

# Generalization and self-supervision for physics simulation



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Work realized in collaboration with Oracle

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## Introduction

- Motivation:
  - Utilization of machine learning algorithms at CERN is increasing together with the complexity of the algorithms
  - Necessity to develop efficient methods for performance tracking and cost optimization
  - Ensure model generalizability and reusability.
- Current focus:
  - Start with a Generative model
    - · Generative Models are amongst the most important architectures studied at CERN,
    - Need to replace Monte Carlo based physics simulations
  - How much can we extrapolate to other geometries and tasks (example: measuring particle properties)
    - Understand how foundation model concepts, such as self-supervised learning and transfer learning, apply to our use case.
    - Understand the minimal scale of the model for reaching meaningful results (No need to reach BERT / GPT-4 scale)
    - · High number of resources needed for training



## What is a foundation model in our study

#### What are foundation models:

- · A model trained on broad data and adaptable to a range of different downstream tasks, zero-shot, few-shot learning.
- · Self/semi-supervised learning + transfer learning but at scale
  - Large and diverse datasets  $\rightarrow$  powerful representations
- Examples: BERT, GPT, DALL-E
- Stanford CRFM (2021) : On the Opportunities and Risks of Foundation Models [arxiv.2108.07258]

#### Motivation:

- · Foundation model trained on MC data to perform different physics related tasks
  - · Simulations one lengthy training, then fast adaptation to different detector geometries
  - **Reconstruction** one base model adaptable to different tasks (particle identification, regression on phys. variables, etc.)
- Understand how foundation model concepts (self-supervised learning and transfer learning) apply to our use case:
  - · Understand the minimal scale of the model for reaching meaningful results



Image obtained from: On the Opportunities and Risks of Foundation Models

## Single particles in calorimeters

- The datasets are simulated using the GEANT4 toolkit (G4)
  - The energy deposits in the calorimeter cells result from the interaction of an incoming primary particle with the calorimeter material. These deposits form a characteristic shape that we call "**shower**".
  - Simplistic cylindrical geometry
  - · The mesh aligns with the direction of incident particle
  - The direction, i.e., the angles are recorded.
- Dataset Characteristics:
  - 1M samples
  - 45x16x9 6480 voxels
  - Incident energies ranging from 1 GeV to 1 TeV
  - Φ **0 to 2**π

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• θ - **0.87 to 2.27** 





## **Diffusion + transformers**

#### Start with a Generative model:

- · Current state of the art are Diffusion models
  - · Lead to higher accuracy and higher diversity
  - · Markov chain that gradually adds noise to the until signal is destroyed
- Denoising Diffusion Probabilistic Models [https://arxiv.org/pdf/2006.11239.pdf]



#### Add transformer blocks:

- A generalized architecture that works with any type of data, e.g., text, images, audio, etc.
- Models long-range dependencies (Attention mechanism).
- Attention is all you need [https://arxiv.org/abs/1706.03762]



## Our model

#### **Conditions:**

- Energy
- Φ
- 0
- Geometry

#### The model:

- Diffusion steps = 400
- Embed dim = 144
- Cosine scheduler

https://arxiv.org/abs/2212.09748



## **Generation Results**

**Good accuracy** throughout all the profiles

**Cell energy shows particular good results** compared to other generative models

Trained for 300 epochs on a single V100 GPU. (around 15 minutes per epoch)

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## So what else can it do?

Reconstruction - one base model adaptable to different tasks

- Energy regression
- Around 75% accuracy
- · Better than other generative models
  - Diffusion Models Beat GANs on Image Classification
    <u>https://arxiv.org/pdf/2307.08702.pdf</u>

#### Energy regression training

- Few shot training (around 20000 samples)
- 1 Linear layer for classification (+ Pooling for dimensional reduction)
- Use internal representation (after 1<sup>st</sup> DiT block)
- Fast adaptation

### PRELIMINARY



## **Conclusion and Future work**

#### Conclusion:

- Development and implementation of a generalizable model for physics simulation
  - · Combination of a diffusion model and transformers
  - Diffusion model used for sampling quality
  - Transformer architecture use as a generalized architecture
- Shown the ability of the model to do downstream task
  - Usage of the model for energy regression

#### Future work:

- · Understand what features of the model are used for downstream tasks
- Leverage this model to better model downstream tasks
- · Increase the quality of the model proposed



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