



IRISH RESEARCH COUNCIL
An Chomhairle um Thaighde in Éirinn

Gravitational wave fluxes for a spinning particle in the
Hamilton-Jacobi formalism
Work in progress...

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Spanish and Portuguese Relativity Meeting, 22-26 July 2024
University of Coimbra, Portugal

Extreme-mass ratio inspirals (EMRIs)

Primary mass M : $10^{5.5} - 10^7 M_{\odot}$

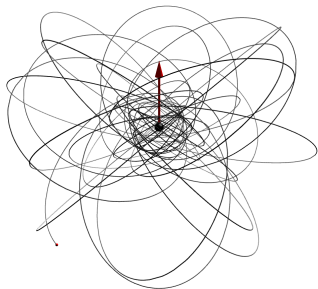
Secondary mass μ : $1 - 100 M_{\odot}$

$q = \mu/M \sim 10^{-4} - 10^{-7} \implies$ expand Einstein equations in q

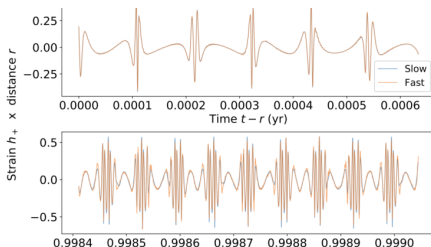
Some features:

mHz GWs \implies targets for LISA

$\sim 1/q$ orbits in 1 year before inspiral in strong gravity regime



Credit: Maarten van de Meent



Credit: Niels Warburton

Why should we consider a spinning secondary in EMRIs?

$$\Phi_{\text{GW}} = \underbrace{q^{-1}\mathcal{C}^{(0)}}_{\text{adiabatic}} + \underbrace{q^{-1/2}\mathcal{C}^{(1/2)}}_{\text{resonances}} + \underbrace{q^0\mathcal{C}^{(1)}}_{\text{post-1-adiabatic}} + \mathcal{O}(q)$$

$\mathcal{C}^{(1)}$ contains self force plus **secondary spin s effects**

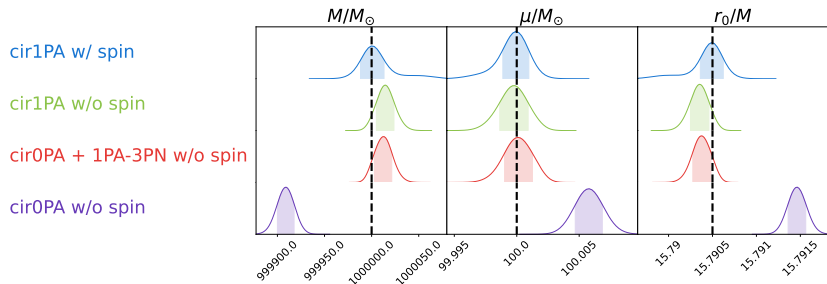


Figure: Biases if you neglect 1PA! ($q = 10^{-4}$). Burke, Piovano+, 2024

We propose a new method to produce EMRI waveform
for spinning binaries

EoM for a spinning body in first order form

(linearized) MPD equations of motion - 2nd order form

$$S/(\mu M) = qs \quad s = S/\mu^2 = \sqrt{s_{\parallel}^2 + s_{\perp}^2}$$

TD condition: $s^{\mu\nu} v_{\nu}^g = 0$

$$\left\{ \begin{array}{l} \frac{D_g v_g^{\mu}}{d\tau} = 0, \\ \frac{D_g v_s^{\mu}}{d\tau} = -\frac{1}{2} R^{\mu}_{\nu\rho\sigma} v_g^{\nu} s^{\rho\sigma}, \\ \frac{D_g s^{\mu\rho}}{d\tau} = 0, \end{array} \right.$$

Spin vector: $s^{\mu} = s_{\perp} (\tilde{e}_{(1)}^{\mu} \cos \psi_p + \tilde{e}_{(2)}^{\mu} \sin \psi_p) + s_{\parallel} e_{(3)}^{\mu}$

Precession angle: ψ_p

For generic orbits, see

Drummond&Hughes (2022), Skuopy+ (2023), Drummond+ (2024),
Witzany&Piovano (2024)

We solve MPD equation in 1st form

Geodesics equations of motion

$$\left\{ \begin{array}{l} \frac{dt_g}{d\lambda} = V_g^t(r_g) + V_g^t(z_g) \\ \frac{dr_g}{d\lambda} = \pm \sqrt{R_g(r_g)} = \pm \sqrt{(r_{1g} - r_g)(r_g - r_{2g}) Y_{rg}(r_g)} \\ \frac{dz_g}{d\lambda} = \pm \sqrt{Z_g(z_g)} = \pm \sqrt{(z_{1g} - z_g)^2 Y_{zg}(z_g)} \\ \frac{d\phi_g}{d\lambda} = V_g^\phi(r_g) + V_g^\phi(z_g) \end{array} \right.$$

$z = \cos \theta$ and $\lambda =$ Mino time

EoM fully separable!!!

See

- Carter Phys. Rev. (1968) 174, 1559
- Schmidt CQG (2002) 19 2743
- Fujita and Hikida (2009) CQG 26 135002
- van de Meent (2020) CQG 37 145007

(linearized) MPD equations of motion - 1st order form

Spin-corrections to the 4-velocities in the Hamilton-Jacobi formalism¹

$$\left\{ \begin{array}{l} \frac{dt_s}{d\lambda} = \frac{\partial V_{rg}^t}{\partial r_g} \delta r + \frac{\partial V_{zg}^t}{\partial z_g} \delta z + \sum_{i=1}^2 \frac{\partial V_g^t}{\partial C_i} \delta C_i + V_s^t \\ \frac{dr_s}{d\lambda} = \pm \frac{1}{2\sqrt{R_g}} \left(\frac{\partial R_g}{\partial r_g} \delta r + \sum_{i=1}^3 \frac{\partial R_g}{\partial C_i} \delta C_i + R_s \right) \\ \frac{dz_s}{d\lambda} = \pm \frac{1}{2\sqrt{Z_g}} \left(\frac{\partial Z_g}{\partial z_g} \delta z + \sum_{i=1}^3 \frac{\partial Z_g}{\partial C_i} \delta C_i + Z_s \right) \\ \frac{d\phi_s}{d\lambda} = \frac{\partial V_{rg}^\phi}{\partial r_g} \delta r + \frac{\partial V_{zg}^\phi}{\partial z_g} \delta z + \sum_{i=1}^2 \frac{\partial V_g^\phi}{\partial C_i} \delta C_i + V_s^\phi \end{array} \right.$$

with $(C_1, C_2, C_3) = (E_g, L_{zg}, K_g)$. EoM valid for any orbits!

EoM **non-separable** because of R_s, Z_s , and V_s^t, V_s^ϕ

¹Original form derived in Witzany, PRD 100 (2019) 10, 104030

Radial and polar spin corrections

$$\frac{dr_s}{d\lambda} = \pm \frac{1}{2\sqrt{R_g}} \left(\frac{\partial R_g}{\partial r_g} \delta r + \sum_{i=1}^3 \frac{\partial R_g}{\partial C_i} \delta C_i + R_s \right)$$
$$\frac{dz_s}{d\lambda} = \pm \frac{1}{2\sqrt{Z_g}} \left(\frac{\partial Z_g}{\partial z_g} \delta z + \sum_{i=1}^3 \frac{\partial Z_g}{\partial C_i} \delta C_i + Z_s \right)$$

$$(C_1, C_2, C_3) = (E_g, L_{zg}, K_g).$$

$$G_s = s_{\parallel} G_{s\parallel}(r_g, z_g) + s_{\perp} \sin(\psi_p) G_{s\perp}(r_g, z_g) + s_{\perp} \cos(\psi_p) G_{s\perp}(r_g, z_g)$$

for $G_s = R_s, Z_s$.

EoM non-separable because of R_s, Z_s !

$$\delta y = s_{\parallel} \delta y_{\parallel}(r_g, z_g) + s_{\perp} \sin(\psi_p) \delta y_{\perp}^{sn}(r_g, z_g) + s_{\perp} \cos(\psi_p) \delta y_{\perp}^{cn}(r_g, z_g)$$

for $y = r, z$. Removable singularities at the geodesic turning points

Azimuthal and coordinate time spin corrections

$$\frac{dt_s}{d\lambda} = \frac{\partial V_{rg}^t}{\partial r_g} \delta r + \frac{\partial V_{zg}^t}{\partial z_g} \delta z + \sum_{i=1}^2 \frac{\partial V_g^t}{\partial C_i} \delta C_i + V_s^t$$
$$\frac{d\phi_s}{d\lambda} = \frac{\partial V_{rg}^\phi}{\partial r_g} \delta r + \frac{\partial V_{zg}^\phi}{\partial z_g} \delta z + \sum_{i=1}^2 \frac{\partial V_g^\phi}{\partial C_i} \delta C_i + V_s^\phi$$

$$(C_1, C_2, C_3) = (E_g, L_{zg}, K_g)$$

$$V_s^{t,\phi} = s_{\parallel} V_{s_{\parallel}}^{t,\phi}(r_g, z_g) + s_{\perp} \sin(\psi_p) V_{s_{\perp}}^{t,\phi}(r_g, z_g) + s_{\perp} \cos(\psi_p) V_{s_{\perp}}^{t,\phi}(r_g, z_g)$$

EoM **non-separable** because of V_s^t, V_s^ϕ !

But easy to solve with Fourier series once you have δr and δz .

What is fixed and what is shifted? - part 1

We solved EoM in two parametrizations:

- fixed constants of motion (FC): $\delta E = \delta L_z = \delta K = 0$ ($\delta C_i = 0$)
- fixed (on average) turning points (DH): $\langle r_{1s}^{\text{DH}} \rangle = \langle r_{2s}^{\text{DH}} \rangle = \langle z_{1s}^{\text{DH}} \rangle = 0$

Easier to compute frequencies in the FC way:

$$\Upsilon_{ys}^{\text{FC}} = \frac{\Upsilon_{yg}}{2\pi} \int_0^{2\pi} d\chi_y f(y_g(\chi_y), K, E, \Pi) \quad y = r, z$$

Similar expressions for $\Upsilon_{ts}^{\text{FC}}$ and $\Upsilon_{\phi s}^{\text{FC}}$

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Now it's plotting time!

Spin flags! - fixed constants of motion

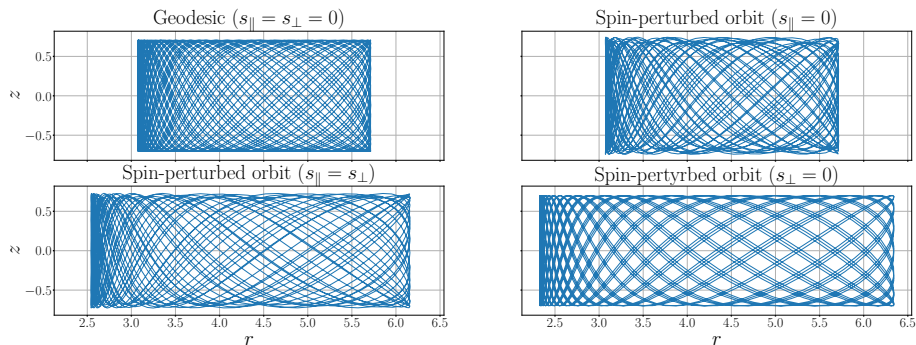


Figure: r vs z plots, $q = 1/20$
 $a = 0.9, p = 4, e = 0.3, z_{1g} = 1/\sqrt{2}$

Spin flags! - fixed turning points (on average)

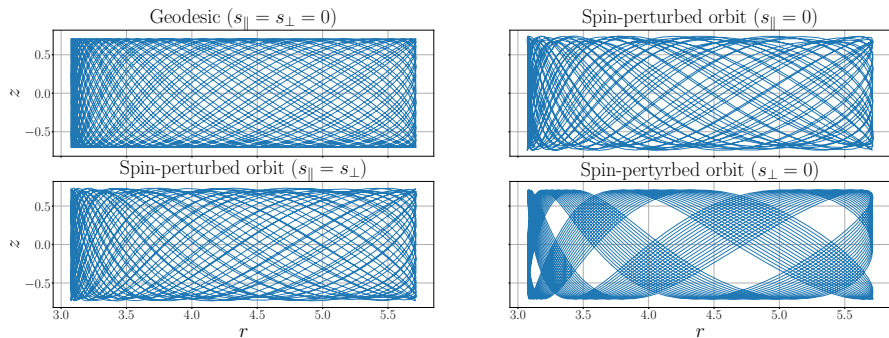


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Projection over the xy plane

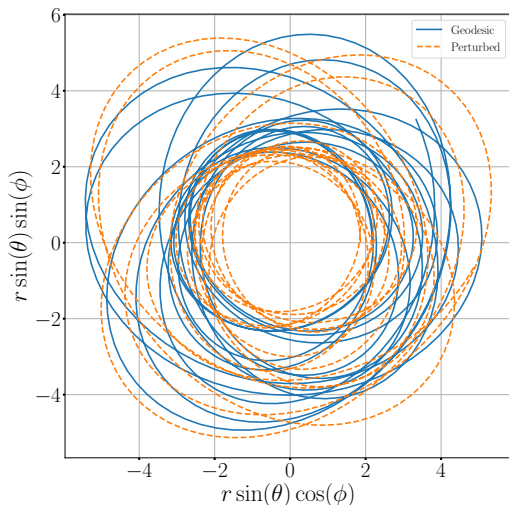


Figure: Projection over the xy plane. Fixed constants of motion, $q = 1/20$
 $a = 0.9, p = 4, e = 0.3, z_{1g} = 1/\sqrt{2}, s_{||} = s_{\perp} = 1/\sqrt{2}$

Gravitational waveforms for a spin-precessing secondary

Teukolsky waveforms for spin precessing secondary

$$h = -\frac{2\mu}{r} \sum_{\ell m \vec{k}} (\mathcal{A}_{\ell m \vec{k}}^g + q \delta \mathcal{A}_{\ell m \vec{k}}^s) e^{im\varphi} e^{-i(\omega_{m\vec{k}}^g + qs_{\parallel} \omega_{m\vec{k}}^s)}$$

where $u = t - r^*$, $\vec{k} = (n, k, j)$, $j = -1, 0, 1$

$$\omega_{m\vec{k}}^g = m\Omega_{\phi g} + n\Omega_{\text{rg}} + k\Omega_{\text{zg}} + j\Omega_{\text{pg}}$$

$$\omega_{m\vec{k}}^s = m\Omega_{\phi s} + n\Omega_{\text{rs}} + k\Omega_{\text{zs}} + j\Omega_{\text{ps}}$$

$$\mathcal{A}_{\ell m n k 1}^g = \mathcal{A}_{\ell m n k -1}^g = 0 \text{ (no dependence on } \psi_p \text{)}$$

$$s_{\parallel} \text{ terms: } \delta \mathcal{A}_{\ell m n k 0}^s \quad s_{\perp} \text{ terms: } \delta \mathcal{A}_{\ell m n k \pm 1}^s$$

Write precessing amplitudes as

$$\delta \mathcal{A}_{\ell m n k \pm 1}^s = |\delta \mathcal{A}_{\ell m n k \pm 1}^s| e^{i \arg(\delta \mathcal{A}_{\ell m n k \pm 1}^s)}$$

- $\arg(\delta \mathcal{A}_{\ell m n k \pm 1}^s)$ is a 2PA term
- Detecting $|\delta \mathcal{A}_{\ell m n k \pm 1}^s|$ requires $\text{SNR} \sim 1/q \dots^2$

²See Burke, Piovano+, PRD 109 (2024) 12, 124048

Computation asymptotic amplitudes

- Computed dominant GW fluxes \mathcal{F}^g and correction \mathcal{F}^s (both for energy and angular momentum)

$$\mathcal{F}^g \propto |\mathcal{A}_{\ell mnk0}^g| \quad \mathcal{F}^s \propto q \mathcal{A}_{\ell mnk0}^{g*} \delta \mathcal{A}_{\ell mnk0}^s + \text{c.c.}$$

- \mathcal{F}^s independent on s_{\perp} because $\mathcal{A}_{\ell mnk\pm 1}^{g*} = 0$
- **Excellent agreement** with Skuopy+, PRD 108 (2023) 4, 044041
- Still need to compute amplitude correction to s_{\perp} : $\delta \mathcal{A}_{\ell mnk\pm 1}^s$

Conclusions and future perspective

Conclusions

We solved MPD equations in 1st form for generic orbits and spin orientation

- excellent agreement with previous results with MPD equations in 2nd order form
- maps between fixed turning points (on average) and fixed constant of motion parametrizations
- ready-to-use expressions for spin corrections to the frequencies

TO DO list

- compute Teukolsky waveform amplitudes with spin-precession...

Paper on arXiv ~~before mid-August~~ before XMas soon!

Final notes and acknowledgments

- Special thanks to Viktor Skuopy and Lisa Drummond for kindly share their codes and data!
- A huge thanks to my collaborators Christiana, Jake and Vojtěch
- this work is proudly powered by the mighty BHPToolkit🌀

<https://bhptoolkit.org/>

Check it out! It is free!

Recommended by 9 out of 10 self-force researchers!*

*Based on pure speculations and not a real survey

- Feel free to contact me at gabriel.piovano@ucd.ie

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Thank you for you attention!

Backup slides

What is fixed and what is shifted? - part 2

Shifts to the constants of motion and frequencies in the DH way

$$\langle r_{1s}^{\text{DH}} \rangle = \langle r_{2s}^{\text{DH}} \rangle = \langle z_{1s}^{\text{DH}} \rangle = 0$$

$$\begin{pmatrix} \delta E^{\text{DH}} \\ \delta L_z^{\text{DH}} \\ \delta K^{\text{DH}} \end{pmatrix} = - \begin{pmatrix} \frac{\partial E_g}{\partial r_{1g}} & \frac{\partial E_g}{\partial r_{2g}} & \frac{\partial E_g}{\partial z_{1g}} \\ \frac{\partial L_{zg}}{\partial r_{1g}} & \frac{\partial L_{zg}}{\partial r_{2g}} & \frac{\partial L_{zg}}{\partial z_{1g}} \\ \frac{\partial K_g}{\partial r_{1g}} & \frac{\partial K_g}{\partial r_{2g}} & \frac{\partial K_g}{\partial z_{1g}} \end{pmatrix} \cdot \begin{pmatrix} \langle r_{1s}^{\text{FC}} \rangle \\ \langle r_{2s}^{\text{FC}} \rangle \\ \langle z_{1s}^{\text{FC}} \rangle \end{pmatrix}$$

$$\gamma_{\text{xs}}^{\text{DH}} = \gamma_{\text{xs}}^{\text{FC}} - \frac{\partial \gamma_{\text{xg}}}{\partial r_{1g}} \langle r_{1s}^{\text{FC}} \rangle - \frac{\partial \gamma_{\text{xg}}}{\partial r_{2g}} \langle r_{2s}^{\text{FC}} \rangle - \frac{\partial \gamma_{\text{xg}}}{\partial z_{1g}} \langle z_{1s}^{\text{FC}} \rangle \quad \text{x = t, r, z, } \phi$$

Amazing agreement with

Drummond&Hughes, PRD 105 (2022) 12, 124041 and
PRD 105 (2022) 12, 124040!

Perturbed radial motion

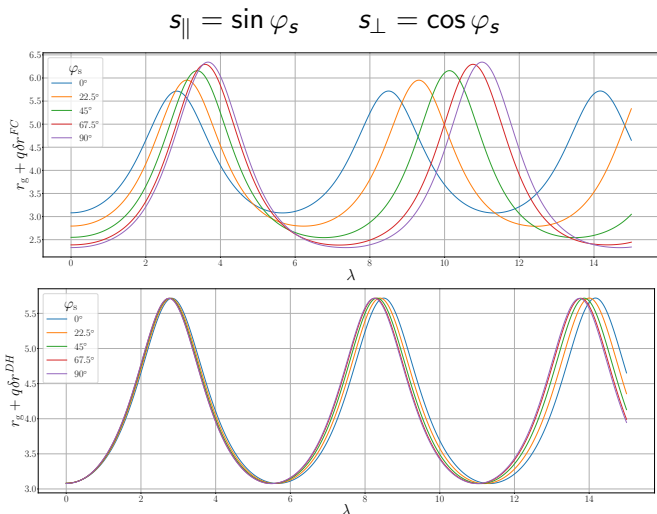


Figure: Top: fixed constants of motion. Bottom: fixed turning points (on average)

$$q = 1/20, a = 0.9, p = 4, e = 0.3, z_{1g} = 1/\sqrt{2}$$