# Experiments in DIY TCAD

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project supervised by Dr. Dan Weatherill

#### About me

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# Agenda

- 1. Motivation
- 2. Development
- 3. Theory
- 4. Implementation
- 5. Further work
- 6. Integration with other software

## Computational Project

- It is worth 17% of the 3<sup>rd</sup> year grade
- There are around 10 computational projects allocated each year

- This project was supervised by Dr. Dan Weatherill and Prof. Ian Shipsey from the OPMD group
- **The aim:** implement a simulation to calculate the shape of a stored cloud of electrons confined in a CCD potential well

#### Motivation

- •Develop a fully open source TCAD-like simulator
- •Drift-diffusion equations model
- •Use the 3D Finite Volume Method
- •Calculating the E-field structure from doping & geometry

Approximat



**SPICE is here**

**We are here**

Easy, fast

#### **Silvaco/Sentaurus are here**

**From "Computational Electronics" by Vasileska, Goodnick, Klimeck Chapter 5**

## Development

- (2019/20) Guo-Zheng "Theo" Yoong & Taavet Kalda first implementations of pn junction
- (2020/21) Mac Zhou & Xihan Deng performance improvements, addition of mobility & recombination models
- (2021/22) Megan Evans first "CCD charge packet" simulation
- (2022/23) Tevz Lotric comparisons against commercial and analytic models from 1D simulator
- (2023/24) Andrei Taropa rewrite in c++ using the DUNE numerics framework. Our first inherently 2D devices simulated!

#### Results on pn junction simulation



#### **Images from Mac Zhou (2020)**

#### Charge Packet Shapes

**Top:** A (1D) charge packet shape simulation in a CCD buried channel with an insulator on top



**Images from Tevz Lotric (2022/23)**

# C++ simulations of diodes **At this point, we can simulate diode**

**structures routinely!**

**But this is the first time we had it working in the new C++ code!**



#### 2D Device Simulation



**An NPN BJT cannot be properly simulated in 1D because the base contact needs to be in the 2nd dimension.**



## 2D Device simulation #2





Extracted transistor characteristics (note we can't yet set constant currents at boundaries, so these don't look "quite" textbook

#### Theory #1 - Poisson's equation

• We start with Poisson's equation, where we assume that the medium has a uniform permittivity  $\varepsilon_r$ :

$$
\nabla^2 V = -\frac{q}{\varepsilon_r \varepsilon_0} (p-n+N_D^+-N_A^-)
$$

 $p = hole density$ 

n = electron density

 $N_D$  = donor doping

- $N_A$  = acceptor doping
- $V = Voltage$

q = electron charge

# Theory #2 – System of equations

• Poisson's equation:

$$
\nabla^2 V = -\frac{q}{\varepsilon_r \varepsilon_0} (p-n+N_D^+-N_A^-)
$$

• Charge continuity equations:

$$
\frac{\partial n}{\partial t} = 0 = \frac{1}{q} \nabla \cdot \mathbf{J_n} + U_n \qquad \qquad \frac{\partial p}{\partial t} = 0 = -\frac{1}{q} \nabla \cdot \mathbf{J_p} + U_p
$$

- $p = hole density$ n = electron density  $N_D$  = donor doping  $N_A$  = acceptor doping  $V = Voltage$ q = electron charge
- **J** = current density U = recombination rate

 $\mu$  = mobility

- Current given by the drift diffusion equation:
- $D =$  diffusivity  $\mathbf{J}_p = qp\mu_p \mathbf{E} - qD_p \nabla p$  $\mathbf{J}_n = qn\mu_n \mathbf{E} + qD_n \nabla n$ **E** = electric field

## Theory #3 – Boltzmann approximation

• We can write the electron and hole number densities in terms of Quasi-Fermi levels  $\phi_{n}$  and  $\phi_{p}$ :

$$
n = n_i \exp\left(\frac{q(V - \phi_n)}{k_B T}\right) \qquad p = n_i \exp\left(\frac{q(\phi_p - V)}{k_B T}\right)
$$

• N.B. these are the Boltzmann approximated densities. You can use Fermi-Dirac instead, which changes the exponential to a more complicated integral, but conceptually similar

#### Theory #4 – Scale factors

• It is also useful to scale voltage quantities:

$$
\bar{V} = \frac{qV}{k_B T} \qquad \qquad \bar{\phi}_n = \frac{q\phi_n}{k_B T} \qquad \qquad \bar{\phi}_p = \frac{q\phi_p}{k_B T}
$$

• We also scale the lengths:

$$
L_D = \sqrt{\frac{\varepsilon_r \varepsilon_0 k_B T}{q^2 N_{\max}}}
$$

#### Theory #5 – Solving Poisson's equation

• Solving Poisson's equation:

$$
\bar{\nabla}^2 \bar{V} = \frac{n_i}{N_{\text{max}}} \left( \exp \left( \bar{V} - \bar{\phi_n} \right) - \exp \left( \bar{\phi_p} - \bar{V} \right) - \frac{C}{n_i} \right)
$$

• We use "Gummel's method": Taylor expand:

- $\bar{V}_{\text{new}} = \delta \bar{V} + V_{\text{old}}$  $\exp \pm \delta \bar{V} \approx 1 \pm \delta \bar{V}$
- After substituting into Poisson's equation:

$$
\frac{d^2\bar{V}_{\text{new}}}{d\tilde{x}^2} = \frac{n_i}{N_{\text{max}}} \underbrace{\left(\exp\left(\bar{V}_{\text{old}} - \bar{\phi}_n\right) - \exp\left(\bar{\phi}_p - \bar{V}_{\text{old}}\right) - \frac{C}{n_i}\right)}_{A} + \frac{n_i}{N_{\text{max}}} \delta\bar{V} \underbrace{\left(\exp\left(\bar{V}_{\text{old}} - \bar{\phi}_n\right) + \exp\left(\bar{\phi}_p - \bar{V}_{\text{old}}\right)\right)}_{B}
$$

#### Theory #6 - Solving Poisson's equation

• … substituting into Poisson's equation:

$$
\frac{d^2\bar{V}_{\text{new}}}{d\tilde{x}^2} = \frac{n_i}{N_{\text{max}}} \underbrace{\left(\exp\left(\bar{V}_{\text{old}} - \bar{\phi}_n\right) - \exp\left(\bar{\phi}_p - \bar{V}_{\text{old}}\right) - \frac{C}{n_i}\right)}_{A} + \frac{n_i}{N_{\text{max}}} \delta\bar{V} \underbrace{\left(\exp\left(\bar{V}_{\text{old}} - \bar{\phi}_n\right) + \exp\left(\bar{\phi}_p - \bar{V}_{\text{old}}\right)\right)}_{B}
$$

• And after some rearrangement:

$$
\left(\bar{\nabla}^2 - B\right)\bar{V}_{\text{new}} = A - \frac{C}{N_{\text{max}}} - \bar{V}_{\text{old}}B
$$

• This solves the voltage

# Theory #7 – Einstein approximation

• For current we use the Einstein approximation:

$$
\mu k_B T = Dq
$$

• … to obtain a simplified form for current density:

$$
\mathbf{J}_n=-qn\mu_n\nabla\phi_n
$$

• However, we are interested in the current at the cell's boundary and since we already use a linear approximation for V, using another linear approximation to interpolate n at the cell boundaries is going to lead to a very rapid numerical instability. This is because n depends on V exponentially. The optimal solution for the interpolation problem is given by the Scharfetter-Gummel Discretization

#### Theory #8 - Scharfetter-Gummel Discretization

• Scharfetter-Gummel Discretization for electrons:

$$
\mathbf{J}_n^{\text{mid}} = \frac{D^{\text{mid}}q}{dL_D} \left( \text{Ber}(\bar{V}^{\text{out}} - \bar{V}^{\text{in}}) n^{\text{out}} - \text{Ber}(\bar{V}^{\text{in}} - \bar{V}^{\text{out}}) n^{\text{in}} \right)
$$

• Where we use the Bernoulli function:

$$
\text{Ber}(x) = \frac{x}{e^x - 1}
$$



#### Theory #9 - Finite volume method

• Using the divergence theorem:

$$
\int_{\mathcal{V}} f(\mathbf{r}) d\mathcal{V} = \int_{\mathcal{V}} \nabla \cdot \mathbf{\Phi} d\mathcal{V} = \int_{S} \mathbf{\Phi} \cdot d\mathbf{S} \qquad \qquad \sum_{\text{faces}} \mathbf{\Phi} \cdot \mathbf{S} = \mathcal{V} f(\mathbf{r})
$$

• We discretize the equation for voltage:

$$
\sum_{\text{faces}} (V_{\text{new}}^{\text{out}} - \bar{V}_{\text{new}}^{\text{in}}) \frac{S}{d} - \mathcal{V} B \bar{V}_{\text{new}}^{\text{in}} = \mathcal{V} \left(A - \frac{C}{N_{\text{max}}} - \bar{V}_{\text{old}} B \right)
$$

• and for current continuity:

$$
\sum_{\text{faces}}\mathbf{J}_n^{\text{mid}}\cdot\mathbf{S}=-U_nq\mathcal{V}
$$

$$
\sum_{\text{faces}} \mathbf{J}^{\text{mid}}_p \cdot \mathbf{S} = U_p q \mathcal{V}
$$

#### Implementation - Gummel Iteration scheme

• For the initial guess we assume charge neutrality, which gives an analytical solution for the voltage.



- Solution is in the form (V, n, p)
- We need to adjust biasing of the simulated device in small steps, otherwise the solution will no longer converge

#### Implementation – discretization 1D

• 1D–easy: 
$$
(\bar{\nabla}^2 - B)\bar{V}_{\text{new}} = A - \frac{C}{N_{\text{max}}} - \bar{V}_{\text{old}}B
$$

• We calculate the second order derivative as follows:

$$
f''(\mathbf{x}_i) = \frac{1}{h^2} \begin{pmatrix} \dots & \dots & \dots & \dots & \dots \\ \dots & 1 & -2 & 1 & 0 & 0 & \dots \\ \dots & 0 & 1 & -2 & 1 & 0 & \dots \\ \dots & 0 & 0 & 1 & -2 & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} \uparrow \\ x_{j-1} \\ x_j \\ x_{j+1} \\ \downarrow \end{pmatrix}
$$

- The matrix only has non-zero elements next to the diagonal
- Note: we use sparse matrices

#### Implementation – DUNE Numerics

• DUNE, the Distributed and Unified Numerics Environment is a modular toolbox for solving partial differential equations (PDEs) with grid-based methods. It supports the easy implementation of methods like Finite Elements (FE), Finite Volumes (FV), and also Finite Differences (FD). [\(https://www.dune-project.org](https://www.dune-project.org/) )



**Distributed and Unified Numerics Environment** 

#### Implementation – discretization 3D

• Dune provides an easy way to find neighboring cells:

```
for(const auto& elem: elements(view))
 \mathcal{I}\overline{2}\left\{ \right.for(const auto& isect: intersections(view, elem))
 3
 \angle\{if(isect.boundary())5
                \{6
                      // code goes here
 \overline{7}\mathcal{F}8
                if(isect.neighbor())
 9
                \overline{\mathcal{X}}10
                      // code goes here
11
                \}1213
          \rightarrow14 }
```
The index of any element can be easily retrieved using the mapper concept:

mapper.index(elem)

#### Implementation – benefits of using DUNE

- Implementation is the same for any number of dimensions
- Implementation is independent of grid geometry
	- this allows us to use cells of variable sizes in the future
- Data output in the format of the visualization toolkit (vtk)
- BiCGSTABSolver from the Iterative Solvers Template Library
	- $\cdot$  Can run in parralel

#### ParaView

• Open source



#### Implementation - summary

- Simulate using the drift-diffusion model
	- good tradeoff between performance and accuracy
- Using C++
	- a lot faster since it is a compiled language
	- DUNE library
- Abstract implementation
	- we use templated classes that work with different data types
	- the implementation is independent from the grid's geometry and the number of dimensions
	- the mobility and recombination physics models used by the simulation can be easily changed

# Further work

- Port mobility & recombination models over to new code
- Implement insulating boundary conditions properly in 2D
- Parallelize (this should be easy due to the DUNE architecture)
- Compare with commercial simulators
- 3D
- Implement Newton iterations, and a "smart" heuristic for when to switch implementation strategies

#### Further work

There are 3 bits of "physics" we might want to add into our simulation (before going to more advanced equations entirely)

**Mobility models –** allowing mobility to vary with field and other quantities adds a lot more realism to driftdiffusion simulations

**Recombination / generation** – including SRH trapping, impact ionization, zener breakdown etc. **Thermodynamics** – swap Boltzmann out for Fermi-Dirac, this is a lot more accurate in some temperature regimes



$$
\mu_n(E) = \mu_{n0} \left[ 1 + \left( \frac{\mu_{n0} E}{V_{\text{sat}}^n} \right)^{\beta_n} \right]^{-\frac{1}{\beta_n}}
$$

$$
\mu_p(E) = \mu_{p0} \left[ 1 + \left( \frac{\mu_{p0} E}{V_{\text{sat}}^p} \right)^{\beta_p} \right]^{-\frac{1}{\beta_p}}
$$

**Xihan Deng & Yichen "Mac" Zhou Implemented several mobility and recombination models For our 1D python simulation in 2020/2021**

#### Integration with other software

- Simulator calculates the E-field structure from doping & geometry
- Can be used to provide field structure for Allpix Squared

# Thank you!

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