

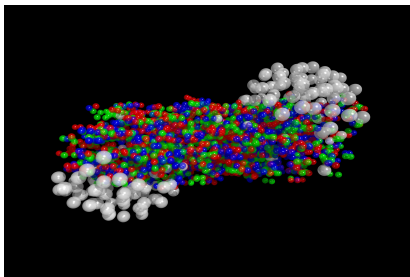
# Quantifying the degree of hydrodynamic behaviour in heavy-ion collisions

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Sören Schlichting

based on: PRD 107, 094013  
PRL 130, 152301  
and WiP

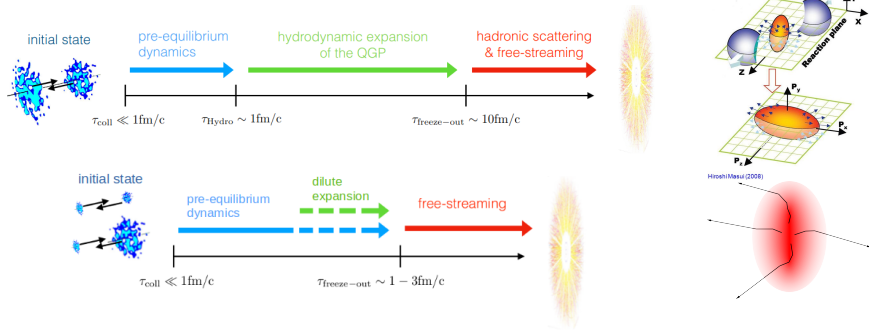


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# Dynamical modelling in small vs. large systems



- large systems: dominated by hydrodynamic QGP, leaves imprints of thermalization and collectivity in final state observables:  
 $\mathbf{v}_n$ ,  $\langle p_T \rangle$ , particle yields, ...
- small systems: might not fully equilibrate  $\Rightarrow$  applicability of hydro unclear
- kinetic theory can describe off-equilibrium systems, applicable to free-streaming and hydrodynamic systems  $\Rightarrow$  in comparison to hydrodynamics, can discern where it is accurate

# Applicability of hydrodynamics in terms of opacity

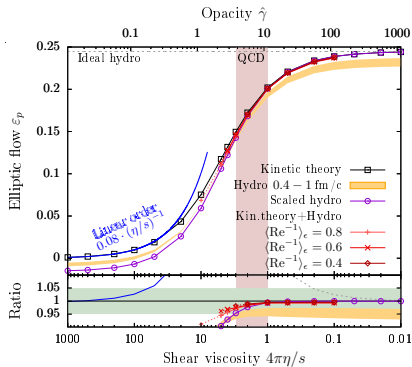
previous study: in kinetic theory + hydro simulations, results for flow observables accurate on 5% level if opacity  $\hat{\gamma} \gtrsim 3$   
 $\hat{\equiv}$  central O+O

Ambruş, Schlichting, Werthmann PRD 107 (2023) 094013

and PRL 130 (2023) 152301

problem: Flow results from dynamical response to initial state geometry, which is poorly constrained in small systems

$$v_n = \kappa_{n,n} \cdot \epsilon_n$$



## New Aim

- find observables that untangle effects of response and geometry on flow
- look for model-independent quantification of hydrodynamicity
- verify these in event-by-event simulations

# Model and Setup: Kinetic Theory

- microscopic description in terms of averaged on-shell phase-space distribution of massless bosons:

$$f(\tau, \mathbf{x}_\perp, \eta, \mathbf{p}_\perp, y) = \frac{(2\pi)^3}{\nu_{\text{eff}}} \frac{dN}{d^3x d^3p}(\tau, \mathbf{x}_\perp, \eta, \mathbf{p}_\perp, y)$$

- boost invariance
- initialized with vanishing longitudinal pressure and no transverse momentum anisotropies
- time evolution: Boltzmann equation in conformal relaxation time approximation

$$p^\mu \partial_\mu f = C_{\text{RTA}}[f] = -\frac{p^\mu u_\mu}{\tau_R} (f - f_{\text{eq}}), \quad \tau_R = 5 \frac{\eta}{s} T^{-1}$$

results will depend only on initial state and opacity

- dimensionless parameter: opacity  $\sim$  “total interaction rate”

Kurkela, Wiedemann, Wu EPJC 79 (2019) 965

$$\hat{\gamma} = \left(5 \frac{\eta}{s}\right)^{-1} \left(\frac{1}{a\pi} R \frac{dE_\perp^{(0)}}{d\eta}\right)^{1/4}$$

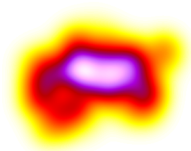
- encodes dependencies on **viscosity**, **transverse size** and **energy scale**

# Initial conditions

- initial conditions with event-by-event fluctuations (TRENTO model)  
Moreland, Bernhard, Bass PRC 92 (2015) 011901(R)
- pre-generated nucleon positions to account for correlations like  $\alpha$ -clustering
- reasons for O+O:
  - intermediate system size ( $\hat{\gamma} \sim 3$ )
  - same collision system ran at RHIC and LHC for the first time!

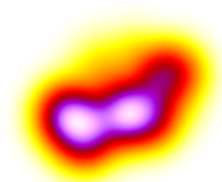
Pb+Pb 2.76 TeV

Alvioli, Drescher, Strikman PLB 680 (2009) 225



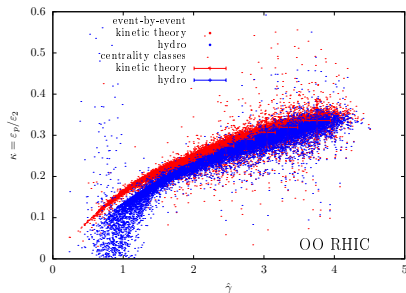
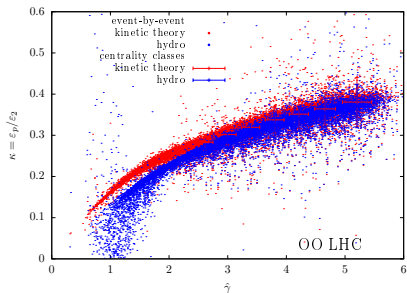
O+O 7 TeV

Loizides, Nagle, Steinberg SoftwareX 1-2 (2015) 13



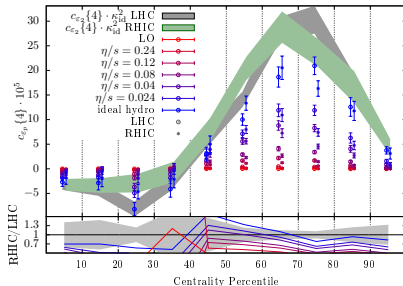
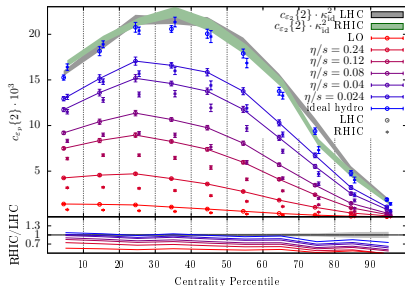
(example profiles from 20-30% centrality class)

# Event-by-event flow responses



- main difference between RHIC and LHC is energy scale
- variation in geometry introduces spread of flow response
- still mostly depends on  $\hat{\gamma}$  with  $\varepsilon_p^{\text{hydro}} \nearrow \varepsilon_p^{\text{RTA}}$  as before

# Flow cumulants in O+O



- larger opacity: larger magnitude of flow response and better agreement between RHIC and LHC
- centrality dependence of  $\kappa(\hat{\gamma})$  introduces modulation
- flow fluct. dominated by avg. response to geometry fluct.

$$\langle (\epsilon_p)^n \rangle = \langle (\kappa \epsilon_2)^n \rangle = \bar{\kappa}^n \langle (\epsilon_2)^n \rangle + \dots$$

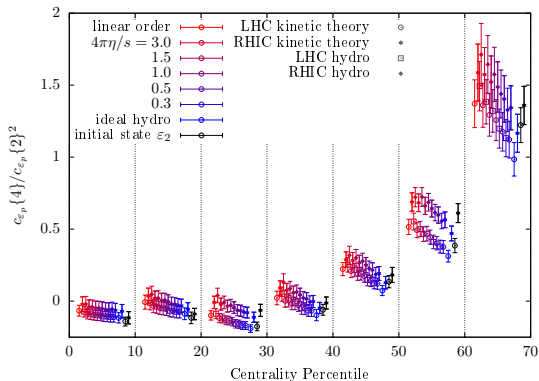
# Cumulant ratios probe geometry

If  $\langle(\epsilon_p)^n\rangle \approx \bar{\kappa}^n \langle(\epsilon_2)^n\rangle$ , then  $\bar{\kappa}$  cancels in ratios:

$$\frac{c_{\epsilon_p}\{4\}}{c_{\epsilon_p}\{2\}^2} = \frac{\langle(\epsilon_p)^4\rangle - 2\langle(\epsilon_p)^2\rangle^2}{\langle(\epsilon_p)^2\rangle^2} \approx \frac{\langle(\epsilon_2)^4\rangle - 2\langle(\epsilon_2)^2\rangle^2}{\langle(\epsilon_2)^2\rangle^2} = \frac{c_{\epsilon_2}\{4\}}{c_{\epsilon_2}\{2\}^2}$$

$\Rightarrow$  ratio sensitive mostly to geometry

Giacalone, Yan, Noronha-Hostler, Ollitrault PRC 95 (2017) 1, 014913





## Hydrodynamization observable: definition

- cancel geometry: comparing systems with same geometry (and same  $\eta/s$ ):

$$\frac{c_2^{\text{RHIC}}\{2k\}}{c_2^{\text{LHC}}\{2k\}} \approx \frac{\bar{\kappa}_{\text{RHIC}}^{2k}}{\bar{\kappa}_{\text{LHC}}^{2k}} \quad \frac{\hat{\gamma}_{\text{RHIC}}}{\hat{\gamma}_{\text{LHC}}} = \left( \frac{\frac{dE_{\perp}}{d\eta}_{\text{RHIC}}}{\frac{dE_{\perp}}{d\eta}_{\text{LHC}}} \right)^{1/4}$$

- use logarithm to turn ratios into differences:

hydrodynamization observable

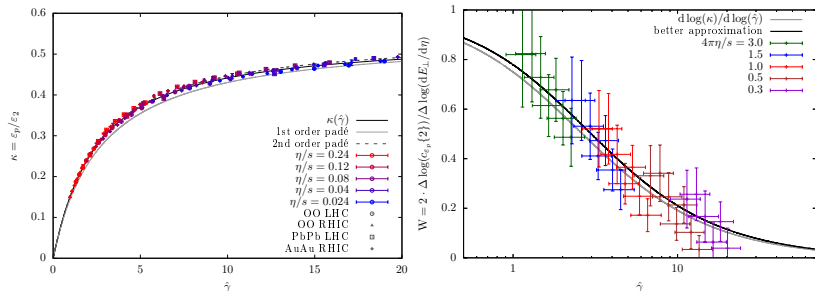
$$W = \frac{2}{k} \frac{\Delta \log(c_2\{2k\})}{\Delta \log(dE_{\perp}/dy)} \approx \frac{d \log \kappa}{d \log \hat{\gamma}}$$

- small  $\hat{\gamma}$ : linear buildup,  $\frac{d \log \kappa}{d \log \hat{\gamma}} \lesssim 1$   
large  $\hat{\gamma}$ : saturation,  $\frac{d \log \kappa}{d \log \hat{\gamma}} \rightarrow 0$

# Hydrodynamization observable: Proof of principle

crosscheck of  $W$ -observable:

1. extract  $\kappa(\hat{\gamma})$  from fit to simulation results
2. compute  $\frac{d \log \kappa}{d \log \hat{\gamma}}$ : smooth monotonous transition from 1 to 0
3. compare with simulation data for  $W$ -observable: agreement!

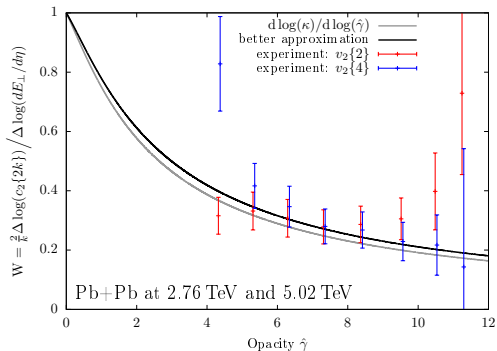


previous hydrodynamization criterion

$\hat{\gamma} \sim 3$  corresponds to  $W \sim 0.5$

## Hydrodynamization observable: real data

- first test with LHC data: results agree with theory ( $\hat{\gamma}$  from Trento initial conditions,  $\eta/s$  chosen s.t. flow matches)



- centrality dependence off for  $v_2\{2\}$  (nonflow?), but accurate for  $v_2\{4\}$

- applicability of hydrodynamics can be assessed by comparing to kinetic theory, but uncertainties in initial state obscure results
- effects of initial state and dynamical response on flow can be untangled using appropriate observables:
  - cumulant ratios for initial state geometry
  - $W$ -observable for hydrodynamization via slope of flow response curve

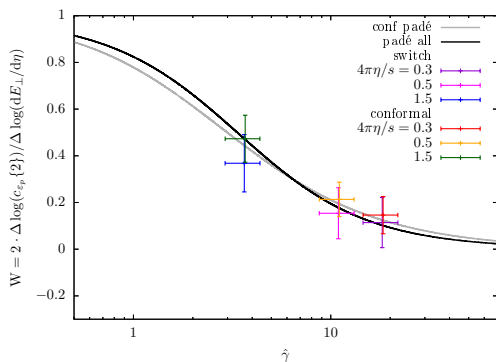
$$W = \frac{2}{k} \frac{\Delta \log(c_2\{2k\})}{\Delta \log(dE_{\perp}/dy)} \approx \frac{d \log \kappa}{d \log \hat{\gamma}}$$

- verified discriminative power in event-by-event simulations
- criterion for hydrodynamic behaviour in experiment:  $W \lesssim 0.5$

**Backup**

# Non-conformal effects

- probing non-conformal effects in hydro simulations with chiral eos
  - losing theoretical control over setup
- might need to adjust calibration curve; at the very least still applicable for mid-central collisions at  $\hat{\gamma} \gtrsim 4$



# Hydrodynamics in real collision systems

Taking the criterion of  $\hat{\gamma} \gtrsim 3$  seriously, what does this mean for the applicability of hydrodynamics to “real-life” collisions?

$$\text{Pb} + \text{Pb} : \hat{\gamma} \sim 5.7 \left(\frac{\eta/s}{0.16}\right)^{-1} \left(\frac{R}{2.78 \text{ fm}}\right)^{1/4} \left(\frac{dE_{\perp}^{(0)}/d\eta}{1280 \text{ GeV}}\right)^{1/4} \sim \begin{matrix} 70-80\% & 0-5\% \\ 2.7 & - & 9.0 \end{matrix}$$

hydrodynamic behaviour in all but peripheral collisions

$$\text{O} + \text{O} : \hat{\gamma} \sim 2.2 \left(\frac{\eta/s}{0.16}\right)^{-1} \left(\frac{R}{1.13 \text{ fm}}\right)^{1/4} \left(\frac{dE_{\perp}^{(0)}/d\eta}{55 \text{ GeV}}\right)^{1/4} \sim \begin{matrix} 70-80\% & 0-5\% \\ 1.4 & - & 3.1 \end{matrix}$$

probes transition region to hydrodynamic behaviour

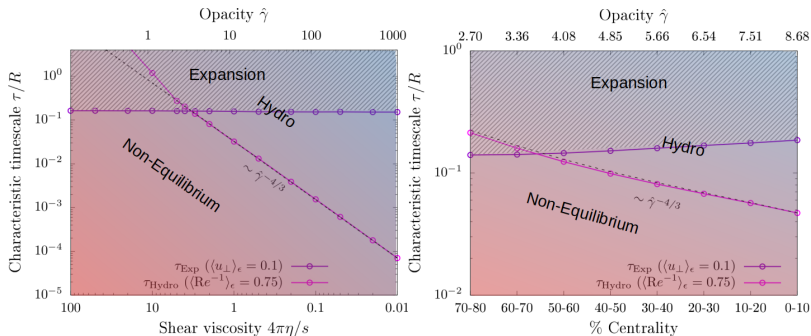
$$\text{p} + \text{Pb} : \hat{\gamma} \sim 1.5 \left(\frac{\eta/s}{0.16}\right)^{-1} \left(\frac{R}{0.81 \text{ fm}}\right)^{1/4} \left(\frac{dE_{\perp}^{(0)}/d\eta}{24 \text{ GeV}}\right)^{1/4} \begin{matrix} \text{high mult.} \\ \lesssim 2.7 \end{matrix}$$

very high multiplicity events approach regime of applicability, but do not reach it

$$\text{p} + \text{p} : \hat{\gamma} \sim 0.7 \left(\frac{\eta/s}{0.16}\right)^{-1} \left(\frac{R}{0.12 \text{ fm}}\right)^{1/4} \left(\frac{dE_{\perp}^{(0)}/d\eta}{7.1 \text{ GeV}}\right)^{1/4}$$

far from hydrodynamic behaviour

# Hydrodynamization in viscosity and centrality dependence



- transverse expansion sets in at  $\tau_{\perp} \sim 0.2R$ , independent of opacity
- Hydro applicable when  $\text{Re}^{-1} < \text{Re}_c^{-1} \sim 0.75$  after timescale

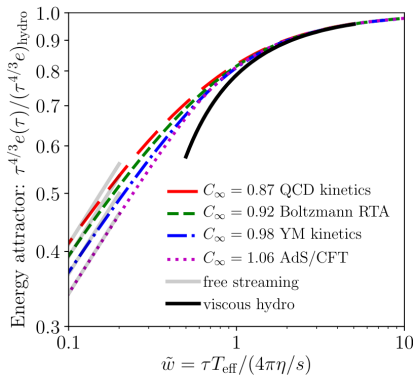
$$\tau_{\text{Hydro}}/R \approx 1.53 \hat{\gamma}^{-4/3} \left[ (\text{Re}_c^{-1})^{-3/2} - 1.21(\text{Re}_c^{-1})^{0.7} \right]$$

- hydrodynamization before transv. Expansion for  $\hat{\gamma} \gtrsim 3$



## What might happen when going beyond RTA?

- more complex kernels will introduce further parameter dependence, but opacity dependence might still be "leading order approximation"
- in Bjorken flow, equilibration happens in very similar ways across different model descriptions:



Giacalone, Mazeliauskas, Schlichting, PRL 123 (2019) 262301

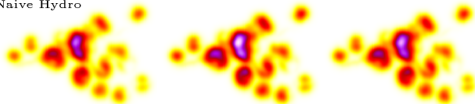
# Model and Setup: Hydrodynamics

- 2nd order Müller-Israel-Steward type hydrodynamics (vHLLE) with RTA transport coefficients

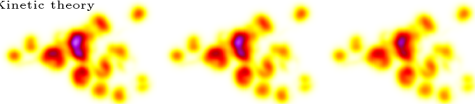
Karpenko, Huovinen, Bleicher *Comput. Phys. Commun.* 185, 3016 (2014)

- How to define initial state? Hydro deviates at early times!

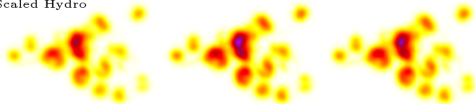
Naive Hydro



Kinetic theory



Scaled Hydro



$$\tau = 3 \cdot 10^{-6} \text{ fm}/c$$

$$\tau = 6 \cdot 10^{-4} \text{ fm}/c$$

$$\tau = 3 \cdot 10^{-3} \text{ fm}/c$$

- solution: hydro initial condition scaled according to attractor curve prediction of early time behaviour

Ambuș, Schlichting, Werthmann *PRD* 107 (2023) 094013

# Initializing on the attractor

- accuracy depends on timescale separation of pre-equilibrium and transv. expansion

