FlashSim: End-to-end simulation with Machine Learning





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Future Artificial Intelligence Research

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Outline

- Why faster simulation?
- What we mean with end-to-end?
- Generative Al
- Normalizing flows and flow matching
- CMS Flashsim structure
- Accuracy of simulated variables
- Speed, bottlenecks and oversampling
- Conclusions





Simulation at LHC

- Simulation is a large fraction of LHC experiment computing costs
- Tens/hundreds of **billions of events** needed in analysis for proper modelling of backgrounds and signals
- The increase in number of events and complexity of single events for HL-LHC further increases the simulation needs
- Various R&D approaches in CMS to speed-up simulation, often using ML (see <u>Phat's Talk</u>)
 - Speed-up of slowest parts of fullsim (<u>Kevin's talk</u>)
 - FastSim accuracy improvements (<u>Dorukhan's</u> <u>poster</u>)
 - Usage of Delphes for current HL-LHC studies
 - End-to-End ML for analysis

this talk!



"la mia parabola" Figure by Federico Carminati, independent parallel inventions by Vincenzo Innocente & Kyle Cramer



CMS Data Tiers / end-to-end

CMS data tiers

- RAW & RECO => lowest level: detector hits, reconstructed objects including all intermediate steps
- AOD => subset of RECO with higher level objects
- MINIAOD => compact version of AOD
- NANOAOD=> ntuple like format usable by most analysis, only ~1-2Kb/event of information

NANOAOD is one of the enabling factors for a general purpose end-to-end simulation:

- Reasonably "simple" target
- Still usable for analysis





Generating LHC events with AI

"conditioning" as in P(x|cond)

Generate an LHC event



an LHC event of ĆMS experiment with a Higgs boson decay to a pair of muons





Accuracy in image generation

Qualitative definitions, no requirement of statistical properties of generated samples





Accuracy for Physics Analysis

- A simulation **usable for analysis** should properly **reproduce PDFs** both for individual variables and for their correlations
- Many AI generative tools (e.g. GAN, VAE) work reasonably well *qualitatively* but are severely limited when looking at distribution details
 - mode collapse for multimodal distributions
 - bridging between peaks

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- accurate in mean and variance but limited handling of long tails
- We tested various alternative models including W-GAN and other modified losses
 - limited success on the low dimensionality problem we face







Normalizing Flows: generative model for *pdf*s!



f(x) as a discrete flow

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- In order to increase the expressivity of *f*(*x*) we can use a **chain** of simple invertible transformations
- The parameters of each transformation are determined by a DNN that takes as input the previous state and the external conditioning information





- In order to catch correlations you want one variable to depend on others f(x;θ), but to keep it invertible you cannot transform the variables θ as they are need to compute f⁻¹(y;θ)
 - <u>Autoregressive</u>: 1st variable depends on nothing, 2nd variable depends on 1st, 3rd on (1st, 2nd)... etc..
 - <u>Coupling</u>: at each step only transform some variables, and explicitly depend on the others





Continuous Flows

Possible solution: continuous flow

f(0; z) = z = Gaussian f(1; z) = target p.d.f. $f(t + dt) = f(t) + v(t) \cdot dt$ $f(t + dt) = f(t) + DNN(f(t)) \cdot dt$

A technique called Flow Matching allows to train continuous flows learning the vector field v_t

- Solves the conditioning problem: each step is infinitesimal hence *f*(*t*) ~ *f*(*t*+*dt*)
- No need to chose a function for the transformation as we simply learn its gradient in every point of space
- At inference time we will need to integrate the path from t=0 to t=1
- Use a single DNN to predict the vector field in any point
 - while discrete flow have one DNN for each step



see <u>https://arxiv.org/abs/2210.02747</u>, and **Z** <u>https://arxiv.org/abs/2302.00482</u>, figure from https://ehoogeboom.github.io/post/en_flows/



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CMS FlashSim

Goals and ideas of CMS "FlashSim"

- Provide an **analysis agnostic simulation** exploiting the common NANAOD format as a baseline target of the simulation
- Be **sample independent**, learning the **"detector response**" to different type of generated particles and in different running conditions
- Reach a speed that is **orders of magnitude faster** than existing simulations
- Maintain an accuracy that is good enough for analysis, with a "delta" to full-sim that is the same order of magnitude of the delta between full-sim and real data.





FlashSim structure

A **reconstructed object** may originate from **multiple sources**

- genuine signal
- particles with similar signature
- detector interactions and decays
- fakes, duplicates, pileup

Each object is handled by FlashSim with various models

- An **efficiency model** for each source
- A properties model for each source





Efficiency models

Given a soure object to we get a reconstructed one?

- Efficiency models are **trained as simple classifiers** with binary cross-entropy loss
 - output can be interpreted as a probability!
- At inference time we just **toss in [0,1] and compare with model probability**

Prompt muon efficiency





Duplicates can be handled by training a second classifier to predict when a second copy is produced



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Properties models

- For each object we need to simulate all its properties
 - e.g. momentum, eta, phi, tagging variables, ID, isolation, etc..
- Some properties have obvious correlations with generator level information
 - generated vs reconstructed four-momentum
 - MC flavour with tagging variables
- Two crucial points to reproduce correlations
 - Conditioning:
 - e.g. is it b-quark jet?
 - Transformations:
 - standard scaling
 - better learn P_T^{reco} or P_T^{reco} / P_T^{gen} ?
 - tails matter for physics (apply logs when needed)





Flashsim status

- Current FlashSim prototypes simulates all object properties for most of the NANOAOD format collections
- Major sources of signal and background are considered, more to be added in the future
- Currently missing: trigger information (some part is trivial, some is less)

Physics objects	Sources (Number of simulated attributes per object			
Jets	Generator Jet	Fake from PU		39	
Muons	Generator Muons	Fake from Jets/PU Duplicates		53	
Electrons	Generator Electrons	Generator Photons (prompt)	Fake from Jets/PU	48	
Photons	Generator Photons (prompt)	Generator Electrons	Fake from Jets/PU	22	
MET	GenMET and HT			25	
FatJets	Generator AK8 Jets			53	
SubJets	Generator AK8 SubJets			13	
Tau	Reconstructed Jets with a Tau	RecoJets without a Tau		27	
Secondary Vertices	Jets with Heavy Flavour	Light Jets	Taus	16	
Non MET scalars (e.g. PV)	Various event level inputs			16	
FSRPhotons	GenMuon/RecoMuon			6	

Results on individual models

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Results on 4M events training

- Trained on a cocktail of a few samples with different signatures covering different corners of the phase space
 - likely suboptimal choice, dedicated samples (e.g. flat QCD or particle guns) could also be considered

Sample		
tī	800k	
DY HT [100, 200], 2J MLL [200-1400]	930k	
$HH \rightarrow bb \ bb$	840k	
$X(3000) \rightarrow Y(500) \text{ H}(125) \rightarrow (bb) (WW \rightarrow 2q 2l\nu)$	147k	
$X \rightarrow HH \rightarrow qq \ qq \ (M_X \ 900, \ 1200, \ 1800; \ M_H \ 365, \ 400, \ 18)$		
SMS TchiZH mNLSP200-1500	300k	
$X(1200) \rightarrow Y(300) \text{ H}(125) \rightarrow \text{bb } \gamma\gamma$	400k	
$VBF H \rightarrow \tau \tau$	270k	
$bbA \rightarrow ZH \rightarrow ll \ \tau \tau \ (M = 900)$	33k	

 FlashSim learned some of the detector features present in the simulation (and missed some other)





Accurate conditioning

- A single model should learn to produce different distributions for different conditioning values (momentum of a particle, flavour of the quark producing a jet, decay mode of a particle, etc...)
- flowmatching is incredibly accurate at catching the multidimensional correlations between conditioning variables and output ones







100

200

Soft Drop Mass (GeV)

18

300

10⁰



Example of correlations





Full Event simulation and toy analyses



Event simulation chain

Simulating a full NANOAOD event implies several steps, to be repeated for each object, for each source

- extract the conditioning information
- run the efficiency model
- run the properties model
- (merge output from different sources)

Some models are conditioned not only on generator information but on reconstructed information from previous steps (e.g. MET is conditioned on the various reconstructed objects ; electron and photon reconstruction are cross-conditioned)

FlashSim event simulation is **extracting data with RDataFrame** and processing batches of events in parallel with **PyTorch**

Simulated ~100M events from various processes, some of them never seen during training.





Sample	Events		
tī	100M		
DY HT [100, 200]	25M		
$H \rightarrow \mu\mu$	1M		
ZH	300k		
jj + ll (ewk)	8M		



Derived quantities

- Once full NANOAOD event are available we can compare derived quantities and implement some analyses
 - Two toy analysis corresponding to VBF Higgs to muons search and $ZH \rightarrow IIbb$ have been tested comparing flashsim with fullsim
 - Analyses tested all the way down to the final DNN output, comparing different samples, some never seen during training

Muons

Jets

Medium

b-tag

Signal

Region

VBF H→	μμ Selection	
Muons	$p_T > 20 \text{ GeV}, \eta < 2.4,$ Iso < 0.25, MediumID	
Jets	$p_T > 25 \text{ GeV}, \eta < 4.7,$ puId > 0, jetId > 0	
Signal Region	$\begin{split} &115 < m(ll) < 135, \ p_T^{\ jl} > 35, \\ &p_T^{\ j2} > 25, \ m(jj) > 150, \ \Delta\eta(jj) > 2 \end{split}$	



DNN output

Speed and bottlenecks



How fast is FlashSim?

- The current prototype with ~20 properties model and ~20 efficiency models, starting from existing generated samples runs between 10Hz and 1KHz
 - \circ Accuracy of integration
 - Availability of GPU vs Single CPU
- How fast do we need FlashSim to be
 - If you already have generated samples, as fast as possible
 - If the generator is very slow, we are easily in the shadow of the generator
- What if we can avoid being generator-speed limited by reusing generated events?
 - Overampling!

Processor	ODE accuracy (timesteps)	Event simulation rate
GPU 3060	100	325 Hz
GPU 3060	20	690 Hz
CPU 1-core	100	15 Hz
CPU 1-core	20	60 Hz
CPU 4-core	20	120 Hz

		Event generation speed			Ratio to Geant/-based			
		Event generation speed			Ratio to Geant4-based			
Generator speed (Hz)	Oversample factor	0.1Hz Geant4 based sim	10Hz Flashsim	100Hz Flashsim	1KHz Flashsim	10Hz Flashsim	100Hz Flashsim	1KHz Flashsim
available	1x	0.10 Hz	10.00 Hz	100.00 Hz	1000.00 Hz	100.0x	1000.0x	10000.0x
50.00 Hz	1x	0.10 Hz	8.33 Hz	33.33 Hz	47.62 Hz	83.5x	334.0x	477.1x
50.00 Hz	10x	0.10 Hz	9.80 Hz	83.33 Hz	333.33 Hz	98.1x	833.5x	3334.0x
1.00 Hz	1x	0.09 Hz	0.91 Hz	0.99 Hz	1.00 Hz	10.0x	10.9x	11.0x
1.00 Hz	10x	0.10 Hz	5.00 Hz	9.09 Hz	9.90 Hz	50.5x	91.8x	100.0x
0.05 Hz	1x	0.03 Hz	0.05 Hz	0.05 Hz	0.05 Hz	1.5x	1.5x	1.5x
0.05 Hz	10x	0.08 Hz	0.48 Hz	0.50 Hz	0.50 Hz	5.7x	6.0x	6.0x



- Typical LHC MC samples are randomly sampled "twice"
 - in the generator
 - in simulating the detector response
- In many cases a large part of the uncertainty originates from the detector response
 - generator information can be reused

We call **"oversampling**" the repeated usage of the same generator event for multiple simulations

- Proper statistical treatment is needed for events originating from "same gen"
 - count events that end up in the same bin of a histogram as correlated
 - consider events in different bins as uncorrelated



Is oversampling introducing biases?

Let's test it against full sim

- We start from a sample for which we have 8M full sim events
- We take a fraction (1/6th, 1.3M events) of the full sim events and we can check how oversampling (6x or 10x) it would compare to the full sim sample



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Conclusions

- We implemented the first complete working prototype of an end-to-end simulation, using ML, for CMS NANOAOD format
- A good tradeoff between speed and accuracy has been found, but we can further tune it as needed
- Tests on toy analyses show a good accuracy also for derived quantities, next tests could be on real analysis
- We introduce the oversampling technique to maximize the exploitation of generator level MC event

<u>References:</u>

- DPS Note with more plot and details:
 - CMS DP-2024/080
- CMS Note with earlier prototype
 - o <u>CMS-NOTE-2023-003</u>
- Paper on toy dataset (see Filippo's talk on <u>Tuesday 17:27 track 5</u>)
 - o <u>arxiv:2402.13684</u>

Backup



Vertex and Pileup





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Secondary Vertices









Secondary Vertex from Taus and Heavy Flavour





SV from GenJets





Jets and Fake Jets



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Tau properties









Counts

105

104

10³

102

101

100

Muon features



CMS Simulation Preliminary











Electrons



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Photon from generator level photons







Photon from Jets





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Z(ll)H(bb)





VBF Higgs to mumu







ODE integration accuracy







Flow Matching as a solution

Main idea:

Learn vector field u, approximation of v

u is the field going from noise to data under a Gaussian assumption

y = NN(x) Loss = || u - y ||

$$p_t(z|x) = \mathcal{N}(z|tx, (t\sigma_{\min} - t + 1)^2),$$
$$u_t(z|x) = \frac{x - (1 - \sigma_{\min})z}{1 - (1 - \sigma_{\min})t},$$



Oversampling: statistical treatment

Usually, a histogram is filled with events (and their weights)



Oversampling → the final histogram is given by the weighted sum of *sub-histograms* filled with the distributions of events sharing the same GEN

Note: the final uncertainty is larger than just calling TH1::Fill()

N = oversampling factor



• Non-oversampled case

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- w statistical weight associated with the MC event
- For the *i*-th bin of an histogram, the probability of being in this bin and the associated uncertainty are

$$p_i = \frac{\sum_{j \in \text{bin}} w_j}{\sum_{k \in \text{sample}} w_k} \qquad \sigma_i = \frac{\sqrt{\sum_{j \in \text{bin}} w_j^2}}{\sum_{k \in \text{sample}} w_k}$$

- Oversampled case
 - \circ A fold is the set of RECO events sharing the same GEN

$$p_{i} = \frac{\sum_{j \in \text{bin}} \sum_{l \in \text{fold} \in \text{bin}} w_{jl}}{N \sum_{k \in \text{sample}} w_{k}} = \frac{\sum_{j \in \text{bin}} \sum_{l \in \text{fold} \in \text{bin}} w_{jl}/N}{\sum_{k \in \text{sample}} w_{k}} \equiv \frac{\sum_{j \in \text{bin}} w_{j} p_{j}^{\text{fold}}}{\sum_{k \in \text{sample}} w_{k}}$$

$$\sigma_{i} = \frac{\sqrt{\sum_{j \in \text{bin}} (w_{j} p_{j}^{\text{fold}})^{2}}}{\sum_{k \in \text{sample}} w_{k}}$$



Discrete Flows: transforms

How do we transform the variables? Various ways to do it (as long as the transformation is invertible!)

Each model is made up of multiple conditioner+transformation blocks

This gives us an expressive final transformation with good correlations between variables Affine:

$$\tau(\mathbf{z}_i; \boldsymbol{h}_i) = \alpha_i \mathbf{z}_i + \beta_i$$









Autoregressive flow







Some technical info

FlashSim uses the following packages and tools

- RDataFrame
- numpy
- pytorch
- torchcfm and nflow

Data transfer RDF <--> numpy not yet fully efficient (would benefit from RDF "custom batch process" capabilities)

