

Sweeping the Dust Away

Removing extinction bias from the Milky Way's potential using Gaia DR3 and unsupervised machine learning

arXiv:240X.XXXXX

Eric Putney (eputney@physics.rutgers.edu) w/ S.H. Lim, M. Buckley, D. Shih - Rutgers University

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- Moment approaches: Rotation curves, Jeans analyses, etc…

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Potential encoded in stellar phase space **f(x,v)**

Phase Space of the Milky Way

Local stellar **f(x,v)** encodes the local **gravitational potential** Φ via the equilibrium collisionless Boltzmann equation (CBE):

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\frac{d}{dt}\ln f = \left[\frac{\partial}{\partial t} + v_i \frac{\partial}{\partial x_i} - \frac{\partial \Phi}{\partial x_i} \frac{\partial}{\partial v_i}\right] \ln f = 0
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Interstellar dust absorbs or scatters starlight, which dims stars below *Gaia*'s sensitivity limit.

Suppression of **f(x,v)** biases our model of the MW's gravitational potential.

We learned **f(x,v)** from dusty stellar data using masked autoregressive flows (MAFs), generative ML density estimators.

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Measured the **dark matter** halo density around the Earth and the halo density profile!

Astronomers craft "dust maps" based on knowledge of the local ISM, extinction laws, etc...

Dust maps undo the dimming of observed stars, but they don't give insight into missing stars.

We note three key insights:

- 1. Only **f(x,v)** satisfies the CBE
- 2. Dust bias factorizable into $\epsilon(x)$, a position-dependent "dust efficiency"
- 3. Velocity dependence of terms breaks degeneracy between $\Phi(x)$ and $\epsilon(x)$

Credit: Lallement et al. 2019 A&A 625, A135

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(up to normalization)

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Solving the dust-corrected CBE

Given $f_{obs}(x, v)$, we can solve the CBE for $\Phi(x)$ and $\epsilon(x)$ simultaneously. We parameterize both with multi-layer perceptrons (MLPs).

(x), **(x)** training steps:

- Sample (x, v) pairs from $f_{obs}(x, v)$
- Compute **df/dx**, **df/dv** at **(x,v)**
- Minimize the MSE of the CBE as a loss

MLP architecture:

- 5x hidden linear layers, 100 wide
- GeLU activation
- Outputs of $\varepsilon(x)$ are clamped within $(0,1)$

$$
\mathcal{L}(\theta) = \sum_{j} \left| v_i \frac{\partial \ln f_{\text{obs}}}{\partial x_i} - v_i \frac{\partial \ln \epsilon_{\theta}}{\partial x_i} - \frac{\partial \Phi_{\theta}}{\partial x_i} \frac{\partial \ln f_{\text{obs}}}{\partial v_i} \right|_{x_j, v_j}^2
$$

Unbiased Phase Space Density

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How do we verify that ϵ is working?

Construct an effective ϵ based on a 3D dust map (Lallement 2022¹ i.e. L22).

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- Compute ratio of number densities: $\epsilon_{1,22}$

Limitations:

- Limited to nearby, totally complete regions of space i.e. within \sim 2.5 kpc
- **c** captures dust and over-smoothing, should look like a blurred version of $\epsilon_{1,22}$

**Comparing ** ϵ and ϵ _{L22}

 ϵ and $\epsilon_{1,22}$ consistent over the comparison volume!

- We are estimating the most dust-dense regions accurately

Comparing *e* and ϵ_{L22}

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 ϵ and ϵ ₁₂₂ consistent over the comparison volume!

- We are estimating the most dust-dense regions accurately
- Dust cloud complexes are reproduced when projected on the sky
- Extinction profiles consistent along dusty lines of sight

Dust-Corrected Potential

We compare **Φ(x)** to the standard benchmark Milky Way potential MWPotential2014².

- We recover a smoother potential in previously dust-obscured regions of the disk

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We compare **Φ(x)** to the standard benchmark Milky Way potential MWPotential2014².

- We recover a smoother potential in previously dust-obscured regions of the disk
- Deviations from the standard axisymmetric picture are apparent

Solid: CBE-derived **Φ(x)** Dashed: MWPotential2014 **Φ(x)**

Acceleration & Mass Density

Acceleration improvements:

- Parameterizing Φ(x) with an MLP smooths **a(x)** significantly
- Dust-correction stabilizes **a(x)** in dusty regions of the sky. Can access the disk!

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- Parameterizing $\Phi(x)$ with an MLP smooths **a(x)** significantly
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Finally, we estimate the local dust-corrected mass density field **ρ(x).**

- Similar smoothing benefit, estimate is stable in the disk
- Exhibits noisy oscillations in some regions

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- Exhibits noisy oscillations in some regions
- Residual map of dark matter coming into focus…

Summary

We have developed a data-driven technique for removing dust extinction bias from kinematic phase space.

Our estimate of this bias is consistent with and builds upon existing 3D dust maps.

Used the unbiased $f(x, v)$ to map the local potential. Closer to a fully data-driven map of dark matter in the Milky Way.

DALL-E: "A visually striking image that represents the phrase "dark matter to dark matter, dust to dust" symbolizing the removal of interstellar dust to reveal a spiral galaxy"

References:

- 1. R. Lallement, J. L. Vergely, C. Babusiaux, and N. L. J. Cox, Astronomy & Astrophysics 661, A147 (2022), ISSN 1432-0746
- 2. J. Bovy, 216, 29 (2015), 1412.3451

Additional Slides

Flying through the clouds (legible edition)

- Consistent profiles for most clouds
- Overshoot distance to some clouds
- We miss fainter clouds
- Dust map error bars are very tight!

Radial Profile of the Milky Way's Dark Matter Halo

Can place loose constraints on the MW halo. Radial profile consistent with NFW (β =1) when fit to a generalized NFW (gNFW) profile.

Phase mixing & equilibrium

Gaia Dataset: The Red Clump (and friends)

Lim, **EP**, Buckley, Shih (2023)

Jeans Equations

Moments of the CBE yield the Jeans equations:

$$
\int d^3p(p_z * \text{CBE}) \longrightarrow a_z = \frac{1}{\nu} \frac{\partial(\nu \overline{v_z^2})}{\partial z} + \frac{1}{\nu R} \frac{\partial(\nu R \overline{v_R v_z})}{\partial R}
$$

$$
\int d^3p(p_R * \text{CBE}) \longrightarrow a_R = \frac{1}{\nu} \frac{\partial(\nu \overline{v_R^2})}{\partial R} + \frac{1}{\nu} \frac{\partial(\nu \overline{v_R v_z})}{\partial z} + \frac{\overline{v_R^2} - \overline{v_\phi^2}}{R}
$$

Key notes:

- Axisymmetry implicitly assumed when $a_{\phi} = 0$.
- Must model each velocity moment and number density
- Many terms are noisy. Calculation of ρ can involve high order derivatives of fits to noisy data.

 $\rho_{\rm DM}(r_{\odot})$ $(10^{-2} M_{\odot}/pc^3)$ 1.0 1.5 2.0 2.5 3.0 This work Normalizing flows Casagrande, (2020) 60 Blue straggler scaling relations Pato, et al., (2015) **61** Circular velocity curve Huang, et al., (2016) 62 Benito, et al., (2019) 63 Karukes, et al., (2019) 64 Lin. et al., (2019) 63 de Salas, et al., (2019) **66** Ablimit, et al., (2020) 67 سمنا Benito, et al., (2020) **68** Sofue, (2020) 69 **SOF** Zhou, et al., (2022) 70 **Hold** Ou, et al., (2023) 50 McMillan, (2017) 77 Circular velocity mass models تسميد Cautun, et al., (2020) 72 Bienyame, et al., (2014) 73 Distribution function fitting Piffl, et al., (2014) $\overline{74}$ Binney, et al., (2015) **73** Cole, et al., (2017) 76 Wegg, et al., (2019) 77 Halo star mass models Hattori, et al., (2020) **78** Nitschai, et al., (2020) **42** Jeans anisotropic Nitschai, et al., (2021) $\overline{13}$ Widmark, et al., (2021) 79 Phase space spirals Guo, et al., (2022) **80** McKee, et al., (2015) 57 Vertical Jeans analysis Xia, et al., (2016) 81 Hagen, et al., (2018) $\overline{43}$ Sivertsson, et al., (2018) $\overline{40}$ Guo, et al., (2020) [14] Salomon, et al., (2020) (North) \overline{H} Salomon, et al., (2020) (South) $\boxed{11}$ Wardana, et al., (2020) 82 Schutz, et al., (2018) 58 Buch, et al., (2019) **83** Very local analysis 0.25 0.75 1.00 0.00 0.50 $\rho_{\rm DM}(r_{\odot})~(\rm GeV/cm^3)$

Lim, **EP**, Buckley, Shih (2023)

Gaia Measurement Errors

Astrometric errors and propagated from ICRS to Cartesian coordinates.

Primary uncertainties for stars are parallax and radial velocities.

- We cut relative stars w/ relative parallax errors $> .33$

Lim, **EP**, Buckley, Shih (2023)

Normalizing Flows

Stats definition: A transformation **g** of a base distribution **p(z)** into a target distribution **p(y)** by a sequence of invertible and differentiable mappings.

Key Ideas:

- There are simple distributions **p(z)** that we understand.
- Our data was drawn from some unknown distribution **p(y)**.
- Training a normalizing flow -> finding a smooth transformation **g** (with inverse **f**) between **p(z)** and **p(y)**. **g** may can be a sequence of smooth and invertible transformations.

Chain rule lets us write the following: $p_Y(y) = p_Z(f(y)) \frac{df(y)}{dy}$ Maximize likelihood of data = minimizing negative log-likelihood of data

Masked Autoregressive Flows

Autoregressive model: transformation modeled as a product of conditionals. MAFs enforce autoregressive property by masking network connections, allowing for complex non-linear transformations.

Eric Putney | Rutgers, the State University of New Jersey | DPF-Pheno 2024 | May 16, 2024

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