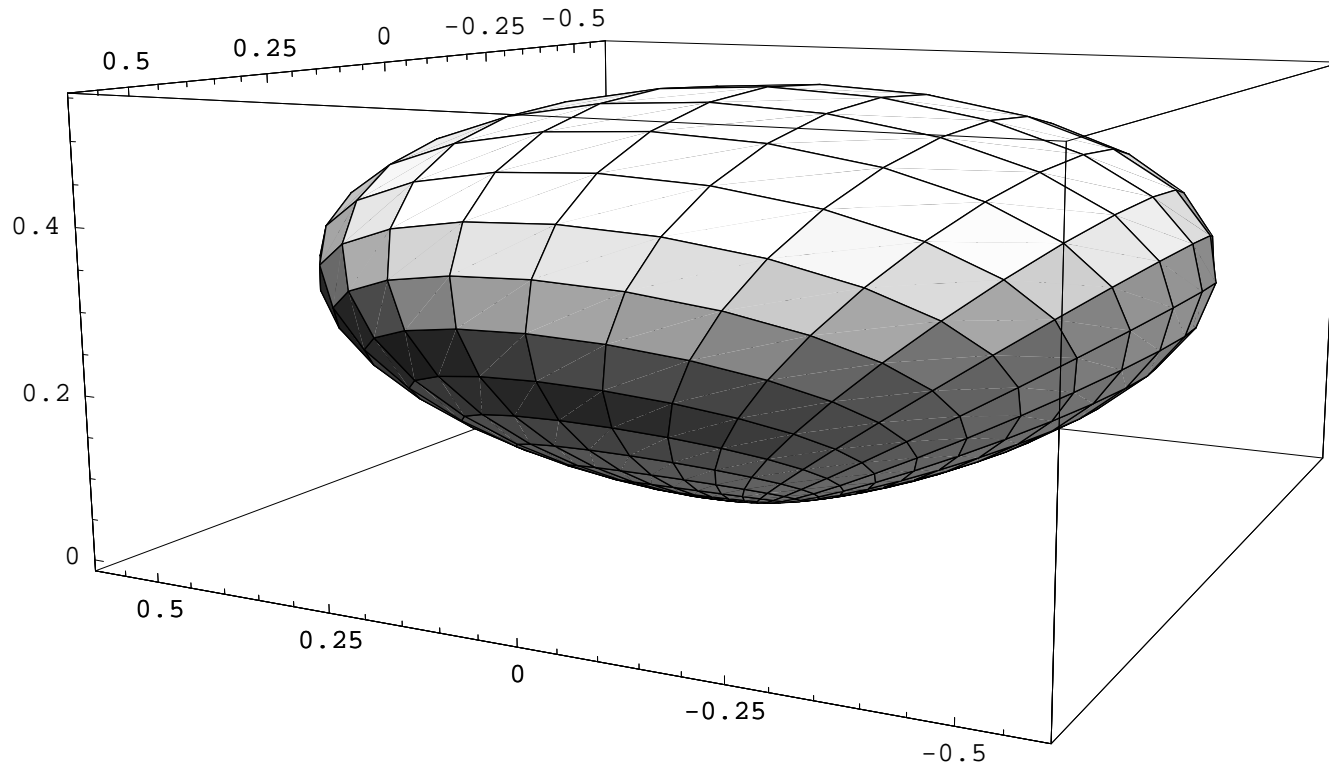
- No IID random vectors.
- Rate of convergence of the Markov chain is a problem.
Only heuristic rules for convergence exist.

“Optimistic Algorithm” (Hörmann)



HITRO

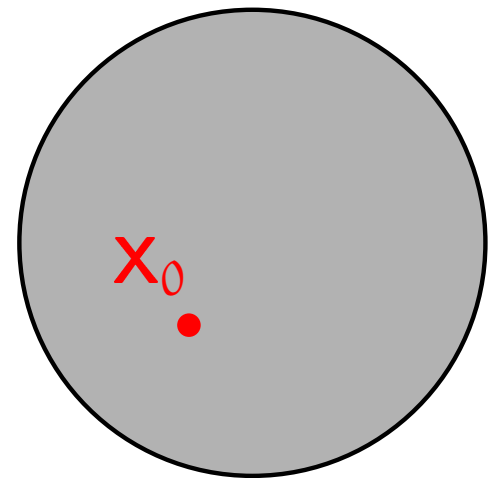
Combines the Hit-and-Run sampler with the multivariate Ratio-of-Uniforms method.



Hit-and-Run Sampler

Generate a sample of random points uniformly distributed in some fixed but arbitrary bounded open set S :

- Choose a starting point $\mathbf{X}_0 \in S$ and set $k = 0$.
 - Generate a random direction \mathbf{d}_k with distribution \mathcal{D} .
 - Generate λ_k uniformly distributed in $\Lambda_k = S \cap \{\mathbf{x} : \mathbf{x} = \mathbf{x}_k + \lambda \mathbf{d}_k\}$.
 - Set $\mathbf{X}_{k+1} = \mathbf{X}_k + \lambda_k \mathbf{d}_k$ and $k = k + 1$.
 - Repeat from Step 2

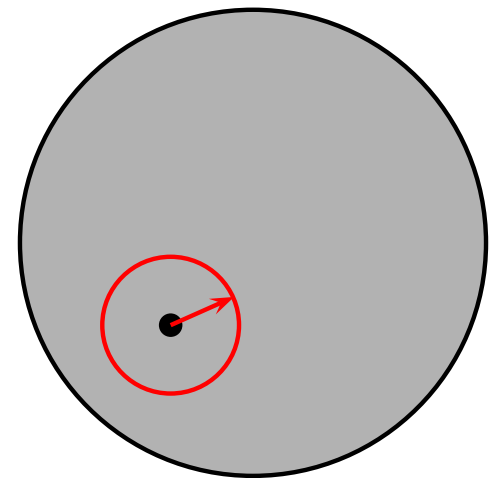


Smith (1984)

Hit-and-Run Sampler

Generate a sample of random points uniformly distributed in some fixed but arbitrary bounded open set S :

- Choose a starting point $\mathbf{X}_0 \in S$ and set $k = 0$.
- **Generate a random direction \mathbf{d}_k with distribution \mathcal{D} .**
- Generate λ_k uniformly distributed in $\Lambda_k = S \cap \{\mathbf{x} : \mathbf{x} = \mathbf{x}_k + \lambda \mathbf{d}_k\}$.
- Set $\mathbf{X}_{k+1} = \mathbf{X}_k + \lambda_k \mathbf{d}_k$ and $k = k + 1$.
- Repeat from Step 2

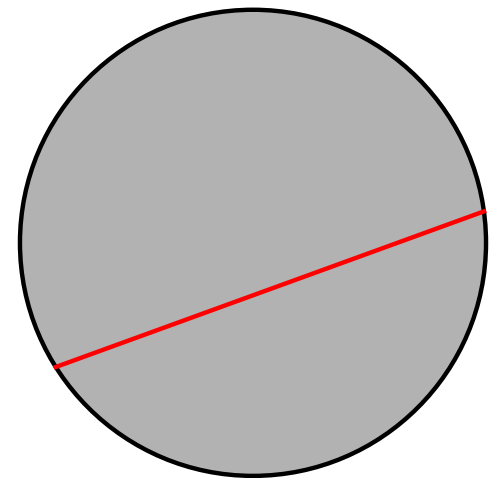


Smith (1984)

Hit-and-Run Sampler

Generate a sample of random points uniformly distributed in some fixed but arbitrary bounded open set S :

- Choose a starting point $\mathbf{X}_0 \in S$ and set $k = 0$.
- Generate a random direction \mathbf{d}_k with distribution \mathcal{D} .
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- Repeat from Step 2

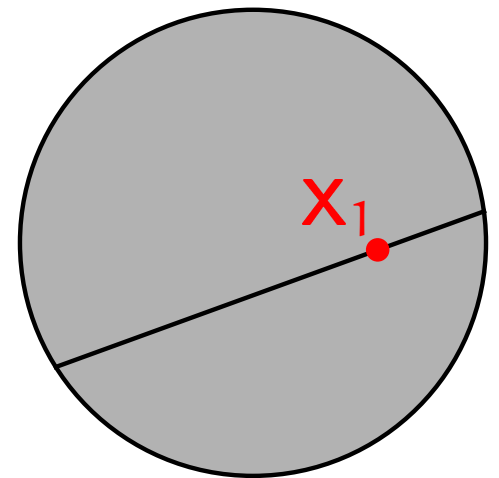


Smith (1984)

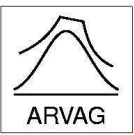
Hit-and-Run Sampler

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- Generate λ_k uniformly distributed in $\Lambda_k = S \cap \{\mathbf{x} : \mathbf{x} = \mathbf{x}_k + \lambda \mathbf{d}_k\}$.
- **Set $\mathbf{X}_{k+1} = \mathbf{X}_k + \lambda_k \mathbf{d}_k$ and $k = k + 1$.**
- Repeat from Step 2



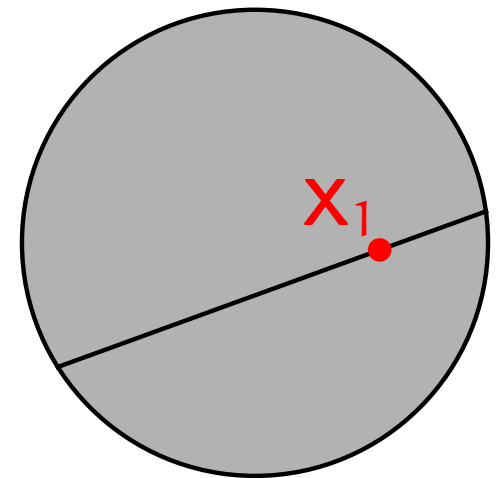
Smith (1984)



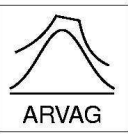
Hit-and-Run Sampler

Generate a sample of random points uniformly distributed in some fixed but arbitrary bounded open set S :

- Choose a starting point $\mathbf{X}_0 \in S$ and set $k = 0$.
- Generate a random direction \mathbf{d}_k with distribution \mathcal{D} .
- Generate λ_k uniformly distributed in $\Lambda_k = S \cap \{\mathbf{x} : \mathbf{x} = \mathbf{x}_k + \lambda \mathbf{d}_k\}$.
- Set $\mathbf{X}_{k+1} = \mathbf{X}_k + \lambda_k \mathbf{d}_k$ and $k = k + 1$.
- Repeat from Step 2



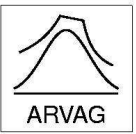
Smith (1984)



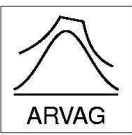
HITRO // Properties

The HITRO (Hit-and-run-Ratio-of-Uniforms) sampler is

- simple;
- easy to implement;
- relatively fast;
- works for many (not necessarily unimodal) distributions out of the box;
- performs similar to the Gibbs sampler but does not need a special and/or expensive generator for conditional distributions.



Implementation: UNU.RAN



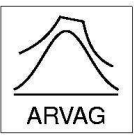
UNU.RAN

We have implemented these (and other) methods in a library, called UNU.RAN
(**U**niversal **N**on**U**niform **R**andom variate generators).

Features:

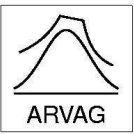
- ANSI C (portable).
- Object oriented programming paradigm.
- Open source.

Can be downloaded from
<http://statistik.wu-wien.ac.at/unuran/>



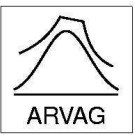
UNU.RAN // Design

- Create a **distribution** object.
- Set **data** for distribution: obligatory and optional data (depending on distribution type).
PDF, CDF, domain, mode, ...
- Choose a **sampling method**.
- Change default **parameters** for chosen method (if required).
- Initialize **generator** object.
- Draw a **sample**.



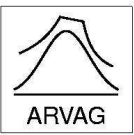
Random Variates for Standard Distributions

```
// The Gaussian random variate Generator is  
// method in class TRandom.  
x = gRandom->Gaus(0,1);  
  
// Mean (0) and sigma (1) are arguments.
```



Generation of Non-Standard Distributions

```
// Describe distribution by its density.  
// Use class TF1  
TF1 *f = new TF1("f", "(1-x)*exp(-x*x)", -10, 1);  
  
// Get a random number.  
x = f->GetRandom();  
  
// "Histogram method":  
// - Truncated domain  
// - Rough approximation of density
```



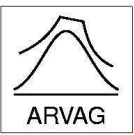
UNU.RAN

```
// Create UNU.RAN continuous distribution
TF1 *f = new TF1("f", "(1-x)*exp(-x*x)", -10, 1);
TUnuranContDist dist(f);
dist.SetDomain(-INFINITY, 1);

// Create UNU.RAN class
TUnuran unur;

// Initialize
retval = unur.Init(dist);
if (!retval) {...catch error ...}

// Get a random number
x = unur.Sample();
```



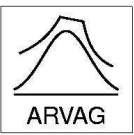
UNU.RAN

```
// Create UNU.RAN continuous distribution
TF1 *f = new TF1("f", "(1-x)*exp(-x*x)", -10, 1);
TUnuranContDist dist(f);
dist.SetDomain(-INFINITY, 1);

// Create UNU.RAN class
TUnuran unur;

// Initialize
retval = unur.Init(dist, "arou");
if (!retval) {...catch error ...}

// Get a random number
x = unur.Sample();
```



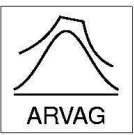
UNU.RAN

```
// Create UNU.RAN continuous distribution
TF1 *f = new TF1("f", "(1-x)*exp(-x*x)", -10, 1);
TUnuranContDist dist(f);
dist.SetDomain(-INFINITY, 1);

// Create UNU.RAN class
TUnuran unur;

// Initialize
retval = unur.Init(dist, "arou; usedars=on");
if (!retval) {...catch error ...}

// Get a random number
x = unur.Sample();
```

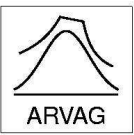
UNU.RAN

```
// Create UNU.RAN continuous distribution
TF1 *f = new TF1("f", "(1-x)*exp(-x*x)", -10, 1);
TUnuranContDist dist(f);
dist.SetDomain(-1, 1);

// Create UNU.RAN class
TUnuran unur;

// Initialize
retval = unur.Init(dist, "arou");
if (!retval) {...catch error ...}

// Get a random number
x = unur.Sample();
```

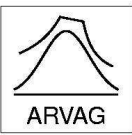


UNU.RAN

```
// Create UNU.RAN continuous distribution
TF1 *f = new TF1("f","(1-x)*exp(-x*x)",-10,1);
TUnuranContDist dist(f);
TF1 *fc = new TF1("fc",
    "0.49+0.28*exp(-x*x)+0.49*Erf(x)",-10,1);
dist.SetCdf(fc);
dist.SetDomain(-INFINITY,1);

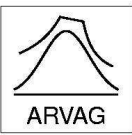
// Create UNU.RAN class and initialize
TUnuran unur;
retval = unur.Init(dist, "hinv");
if (!retval) {...catch error ...}

// Get a random number
x = unur.Sample();
```



Some Results with TRandom3

| Distribution | Method | Time (ns) |
|---------------|---------------|-----------|
| Uniform | Random | 30 |
| Exponential | Random | 170 |
| Gaussian | Random | 160 |
| Gaussian | TF1.GetRandom | 310 |
| Gaussian | UNU.RAN arou | 140 |
| Maxwell | UNU.RAN arou | 140 |
| Maxwell | UNU.RAN hinv | 190 |
| MNormal (2) | UNU.RAN hitro | 1750 |
| MNormal (5) | UNU.RAN hitro | 2150 |
| MNormal (10) | UNU.RAN hitro | 2820 |
| MNormal (100) | UNU.RAN hitro | 34790 |



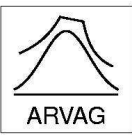
UNU.RAN

Manual:

<http://statmath.wu-wien.ac.at/unuran/>

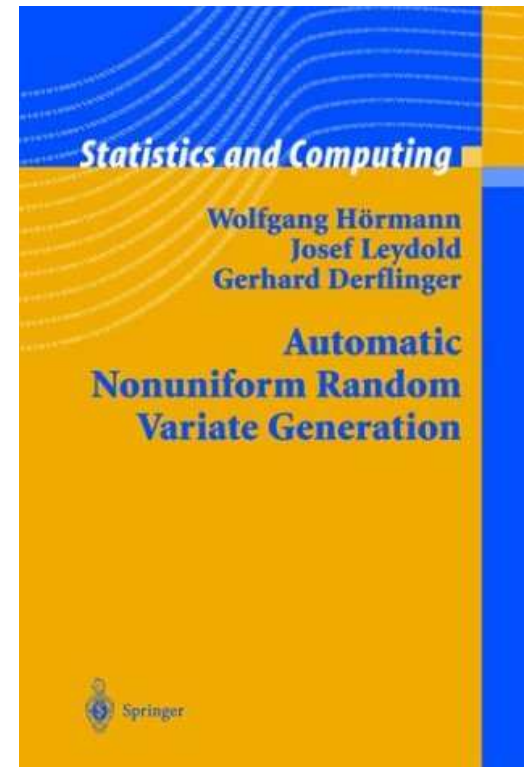
Request for help, Comments, Suggestions:

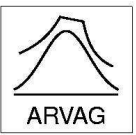
unuran@statmath.wu-wien.ac.at



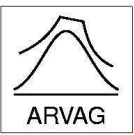
Further Reading

W. Hörmann, J. Leydold, and G. Derflinger
Automatic Nonuniform Random Variate Generation
2004, Springer, Berlin





Thank you



References

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Devroye, L. (1986). *Non-Uniform Random Variate Generation*. New-York: Springer-Verlag.

Gilks, W. R. and P. Wild (1992). Adaptive rejection sampling for Gibbs sampling. *Applied Statistics* 41(2), 337–348.

Hörmann, W. (1995). A rejection technique for sampling from T-concave distributions. *ACM Trans. Math. Software* 21(2), 182–193.

Hörmann, W. and J. Leydold (2003). Continuous random variate generation by fast numerical inversion. *ACM Trans. Model. Comput. Simul.* 13(4), 347–362.

Smith, R. L. (1984). Efficient Monte Carlo procedures for generating points uniformly distributed over bounded regions. *Operations Research* 32, 1296–1308.