

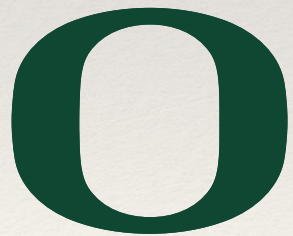
CALOR 2024
Tsukuba



May 20, 2024

The SiD Digital ECal Based on Monolithic Active Pixel Sensors

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University of
Oregon



UNIVERSITY OF
OREGON

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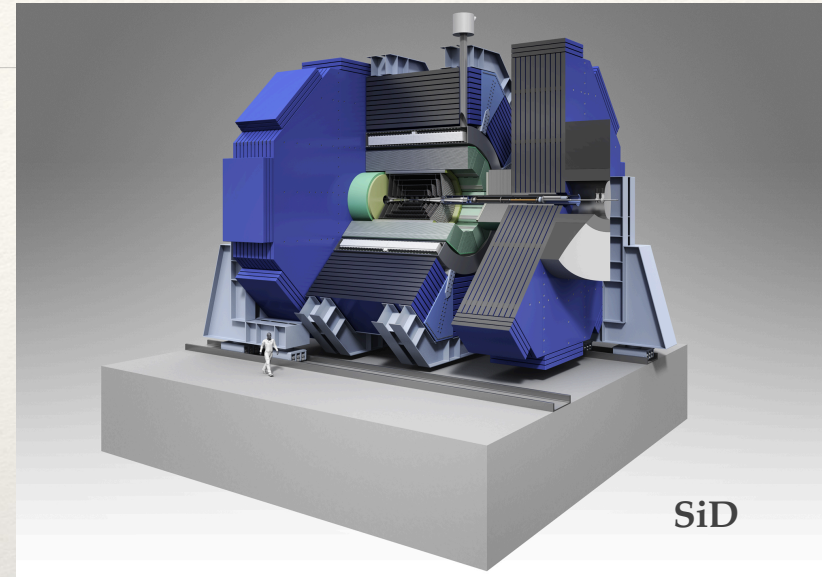
on behalf of
the SiD MAPS Collaboration
(M. Breidenbach, A.Habib,
L. Rota, M. Vassilev, C.Vernieri,
J.B. et al.)

"The SiD Digital ECal Based on Monolithic Active Pixel Sensors",
10.3390/instruments6040051, Instruments, 6, 51 (2022)



SiD Digital ECal Based on MAPS

- ❖ SiD upgrade now under development with $25 \times 100 \mu\text{m}^2$ (or $25 \times 50 \mu\text{m}^2$) digital pixels in electromagnetic calorimeter and tracker.
 - ❖ Replacing the ILC TDR ECal design using 13 mm^2 analog pixel sensors.
- ❖ How well can we measure energy and shower structure with this digital system:
 - ❖ Compared to SiD baseline with analog measurements?
 - ❖ Can the detailed structural measurements be used to improve measurement?
 - ❖ Would a neural net optimization offer an improvement?
- ❖ What are the limits of transverse separation and measurement?



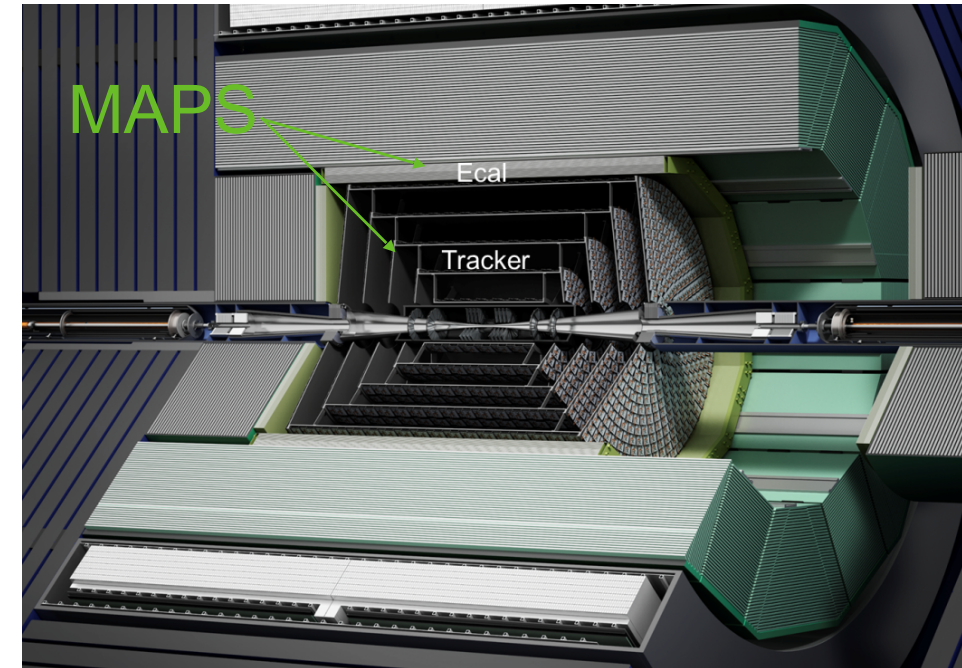
Large area MAPS for SiD tracker & ECal

Benefits of large-area MAPS:

- Standard CMOS foundry, low resistivity: **cost** ↓
- Sensing element and readout electronics on same die
 - In-pixel amplification: **noise** ↓, **power** ↓
 - No need for bump-bonding: **cost** ↓
- Area > **5x20** cm² → enable O(1) m² modules

Several design challenges:

- Large on-die variations, mismatch
- Yield
- Stitching layout rules
- Distribution of power supply
- Distribution of global control signals/references



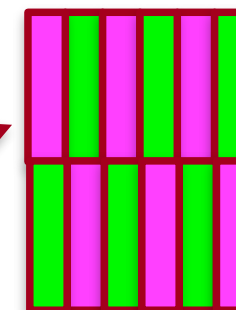
An example of the SiD Tracker and the ECal overall design

Goals of R&D: find solutions and explore novel design techniques

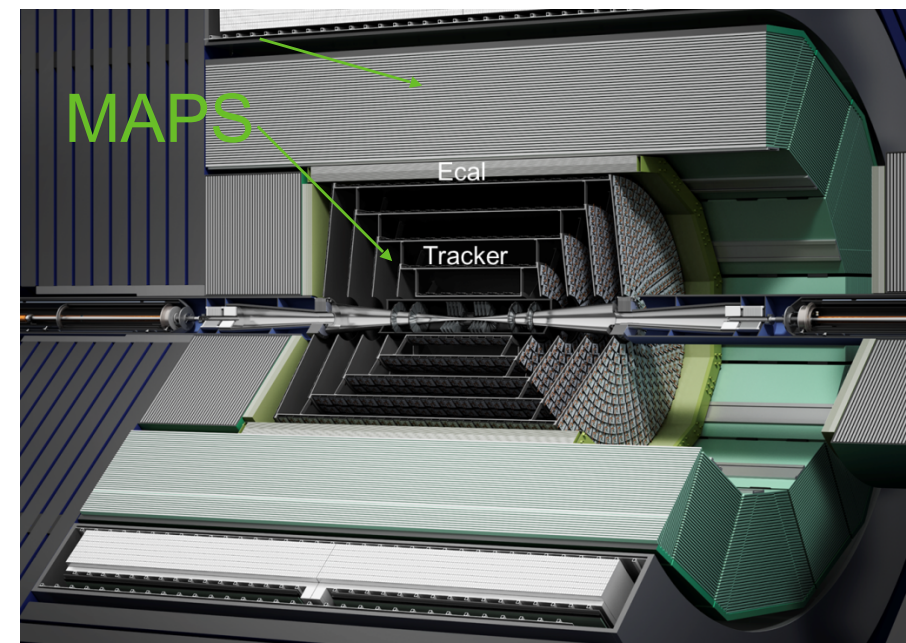
Main specifications for Large Area MAPS development

L. Rota

Parameter	Value	Notes
Min Threshold	140 e ⁻	0.25*MIP with 10 μm thick epi layer
Spatial resolution	7 μm	In bend plane, based on SiD tracker specs
Pixel size	25 x 100 μm ²	Optimized for tracking (or 25 x 50 μm ²)
Chip size	5 x 20 cm ²	Requires stitching on 4 sides
Chip thickness	300 μm	<200 μm for tracker. Could be 300 μm for ECal to improve yield.
Timing resolution (pixel)	~ ns	Bunch spacing: C ³ strictest with 5.3->3.5 ns; ILC is 554 ns
Total Ionizing Dose	100 kRads	Total lifetime dose, not a concern
Hit density / train	1000 hits / cm ²	
Hits spatial distribution	Clusters	Due to jets
Balcony size	1 mm	Only on one side, where wire-bonding pads will be located.
Power density	20 mW / cm ²	Based on SiD tracker power consumption: 400W over 67m ²



25 x 100 μm²
ECal performance same as 50 x 50 μm²



SiD Tracker and the ECal

<1 mW/cm²
for 1% duty cycle

Large Area MAPS - Highlights and Next Steps

Approach:

- Engaged with the scientific community to share know-how
- Focus on long-term R&D, targeting simultaneously:
 - ~ns timing resolution
 - Power consumption compatible with large area and low material budget
 - Fault-tolerant circuit strategies for wafer-scale MAPS

Highlights:

- Designed pixel architecture with binary readout optimized for linear colliders
- Submitted a small pixel matrix for fabrication on CERN WP1.2 shared run
- Architecture will allow us to evaluate technology in terms of defects and RTS

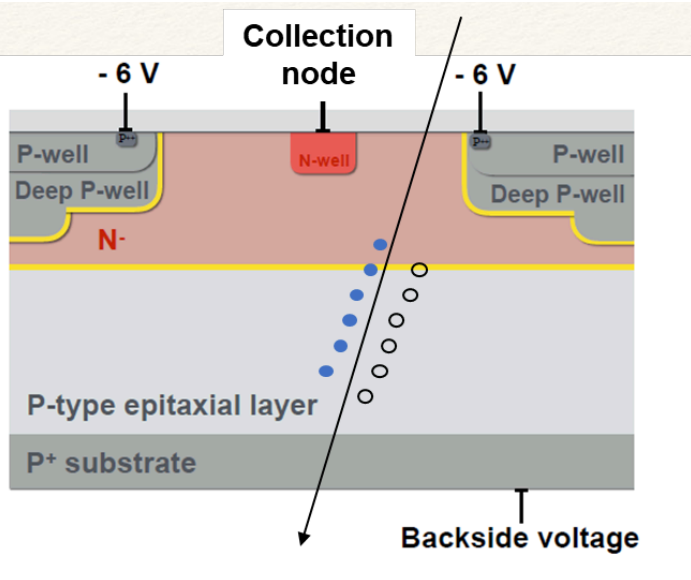
Next steps:

- Evaluate performance of 1st SLAC prototype on TJ65nm (2023).
- New design combining O(ns) timing precision and low-power (2024/2025).
- **Stretch Goals:** design of a wafer-scale ASIC (2025/2026, design only)

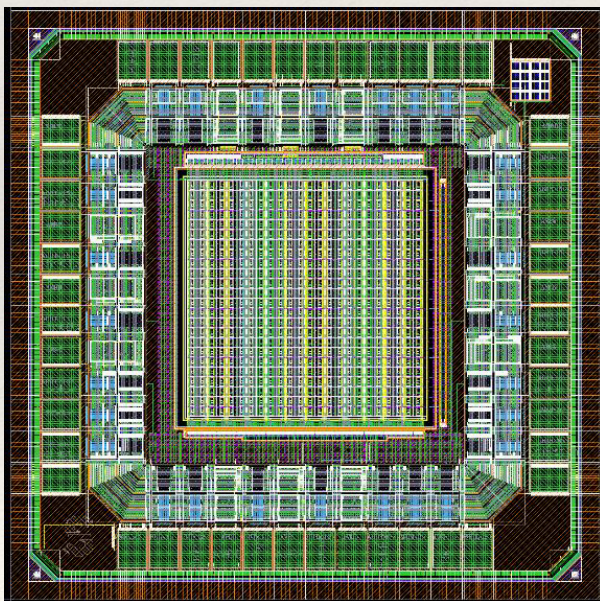
Engagement :

- Higgs Factory detector initiative R&D
- DRD 7.6 on common issues of power distributions compatible with stitching

A. Habib *et al* 2024 *JINST* **19** C04033



Current sensor optimization in TJ180/TJ65 nm process
Effort to identify US foundry on going



Layout of SLAC prototype for WP1.2 2022
shared submission on TowerSemi 65nm

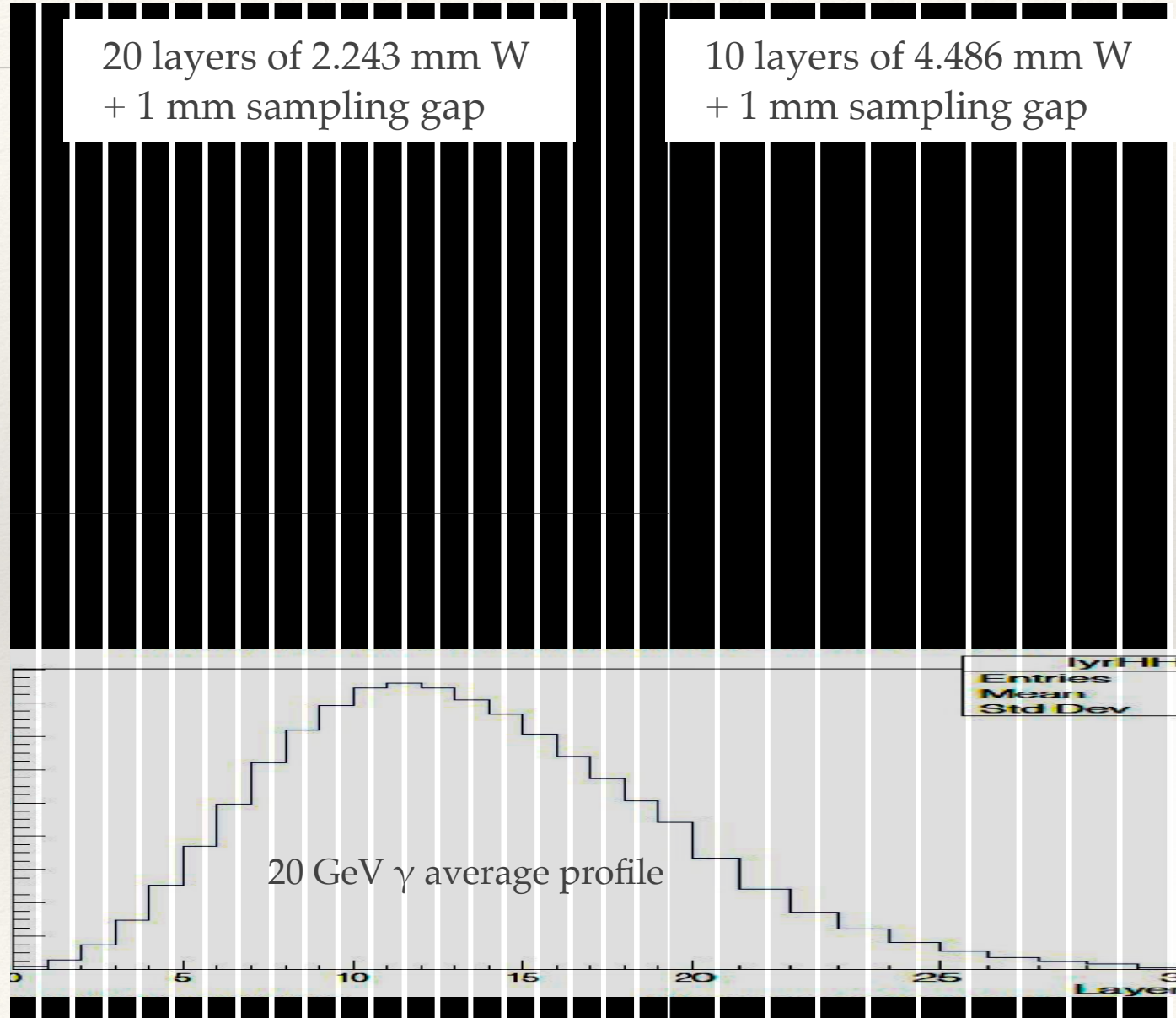


Model of longitudinal structure of SiD ECal

Total = $27 X_0$

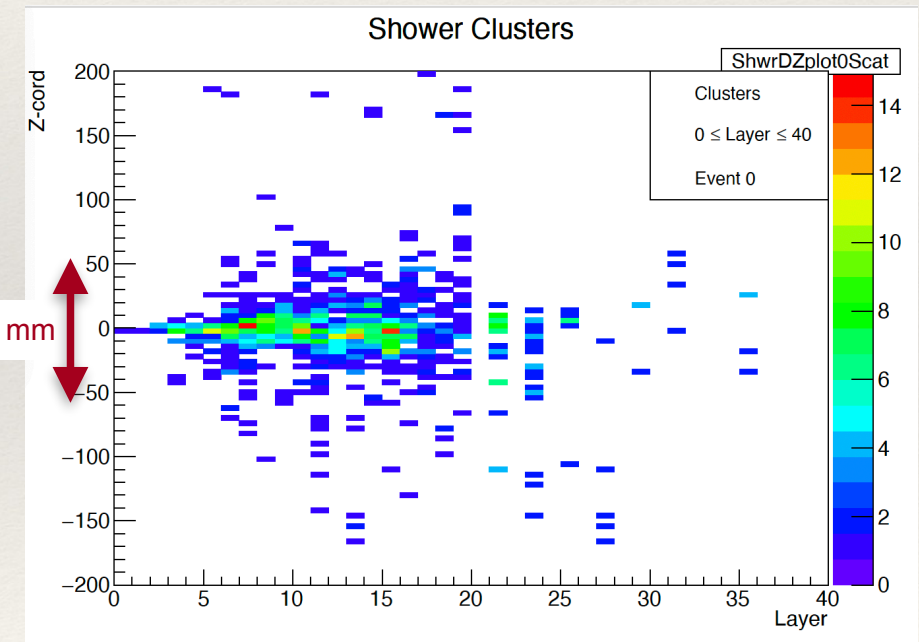
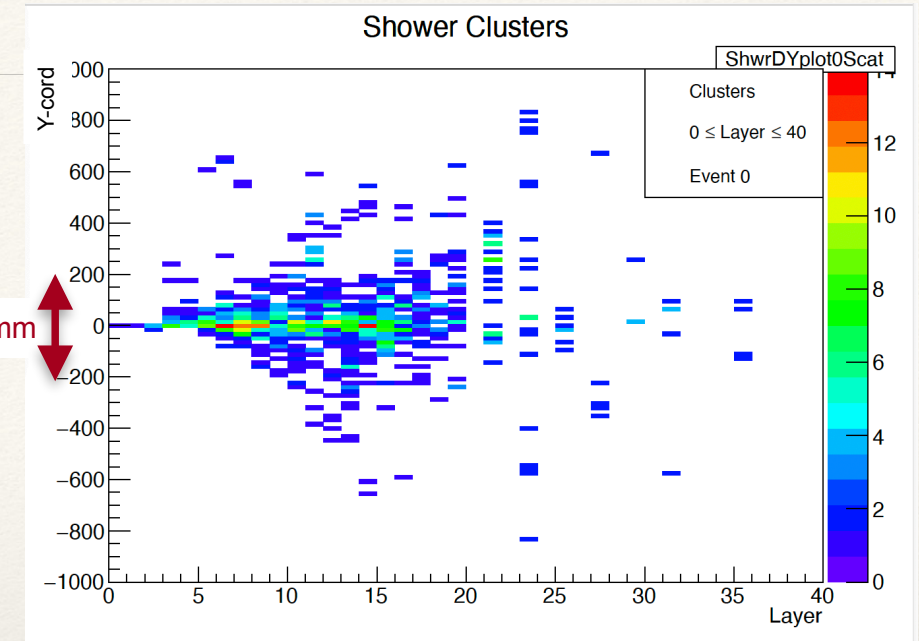
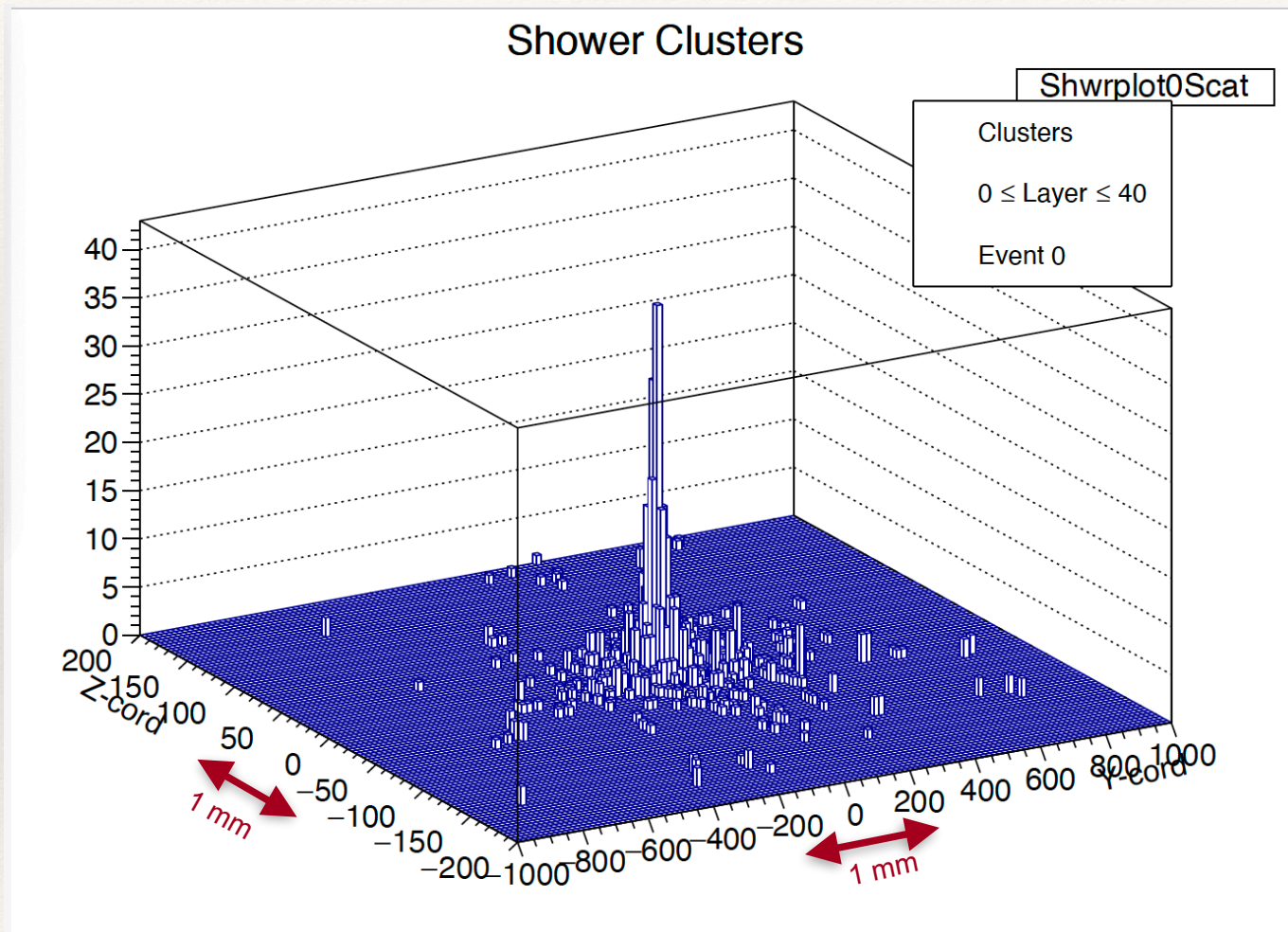


Minimize sampling gap to achieve optimal Moliere radius (14 mm) & shower separation



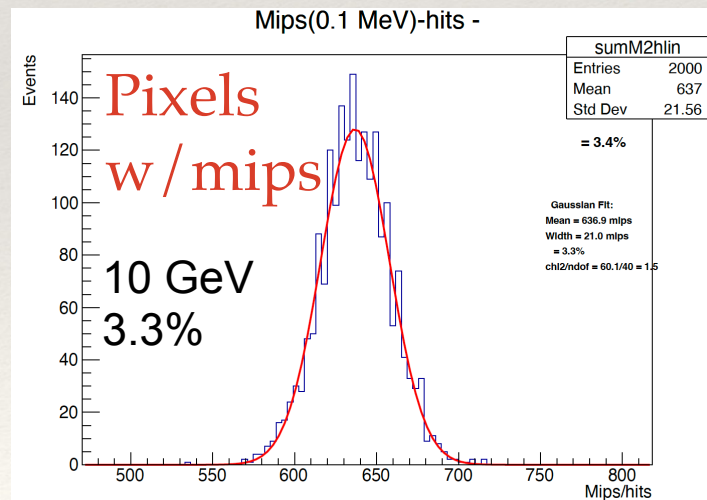
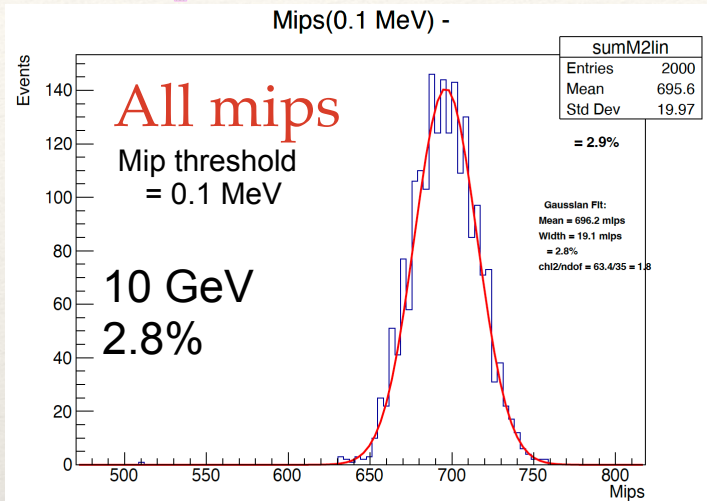


10 GeV Shower in $25 \times 100 \mu\text{m}^2$

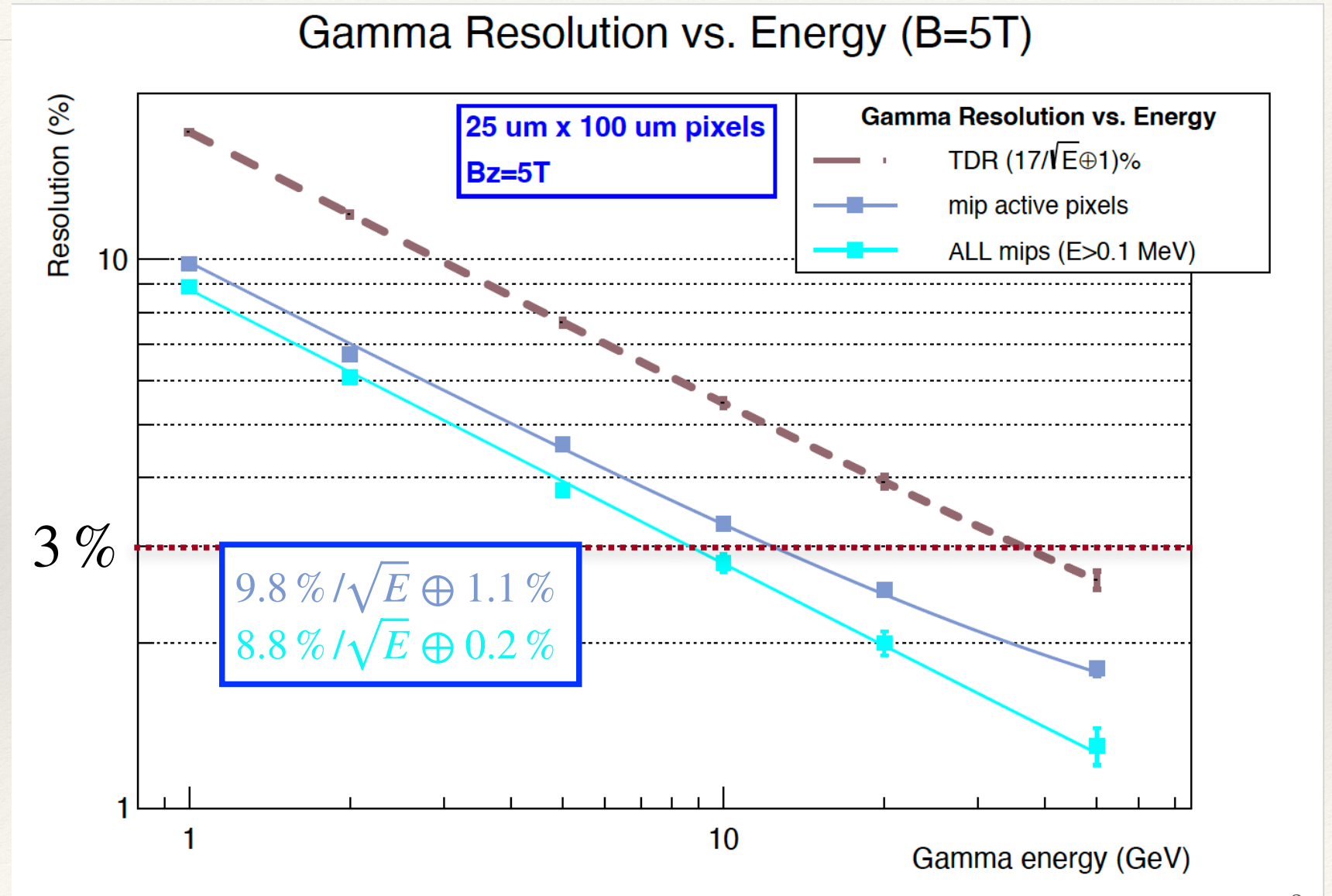




Ultimate Resolution (mips)



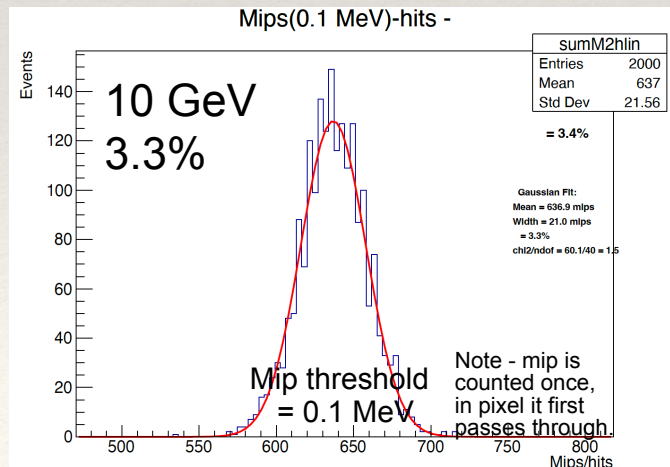
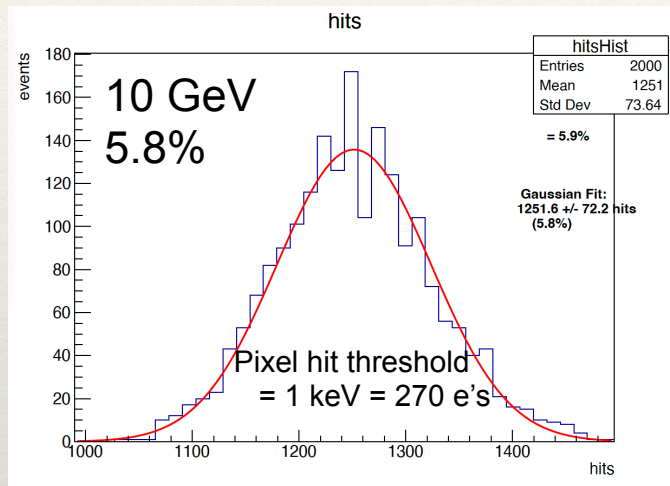
mip counted once in a layer, when it enters sensor.



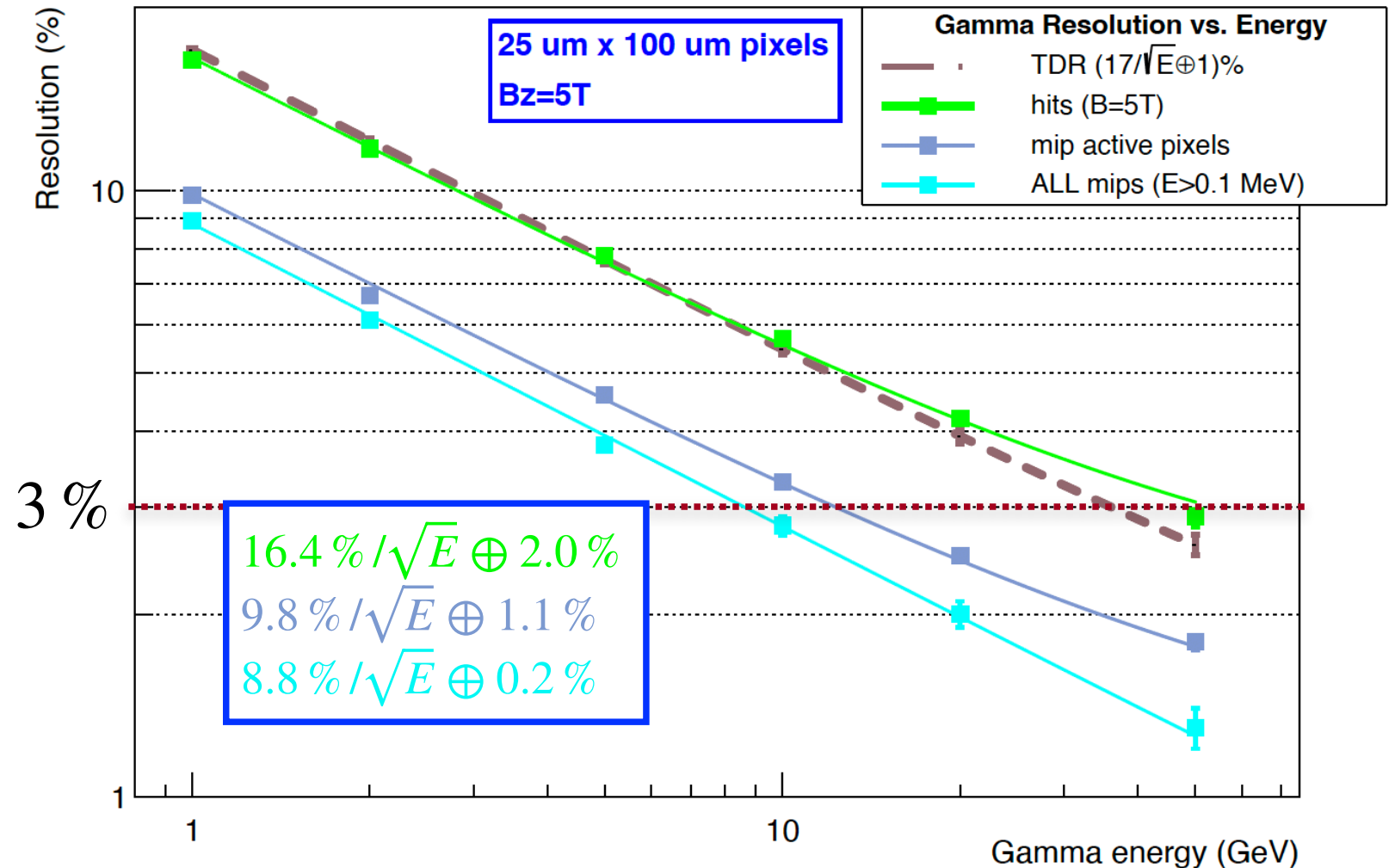


Resolution vs. Energy (hits & mips)

Resolution vs. Energy (hits & mips)



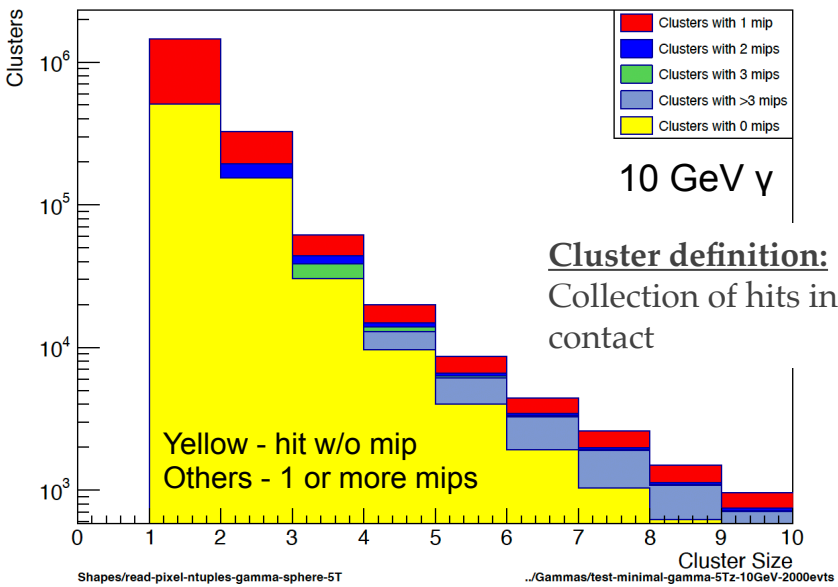
Gamma Resolution vs. Energy (B=5T)



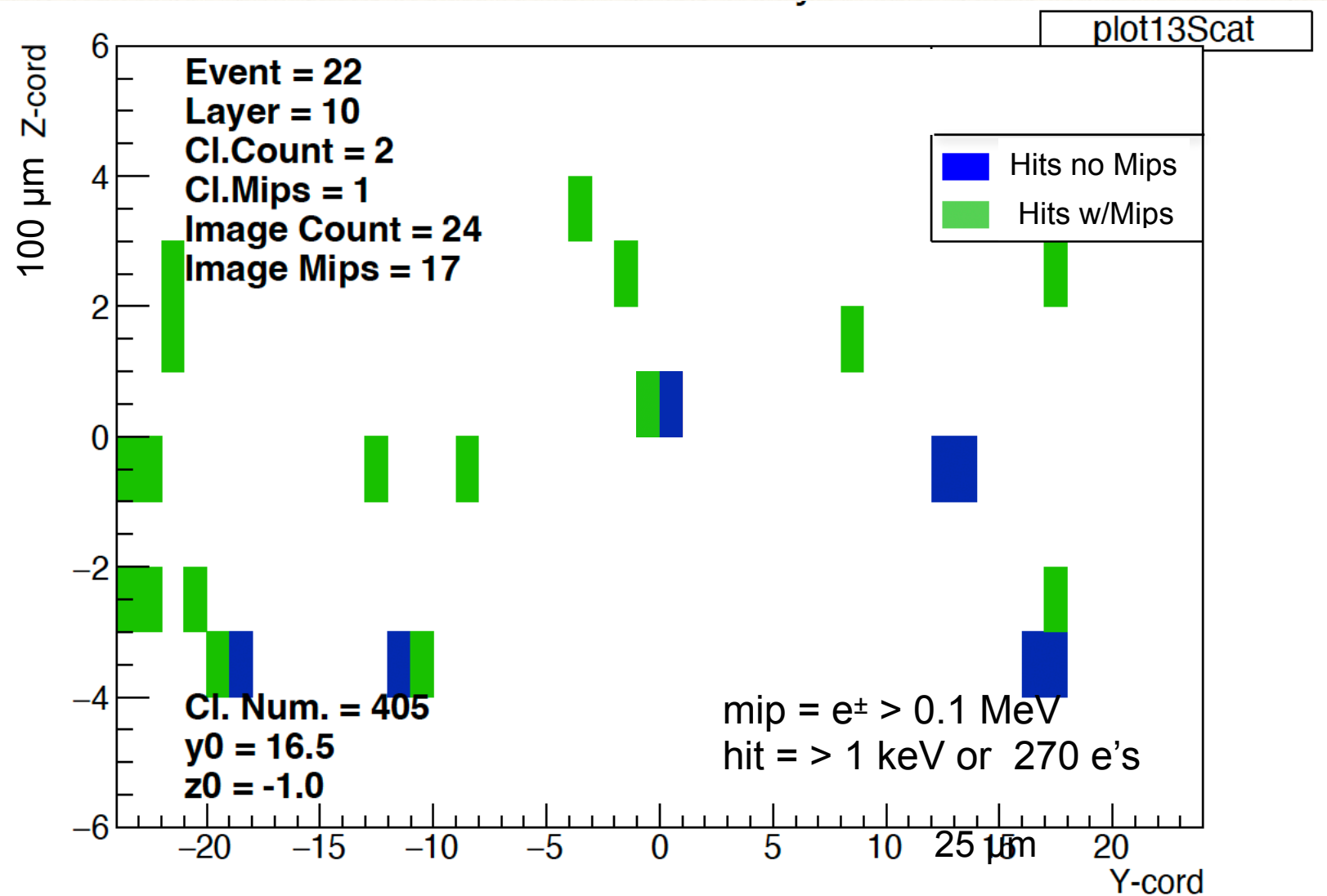


Example of hit distribution in a MAPS

Cluster Size for Mip Counts

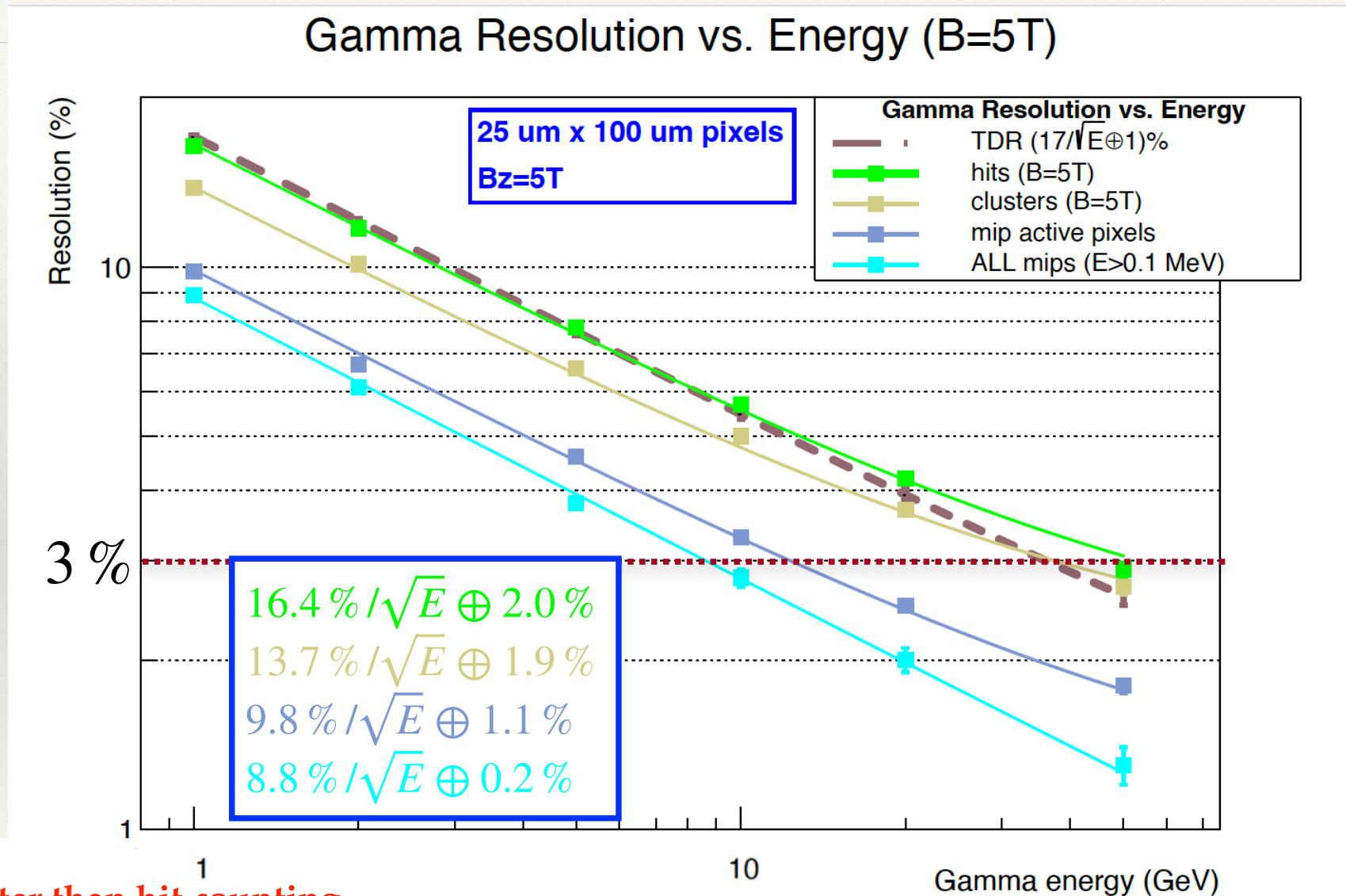
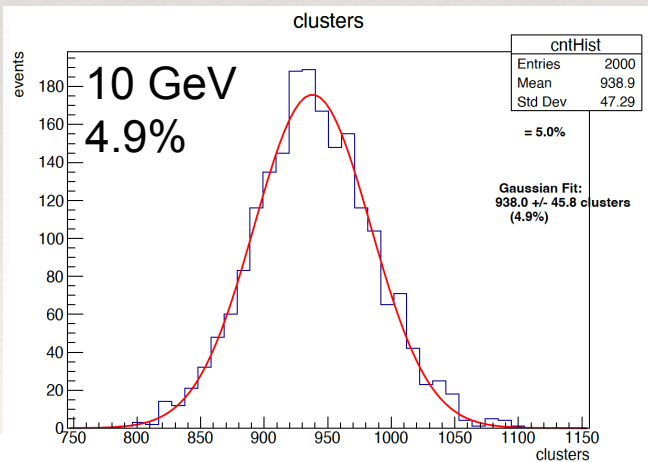
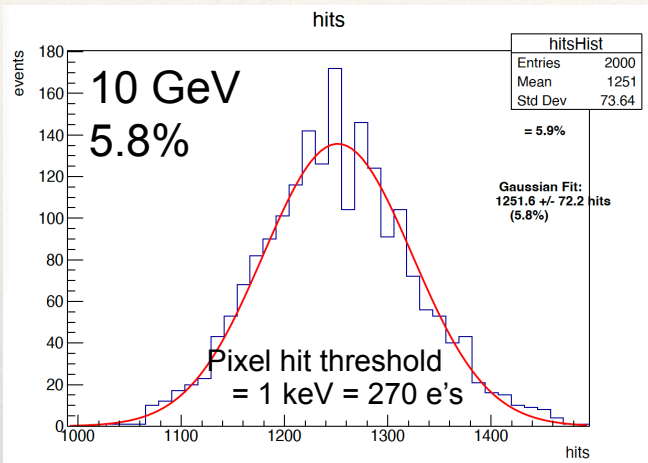


- ❖ Most hits isolated
 - ❖ Single hit cluster
- ❖ Multiple hit clusters
 - ❖ Often single mip,
 - ❖ Or no mip
- ❖ Counting clusters should reduce hit fluctuations



Resolution vs. Energy (hits/clusters/mips)

Resolution vs. Energy (hits/clusters/mips)

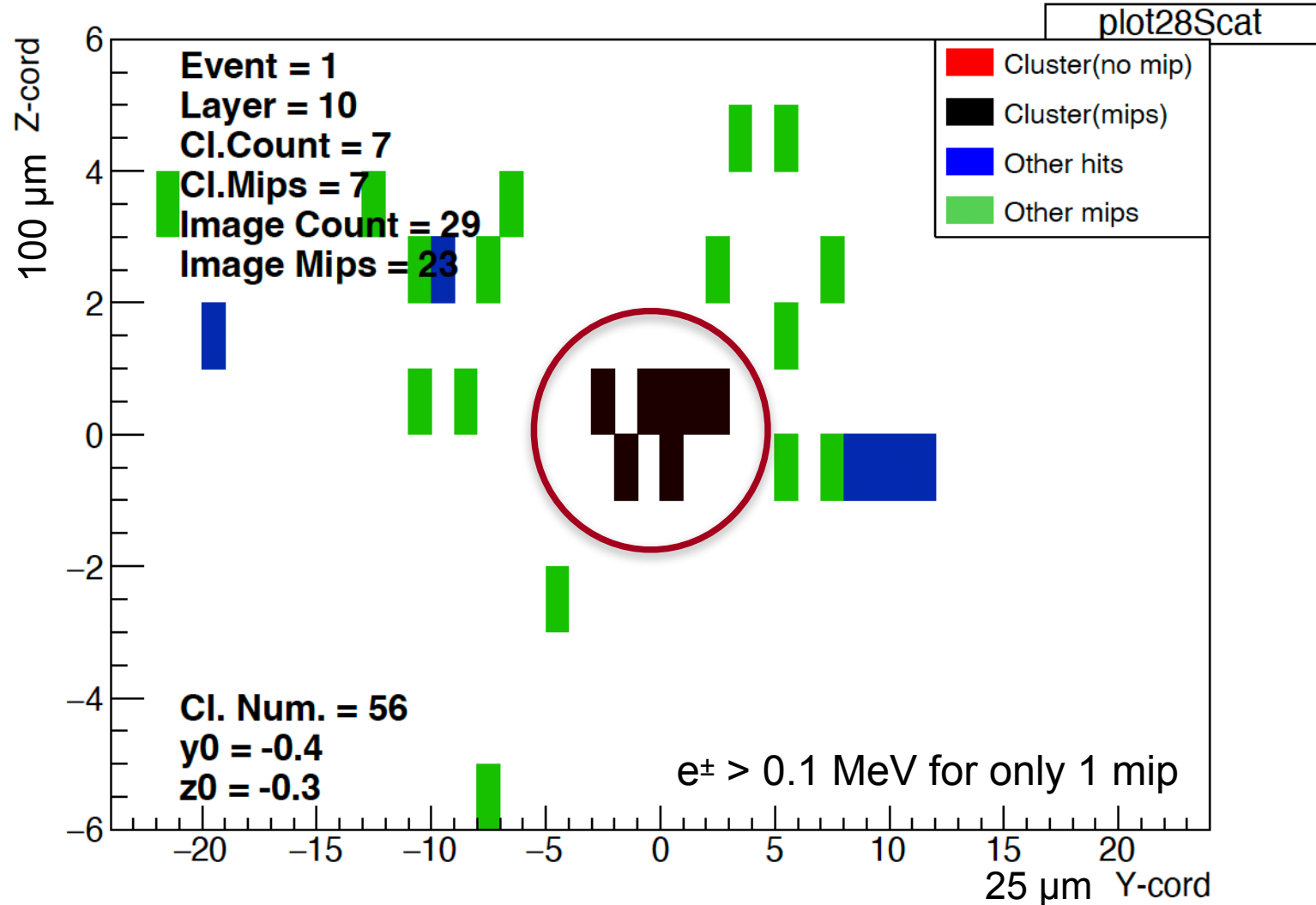


**Simple cluster performance is better than hit counting.
We can do better!**

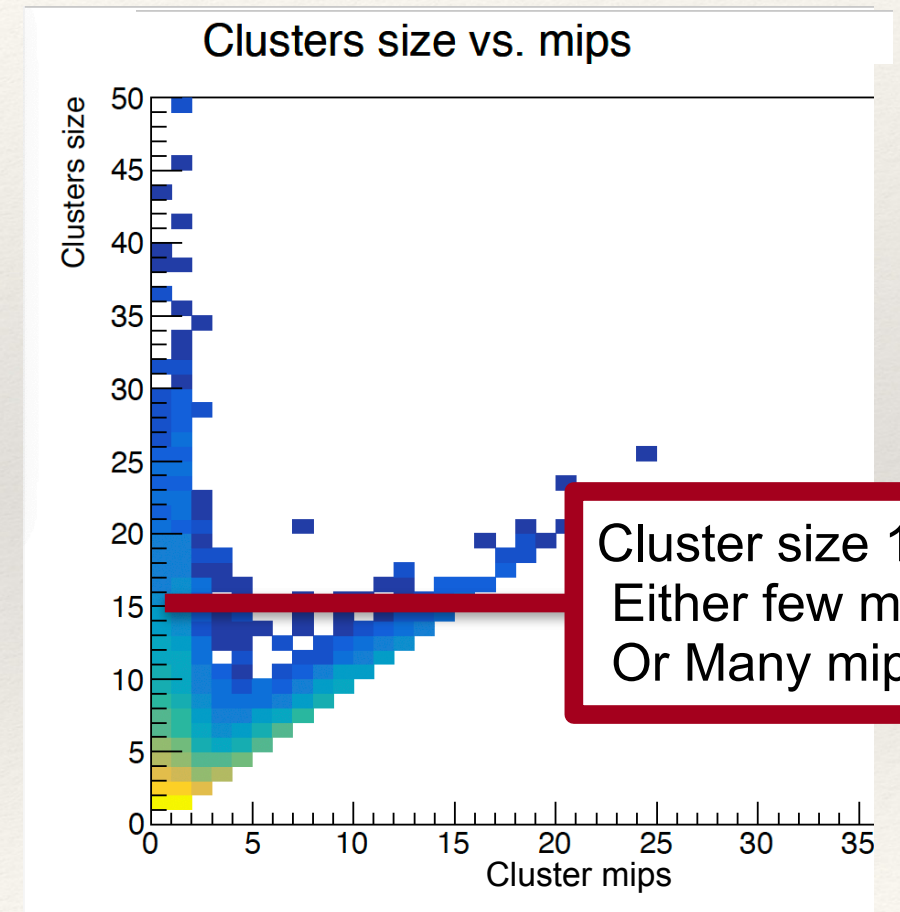


All Clusters are not the same

Cluster and nearby hits

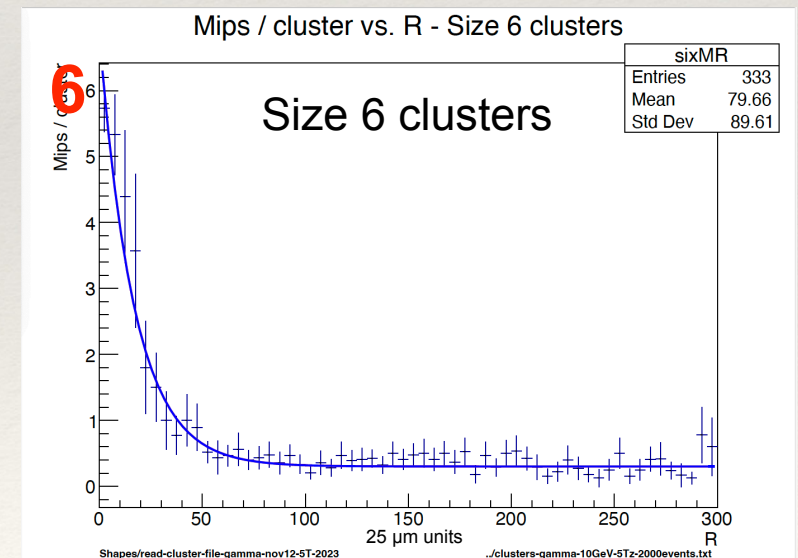
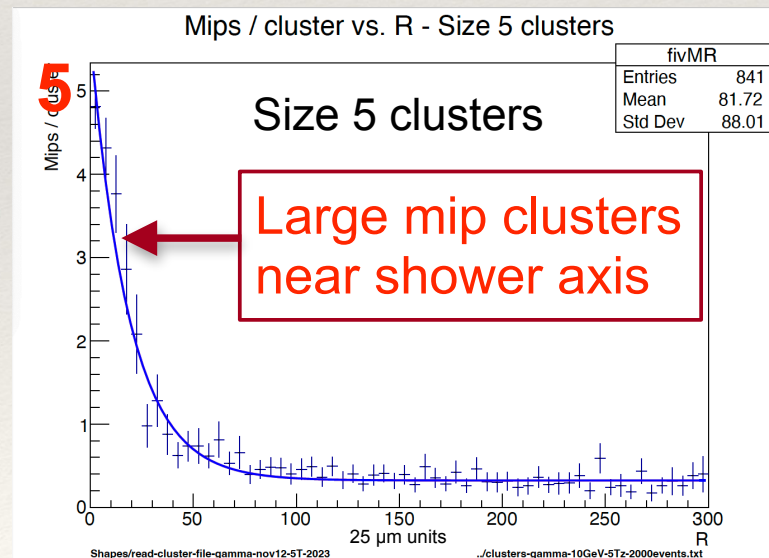
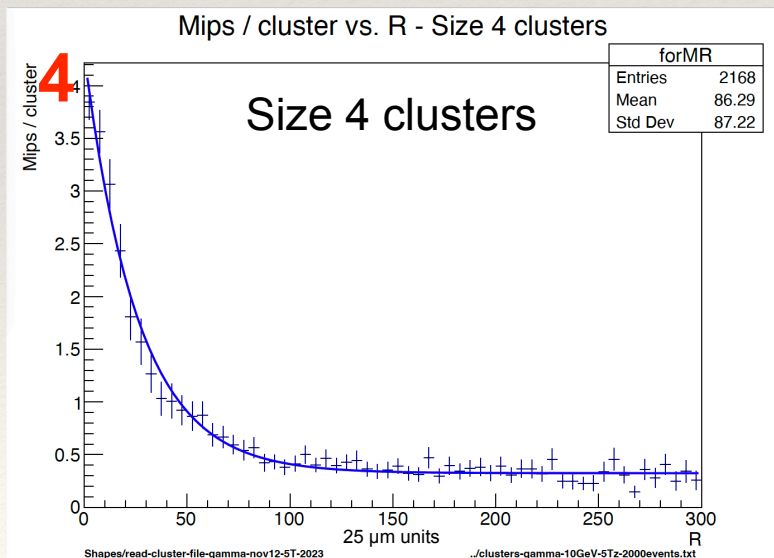
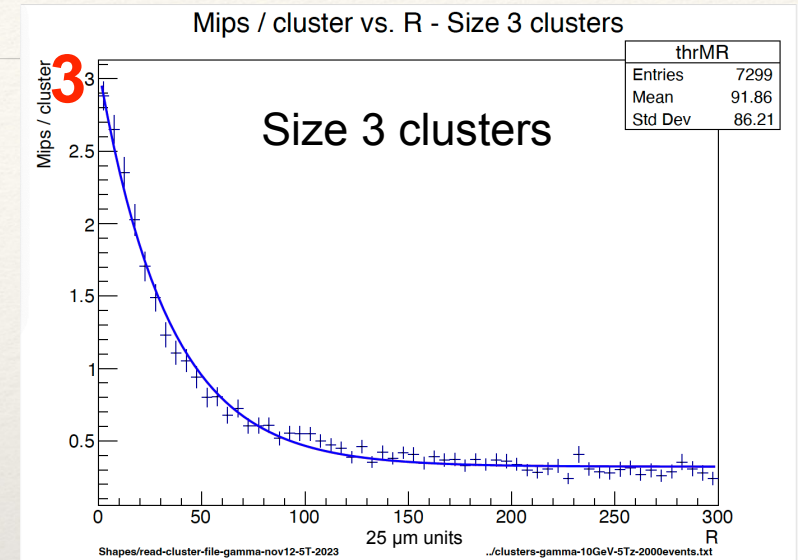
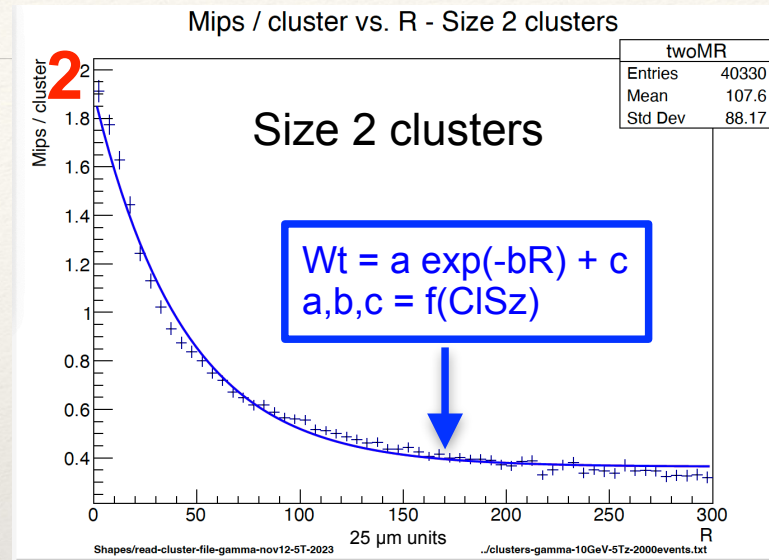
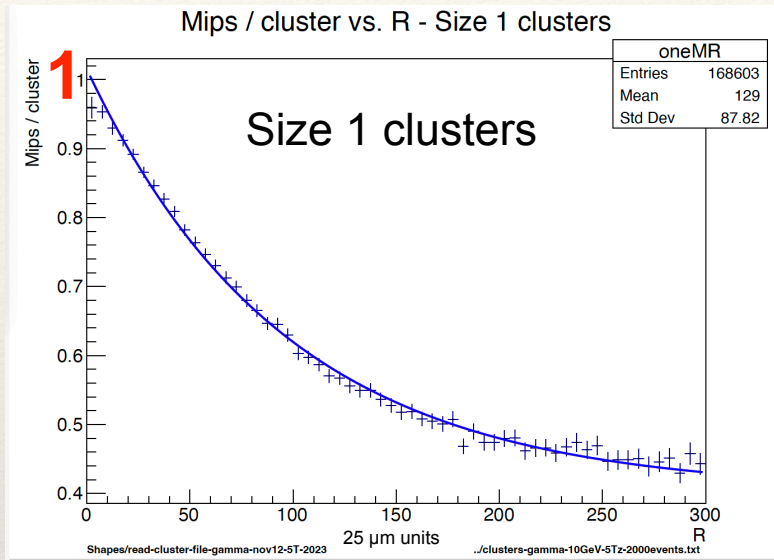


❖ Some clusters are numerous mips.





Mips/cluster vs. showerR 10 GeV γ s - 2000 showers



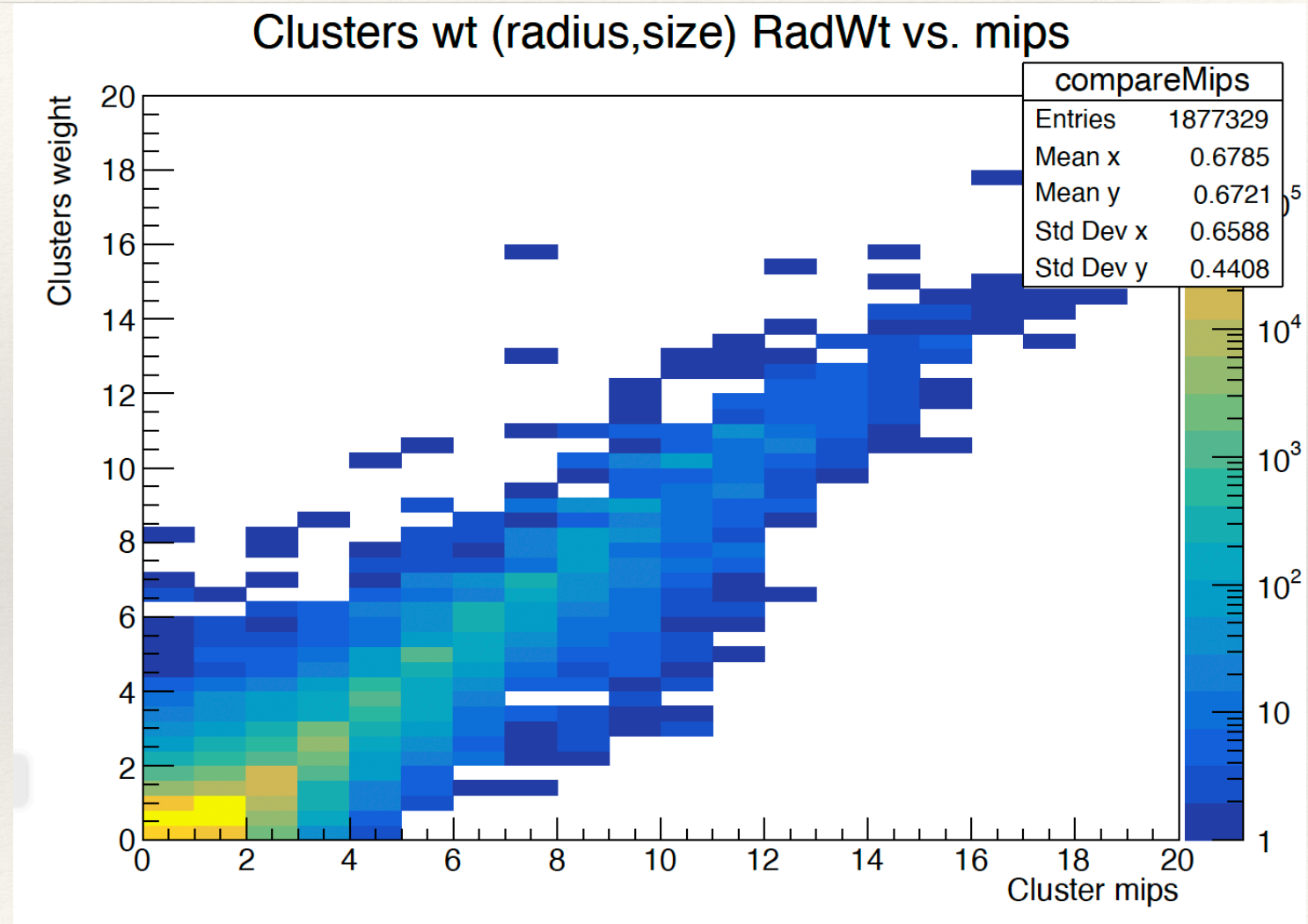


10 GeV γ s - 2000 showers

Apply weight to clusters:

$$\text{RadWt} = a \exp(-bR) + c$$

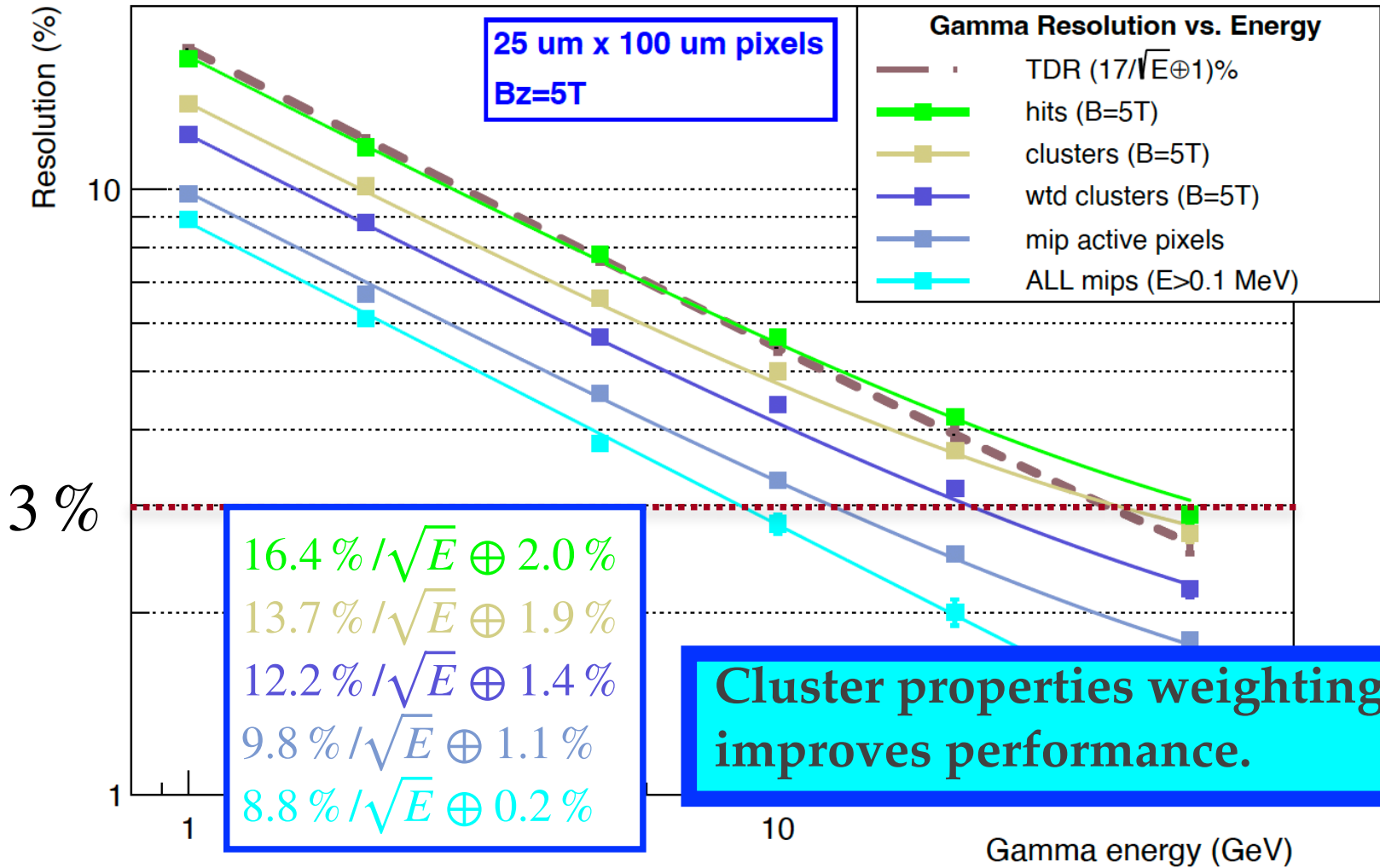
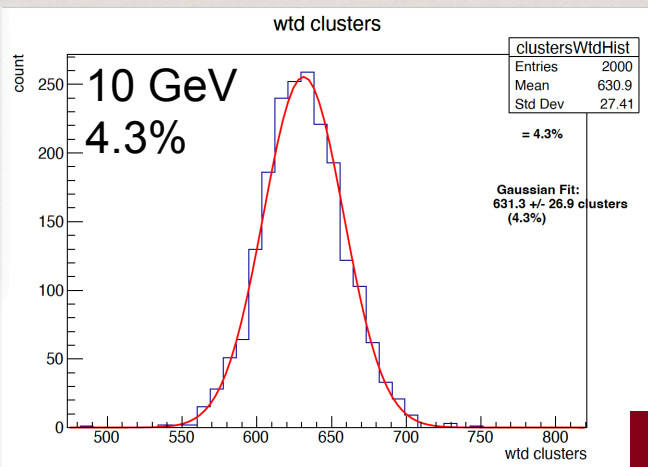
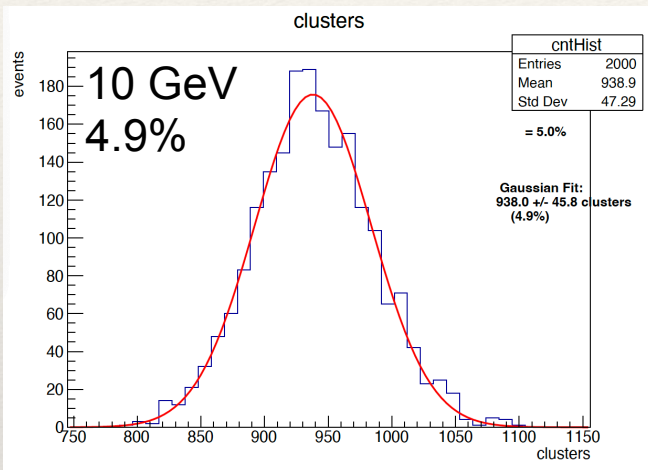
$$a, b, c = f(\text{CISz})$$



Resolution vs. Energy (hits/clusters/mips)

Gamma Resolution vs. Energy (B=5T)

Resolution vs. Energy
(hits / clusters / mips)
& weighted clusters.



Can a Neural Net Improve Performance?



TMVA Neural Net

TRAINING - 10 GeV
2000 events
2,502,000 hits
1,878,999 clusters

Neural net cluster weighting based on

1. Three input parameters =
Cluster size, layer num, shower radius
2. Five input parameters =
Add cluster length in Y and Z

```
# Store model to file  
model.save('modelRegression%s.h5'%Efact)  
model.summary()
```

```
# Book methods  
factory.BookMethod(dataloader, TMVA.Types.kPyKeras, 'PyKeras',  
                  'H:!
```

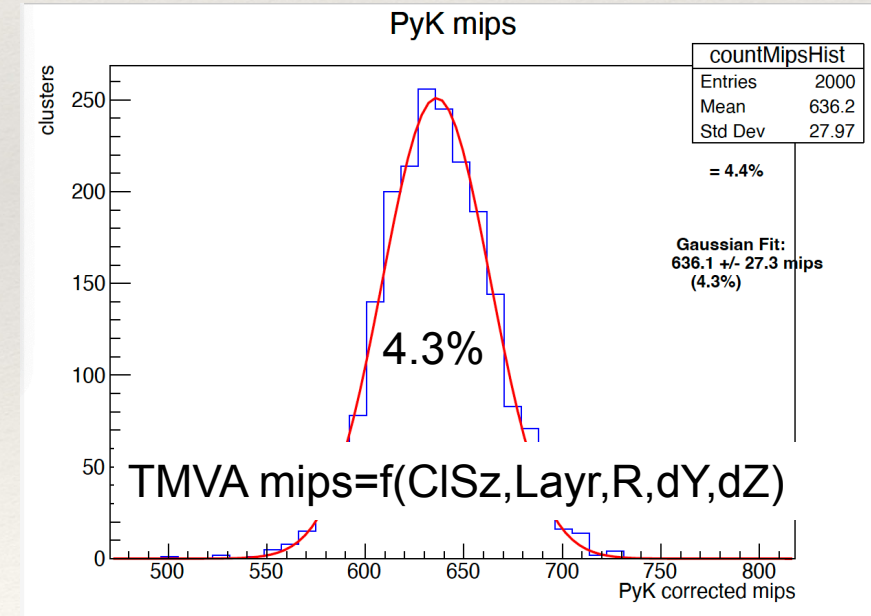
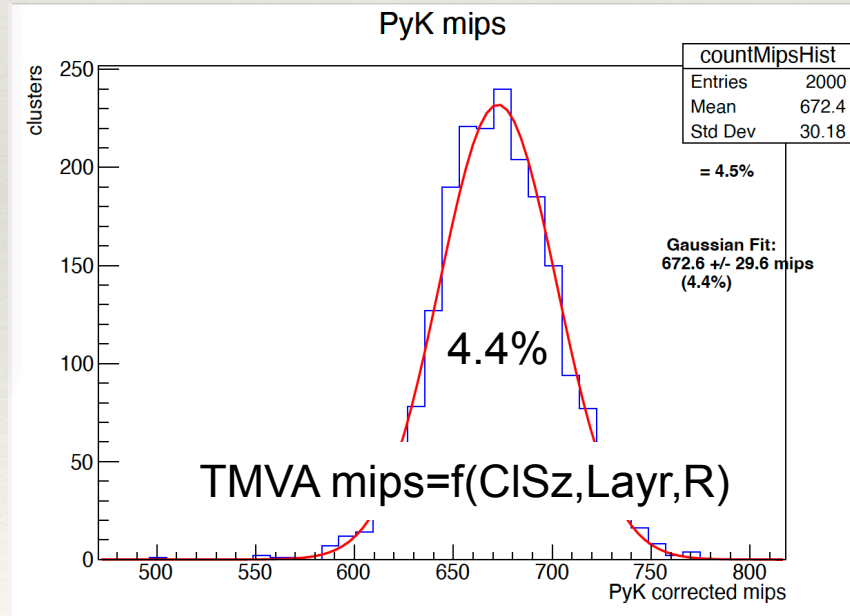
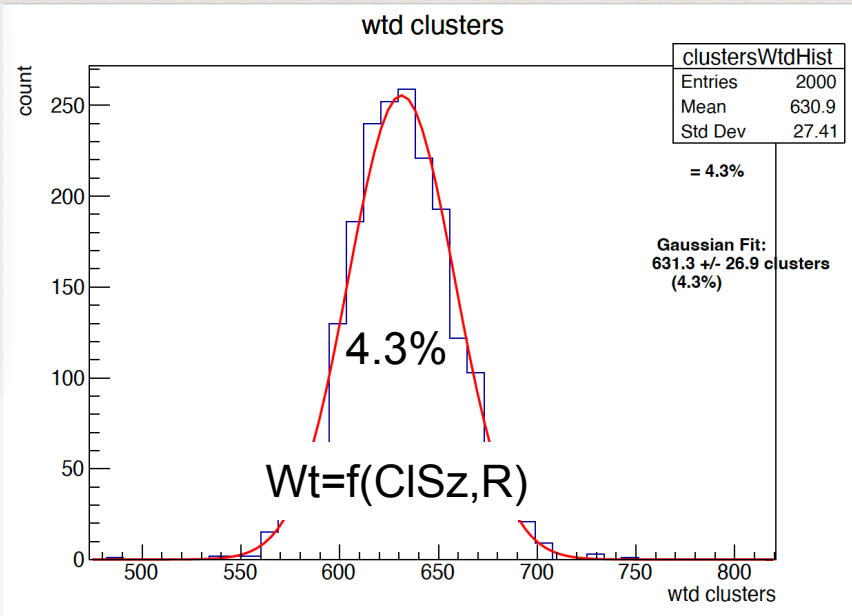
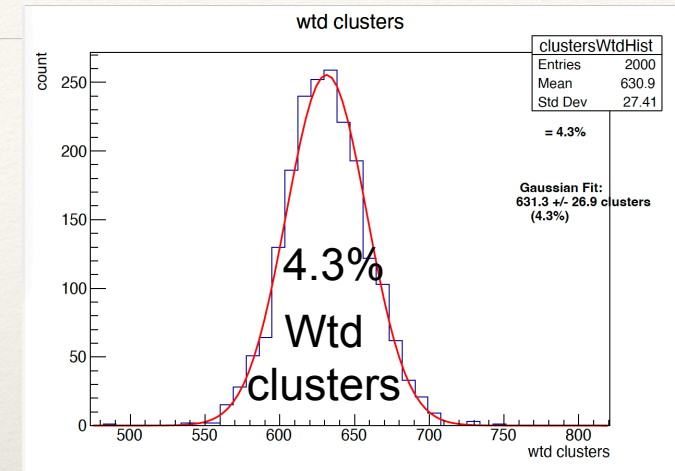
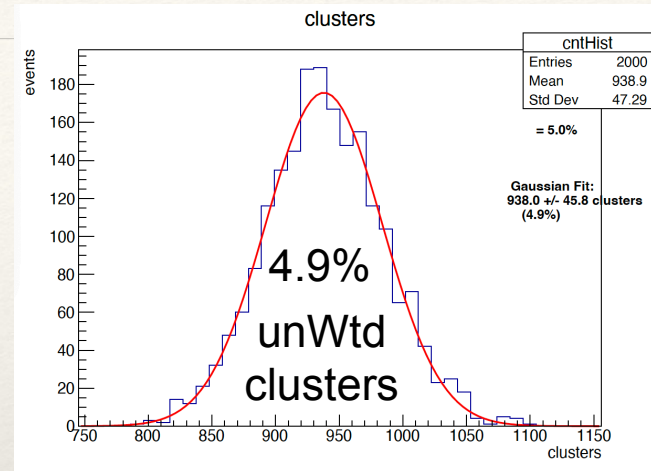
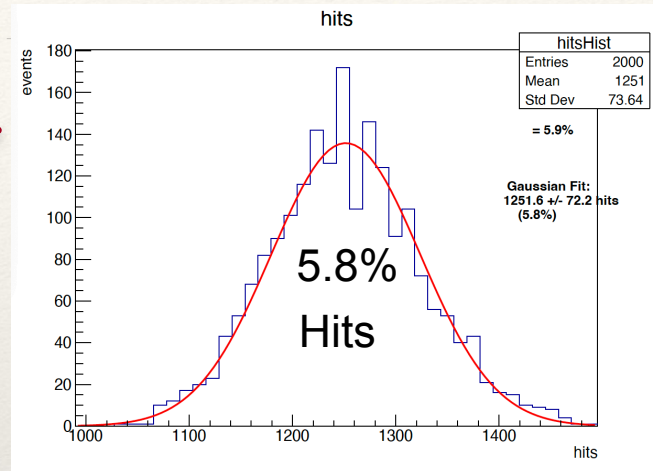
```
V:VarTransform=D,G:FilenameModel=modelRegression%s.h5:FilenameTrainedModel=  
trainedModelRegression%s.h5:NumEpochs=20:BatchSize=32'%(Efact,Efact))
```




Weighted function vs. TMVA neural net (10 GeV γ s)

Weighted Clusters Analysis

Neural Net Analysis





Results: Energy Resolution

Energy	1	2	5	10	20	50
clusters	13.8%	10.1%	6.6%	4.9%	3.7%	2.7%
wtd clusters	12.3%	8.8%	5.7%	4.4%	3.2%	2.2%
3 par TMVA	12.6%	9.5%	6.2%	4.4%	3.4%	2.2%
5 par TMVA	12.8%	9.4%	5.9%	4.3%	3.1%	2.2%

- ❖ Weight fits for 2, 10, 50 GeV; extrapolated for 1, 5, 20 GeV.
- ❖ NN optimized for each energy
- ❖ 3 par = cluster size, layer, radius
- ❖ 5 par = cluster size, layer, radius, dY , dZ

Weighted clusters already achieve performance of this neural net.

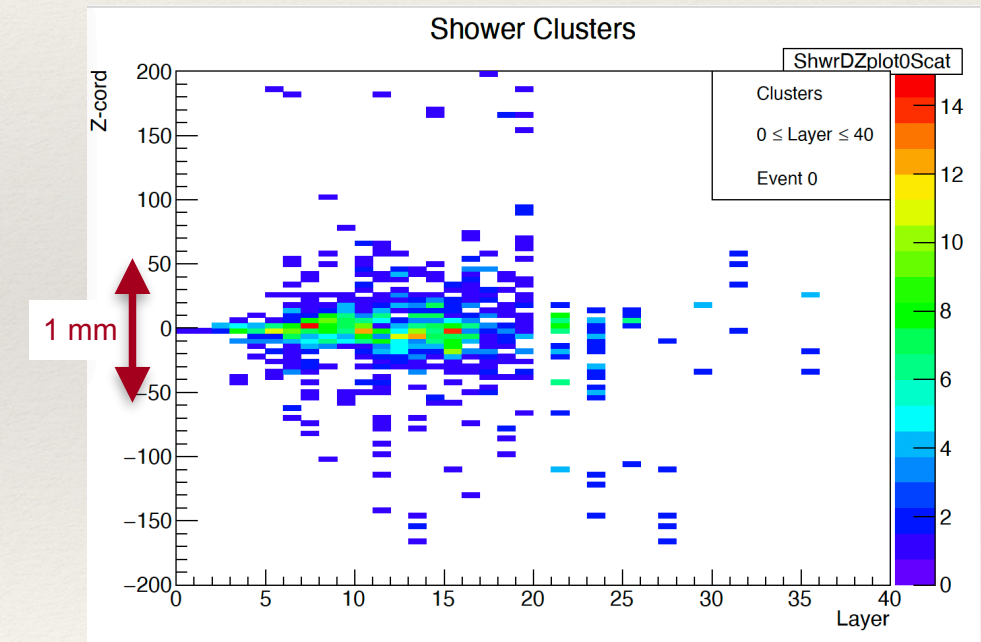
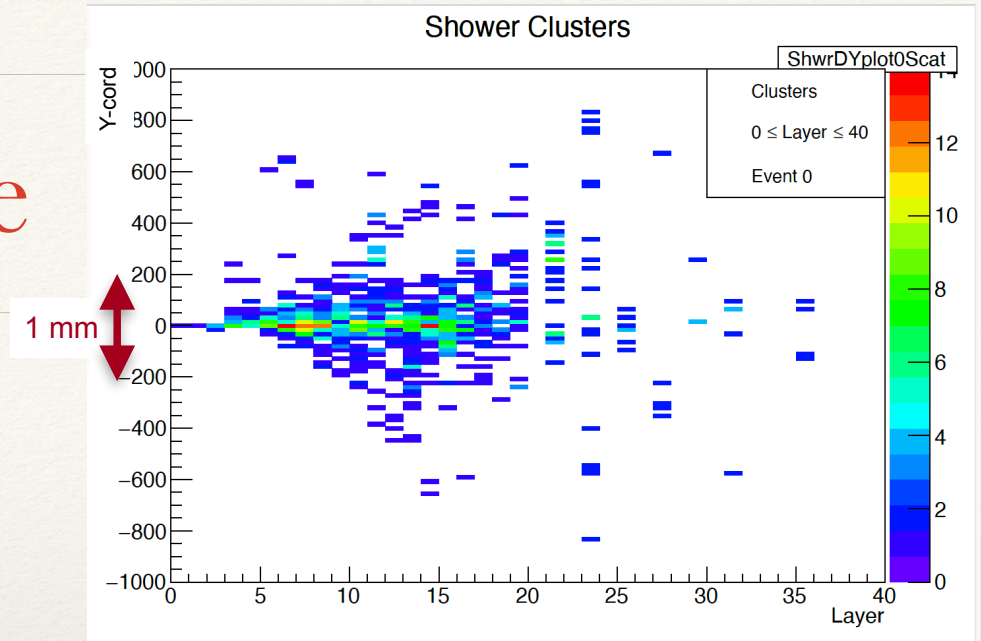
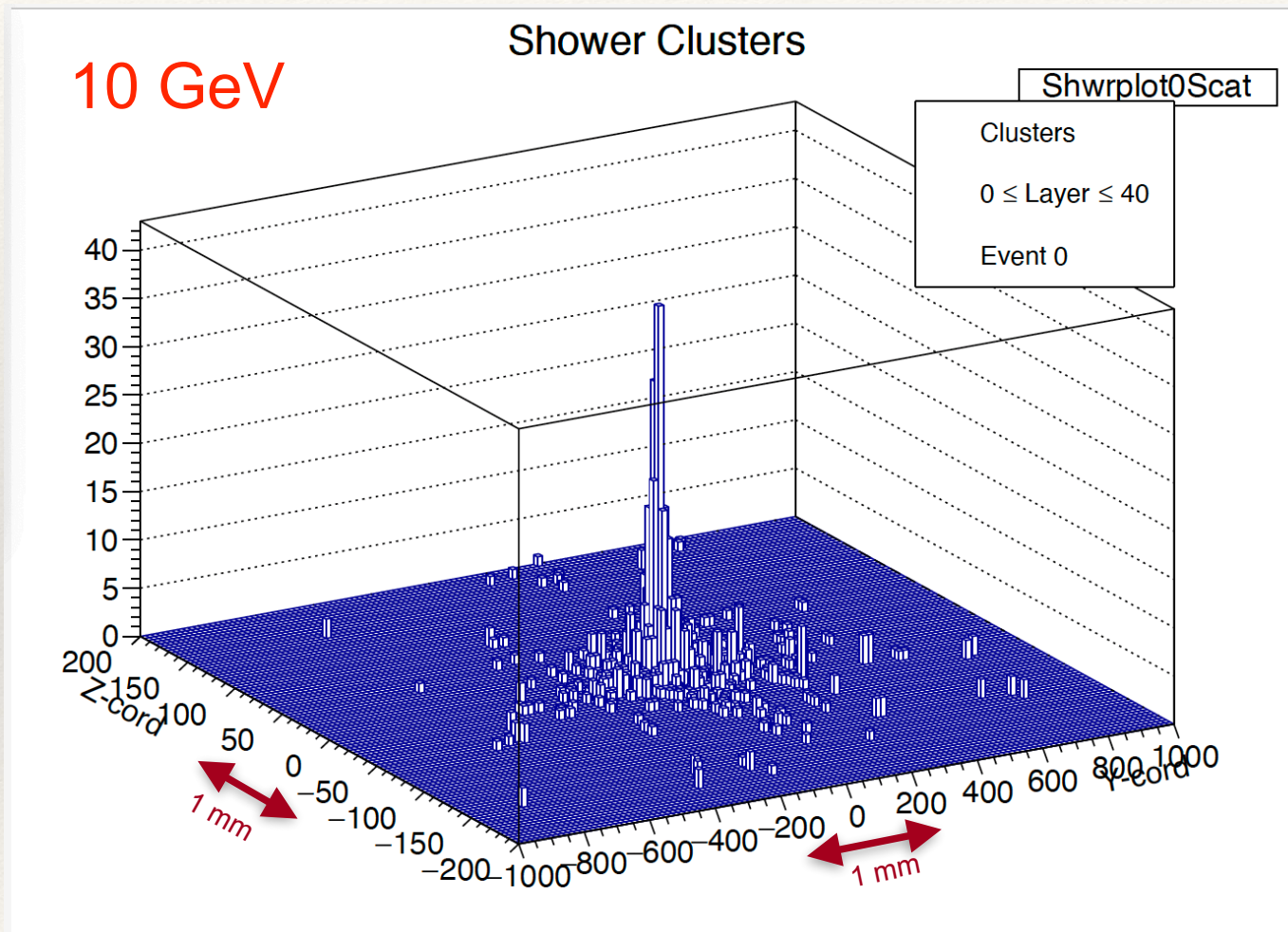


Another topic:

Potential impact of high granularity on particle flow measurements

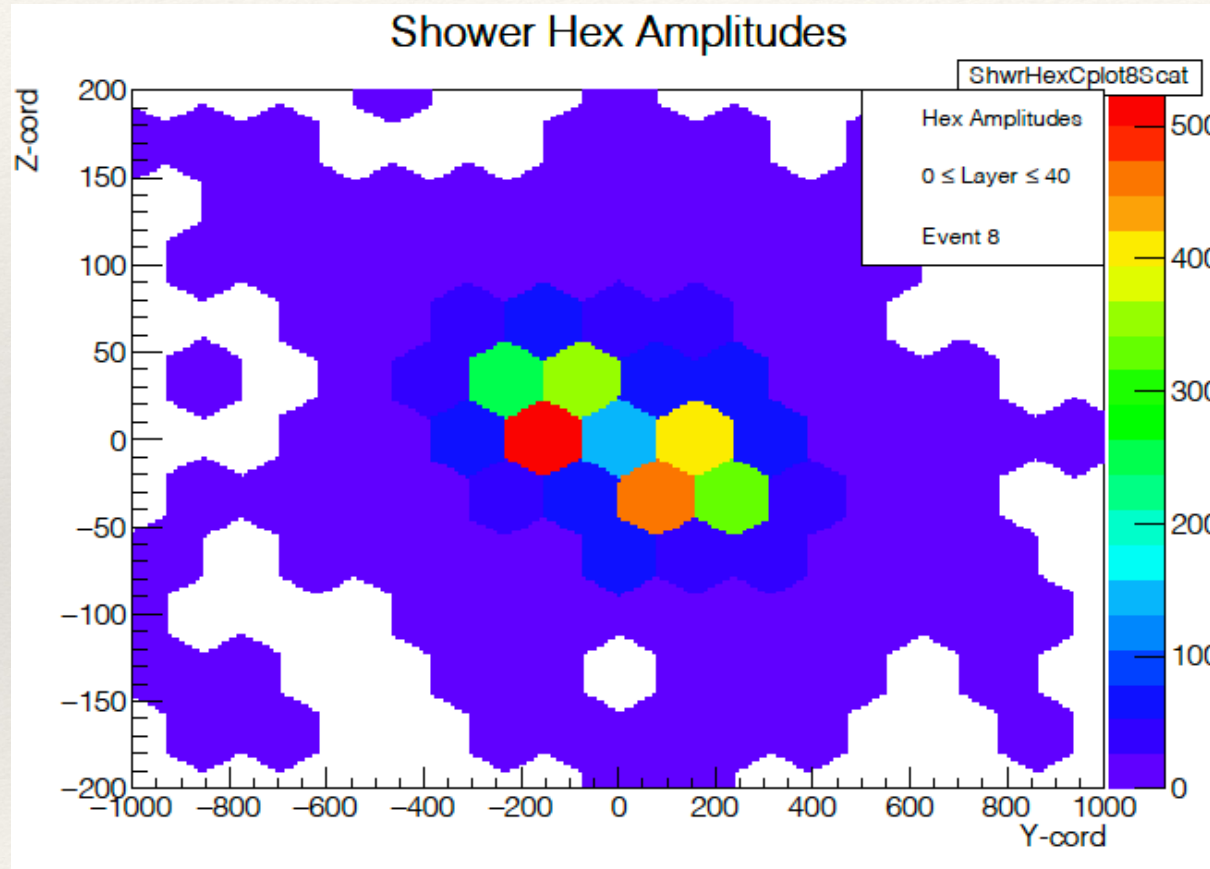


Transverse Shower Structure

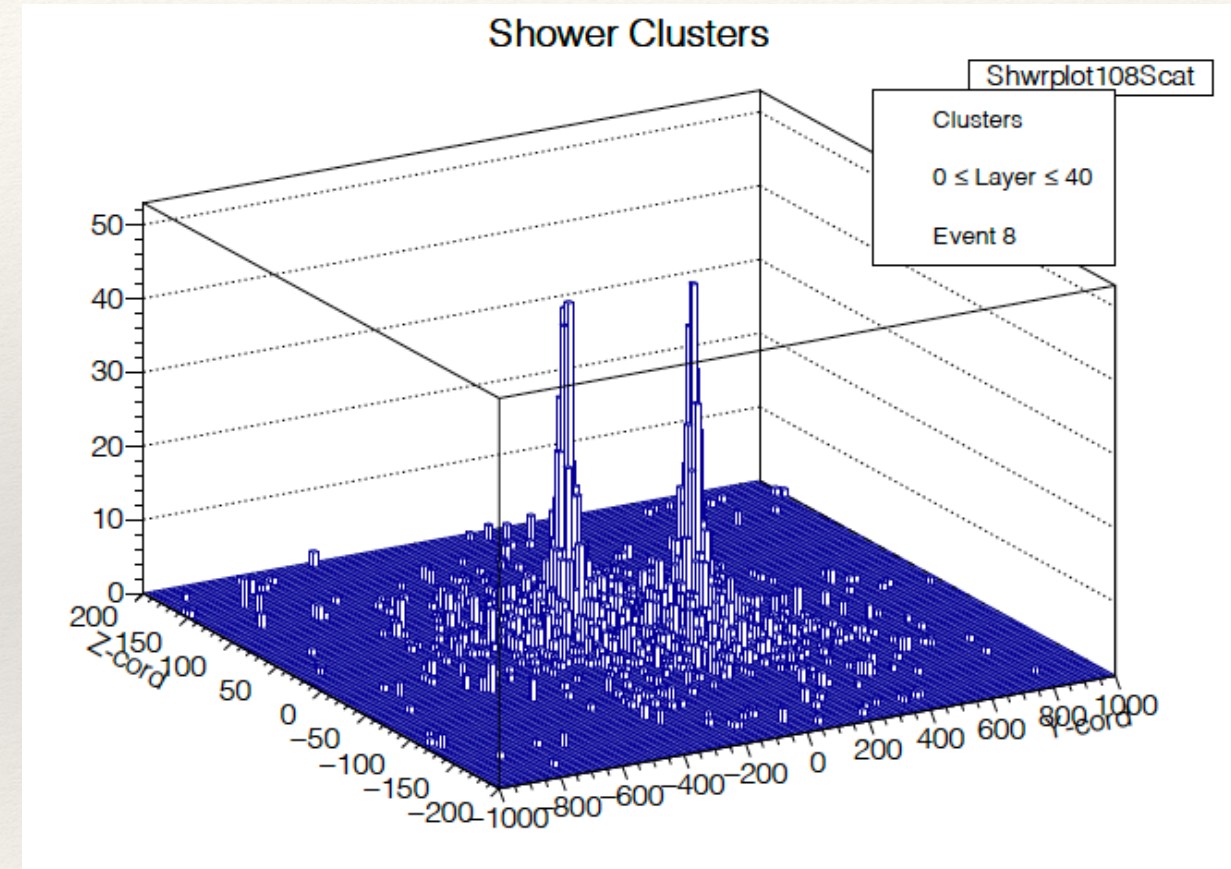


Multi-shower of SiD MAPS compared to SiD TDR

40 GeV $\pi^0 \rightarrow$ two 20 GeV γ 's

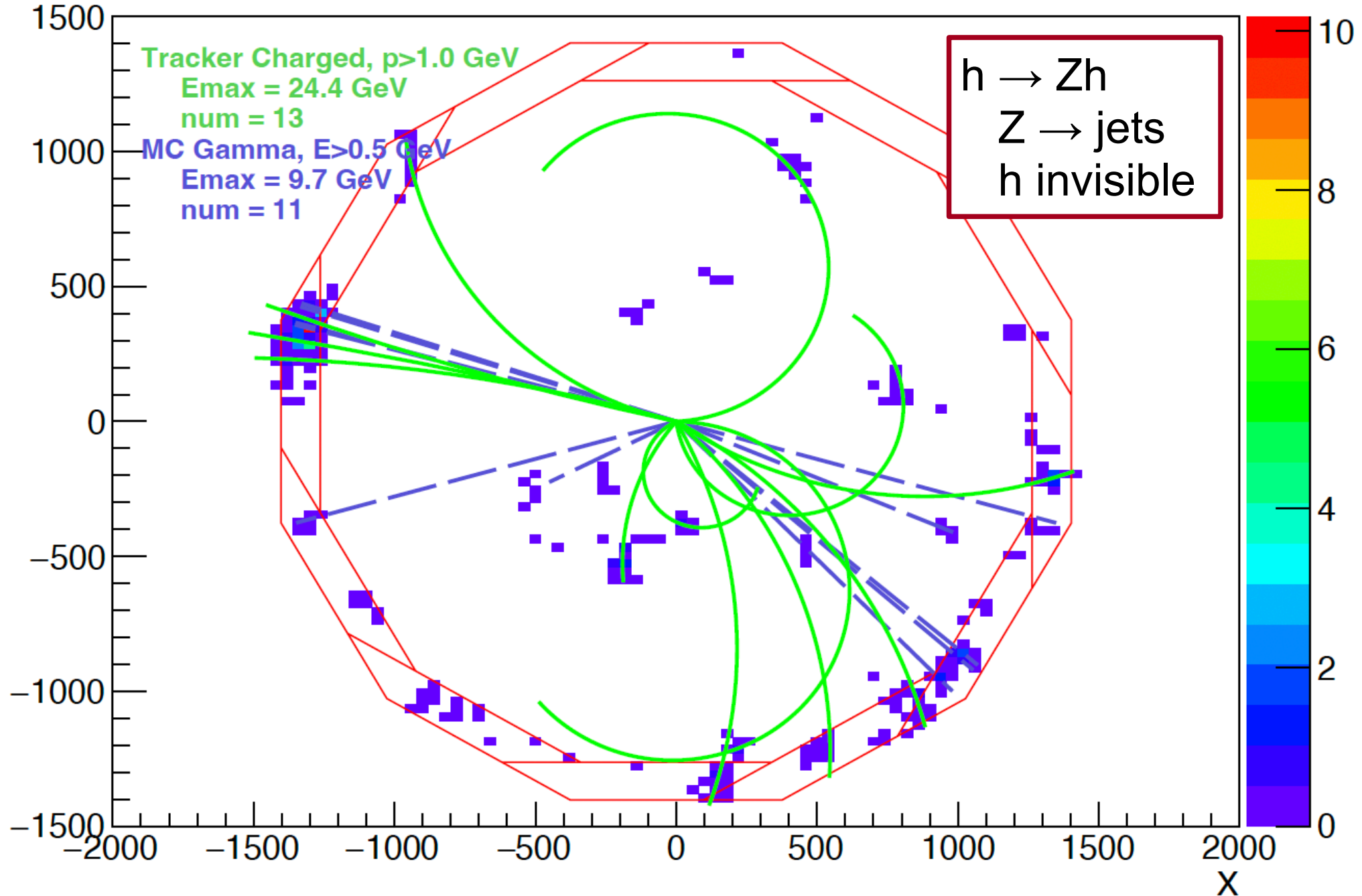


SiD TDR hexagonal sensors
 13 mm² pixels

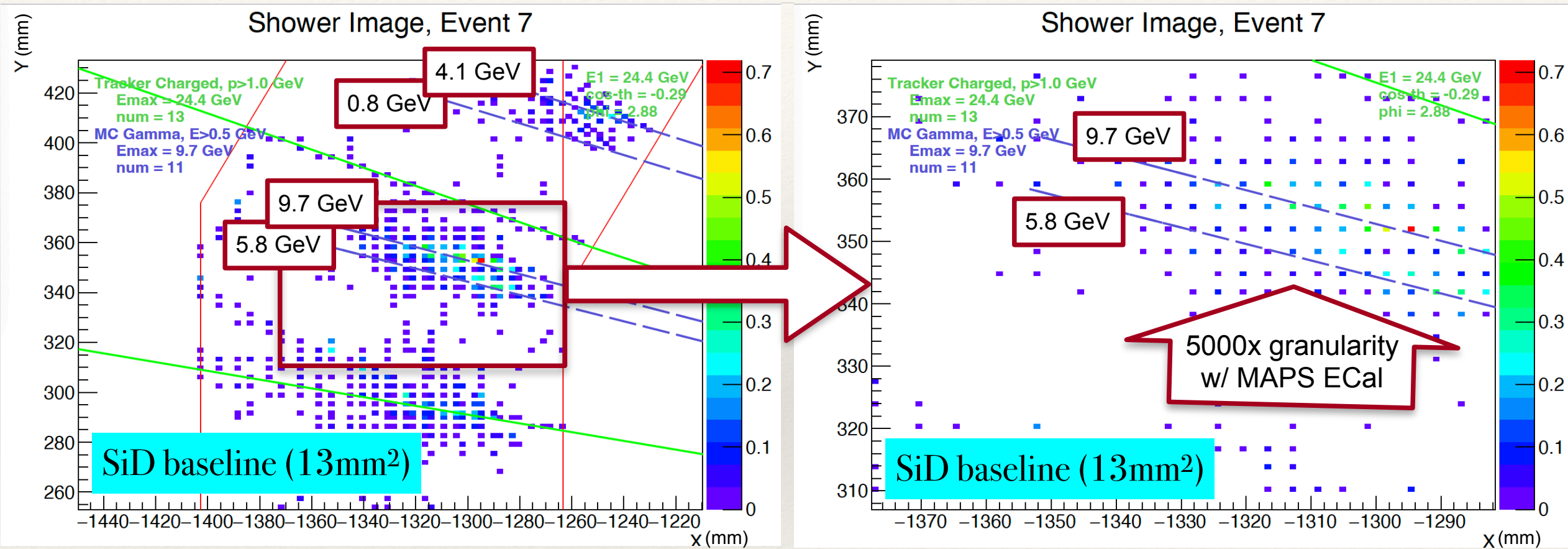


New SiD fine pixel sensors
 25 μm x 100 μm pixels

Shower Image, Event 7



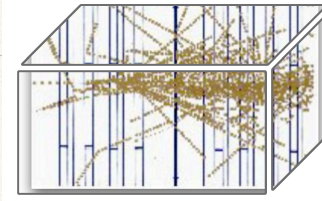
γ 's in jet / SiD baseline ECal (13mm^2 pixels)



- ❖ 13 mm^2 pixels of analog SiD ECal
- ❖ **5000x granularity** with digital MAPS ECal
- ❖ Future MAPS integration into full SiD simulation will define scale of improvement?



Conclusion



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- ❖ Application of monolithic active pixel sensors (MAPS) to SiD digital ECal offers excellent performance:
 - ❖ Energy measurement
 - ❖ Transverse energy containment & particle flow separation
- ❖ Well defined EM shower structure allows simple algorithmic optimization of energy measurement.
- ❖ An effort led by SLAC is progressing on the needed MAPS development.
- ❖ Neural nets have been studied to improve energy measurement:
 - ❖ They have not yet provided improvement over the “informed” algorithm.
- ❖ We are also investigating the application of the timing measurements.
- ❖ Future - simulation of full SiD detector with high granularity of MAPS ECal