Search for single production of vector-like B quarks decaying to a top quark and a W boson in semi-leptonic final states

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DPF 2024

May 16, 2024



Vector-like quarks

- Left-handed components and right-handed components transform the same way under the SM electroweak symmetry (the weak interaction couples to the vector current)
- Hierarchy Problem
- Mass: *O*(1 TeV)
- Not constrained by current Higgs boson cross section measurements



Previous search at CMS

- Search has been done at CMS with 2016 data
- Single production: 2016 VLQ->tW search (arXiv:1809.08597)
 - Decay width 1, 10, 20, 30%
 - Semi-leptonic final states





- Mass exclusion limit: up to 1660 GeV for large decay widths
- Not enough sensitivity for narrow decay width

Analysis strategy $B \rightarrow tW: 1l$

- Select 1 lepton + MET + 1 "opposite-side" fatjet
- Build W from lepton + MET, then study the jets involved:



Reconstruction divided into 4 "cases":

- Leptonic W:
 - Top-tagged jet (case 1)
 - Not top-tagged (case 4)
- Leptonic t:
 - W-tagged jet (case 2)
 - Not W-tagged (case 3)
- Build B 4-vector from fatjet + leptonic particle

Background estimation: Overview

- Yield estimate + shape modelling
- Shape modelling: ABCDnn method
 - General data-driven shape estimation method
 - Learns the shape of the background through a DNN
 - Key components:

2 control variables + 2 transform variables

6 regions defined:

5 control region (training) + 1 "signal" region (application)

Aim for reduced uncertainty over MC modelling



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Background estimation: ABCDnn method

- Control variables: N_{forward jets}, N_b
- Transform variables: B mass, pNetJ score of leading fatjet



Background estimation: ABCDnn method

- Train two DNNs separately:
 - leptonic W (case 1+4)
 - leptonic T (case 2+3)
- Replace major background MC with **ABCDnn** estimation
- Minor backgrounds still modelled by MC



ABCDnn training results for leptonic top (case 2+3):



Private work (CMS data/simulation)



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Background estimation: Apply ABCDnn

- Data-to-prediction agreement from ABCDnn in the background-heavy regions are comparable to MC modelling
- ABCDnn predictions carry uncertainties on the peak position, tail position and closure/yield
- ABCDnn uncertainties are often smaller in magnitude than MC-related





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Expected limits

- Early analysis strategy studies showed promise for improvement over the previous search
- Full Run 2 expected limits are now tested comparing ABCDnn and MC for modelling major background
 - MC uncertainties included for experimental corrections and renormalization/factorization scale
 - Where used, ABCDnn uncertainties replace MC for major background



Summary & future work

- A search for single production of $B \rightarrow tW$ is in progress using CMS full Run2 data
- A new data-driven background estimation method (ABCDnn) is being explored and can be a good alternative to MC background modelling
- Expect an improved sensitivity using ABCDnn to model dominant backgrounds
- We hope to expand the search to include other single B production modes and widths, as well as Run3 data

Backup – Event selection

- Exactly 1 el/mu with high pT; no low pT leptons
- Lepton isolation requirement: loose
- AK4: min pT cut + central + tight ID + 2D cut against lepton
 - Loose b tagging
- AK8 jets: min pT cut + central + tight ID + minDR(lep, AK8) > 0.8
 - Top tagging 1% bkg WP, W tagging 5% bkg WP
- Require min AK4 HT cut + at least 1 AK8 with DR > $\pi/2$ from lepton
- QCD reduction
 - Get rid of low MET region
 - Upper limit on W m_T
 - Triangle Cut for electron events in $\Delta \varphi$ -MET phase space

Backup – Yield correction: alpha-ratio

- Extended ABCD overprediction: overestimate by 49% in some categories
- Alpha-ratio is a better alternative: off by less than 10% (less than 5% in most cases)







Backup – Neural Autoregressive Flow (NAF)

Problem of finding a transformation to a base distribution

 $p(\vec{x}|\vec{c})$

 $p(\vec{x}'|\vec{c}')$

Base distribution: Estimate:

x: transform variable *c*: control variable \vec{c} : control region $\vec{c'}$: signal region

$$p(\vec{x}'|\vec{c}') = \sum_{\vec{c}\neq\vec{c}'} \int \mathcal{T}(\vec{x}';\vec{x}|c';\vec{c}) p(\vec{x}|\vec{c}) d\vec{x}$$

 \mathcal{T} = transformation (to be learned by DNN)

Backup – Neural Autoregressive Flow (NAF)

Build complicated distributions from a base distribution by stacking simple transformations

$$f(x_{1},...,x_{d}) = f_{1}(x_{1})f_{2}(x_{2}|x_{1})...f_{t}(x_{d}|x_{1},...,x_{d-1})$$

$$p(\vec{x}'|\vec{c}') = \sum_{\vec{c}\neq\vec{c}'} \int \mathcal{T}(\vec{x}';\vec{x}|c';\vec{c}) p(\vec{x}|\vec{c}) d\vec{x}$$
In neural network:

$$y_{1} = \hat{f}_{1}(x_{1};\theta_{1}(\vec{c}_{0}))$$

$$y_{2} = \hat{f}_{2}(x_{2};\theta_{2}(\vec{c}_{0},x_{1}))$$

$$\dots$$

$$y_{d} = \hat{f}_{t}(x_{t};\theta_{t}(\vec{c}_{0},x_{1},...,x_{t-1}))$$

$$t = 1,...,d$$

$$p(\vec{x}'|\vec{c}') = \sum_{\vec{c}\neq\vec{c}'} \int \mathcal{T}(\vec{x}';\vec{x}|c';\vec{c}) p(\vec{x}|\vec{c}) d\vec{x}$$

$$f_{i}: \text{neural network}$$

$$\theta_{i}: \text{weights and biases}$$

One common choice of
$$\hat{f}_i$$
: $\hat{f}_i(x_i; \theta_i) = \sigma^{-1} \left[\vec{W}^T(\theta_i) \cdot \sigma(\vec{a_i}(\theta_i)x + \vec{b_i}(\theta_i)) \right]$
Deep Sigmoid Flow
(shown to be universal approximators to any bijective transformations in real space)

Backup – ABCDnn training results





Backup – ABCDnn uncertainties

- Three sources of uncertainty
 - Tail variation $\delta y(x) = \pm c x \left(1 e^{-\left(\frac{x-\mu}{\sigma}\right)^2}\right)$, x: prediction, μ : prediction mean, σ : prediction std



Backup: Background estimation results

Leptonic W (case 2+3)

