



A new SymPy backend for Vector: uniting experimental and theoretical physicists



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Vector

A Python library for JIT-compilable mathematical manipulations of Lorentz vectors, especially arrays of vectors, in a NumPy-like way.

```
vector.MomentumObject4D(pt=0.3, phi=0.5, eta=3.3, m=0.1)
Pure Python Objects
```

```
vector.VectorNumpy4D(
{
"x": [1.1, 1.2, 1.3, 1.4, 1.5],
"y": [2.1, 2.2, 2.3, 2.4, 2.5],
"z": [3.1, 3.2, 3.3, 3.4, 3.5],
"t": [4.1, 4.2, 4.3, 4.4, 4.5],
})
```

NumPy arrays

```
vector.Array(
[
["x": 1, "y": 1.1, "z": 0.1],
["x": 2, "y": 2.2, "z": 0.2]
],
[],
[["x": 3, "y": 3.3, "z": 0.3]],
[
["x": 4, "y": 4.4, "z": 0.4],
["x": 5, "y": 5.5, "z": 0.5],
["x": 6, "y": 6.6, "z": 0.6],
],
)
```

Awkward arrays

12 coordinate systems - cartesian, cylindrical, pseudorapidity, and any combination of these with time or proper time for 4D vectors.

```
v1.to_4D().like(v2).boost(v3).deltaR(v4).px
v1.rotate_axis(...).rotate_euler(...).transform4D(...)
```

Same API for every type of vector

Uses conventions set up by ROOT's TLorentzVector and Math::LorentzVector.

Integrations

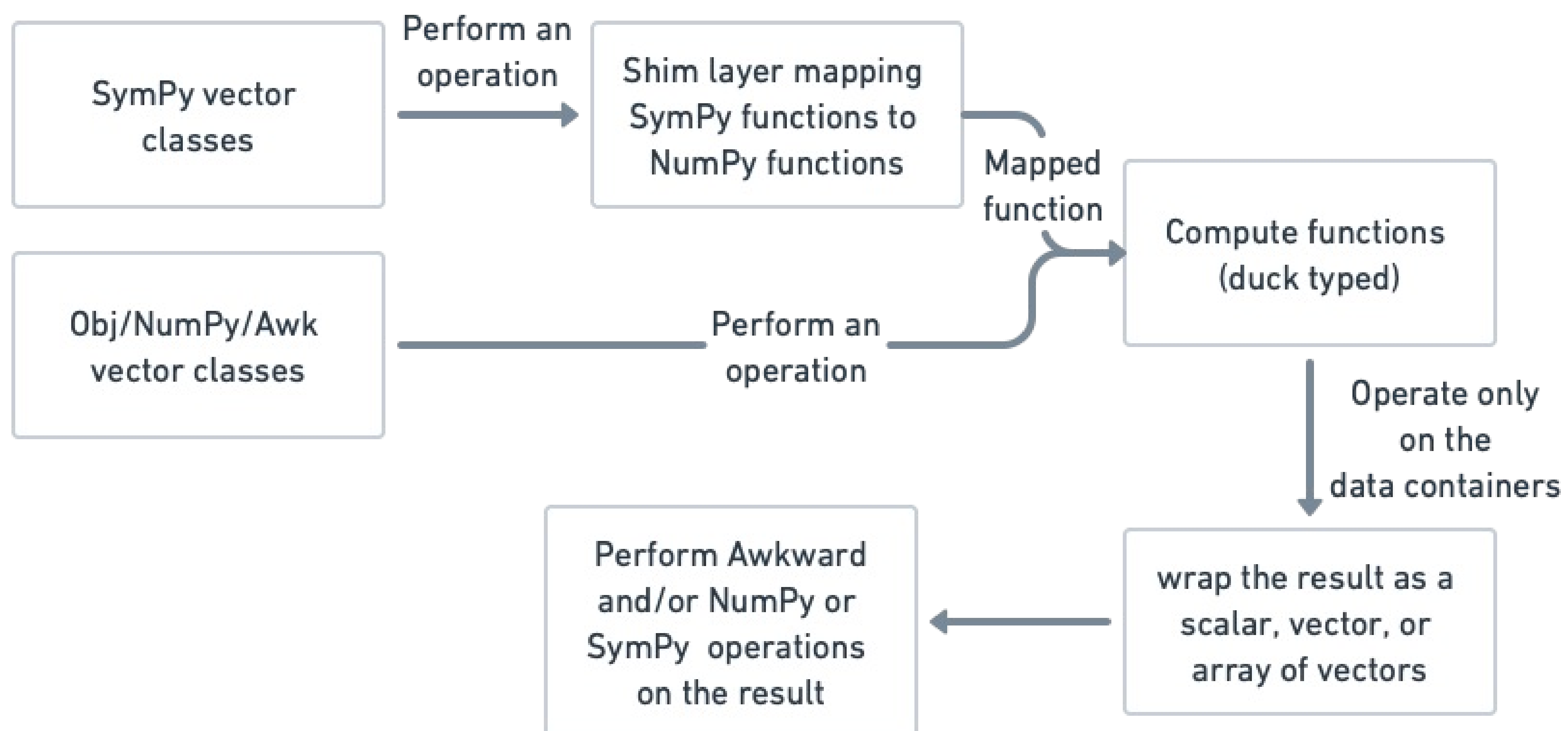


Motivation

Symbolic computations are useful for theorists; now the same library can be used by both experimentalists and theorists.

A SymPy backend is a very different kind of backend because it's not numerical. We wanted to show that Vector is generic enough to support such far-flung use-cases.

Architecture



Results

```
v = vector.MomentumObject(pt=1, phi=2, eta=3, M=4)
v.boost(v.to_beta3()).px
np.float64(-2.2540970733043526)
```

Computations on Object type vectors

```
pt, phi, eta, M = sympy.symbols("pt phi eta M")
v = vector.MomentumSymPy4D(pt=pt, phi=phi, eta=eta, M=M)
```

Sympy vector classes as drop-in replacement

```
v.boost(v.to_beta3()).px
```

$$\left(1 + \frac{pt^2 \sin^2(\phi) \cos(\phi)}{\sqrt{\frac{pt^2 \sin^2(\phi)}{M^2 + 0.25pt^2(1+e^{-2\eta})^2} + 1}}\right) (M^2 + 0.25pt^2(1+e^{-2\eta})^2) \left(-\frac{pt^2 \cos(\phi)}{M^2 + 0.25pt^2(1+e^{-2\eta})^2} - \frac{pt^2 \sin^2(\eta)}{M^2 + 0.25pt^2(1+e^{-2\eta})^2} + 1\right) \left(1 + \frac{pt^2 \sin^2(\eta)}{M^2 + 0.25pt^2(1+e^{-2\eta})^2}\right) \dots$$

Symbolic calculations with the same API

```
v.boost(v.to_beta3()).px.simplify()
```

$$pt \left(1.0M^2 \sqrt{(M^2 e^{2\eta} + 0.25pt^2 e^{4\eta} + 0.5pt^2 e^{2\eta} + 0.25pt^2) e^{-2\eta} e^{2\eta} + 0.25pt^2} \sqrt{(M^2 e^{2\eta} + 0.25pt^2 e^{4\eta} + 0.5pt^2 e^{2\eta} + 0.25pt^2) e^{-2\eta} e^{2\eta} + 0.25pt^2} \sqrt{(M^2 e^{2\eta} + 0.25pt^2 e^{4\eta} + 0.5pt^2 e^{2\eta} + 0.25pt^2) e^{-2\eta} e^{2\eta} + 0.25pt^2} \dots\right)$$

Results compatible with SymPy functions and methods

```
v.boost(v.to_beta3()).px.subs({"pt": 1, "phi": 2, "eta": 3, "M": 4})
```

$$\frac{\sqrt{\cos^2(2) + \sin^2(2) + 16 + \sinh^2(3) \cos(2)}}{\sqrt{1 + 0.015625(e^{-6} + 1)^2 e^6} \sqrt{\frac{\sinh^2(3)}{16 + 0.25(e^{-4} + 1)^2 e^6} - \frac{\sin^2(2)}{16 + 0.25(e^{-4} + 1)^2 e^6} - \frac{\cos^2(2)}{16 + 0.25(e^{-4} + 1)^2 e^6} + 1}} + \frac{\cos(2) \sinh^2(3)}{\left(1 + \frac{1}{\sqrt{\frac{\sinh^2(3)}{16 + 0.25(e^{-4} + 1)^2 e^6} - \frac{\sin^2(2)}{16 + 0.25(e^{-4} + 1)^2 e^6} - \frac{\cos^2(2)}{16 + 0.25(e^{-4} + 1)^2 e^6} + 1}}\right) (16 + 0.25(e^{-6} + 1)^2 e^6) \left(-\frac{\sinh^2(3)}{16 + 0.25(e^{-4} + 1)^2 e^6}\right) \dots$$

Use any SymPy functionality on the expressions

```
v.boost(v.to_beta3()).px.subs({...}).evalf()
-2.25409707330435
```

Evaluated results consistent with numerical backends

Caveats

