#### From Components to Cohesion: ATLAS ITk Inner System Assembly and Testing

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### **ATLAS Subsystems**

- General particle detector used for wide range of studies

  - Precision HiggsDark Matter Searches
  - Long Lived Particle searches Etc





- Multiple subsystems to measure particles
  - Momentum
  - Energy
  - Charge
  - Angle
  - **Ionization Energy** Loss

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### ITk An Upgrade For HL-LHC

	LHC Run 3 (Current run)	HL-LHC					
Pileup	30	200					
Instantaneous Luminosity	$2\times10^{34}~\mathrm{cm}^{-2}~\mathrm{s}^{-1}$	$7.5  imes 10^{34}  m \ cm^{-2} \ s^{-1}$		ATLAS tracker is to be replaced with a new all-silicon inner tracker (ITk), to accommodate HL-LHC conditions. 1. Increased granularity			
Target Integrated Luminosity	300 fb <sup></sup> 1	4000 fb <sup></sup> 1					
					<ol> <li>Increased radiation hardness</li> <li>Full silicon</li> </ol>		
					Current Tracker	HL-LHC Inner Tracker	
	Carles and the second sec	KKKKKKKK		# Pixels	92 Million	5 Billion	
	A SPIEL AND MYN	KKKKKKKKKKKKKKKKKKKKKKKKKKKKKKKKKKKKKK		Pixel Silicon Area	1.9 m <sup>2</sup>	$12.98 m^2$	
	PRODUCT DEPOS			Trigger Rate	100 kHz	1 MHz	
				$\eta$ Coverage	2.5	4	
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## ITk Pixel Layout

- ITk Pixel is the innermost layers of ATLAS detector
- The Inner System
  - Independent from outer system
  - Replaceable
  - Receives highest radiation dose





#### ITk Pixels Inner System Components Loaded Local Support Sensor and front end Modules **Barrel Assembly** Type 1 services Local supports OREGON Barrel shell 6

# **Overview of Integration At SLAC**

- Integration of components
  - Test received modules for functionality
  - Load Modules onto local supports
  - Load services (Power and Data)
  - Test modules at operating conditions on local support
  - Load local supports into shells Check that modules still have
  - connectivity
  - Integrate 2 shells together Ship halves to CERN





# Focus on: Module Loading on Local Support



Back of module after glue is dispensed



- Modules are tested for damage during shipping to SLAC
- Local Supports are loaded into fixture
- Glue is deposited on the back of modules
  - Glue is a thermal compound SE4445
  - Glue location is controlled by robot
  - Glue dispensing is controlled by volumetric dispenser
- Modules are flipped over and placed into position on the local support

Controller for dispenser

Robot



Delicate

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# Quality Control and Fixing Glue Dispensing

Needed input for dispenser

#### Output of Robot

- Originally used pneumatic glue dispenser with inconsistent results
- Upgraded to volumetric dispenser currently see around 1% variance
  - Glue robot and volumetric dispenser had no premade solution to interface together.
  - Created interposer board that changed output digital signals from robot to input signal for dispenser

Glue coverage is important to thermal conductivity of module

 Thermal performance of modules ensures longevity and reduced radiation damage
 Glue coverage is inferred from mass deposited and height of module





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- Need to test loaded local support.
  - Tested at operating conditions
    - Minimum Temp -30C
    - Maximum Pressure in evaporators 1500 PSI
    - HV to modules and serial powered modules
- Requires making connection to the delicate 3mm titanium evaporator tubes
- 8 unique evaporator tubes of local supports and all lengths and reflections of loaded services all fit in same test fixture
- Testing is last chance to catch issues before reworking any modules because nearly impossible

#### Loaded Local **Support** Testing





# Integration and Shipping

- Developed special tooling specifically for integration
- Made 3d printed mock up of IS
- Tested and practiced assembling IS
  - Difficult to route cables through shell without touching the delicate wire bonds on modules
  - Found early enough that we have to add carbon fiber protection structur on the edge of the stave to protect modules during integration



#### Status and outlook

- Prototyping is finished. Now working on finishing our preproduction setup o Proof of ability to do
  - production
  - Setting up quality control and quality assurance steps
  - Looking for potential Ο problems
- Currently on schedule to ship first parts of the Inner System to CERN in early 2025

	Prototyping	Preproduction	Production
Modules Assembly	Complete	Ongoing	Upcoming
Local Supports	Complete	Ongoing	Upcoming
Loaded Local Supports	Complete	Upcoming	Upcoming
Data Transmission	Complete	Upcoming	Upcoming
Services	Complete	Ongoing	Upcoming
Mechanics/ Shells etc	Complete	Ongoing	Upcoming
Integration	Complete	Upcoming	Upcoming

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## Conclusion

- US ATLAS is on schedule for delivering the Inner System
- Integration of ITk is built by a large group of different institutes and labs
- Integration efforts have relied on finding problems early to ensure smooth path from components to cohesion



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