

# **Experiences from the CBM collaboration: CAD to ROOT conversion for Detector Geometries**

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# Experimental Setup [1]





### **Tessellation | Meshing**

- Accurately approximate an intricate CAD solid by completely surrounding its surface with a large number of small triangles of varying size
- Almost all CAD software can convert from

# **Two Geometry Worlds**



### Silicon Tracking System [2]





Solution A - VecGeom [4,5]

 $\mathbf{C}$ of a - New CAD designs imported as STP files b - CAD-GDML module on FreeCAD as Status c - GDML support not in FairRoot version d - CATIA-GDML Geometry Builder e - Macros are quickly modified

# Preliminary Comparison

• Runtime comparison using GSI Virgo3 computing cluster, one tessellated volume (beamcross in RICH section) for Solution A & B with 100 URQMD events per job



#### CAD - cut-away





Aim: Model complex C-frame inside acceptance to validate current speed optimised implementation

Ring Imaging Cherenkov [3]		
CAD	ROOT	Beamcross

Aim: Fast assessment of the effect of supporting structure (right) added to traditional ROOT geometry (middle)

- Geometry modeller library (in development) as part of the GEANT V R&D initiative
- Offers traditional functionality for use in GEANT 3 / 4, and ROOT/TGeo
- SIMD support in various flavours (multi-particle API, singleparticle API)
- Collision detection and navigation in complex scenes

CHEP2024 presentation on Monday by Mehul Shiroya discussing VecGeom implementation to mini-CBM 首級法 mini-STS geometry

CHEP2024 presentation on Tuesday by Phat Srimanobhas discussing R&D adoption and process in CMS using VecGeom



CHEP2024 presentation on Tuesday by Severin Diederichs discussing VecGeomm and GPU-friendly surface models

# Solution B - TGeoArbN [6]

- A tessellation tool conceived for the PANDA experiment, being newly developed by University of Bonn

• Ratio of number of conversion vertices with/without beamcross

#### with/without Octree



# Conclusion

- The CBM collaboration continues assessment of its CAD2ROOT methods and procedures.
- In the last two years, these four use cases were trailed and completed by us using these procedures.
- When and how to implement are of importance to the labour saving efforts of the collaboration.

### References

[1] E. Clerkin and P. Dahm, "Recommended SIS100 subsystem positions for simulation of the future CBM experiment at FAIR"

# **Beam Monitoring Assembly**



Has own navigation/propagation functionality and is Geant3 and Geant4 compatible

- TGeoArbN objects behave like other TGeoVolume, allowing easy installation and compilation on top of our existing ROOT, FAIRROOT environments
- Includes functionality for partitioning with Octree
- 3D version of binary decision trees
- Divide geometry in eight smaller cuboids each step
- Stop dividing at given depth or for "empty" volumes

CHEP2024 presentation on Wednesday by Ben Sal-isbury which publicly introduces TGeoArbN for first 直 總 建 time.

CBM Progress Report 2020, pg. 170-172

- [2] O. Singh, et al. "Modelling of simulation geometries using Tessellated Shapes with the Vectorized Geometry (VecGeom) package" CBM Progress Report 2023 pg. 174-175
- S. Neuhaus, C. Pauly, and K.-H. Kampert "New RICH geometry" [3] v24a and first Monte Carlo tests" CBM Progress Report 2023
- J. Apostolakis, et al. "Towards a high performance geometry [4] library for particle-detector simulations." Journal of Physics: Conference Series. Vol. 608. No. 1. IOP Publishing, (2015)
- S. Wenzel, J. Apostolakis, and G. Cosmo "A VecGeom navigator plugin for Geant4" EPJ Web of Conferences 245, 02024
- B. Salisbury, "TGeoArbN" privately communicated with [6] S. Neuhaus, University of Bonn (2024)

Aim: To handle complexity in conversion of complete assembly with multiple detectors











