

# High Field Magnets

# WP3.1 - Nb3Sn robust performance double aperture 12T cosO dipole models

**CERN** 20.12.2023

Lucie Baudin on behalf of the 12 T project team



20 December 2023

# Content

- 12T Design Guidelines
- Conceptual Design
- Mechanical design, FEM simulations and test campaign with mock-ups



# **12T Design Goals and Guidelines**

Minimize coil compression at all stages of magnet lifecycle

Protect the coils against risk of overstress due to accidental loads → work with close cavity A soft component deforms until the rigid cavity closes. Once the cavity is closed, the load is handled by the cavity, the soft component do not further deform

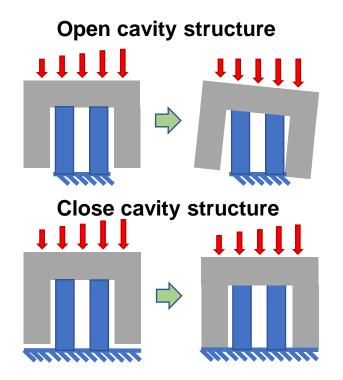
**Decrease influence** of manufacturing **tolerances** on magnet performances

Limit the number of components to avoid piling-up tolerances



**Decrease the degree of redundancy** in the structure to enable better control of contact force distribution between parts

Stress at room temperature < 120 MPa **Stress at cold < 130 MPa** Pole – Coil contact closed at cold





# **Conceptual Design**

### Robust, intrinsically safe mechanical structures

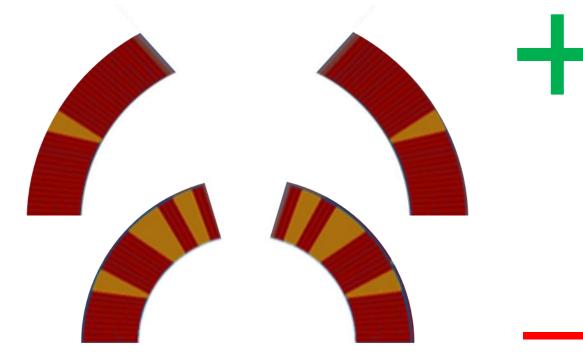
Presented at the Conceptual Design Review at CERN on 5 July 2023.





### Separation of inner and outer layer coils

Inner and outer layers are winded and reacted separately and placed on top of each other with an interlayer



#### Mechanical kinetics:

**less statically indeterminate,** the coils can slightly move with respect to each other **peaks of stresses** (possibly leading to cracks, *see Diego's presentation*) **are reduced** 

### Cooling:

possibility of using the coil interlayer to bring helium closer to the coils

### Winding:

simpler winding

no need of primer in the layers

Coil production:

inspection of outer layer of inner layer coil at each manufacturing step

in case of accident, only the concerned layer cable is discarded and not the total length of the pole

#### Winding/tolerances:

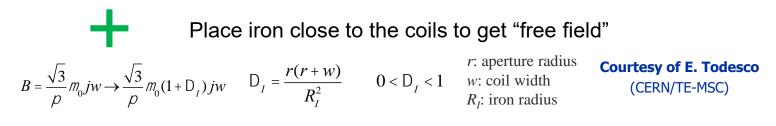
two systems of molds (for the 1<sup>st</sup> and 2<sup>nd</sup> layers) <u>Coil production:</u> need of a coil splice



### **Collared coils**

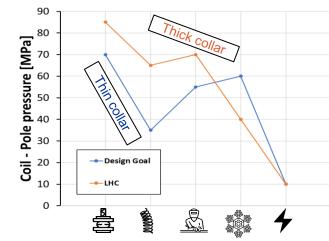
For reasons of **time and resources** we concentrate on the collared coils

### Thin stainless-steel collars:



Thin collars will result in important springback

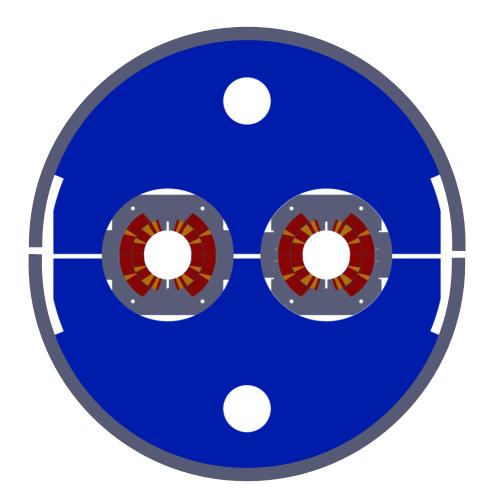
Average coil prestress at the contact with the collar pole during the assembly and energization



We want to keep moderate coil prestress during collaring

We must **recover pre-stress** in the following assembly steps and during cool down





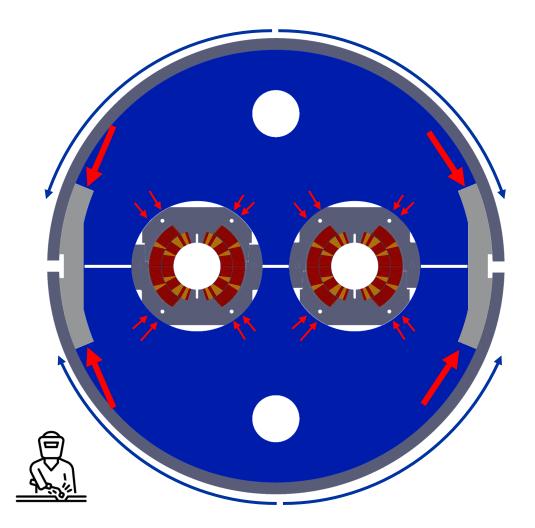
### Horizontal iron yoke gap structure

Enable coil pre-compression increase during cool down

### **Stainless steel shell**

Enable longitudinal preload via bullet cage





### Horizontal iron yoke gap structure

Enable coil pre-compression increase during cool down

### **Stainless steel shell**

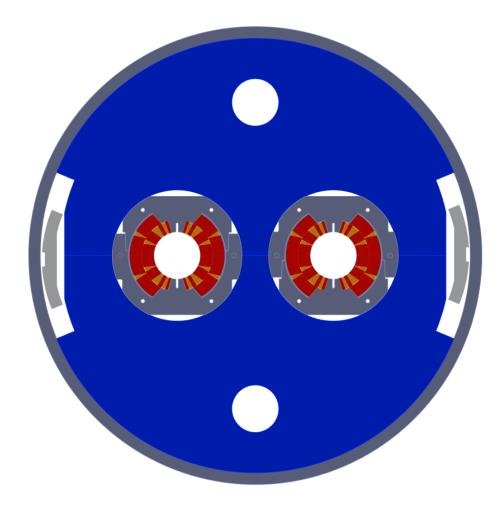
Enable longitudinal preload via bullet cage

### **Aluminium stoppers**

Protect the coils against risk of overstress due to accidental loads during assembly process

Decrease influence of manufacturing tolerances on magnet performances





### Horizontal iron yoke gap structure

Enable coil pre-compression increase during cool down

### **Stainless steel shell**

Enable longitudinal preload via bullet cage

### **Aluminium stoppers**

Protect the coils against **risk of overstress** due to **accidental loads during assembly process** Decrease influence of **manufacturing tolerances** on **magnet performances Increase pre-compression** of the coil, at cold

### Close horizontal gap at cold

Protect the coils against risk of overstress due to accidental loads during operation

A yoke which is one piece horizontally provides stiffness against the electromagnetic forces

Minimize retaining structure deformations as these can generate extra coil deformations in the horizontal midplane

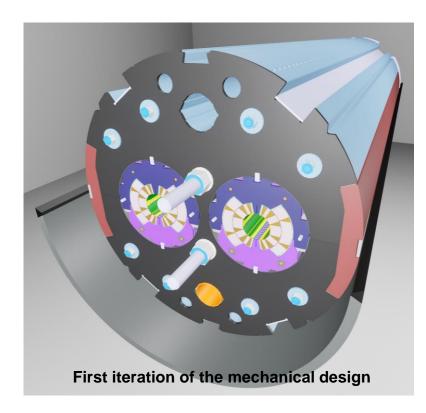


# Mechanical design FEM simulations and test campaign with mock-ups



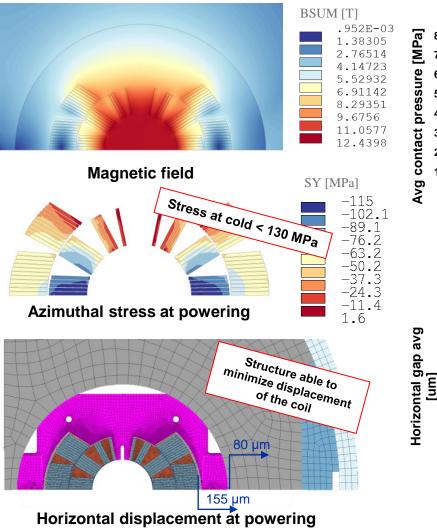
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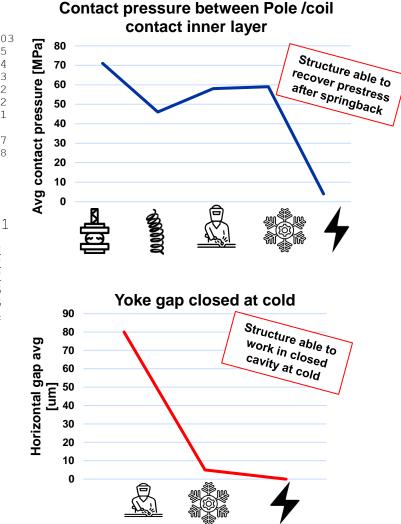
# **Mechanical design and simulations**



The FEM shows that, with the baseline design, the structure, is able to:

- Recover pole prestress after springback
- Minimize coil compression
- Provide rigidity against the EM forces







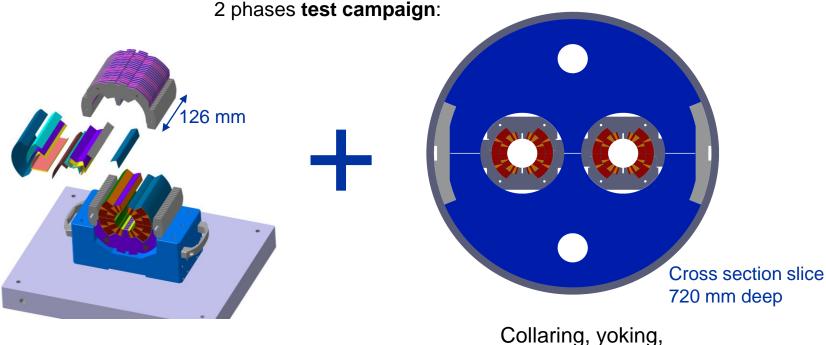
### Understand and control the coil stress distribution during magnet lifecycle

Courtesy of O. Id Bahmane (CERN/EN-MME)

inner and outer layers reacted and impregnated separately



As **intermediate step**, mock-up will be done by taking advantage of the **available resources**, non-conforming straight sections of **11T's coils**. Inner and outer layers have been reacted and impregnated separately.



Collaring mock-up

Collaring, yoking, welding and cooling down mock-up



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Employing the available resources : 11T coil, 11T stainless steel shell.

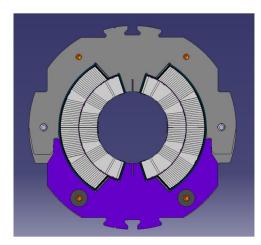
inner and outer layers reacted and impregnated separately

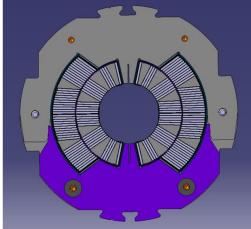


As **intermediate step**, mock-up will be done by taking advantage of the **available resources**, non-conforming straight sections of **11T's coils**. Inner and outer layers have been reacted and impregnated separately.



**11 T modified** ST1685289\_01





12 T

ST1757039\_01

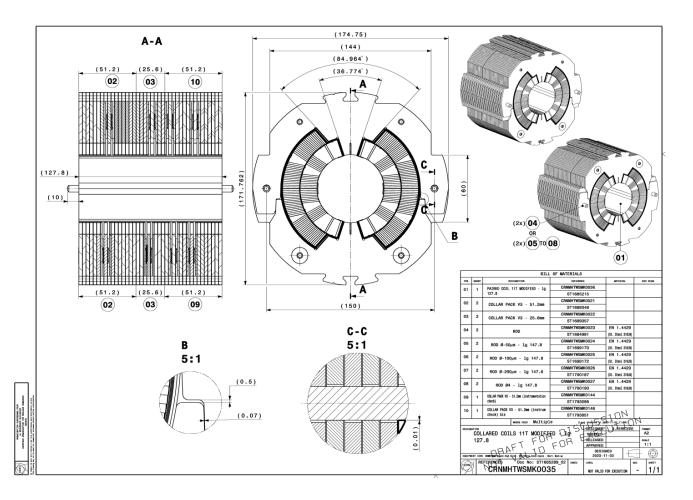
|     |  |   | E     |
|-----|--|---|-------|
| Sar |  | R |       |
|     |  |   | 1 A A |
|     |  |   |       |

| Coil  | 11T<br>modified | 12T<br>baseline | 12T<br>backup |
|---|-----------------|-----------------|---------------|
| Ø Internal<br>Coil [mm]                                   | 60              | 50              | 60            |
| R int<br>collar<br>[mm]                                   | 62.375          | 64.675          | (69.675)      |
| R ext<br>collar<br>[mm]                                   | 87.375          | 89.675          | (94.675)      |
| Collaring<br>tool<br>distance<br>between<br>teeth<br>[mm] | 144             | 148             | (158)         |





### Evaluate the influence of the two layers separation and interlayer characteristics



Dummy coil aluminum:

- 1 block
- 2 separated layers
  11T coil:
- 1 block (section of 11T coil with the two layers impregnated together)
- 2 separated layers

### Interlayer characteristics:

- thickness
- materials : mica, fiberglass, wax impregnated fiberglass, fishbone...

### Experimental measurement and benchmark of FEM parameters

CTE, Interlayer frictional coefficient, E-modulus...



### Knowledge of coil material properties

Nb3Sn coil characteristics – Non-linear Young Modulus Tests and measurement done on 11T coil

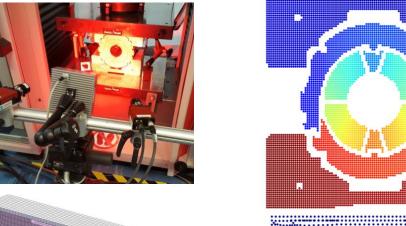
FEM mechanical simulations are now carried out using this curve (or bi-linear approximation).

s curve (or bi-linear approxim

Mock-up Based Testing Methodology for the

Mechanics of High-Field Superconducting

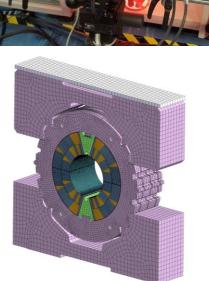
Magnets, A. Bertarelli and all, MT28

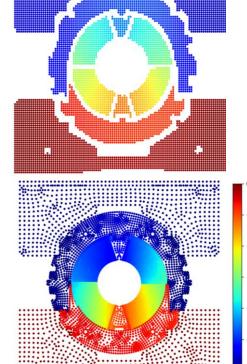


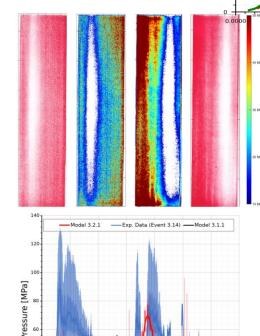


VS

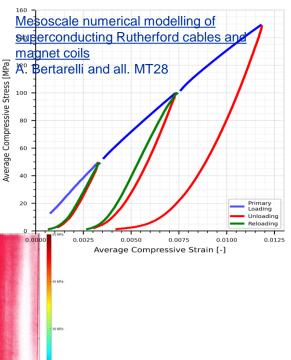
FEM computations







Lateral Position [mm

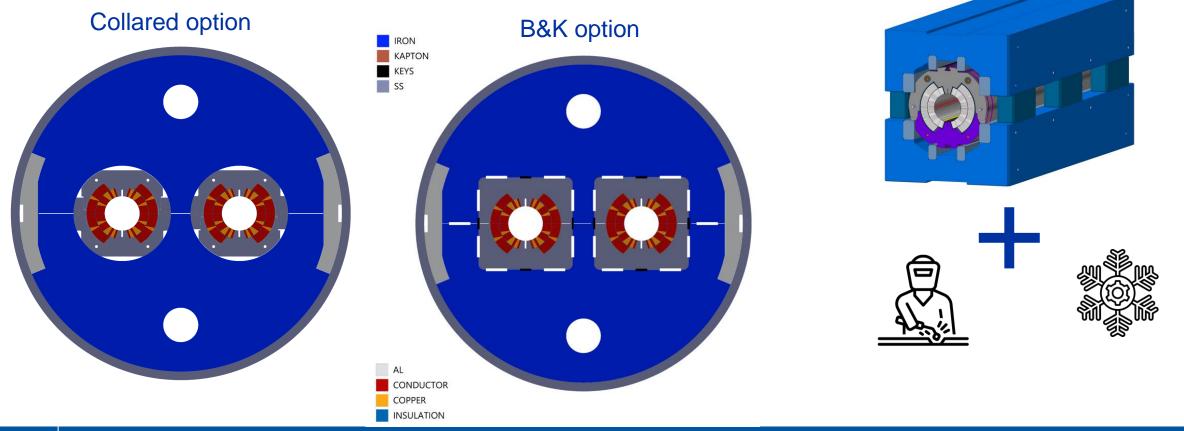


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Experimental verification of the assembly parameters in the pre-compression of the coils during magnet lifecycle

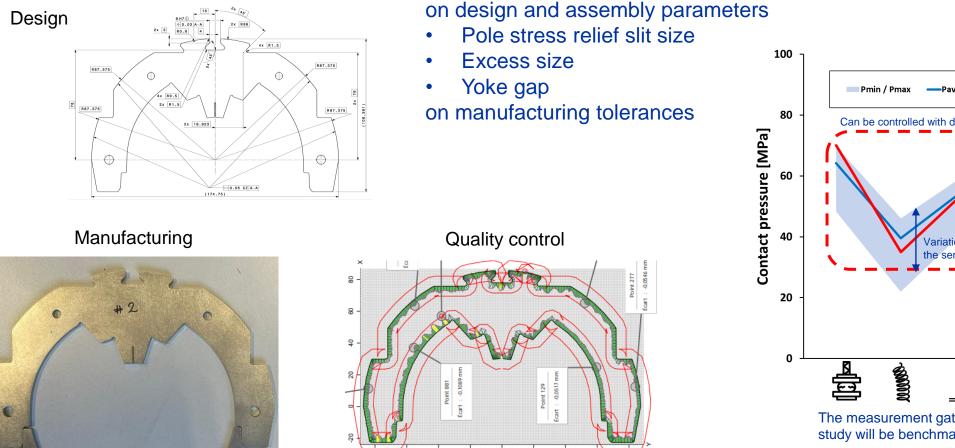
720 mm cross section slice Reusing 11T stainless steel shell

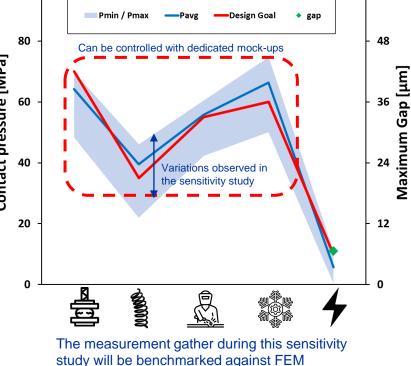




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### Evaluate the influence of manufacturing tolerances and assembly parameters in the precompression of the coils Sensitivity study







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# Thanks for your attention

Thanks to

### CERN/TE-MSC-SMT section and

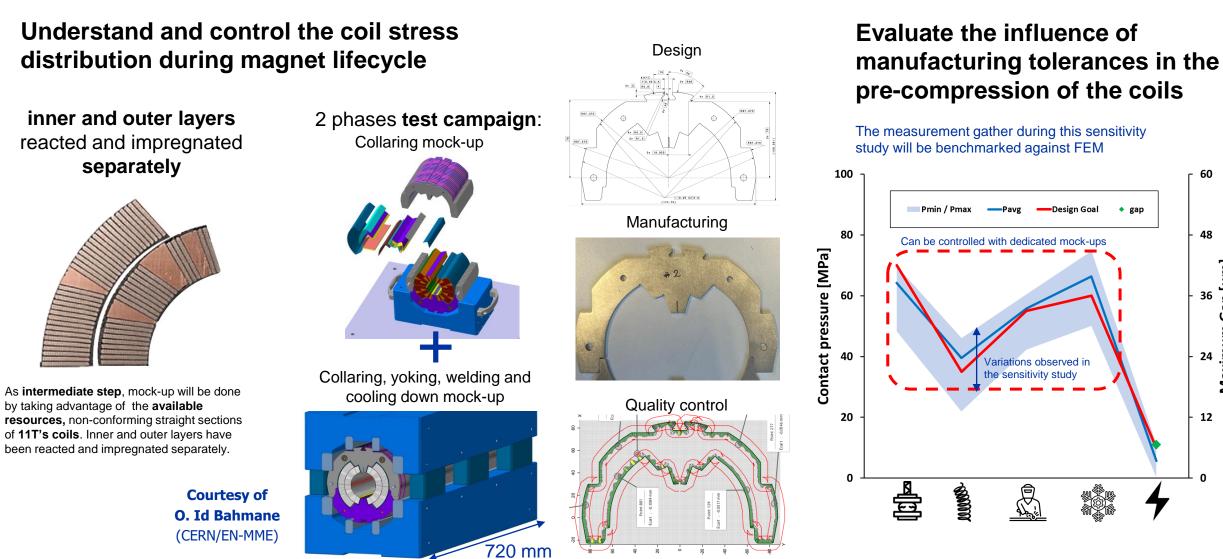
### **12T project team members**

D.Perini, C. Abad Cabrera, L.Baudin, T. Boutboul, L.Fiscarelli, A.Foussat, A.Haziot, S.Hopkins, V.Ilardi, K.Lazaridou, N.Lusa, R.Piccin, P.Wachal, F.Mangiarotti, M.Masci, D.Paudel, S.Russenschuck, M.Wozniak





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60

48

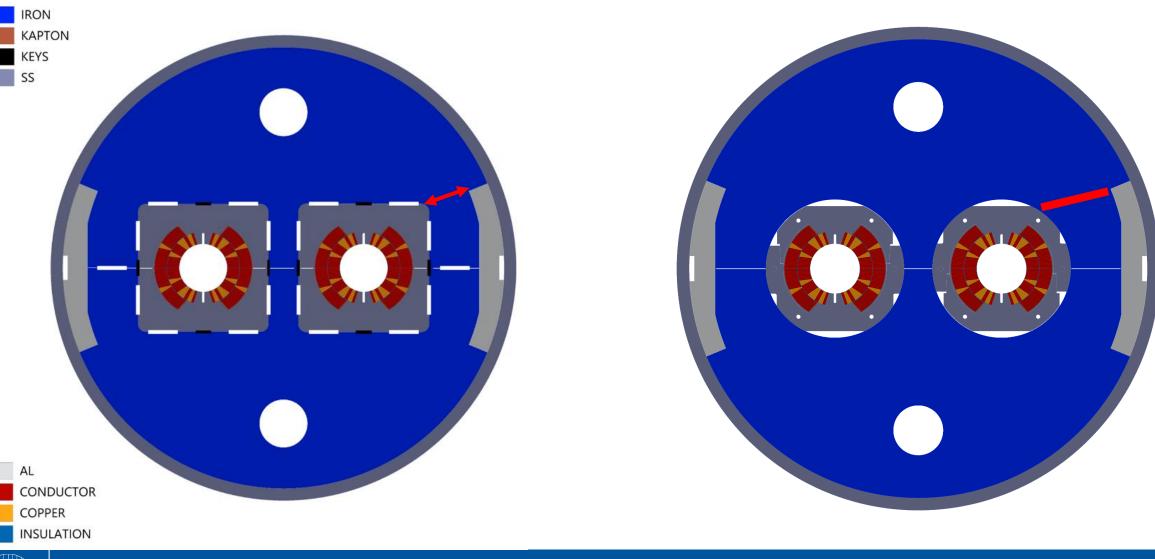
36

24

12

Maximum Gap [μm]

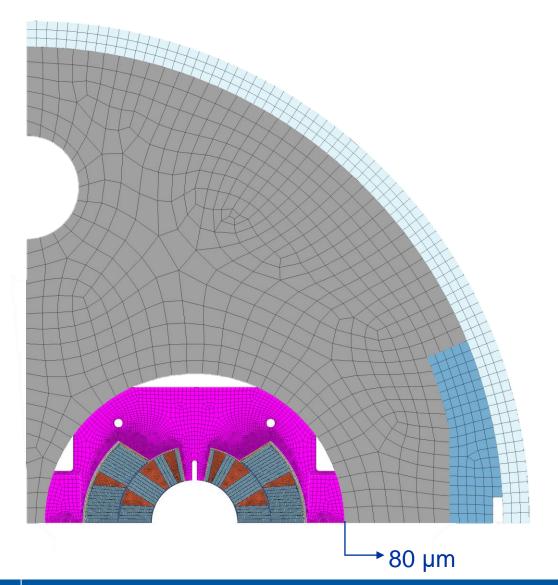
# Iron yoke stiffness with the b&k version

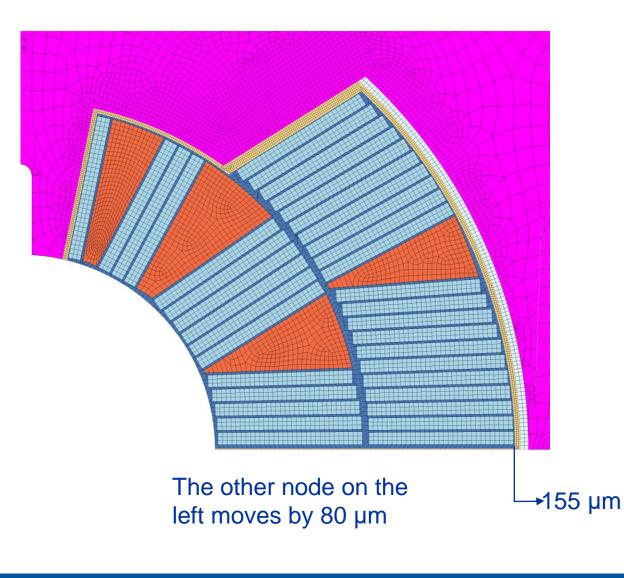




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# **Displacement 12T**

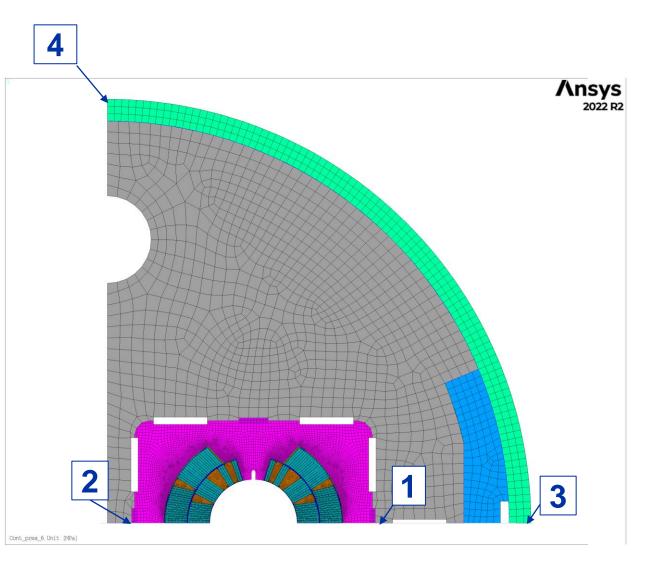






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# **Displacements – closed gap**



|   | 1     |       | 2     |        | 3      |    | 4  |        |
|---|-------|-------|-------|--------|--------|----|----|--------|
|   | Ux    | Uy    | Ux    | Uy     | Ux     | Uy | Ux | Uy     |
| 9 | 64    | 76.4  | -6.2  | -106.3 | 30.4   | 0  | 0  | -104.8 |
|   | -392  | -29.2 | -33.1 | -22.8  | -689.2 | 0  | 0  | -636.2 |
| 4 | 127.9 | -26.9 | -7.6  | -73.6  | 109.6  | 0  | 0  | -79.6  |



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# Magnetic design

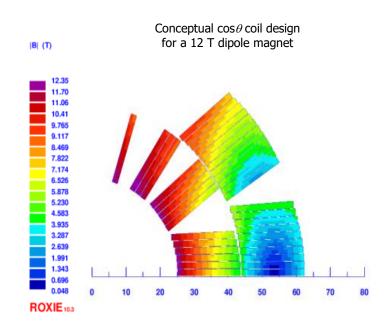
# Choice of conductor motivated by the availability of strands and cable

| Parameter         | Unit              | Value                     |  |  |  |
|-------------------|-------------------|---------------------------|--|--|--|
| Strand            |                   |                           |  |  |  |
| Strand type       |                   | MQXF                      |  |  |  |
| Strand layout     |                   | RRP 108/127               |  |  |  |
| Strand diameter   | mm                | 0.85                      |  |  |  |
| Non-Cu Jc         | A/mm <sup>2</sup> | 2087 at 4.4 K and 13.54 T |  |  |  |
|                   | C                 | able                      |  |  |  |
| Number of strands |                   | 40                        |  |  |  |
| Pitch direction   |                   | Left                      |  |  |  |
| Cable mid         | mm                | 1.525 ± 0.010             |  |  |  |
| thickness         |                   | 1.525 ± 0.010             |  |  |  |
| Cable width       | mm                | $18.15 \pm 0.05$          |  |  |  |
| Cable Keystone    | o                 | $0.40 \pm 0.1$            |  |  |  |
| Pitch             | mm                | 109 ± 3                   |  |  |  |
| Core material     |                   | 316L                      |  |  |  |
| Core thickness    | μm                | 25                        |  |  |  |
| Core width        | mm                | 12                        |  |  |  |
| Cabling Ic        |                   | < 5%                      |  |  |  |
| degradation       |                   | < 576                     |  |  |  |
| RRR               |                   | 150                       |  |  |  |

Cable characteristics for a 12 T dipole magnet

| Aperture          | mm        | 50      | 56      |
|-------------------|-----------|---------|---------|
| Cable             | #str x mm | 40x0.85 | 40x0.85 |
| Number of blocks  |           | 6       | 6       |
| Number of turns   |           | 37      | 41      |
| Coil outer radius | mm        | 62.5    | 65.5    |
| Current           | kA        | 17.750  | 17.110  |
| Bore field        | Т         | 12.01   | 12.00   |
| Peak field        | Т         | 12.42   | 12.33   |
| Load line         | %         | 83.62   | 82.48   |
| Temp. margin      | К         | 4.1     | 4.3     |
| b3                | units     | -0.4    | -0.1    |
| b5                | units     | 0.0     | 0.0     |
| b7                | units     | 15.8    | 5.6     |
| b9                | units     | 2.5     | 0.3     |
| Diff. inductance  | mH/m      | 2.641   | 3.128   |
| Stored energy     | MJ/m      | 0.451   | 0.508   |

### Design of the 2D cross section geometry



### Protection must be evaluated

Baseline to start working on mock-ups, tooling: 50 mm diameter aperture Winding tests are required





Extensive winding tests to optimize the geometry of the end spacers, tooling and the winding parameters

First trials with a 50 mm aperture

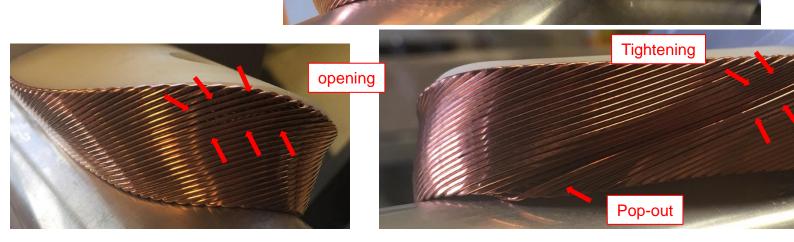
**3D rapid prototyping** allows us a quick and low-cost way to compute, manufacture and test end spacers, **fast feedback loop** 

Variants characterized by quantifiable parameters: torque, soft bending, hard bending

Benchmarked against Roxie computations

The parameters to be optimized:

- cable tension
- angle and external torque
- tooling
- geometry of the spacer head



tooling



# **Design of suitable production tools**

Objectives for a robust design (tooling and process) :

- minimize of coil handling during fabrication (minimize human errors)
- remove of the ceramic binder (see Roland's presentation)
- strong attention to the scaling up in length

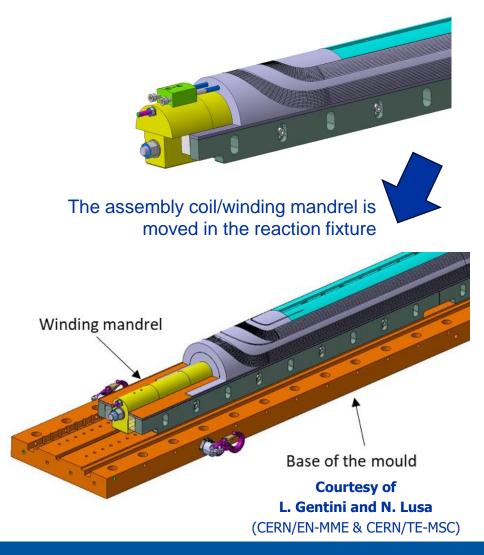
Design baseline: CERN contribution on FalconD Project (see Stefania's presentation)

Main idea:

The **winding mandrel** becomes **part of heat treatment mould** no need to move the stand-alone coil from the winding machine to the heat treatment mould

Coil production steps tooling final design for 12 T VE :

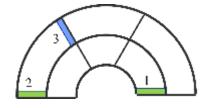
- winding & press cycle
- reaction heat treatment
- impregnation







### **Internal Splice**

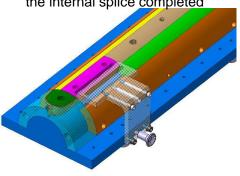


#### Challenges:

- Support the brittle Nb3Sn cable
- Splicing in the **limited space** of the pole region
- Splice in the high field region

### Mechanical design for the mould for the internal splice completed

First iteration with 3D printed plastic parts





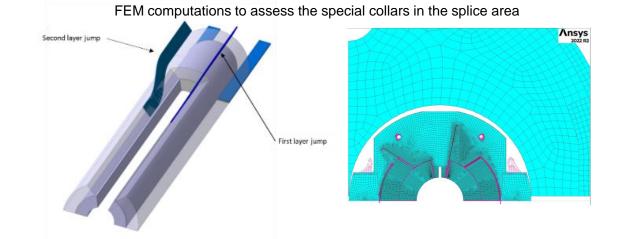
First soldering tests done. Results under analysis

### **External Splice**

- Nb<sub>3</sub>Sn Nb-Ti splice
- Nb-Ti Nb-Ti splice

Challenges:

- Support the brittle Nb3Sn cable
- **Two layer-jumps** to be accommodated into the coil pack
- **Double-layer jump** for the inner layer cable



### Modular coil molds and assembly tooling are designed to realize the two different splices



# **Control the reproducibility of coil** fabrication procedures

### Size and rigidity measurements of the coils

Refurbishment of the E-modulus press in 927 Measured data used to define procedure for the **pre-compression** assembly on the coil **during collaring** 

### Test coil structure under production

Construction of a coil test device to validate single coils in a 'mirror' configuration

#### Step by step approach:

Validation of coil design and manufacture before going to final dipole configuration and production

Fast feedback loop on the coil fabrication

Part of the technology development program as between a test structure *(see Diego's presentation)* 

Mid-plane pressure sensors



Courtesy of L.Dassa, N.Vejnovic (CERN/EN-MME)

'bladders and keys' type of loading for modularity



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Single aperture half (mirrored)

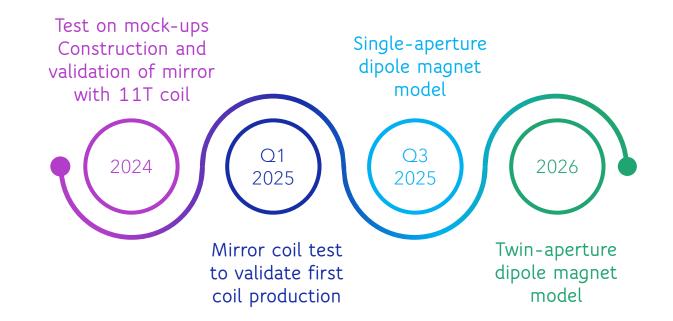
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MSC-SMT

# **Conclusions and perspectives**

Scope of the 12 T VE program is the design, manufacture, and qualification of a value-engineered, accelerator-fit, 12-T, Nb3Sn dipole magnet model, by 2026.

Robust, intrinsically safe structures Knowledge of coil material properties Rigorous procedures and suitable assembly tools





# Requirements

# Scope of the 12 T VE program is the design, manufacture, and qualification of a value-engineered, accelerator-fit, 12-T, Nb3Sn dipole magnet model, by 2026.

Coils made from Nb3Sn Rutherford cables with a cosO layout and two layers

The **solutions** for a short dipole must be **scalable to a long one** Magnetic length of ~1.2 m for short models, ~5 m and 15 m for the long versions

### Step by Step approach:

Evaluation of possible diverse solutions. Choice of most promising options and final analysis.

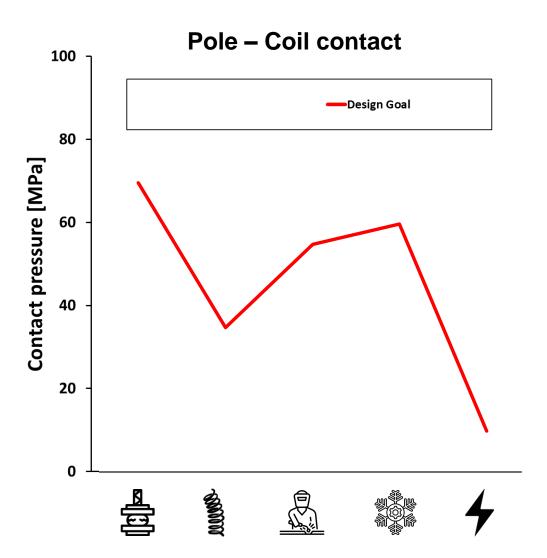
**Test campaign** with **mock-ups** to understand and control the coil stress distribution during the magnet lifecycle. Confirmation of the **FEM computation**.

Construction of a **coil test device** to validate single coils in a 'mirror' configuration and two coils in a single aperture structure.

Only when we obtain satisfactory coils, we can go to a double aperture dipole



# **Design goals:**



**Stress at room temperature < 120 MPa** 

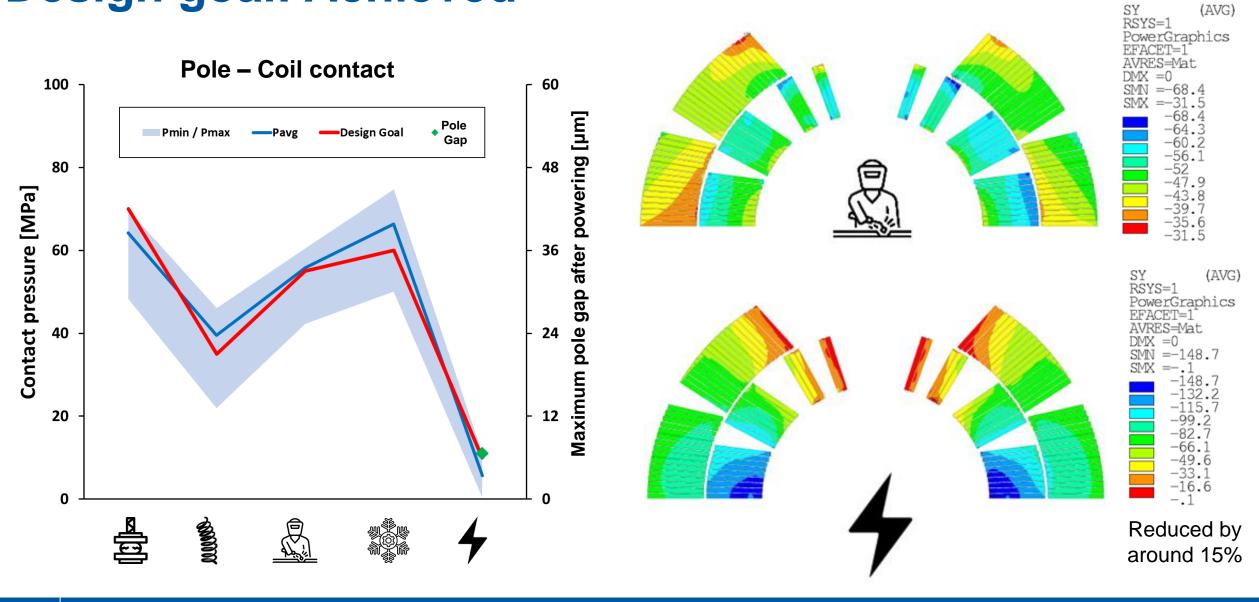
Stress at cold < 130 MPa

Pole – Coil contact closed at cold



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# **Design goal: Achieved**



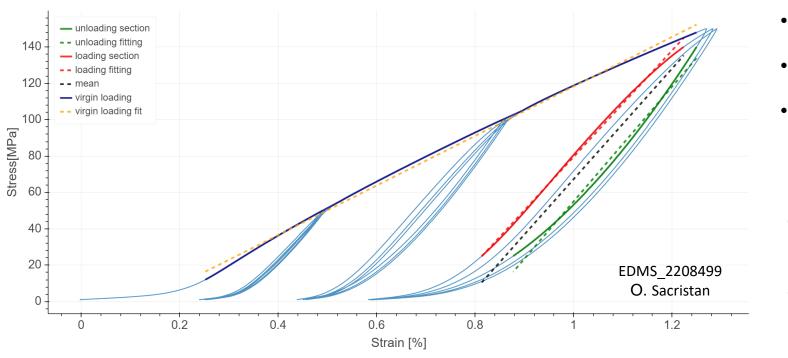


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(AVG)

# **Material models**



| Material        | Young's modulus [GPa] | Poisson's ratio [-] | CTE [mm/m/ΔT] |
|-----------------|-----------------------|---------------------|---------------|
| Copper          | 100/110               | 0.3                 | 3.37          |
| Kapton          | 1.9/2.7               | 0.3                 | 4.37          |
| Stainless Steel | 191/210               | 0.28                | 2.8           |
| Kawasaki        | 186/204               | 0.28                | 1.8           |
| Iron            | 203/225               | 0.28                | 2.0           |
| Aluminium       | 72/79                 | 0.3                 | 4.2           |

### **Calculated Stiffness**

| • | Virgin | Loading (I | RT and | 77K): | 14 ±2 GPa |
|---|--------|------------|--------|-------|-----------|
|---|--------|------------|--------|-------|-----------|

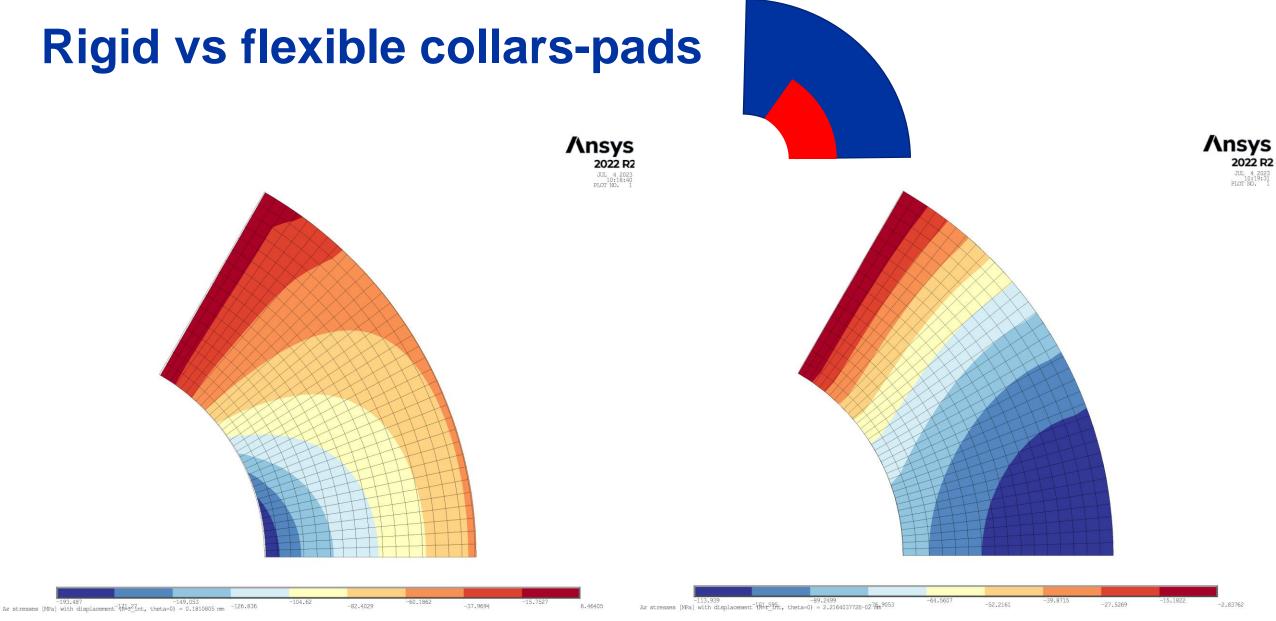
- RT Loading/unloading phase: 31 ±3 GPa
- 77K Loading/unloading phase: 39 ±3 GPa

### Orthotropic CTE

| Direction    | ΔL/L <sub>0</sub> at 1.9 K * 1000<br>Inner/outer layer | σ(ΔL/L <sub>0</sub> ) at 1.9 K * 1000<br>Inner/outer layer |
|--------------|--|--|
| Longitudinal | -2.98  | 0.06   |
| Radial       | -1.61 / -1.75  | 0.04 / 0.03  |
| Azimuthal    | -2.55 / - <b>3</b> . <b>77</b>                         | 0.38 / 0.47  |
|              |  |  |

CERN-THESIS-2022-274 (Stefan Höll)

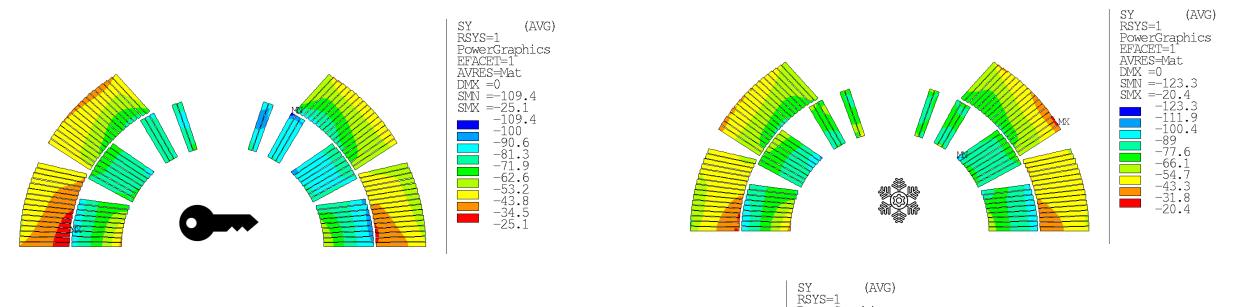


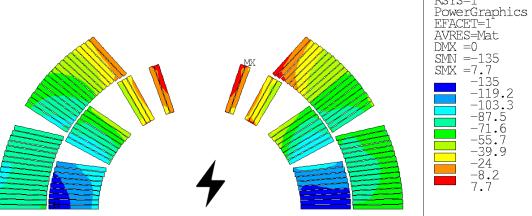


#### Curtesy of G.Vernassa

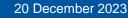


### **Stress – AZ**

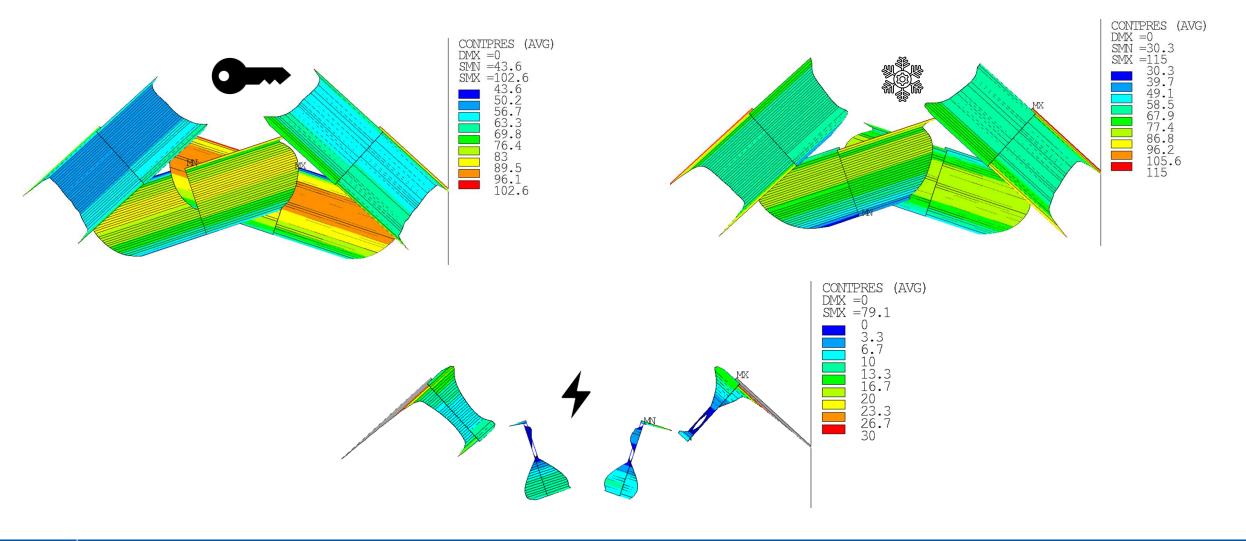








## **Pole pressure**





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