Accelerator & Technology Sector Beams Department Accelerator Beam Physics Group

Particle Accelerators and Beam Dynamics

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Disclaimer

Based on:

- Y. Papaphilippou : "Introduction to Accelerators"
- Summer student lectures:
	- B. Holzer, V. Kain, and M. Schaumann
- CERN accelerator school (CAS):
	- F. Tecker: "*Longitudinal beam dynamics"*
- Joint Universities Accelerator School (JUAS):
	- F. Antoniou, H. Bartosik and Y. Papaphilippou*: "Linear imperfections"* and *"nonlinear dynamics"*
- Books:
	- K. Wille: "*The Physics of Particle Accelerators"*
	- S.Y. Lee: *"Accelerator Physics"*
	- A. Wolski: *"Beam Dynamics in High Energy Particle Accelerators"*
	- H. Wiedemann: "Particle Accelerator Physics"

Images: cds.cern.ch

Overview

I. Introduction to Accelerators

- II. Accelerator beam dynamics
	- Transverse beam dynamics
		- Optics functions
		- Tune and resonances
	- Longitudinal beam dynamics
		- Acceleration
		- Synchrotron motion

Reminder – Synchrotron

The most common accelerator

- Fixed beam trajectory | magnetic field changes synchronous to the energy
- Magnets around the beam path to control the motion | **bending** (dipoles) & **focusing** (quadrupoles)
- Electric fields used to **accelerate** (RF cavity) the beam

How do particles move under the influence of these elements?

→ Transverse & Longitudinal Beam Dynamics

Charges in electromagnetic fields

Maxwell's equations for electromagnetism

$$
\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}
$$

Gauss law for electricity

electric field diverges from electric charges

$$
\nabla \times {\bf E} = - \frac{\partial}{\partial t} {\bf B}
$$

Faraday's law of induction

changing magnetic fields produce electric fields

 $\nabla \cdot \mathbf{B} = 0$

Gauss law for magnetism no isolated magnetic poles

$$
\nabla \times \mathbf{B} = \mu_0 \mathbf{j} + \frac{1}{c^2} \frac{\partial}{\partial t} \mathbf{E}
$$

Ampere-Maxwell law

changing electric fields and currents produce circulating magnetic fields

Lorentz force

• Force acting on **charged particles** moving under the influence of **electromagnetic fields**

$$
\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})
$$

• Kinetic energy (T) change is caused by the **electric field** – *acceleration*

$$
\frac{dT}{dt} = \mathbf{v} \cdot \mathbf{F} = q\mathbf{v} \cdot (\mathbf{E} + \mathbf{v} \times \mathbf{B}) = q\mathbf{v} \cdot \mathbf{E}
$$

• **Horizontal component** of the Lorentz force (particle moving on the longitudinal plane $\mathbf{F_x} = q(E_x - v_z B_y)$

• For high energy (relativistic limit):
$$
v_z \approx c
$$
 & $v_z B_y >> E_x (1 \text{ T corresponding to 300 MV/m)}$

→ **Magnetic fields** much more efficient for *steering*

Transverse motion – Field expansion

- In a synchrotron we want to study particles on the design orbit
- Magnetic fields are present all along s
- The magnetic field at the vicinity of the particle can be expanded as:

$$
\frac{e}{p}B_y(x) = \frac{e}{p}B_{y0} + \frac{e}{p}\frac{dB_y}{dx}x + \frac{1}{2!}\frac{e}{p}\frac{d^2B_y}{dx^2}x^2 + \frac{1}{3!}\frac{e}{p}\frac{d^3B_y}{dx^3}x^3 + \dots + \frac{1}{2!}\frac{1}{2!}mx^2 + \frac{1}{3!}px^3 + \frac{1}{3!}mx^2 + \frac{1}{3!}px^3 + \dots
$$

Transverse motion – Dipoles

In a circular accelerator of energy *E*, with *N* dipoles, each of length *L* 2π

• Bending angle:

$$
= \frac{N}{\frac{L}{a}}
$$

• Bending radius:

 ρ $\boldsymbol{\theta}$

- Dipole field: $B = 2\rho p / (qNl)$
- \rightarrow Choosing a dipole magnetic field: the length is determined (and vice versa)
- \rightarrow For higher fields, smaller and fewer dipoles can be used
- \rightarrow Ring circumference (cost) depends on field selection

7000 GeV Proton storage ring dipole magnets $N = 1232$ $l = 15$ m $q = +1$ e

 $\int B dl \approx N l B = 2\pi p/e$

$$
B \approx \frac{2\pi \ 7000 \ 10^9 eV}{1232 \ 15 \ m \ 3 \ 10^8 \ \frac{m}{s}} = \frac{8.3 \ Tesla}{e}
$$

03/06/2024
E. Asvesta | Introduction to Accelerators

Transverse motion – Dispersion

Reminder:

- From the RF cavities | **bunches formation**:
	- *The particles forming a bunch have a spread of momenta around the reference particle*
	- → *Off-momentum particles (Δp/p,* with respect to the reference*)*
- From the **beam rigidity** (& dipole field):
	- *The synchrotron has a constant radius if the field follows the momentum*
	- \rightarrow *Off-momentum particles:* $B(\rho + \Delta \rho) = \frac{P_0 + \Delta P}{q} \Rightarrow \frac{\Delta \rho}{\rho} = \frac{\Delta P}{P_0}$
- *The off-momentum particles follow a different orbit than the reference!*
- → The different orbit when *Δp/p = 1* is called: *Dispersion*

Transverse motion – Quadrupoles

Transverse motion – FODO

Alternating gradient focusing:

- *Alternating focusing and defocusing lenses can have an overall focusing effect*
- Combination of lenses with focal lengths, f_1 and f_2 in a distance *d* gives a focal length:

$$
\frac{1}{f} = \frac{1}{f_1} + \frac{1}{f_2} - \frac{d}{f_1 f_2}
$$

• if $f_1 = -f_2$, we get an overall focusing effect: $\frac{1}{f} = |\frac{d}{f_1 f_2}|$

FODO structure

- *"Cell" of alternating focusing and defocusing elements (along with drifts, dipoles etc)*
- Structure repeats itself giving a strong periodicity in the ring

Transverse motion – FODO

position *s and K_{x,y}*($s+L$) = $K_{x,y}$ (s) periodic functions, where *L* is the periodicity

➢Solutions describe a quasi harmonic oscillation, where **amplitude**, **phase** (and **dispersion**) depend on the position s in the ring

$$
y(s) = \sqrt{\varepsilon_y \beta_y(s)} \cos(\varphi_y(s))
$$

$$
x(s) = \sqrt{\varepsilon_x \beta_x(s)} \cos(\varphi_x(s)) + \varphi(s) \frac{\Delta p}{p}
$$

Transverse motion – betatron oscillations

- Particles perform **oscillations** (**betatron**) around the **design orbit**
- The motion is bound from the **envelope** $(\sqrt{\varepsilon_y \beta_y(s)})$,
	- $\beta_{\gamma}(s)$: **beta function** characteristic of the ring
	- ϵ_{v} : **emittance** is a **constant** of the motion (Liouville's theorem: the area is preserved)
		- It defines an **ellipse in the phase space** (Courant-Snyder invariant)

 $\varepsilon_y = \gamma_y(s)y^2(s) + 2\alpha_y(s)y'(s)y(s) + 2\beta_y(s)y'^2(s),$ α,β,y: optics functions

- It cannot be changed by the optics functions
- The envelope gives the **beam size** of a particle ensemble
- # of oscillations per turn, **tune:**

$$
Q = \frac{1}{2\pi} \int \frac{ds}{\beta(s)}
$$

Resonances

The tunes in the respective planes: (Q_x, Q_y)

Define resonance conditions described by: $mQ_x + nQ_y = l$,

- where m,n,l integers
- $m|+|n|$ the resonance order
- If the above condition is satisfied:
	- *Particle losses*
	- *Emittance increase*

Magnetic Field Component

Machine Periodicity

Machine Periodicity

Transverse motion – betatron resonances

Under normal conditions the emittance is preserved turn after turn:

• Observing the phase space turn-by-turn we get the emittance ellipse

Mitigation measures:

- **1. Careful tune choice – avoid resonance condition**
- **2. Higher order elements – corrections to cancel the effect of the resonance**

In the presence of a strong **resonance:**

- Emittance of a particle on the **1st turn**
- Emittance increases on the **2nd turn**
- Emittance increases further on the **3rd turn** *Emittance (and amplitude) will keep increasing until the particle is lost*

Transverse motion – phase space

Longitudinal motion - Acceleration

Reminder:

- Acceleration in a synchrotron is achieved in the **RF cavities**, using a voltage V
- During operations, we have a **synchronous RF phase** for which the **energy gain** fits the **increase of the magnetic field** at each turn. → *condition for constant radius*

• Energy gain per turn:

 $qV\sin\phi = qV\sin\omega_{RF}t$

• synchronous phase:

 $\phi = \phi_s = const$

• RF synchronism - frequency must be on the revolution frequency (1 turn around the

$$
\omega_{RF}=\hskip-7pt\bigwedge_{rev}
$$

ring): *h (*integer): **harmonic number**

- number of RF cycles per revolution
- ➢ *Defines the maximum number of bunches in the synchrotron (available RF buckets)*

Longitudinal motion – f_{RF} and ϕ_s change

During acceleration "*ramping"* energy & the magnetic field are changing:

- The revolution frequency changes: $\omega(B, R_s)$
- From the synchronism condition RF frequency needs to follow (using $p(t) = eB(t)$, $E^2 = (m_0c^2)^2 + p^2c^2$): $^{2})^{2}+p$ 2 *c* $p(t) = eB(t)\Gamma$, $E^2 = (m_0c^2)^2 + p^2c^2$

Can be omitted at the relativistic limit where $B \gg m_0 c$ 2 /(*ec*^r)

> $\overline{}$ $\overline{}$

 $\phi_s = \arcsin \left(2\pi \rho R \right)$

=

 \setminus

s \overrightarrow{v} \overrightarrow{v} \overrightarrow{v}

$$
\frac{f_{RF}(t)}{h} = \frac{v(t)}{2\rho R_s} = \frac{1}{2\rho} \frac{ec^2}{E_s(t)} \frac{r}{R_s} B(t) = \frac{c}{2\rho R_s} \frac{1}{\hat{l}} \frac{B(t)^2}{(m_s e^2/e c r)^2 + B(t)^2} \frac{\hat{u}^{\frac{1}{2}}}{\hat{l}}
$$

- Similarly, the phase, φ_{s} needs to follow
- From Bρ:

$$
(\Delta p)_{turn} = e \rho \dot{B} T_r = \frac{2 \pi e \rho R B}{v} \Rightarrow (DE)_{turn} = (DW)_s = 2 \rho e r R \dot{B} = e \hat{V} \sin F_s
$$

 $\bigg)$

 \int

RF

B

e

 R $\overline{}$

Longitudinal motion – Dispersion effects

Reminder:

Off-momentum particles follow a different orbit than the design: *Dispersion*

• The *orbit length* is different – the *momentum compaction factor* shows the variation of the orbit length with respect to the variation of the momentum:

$$
\alpha_c = \frac{dR}{dp/p}
$$

• From different momentum, different velocity & different path: different time (& revolution frequency) to arrive to the RF cavity – *slip factor*, variation of the revolution frequency with respect to the variation of the momentum:

$$
h = \frac{df_r}{dp} \frac{f_r}{p}
$$

Longitudinal motion – Dispersion effects

• The revolution frequency change depends both on the **orbit** and **velocity** change:

$$
\frac{df_r}{f_r} = \frac{d\beta}{\beta} - \frac{dR}{R} = \frac{d\beta}{\beta} - \alpha \frac{dp}{p}
$$
\n• For $\frac{d\beta}{\beta}$: $p = mv = bg\frac{E_0}{c}$ \Rightarrow $\frac{dp}{p} = \frac{db}{b} + \frac{d(1-b^2)^{-1/2}}{(1-b^2)^{-1/2}} = (1-b^2)^{-1} \frac{db}{b}$

• Finally, we get the relation between momentum compaction and slip factor:

• The energy in which $\eta = 0$, is called *transition energy*:

$$
\gamma_t = \frac{1}{\sqrt{\alpha_c}}
$$

 \triangleright **Below** γ_t **(η>0)** the arrival at the cavity depends on the **velocity** ➢**At (η=0)** the velocity change and the path length change **compensate each other** \triangleright Above γ_t (η <0) the arrival at the cavity depends only on the path length **()** $p = mv = bg \frac{dv}{dt} + \frac{dv}{dt} = \frac{hc}{dt} + \frac{dv}{dt} = \frac{hc}{dt} + \frac{hc}{dt}$
 (n - b²)^{-1/2} = $\frac{1}{g^2}$
 (n - b) is called **transition energy**: $\gamma_t = \frac{1}{\sqrt{\alpha_c}}$
 (n - **0**) the arrival at the cavity depends on the **velo**

 $\eta =$

1

 $\frac{1}{2} - \alpha_c$

 γ

Longitudinal motion – Phase stability

Reminder:

- Phase focusing: bunches are formed as particles arriving at the cavity before or after the synchronous particle are "brought closer" to it
- This stands for $\varphi_s < \pi/2$ as:

Longitudinal motion – Phase stability

Since:

- **Below (η>0)** the arrival at the cavity depends on the **velocity**
- Above γ_t (η<0) the arrival at the cavity depends *only* on the path length
- ➢ **The behaviour for the phase stability is reversed around transition crossing**

Longitudinal motion – Transition crossing

• Change of stable phase implies:

• *Crossing transition during acceleration makes the previous stable synchronous phase unstable.*

- ➢ The RF system needs to make a rapid change of the RF phase, a "phase jump".
- *Such a manipulation is needed at the CERN PS*

Longitudinal motion – Synchrotron oscillations

Operating below transition & at constant energy (and B)

- Synchronous phase $\phi_0=0$
- Particle with a $\phi > \phi_0$: particle gets accelerated and moves towards ϕ_0
- Particle with a $\phi < \phi_0$: particle gets decelerated and moves towards ϕ_0

➢*Particles will start performing oscillations around the synchronous particle*

Longitudinal motion – Phase space

Takeaways

Transverse motion

- The beam moves in *FODO structure*
- Particles perform oscillations around the design orbit called *betatron*
- Turn-by-turn the ellipse formed in the phase space is called *emittance*
- The number of betatron oscillations in 1 turn is called **tune**
- Emittance remains **constant** for "normal" conditions
- In the presence of *resonances* in the tune space, the emittance increases
- The *beam size* is defined as $\sqrt{\varepsilon_{\nu}\beta_{\nu}(s)}$

Longitudinal motion

- **Synchronism:** RF frequency needs to be locked to revolution frequency
- During acceleration the *phase and frequency* need to adjust to the *energy & B increase*
- Path length changes with momentum *momentum compaction factor*
- Frequency changes with momentum *slip factor*
- Phase stability depends on *transition energy*
- **Phase jump** to cross transition
- Particles perform oscillations around ϕ_s called *synchrotron*