



Full event particle-level unfolding

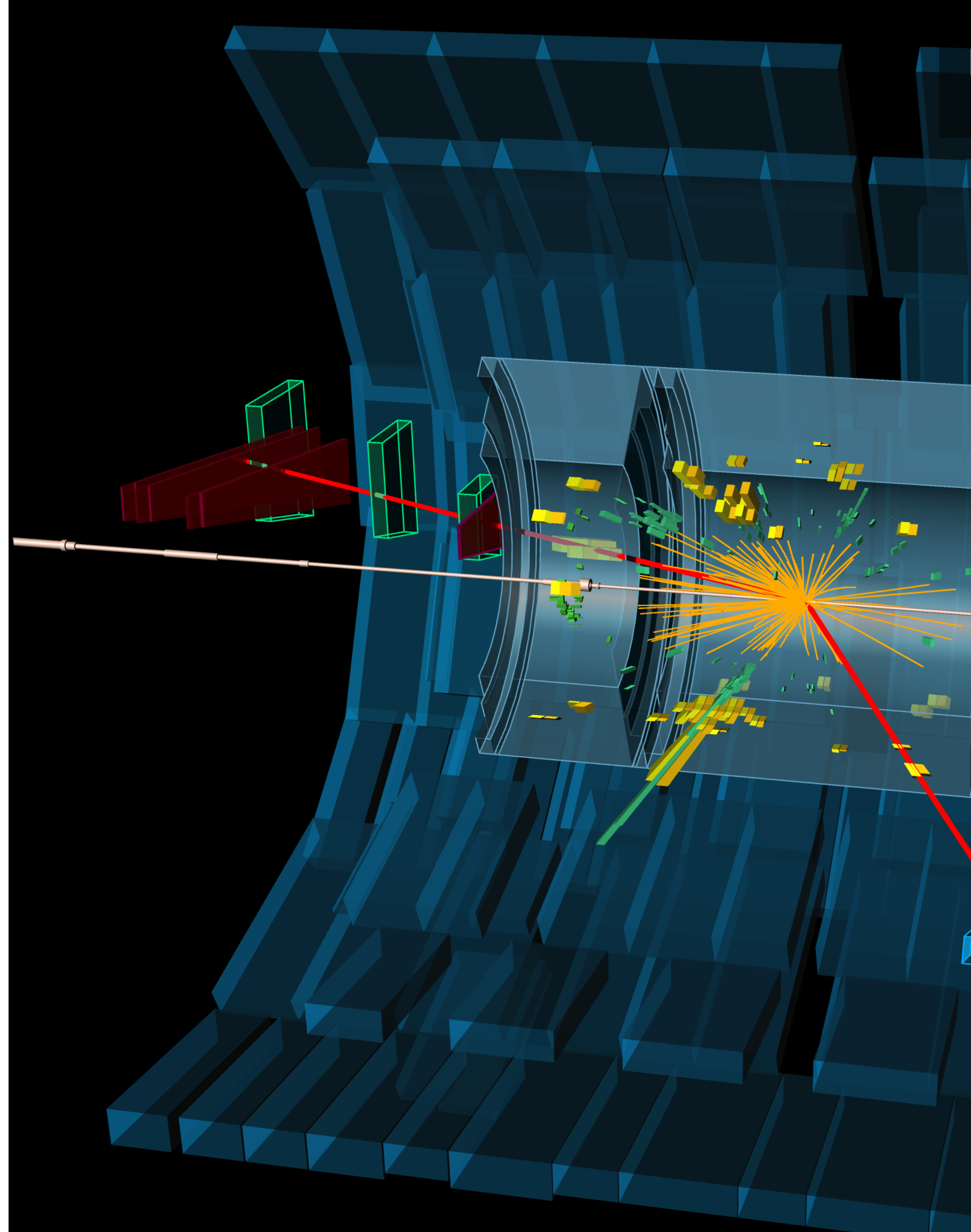
with variable length variational latent diffusion (VL-VLD)

Alexander Shmakov, Kevin Greif, Michael Fenton, Aishik Ghosh, Pierre Baldi, Daniel Whiteson

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LPNHE

Why variable dimensions?

- Most unfolding at the LHC targets **particle-level**
 - Phase space is inherently variable dimensional
- No existing generative method for unfolding variable dimensions
- Necessary for **full-event** unfolding at particle level



Latest generative model: diffusion

Diffusion model: a class of generative model which samples from a high-variance “base” distribution, and iteratively de-noises the sample

- **Forward / noising process**

- Sample data $p(\mathbf{x}_0)$ → turn to noise



- **Reverse / denoising process**

- Sample noise $p_T(\mathbf{x}_T)$ → turn into data

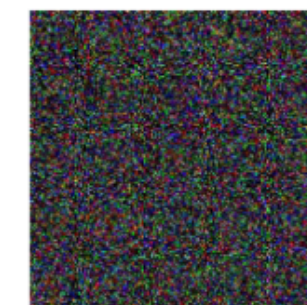
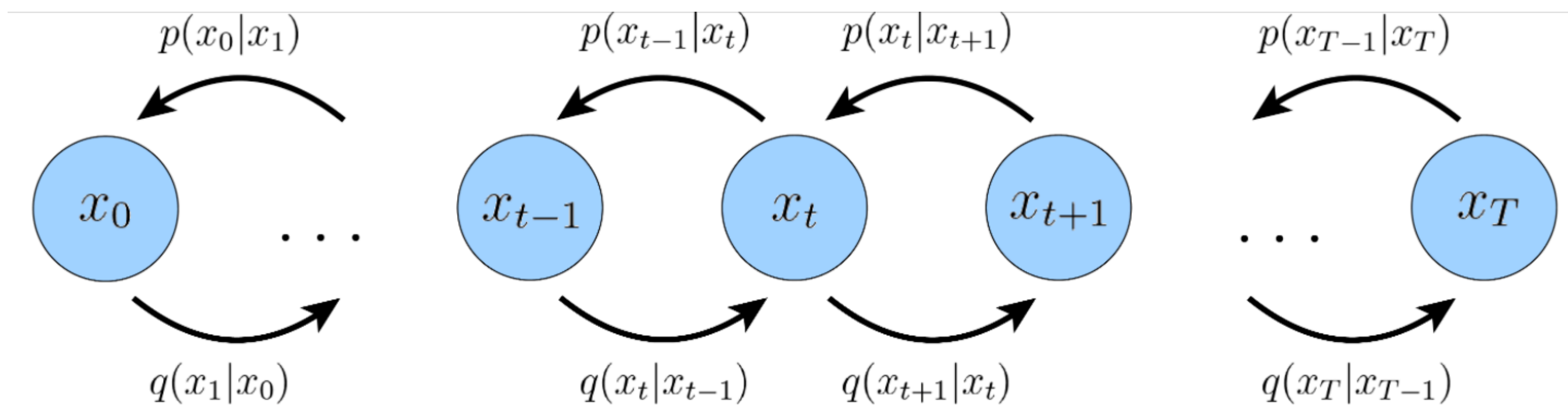
[Credit: Binxu Wang](#)

Elements of latent variational diffusion

Latent diffusion model ([2112.10752](#)): perform the diffusion process in the latent space of a pre-trained variational autoencoder (VAE)

$$x \rightarrow z \sim VAE(x)$$

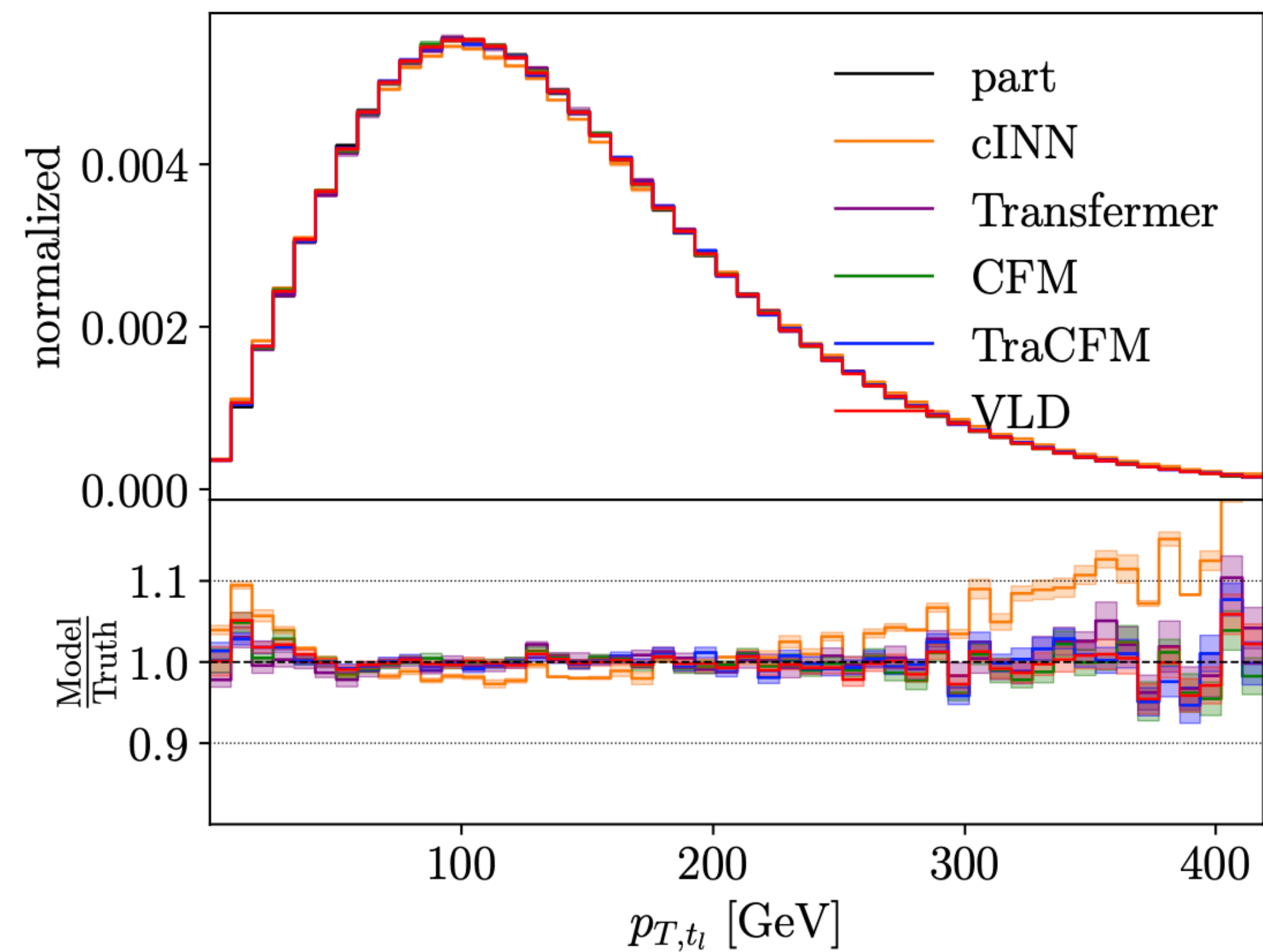
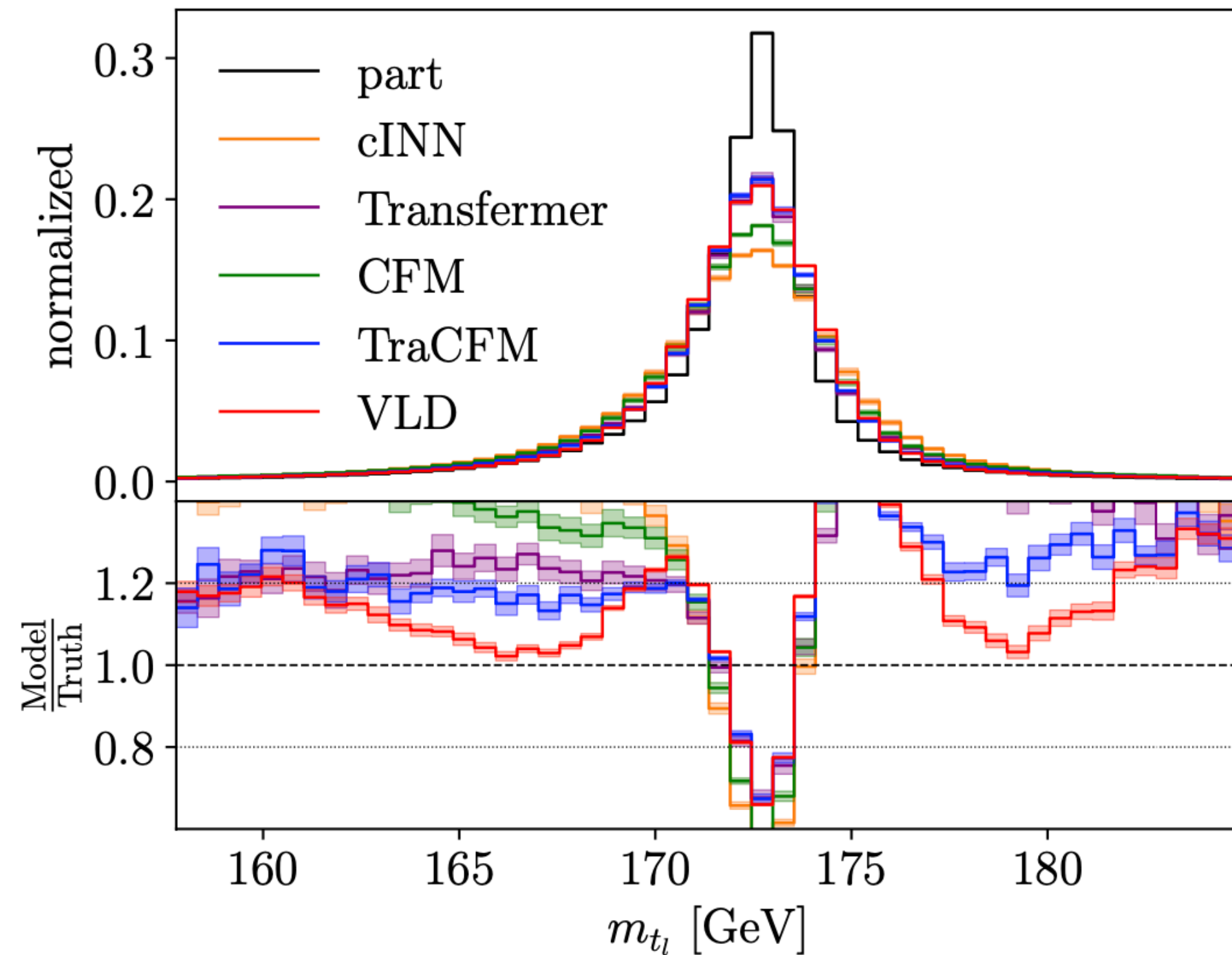
Variational diffusion model ([2107.00630](#)): interpretation of the diffusion model as an (infinitely deep) chain of VAEs



[2208.11970](#)

On a parton level (fixed dimension) problem

- Base model tested on parton-level $t\bar{t}$ unfolding: fixed dimensions
- Results included in comparison paper [2404.18807](#)

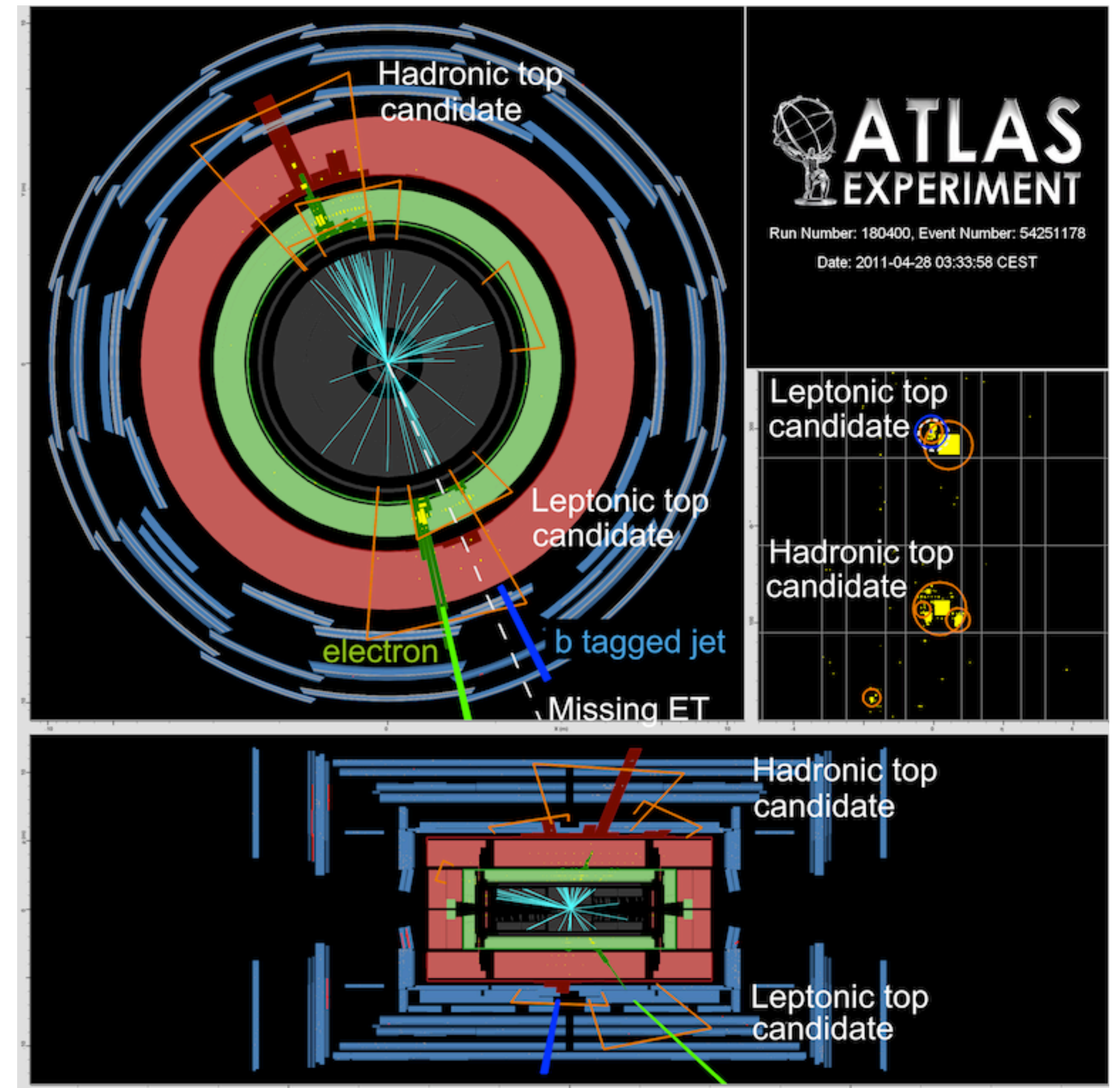


Results are shown without mass parametrization!

From partons to particles

Particle-level unfolding: invert only the detector response

- Targets are particle-level objects:
 - Can be light quark jets, b tagged jets, electrons, or muons
 - Also interested in E_T^{miss} , ϕ^{miss} , η^ν
- **Do not always have 5 objects!**



Variable length generative models

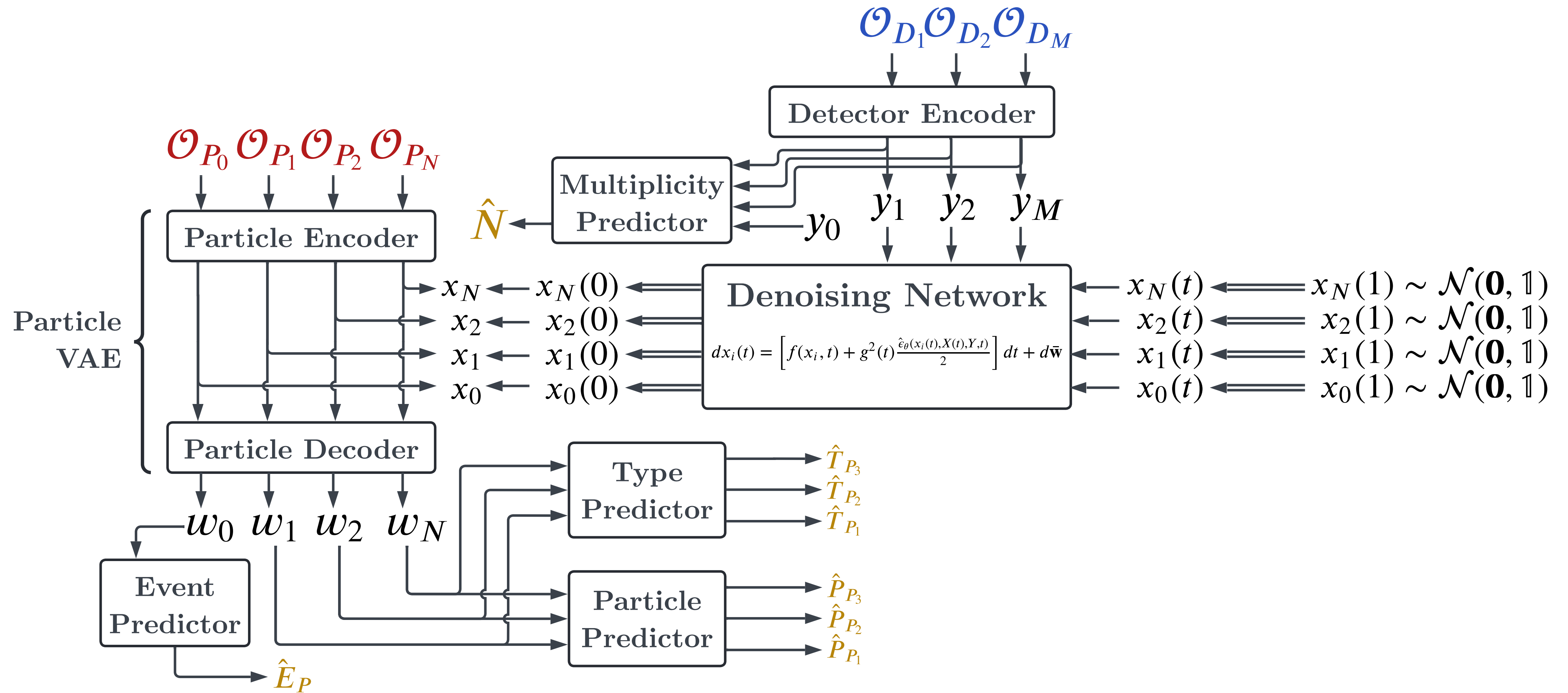
Autoregressive approach:

- Treat event as a sequence of objects, repeatedly run inference on model to generate sample object by object
- Output a special stop token to finish generating
- Approach used by ChatGPT, see [2305.10475](https://arxiv.org/abs/2305.10475) for a HEP example

Multiplicity predictor approach:

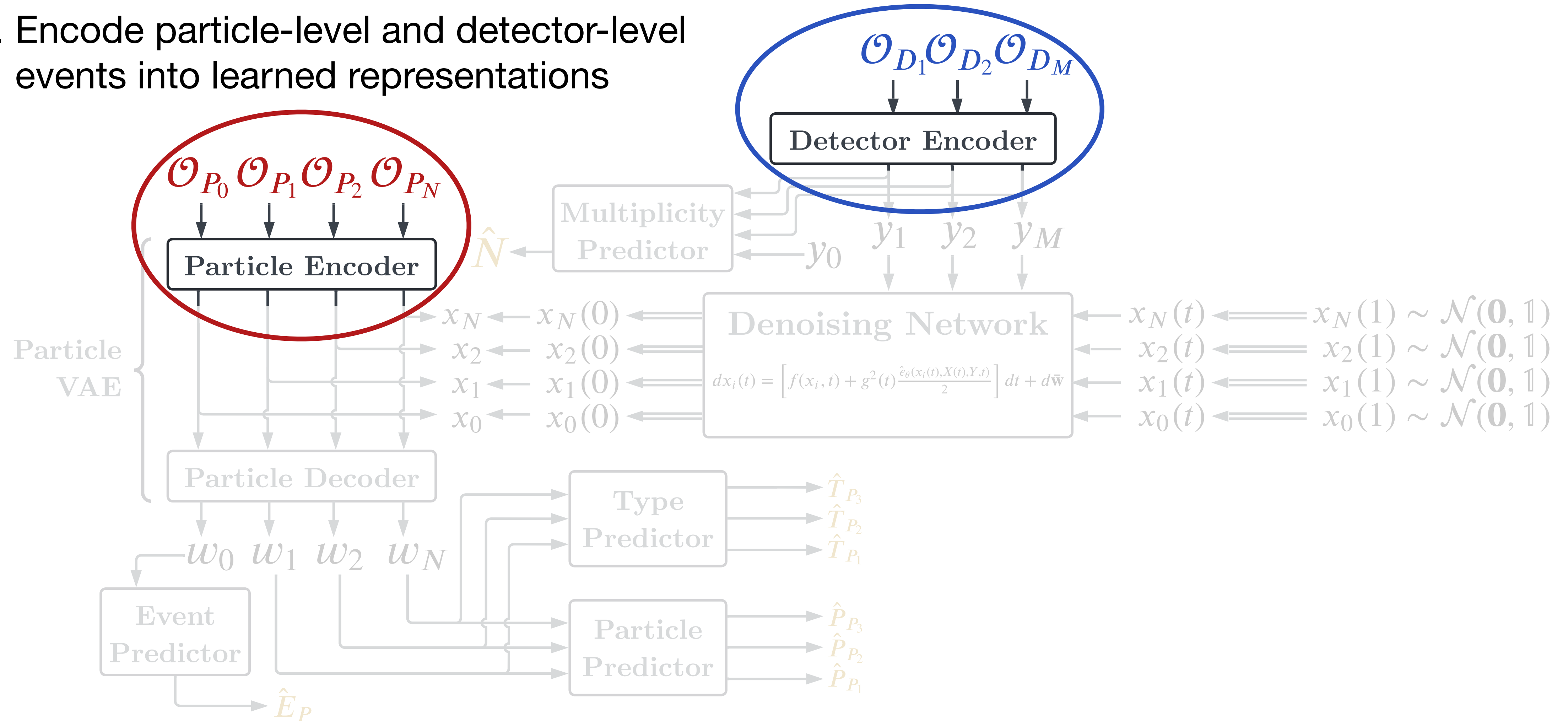
- Standard in HEP applications of point-cloud generative models (see backup)
- Use auxiliary network to predict particle multiplicity
- Generation is conditioned on the output of this model
- We take $\hat{N} = [N]; N \sim \Gamma(MLP_k(y), MLP_\theta(y))$

Training variable length VLD (VL-VLD)

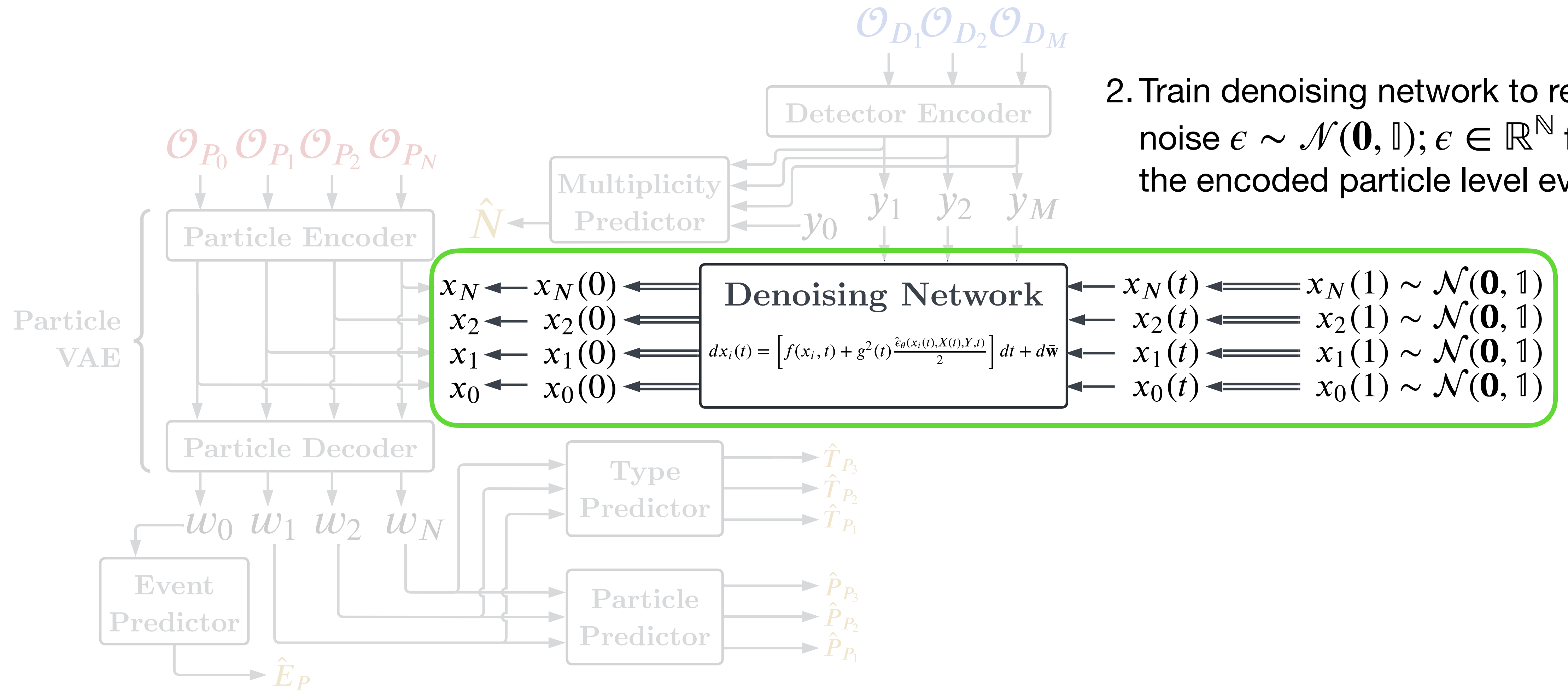


Training variable length VLD (VL-VLD)

1. Encode particle-level and detector-level events into learned representations

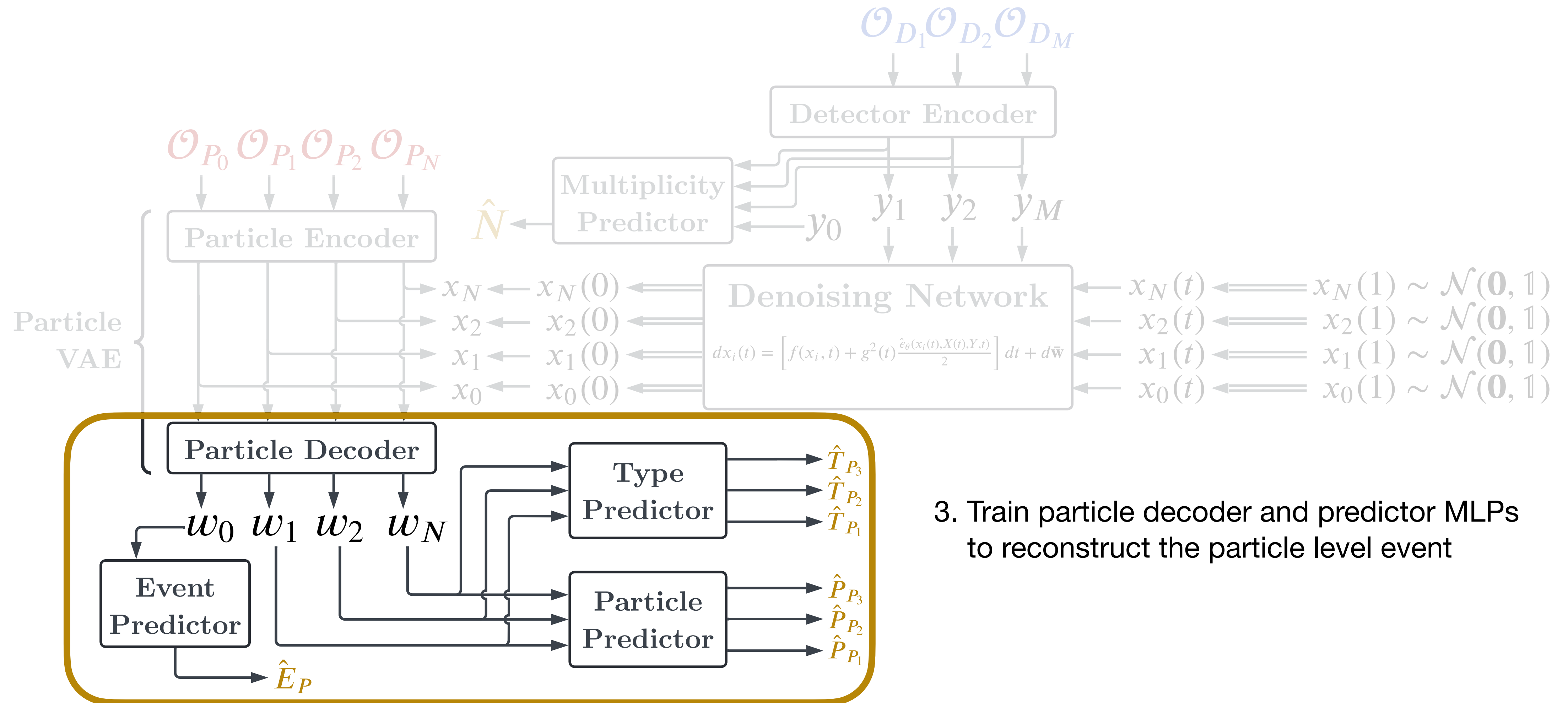


Training variable length VLD (VL-VLD)



2. Train denoising network to remove noise $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbb{I})$; $\epsilon \in \mathbb{R}^N$ from the encoded particle level event

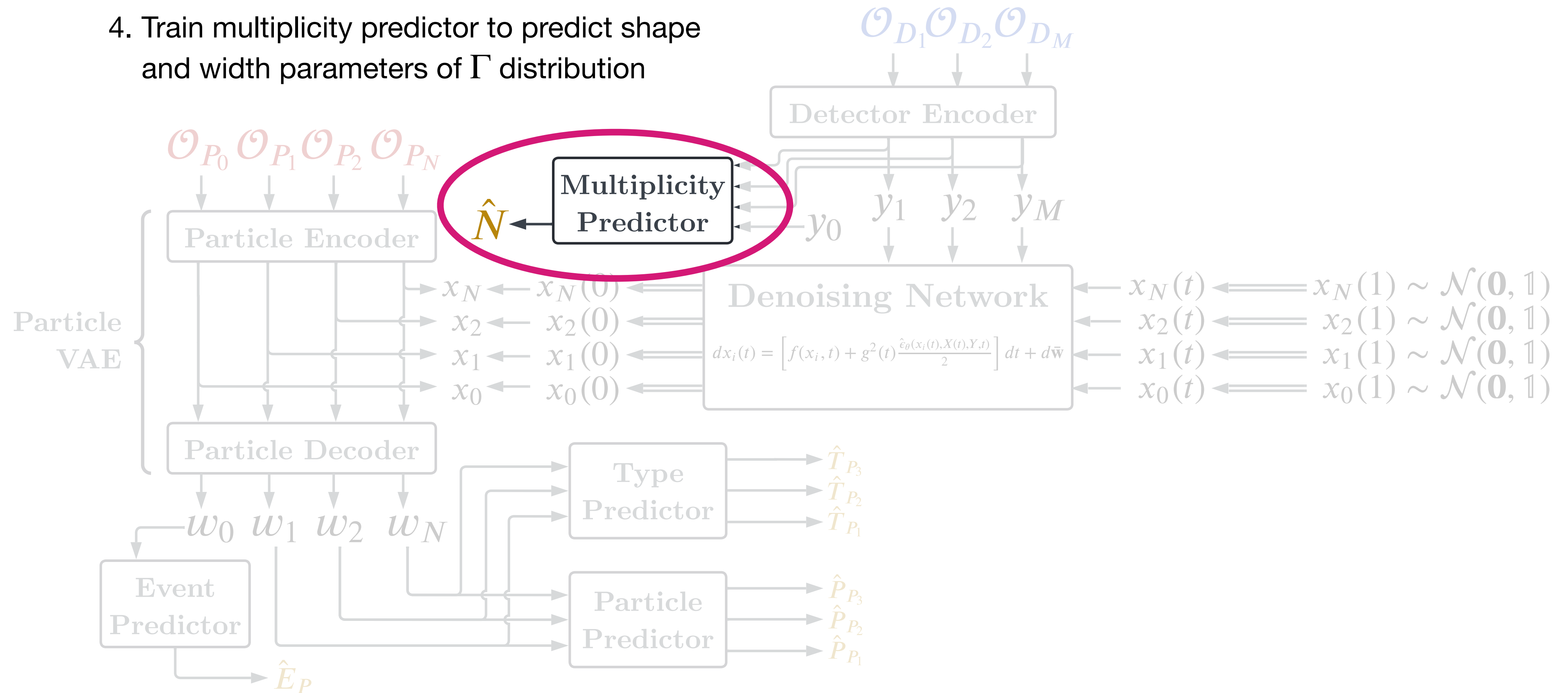
Training variable length VLD (VL-VLD)



3. Train particle decoder and predictor MLPs to reconstruct the particle level event

Training variable length VLD (VL-VLD)

4. Train multiplicity predictor to predict shape and width parameters of Γ distribution



VL-VLD loss function

All networks are trained simultaneously to minimize a unified loss function:

$$\begin{aligned} \mathcal{L} = & \sum_{i \in \{0,1,\dots,N\}} D_{KL}[q(x_i(1)|\mathcal{O}_P, \mathcal{O}_D) \parallel p(x_i(1))] && \text{PRIOR LOSS} \\ & + \sum_{i \in \{0,1,\dots,N\}} \mathbb{E}_{q(x_i(0)|\mathcal{O}_P)} [-\log p(\hat{\mathcal{O}}_P|x_i(0))] && \text{RECONSTRUCTION LOSS} \\ & + \sum_{i \in \{0,1,\dots,N\}} \mathbb{E}_{\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbb{I}), t \sim \mathcal{U}(0,1)} [\gamma'_\phi(t) \|\epsilon - \hat{\epsilon}_\theta(x_i(t), X(t), Y, t)\|_2^2] && \text{DENOISING LOSS} \\ & - \log p(\hat{N} = N | \mathcal{O}_D). && \text{MULTIPLICITY LOSS (12)} \end{aligned}$$

Transformer architectures ensure that network predictions are **position equivariant**

VL-VLD loss function

All networks are trained at once to minimize a unified loss function:

$$\begin{aligned} \mathcal{L} = & \sum_{i \in \{0,1,\dots,N\}} D_{KL}[q(x_i(1)|\mathcal{O}_P, \mathcal{O}_D) \parallel p(x_i(1))] && \text{PRIOR LOSS} \\ & + \sum_{i \in \{0,1,\dots,N\}} \mathbb{E}_{q(x_i(0)|\mathcal{O}_P)} [-\log p(\hat{\mathcal{O}}_P|x_i(0))] && \text{RECONSTRUCTION LOSS} \\ & + \sum_{i \in \{0,1,\dots,N\}} \mathbb{E}_{\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbb{I}), t \sim \mathcal{U}(0,1)} \left[\gamma'_\phi(t) \|\epsilon - \hat{\epsilon}_\theta(x_i(t), X(t), Y, t)\|_2^2 \right] && \text{DENOISING LOSS} \\ & - \log p(\hat{N} = N | \mathcal{O}_D). && \text{MULTIPLICITY LOSS (12)} \end{aligned}$$

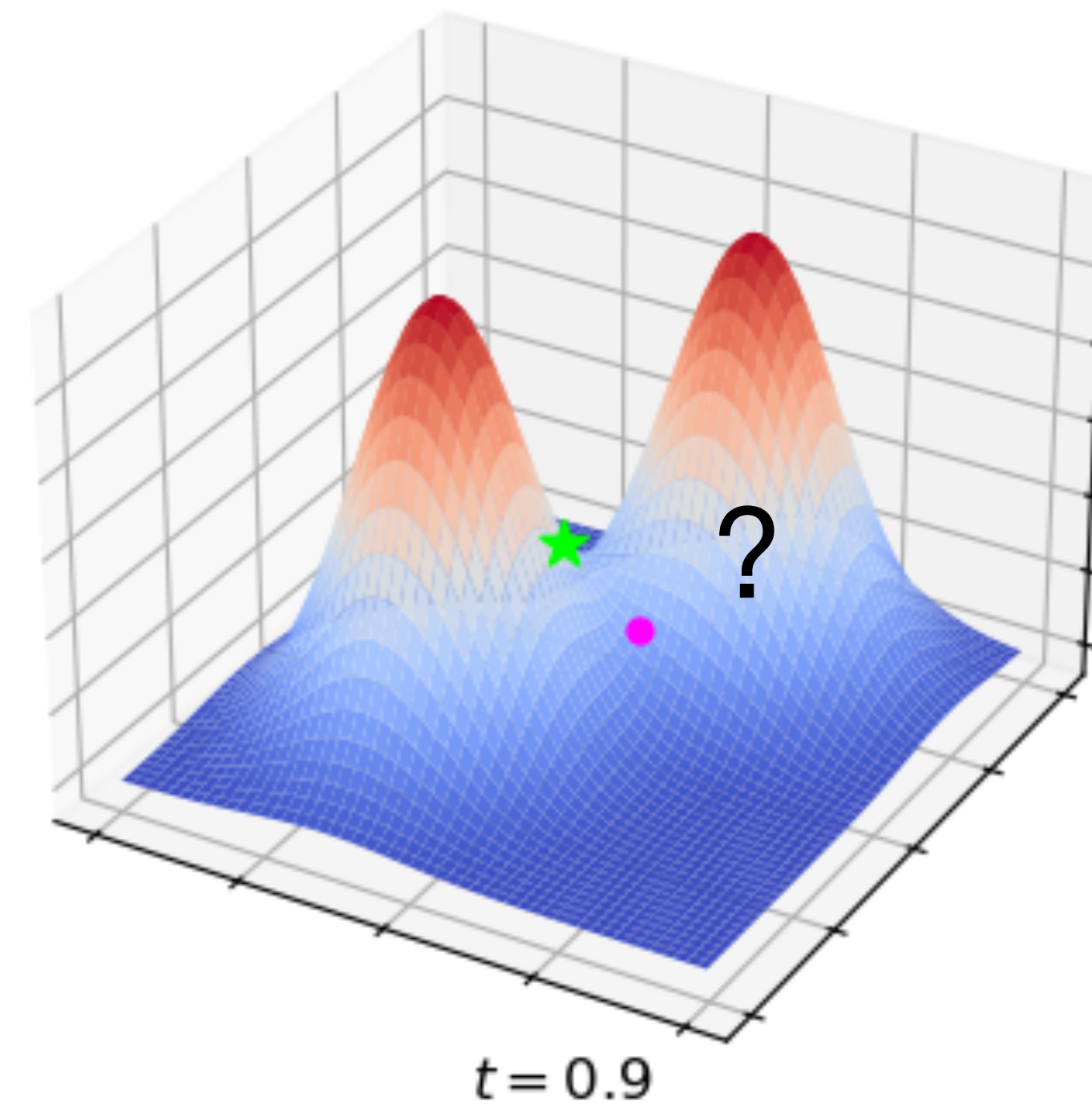
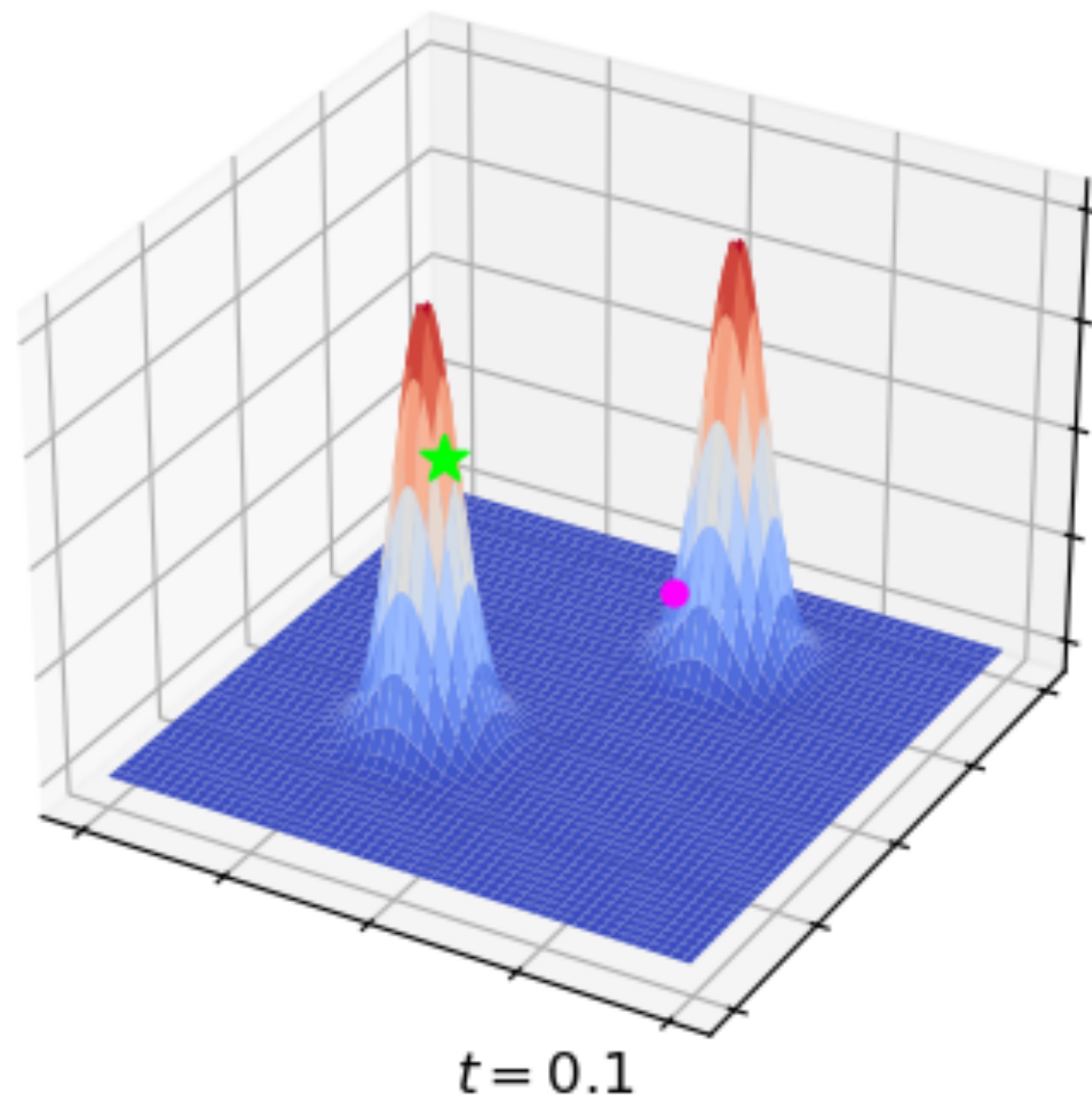
Transformer architectures ensure that network predictions are **position equivariant**

Except there's a problem with the denoising loss

Ambiguous loss function

$$\sum_{i \in \{0, 1, \dots, N\}} \mathbb{E}_{\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbb{I}), t \sim \mathcal{U}(0, 1)} \left[\gamma'_\phi(t) \|\epsilon - \hat{\epsilon}_\theta(x_i(t), X(t), Y, t)\|_2^2 \right]$$

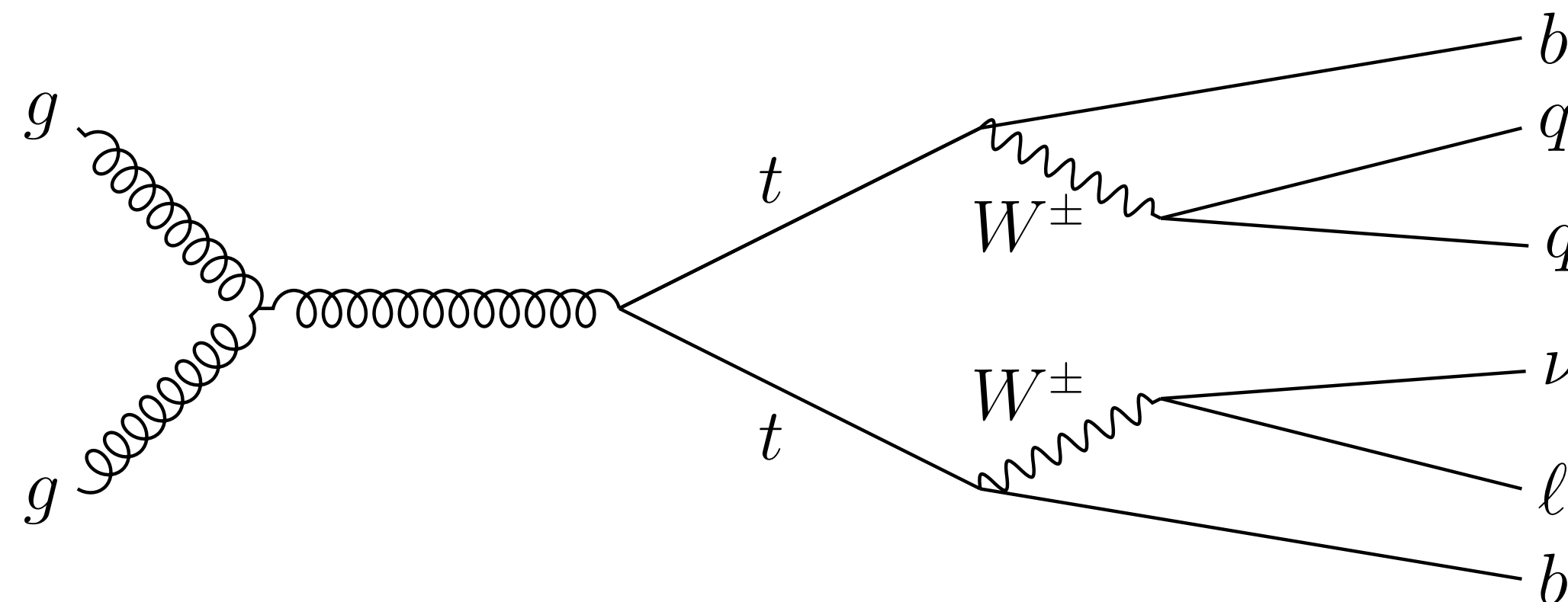
At high level of noise, the distinction between two objects can become ambiguous, making object-wise MSE loss undefined:



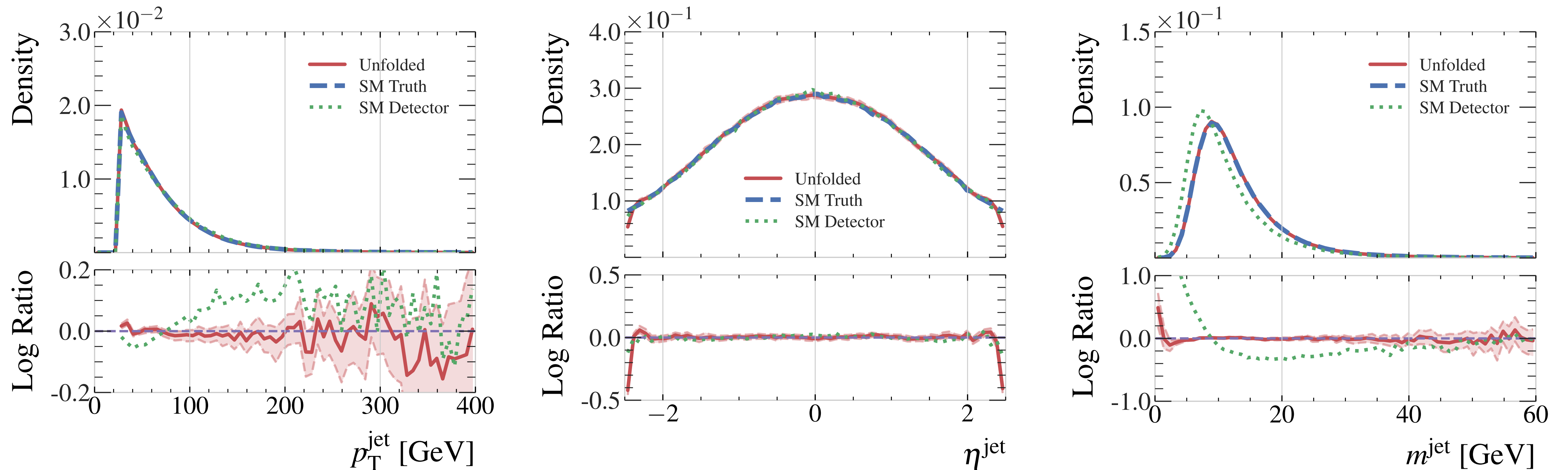
Solution: Impose ordering of objects by true particle-level p_T when training denoising network

Particle-level $t\bar{t}$ unfolding dataset

- Semi-leptonic decay mode: expect 2 light quark jets, 2 b jets, 1 lepton, MET
- Detector response simulated with Delphes
- **Identical detector and particle-level phase space requirements:**
 - Leptons and jets required to have $p_T > 25$ GeV, $|\eta| < 2.5$
 - Require 1 lepton and at least 4 jets (at least 2 b-tagged)
- Targets are object kinematics vectors: $P_i = (p_x, p_y, p_z, \log(E + 1), \log(M + 1))$
 - Also object type, encoded as one-hot vector
- Event-level targets: $E_T^{miss}, \phi^{miss}, p_x^\nu, p_y^\nu, p_z^\nu, E^\nu$

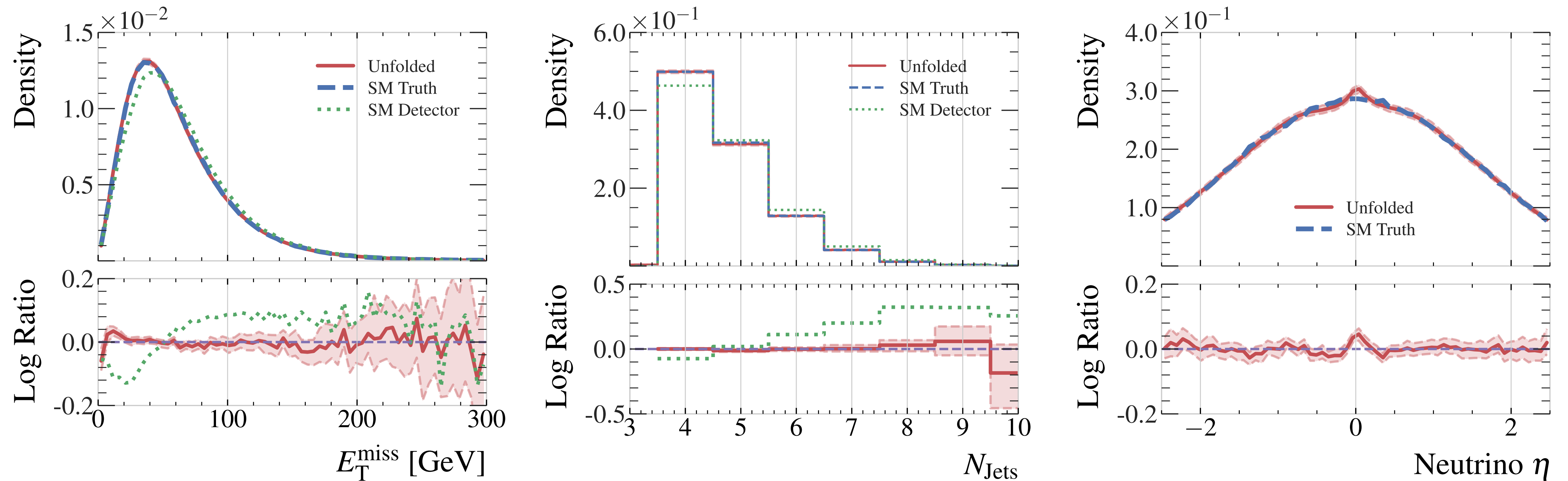


Inclusive kinematic distributions for jets



- Kinematics of the particle level objects close well: these are directly optimized
- Struggle in edges of phase space where we lack training examples of events migrating across phase space boundaries

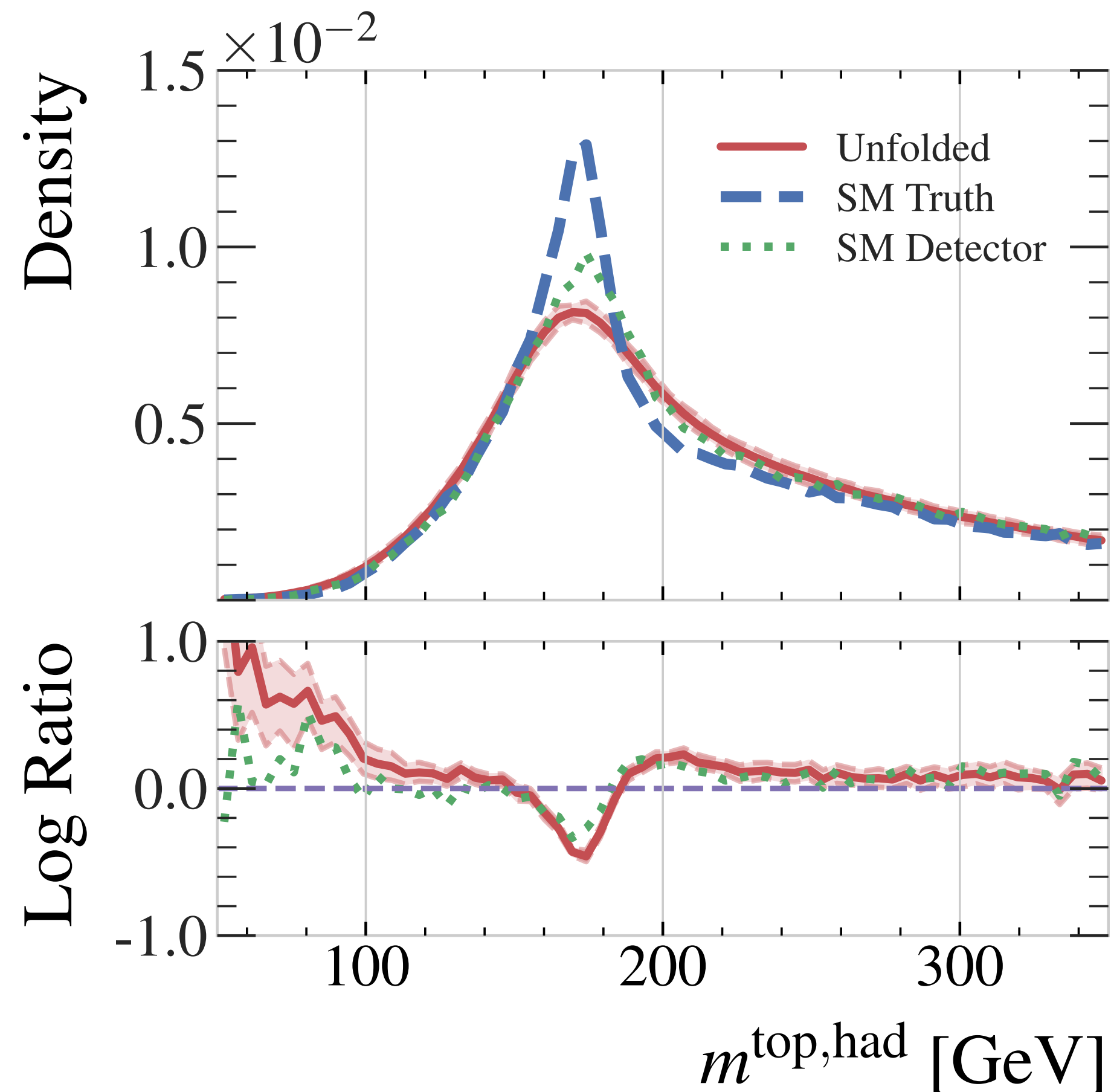
Event-level distributions



- Event-level features also close well
- Neutrino η is not constrained at detector-level, expect excess at 0 to result from model returning mean

Particle-level top quark distributions

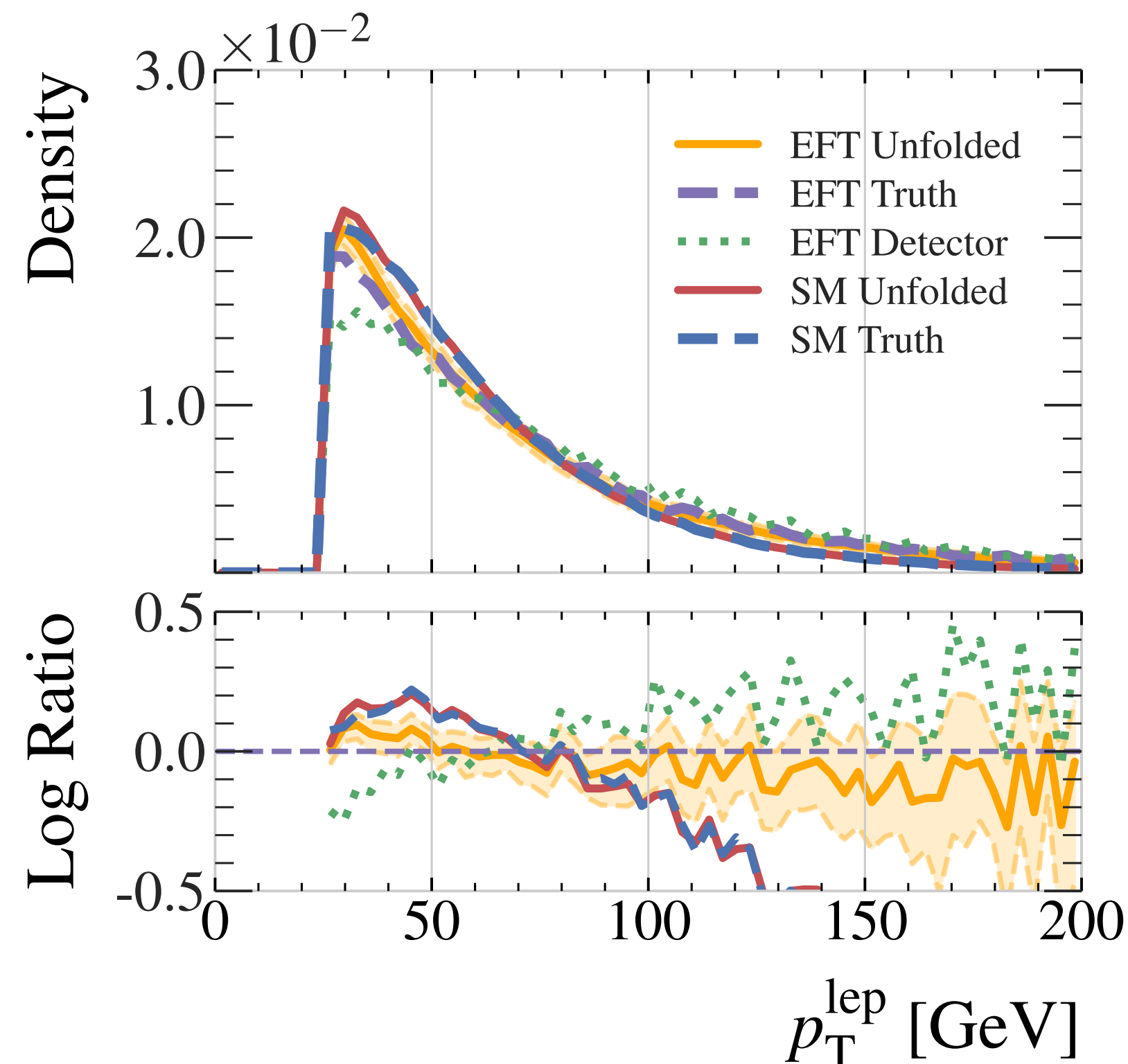
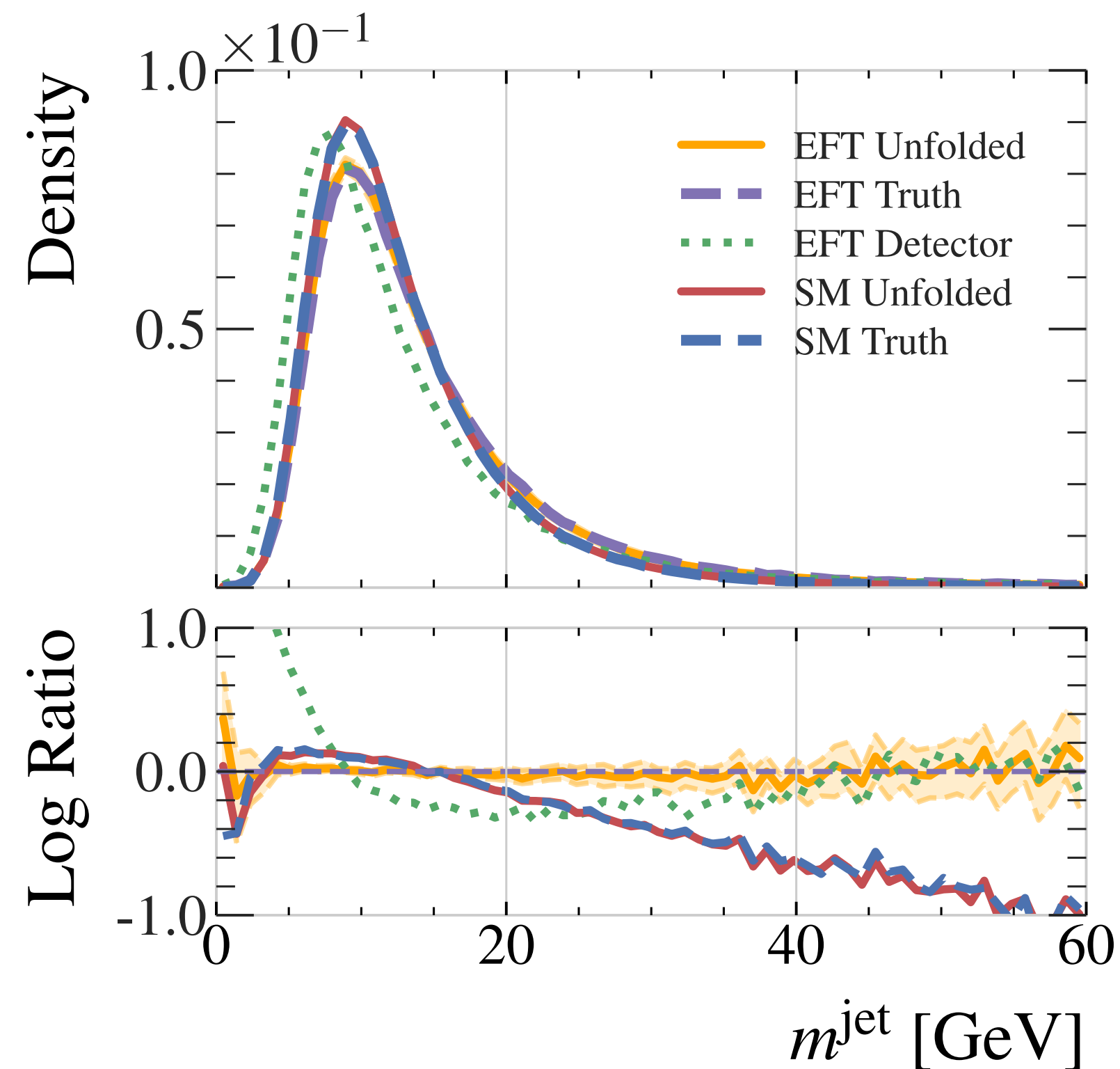
Assumes pseudotop jet/parton assignment (see backup)



- Top kinematics: not directly optimized
- Sharply peaked distributions difficult to model without direct optimization
- Why not optimize?
 - Requires assumption of a reconstruction algorithm in training
 - Further algorithm must be differentiable to optimize top kinematics calculated from particle-level objects

EFT operator prior shift

- Generative models can suffer from prior-dependence
- Test by evaluating model over dataset generated with non-zero EFT operator
 - $c_{tg} = 25$



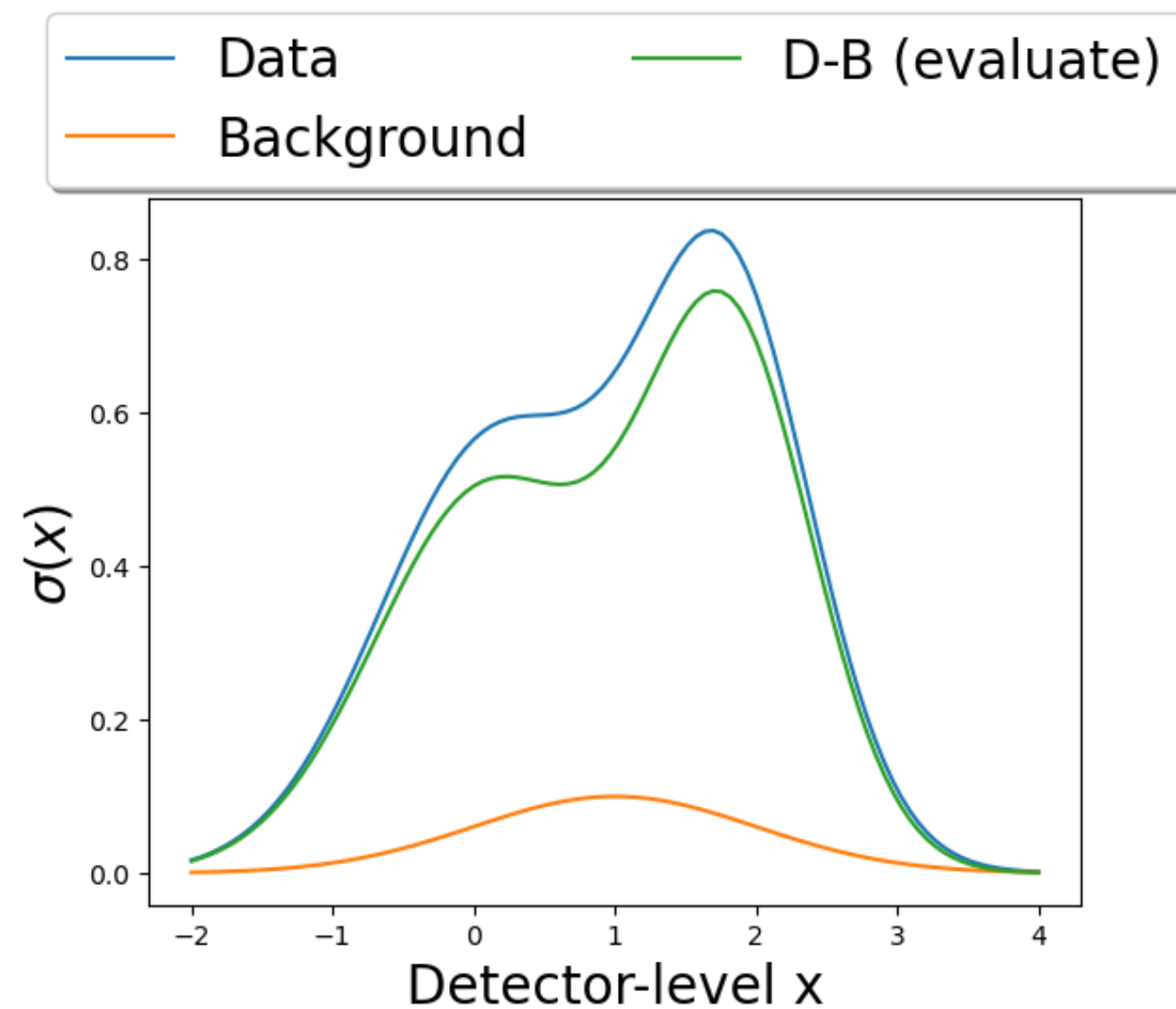
Clearly not just reproducing the SM distributions!

However iteration likely necessary in practice

Background subtraction

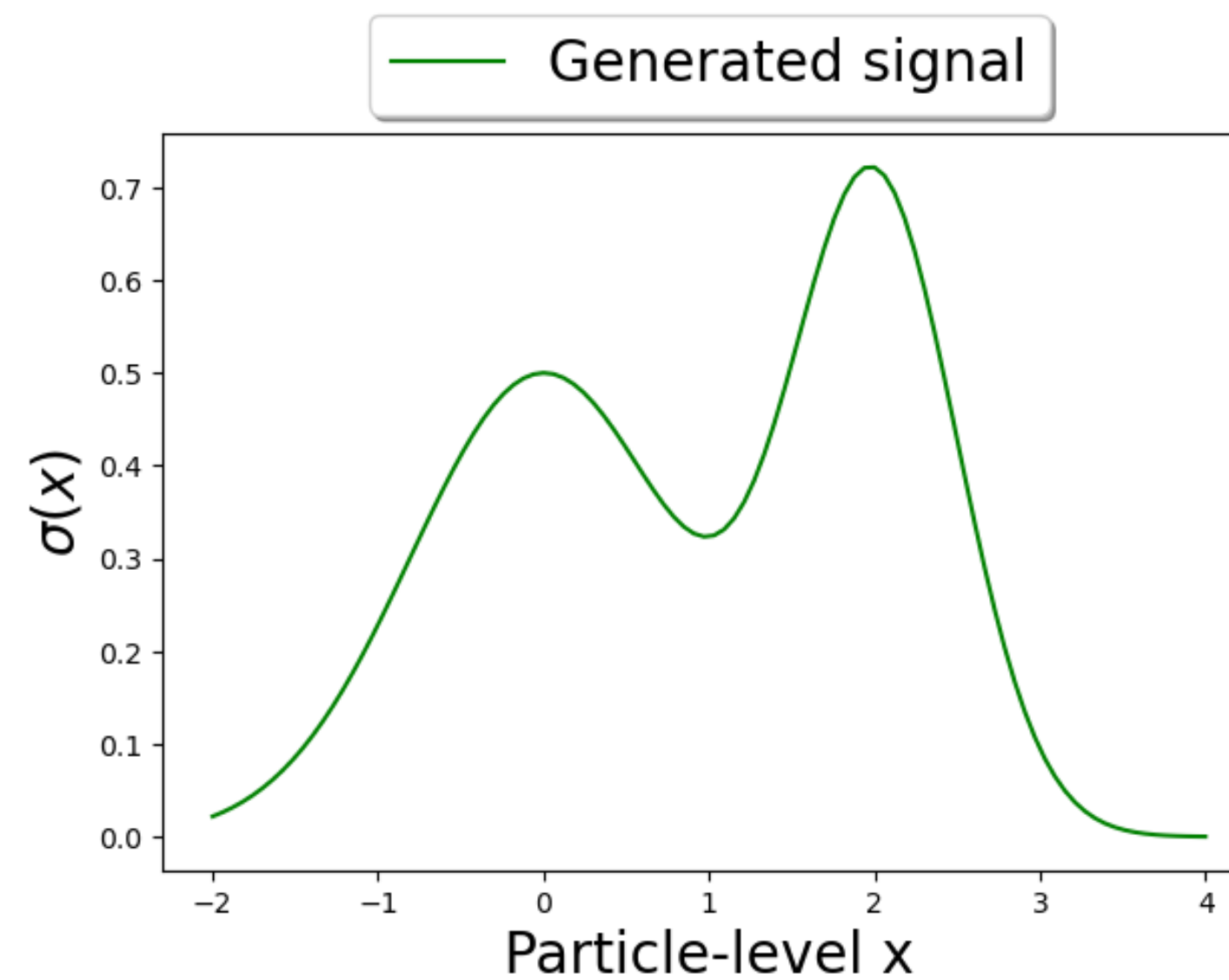
Before Unfolding

Perform un-binned subtraction of background, then run inference on generative model trained with only signal



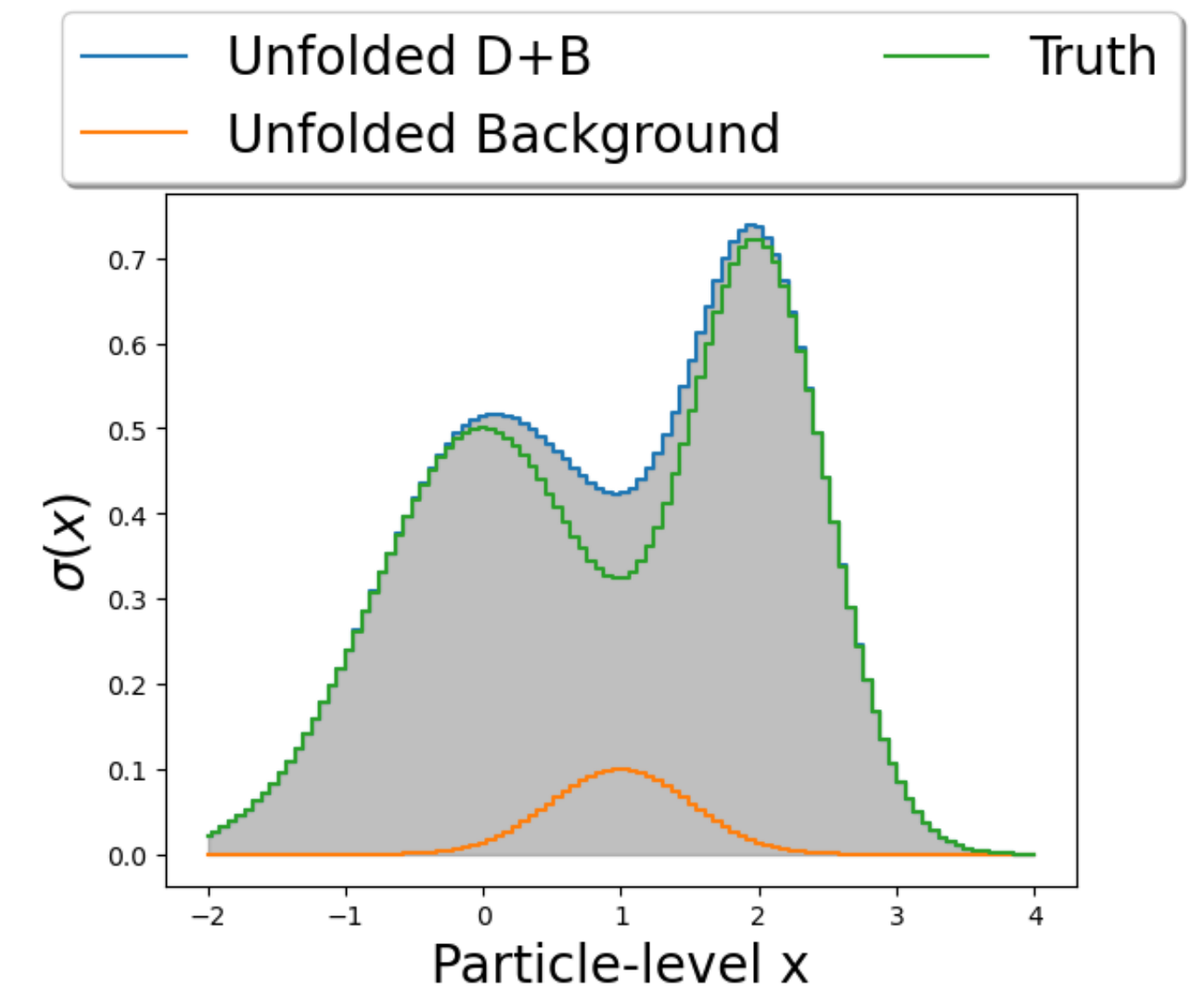
During Unfolding

Train generative model with negative weights for background events, then run inference on data

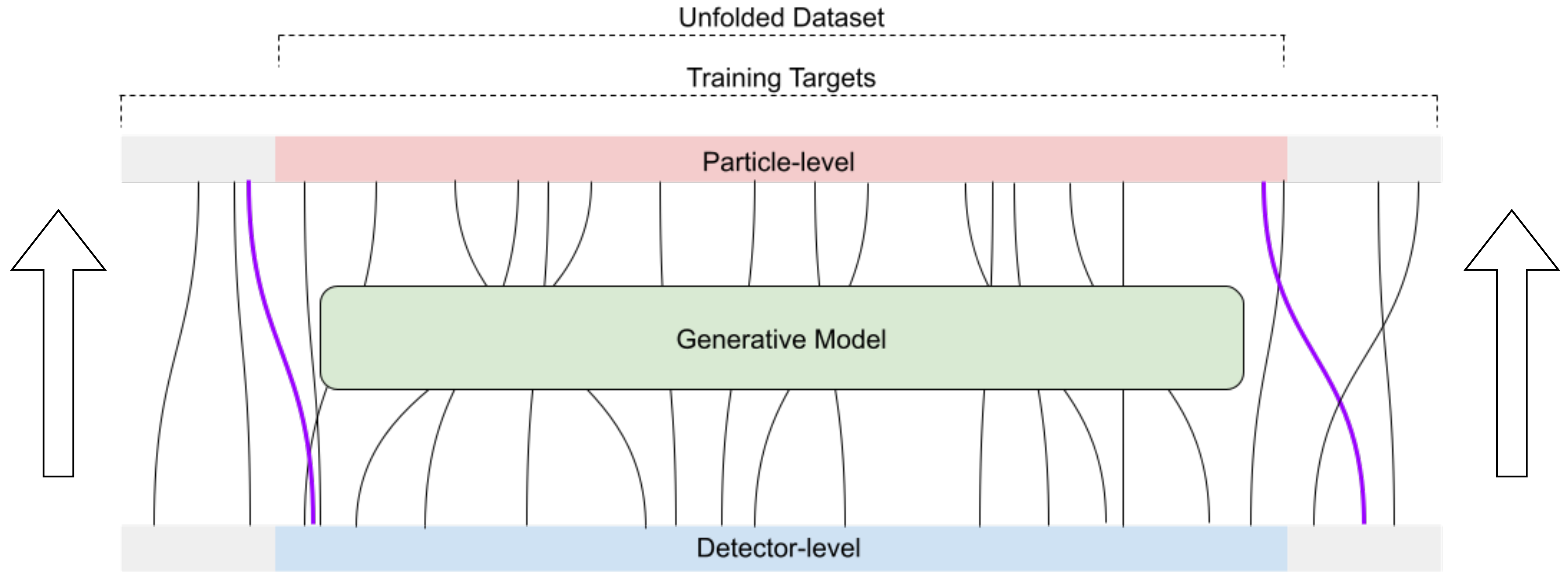


After Unfolding

Train to unfold S+B together, then run inference on data and perform binned subtraction after unfolding



Acceptance effects



Fakes:

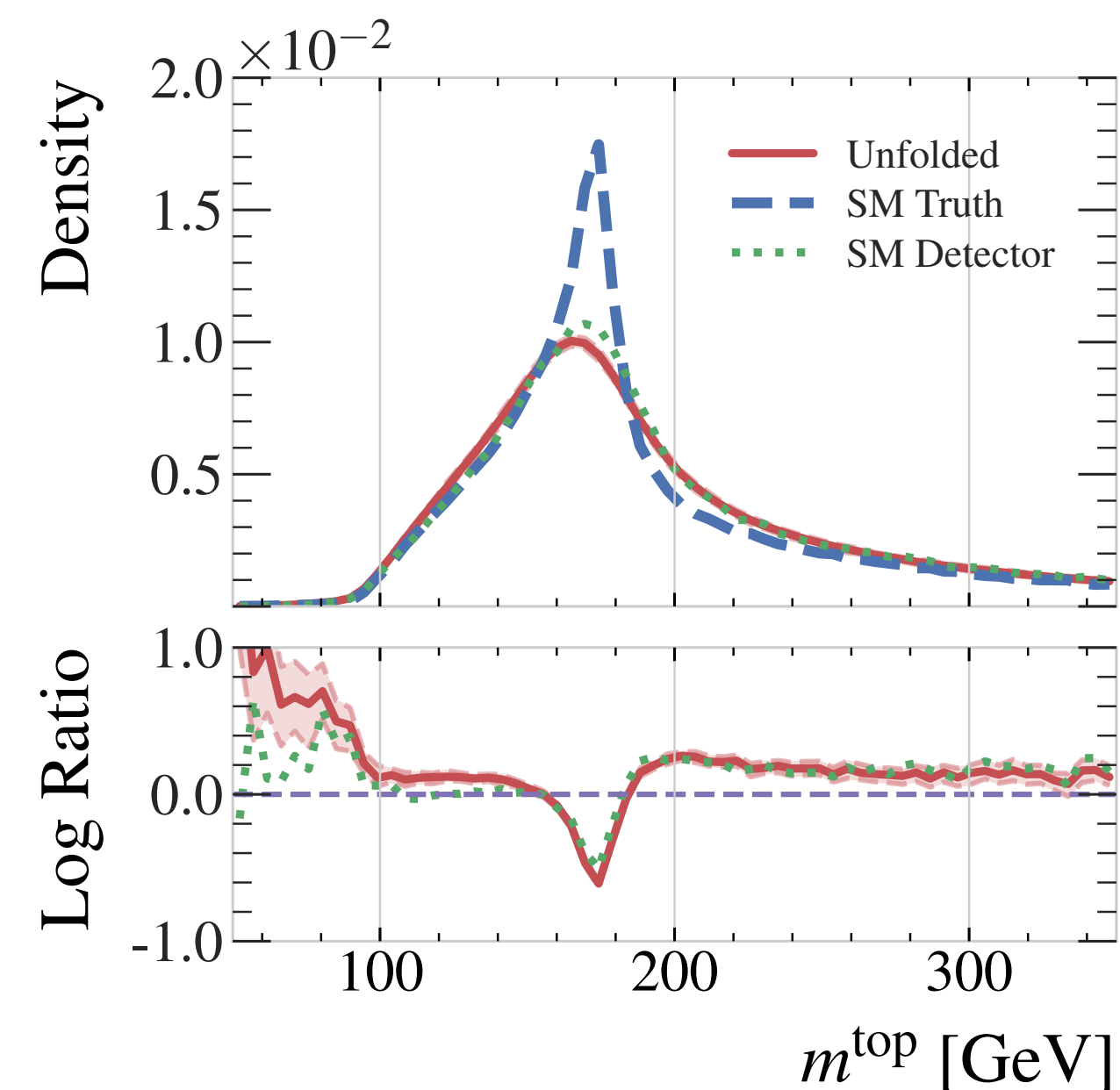
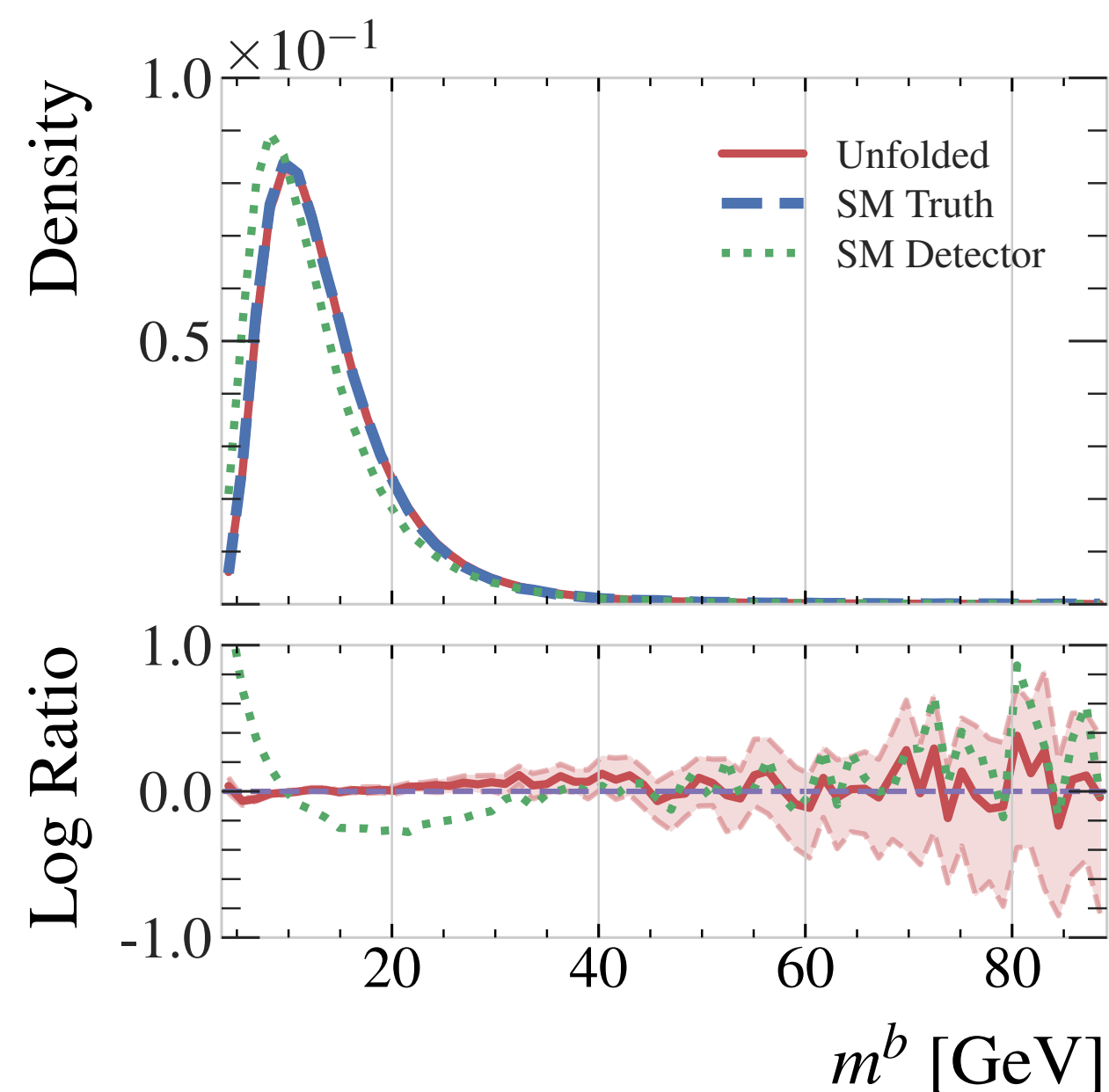
Train generative model on large phase space region then place cuts on particle-level phase space after evaluation

Inefficiencies:

Challenging, since have no event to condition generation. Engineer particle-level phase space to avoid inefficiencies?

Conclusions

- First attempt at full event particle-level unfolding with a generative model
 - Method also applies to unfolding **all particles**, but this is an order of magnitude higher dimensional problem
- Directly optimized quantities close well
- Derived quantities, like reconstructed top quark kinematics, are difficult
 - Can we improve?

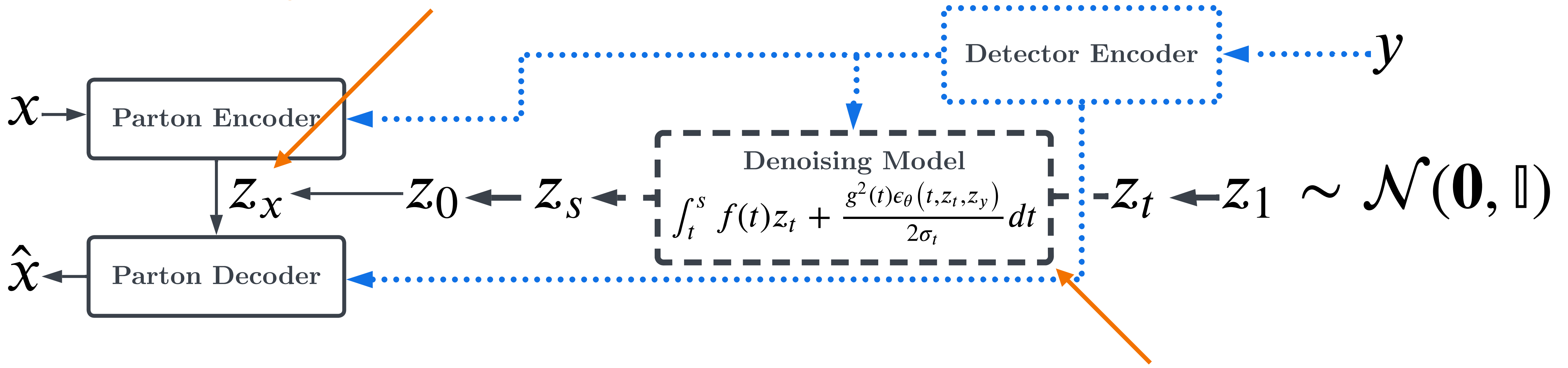


Backup

Variational Latent Diffusion (VLD)

Combine these ideas in an end-to-end model:

Latent space of VAE optimized for diffusion process.
Can even be higher dimensional than the data distribution



Learned noise schedule as in variational diffusion

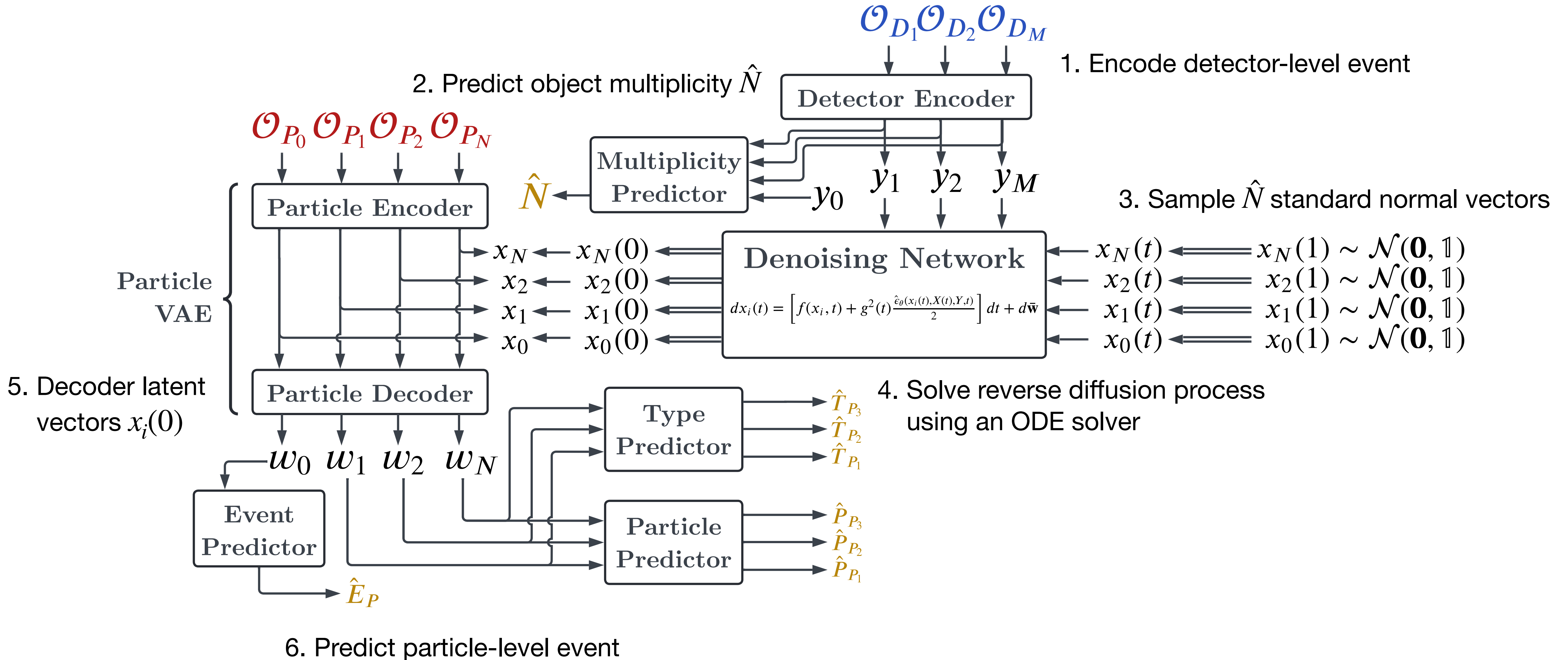
Other point-cloud conditional generative models

- The primary use case is fast generation / calorimeter simulation
- Set conditional set generation of jets: [slot attention](#), [graph diffusion](#)
 - Generate reconstructed jet based on particle-level constituents
 - Note this is learning the detector simulation forward operator
- JetNet/JetClass datasets: [mpgan](#), [pc-jedi/droid](#), [fpced](#), [mean-field gan](#), [epic-gan](#), [epic-jedi](#), [deeptree gan](#), [epic-fm](#)
 - Fixed length conditions (jet p_T , mass, constituent multiplicity, particle type)
- ILD calorimeter simulation dataset: [caloclouds](#), [calopointflow](#)
 - Fixed length conditions (energy, number of shower points)
- I am likely missing more than a few!
- **Conditioning is very different for fast generation / calorimeter simulation**

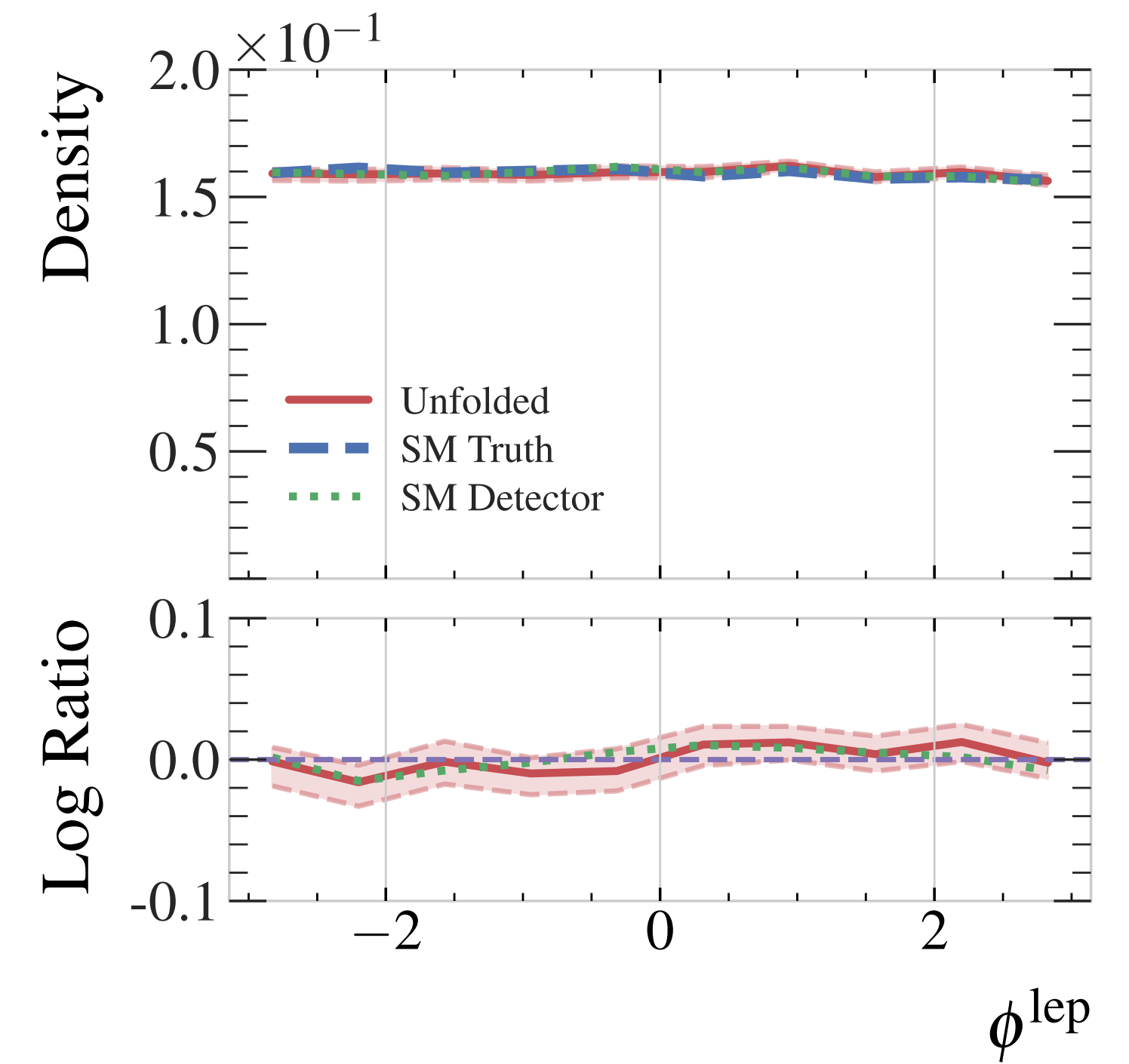
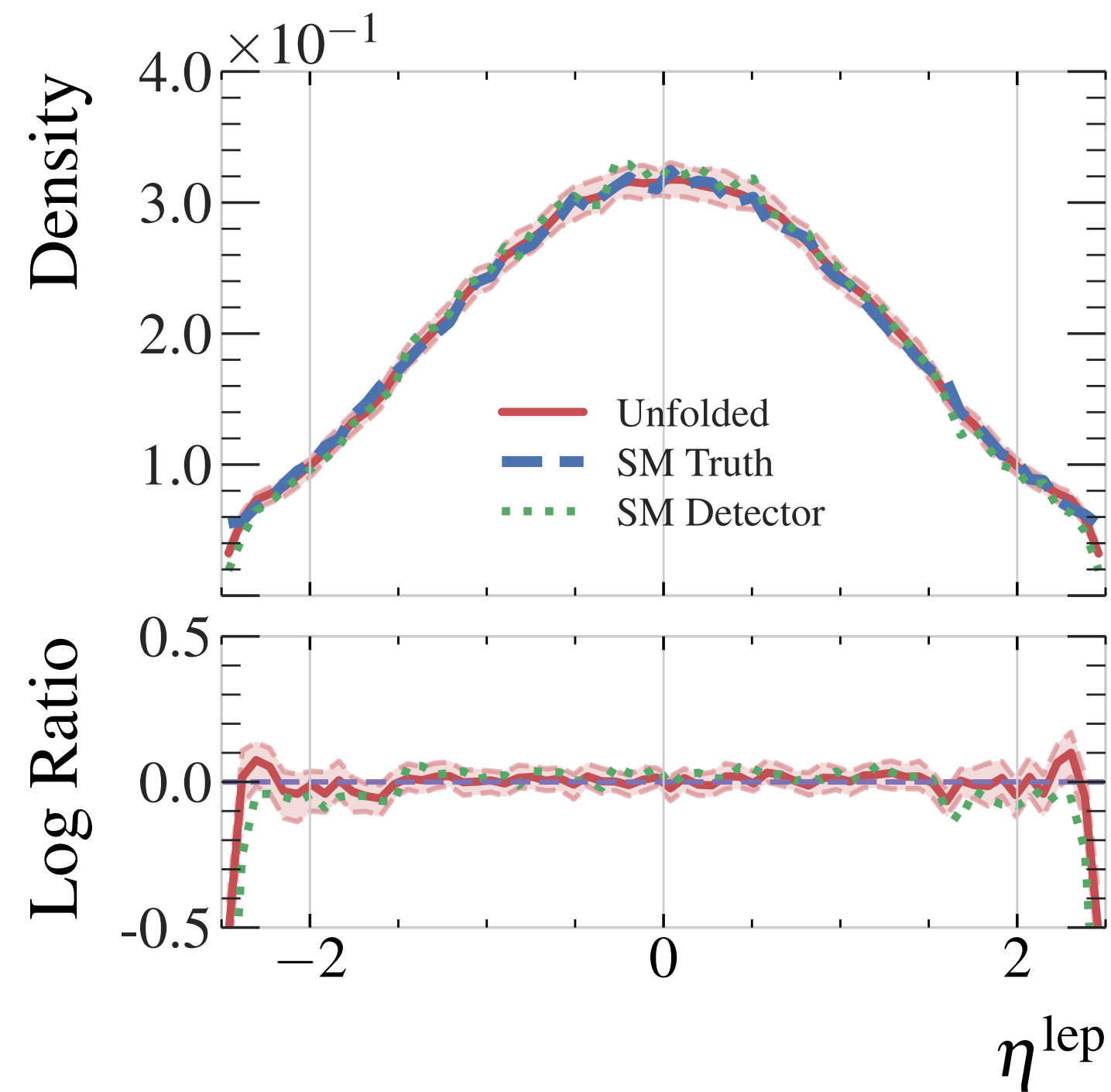
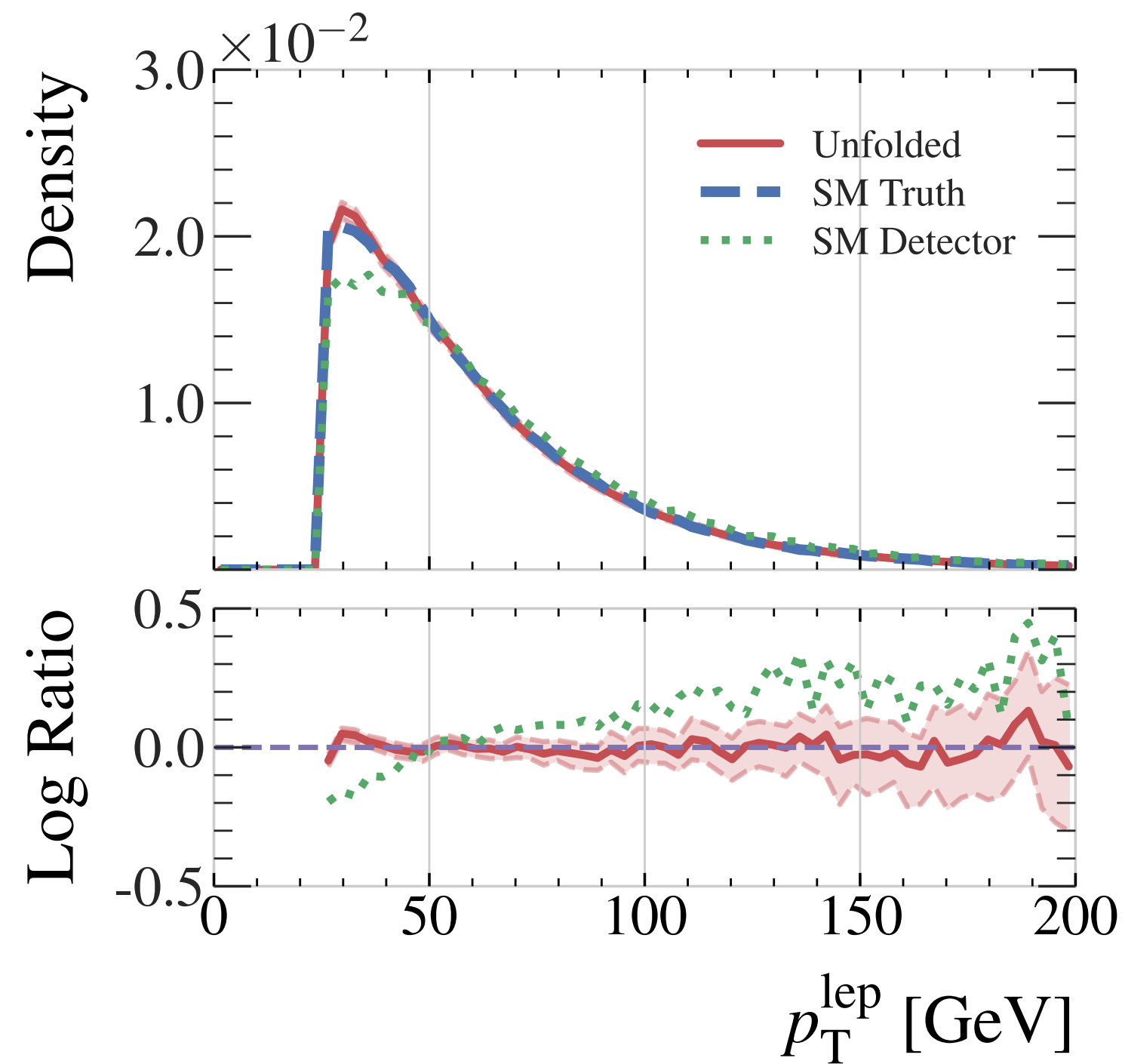
Diffusion loss ambiguity in the literature

- CaloClouds: denoising network acts only pointwise, so the MSE loss is always well defined. This is not an option in unfolding, as producing proper correlations between generated objects is essential.
 - They note that introducing point interactions did not help performance
- Set conditional set generation: use sinusoidal positional encoding

Inference with VL-VLD

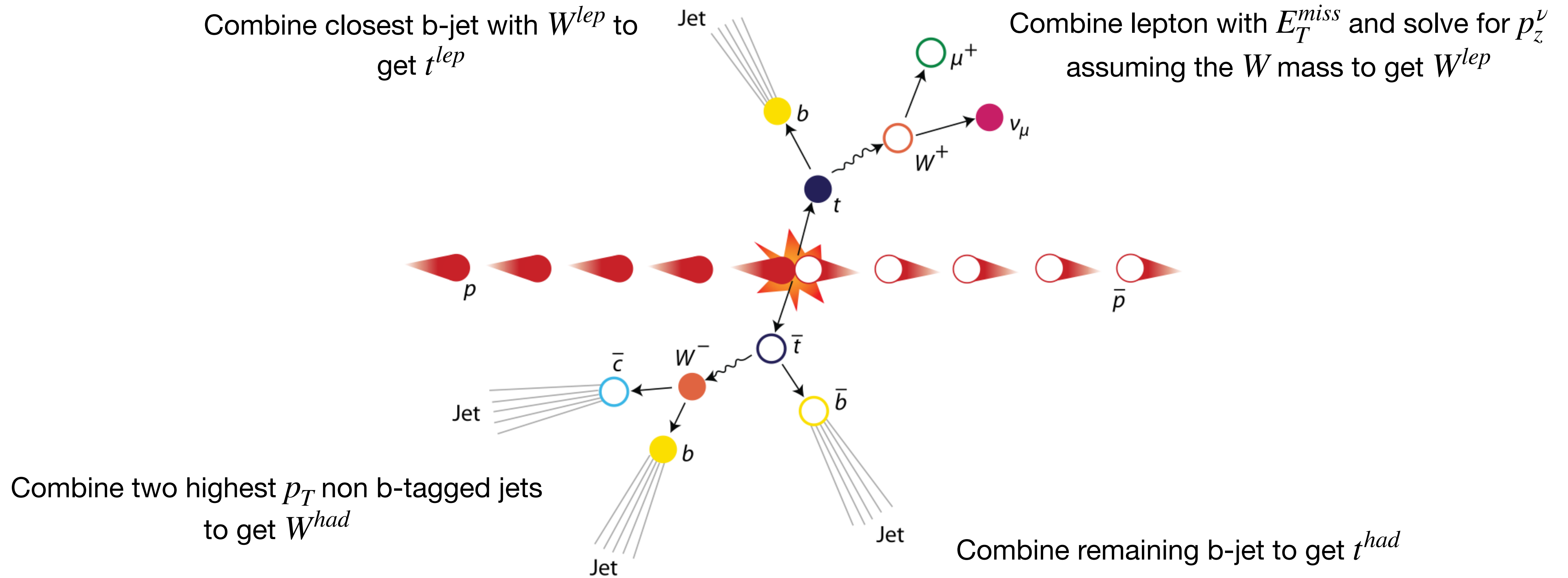


Inclusive kinematic distributions (leptons)



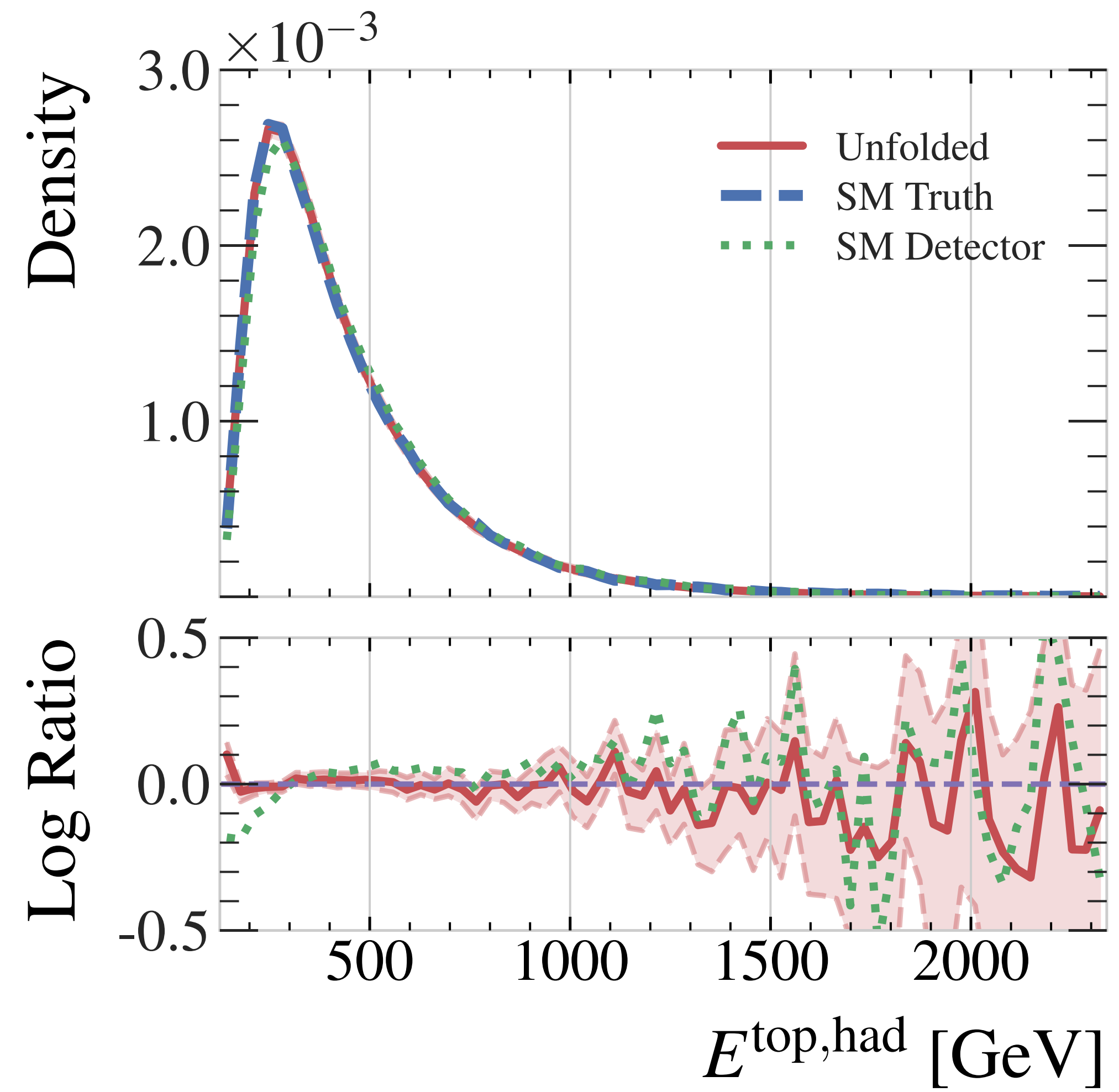
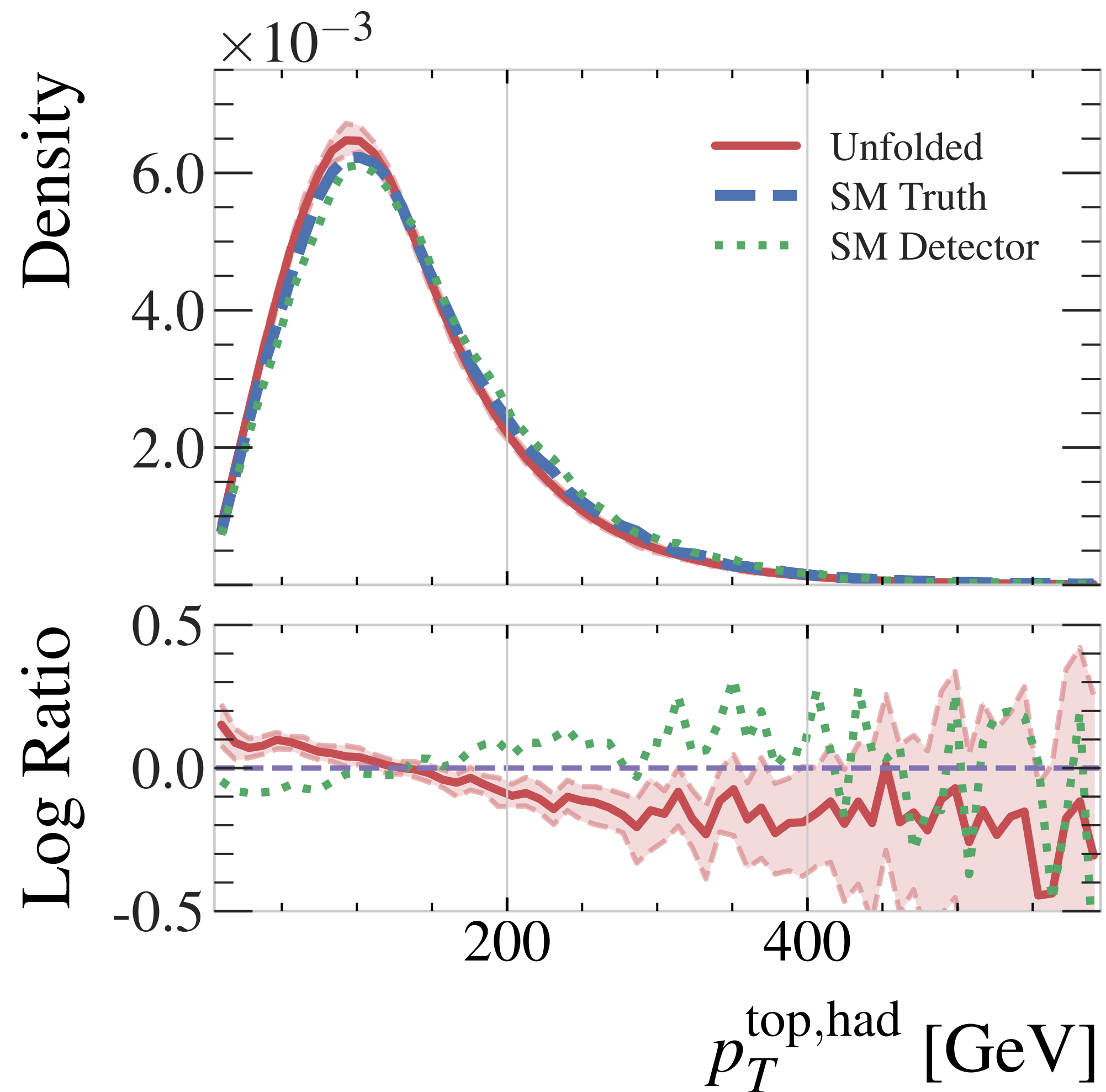
- Error bands estimated by sampling each particle-level configuration 128 times
- Kinematics of the directly optimized objects close well.
- Can struggle in edges of phase space where we lack training examples of events migrating across phase space boundaries from detector to particle-level

Pseudotop algorithm



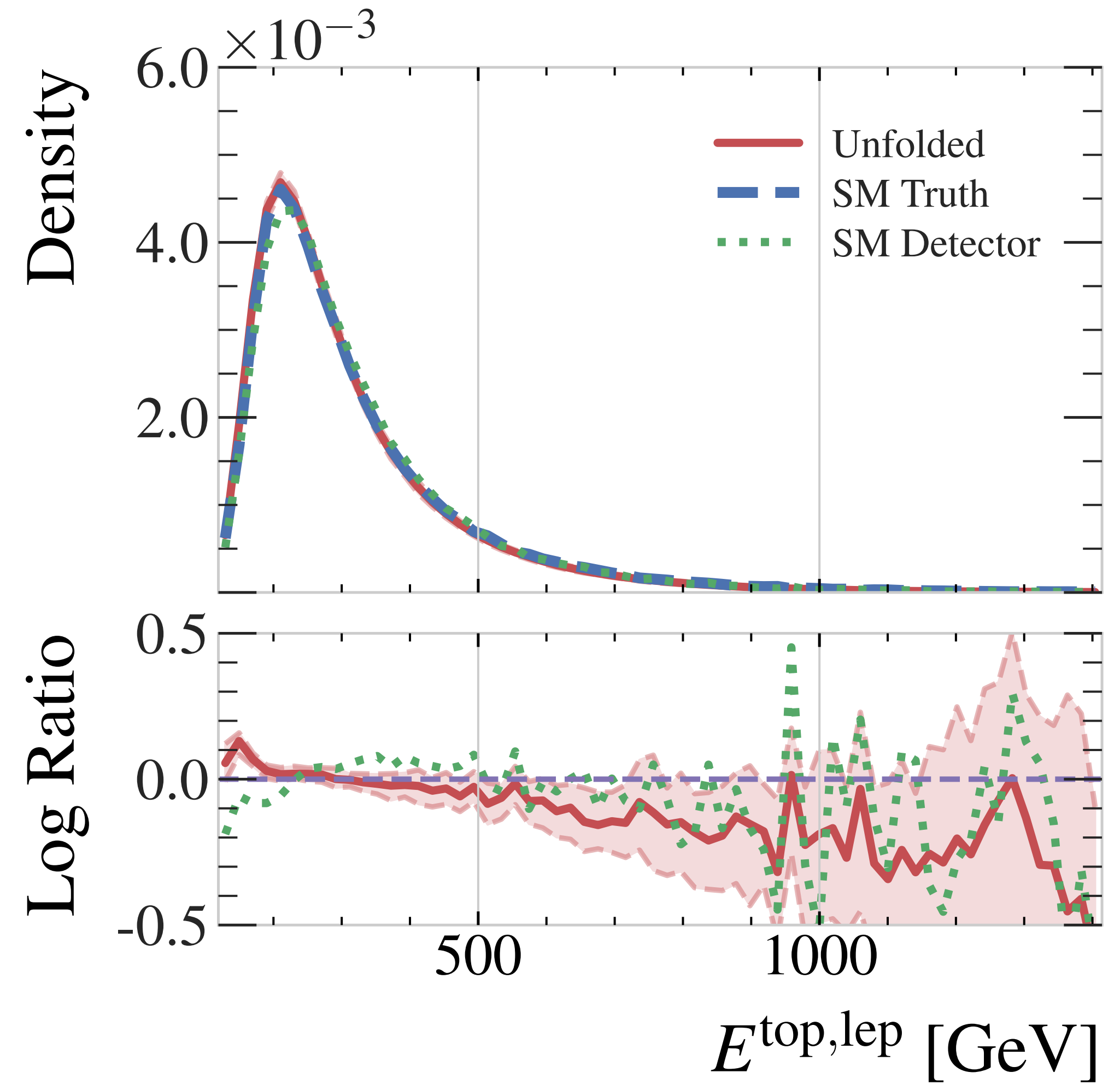
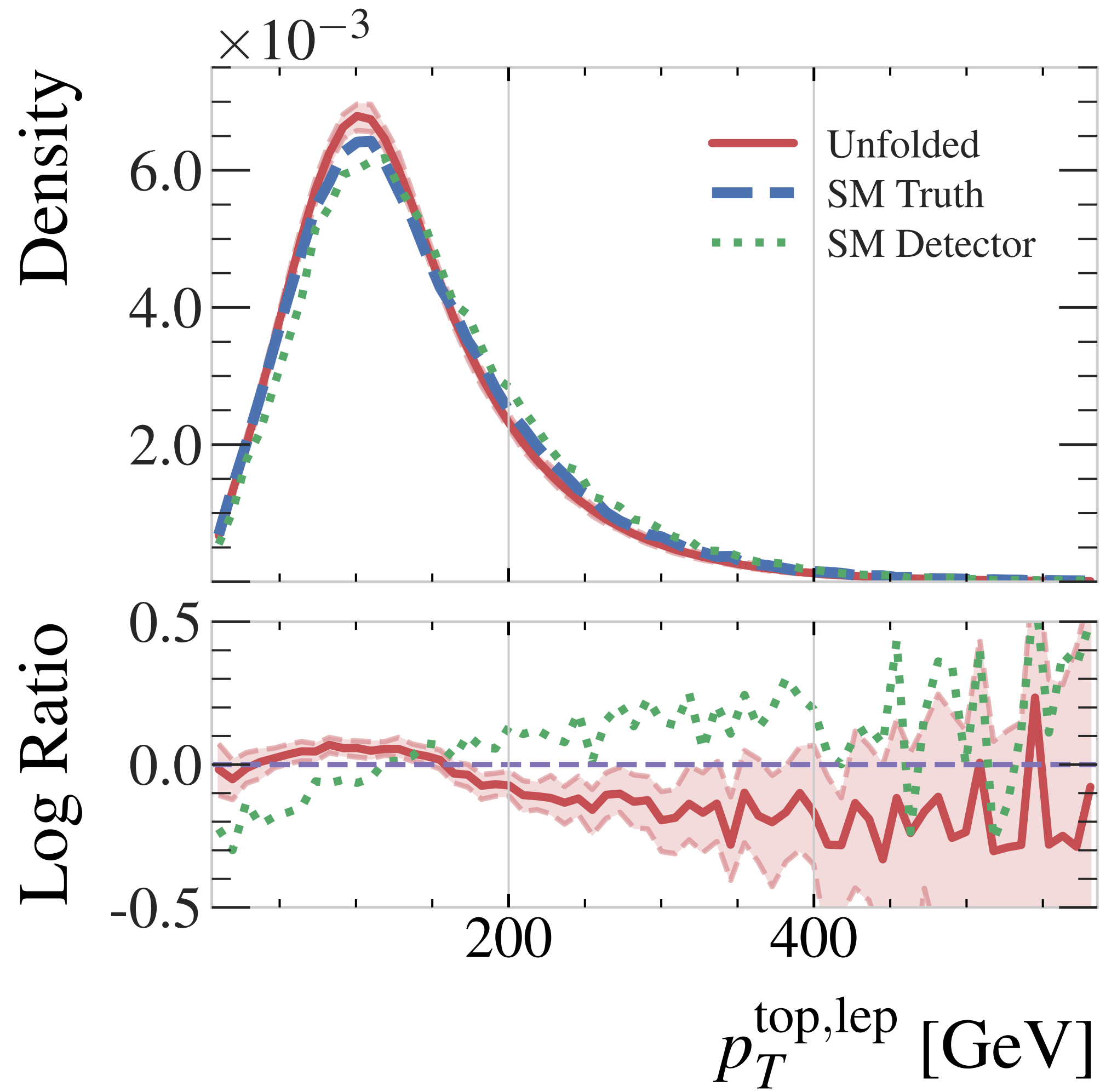
Hadronic top kinematics

Assumes pseudo-top jet/parton assignment



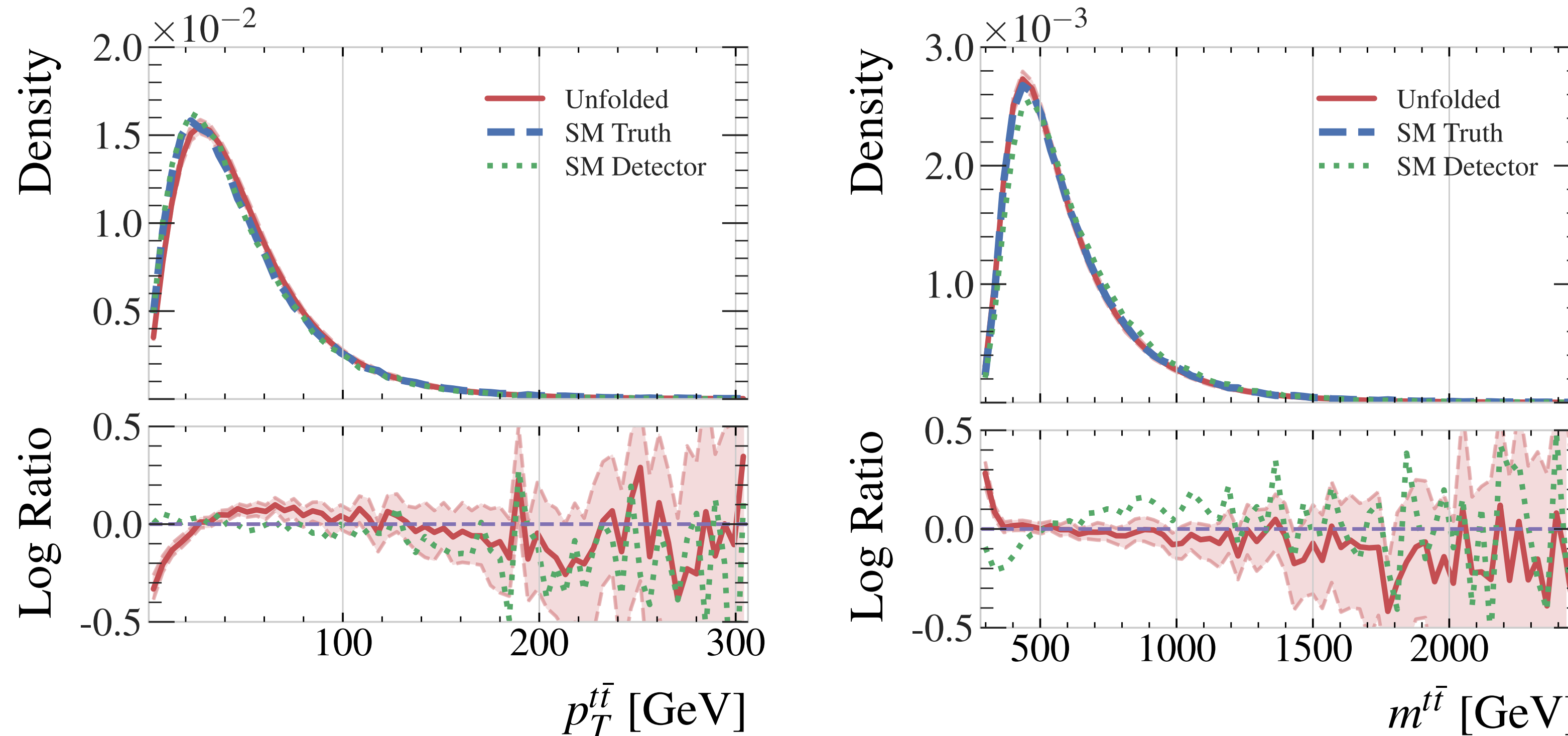
Leptonic top kinematics

Assumes pseudo-top jet/parton assignment



$t\bar{t}$ system kinematics

Assumes pseudo-top jet/parton assignment



- These distributions are not directly optimized, but are less peaked than hadronic top mass
- Predictions are decent in high p_T and mass events, but struggle in the low kinematic range