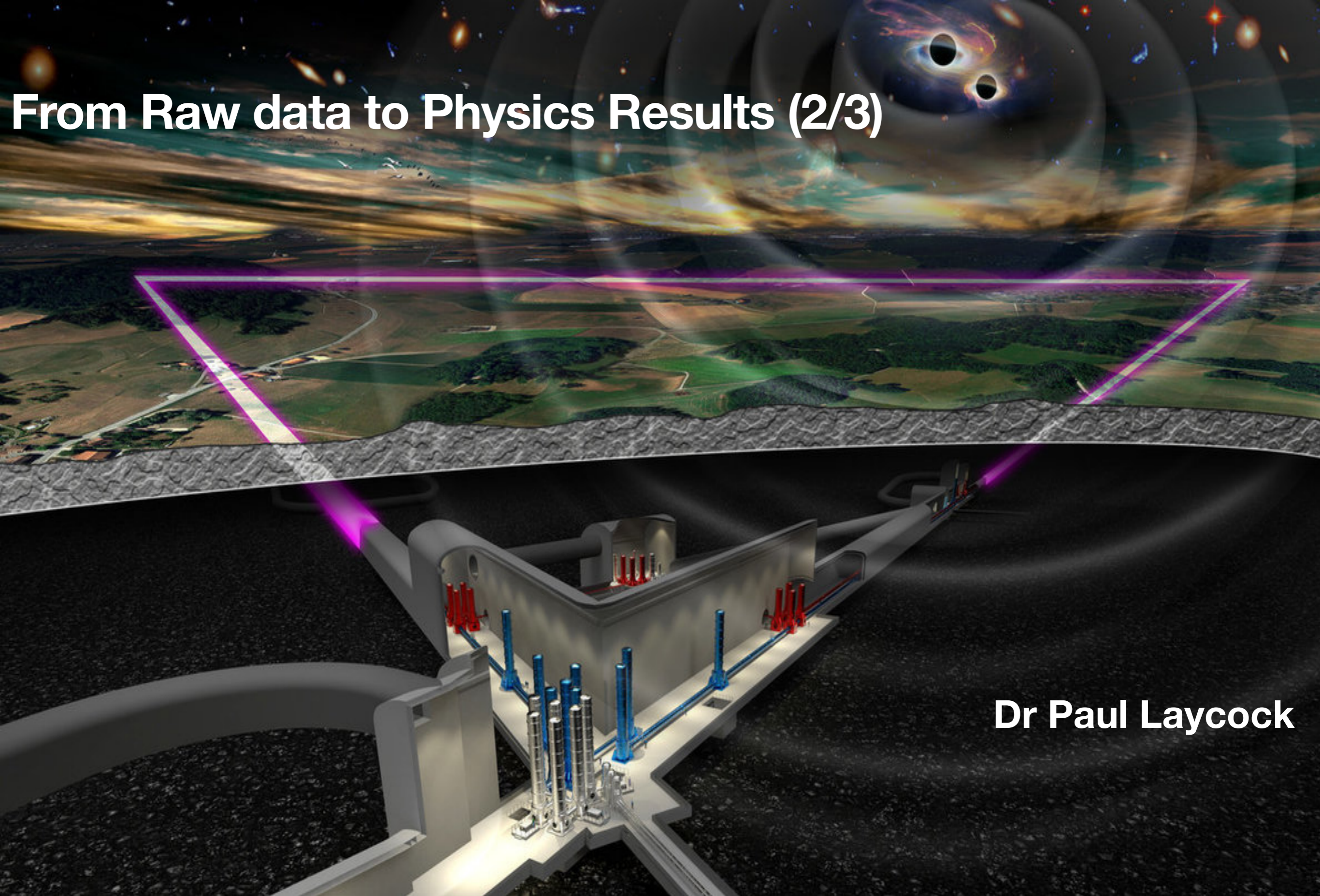
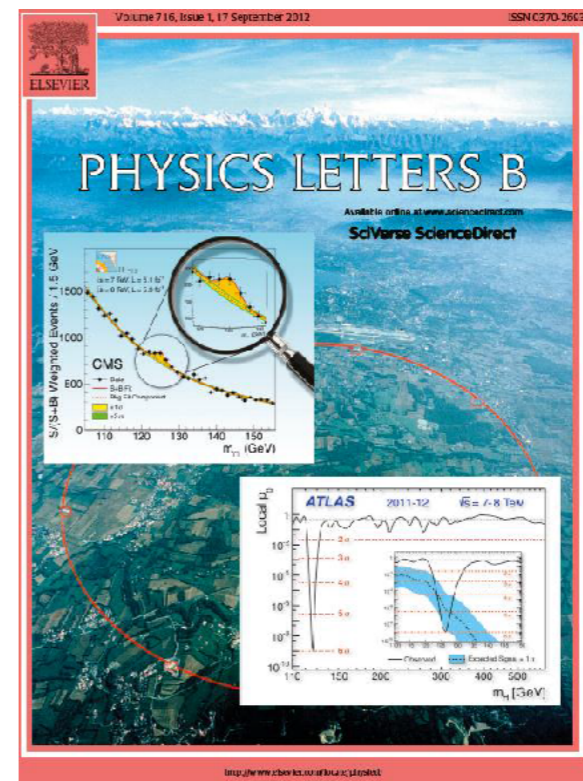
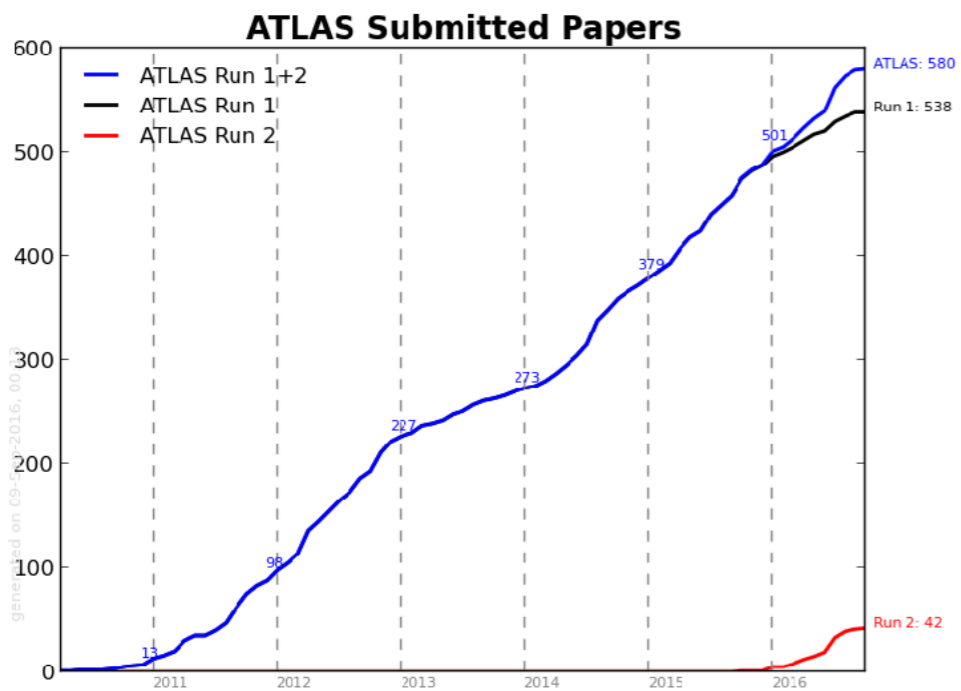
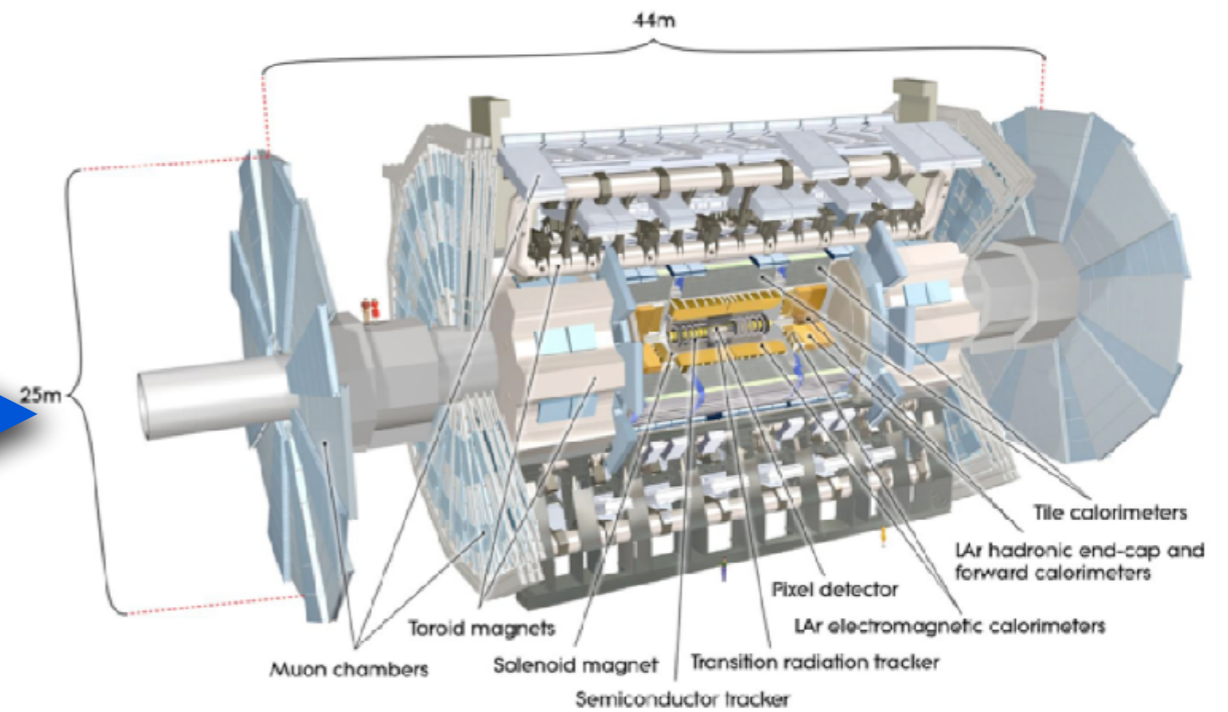
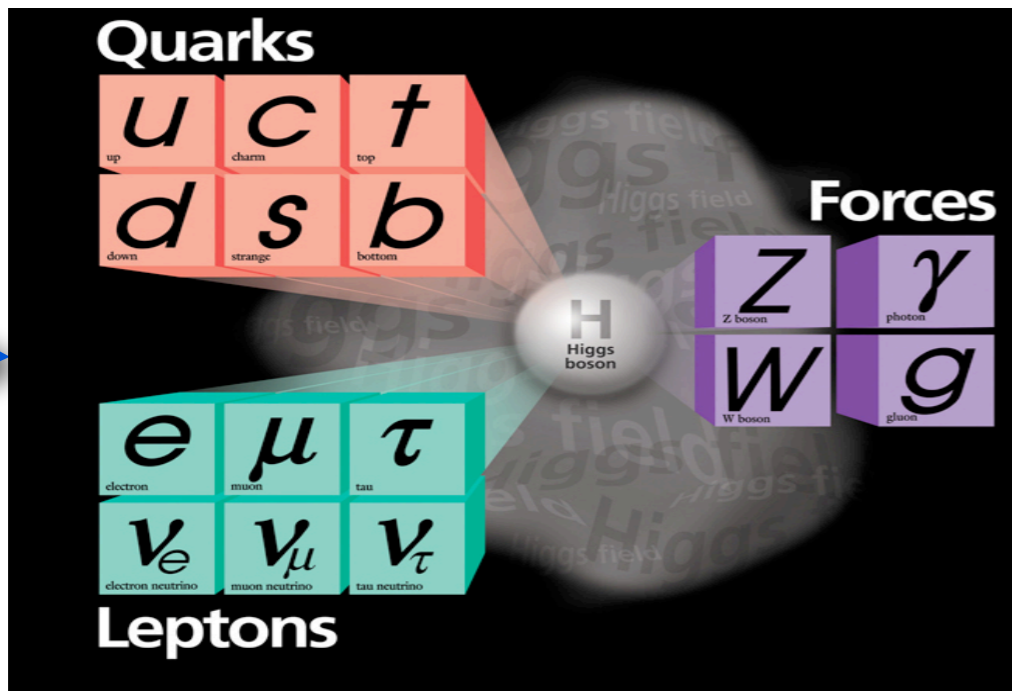


From Raw data to Physics Results (2/3)



Dr Paul Laycock

The particle physics cycle



Course outline

- **Lecture 1**

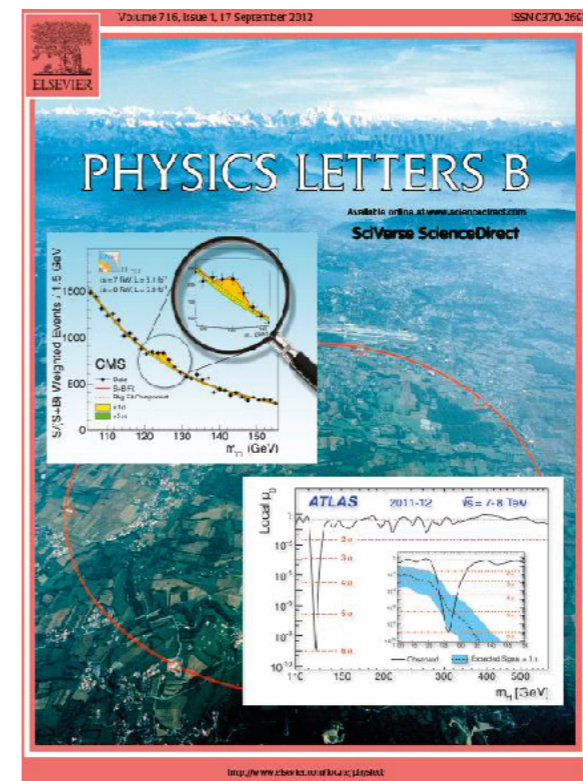
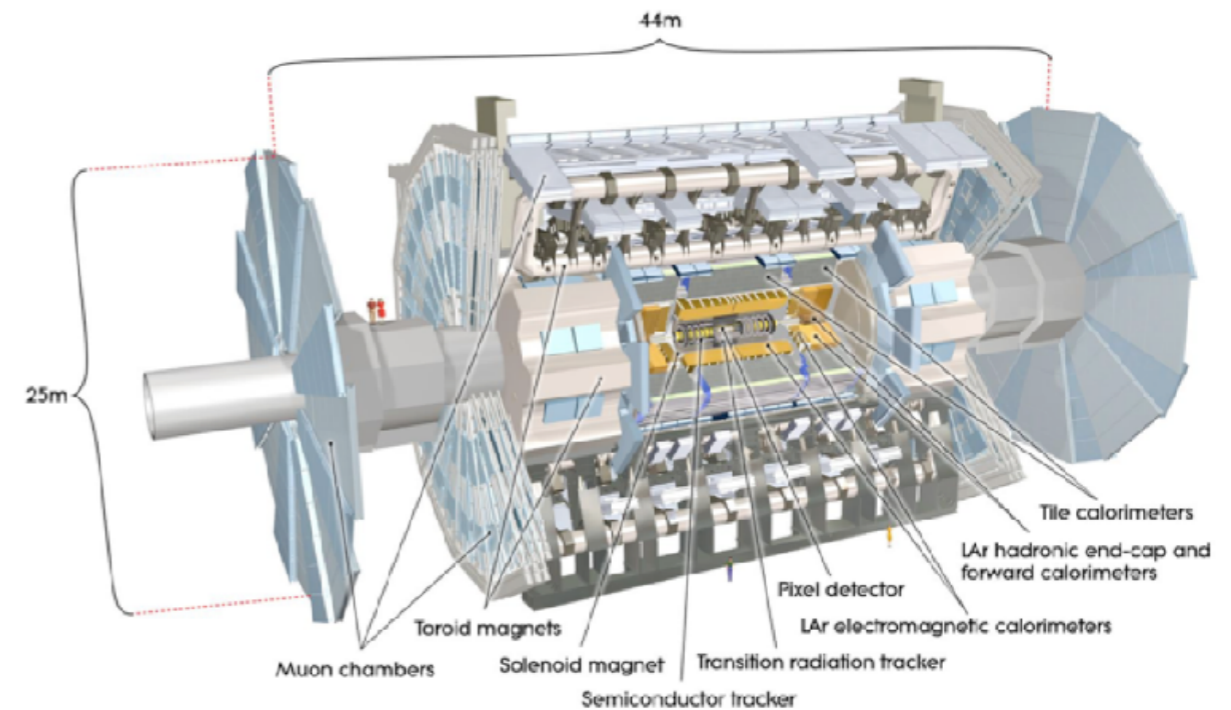
- The journey of raw data from the detector to a publication

- **Lecture 2**

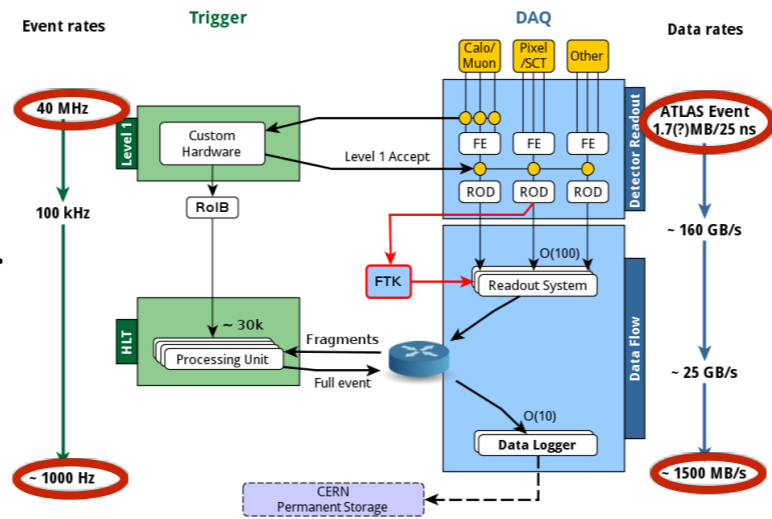
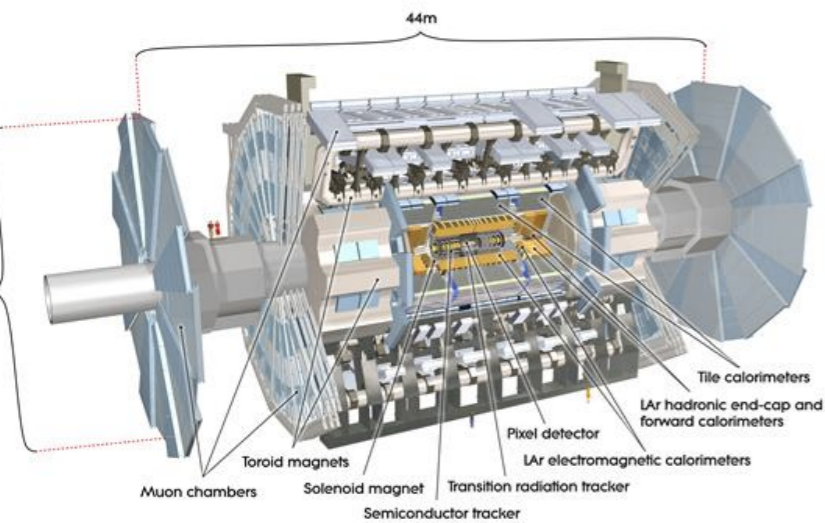
- How we reconstruct fundamental physics processes from raw detector data

- **Lecture 3**

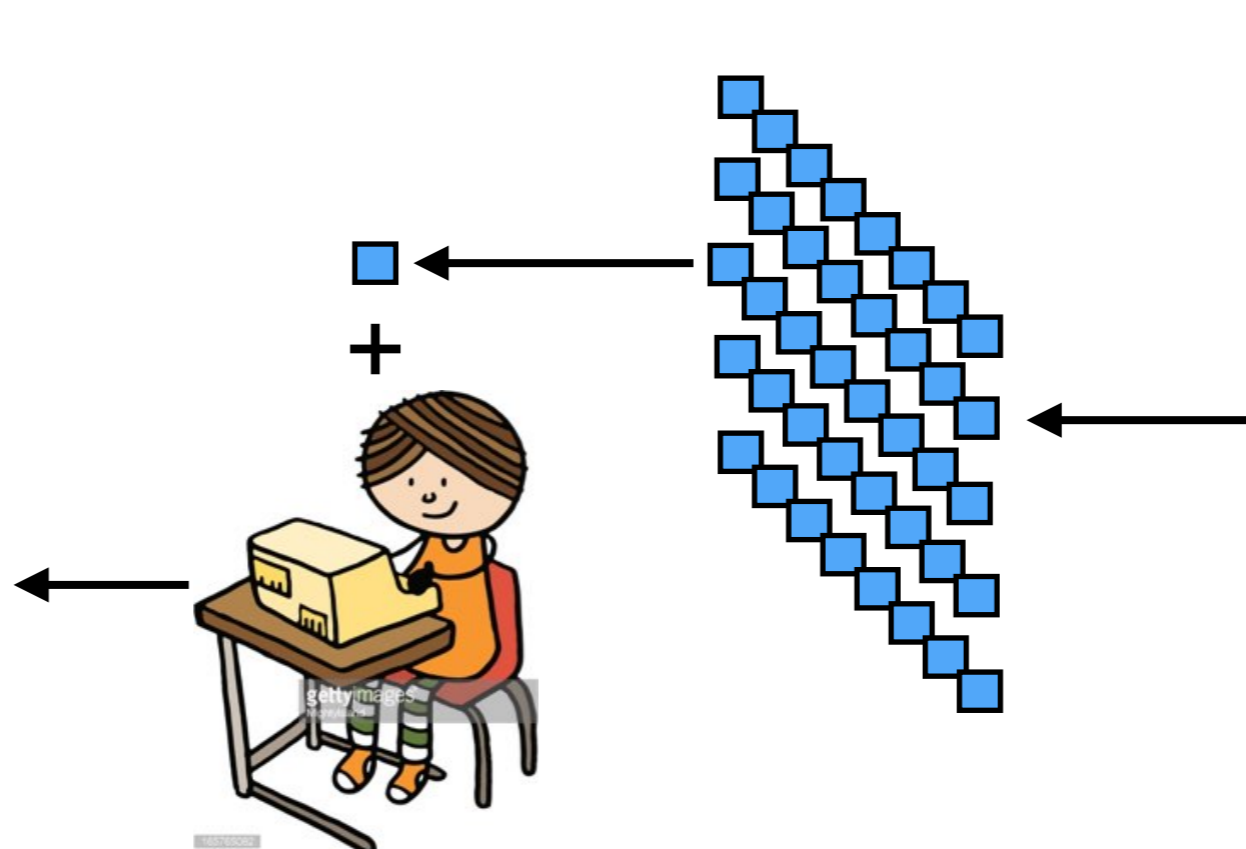
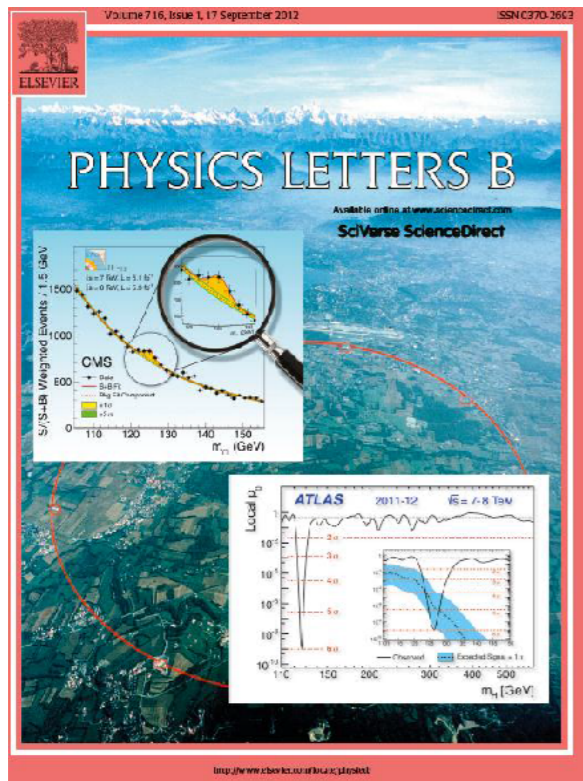
- How we extract our signals from the mountain of data, finding needles in the haystack



Data's journey

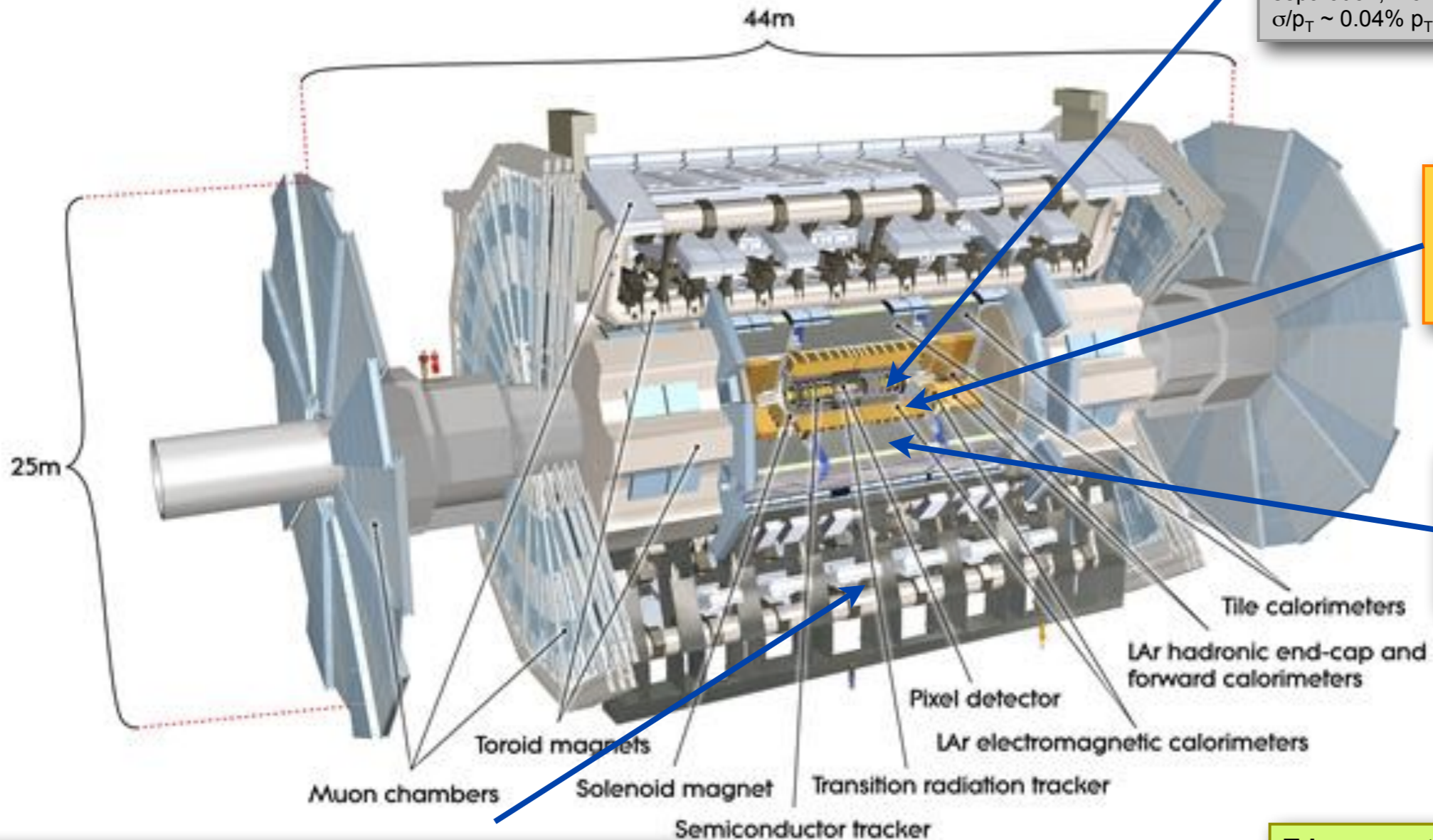


Data Preparation



The ATLAS Detector @ LHC

L ~ 46 m, \varnothing ~ 22 m, 7000 tons
~ 10^8 electronic channels



Inner Tracker ($|\eta| < 2.5$, $B=2T$):
Si Pixels, Si strips, Trans. Rad. Det.
Precise tracking and vertexing, e/π
separation, momentum resolution:
 $\sigma/p_T \sim 0.04\% p_T (\text{GeV}) \oplus 1.5\%$

EM calorimeter:
Pb-LAr Accordion, e/γ
trigger, id. and meas.,
energy res.: $\sigma/E \sim$
 $10\%/\sqrt{E} \oplus 0.7\%$

HAD calorimetry ($|\eta| < 5$): Fe/
scintillator Tiles (cen), Cu/W-LAr
(fwd). trigger and meas. of jets
and $E_{T,miss}$, energy res.: $\sigma/E \sim$
 $50\%/\sqrt{E} \oplus 3\%$

Muon Spectrometer: air-core toroids with gas-based muon chambers.
trigger and meas. with momentum resolution $< 10\%$ up to $E_\mu \sim 1 \text{ TeV}$

Trigger system: 3-levels reducing
the IA rate from 40 MHz to ~200 Hz

Millions of detector readout channels read out to reconstruct one “event”

Data Preparation

- Three major steps to **prepare data for physics analysis** and achieve
 - reliable, high quality data (yes, we **reject** low quality data)
 - the **best performance** from our detectors
 - readiness for **physics analysis**

1. Reconstruct physics signals from the data

- Produce information like how many muons does the event have?

Muon Spectrometer

Hadronic Calorimeter

Electromagnetic Calorimeter

Tracking

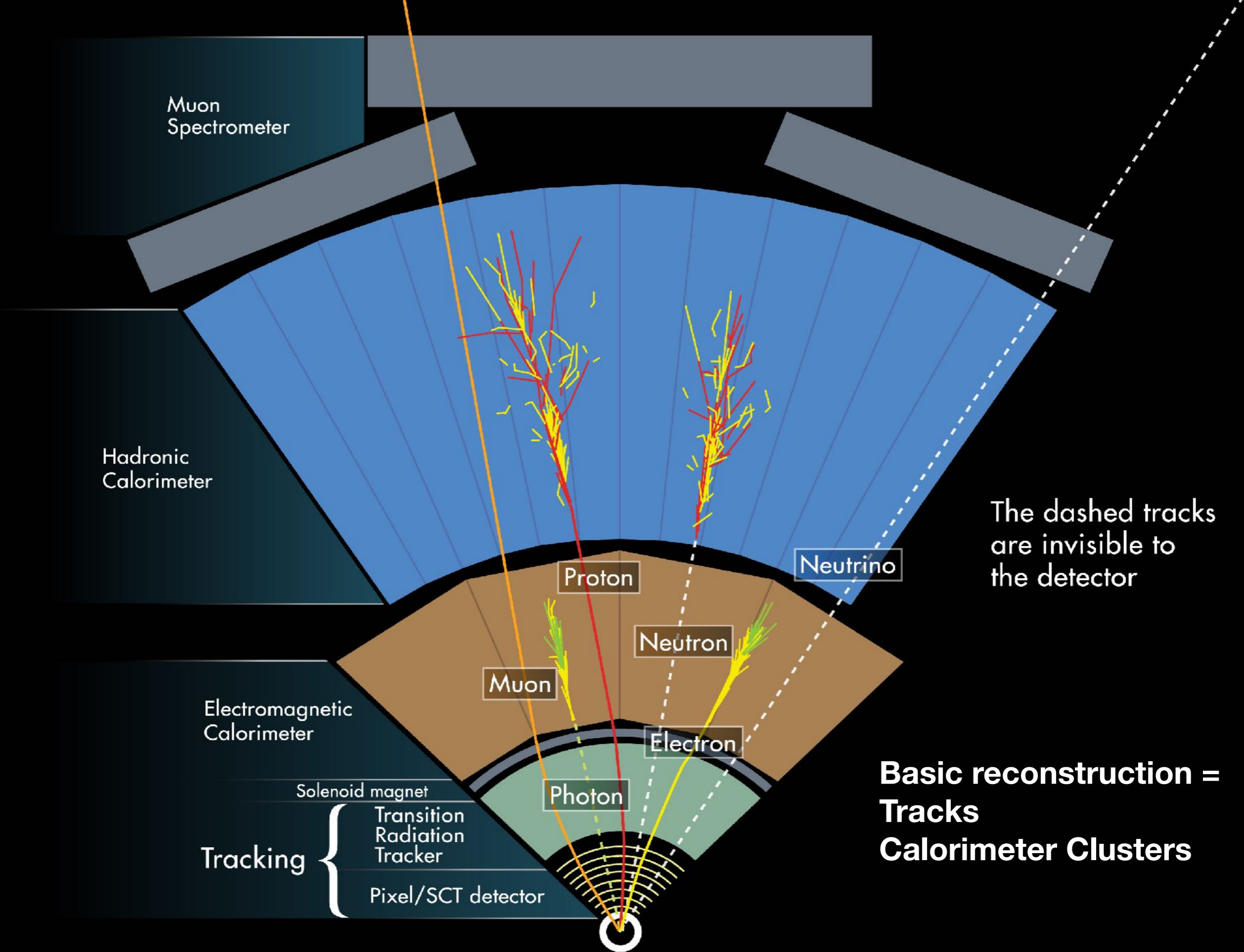
Solenoid magnet

Transition Radiation Tracker

Pixel/SCT detector

The dashed tracks are invisible to the detector

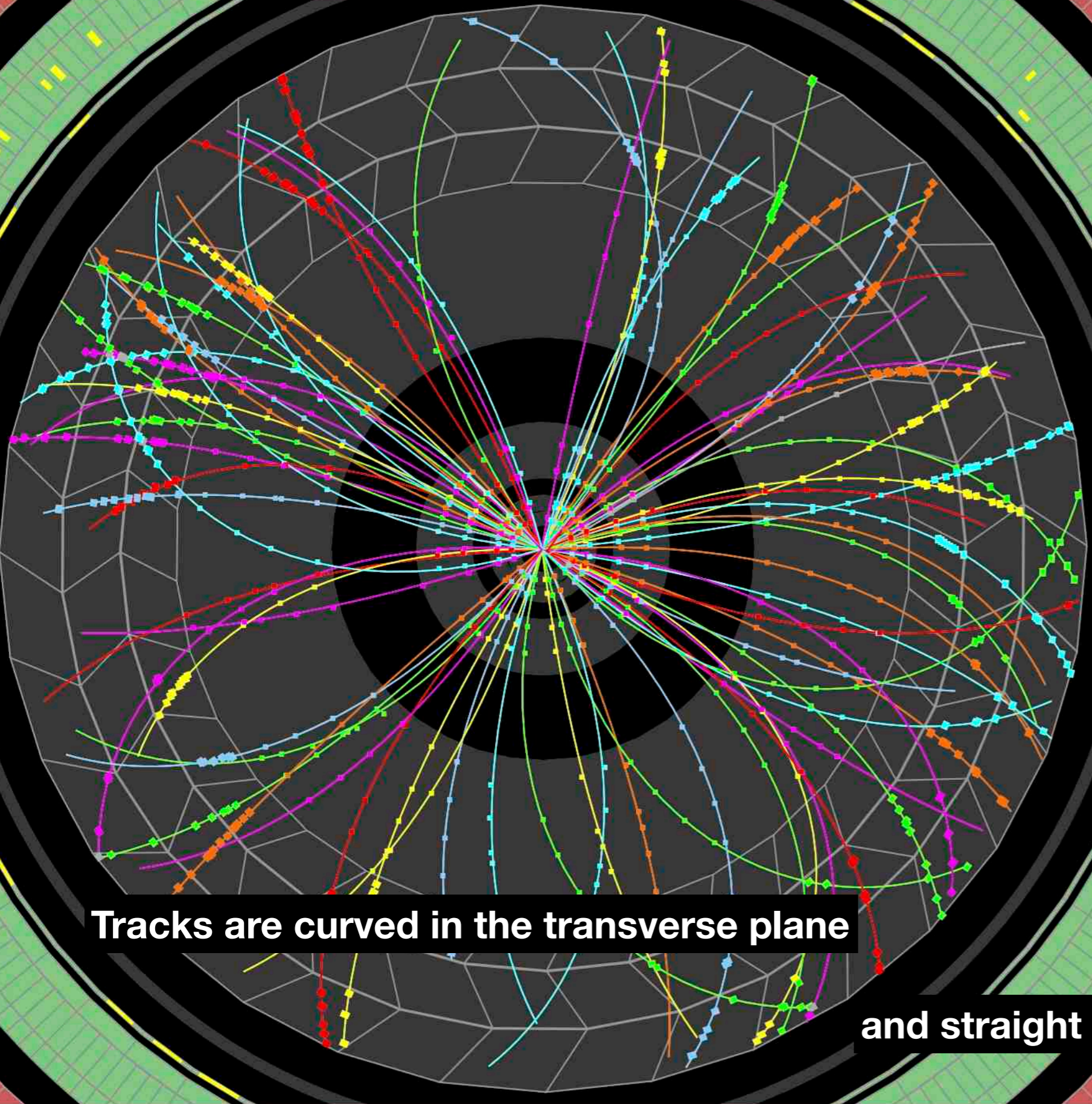
**Basic reconstruction =
Tracks
Calorimeter Clusters**



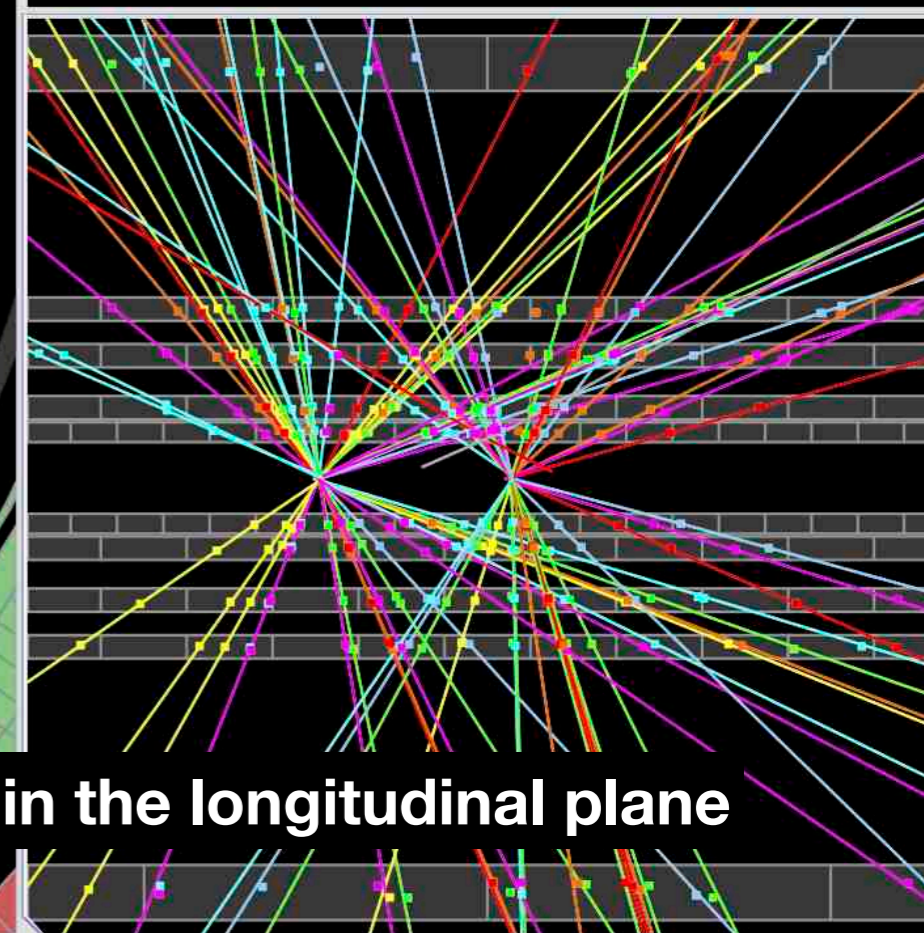


Run Number: 265545, Event Number: 5720351

Date: 2015-05-21 10:39:54 CEST



Tracks are curved in the transverse plane



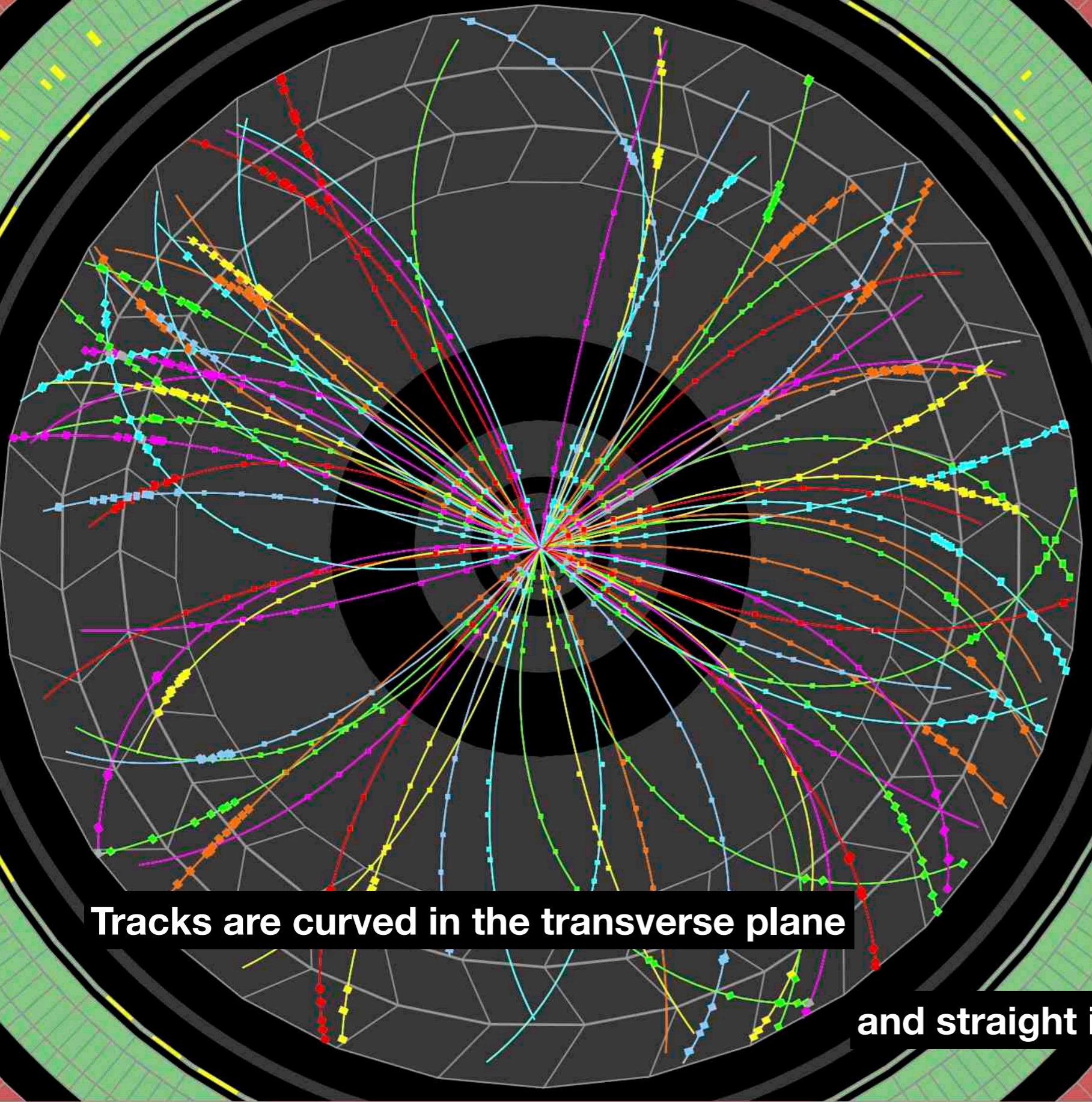
and straight in the longitudinal plane

This is a pattern recognition problem, which technique might be used to solve it?

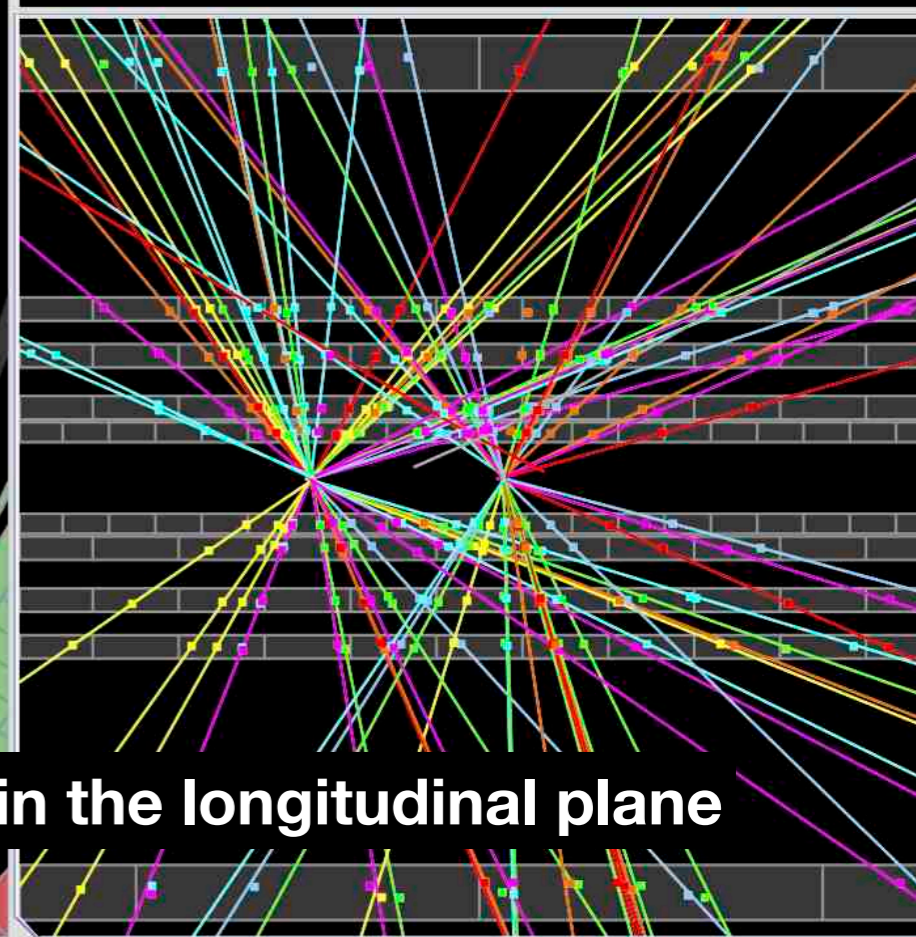


Run Number: 265545, Event Number: 5720351

Date: 2015-05-21 10:39:54 CEST



Tracks are curved in the transverse plane

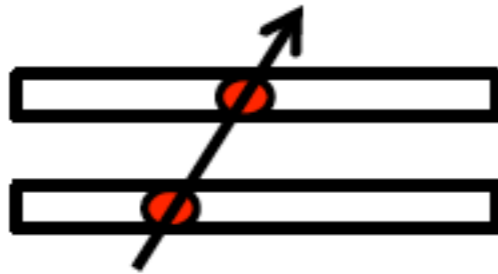


and straight in the longitudinal plane

Modern track pattern recognition uses Machine Learning: Connect the Dots

Track fitting

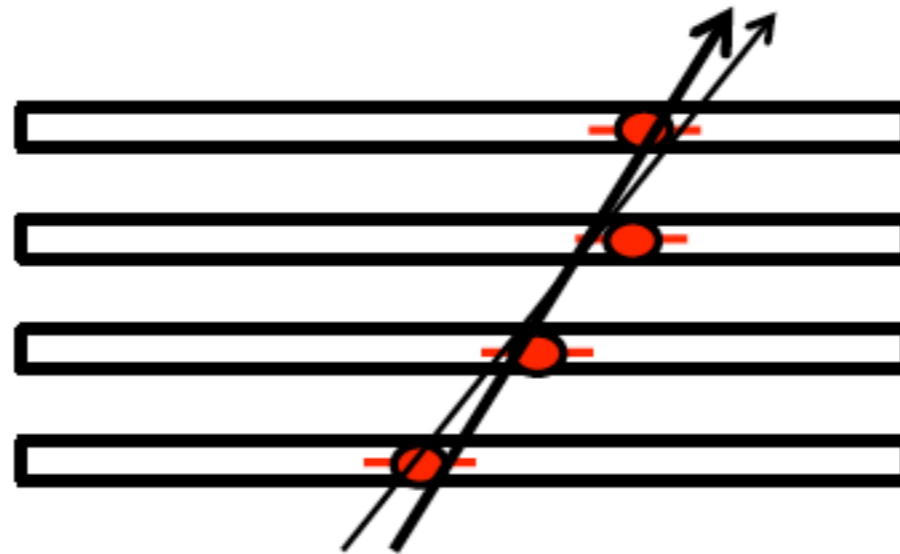
⊙ Perfect measurement – ideal



⊙ Imperfect measurement – reality



⊙ Small errors and more points help to constrain the possibilities



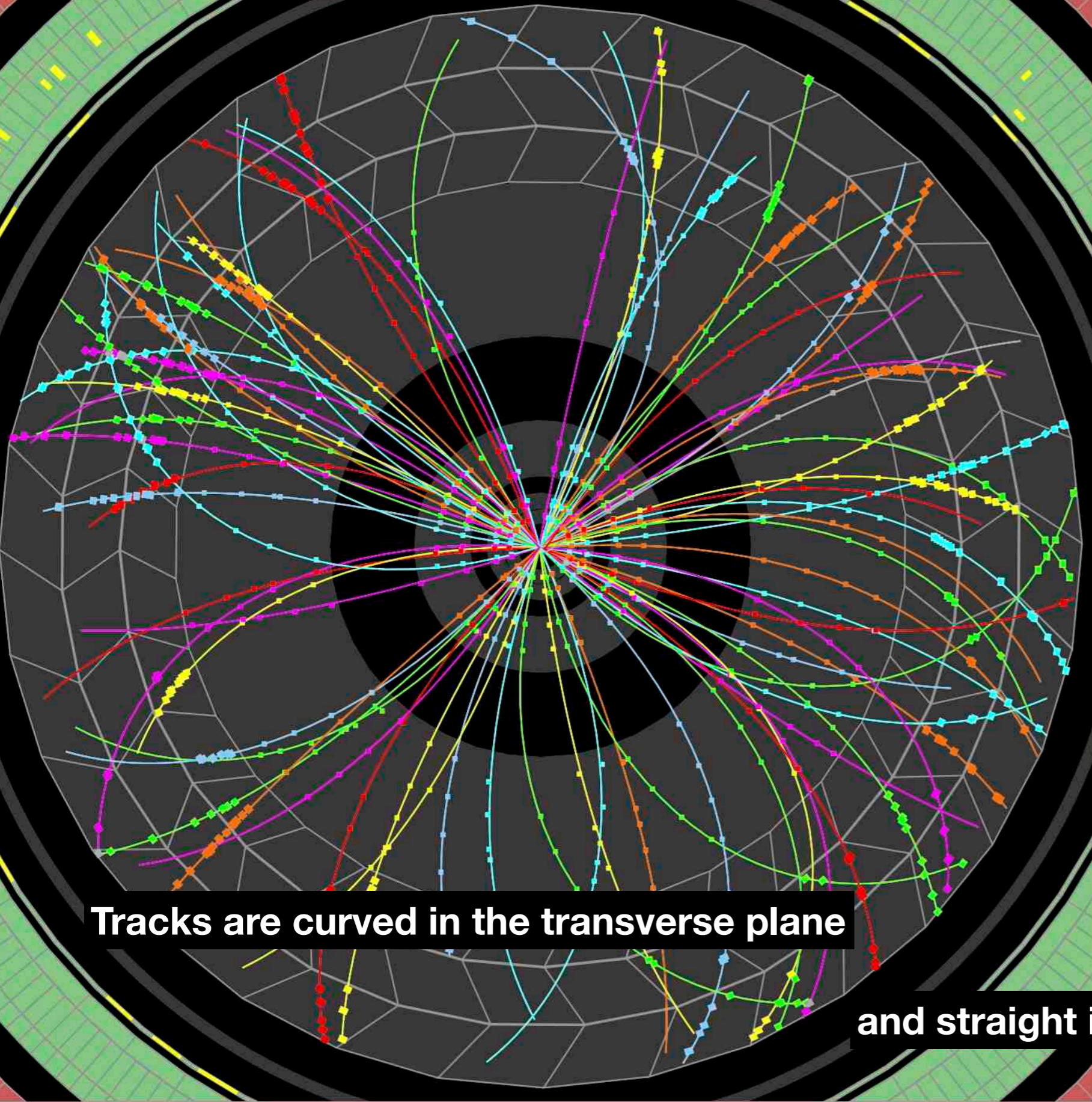
⊙ Quantitatively:

- ⊙ Parameterize the track;
- ⊙ Find parameters by Least-Squares-Minimization;
- ⊙ Obtain also uncertainties on the track parameters.

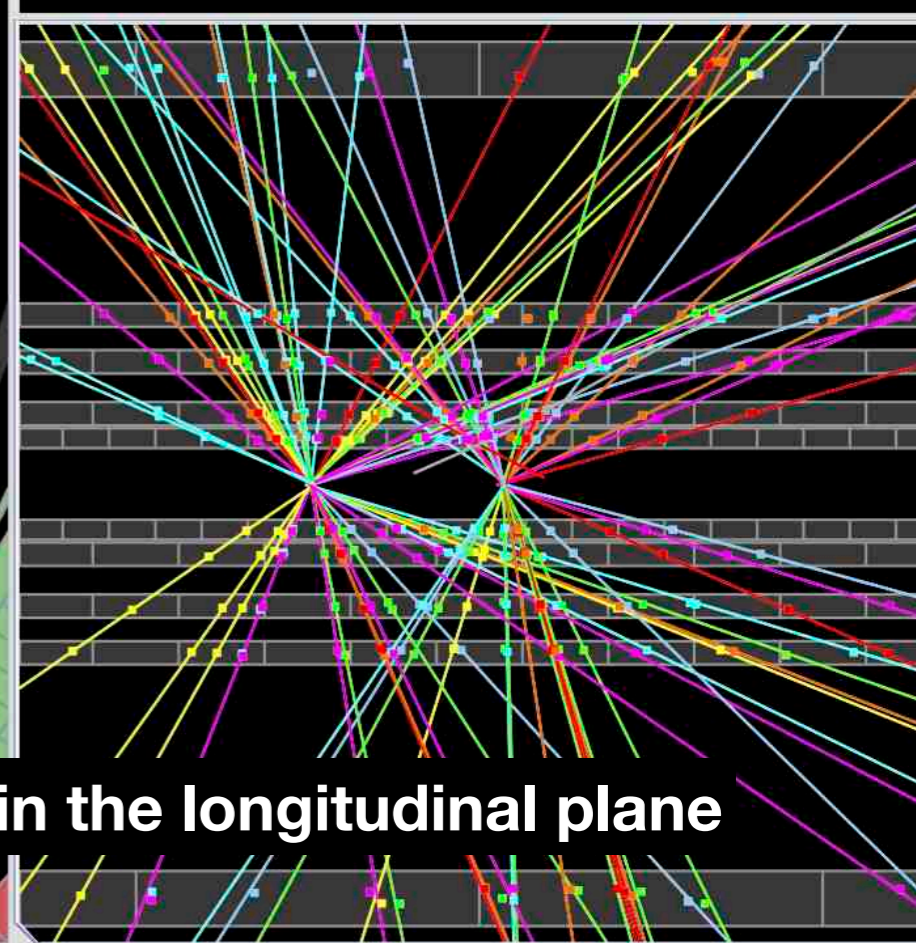


Run Number: 265545, Event Number: 5720351

Date: 2015-05-21 10:39:54 CEST



Tracks are curved in the transverse plane



and straight in the longitudinal plane

Q. What would be a good track model ?

Here be dragons... and muons

Muon Spectrometer

Hadronic Calorimeter

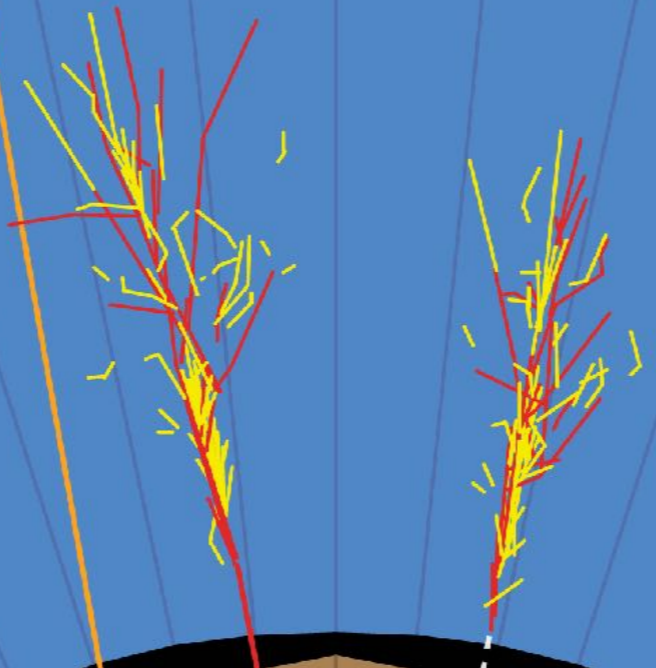
Electromagnetic Calorimeter

Solenoid magnet

Tracking

Transition Radiation Tracker

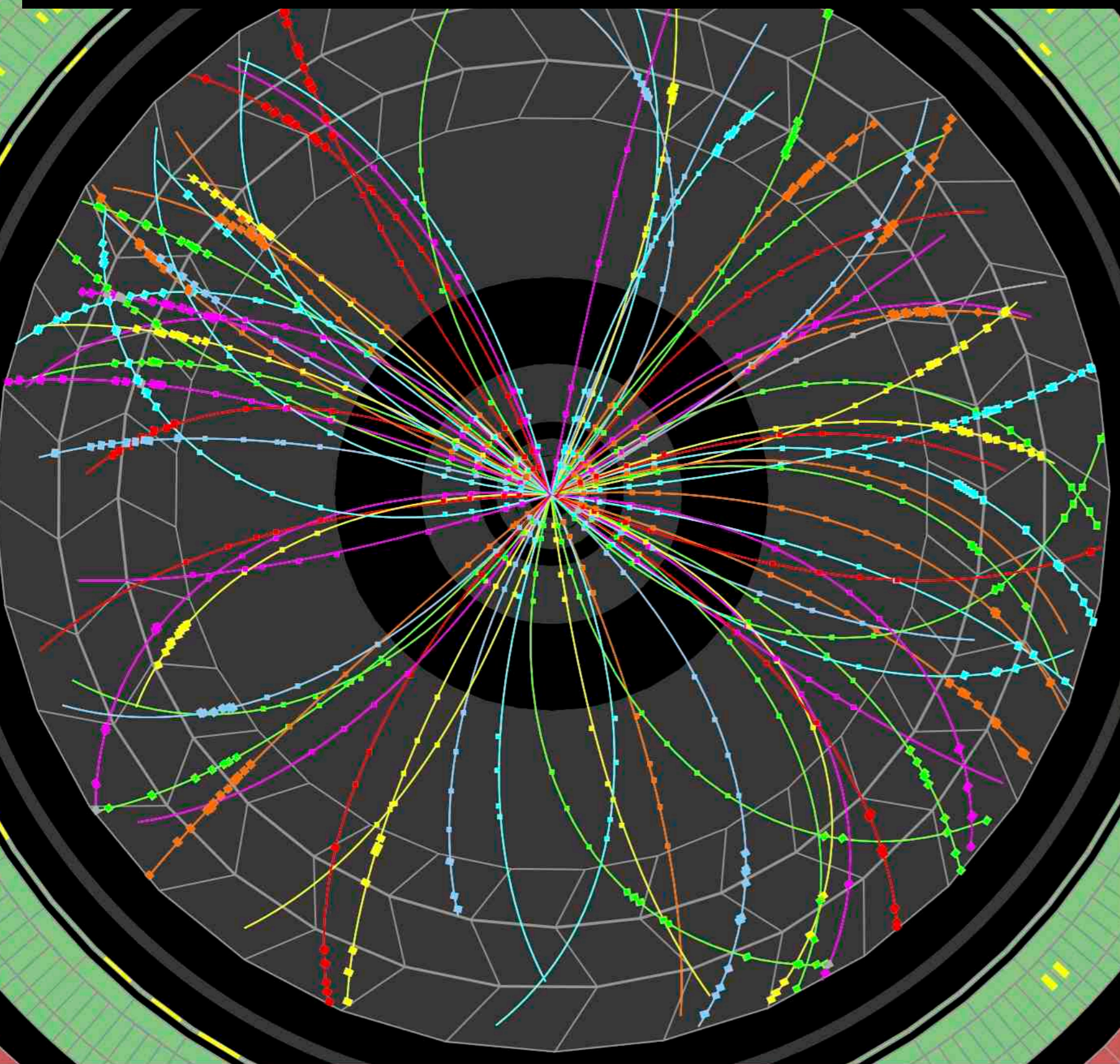
Pixel/SCT detector



The dashed tracks are invisible to the detector

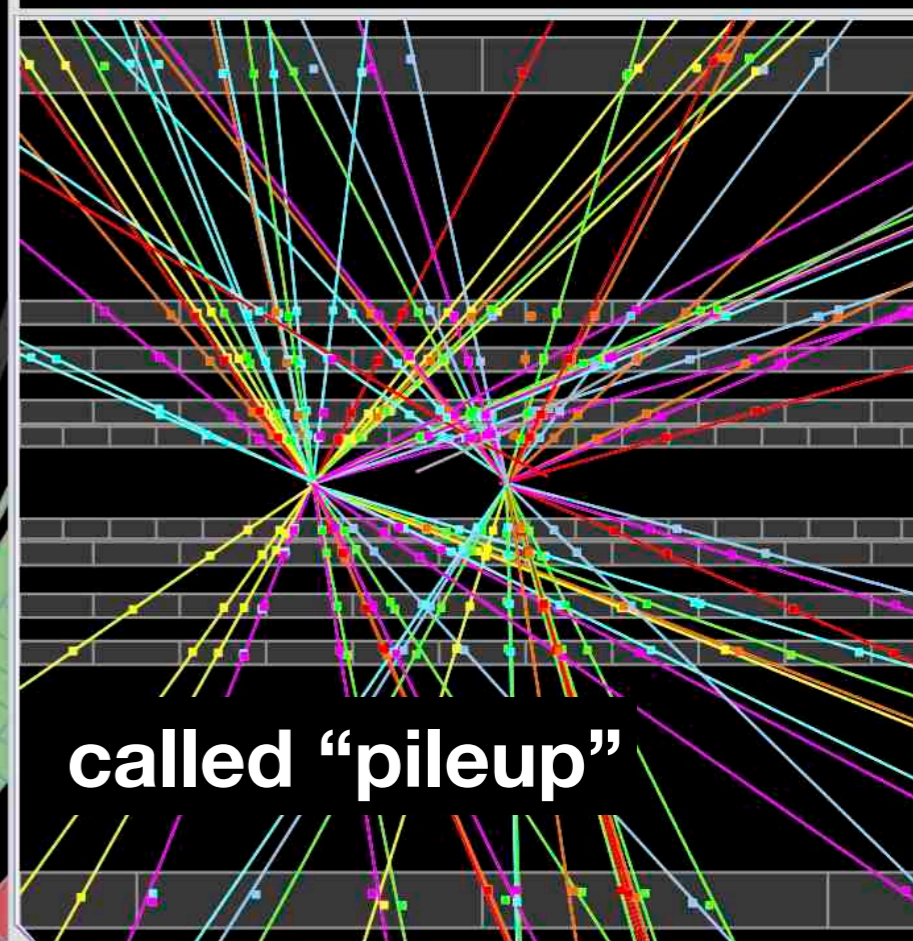
**Muon reconstruction =
Track reconstruction
+ muon spectrometer hits**

At the LHC: more than one proton collision - more than one vertex



Run Number: 265545, Event Number: 5720351

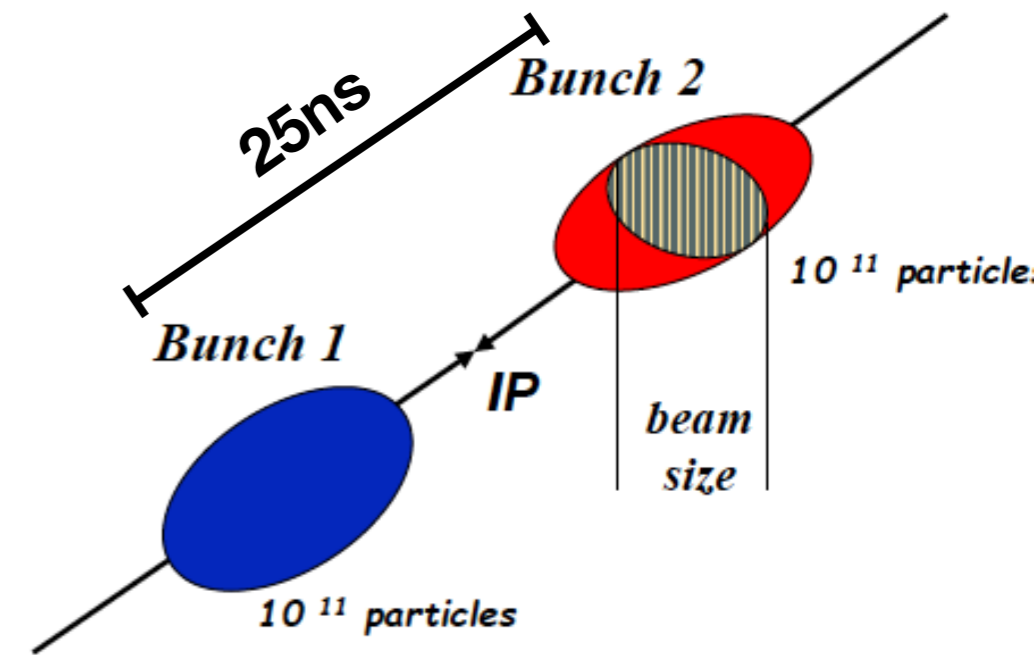
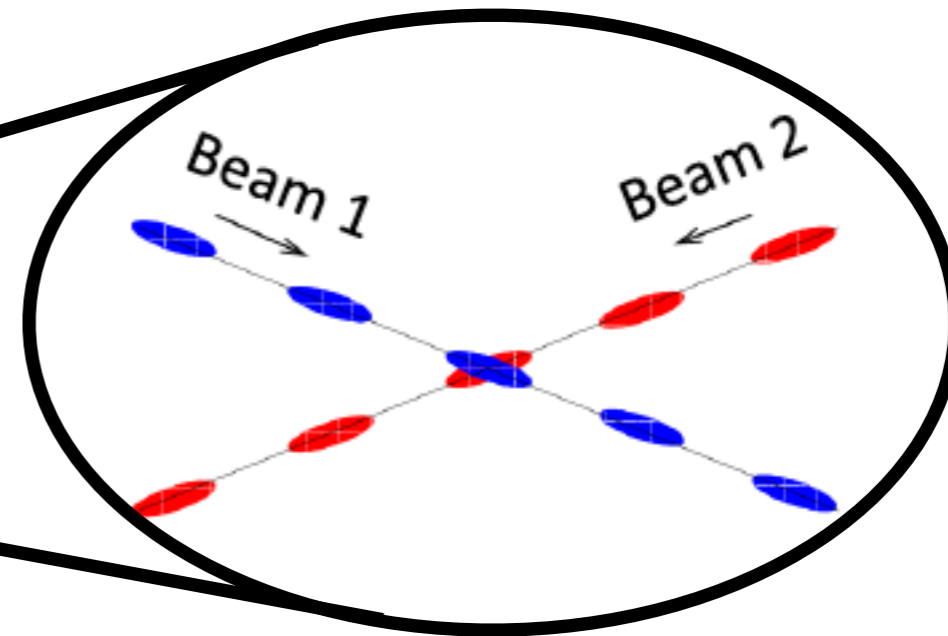
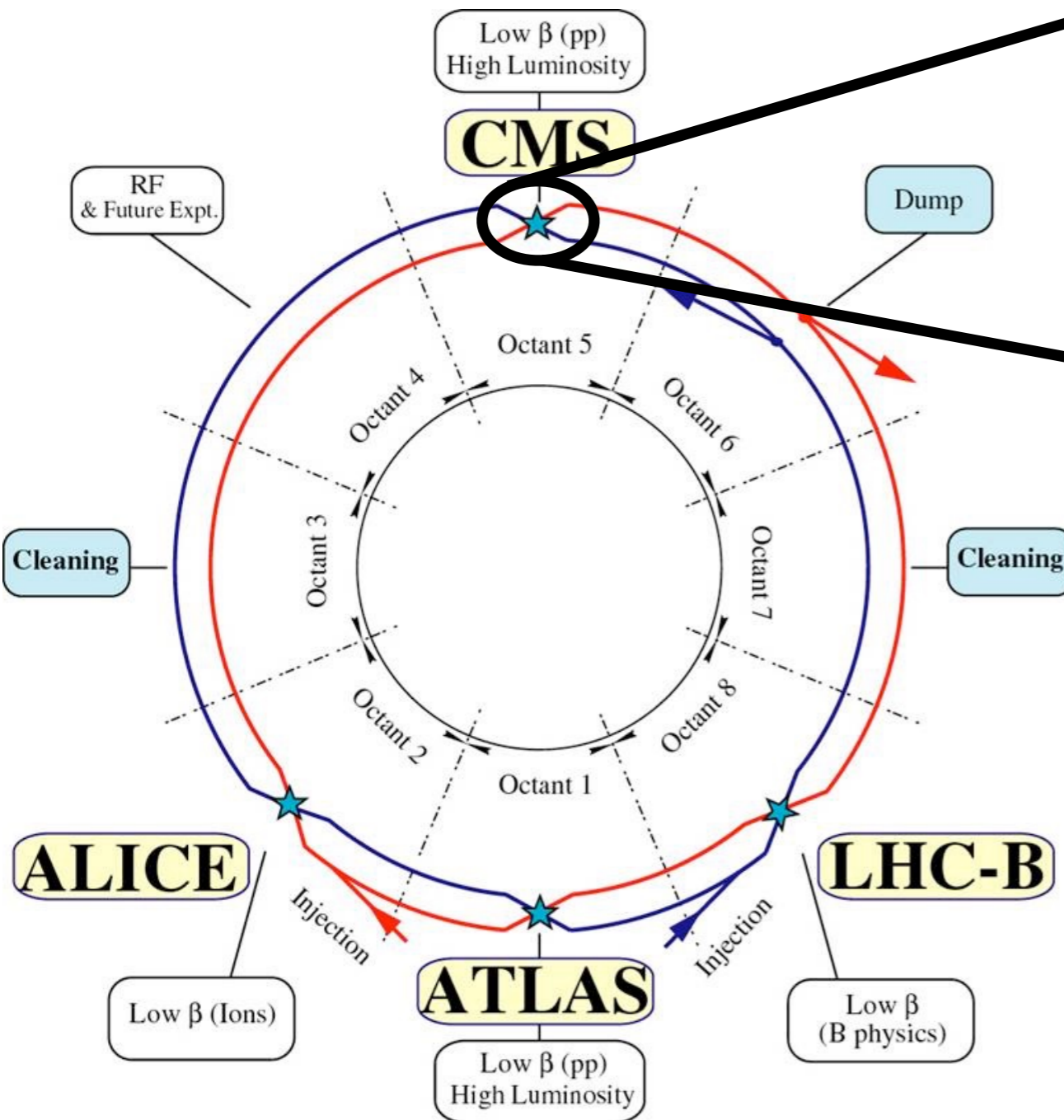
Date: 2015-05-21 10:39:54 CEST



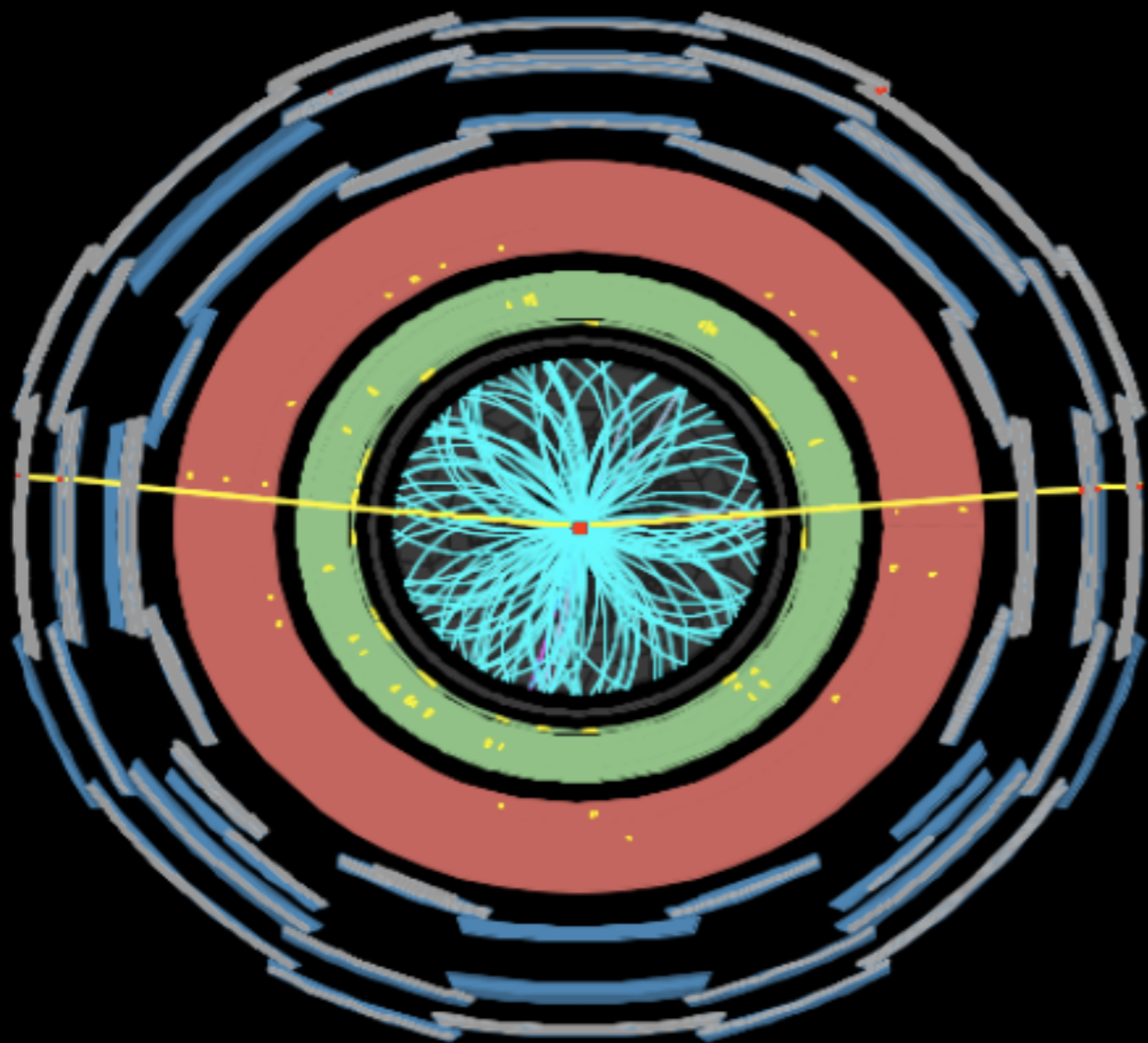
called "pileup"

LHC collisions

Figures adapted from Michaela Schaumann's third lecture (11/07/19) on "Particle Accelerators and Beam Dynamics"



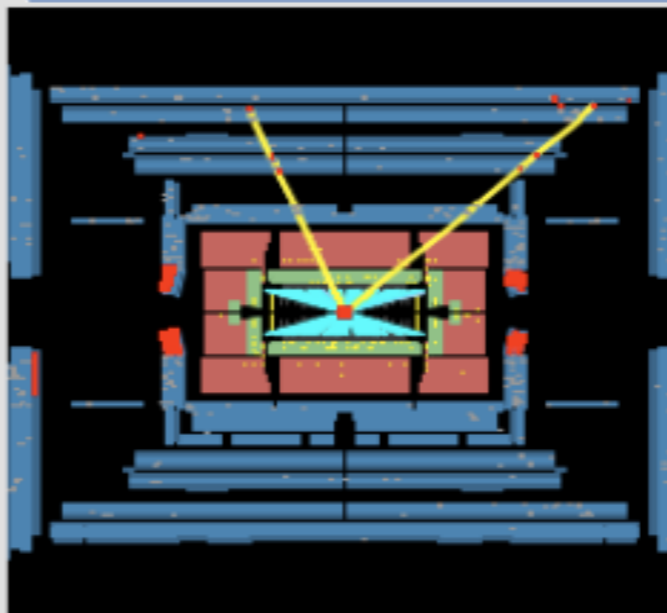
- The LHC accelerates **bunches of 10^{11} protons** separated by 25ns gaps



ATLAS
EXPERIMENT

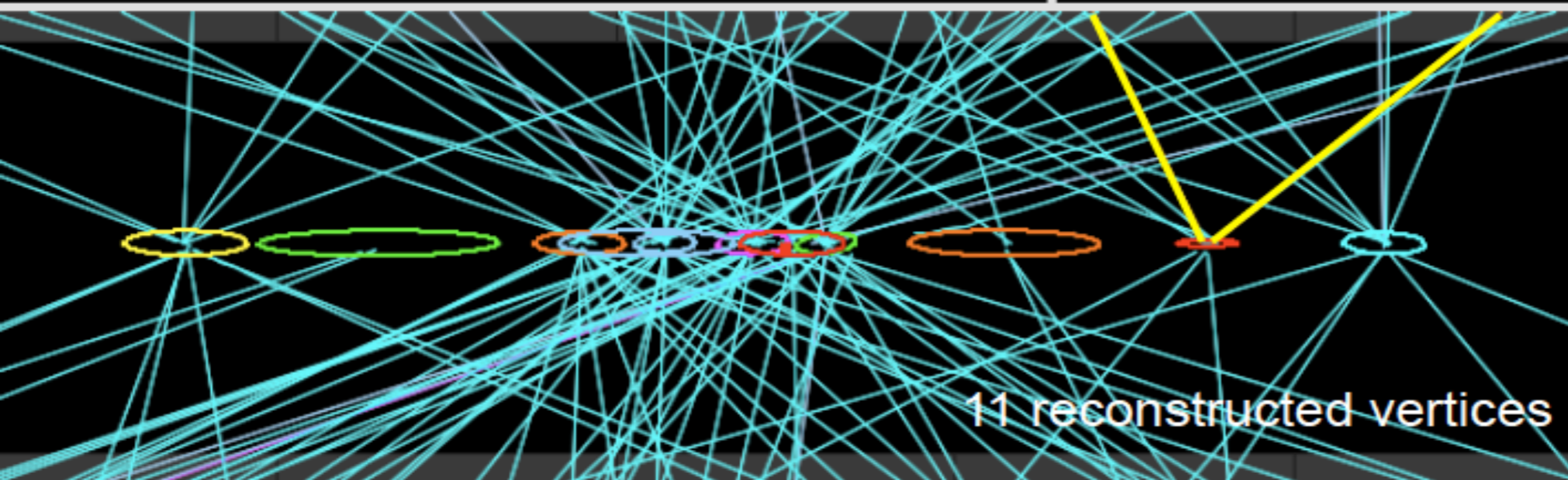
Run Number: 180164, Event Number: 146351094

Date: 2011-04-24 01:43:39 CEST



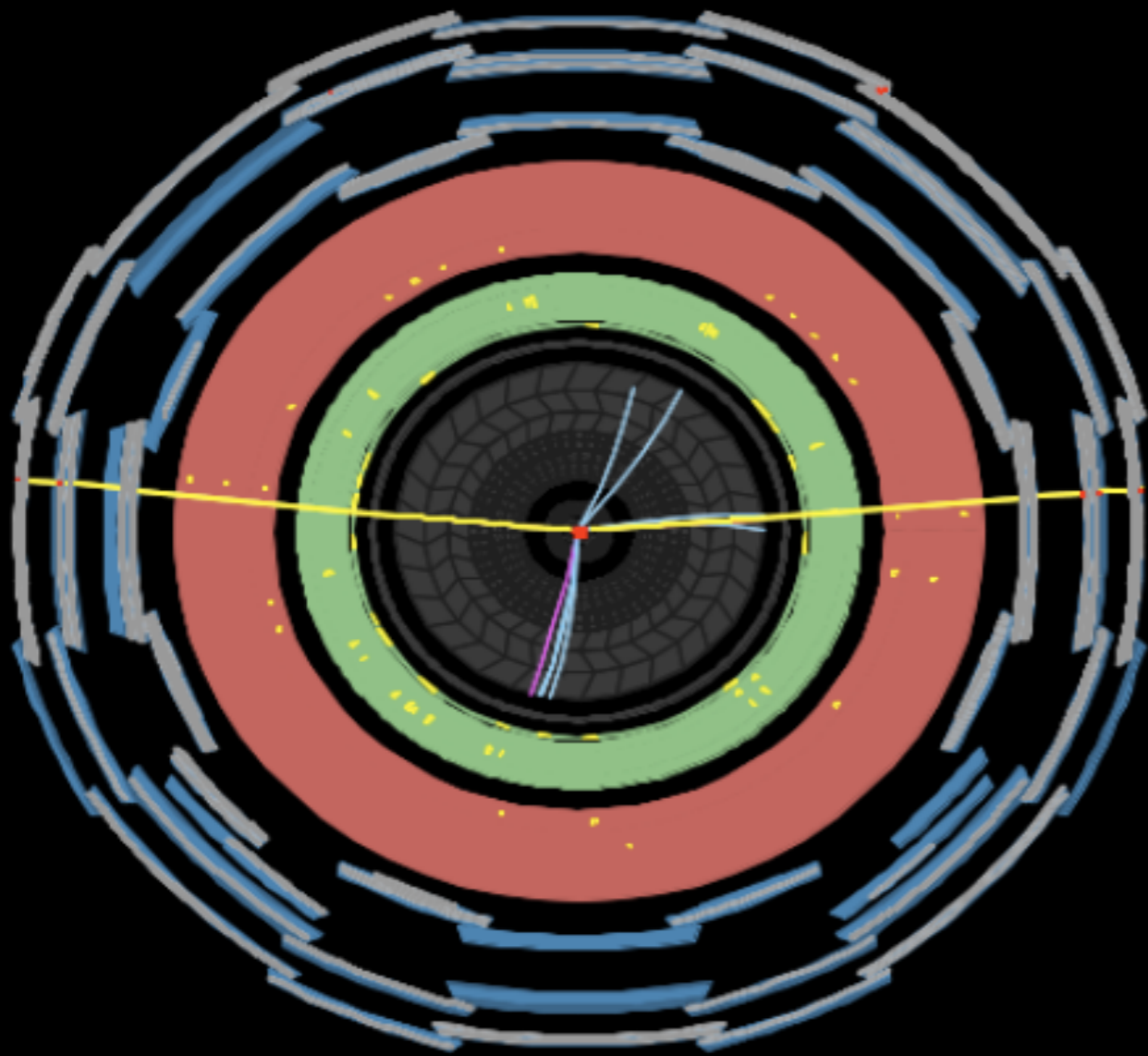
Z- \rightarrow $\mu\mu$ event;
2011 data.

The more bunches are squeezed, the higher the luminosity, the larger the number of simultaneous proton collisions in one recorded event



11 reconstructed vertices

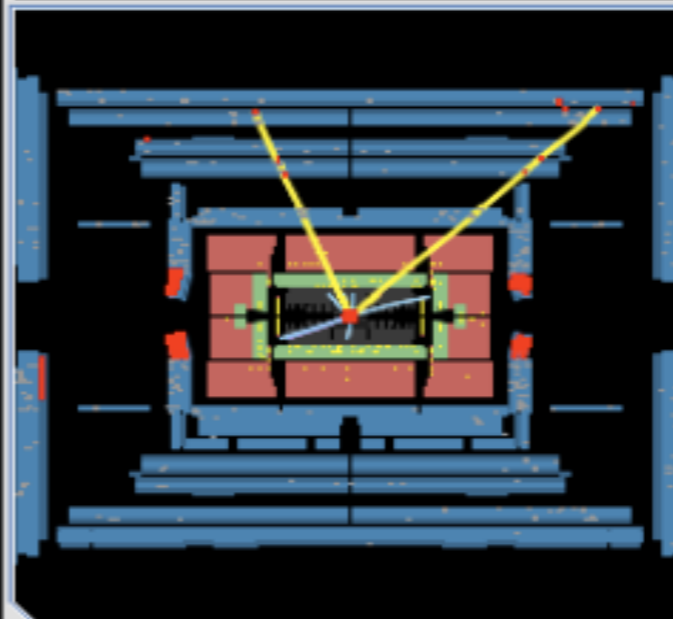
Track $p_T > 0.5$ GeV



ATLAS
EXPERIMENT

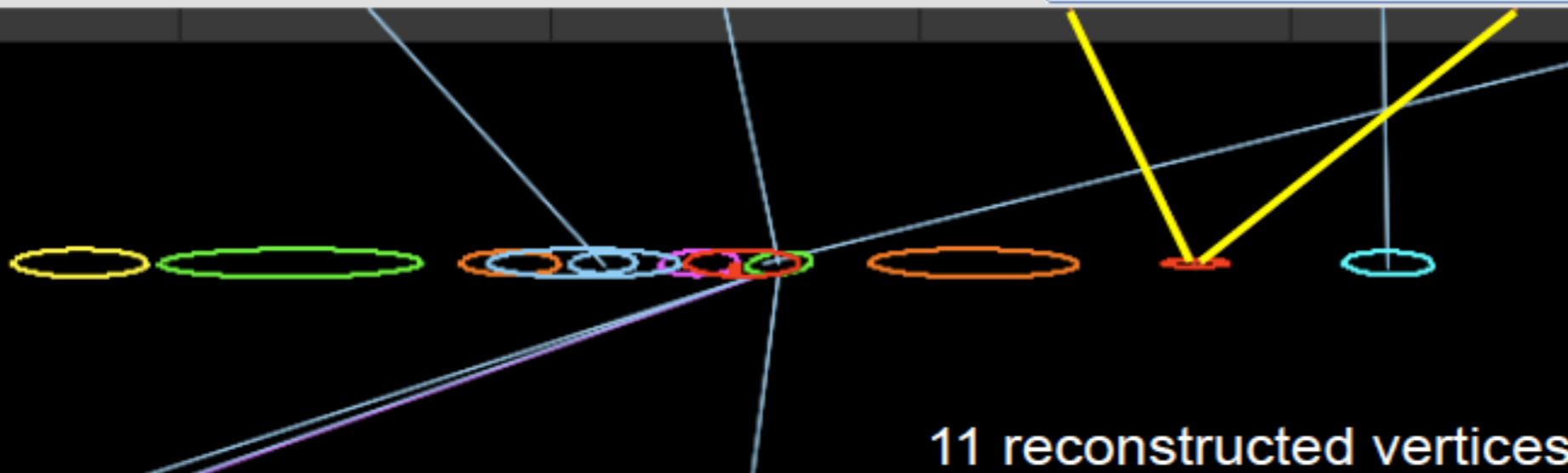
Run Number: 180164, Event Number: 146351094

Date: 2011-04-24 01:43:39 CEST



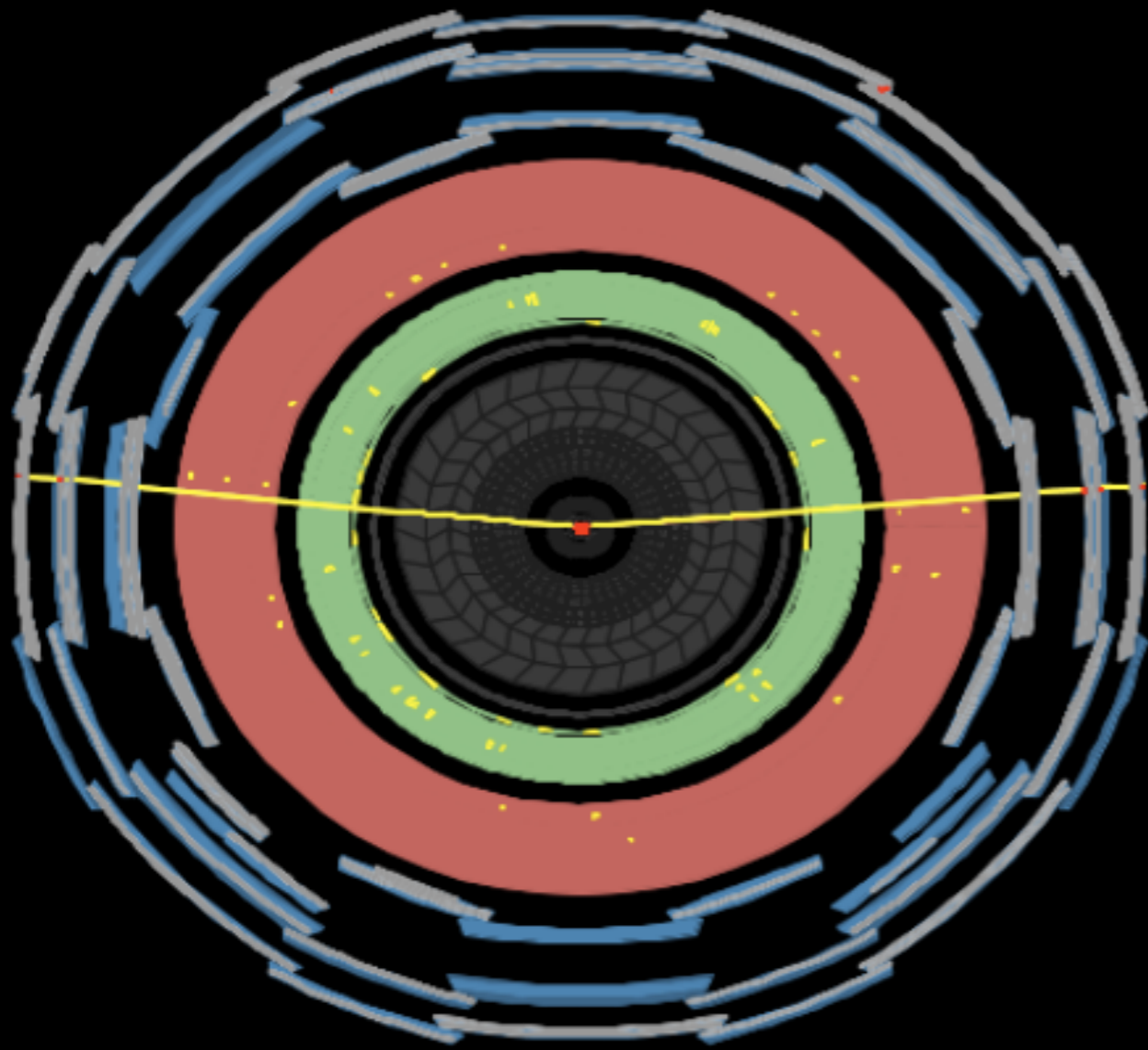
Z- \rightarrow $\mu\mu$ event;
2011 data.

Most proton collisions are low momentum and uninteresting. We can remove them simply by making a cut on the transverse momentum



Track $p_T > 2$ GeV

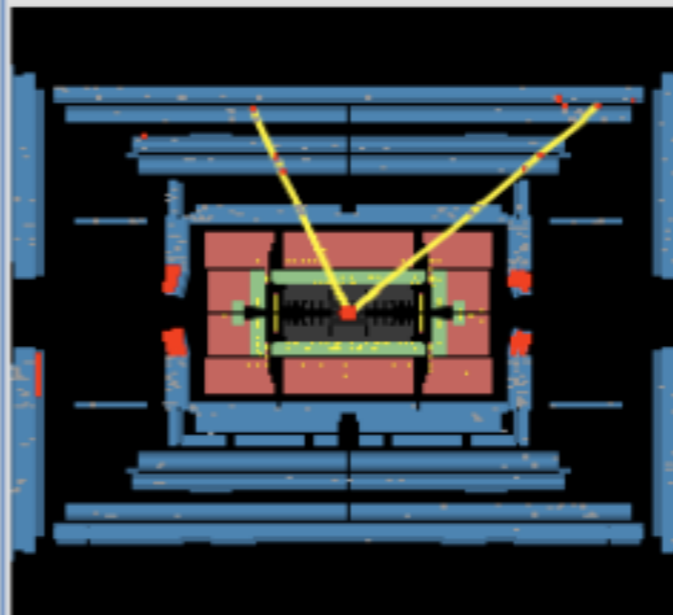
11 reconstructed vertices



ATLAS
EXPERIMENT

Run Number: 180164, Event Number: 146351094

Date: 2011-04-24 01:43:39 CEST



Z- $\rightarrow\mu\mu$ event;
2011 data.

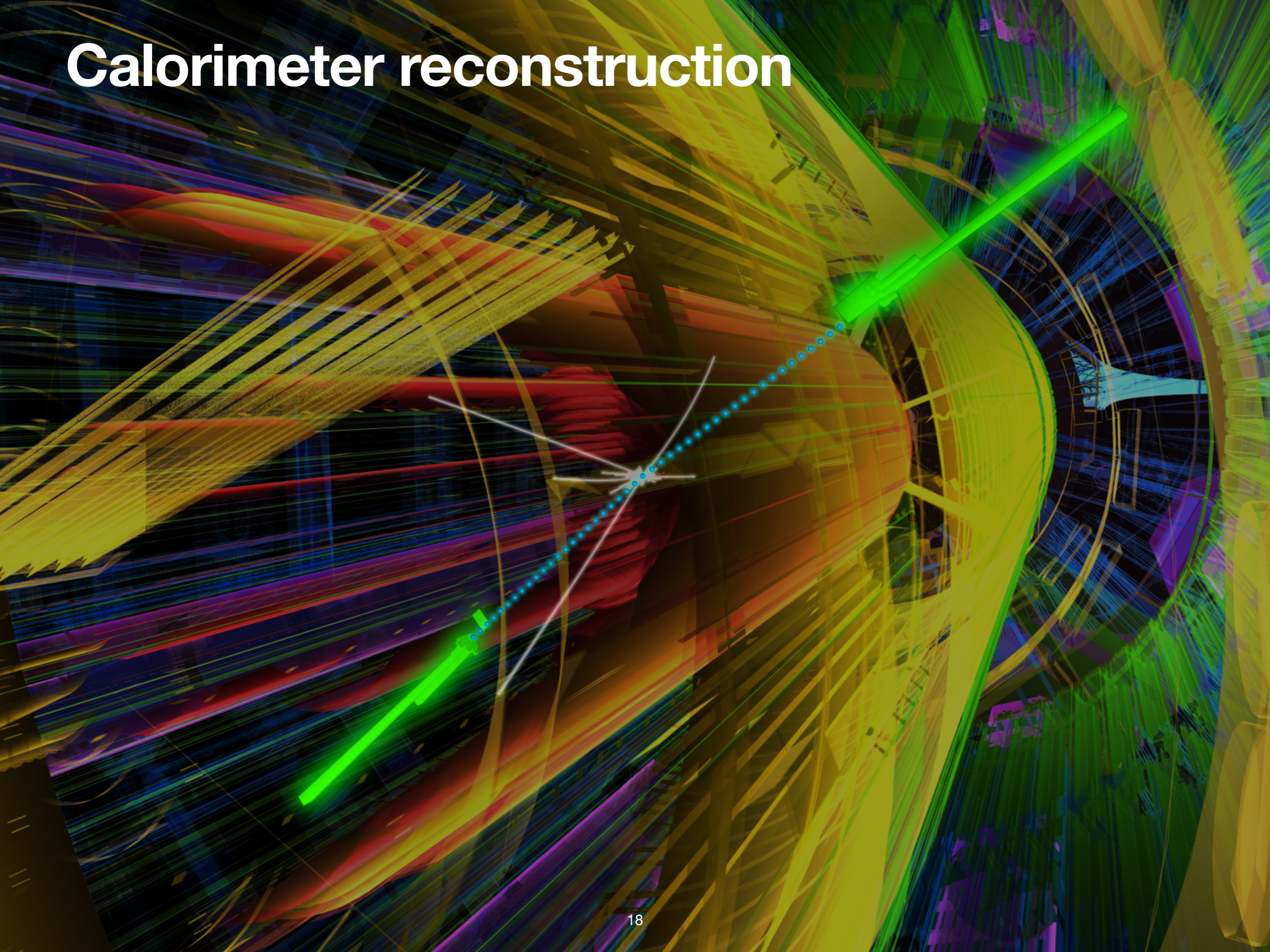
Once we increase the transverse momentum cut sufficiently, we are left with only the interesting proton collision



11 reconstructed vertices

Track $p_T > 10$ GeV

Calorimeter reconstruction



Muon Spectrometer

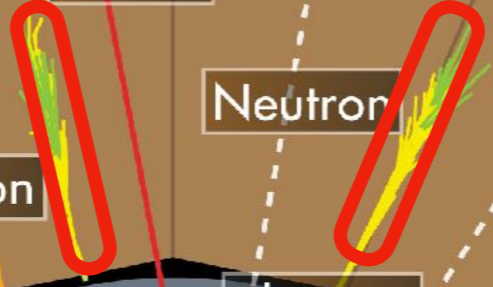
Hadronic Calorimeter

Electromagnetic Calorimeter

Tracking

Solenoid magnet
Transition Radiation Tracker

Pixel/SCT detector



Proton

Neutron

Muon

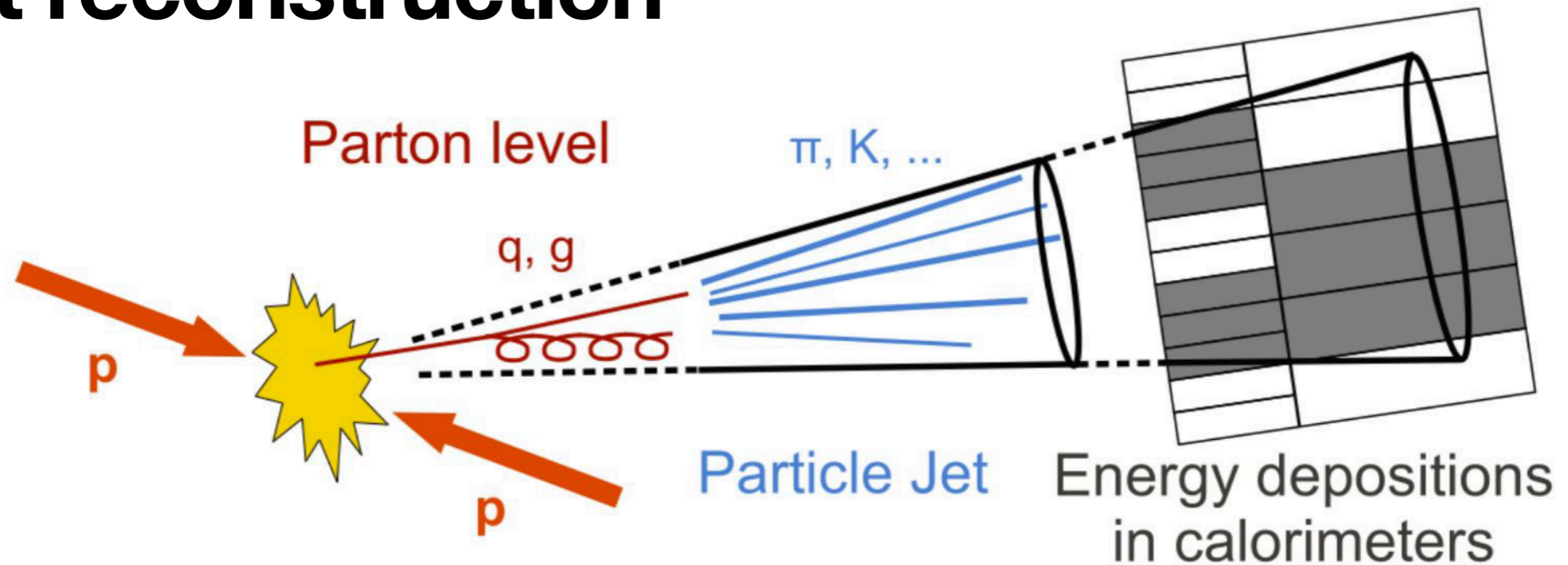
Electron

Neutrino

The dashed tracks are invisible to the detector

**Basic reconstruction =
Calorimeter Clusters,
aka Jets**

Jet reconstruction



- Quarks and gluons **hadronize** quickly and we detect **sprays of hadronic particles** in our detectors - we call these **jets**, proxies for the initial particle(s), we reconstruct them using **jet algorithms**
- Hadronic particles leave energy deposits in the **cells** of the calorimeter, to reconstruct the energy of the hadronic particle, e.g. a pion, we need to sum the energy of the **cluster** of cells in which the pion deposited energy
- Deciding which cells belong to which cluster is a pattern recognition problem

Modern jet reconstruction uses Machine Learning!

Here be dragons... and muons

Muon Spectrometer

Hadronic Calorimeter

Electromagnetic Calorimeter

Solenoid magnet

Tracking

Transition Radiation Tracker

Pixel/SCT detector



Proton

Neutron

Muon

Electron

Photon

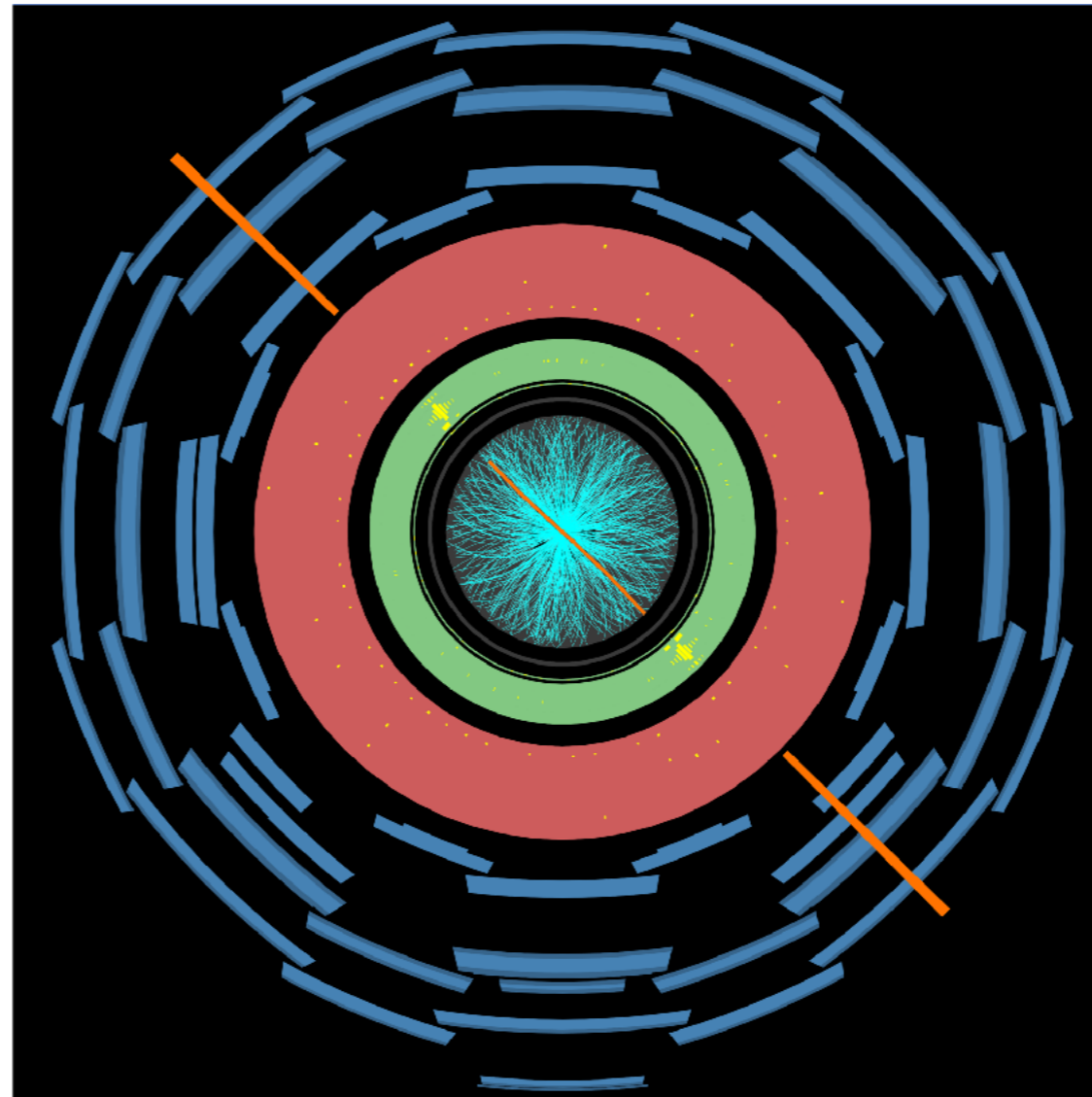
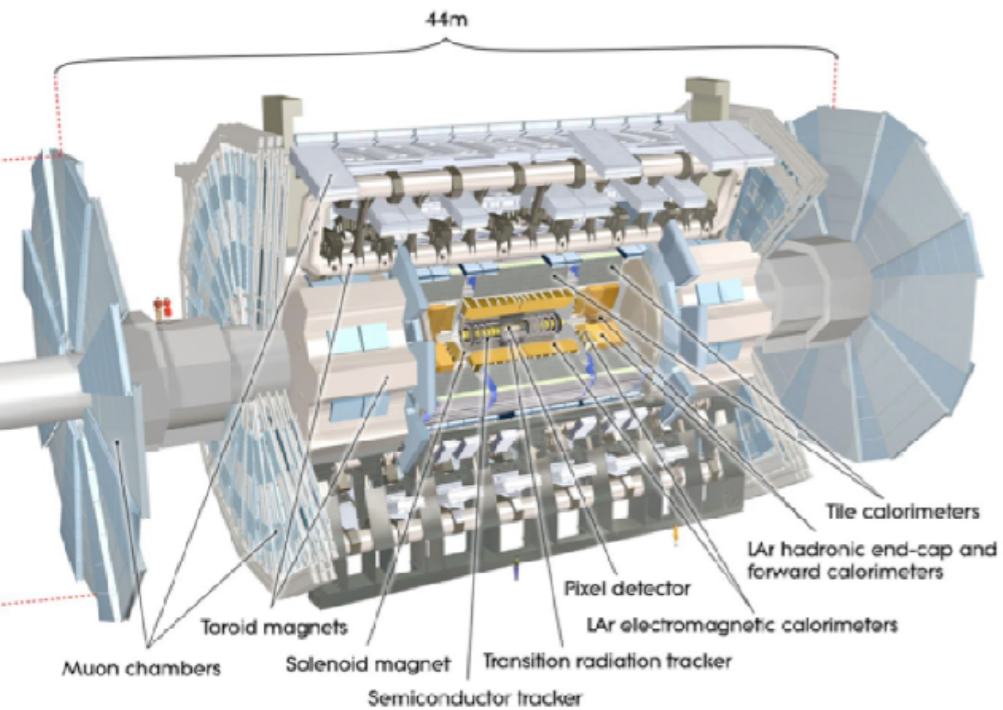
Neutrino

The dashed tracks are invisible to the detector

Physics object reconstruction =
Tracks +
Jets
+ Muons



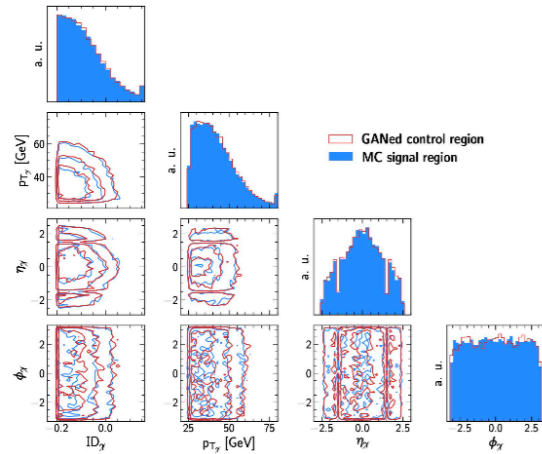
Neutrinos



- Let's look at the simplest case for reconstructing neutrinos
- Remember, we are looking down the beam pipe, so the plane of the display is transverse to the proton beam direction
- **Recall:** Can you quantify the momentum in this plane **before** the proton collision
 - What does that tell you about the distribution of momentum **after** the collision?

Q. How would this look if we had a **W boson** instead of a **Z boson** ?

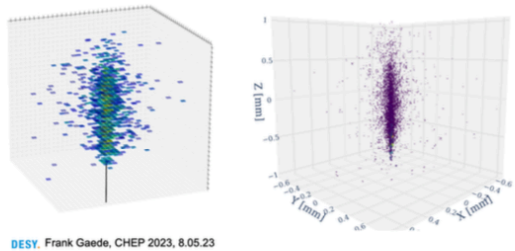
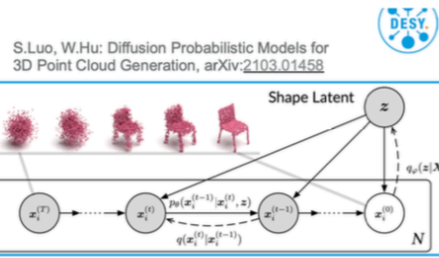
Reconstruction today



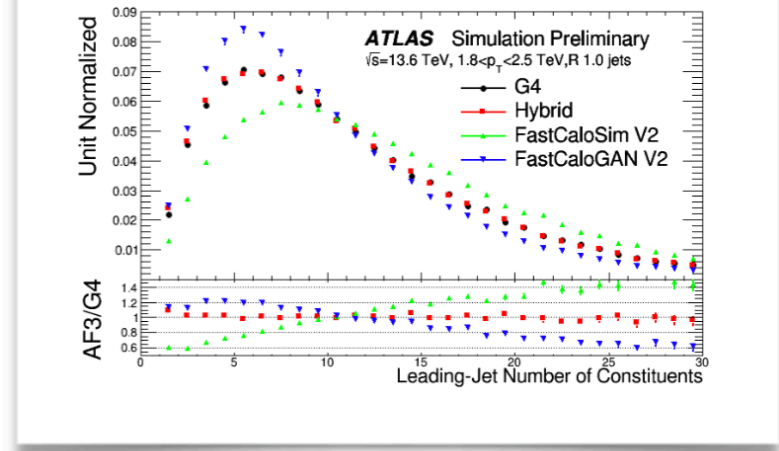
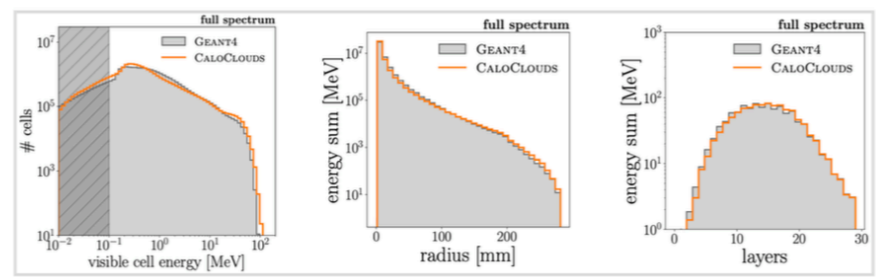
CaloCloud diffusion model

from regular grids to point clouds

- regular grid models like WGAN or BIB-AE show very high physics fidelity - yet they have two problems:
 - low occupancy -> lots of superfluous compute
 - projecting energy back into realistic detector cells causes artefacts
- are point clouds a "way out" ?



- recently and diffusion
- can we a case - u by indic

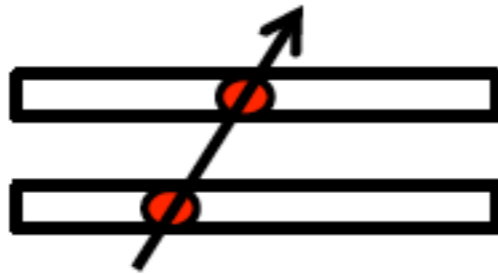


• Modern simulation, reconstruction and analysis employ heavy use of Machine Learning techniques. See Foundations of Statistics for an introduction to the key concepts. There are also some excellent resources online, e.g.:

- [Google Machine Learning Crash Course](#)

Track fitting

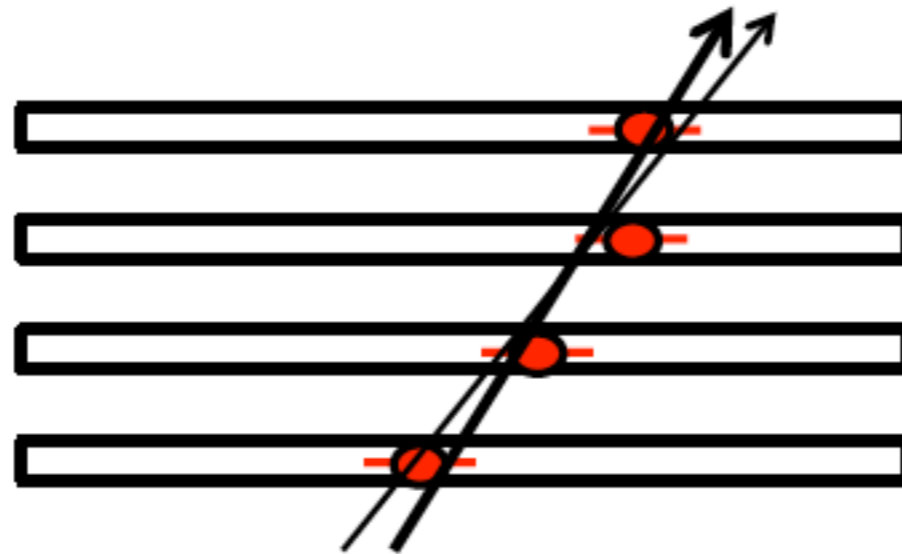
⊙ Perfect measurement – ideal



⊙ Imperfect measurement – reality



⊙ Small errors and more points help to constrain the possibilities

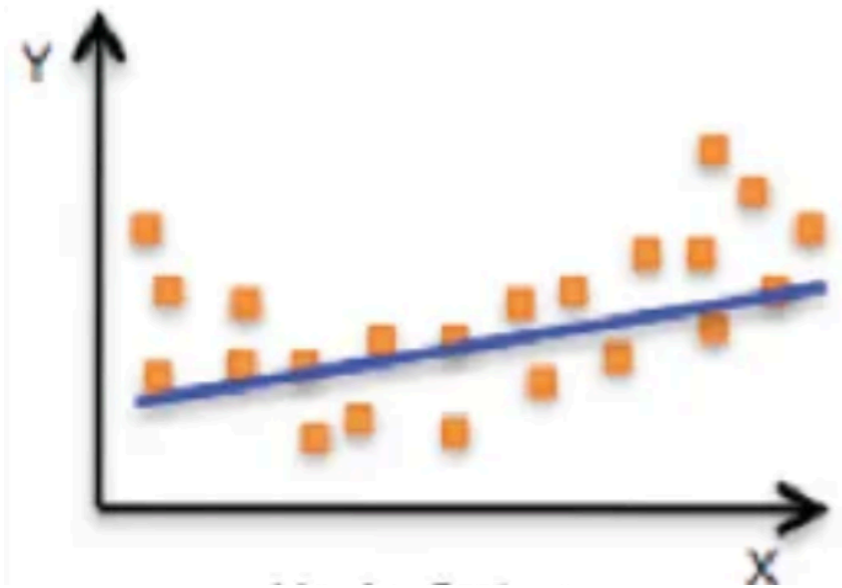


⊙ Quantitatively:

- ⊙ Parameterize the track;
- ⊙ Find parameters by Least-Squares-Minimization;
- ⊙ Obtain also uncertainties on the track parameters.

What is the connection between least-squares minimisation and machine learning?

Machine learning (regression)

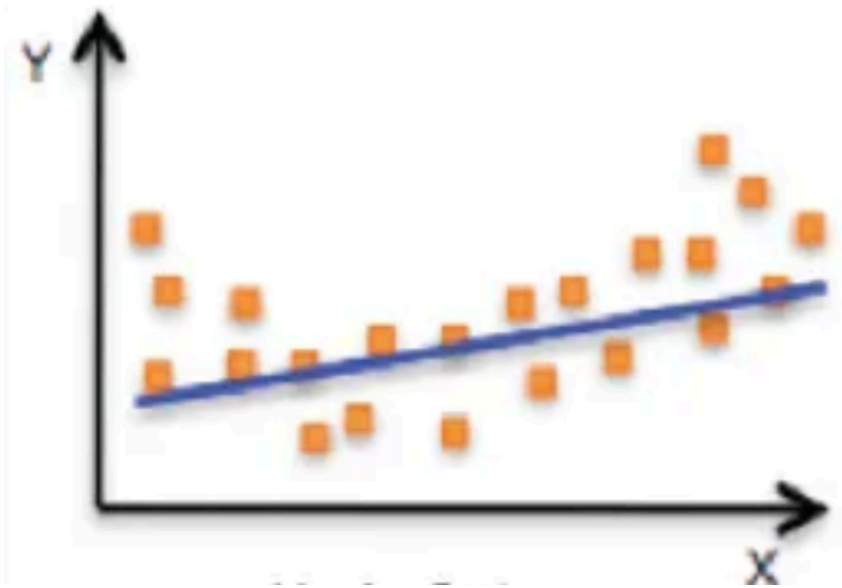


$$y_{model} = (x * a_{model}) + b_{model}$$

$$L = \sum_N (y_{model} - y_{data})^2$$

- Linear least squares minimisation compares a model to data
- L is the sum of the (squared) differences between the model prediction and the data
- Minimising L gives us the best parameters of the model

Machine learning (regression)



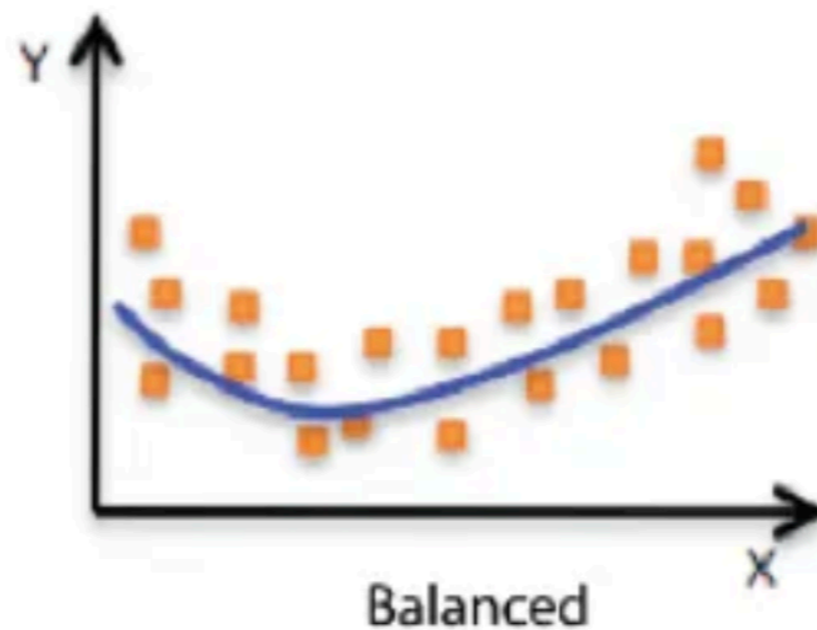
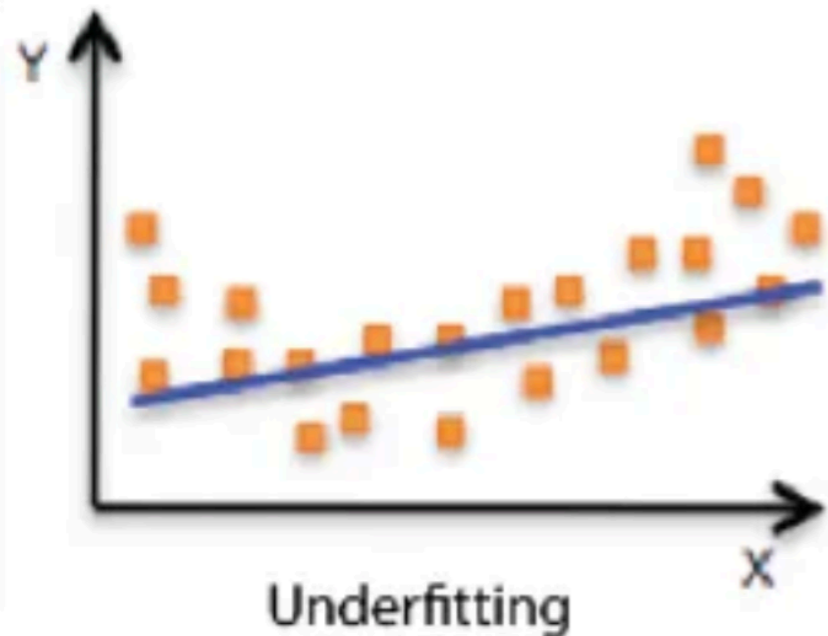
$$y_{model} = (x * a_{model}) + b_{model}$$

$$L = \sum_N (y_{model} - y_{data})^2$$

- Linear least squares minimisation compares a model to data
- L is the sum of the (squared) differences between the model prediction and the data
- Minimising L gives us the best parameters of the model
- We are often in a situation where we need to guess the model

Machine learning (regression)

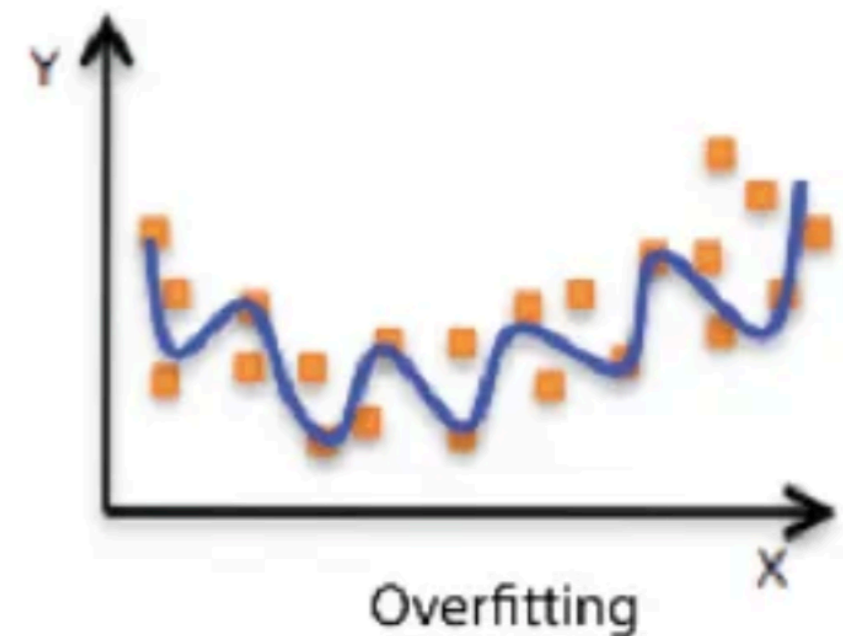
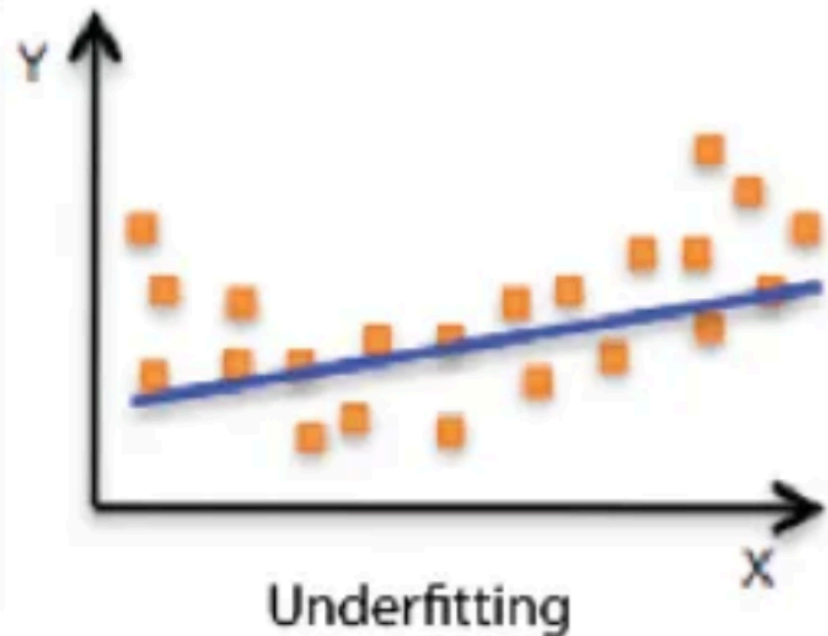
$$L = \sum_N (y_{model} - y_{data})^2$$



- Increasing the #parameters of the model will often achieve a better description of the data (reduce L)

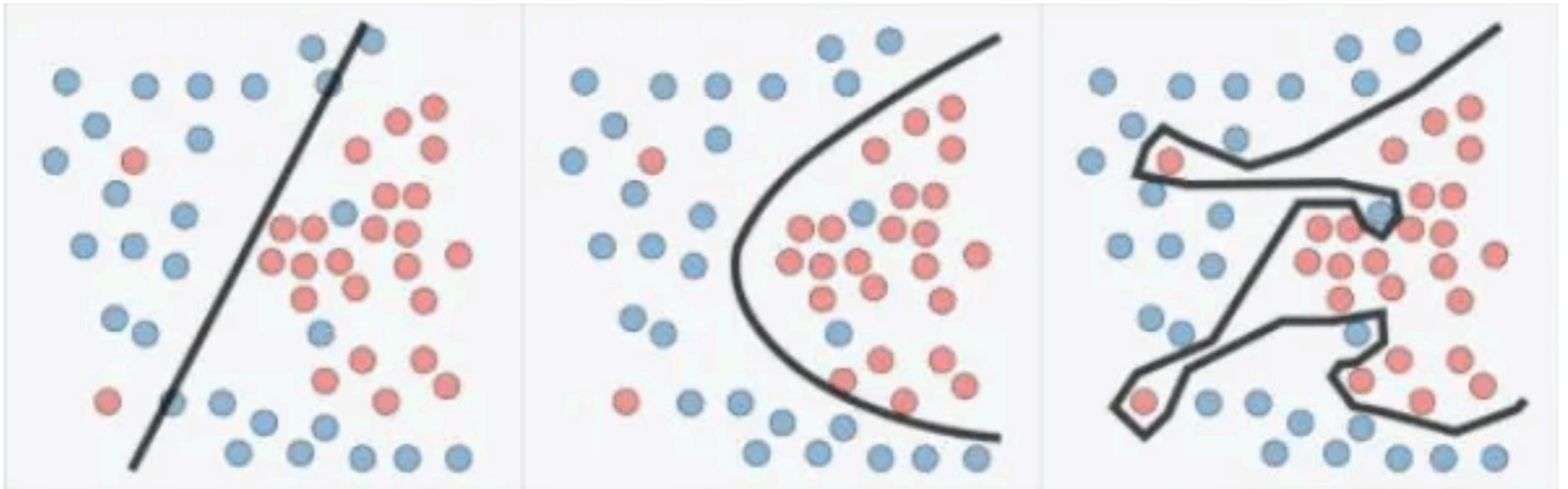
Machine learning (regression)

$$L = \sum_N (y_{model} - y_{data})^2$$



- Increasing the #parameters of the model will often achieve a better description of the data (reduce L)
- But this has drawbacks, we want a model that can describe ALL data, including data we haven't seen yet / data not included in the fit
- Important to strike a balance between #parameters and quality of fit (L)

ML classification (supervised)



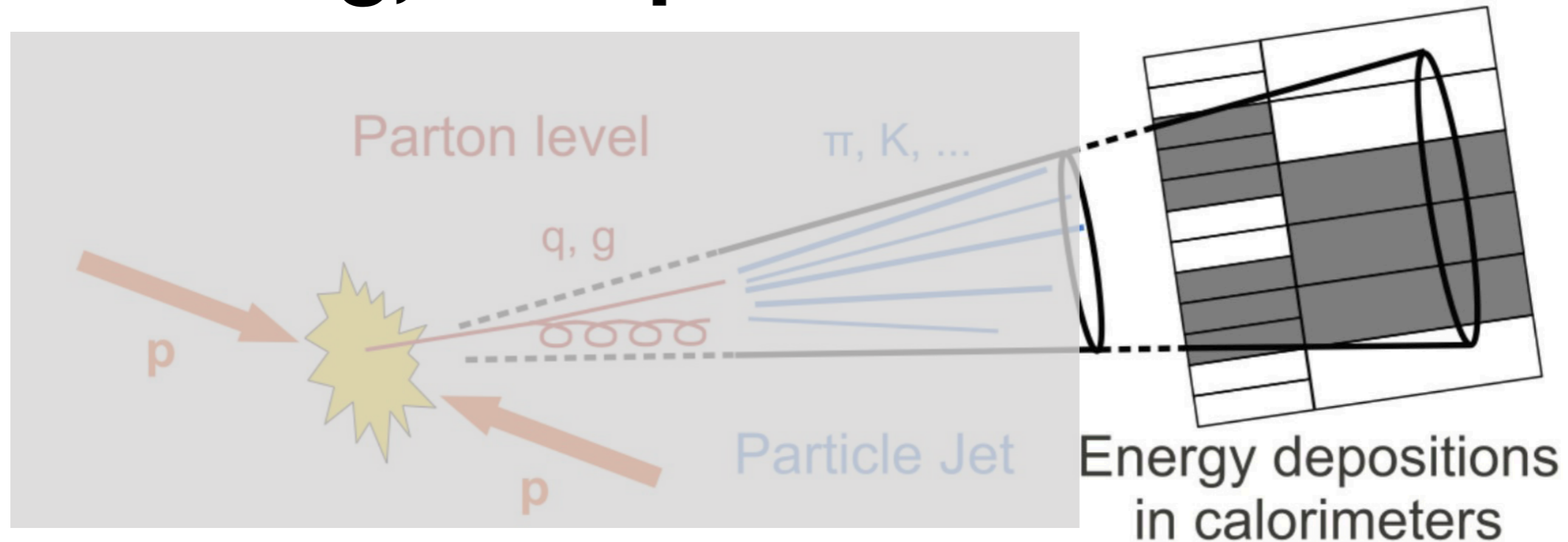
Underfitting

Balanced

Overfitting

- Classification works in a similar way, here we model the separation between two populations, **red** and **blue**
 - ***We fit a model that describes the shape that separates the data points***
- Again we need to be careful not to overfit our training data or our model will not be general enough to describe new data that were not included in the fit

Clustering, unsupervised ML classification



- Sometimes there is no model, for example reconstructing clusters of energy deposits in calorimeters
- Instead of defining a number of clusters to reconstruct and tuning that model, we cluster energy deposits (cells) around a varying number of centres ($N_{clusters} = 1, 2, 3, \dots$)
- We need a metric to choose the best solution ($N_{clusters}$), e.g. increasing the number of clusters by 1 did not improve the total cluster quality by $>10\%$

Data Preparation

- Three major steps to **prepare data for physics analysis** and achieve
 - reliable, high quality data (yes, we **reject** low quality data)
 - the **best performance** from our detectors
 - readiness for **physics analysis**

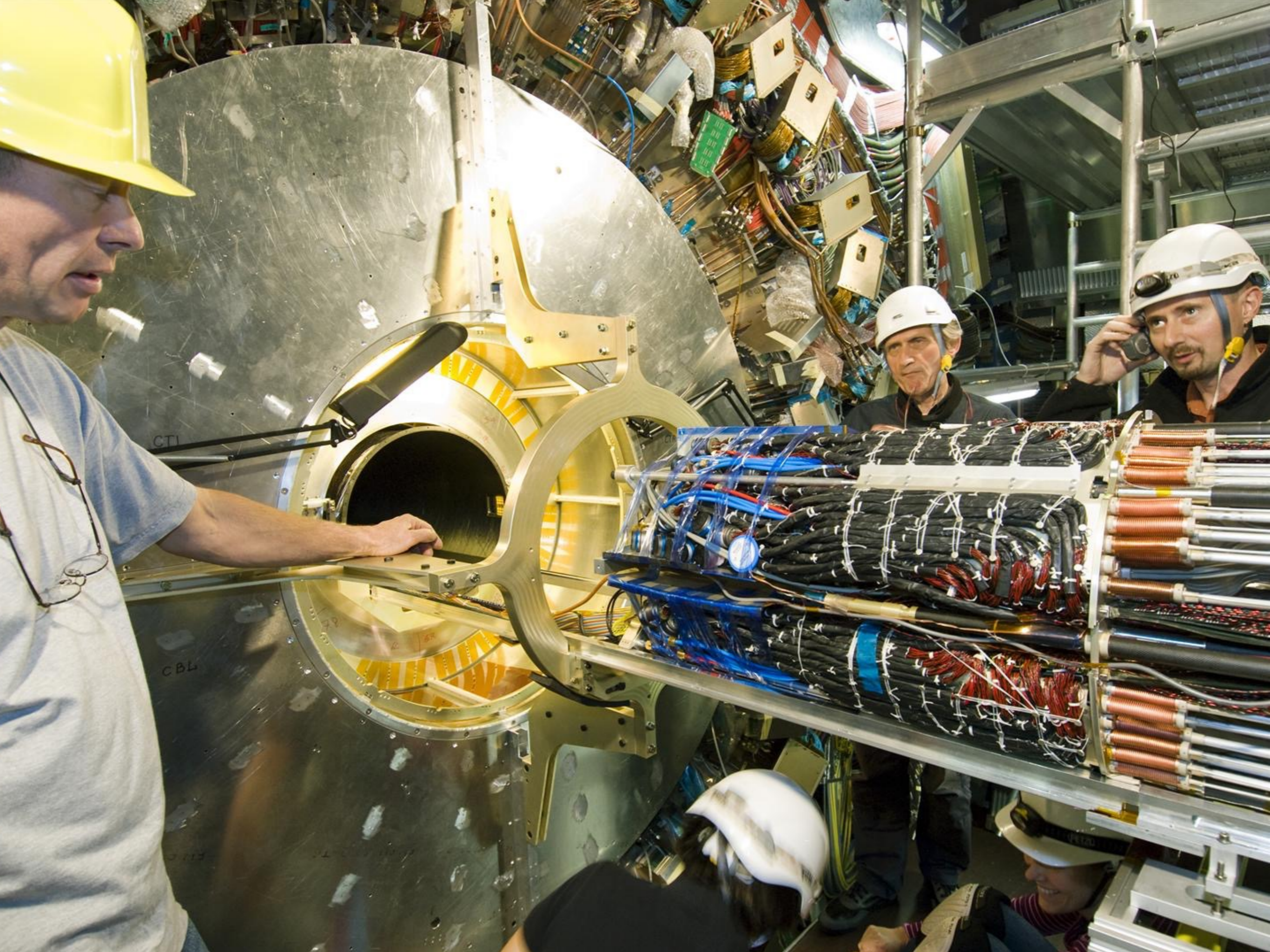
1. Reconstruct physics signals from the data

- Produce information like how many muons does the event have?



2. Calibrate the detectors

- Correct imperfections, account for changes over time...



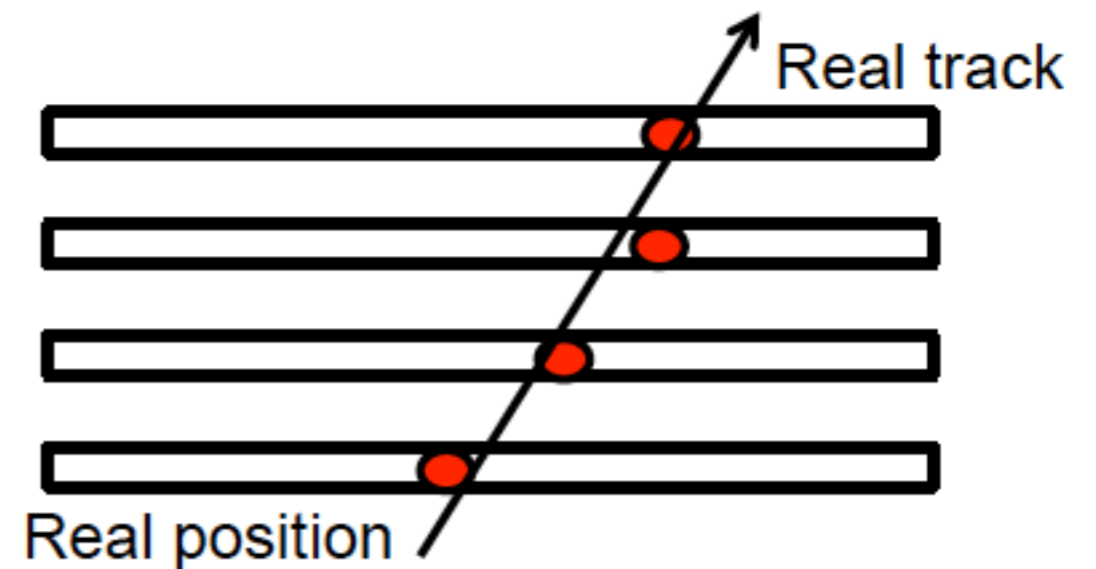
Real detector effects

⊙ Presence of Material

- ⊙ Coulomb scattering off the core of atoms
- ⊙ Energy loss due to ionization
- ⊙ Bremsstrahlung
- ⊙ Hadronic interaction

⊙ Misalignment

- ⊙ Detector elements not positioned in space with perfect accuracy.
- ⊙ Alignment corrections derived from data and applied in track reconstruction.



Correcting detector effects - calibration

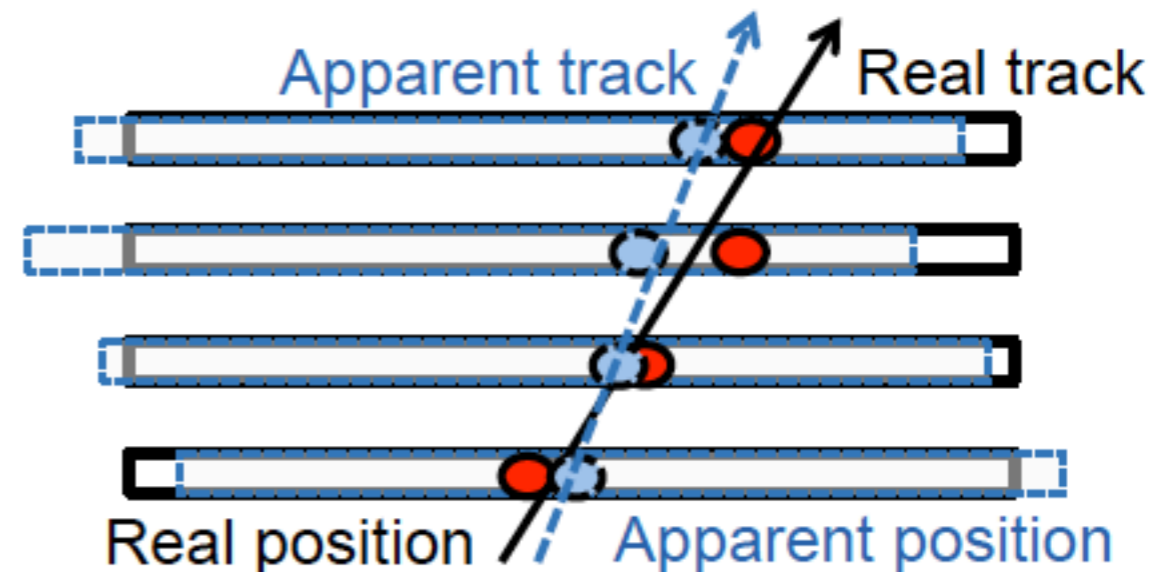
⊙ Presence of Material

- ⊙ Coulomb scattering off the core of atoms
- ⊙ Energy loss due to ionization
- ⊙ Bremsstrahlung
- ⊙ Hadronic interaction

⊙ Misalignment

- ⊙ Detector elements not positioned in space with perfect accuracy.
- ⊙ Alignment corrections derived from data and applied in track reconstruction.

Q. How could we measure detector misalignment ?

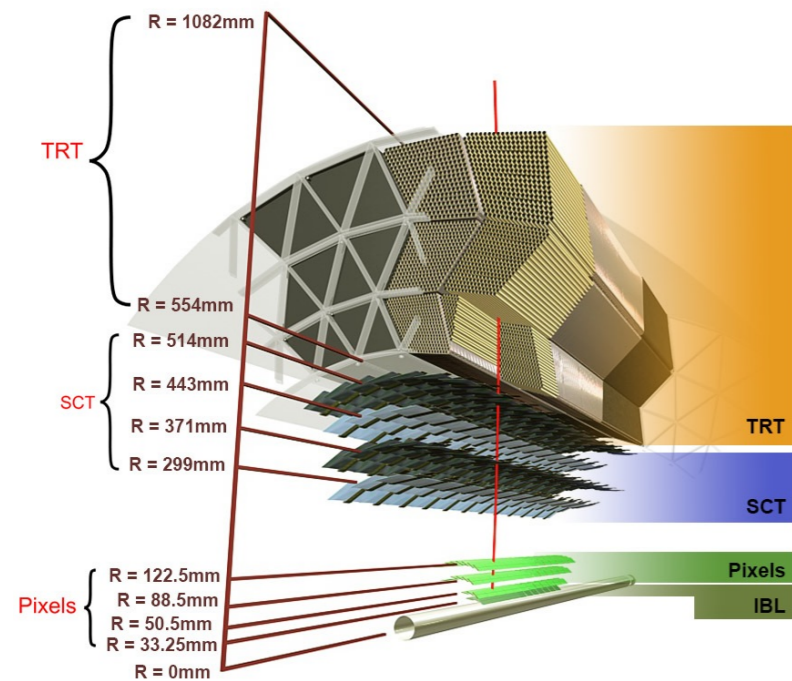


Real vs perfect tracking detectors

- **The perfect tracking detector**
 - is constructed from zero mass material
 - has no noise
 - is 100% efficient
 - has perfect resolution
- **A real tracking detector**
 - is constructed from real material
 - particles interact with the detector and scatter, altering the particle trajectory
 - suffers from noise
 - noise can be confused with particle tracks
 - has less than 100% efficiency
 - particles are not always detected, there can be dead regions
 - has finite resolution
 - it may not always be possible to resolve two particle trajectories

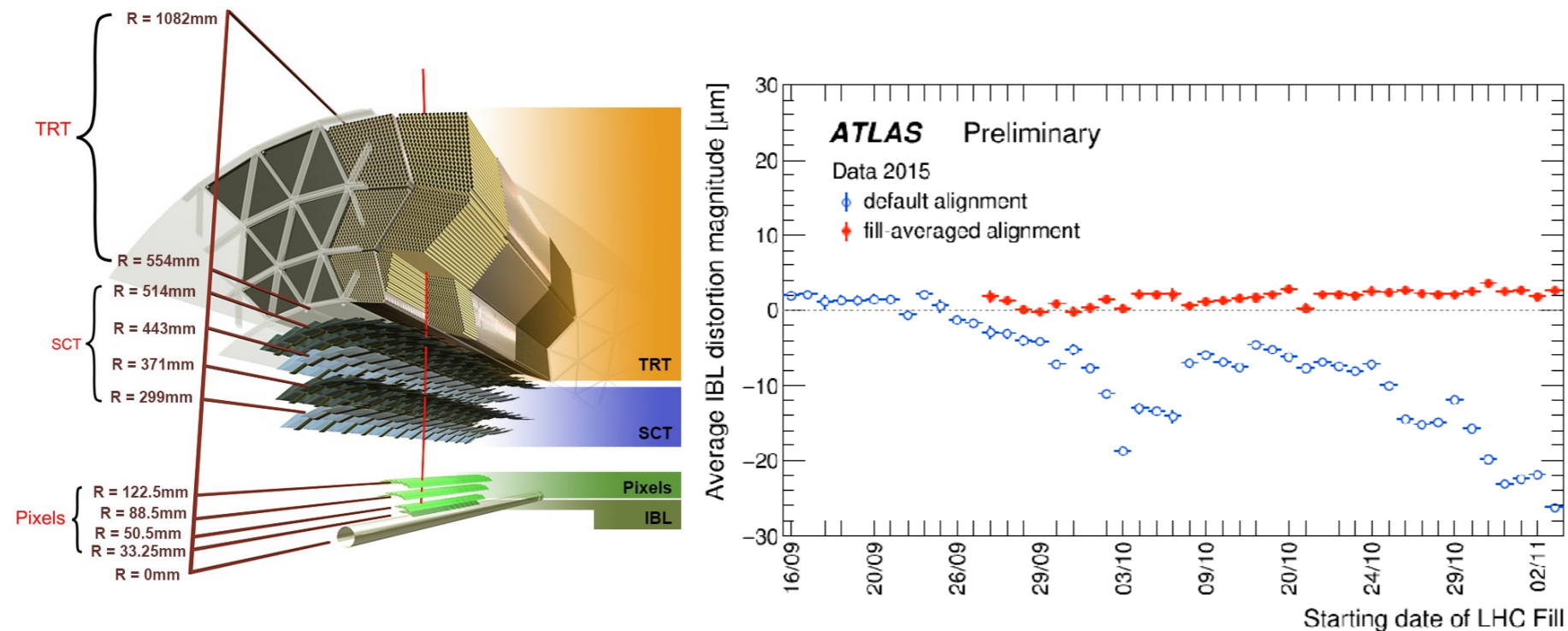


Calibration



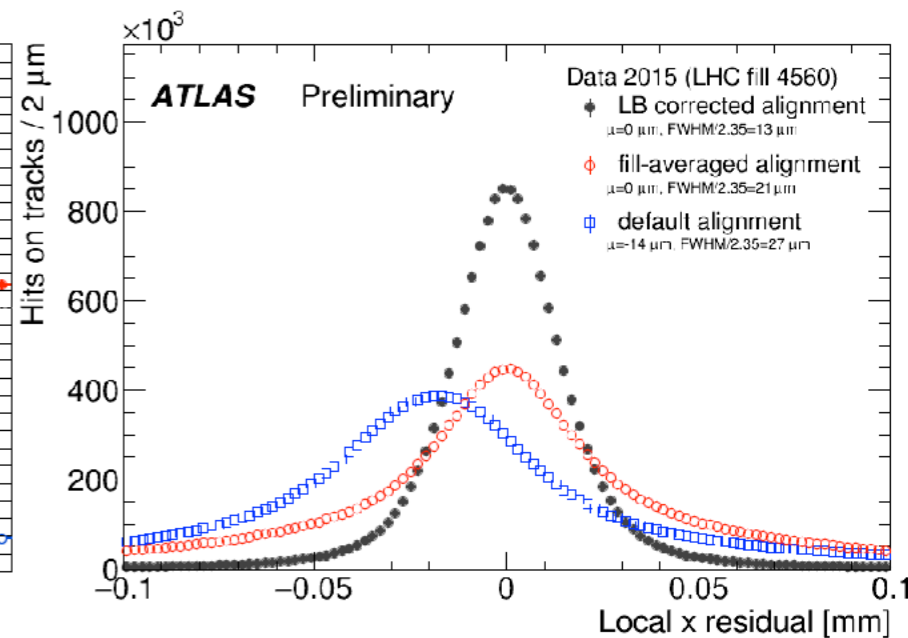
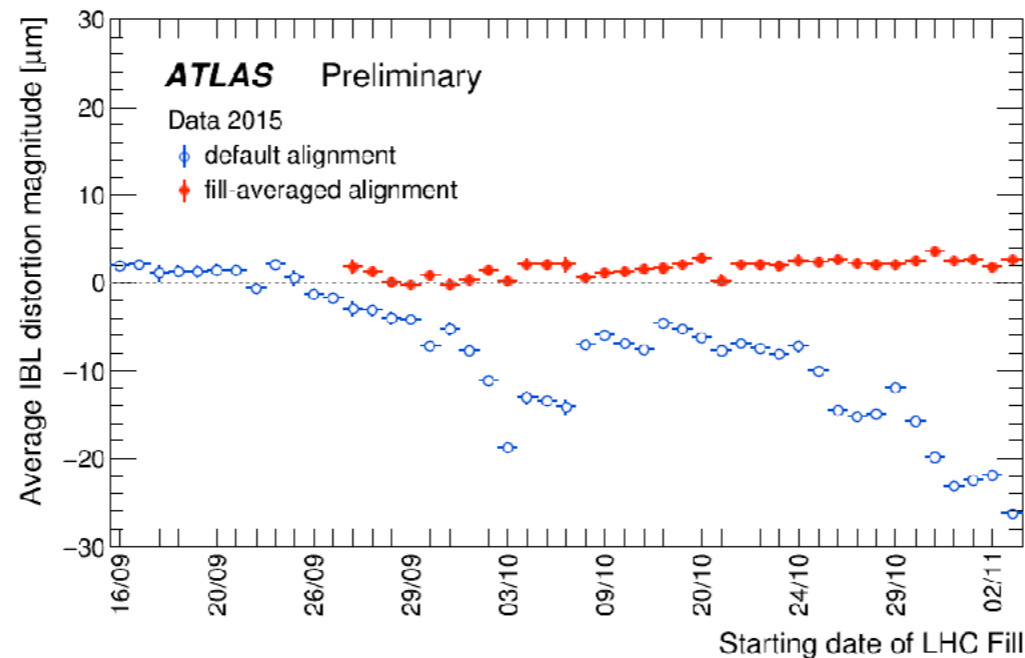
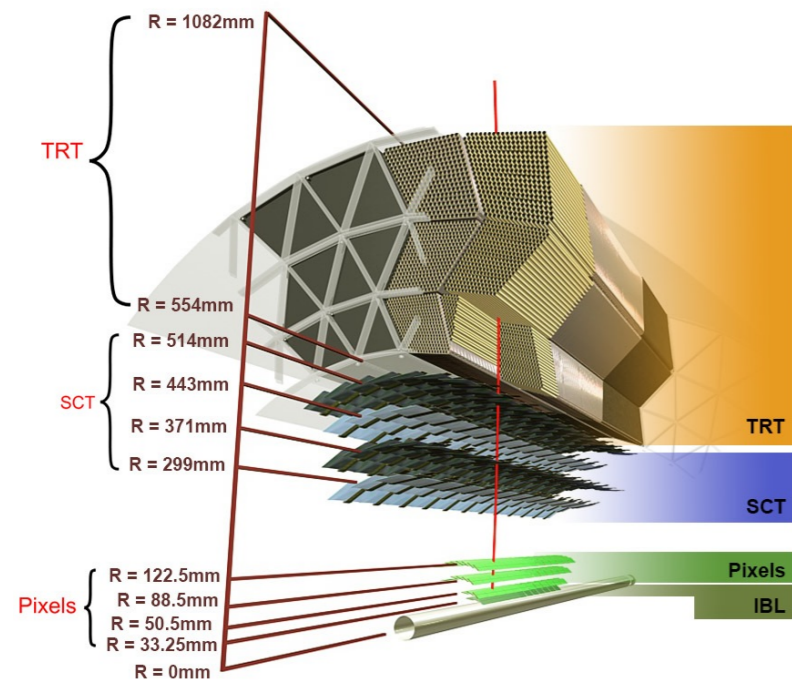
- During the break between Run 1 and Run 2, ATLAS inserted the IBL, an extra layer of silicon tracker close to the beam pipe

Calibration



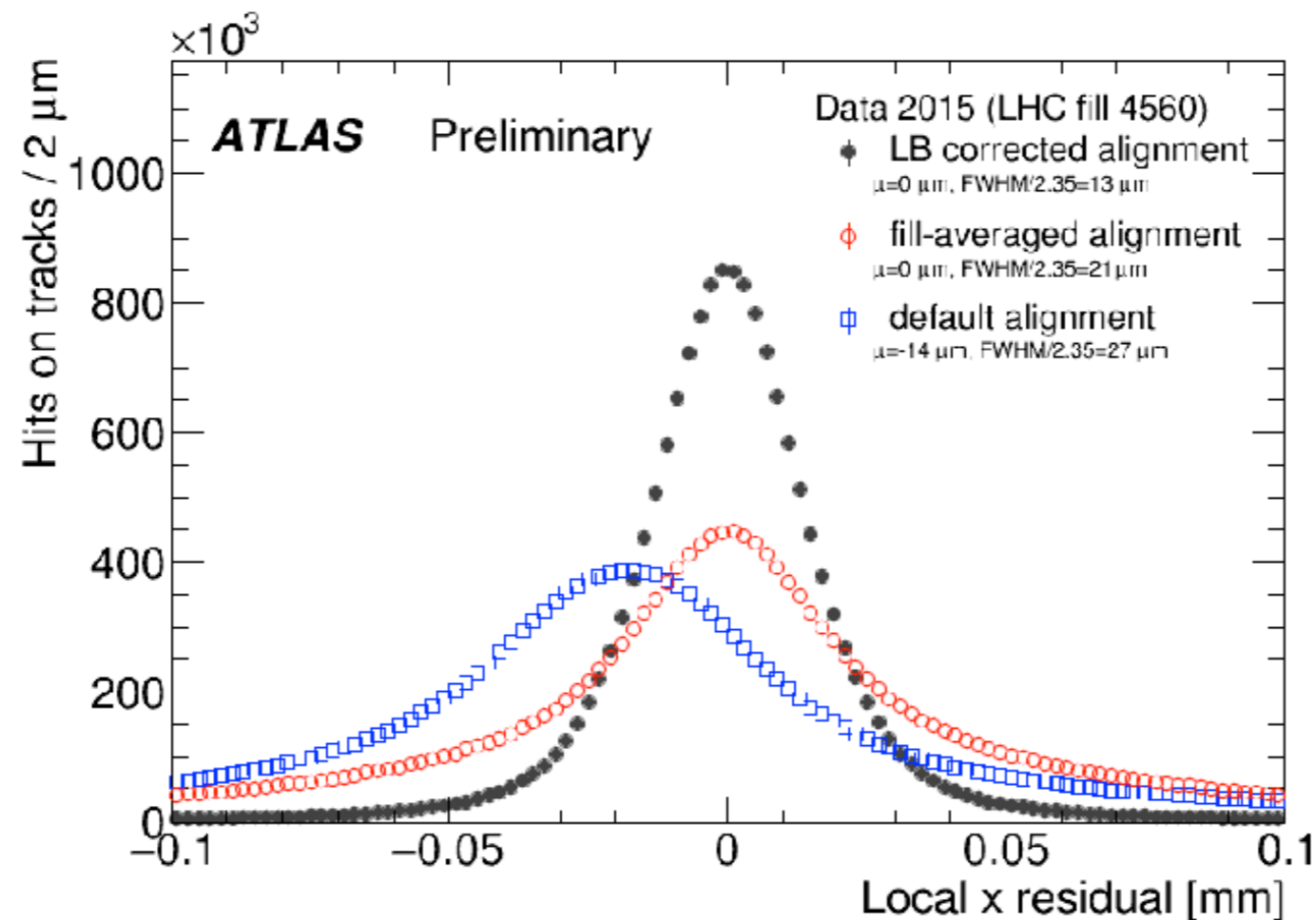
- During the break between Run 1 and Run 2, ATLAS inserted the IBL, an extra layer of silicon tracker close to the beam pipe
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Calibration



- During the break between Run 1 and Run 2, ATLAS inserted the IBL, an extra layer of silicon tracker close to the beam pipe
- At the start of data taking in Run 2, it started to move during data taking runs
- As time went on, the movement was very significant, much more than the detector precision, so the movement could be seen in physics distributions and data quality
- ATLAS implemented and commissioned a correction procedure **per run (red)** and then per **sub-run (black)** as part of its calibration process
- Following the correction the performance of the detector was back to nominal

Calibration quality



- Explain why the correction procedure **per run (red)** still resulted in a loss of precision and the per **sub-run (black)** procedure was necessary to retrieve the nominal detector performance

Data Preparation

- Three major steps to **prepare data for physics analysis** and achieve
 - reliable, high quality data (yes, we **reject** low quality data)
 - the **best performance** from our detectors
 - readiness for **physics analysis**

1. Reconstruct physics signals from the data

- Produce information like how many muons does the event have?



2. Calibrate the detectors

- Correct imperfections, account for changes over time...



3. Make sure that the **data quality** is excellent, also in real time

- Maximise the amount of useful data

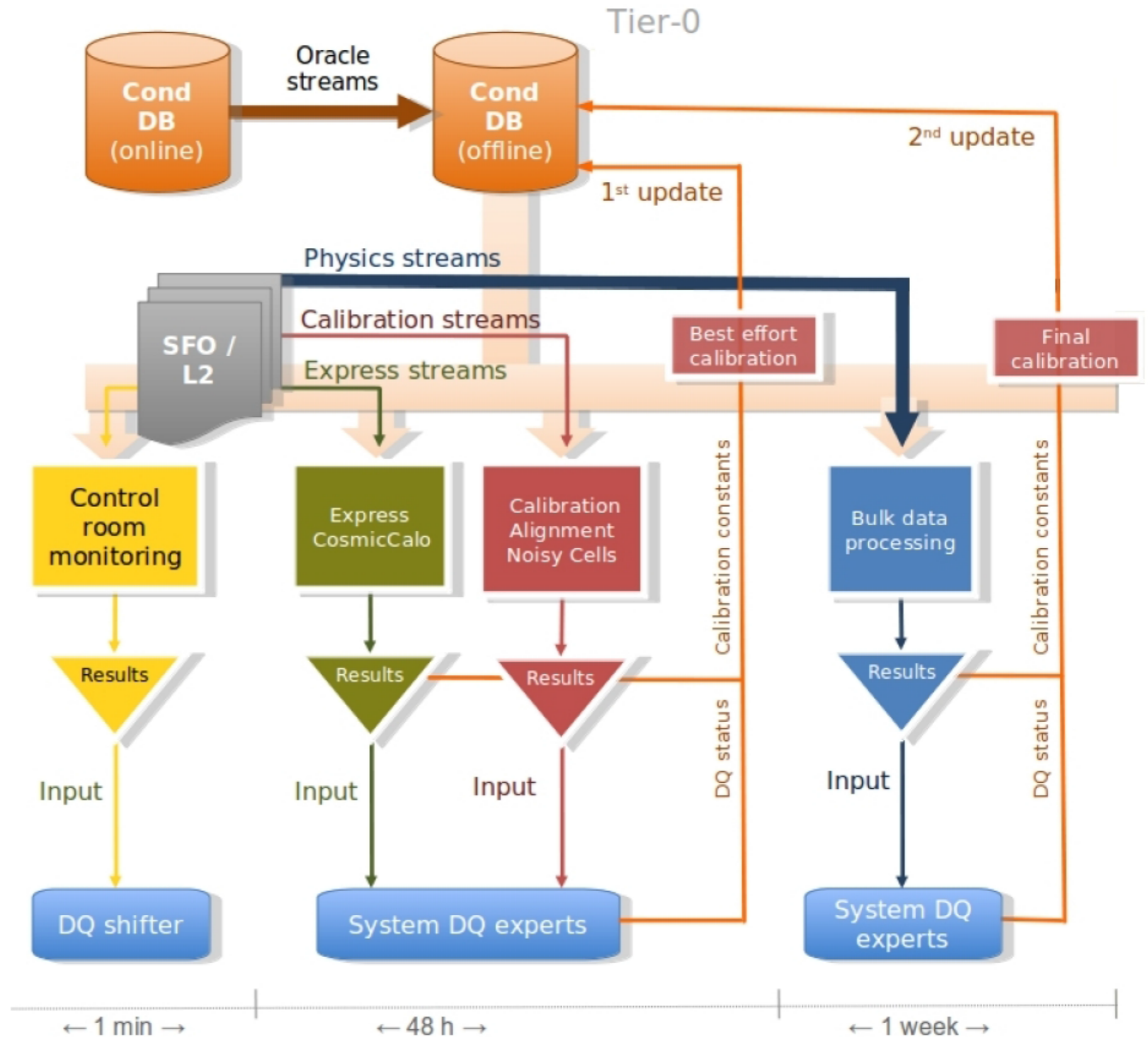
Data Quality

Check during data taking

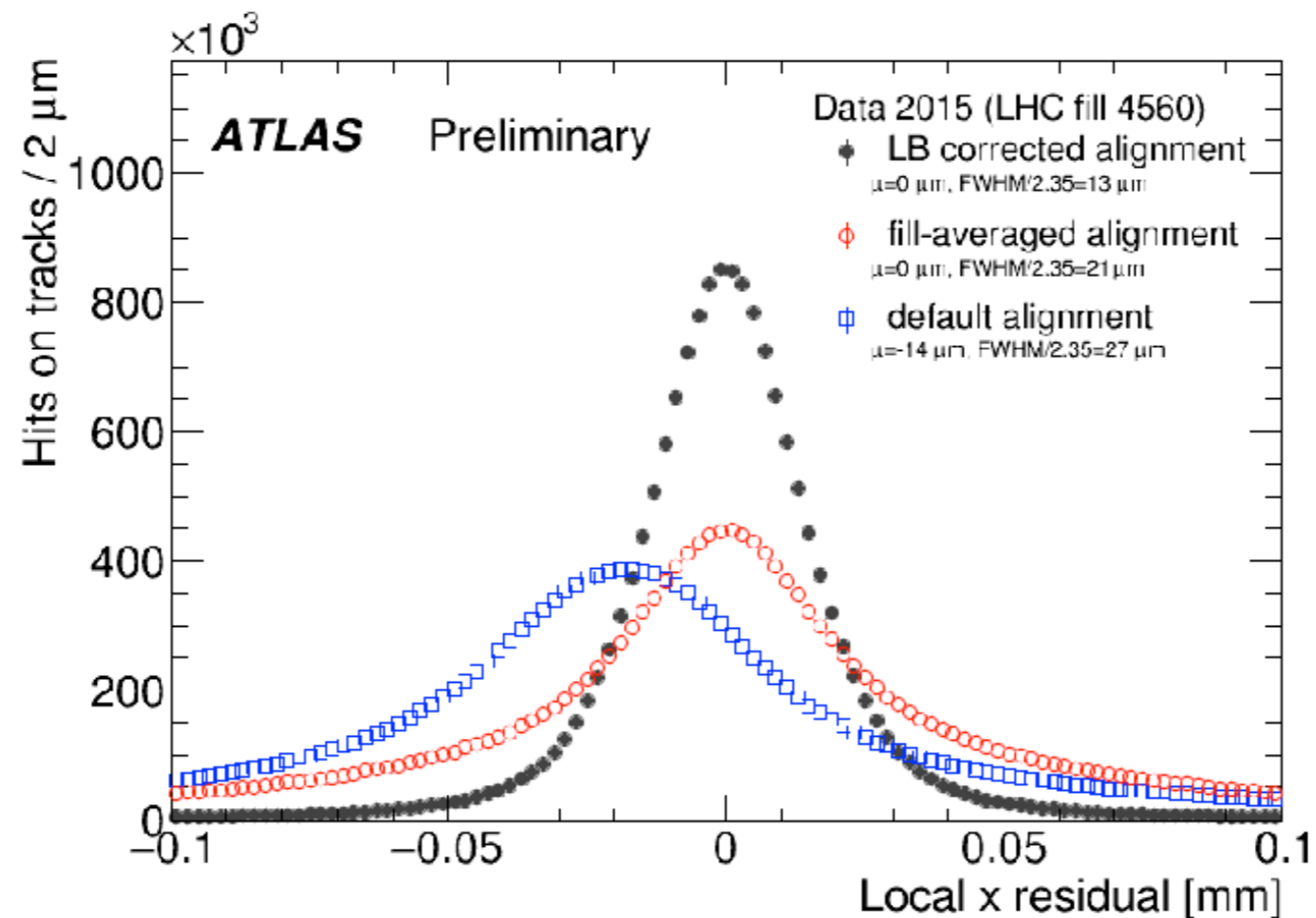
Check a fraction of the data with a quick calibration

Check all of the data with the best calibration

- Publish this data !!



What makes good data quality?



- The **ATLAS IBL** is a good example of a *data quality* problem

Potential data quality issues need to be monitored

- We need a reference, here that would be the **black** histogram, how we expect the data to look
- If the data quality shifter sees the **blue** or **red** histogram, they will raise the alarm!

Reconstruction figures of merit and data quality

	Definition	Example		Needs be:
Efficiency	how often do we reconstruct the object	electron identification efficiency = (number of reconstructed electrons) / (number of true electrons) in bins of transverse momentum		High
Resolution	how accurately do we reconstruct the quantity	energy resolution = (measured energy – true energy) / (true energy)		Good
Fake rate	how often we reconstruct a different object as the object we are interested in	a jet faking an electron, fake rate = (Number of jets reconstructed as an electron) / (Number of jets) in bins of pseudorapidity		Low

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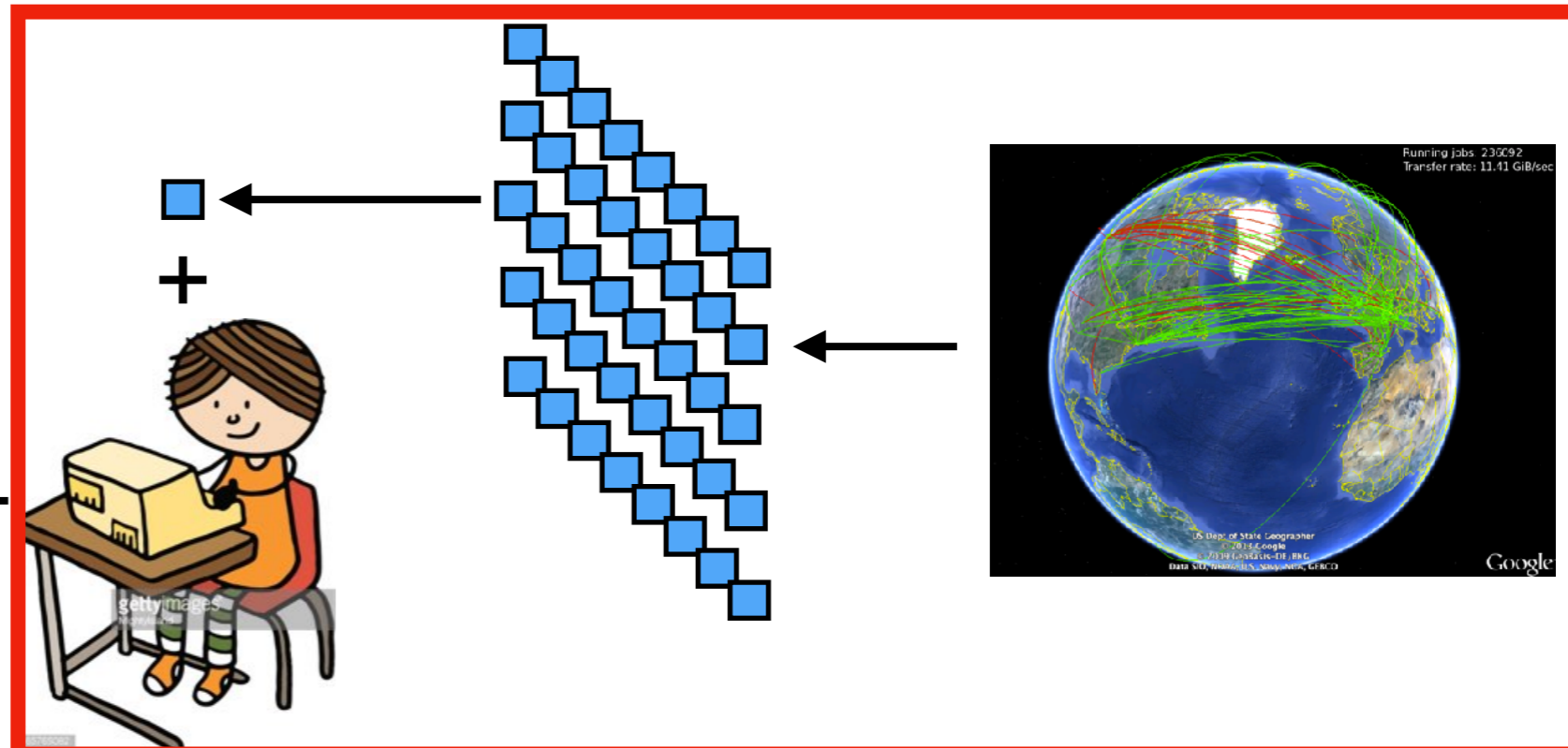
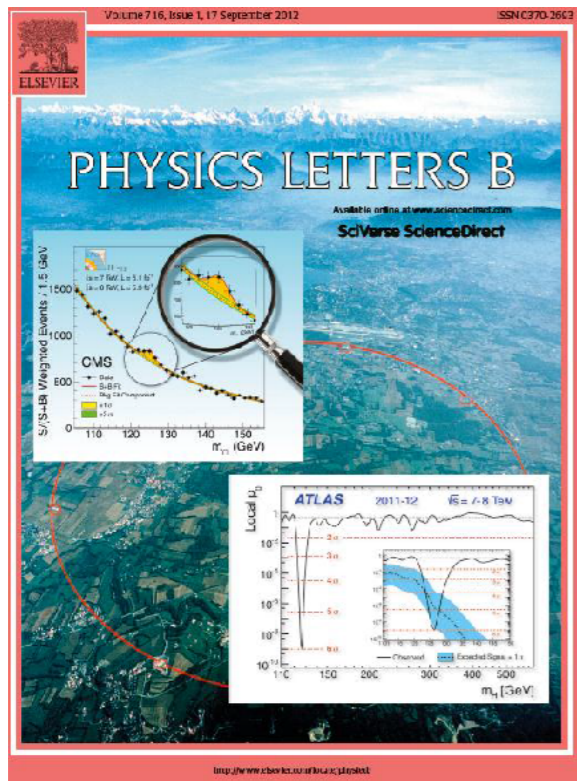
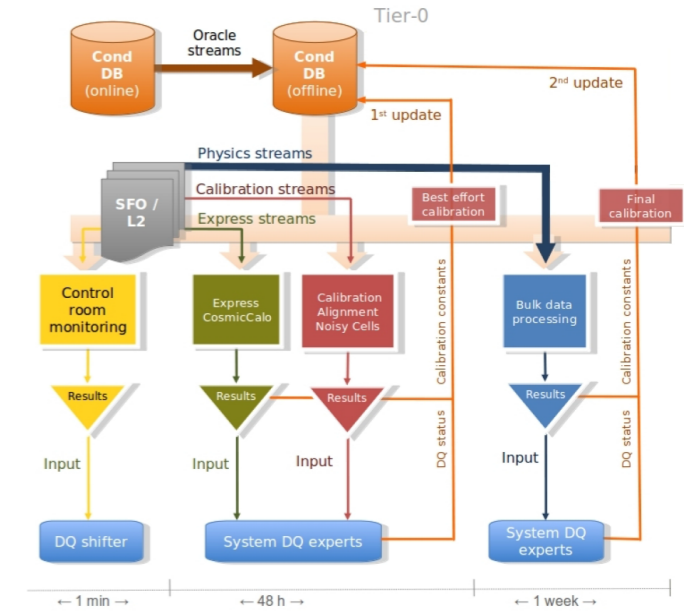
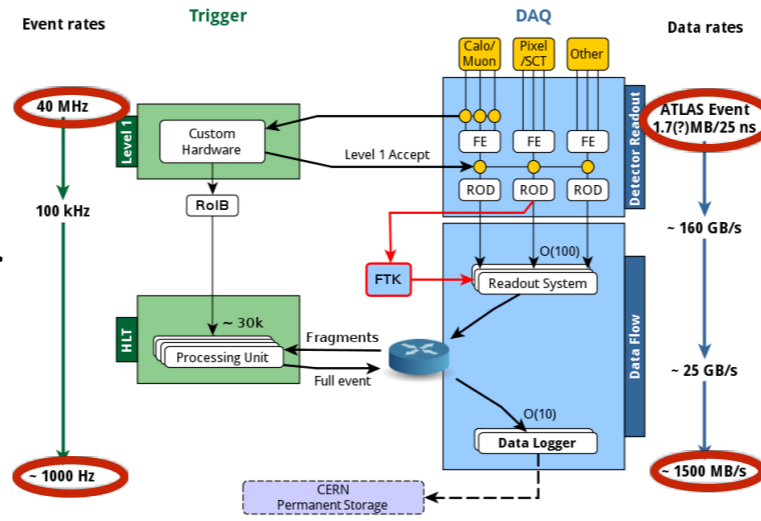
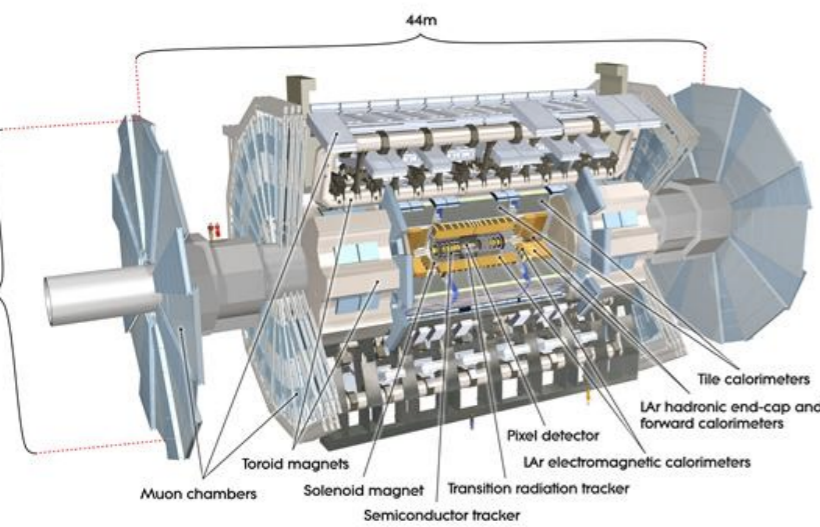


3. Make sure that the **data quality** is excellent, also in real time


- Maximise the amount of useful data



Data's journey - next time, analysis!



Contact details

- I am usually based at Geneva Observatory in Versoix, but will be here at CERN Wednesday 3rd through Friday 5th July
 - Tonight you will find me here 
- email: paul.laycock@unige.ch



**OPEN
MIC**

AT THE CROWNED EAGLE

Independence day special

Thursday July 4th

**OPEN MIC NIGHT AT THE CROWNED EAGLE.
7:30PM ONWARDS.**

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GENEVA**