



# Deep Learning at DUNE Far Detector

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05-13-2024

DPF-PHENO 2024, Pittsburgh, PA



- New neutrino beam at Fermilab (1.2 MW, upgradeable to 2.4 MW), 1300 km baseline
- Utilize 17 kton Liquid Argon Time Projection Chamber (LArTPC) Far Detector modules at SURF: Horizontal-drift (HD), Vertical-drift (VD)
- Multiple technologies for the Near Detector (ND)
- Far Detector Prototypes at CERN: ProtoDUNE-HD (SP), ProtoDUNE-VD
- Neutrino oscillation and diverse non-beam neutrino and BSM projects



### **Motivation: AI based reconstruction chain for DUNE**

- DUNE's high-resolution LArTPC pixel map readout is ideal for image processing neural networks to reconstruct neutrino events
- Developing AI based Reconstruction Chain:
  - Energy, Direction, Vertex (regression, CNN)
  - Particle ID, Neutrino flavor ID (classification, CNN, Transformer)
  - Shower/Track Clustering (image segmentation, CNN, GNN)
- Goals: Performance, Robustness, Interpretability



Event display at ProtoDUNE-SP

#### **Convolutional Neural Network (CNN) for classification and regression**



Uses the 3 x 2D readout images, one for each wire/strip-plane, directly as input to a ResNet CNN architecture, then merges information across the 3 planes and uses a fully connected layer at the end for neutrino flavor classification or energy regression

- DUNE's high-resolution LArTPC images are challenging to process due to the large number of pixels
- CNNs are deep neural networks take raw pixel values input
- To reduce the number of parameters, CNNs apply convolutional filters to small regions of an image and then combine the features from these filters to produce the final decision
- Use the 3 x 2D readout images, one for each anode plane, as input to a ResNet CNN

## **Event Classification CNN identifiers in DUNE FD HD**

- Convolutional Neural Network (CNN)-based classifier ("CVN") to tag neutrino flavor, for both Horizontal-Drift FD (Phys. Rev. D 102, 092003, 2020) and Vertical-Drift FD (arXiv:2312.03130)
- Identify  $v_{\mu}$  charged current (CC),  $v_e$  CC and neutral current (NC) events
- Basis for sensitivity projections



CVN for VD,  $v_e$  CC identification, Neutrino beam (FHC)



## **Transformer CNN for Event and Particle Identification**

- Transformer: attention based network, foundation of ChatGPT, ideal for training on variable-length collection of object such as prongs (shower/track reconstructed by Pandora)
- Uses both event and prong images as inputs, identifies neutrino flavor and each particle simultaneously.
- Attention mechanisms automatically focus training and evaluation on image regions important to the final decision, significantly reducing the computing burden and enhancing training performance
- Attention mechanisms also provides interpretability, making deep learning more than just a "black box"



6

**Event ROC Curves** 

T-CVN = Transformer CNN, E-CVN = CVN



#### **Event Confusion Matrices**



#### Prong Confusion Matrices Prediction Normalized



# Interpretability

- Attention scores indicate importance of different elements to the network output → diagnose neural network and explain decision
- Identify image regions that are important to the final decision; analyze correlations between inputs and outputs, as well as among outputs





Red: more likely to predict the given flavor/particle type with more energy in that location. Blue: less likely to predict if there is more activity (anticorrelation).

Note: These interpretability studies come from NOvA (arxiv2303.06201), have not been conducted yet for DUNE simulation. 8

# $\nu_e CC$ and $\nu_\mu CC$ Event Energy

- CNN with linear output regression for event energy, optimizing resolution  $(E_{reco}-E_{true})/E_{true}$
- Weighted events by energy to reduce energy dependent bias in training
- Better resolutions than leption+hadronic energy method, less energy dependent bias with energy-reweighted training arXiv:2012.06181



9

### **Particle Energy Reconstruction**

- Regression CNNs for final state particle energies
- Trained on clustered lepton shower/track pixelmaps produced by Pandora



## **3-D Particle Direction Reconstruction**

- Direction regression heavily dependent on 3-D geometry
- Designed a 3-D CNN to reconstruct particle directions.
- 3-D image constructed from the 3x2D detector images
- Train direction CNNs on full-event pixelmaps or clustered lepton shower/track pixelmaps



# **Particle Direction Reconstruction**

- 3D CNNs beat traditional fit-to-hits method (PCA) with better electron and muon resolutions in all energy regions
- 3D CNN trained with full-event pixelmaps shows comparable performance to that trained with clustered lepton shower/track pixelmaps  $\rightarrow$  extract particle kinematics without clustering/tracking



## **Neural Network Robustness Tests**

- CNNs show robustness against neutrino interaction modes
- GENIE versions have small effects in CNNs
- Robustness studies still on going





 $\nu_{e}$  Event Energy vs. interaction modes

### **CNN for Shower/Track Separation in ProtoDUNE**



- ProtoDUNE-HD (SP in Phase I) and VD are two large DUNE prototype detectors at CERN
- ProtoDUNE-SP has collected test beam and cosmic ray data
- Use CNN to classify hits (pixels on LArTPC image) from Shower, Track and Michel electrons in ProtoDUNE-SP
  - Showers: Energy deposit pattern caused by electron, gamma, etc
  - Tracks: Energy deposit pattern caused by muon, pion, etc
  - Michel electrons: Low energy electron from muon decays
- Hit classification used in clustering and PID

### **CNN for Shower/Track Separation in ProtoDUNE**

- The inputs are 48-pixel images centered on the reconstructed hit to be classified
- Output is the classification of hit: from shower? Track? Michel electron?
- Successful identify hits and cluster shower/track





Eur.Phys.J.C 82 (2022) 10, 903

#### Shower Classifier Scores for each hit

## **Performance of CNN in ProtoDUNE Data**



- Test shower classifier scores for different particle species in the ProtoDUNE-SP
- Reasonable DATA/MC agreement

Eur.Phys.J.C 82 (2022) 10, 903

#### **Graph Neural Network for Object Reconstruction in LArTPC** (ExtExa.TrkX project)

Graph Neural Networks (GNN): define input data as a graph represented by nodes and edges, convolutions on nodes and edges rather than the entire pixel to speed up training

0.4

0.2

0.1

Successfully cluster LArTPC showers/tracks with GNN in ExtExa.TrkX project (a collaboration developing GNN reconstruction for HEP)



Implementing under DUNE context



#### **Confusion Matrix**



**Figure 2.** Example graph of a  $v_e$  interaction (left: ground truth, right: model output). Shower-like edges are drawn in red, hadronic edges are drawn in blue, muonic edges are drawn in green and false edges are drawn in grey.

V Hewes, A. Aurisano etc., EPJ Web of Conferences 251, 03054 (2021), arXiv:2403.11872

# Summary

- Systematically developed most elements of the reconstruction chain for DUNE far detectors using deep-learning methods.
  - neutrino flavor ID, particle ID, neutrino energy reconstruction, particle energy reconstruction, particle direction reconstruction and shower/track clustering ...
- Achieve very good selection efficiency and resolution
- Introduced Transformer/Attention to enhance performance and interpretability in Deep-Learning reconstruction
- Developing GNN, sparse neural networks and other new technologies to reduce computational burden
- Performing robustness tests with ProtoDUNE data and alterative simulation models

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