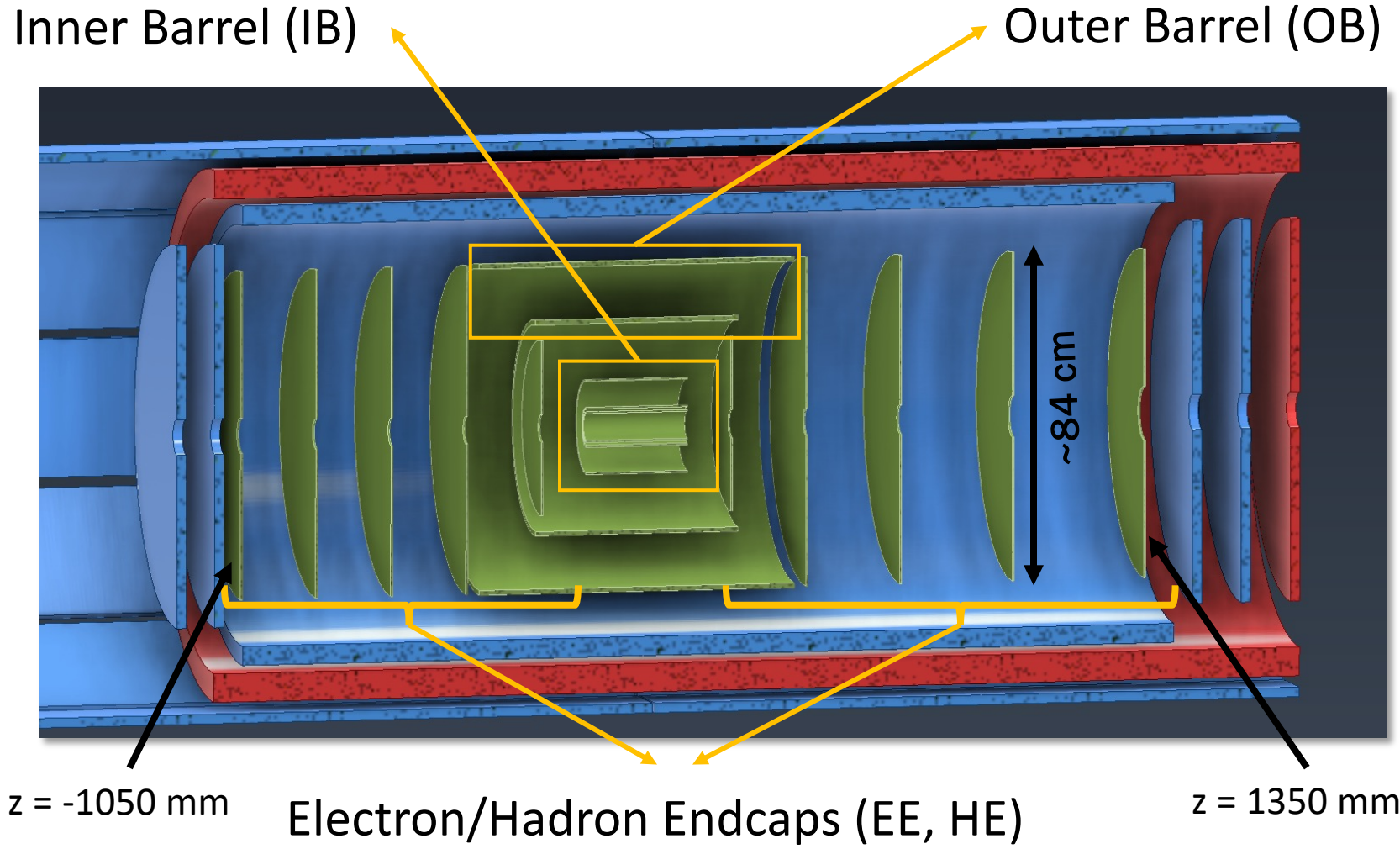
A 3D cutaway diagram of a corrugated carbon composite disc. The disc is shown in a perspective view, revealing its internal structure. It consists of multiple layers of material, with a central core and an outer shell. The core is a light blue color, and the shell is a reddish-brown color. The disc has a corrugated or ribbed appearance, with several vertical ridges or grooves running along its length. The text is overlaid on the central part of the disc.

Corrugated carbon composite disc design for the ePIC SVT

Nicole Apadula, Eric Anderssen, Jim Curtis, Ernst Sichtermann, Joe Silber
Lawrence Berkeley National Laboratory
Forum on Tracking Detector Mechanics

May 29, 2024

Silicon Vertex Tracker (SVT) Overview



Target Specifications

- IB
 - L0 - L2: 0.05% X/X_0
- OB
 - L3: 0.25% X/X_0
 - L4: 0.55% X/X_0
- Endcaps
 - ED0-4: 0.25% X/X_0
 - HD0-4: 0.25% X/X_0

Towards a disc design

- Double-sided design
 - Overlap to account for inactive areas on sensor (EIC-LAS)
- Needs to be assembled in halves
- Material budget is a concern
 - Want strength without added mass
- Minimal number of module types to simplify production/construction
- Sensor layout varies disc-to-disc
 - Beam pipe separates & widens → Disc inner radius grows with $|z|$

5-6 Repeated Sensor Units (RSUs)

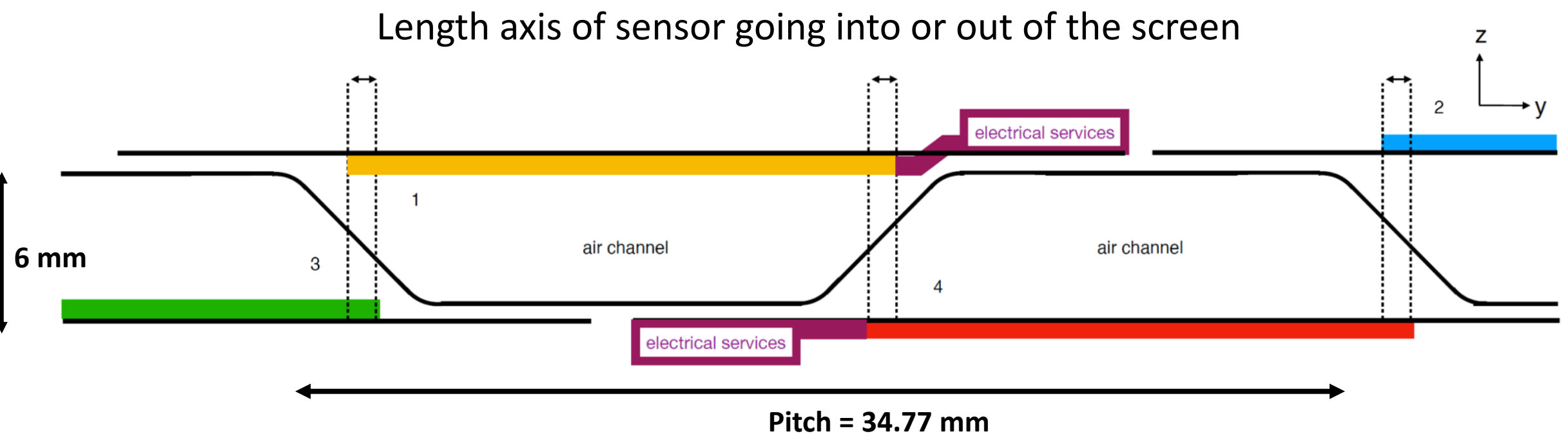


Left Endcap (LEC): Inactive Area

Region	Disk	z [mm]	inner radius [mm]	outer radius [mm]	X/X0
EE	ED0	-250	36.76	240	0.24 %
	ED1	-450	36.76	415	0.24 %
	ED2	-650	36.76	421.4	0.24 %
	ED3	-850	40	421.4	0.24 %
	ED4	-1050	46.35	421.4	0.24 %

Region	Disk	z [mm]	inner radius [mm]	outer radius [mm]	X/X0
HE	HD0	250	36.76	240	0.24 %
	HD1	450	36.76	415	0.24 %
	HD2	700	38.46	421.4	0.24 %
	HD3	1000	53.43	421.4	0.24 %
	HD4	1350	70.14	421.4	0.24 %

Corrugated core

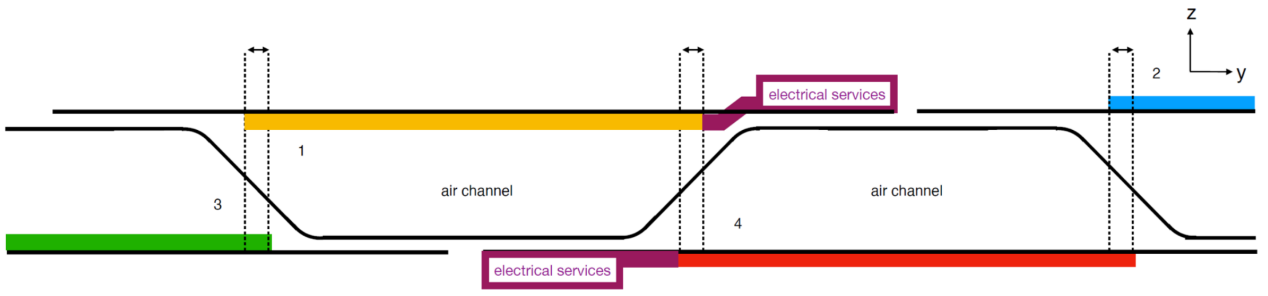
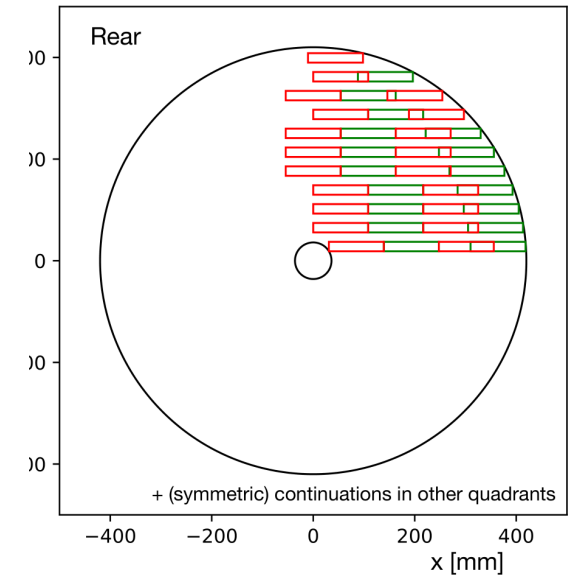
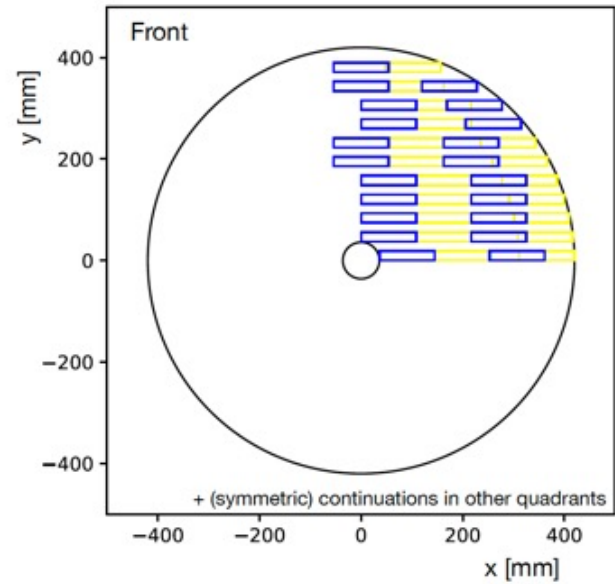


Overlap along the length axis by alternation

Corrugation pitch and height determine overlap along the short axis → Optimization ongoing

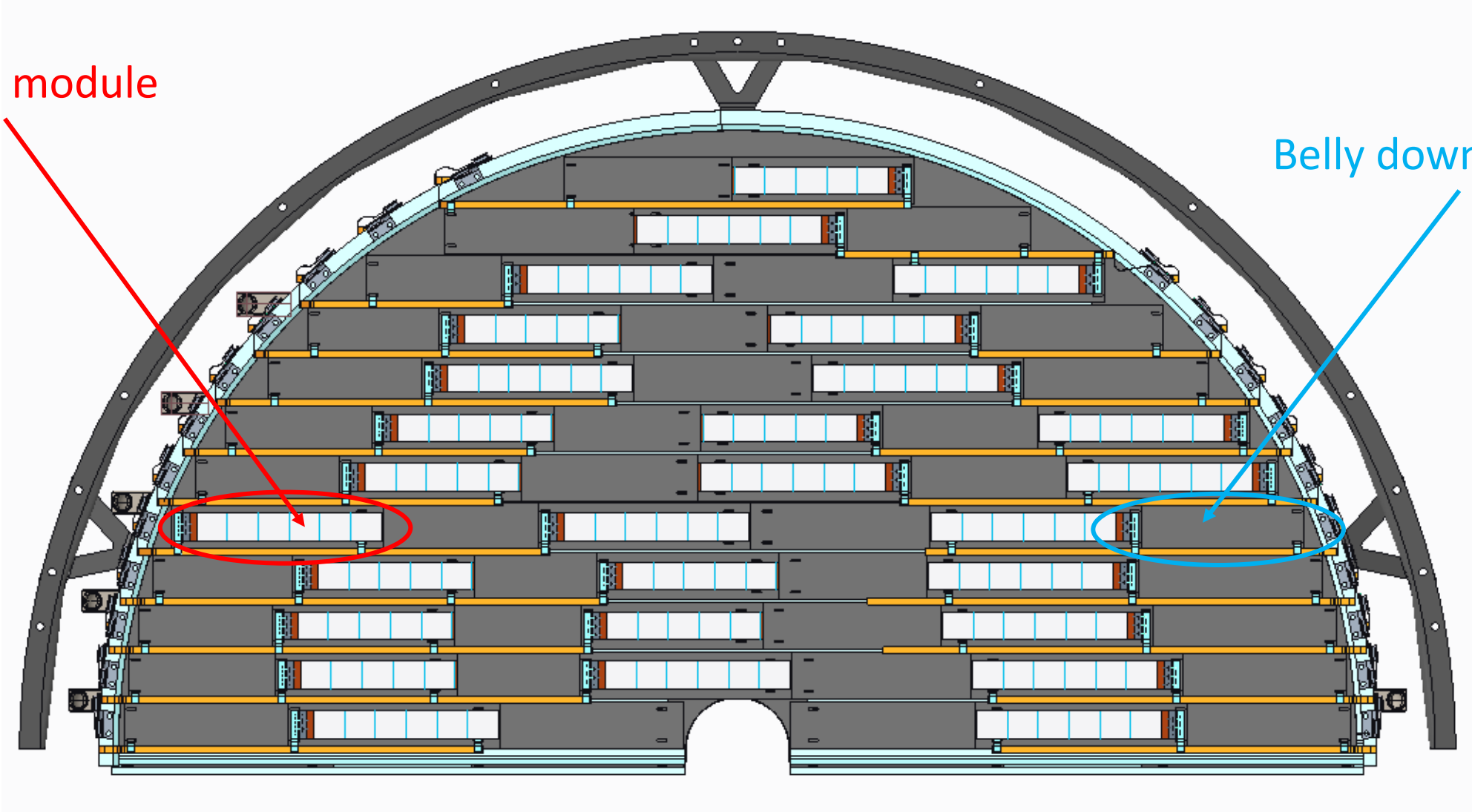
Corrugated disc design

- Face sheet constructed out of modules
- Two module types:
 - **Belly up** (sensor facing outward from corrugation)
 - **Belly down** (sensor facing inward to corrugation)



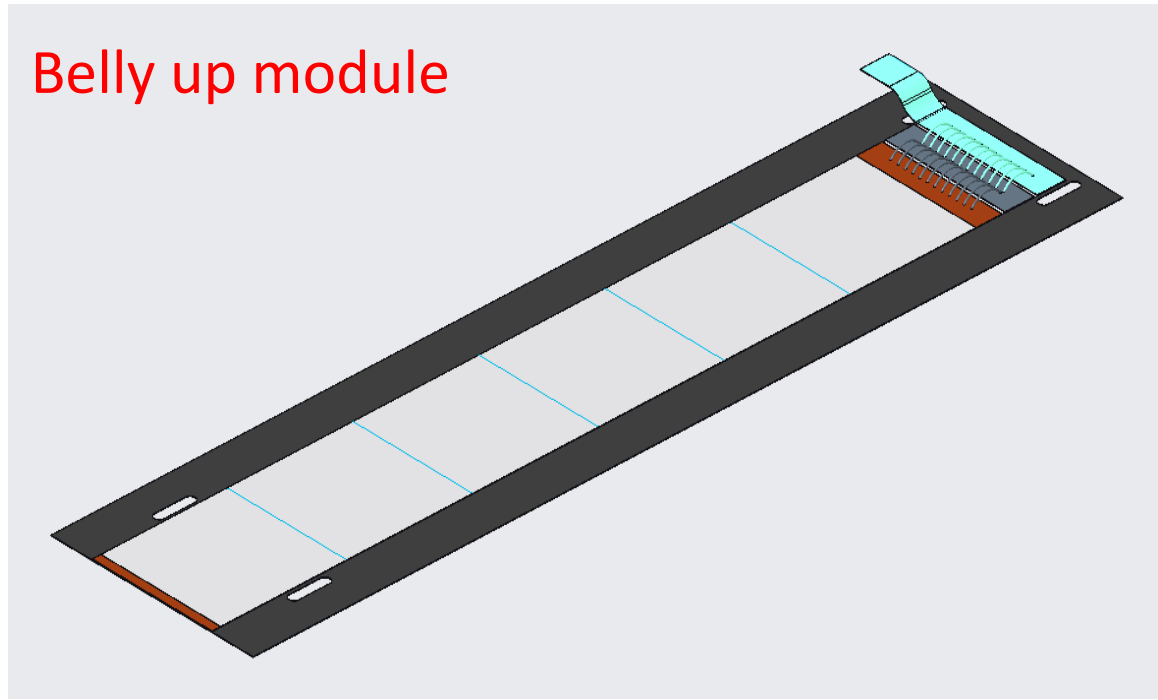
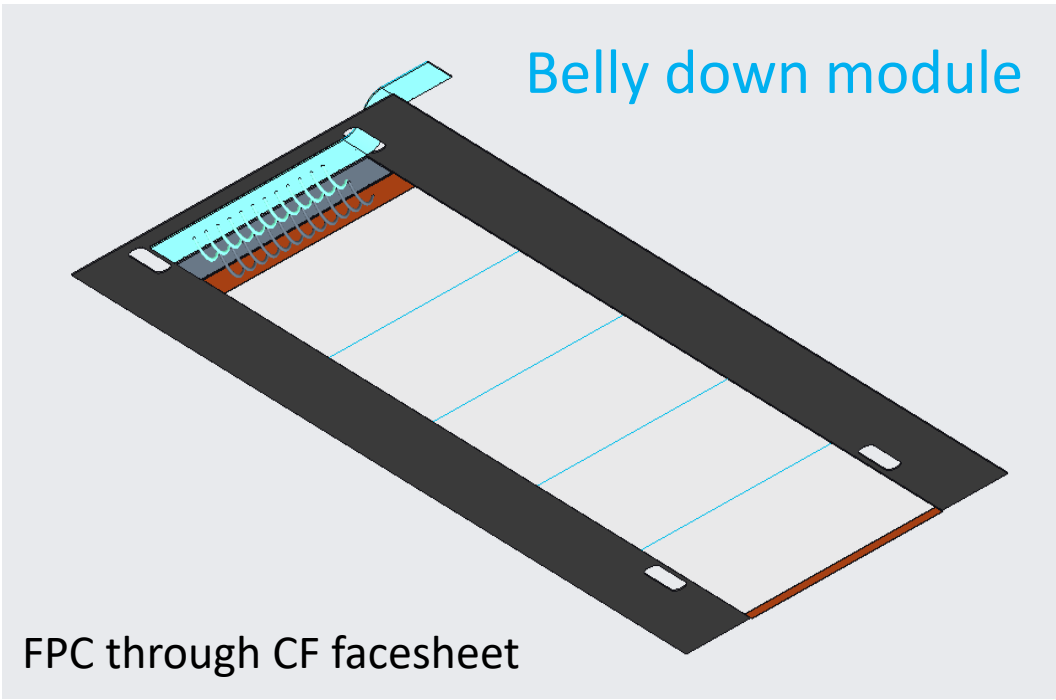
Sensor layout

"Front" face of disc (facing in towards interaction region)



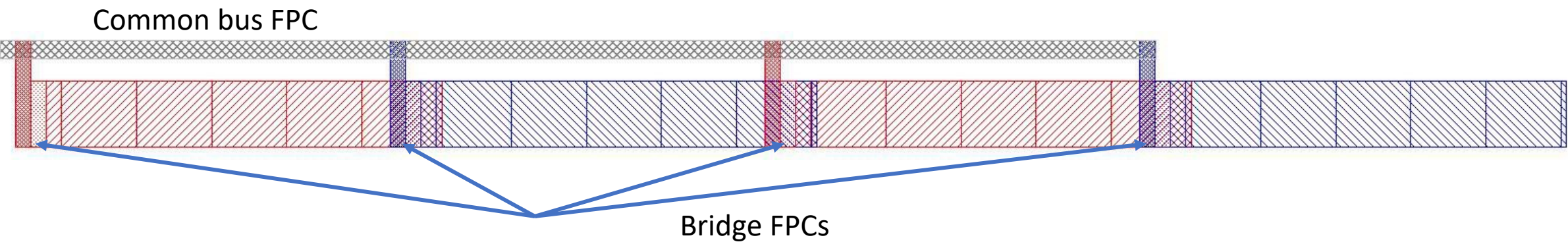
Modules

- One sensor glued to a carbon fiber sheet & bonded to an Ancillary ASIC (AncASIC) and Flexible Printed Circuit (FPC)

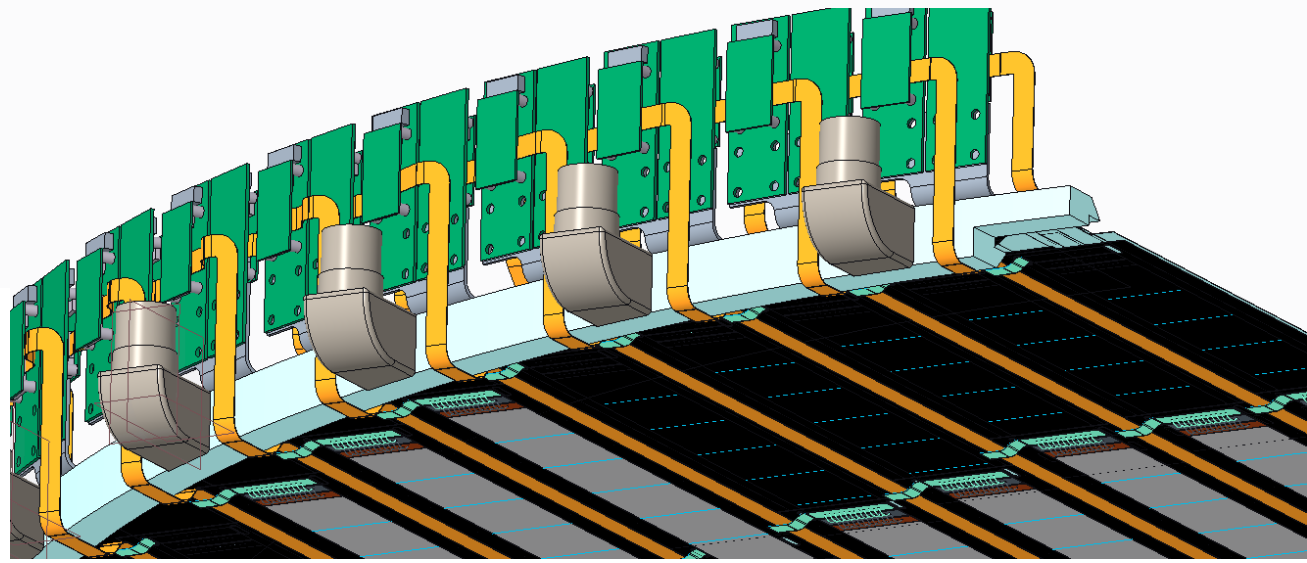
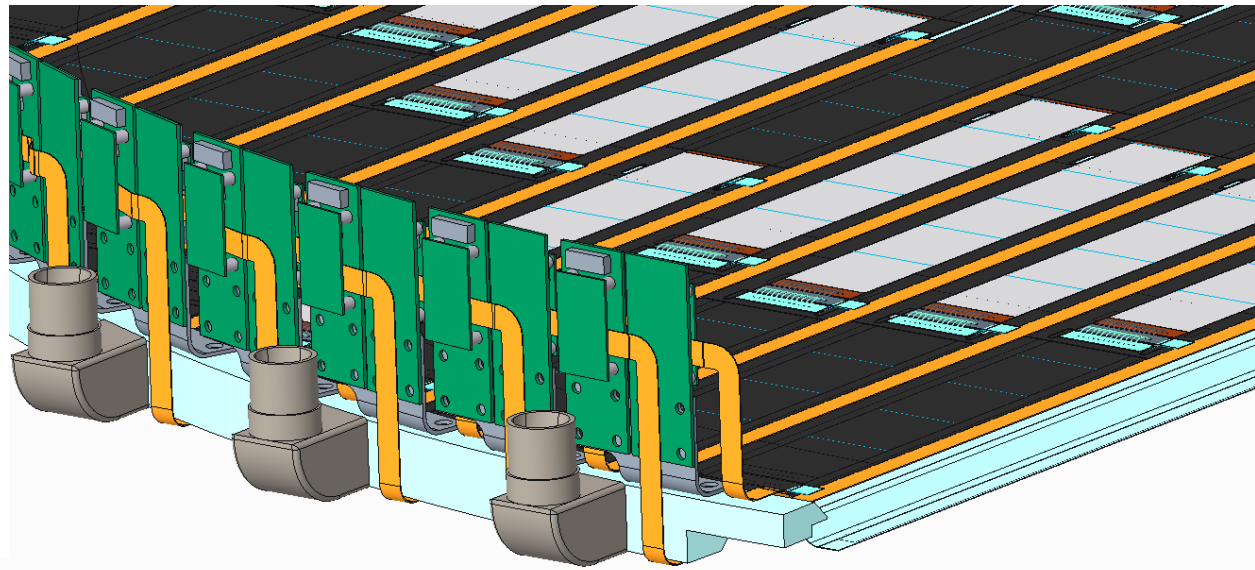
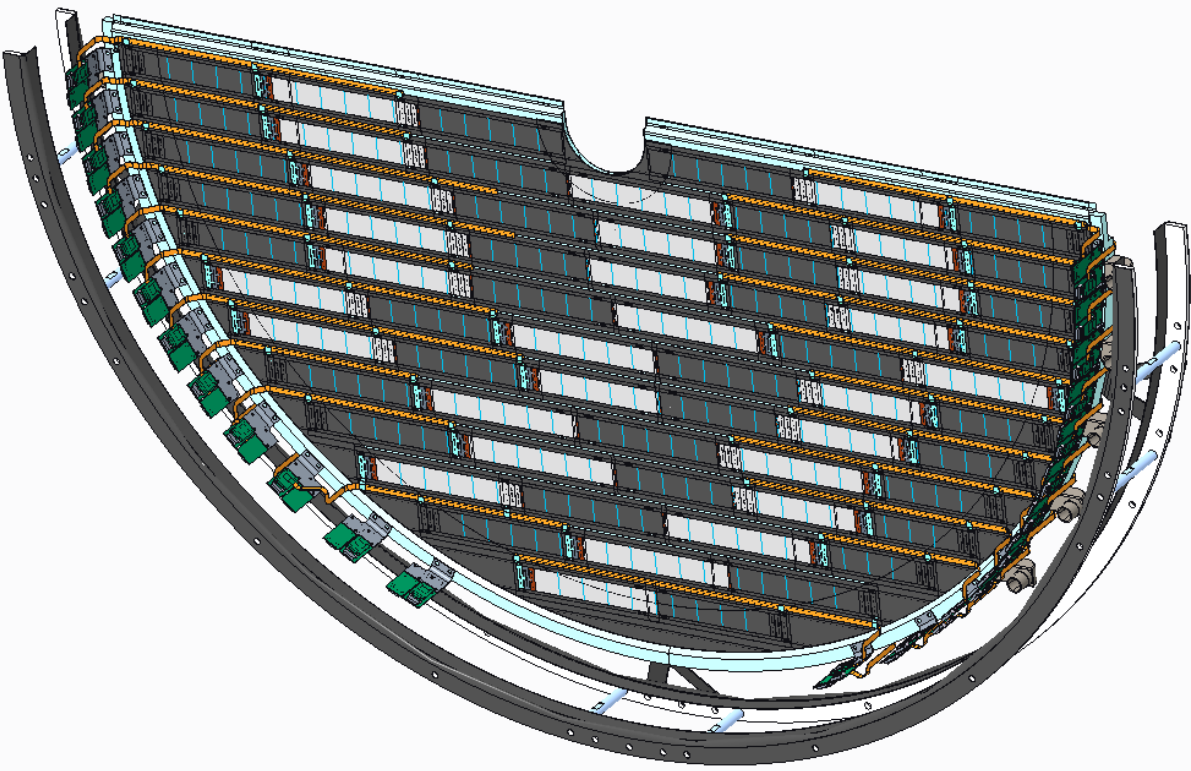


Module grouping

- Up to four EIC-LAS grouped together
- Reduces services with serial powering and multiplexed slow control
- EIC-LAS bonded to AncASIC and FPC bridge
- Up to four FPC bridges connect to common bus FPC
- Common bus FPC connects to Readout Board up to 40 cm away

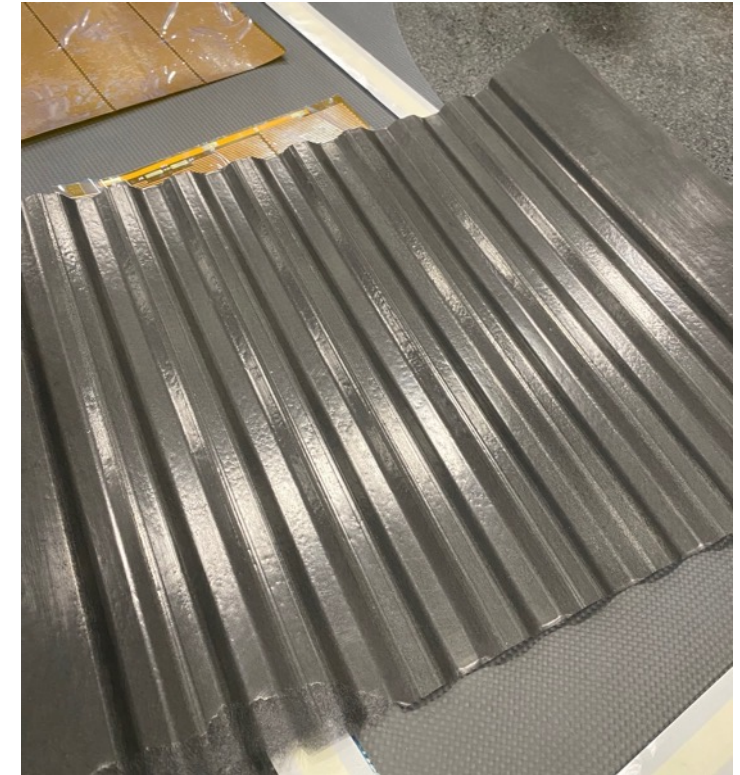


Readout boards

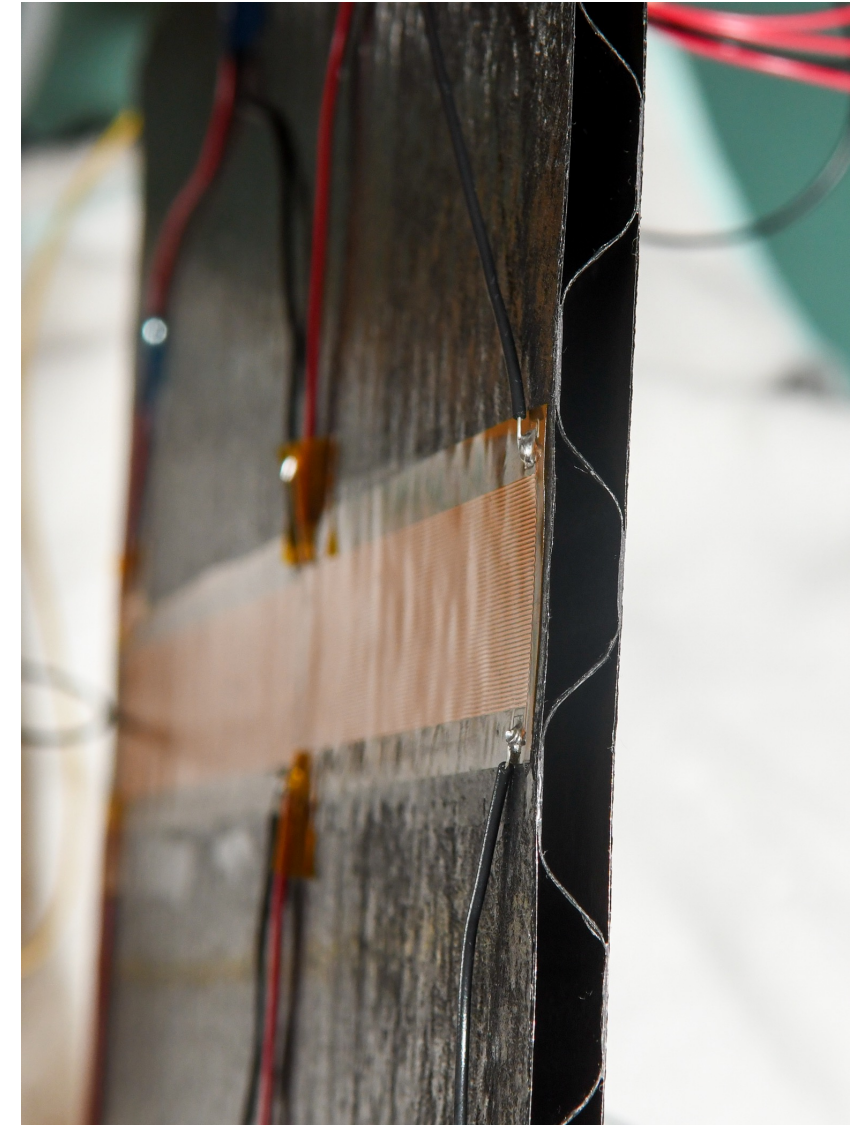
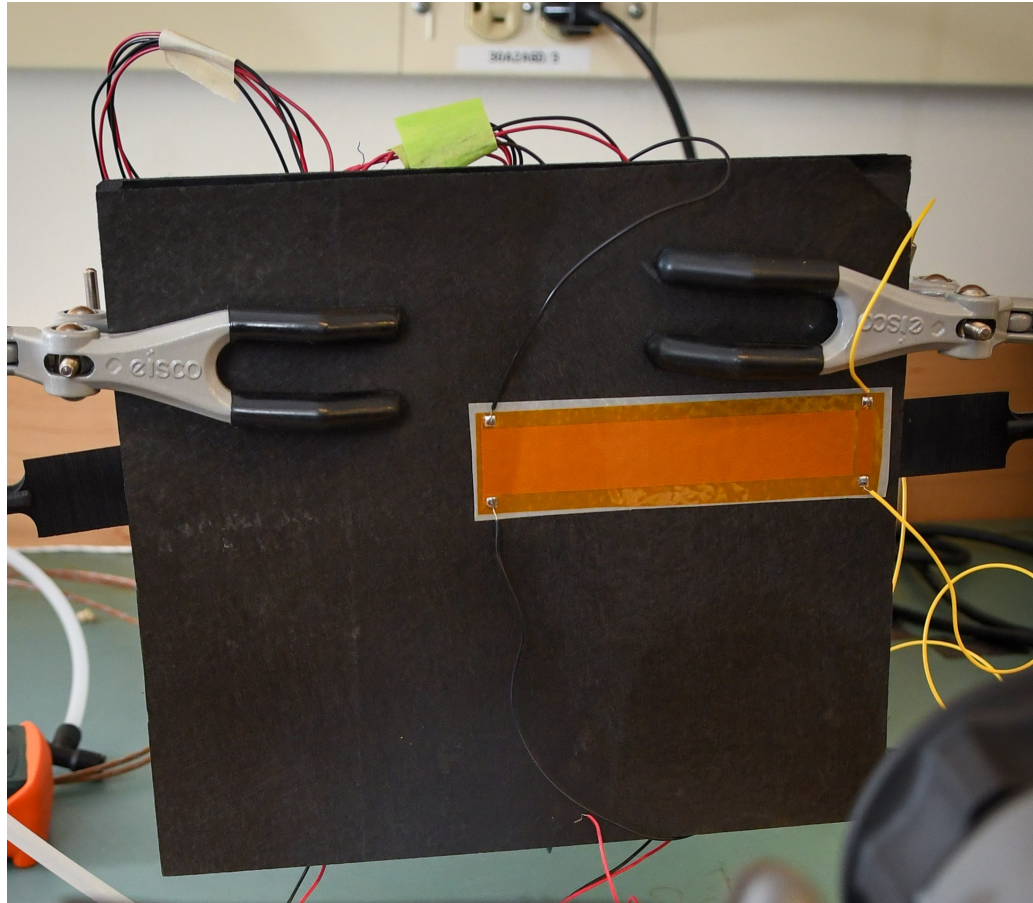


First prototype test piece

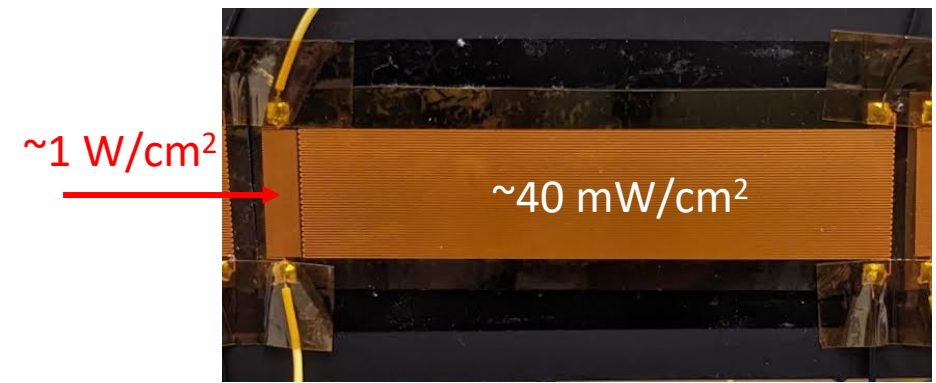
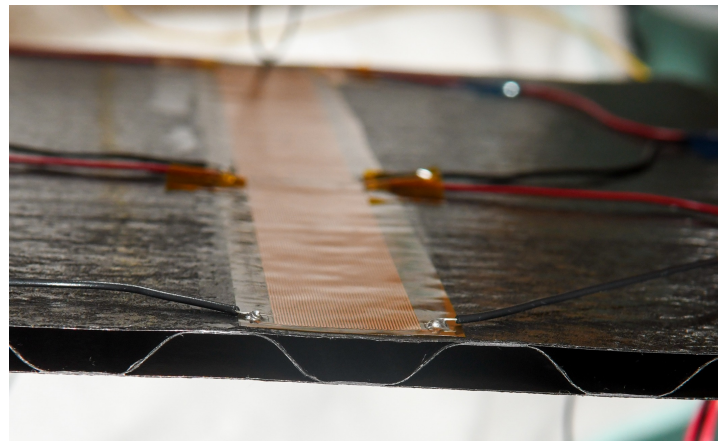
- 2 layers 34 gsm veil & 5 layers 10 gsm resin
- Face sheet glued with 9309 adhesive in 5 mm strips
- Final size of prototype test piece = 22.4 cm x 20.2 cm
- Final weight of prototype test piece = 22.5 g
- Density = 497 gsm \rightarrow $\sim 0.12\%$ X/X₀



First prototype test piece

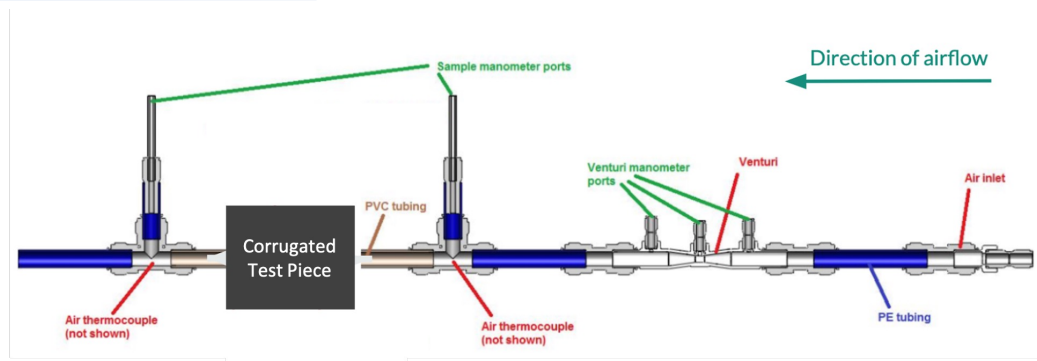


Air cooling



- Corrugated design provides channels for forced air convection
- Thermal prototype → use corrugated test piece
- Heaters with separate zones to mimic sensor power dissipation
 - Left Endcap (LEC): $\sim 1 \text{ W/cm}^2$
 - Matrix/RSUs: $\sim 40 \text{ mW/cm}^2$
- Heaters attached with 3M 467MP double-sided tape, 60 μm thick (used for STAR HFT)

Thermal tests

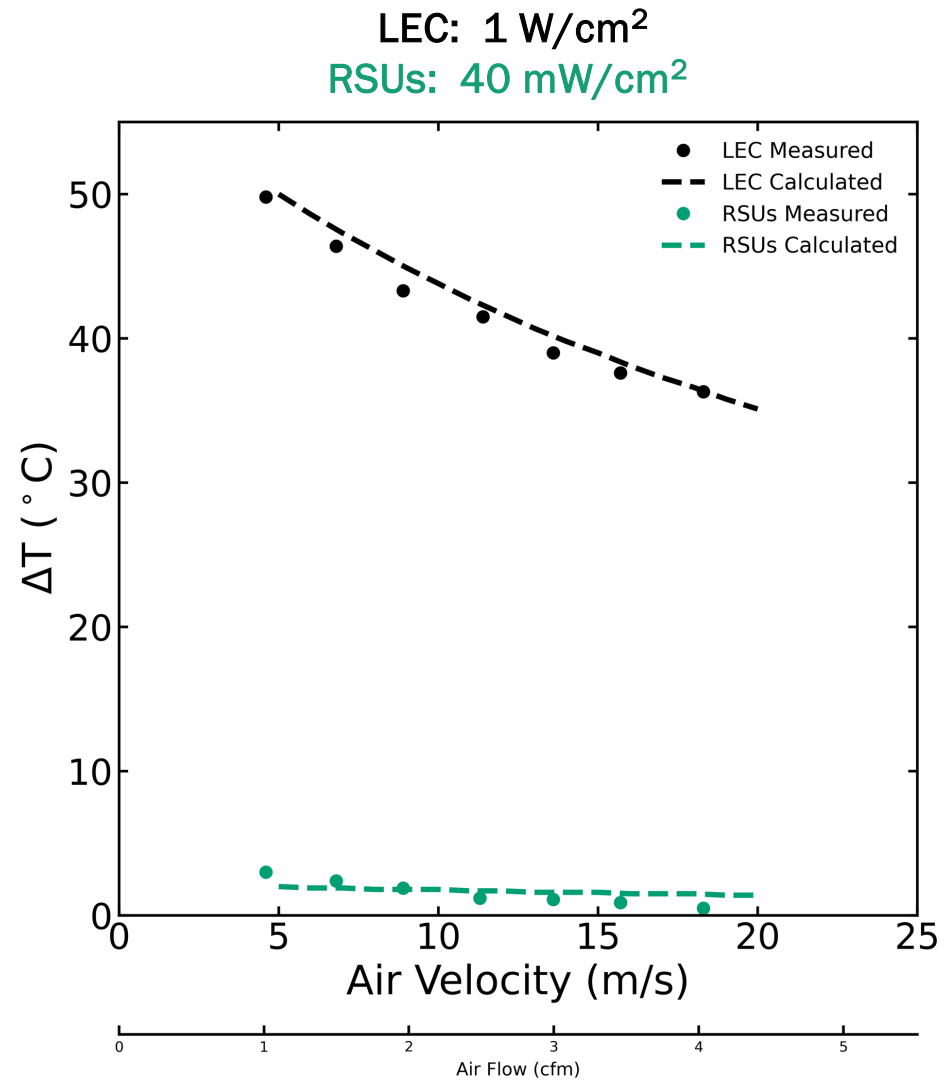


- End goal is operation of sensor at/near *room temperature*
- Temperatures measured with thermal camera
- $\Delta T = T_{\text{Heater}} - T_{\text{Inlet Air}}$
- “Reasonable” ΔT is one that achieves room temperature operation with sensible air inlet temperature
 - $\Delta T < 10^{\circ}\text{C}$ is used often as a “standard”, but is not a requirement



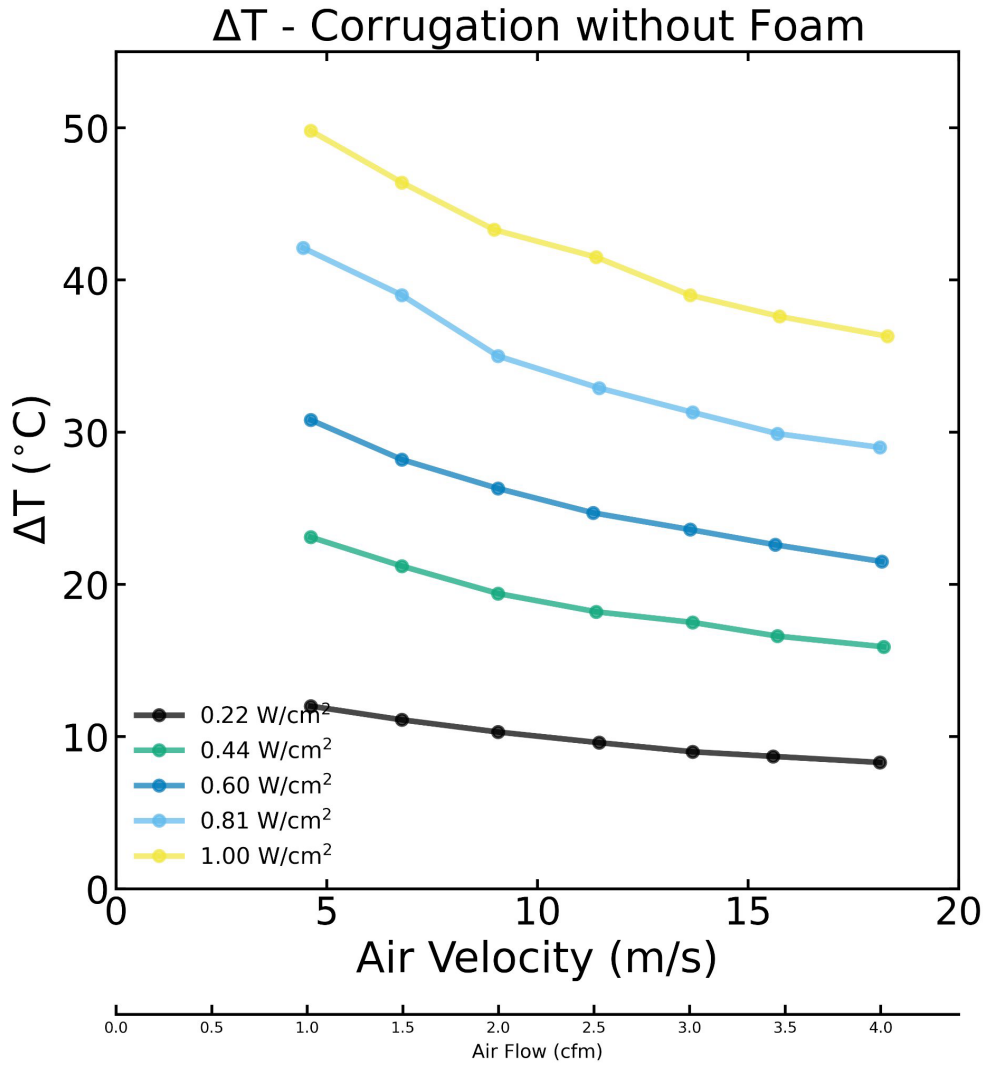
Thermal tests

- $\Delta T = T_{\text{Heater}} - T_{\text{Inlet Air}}$
- Air cooling sufficient for **RSUs**
- **LEC** trending in the right direction
- Add carbon foam to mitigate high power density regions?
- Sensor designers believe the LEC power can be reduced



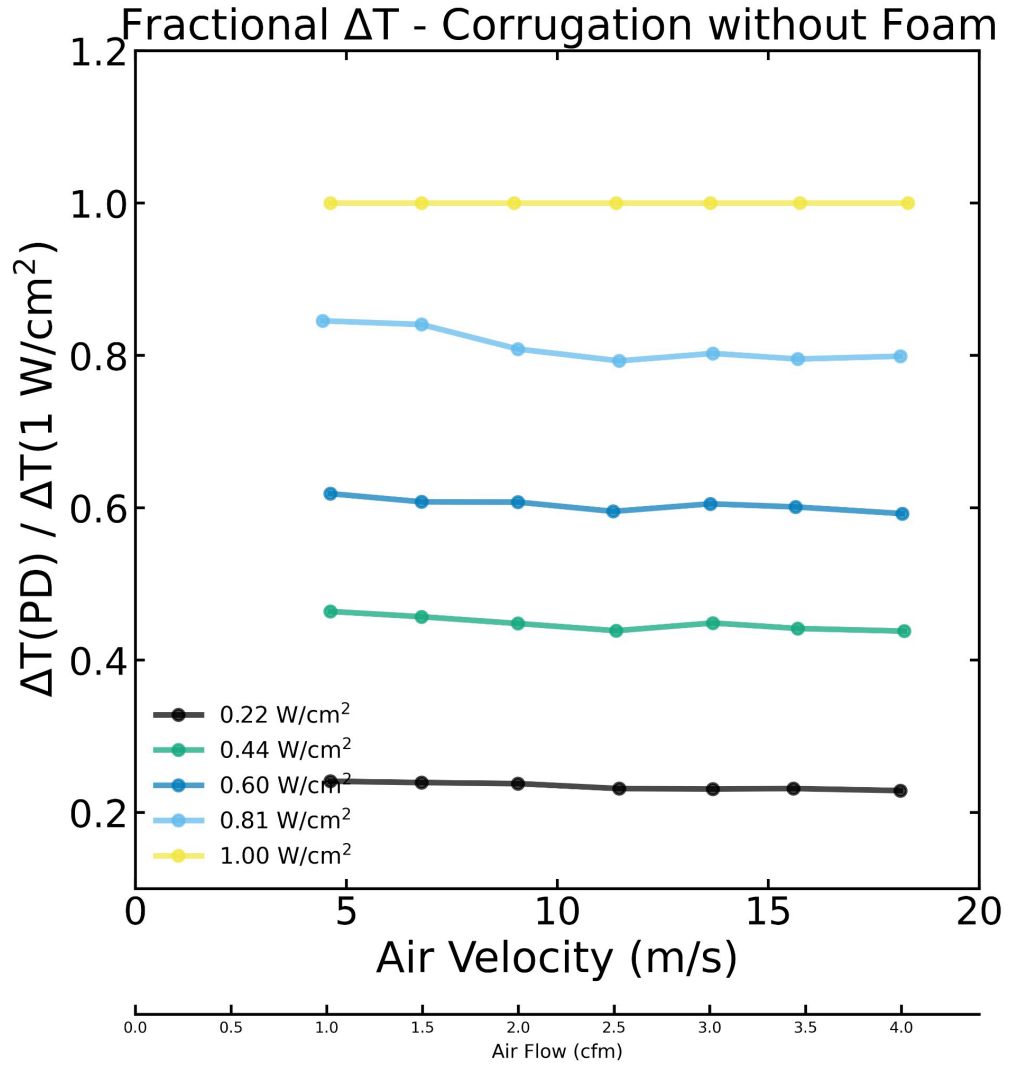
Thermal tests

- Studied a range of LEC power densities
- ΔT reasonable for power $< 0.6 \text{ W/cm}^2$



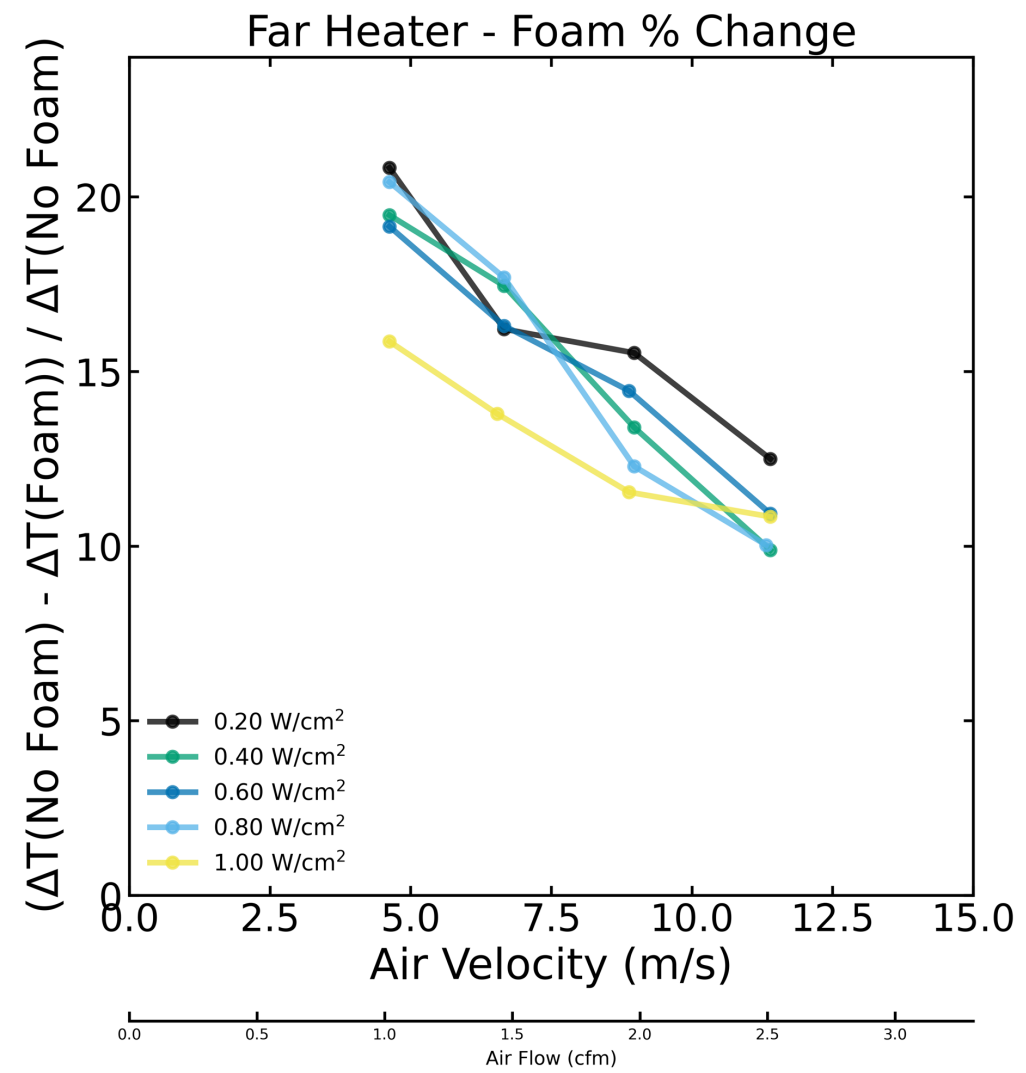
Thermal tests

- Studied a range of LEC power densities
- ΔT reasonable for power $< 0.6 \text{ W/cm}^2$
- ΔT scales with power density

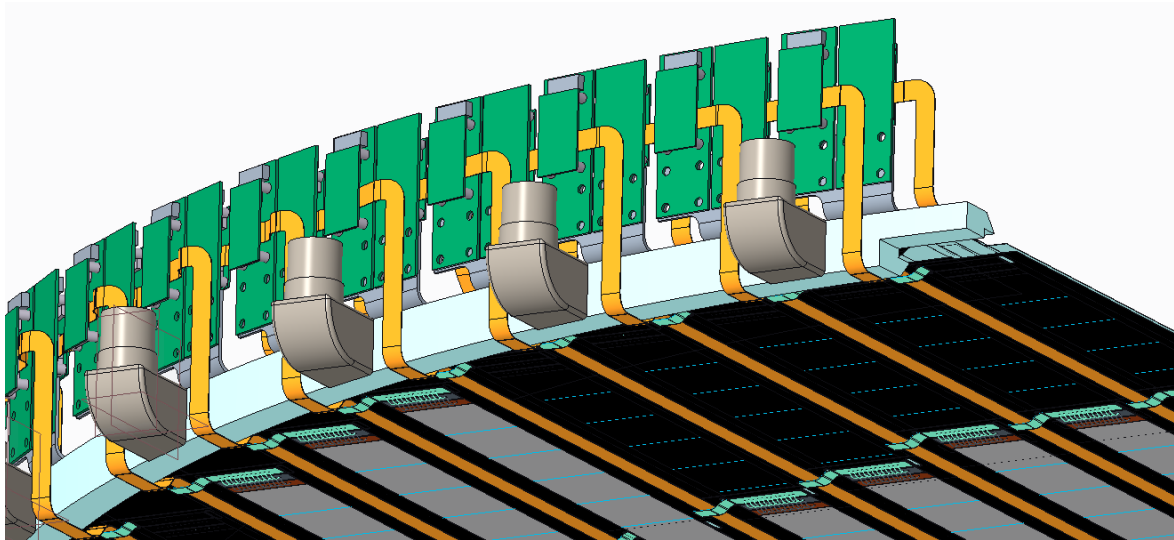


Thermal tests

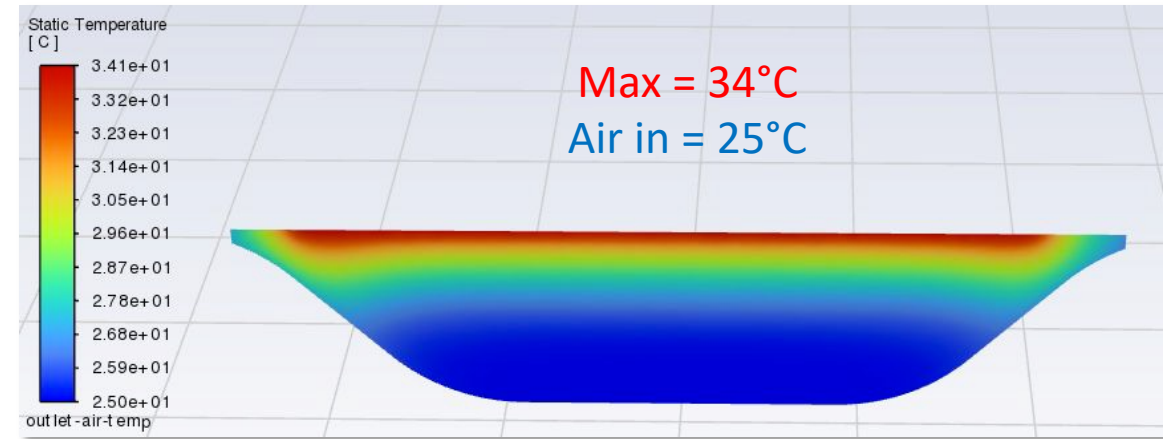
- Studied a range of LEC power densities
- ΔT reasonable for power $< 0.6 \text{ W/cm}^2$
- ΔT scales with power density
- **Carbon foam** under LEC provides **10-20% reduction in ΔT**
 - Caveat: this is insulating foam. Will be measured with thermally conductive foam



Air cooling

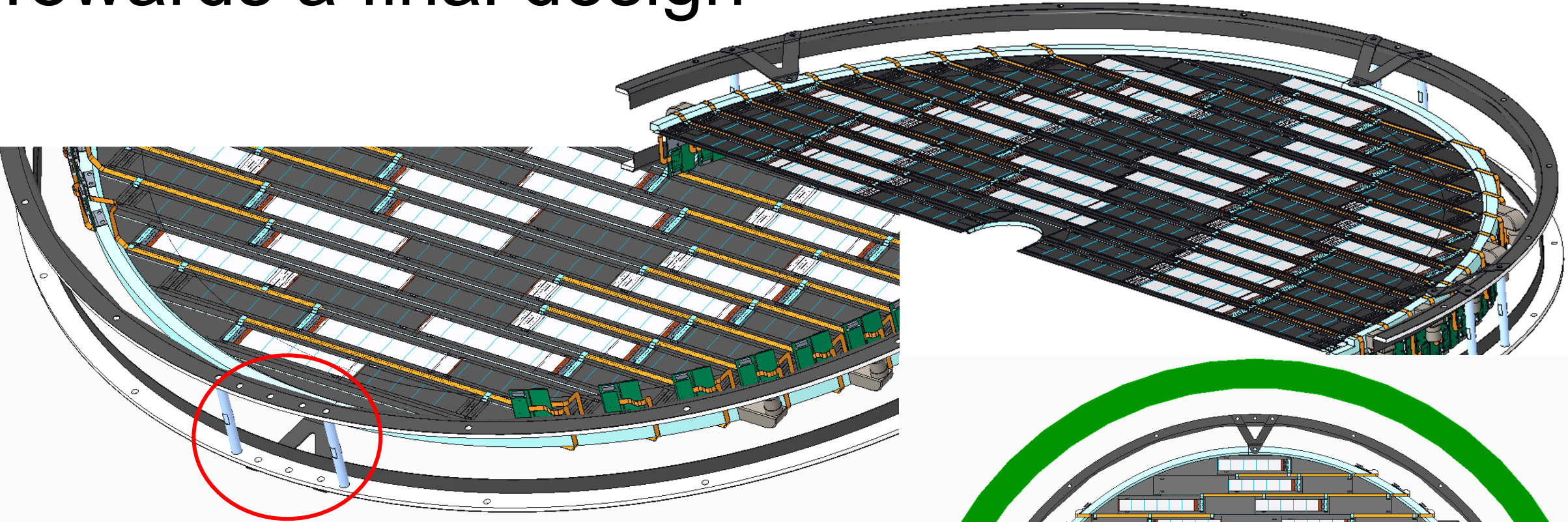


Static Temperature of Cooling Channel
Outlet at a Velocity of 10 m/s



- Volumetric static temperature of air minimal
 - Air can be used in multiple channels → reduces total air volume

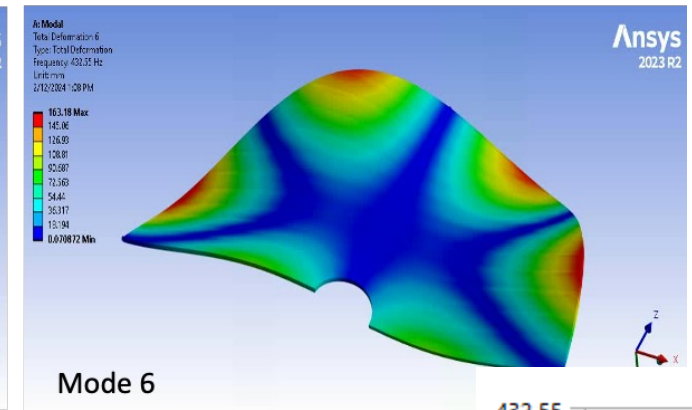
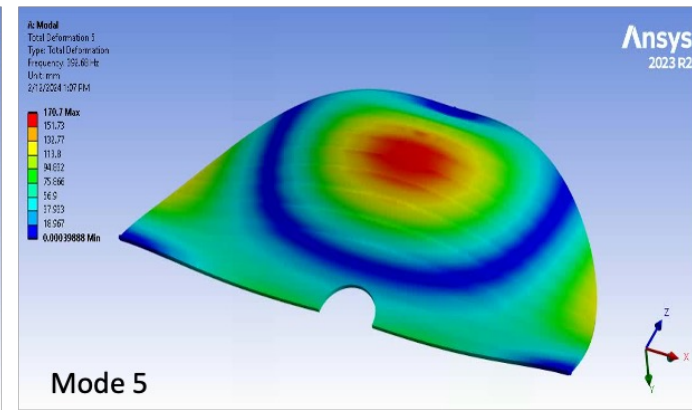
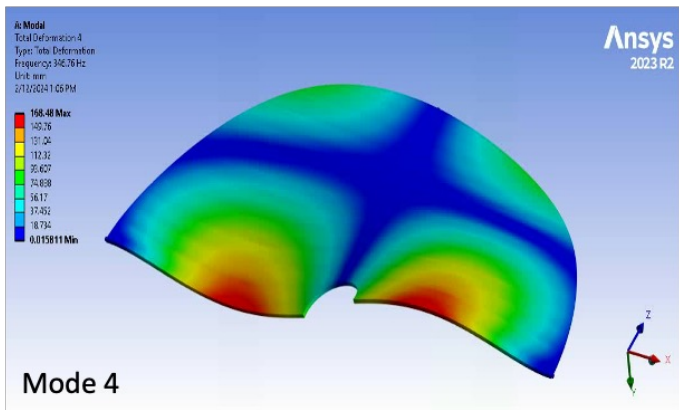
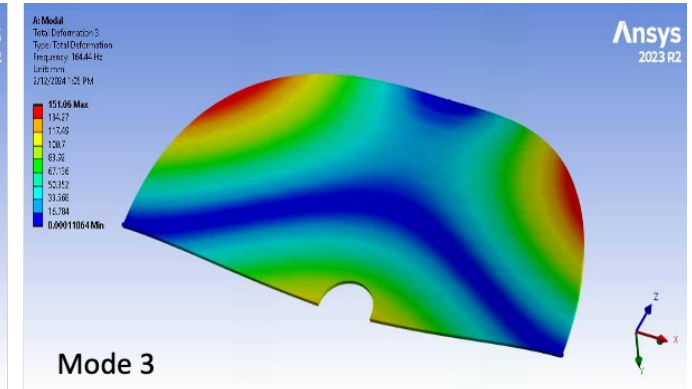
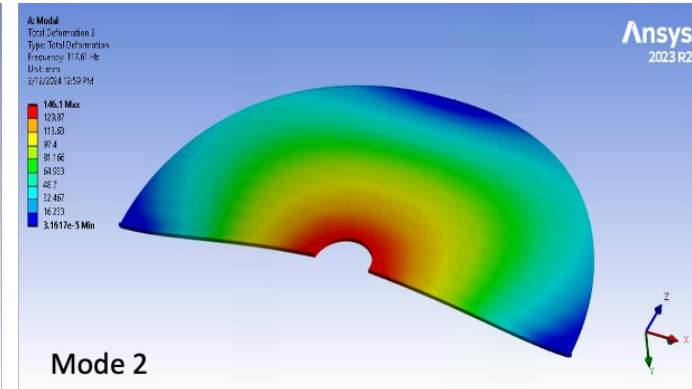
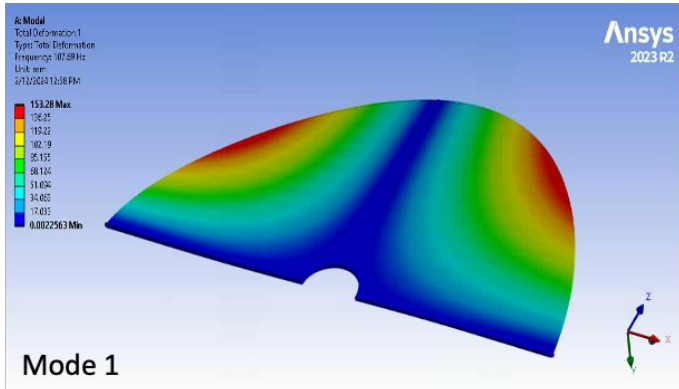
Towards a final design



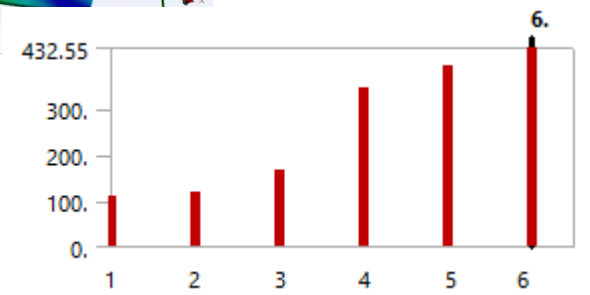
Three connection points per half-disc
Outer rails allow for resting points for the discs

Outer gas detector

Natural frequency



Mode	Frequency [Hz]
1.	107.69
2.	117.61
3.	164.44
4.	346.76
5.	392.68
6.	432.55

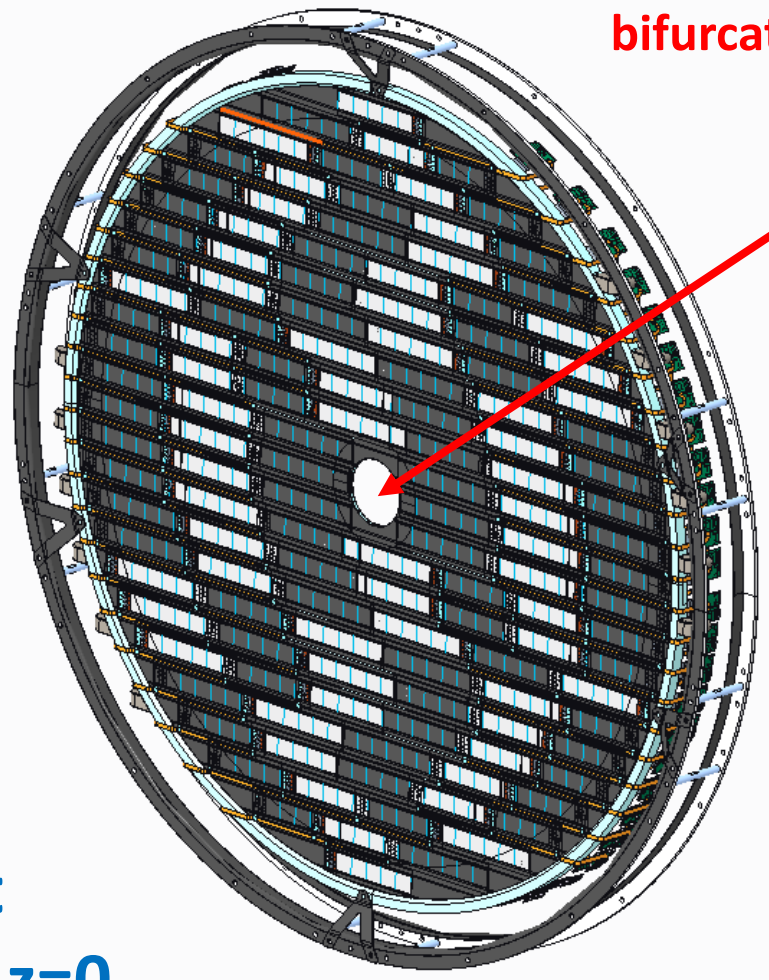


Corrugated Disc of 6 mm Height – Rev 2 (Mesh size = 2 mm)

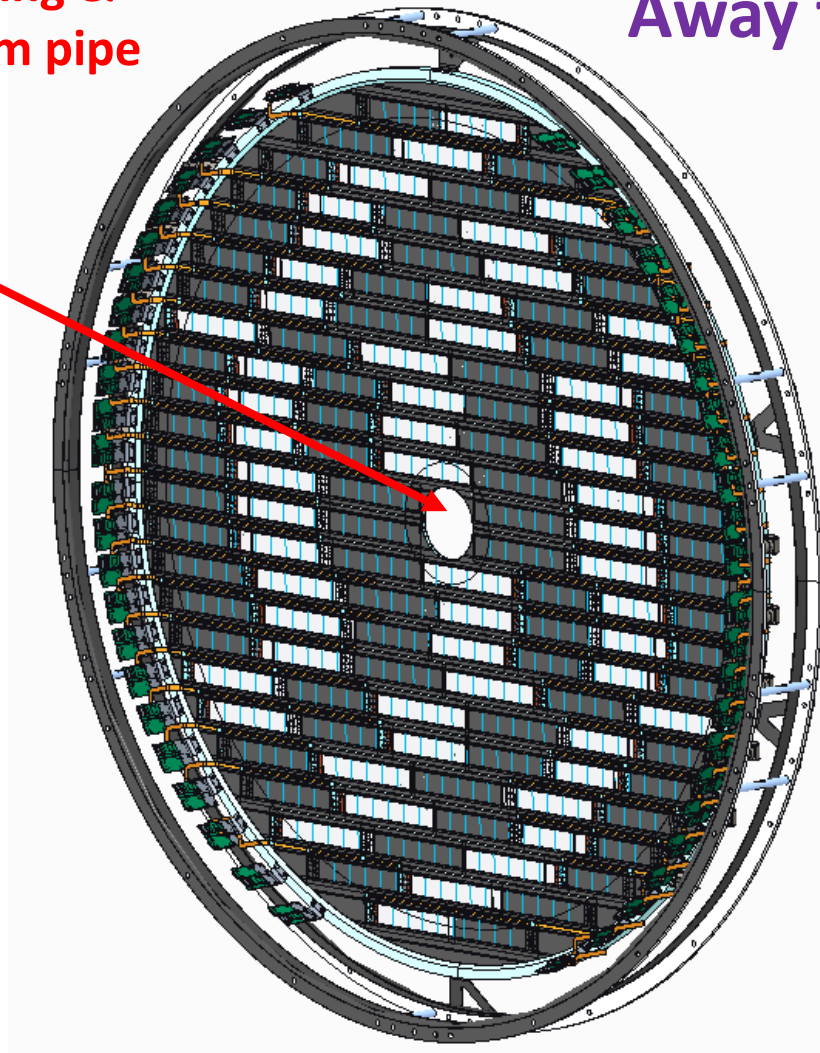
Full discs

Inner Radii will grow with $|z|$ due to the widening & bifurcation of the beam pipe

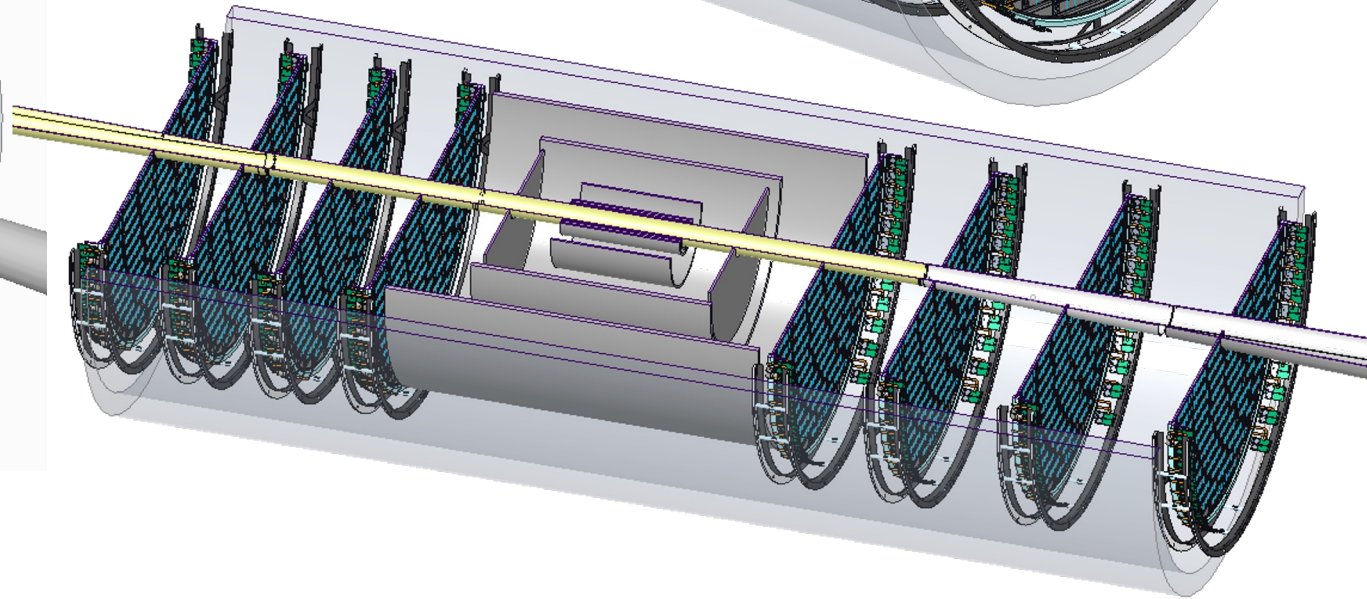
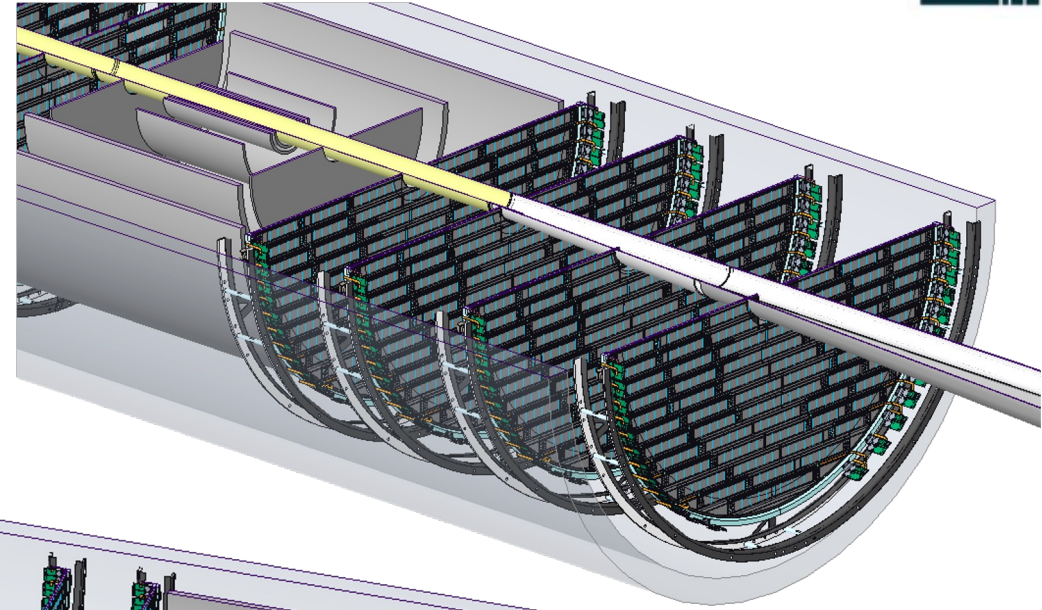
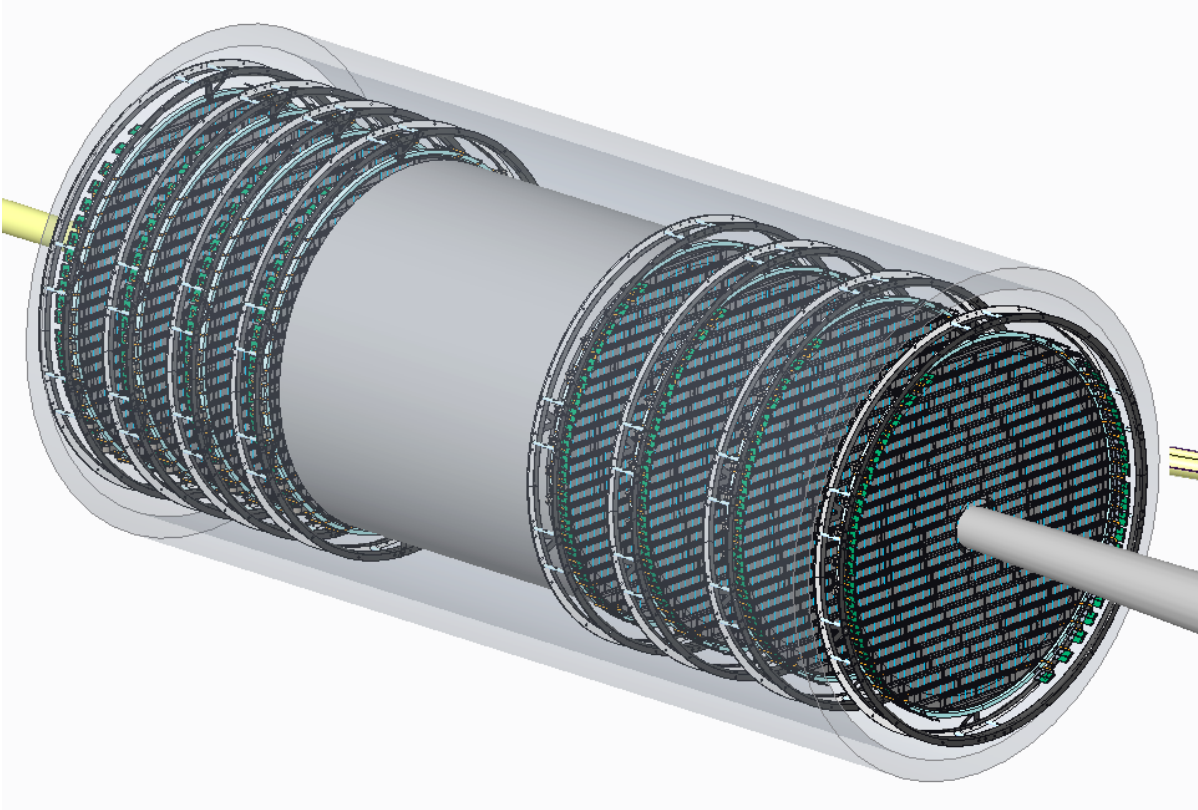
Back
Away from $z=0$



Front
Towards $z=0$



Within the ePIC SVT design



Top-down symmetry favors a horizontal segmentation of the discs

Summary

- EIC tracking requirements pose challenges for a low mass, high acceptance tracker
- Developed a double-sided disc design with a corrugated carbon fiber core
 - Sensors in 4 planes (front/back, belly up/down)
 - Provides channel for forced air convection
- First prototype piece made and tested with thermal mock ups of the sensor
- Prototypes with new layups currently being made for thermal and mechanical tests
- Pre-production/construction begins in 2026

