## Improving Computational Performance of ATLAS GNN Track Reconstruction Pipeline

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#### Track Reconstruction

- Track Reconstruction<br>• In a collision event, generated particles<br>• leave hits in the detector. Track<br>• reconstruction recreates particle<br>• trajectories from detector hits. leave hits in the detector. Track reconstruction recreates particle trajectories from detector hits.
- Track Reconstruction<br>• In a collision event, generated particles<br>leave hits in the detector. Track<br>reconstruction recreates particle<br>trajectories from detector hits.<br>• An expensive process, especially at<br>high pile-up ( $\mu$ Tack Reconstruction<br>
In a collision event, generated particles<br>
leave hits in the detector. Track<br>
reconstruction recreates particle<br>
trajectories from detector hits.<br>
An expensive process, especially at<br>
high pile-up ( $\$ high pile-up ( $\mu$  = 200). HEP community<br>seeks to develop hardware-accelerated, ML-based tracking algorithms. Track Reconstruction<br>
• In a collision event, generated particles<br>
leave hits in the detector. Track<br>
reconstruction recreates particle<br>
trajectories from detector hits.<br>
• An expensive process, especially at<br>
high pile-u
- based on Graph Neural Network (GNN) for track finding under HL-LHC



## The GNN4ITk Reconstruction Pipeline The GNN4ITk Reconstruction Pipeline



## The GNN4ITk Reconstruction Pipeline<sup>2</sup>





#### GNN4ITk for Track Reconstruction Goals

- **GNN4ITK for Track Reconstruction Goals**<br>• The main goal is to optimize the GNN4ITk pipeline. To increase throughput,<br>decrease **latency**, and reduce **memory usage** in the context of Offline & Online<br>track reconstruction f track reconstruction for the High-Luminosity Large Hadron Collider (HL-LHC).
- Acceleration: Implementing computing optimization techniques using GPUs (Graphics Processing Units) or FPGAs (Field-Programmable Gate Arrays) to accelerate the execution of the stages in the pipeline.
- Memory Optimization: Efficiently managing memory usage by optimizing data structures to minimize the memory footprint.
- Algorithmic Efficiency: Developing and refining algorithms that reduce computational complexity to maintain accuracy while lowering the number of computations. Experience interview and track reconstruction for the High-Luminosity Large Hadron Collider (HL-LHC).<br>
• Acceleration: Implementing computing optimization techniques using GPUs<br>
• Calceleration: Implementing computing opti



• Using ATLAS simulation event samples (10,000 events): mulation Data - CTD 202<br>
Using ATLAS simulation event<br>
samples (10,000 events):<br>  $\frac{1}{2}$ <br>  $\frac{1}{2}$ 



- distribution of passive material with greater detail and accuracy)
- Target particles (dominated by soft interactions): Using ATLAS simulation event<br>
samples (10,000 events):<br>  $pp$  collisions at  $\sqrt{s} = 14$  TeV,  $t\bar{t}$  process,<br>  $\langle \mu \rangle = 200$   $pp$  interaction pileup<br>
Updated ITk layout 23-00-03 (reduced radius of innermost pixel layer, and Only primary particles (including B hadron decays, without "secondary" Geant4 particles from material interactions) Samples (10,000 events):<br>
pp collisions at  $\sqrt{s} = 14 \text{ TeV}$ ,  $\vec{t}$  process,<br>  $\langle \mu \rangle = 200 \text{ pp}$  interaction pileup<br> **11**<br> **11**<br>

#### Physics Performance



Track reconstruction efficiency as a function of the generator-level pseudorapidity  $\eta$  (a) and  $p_{\tau}$  (b)

CFK is the current reconstruction method using combinatorial Kalman Filter algorithm

ATLAS Collaboration, IDTR-2023-06, October 2023 (link)

#### Computing Performance

![](_page_7_Picture_69.jpeg)

Stage 3 is evaluated on CPU (AMD EPYC 7763).

# Computing Optimizations of the GNN4ITk Reconstruction Pipeline COMPUTING UPTIMIZATIONS OT THE<br>
GNN4ITk Reconstruction<br>
Craph Construction<br>
GNN Inference and Architecture Optimizations<br>
Graph Segmentation<br>
Inference As a Service (laaS)<br>
CHEP 2024

Graph Construction GNN Inference and Architecture Optimizations Graph Segmentation Inference As a Service (IaaS)

![](_page_9_Picture_0.jpeg)

![](_page_9_Figure_1.jpeg)

#### Current timing around 69 ms on an Nvidia A100 GPU (140x speedup)

Christophe Collard @CHEP2024

## GNN for Edge Classification

- 1. Encode nodes and edge features.
- 2. Aggregate edge vectors, acting as messages between nodes.
- 3. Update node features with aggregated  $\sum_{v_{3}^{k}}$ messages. Update edge features using updated node features.
- 4. Repeat n times steps 2 and 3.
- 5. Compute an edge score representing the probability of being a true edge.

![](_page_10_Picture_6.jpeg)

![](_page_11_Picture_0.jpeg)

#### Computing Optimizations for the GNN of the Module Map Pipeline

![](_page_11_Figure_2.jpeg)

- the GNN timing to around 322 ms
- **Or the SATLAS**<br> **Deline SERV**<br> **A variety of improvements have brought**<br>
the GNN timing to around 322 ms<br>
 Average running time over 1,000 events,<br>
evaluated on a Nyidia A100 40 GB GPU,<br>
CIJDA 12.1 in stable release of Or the **ATLAS**<br>
Deline **Average running to around 322 ms**<br>
Average running to around 322 ms<br>
Average running time over 1,000 events,<br>
evaluated on a Nyidia A100 40 GB GPU,<br>
CUDA 12.1, the stable release of PyTorch 2.3 and evaluated on a Nvidia A100 40 GB GPU, CUDA 12.1, the stable release of The **Participal Property of Starture 1.1 and PyG 2.5.**<br>A variety of improvements have brought<br>the GNN timing to around 322 ms<br>Average running time over 1,000 events,<br>evaluated on a Nvidia A100 40 GB GPU,<br>CUDA 12.1, the sta ● A variety of improvements have brought<br>
• A variety of improvements have brought<br>
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CUDA 12.1, the stable release of<br>
PyTorch 2.3 and PyG 2.5
- on a Nvidia A100 80 GB GPU, PyTorch

![](_page_12_Picture_0.jpeg)

## Computing Optimizations for the GNN Pipeline ~ Work in Progress Computing Optimizations for the SATLAS<br>GNN Pipeline ~ Work in Progress<br>GNN Model Reduction Knowledge Distillation

![](_page_12_Figure_4.jpeg)

![](_page_12_Figure_5.jpeg)

![](_page_13_Picture_0.jpeg)

### Track Building

- Track Building<br>• 2-step sequence: connected<br>• components (CC) and walkthrough:<br>• 1. Use CC to isolate subgraphs with no components (CC) and walkthrough: 1. Use CC to isolate subgraphs with no<br>
2. On subgraphs with branching.<br>
Walkthrough:<br>
2. On subgraphs with branching, use a<br>
walkthrough to separate track
	- branching.
	- 2. On subgraphs with branching, and walkthrough:<br>
	2. On subgraphs with branching, use a<br>
	2. On subgraphs with branching, use a<br>  $\frac{\text{CDD:}}{\text{CDD:}}$ <br>
	walkthrough to separate track<br>
	candidates. walkthrough to separate track candidates.
- extract track parameters by a track fit and match to generator-level particles for physics performance evaluation. 1. Use CC to isolate subgraphs with no<br>
branching.<br>
2. On subgraphs with branching, use a<br>
walkthrough b separate track<br>
candidates.<br>
• Each track candidate is a list of hits  $\rightarrow$  connected Components<br>
extract track param

Daniel Murnane @CHEP2024

![](_page_13_Picture_111.jpeg)

![](_page_13_Figure_8.jpeg)

![](_page_13_Figure_9.jpeg)

14

![](_page_14_Picture_0.jpeg)

![](_page_14_Figure_2.jpeg)

![](_page_15_Picture_0.jpeg)

# Computing Optimizations Summary Computing Optimizations Summary<br>
Starborship Construction with Module Map - 140x speedup<br>
Starborship - Automatic Mixed Precision (AMP) - 1.5x speedup<br>
Automatic Mixed Precision (AMP) - 1.5x speedup Mexical Construction with Module Map - 140x speedup<br>
Straph Construction with Module Map - 140x speedup<br>
SNN:<br>
• Automatic Mixed Precision (AMP) → 1.5x speedup<br>
• torch.compile() → 1.3x speedup<br>
• MMP + torch.compile() + **Imputing Optimizations 9**<br>
Sraph Construction with Module Map - 140x sp<br>
SNN:<br>
• Automatic Mixed Precision (AMP)  $\rightarrow$  1.5x speedup<br>
• torch.compile()  $\rightarrow$  1.3x speedup<br>
• AMP + torch.compile()  $\rightarrow$  3.2x speedup<br>
• New ve

- Fraph Construction with Module Map 140x speedup<br>
FRIN:<br>
Automatic Mixed Precision (AMP) → 1.5x speedup<br>
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 New version of torch.compile() from PyT Graph Construction with Module Map - 140x speedup<br>
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- New version of torch.compile() from P
- **∻ GNN:** 
	- Automatic Mixed Precision (AMP)  $\rightarrow$  1.5x speedup
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	-
	- Nvidia A100 80 GB GPU
	-
- **\*** Track Building:
	-
	-
- → Graph Construction with Module Map 140x speedup<br>
→ GNN:<br>
→ Automatic Mixed Precision (AMP) → 1.5x speedup<br>
→ torch.compile() → 1.3x speedup<br>
→ MMP + torch.compile() → 3.2x speedup<br>
→ MMP + torch.compile() from PyTorc 11. Automatic Mixed Precision (AMP) → 1.5x speedup<br>
• torch.compile() → 1.3x speedup<br>
• AMP + torch.compile() → 3.2x speedup<br>
• New version of torch.compile() from PyTorch 2.5<br>
• Nividia A100 80 GB GPU<br>
• Total - 5x spee

![](_page_16_Picture_0.jpeg)

#### Conclusions

- CONCLUSIONS<br>• We have demonstrated that GNN4ITk is a viable algorithm for HL-LHC tracking<br>• Physics performance comparable with CKF, run @ ≳10 evts/s on A100<br>• Focus on decreasing latency, and reducing the memory usage
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- 
- **CONCLUSIONS**<br>• We have demonstrated that GNN4ITk is a viable algorithm for HL-LHC tracking<br>• Physics performance comparable with CKF, run @ ≳10 evts/s on A100<br>• Focus on decreasing latency, and reducing the memory usage<br>
- **CONCIUSIONS**<br>• We have demonstrated that GNN4ITk is a viable algorithm for HL-LHC tracking<br>• Physics performance comparable with CKF, run @ ≳10 evts/s on A100<br>• Focus on decreasing latency, and reducing the memory usage<br>• • Reducing the other steps of our pipeline, including the Metric Learning models<br>• Physics performance comparable with CKF, run @ ≳10 evts/s on A100<br>• Focus on decreasing latency, and reducing the memory usage<br>• Leveraged their physics performance • We have demonstrated that GNN4ITk is a viable algorithm for HL-LHC tracking<br>• Physics performance comparable with CKF, run  $@ \ge 10$  evts/s on A100<br>• Focus on decreasing latency, and reducing the memory usage<br>• Leveraged • Physics performance comparable with CKF, run  $@ \ge 10$  evts/s on A100<br>• Focus on decreasing latency, and reducing the memory usage<br>• Leveraged acceleration techniques for the GPU, such as AMP and torch\_compil<br>• Reducing
- 

![](_page_17_Picture_0.jpeg)

- High Performance Graph Segmentation for ATLAS GNN Track Reconstruction by Daniel T. Murnane
- EggNet: An Evolving Graph-based Graph Attention Network for End-to-end Particle Track Recontruction by Jay Chan
- Energy-efficient graph-based algorithm for tracking at the HL-LHC by Heberth Torres
- New approaches for fast and efficient graph construction on CPU, GPU and heterogeneous architectures for the ATLAS event reconstruction by Christophe Collard (poster) Energy-efficient graph-based algorithm for tracking at the HL-LHC by Heberth Torres<br>
New approaches for fast and efficient graph construction on CPU, GPU and heterogeneous architectures for the ATLAS<br>
event reconstruction
- AthenaTriton: A Tool for running Machine Learning Inference as a Service in Athena by Yuan-Tang Chou
- Machine Learning Inference in Athena with ONNXRuntime by Xiangyang Ju
- Performance of the ATLAS GNN4ITk Particle Track Reconstruction GPU pipeline by Aleksandra Poreba (poster)
- Online track reconstruction with graph neural networks on FPGAs for the ATLAS experiment by Sebastian Dittmeier

# The End

Thank you!

# Back-up  $\textsf{Back-up}\ \textsf{\tiny CHEP2024}\ \textsf{\tiny CHEP2024}\ \textsf{\tiny CHEP2024}\ \textsf{\tiny ZD}\ \textsf{\tiny CHEP2024}$

![](_page_20_Picture_0.jpeg)

#### GNN Architecture Optimizations

![](_page_20_Figure_2.jpeg)