

# R-defects Topological defects in non-Abelian Chern-Simons

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Work in progress with Alex Arvanitakis, Lewis Cole, Daniel Thompson

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# **Topological defects**

A defect is called topological when the energy momentum tensor

satisfies  $T_L = T_R$  &  $\overline{T}_L = \overline{T}_R$  at the defect locus



 $\cong$ 

 $\rightarrow$  "Topological" = can be deformed and moved at no cost

 $\rightarrow$  Encode dualities and symmetries

[Bachas, de Boer, Dijkgraaf, Ooguri, Kapustin, Tikhonov, Fröhlich, Fuchs, Gaberdiel, Runkel, Schweigert, Brunner, Roggenkamp, Carqueville,...]

 $\rightarrow$  "Fusion" = move and compose topological defects

#### Motivation

T-duality is an example of a topology defect [Fuchs, Gaberdiel, Runkel, Schweigert] [Kapustin, Saulina][Niro, Roumpedakis, Sela]

Talks of Camille and Marcia

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**T-duality is** an example of a topology defect [Fuchs, Gaberdiel, Runkel, Schweigert] [Kapustin, Saulina][Niro, Roumpedakis, Sela]



is a topological defect !

.... but is also a topological defect !

[SD, Raml]

Goal: Use the technology of defects and their fusion to understand generalised T-duality

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Goal: Use the technology of defects and their fusion to understand generalised T-duality

 $\rightarrow$  problem: fusion remained a difficult question

.... but is also a topological defect !

 $\rightarrow$  needed a way to construct topological defects for non-Abelian Chern-Simons...





$$\begin{split} S_{\mathrm{unfolded}}[A_N,A_S] &= S_{\mathrm{CS}}[A_N] + S_{\mathrm{CS}}[A_S] + S_D[\mathbb{A}] \\ & \text{with} \quad A_S \in \mathfrak{u}(1)_S^d \;, \quad A_N \in \mathfrak{u}(1)_N^d \end{split}$$



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In the 3d Abelian Chern-Simons:

when does Chern-Simons theory admit a topological surface ?

Elegant algebraic answer: [Kapustin, Saulina] Look for Lagrangian subalgebras !



$$S_{\rm CS} = k \int_{M_N} \langle\!\langle \mathbb{A}, d\mathbb{A} \rangle\!\rangle \qquad \text{where} \quad \langle\!\langle \mathbb{X}, \mathbb{Y} \rangle\!\rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle$$

with gauge group  $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$ 



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Varying the action

$$\delta S_{\rm CS} = 2 k \int_{M_N} \langle\!\langle \delta \mathbb{A} , \mathrm{d} \mathbb{A} \rangle\!\rangle + k \int_D \langle\!\langle \delta \mathbb{A} , \mathbb{A} \rangle\!\rangle$$

Vanishes by the e.o.m.  $F[\mathbb{A}] \equiv d\mathbb{A} = 0$ 

requires a **boundary cond**. that we will take to be **topological** 

Demand that  $\mathbb{A}|_D \in$  "Lagrangian subspace S" of  $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$  $\langle\!\langle \mathbb{X}, \mathbb{Y} \rangle\!\rangle = 0 \qquad \forall \mathbb{X}, \mathbb{Y} \in S$ 



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Instead of **boundary condition**: include the **boundary term** 

🥎 projector

$$S = k \int_{M_N} \langle\!\langle \mathbb{A} \,, \mathrm{d} \mathbb{A} \,\rangle\!\rangle + k \int_D \langle\!\langle \mathbb{A} \,, P_S \,\mathbb{A} \rangle\!\rangle$$



For Abelian Chern-Simons, the gauge group is

$$\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)_N^d \oplus \mathfrak{u}(1)_S^d$$

And there are two Lagrangians

diagonal	:	$\mathfrak{u}(1)_{+}^{d} = \{ (X_N, X_S) \in \mathfrak{u}(1)^{2d} \mid X_N = X_S \} ,$
anti-diagonal	:	$\mathfrak{u}(1)_{-}^{d} = \{ (X_N, X_S) \in \mathfrak{u}(1)^{2d} \mid X_N = -X_S \}$



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anti-diagonal :  $\mathfrak{u}(1)^d_- = \{(X_N, X_S) \in \mathfrak{u}(1)^{2d} \mid X_N = -X_S\}$ 



Yields the fusion algebra

$$\mathfrak{u}(1)^d_- \circ \mathfrak{u}(1)^d_- = \mathfrak{u}(1)^d_+ \qquad \mathfrak{u}(1)^d_+ \circ \mathfrak{h} = \mathfrak{h} \ , \qquad \mathfrak{h} \circ \mathfrak{u}(1)^d_+ = \mathfrak{h}$$

That is 
$$\left(\left\{\mathfrak{u}(1)^d_+,\mathfrak{u}(1)^d_-\right\},\circ\right)\cong\mathbb{Z}_2$$

identity idempotent

5/12

# **Topological surfaces in non-Abelian Chern-Simons**

In the 3d non-Abelian Chern-Simons:

when does Chern-Simons theory admit a topological surface ?

[Fuch, Schweigert, Valentino] [Kapustin, Saulina]

$$S_{\rm CS} = k \int_{M_N} \left( \langle\!\langle \mathbb{A} \,, \mathrm{d} \mathbb{A} \rangle\!\rangle + \frac{1}{3} \langle\!\langle \mathbb{A} \,, [\![\mathbb{A} \,, \mathbb{A}]\!] \rangle\!\rangle \right)$$

$$\mathbb{A} = (A_N, A_S) \in \mathfrak{d} = \mathfrak{g}_N \oplus \mathfrak{g}_S \qquad \langle\!\langle \mathbb{X}, \mathbb{Y} \rangle\!\rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle$$



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We showed: [Arvanitakis, Cole, SD, Thompson *WIP*]

- $\rightarrow$  Canonical way to constructed topological defects
- → Crucial tool: (modified) Yang-Baxter equation
- $\rightarrow$  Defined and studied their fusion

# Lagrangians via the mCYBE: *R*-defects

Strategy: simplify one's life a little by looking for a subclass of defects

Solve the modified classical Yang-Baxter equation

$$[\mathcal{R}X, \mathcal{R}Y] - \mathcal{R}([\mathcal{R}X, Y] + [X, \mathcal{R}Y]) + [X, Y] = 0$$

Yields a Lagrangian subalgebra  $\mathfrak{g}_{\mathcal{T}}$ 

$$_{\mathcal{R}} = \{ ((\mathcal{R}+1)X, (\mathcal{R}-1)X) \in \mathfrak{d} \}$$

With Lie-bracket  $[X,Y]_{\mathcal{R}} = [\mathcal{R}X,Y] + [X,\mathcal{R}Y]$ 

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With Lie-bracket  $[X, Y]_{\mathcal{R}} = [\mathcal{R}X, Y] + [X, \mathcal{R}Y]$ 

Called a "bi-algebra" or "Manin triple"  $\mathfrak{d} = \mathfrak{g}_{\Delta} \oplus \mathfrak{g}_{\mathcal{R}}$ 

 $\rightarrow$  Directly generalises the Abelian case  $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_{\Delta} \oplus \mathfrak{u}(1)^d_{-}$ 

 $\rightarrow$  Technical requirement  $\mathfrak{d} = \mathfrak{g}_{\Delta} \oplus \mathfrak{g}_{\mathcal{R}} \cong \mathfrak{g} \oplus \mathfrak{g}$ 

Effectively specialising to non-compact algebras

## Lagrangians via the mCYBE: *R*-defects

We have a topological boundary condition for the Lagrangian subalgebra

$$\mathfrak{g}_{\mathcal{R}} = \{ ((\mathcal{R}+1)X, (\mathcal{R}-1)X) \in \mathfrak{d} \}$$

Since with the R-matrix we can construct a projector

$$\langle\!\langle \mathbb{A}, \mathcal{P}_{\mathcal{R}} \mathbb{A} \rangle\!\rangle = \langle A_S, A_N \rangle + \frac{1}{2} \langle A_N - A_S, \mathcal{R}(A_N - A_S) \rangle$$

Yielding the (folded) Chern-Simon action

Boundary for 
$$\mathfrak{g}_{\mathcal{R}}$$
  
Nothing  $S_{\text{folded}} = \int \operatorname{CS}[\mathbb{A}] + \int_D \langle\!\langle \mathbb{A}, \mathcal{P}_{\mathcal{R}} \mathbb{A} \rangle\!\rangle$ 



$$\mathfrak{h}_{NI} \circ \mathfrak{h}_{IS} = \Pi_{NS} \Big( \big( \mathfrak{h}_{NI} \oplus \mathfrak{h}_{IS} \big) \cap \big( \mathfrak{g}_N \oplus \mathfrak{g}_\Delta \oplus \mathfrak{g}_S \big) \Big)$$

$$\checkmark$$

 $\mathfrak{g}_{\mathcal{R}} \circ \mathfrak{g}_{\mathcal{R}} = \{ (X_N, X_S) \in \mathfrak{d} \mid X_N^{\mathfrak{t}} = X_S^{\mathfrak{t}}, X_N^- = 0, X_S^+ = 0 \}$ 

 $\rightarrow$  Proved that  $\mathfrak{h}_{NI} \circ \mathfrak{h}_{IS}$  is

- ✓ Lagrangian
- ✓ a subalgebra
- with identity element  $\mathfrak{g}_{\Delta} \circ \mathfrak{h} = \mathfrak{h}$ ,  $\mathfrak{h} \circ \mathfrak{g}_{\Delta} = \mathfrak{h}$
- reduces to Lagrangian fusion in the Abelian case



Admits a re-formulation in terms of Chern-Simons theories

$$S_{\text{grav}} = S_{\text{CS}}[A] - S_{\text{CS}}[\bar{A}] + S_{\text{bdy}}$$

"folded" Chern-Simons theory for the gauge group  $\mathfrak{sl}(2,\mathbb{R})\oplus\mathfrak{sl}(2,\mathbb{R})$ 

Where the gauge connections are related to the metric vielbein and the soldering form

$$A^a = \omega^a + \frac{1}{\ell}e^a$$
,  $\tilde{A}^a = \omega^a - \frac{1}{\ell}e^a$ 

With respect to the  $\mathfrak{sl}(2,\mathbb{R})$ -generators  $[L_a,L_b]=(a-b)L_{a+b}$ 



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In the Feffer-Graham gauge the boundary term is [Llabres; Apolo; Ebert, Hijano, Kraus, Monten, Myers]

$$S_{\text{bdy}} = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} A \wedge \bar{A} - \frac{k}{2\pi} \int_{\partial M} \operatorname{tr} \left( L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) \quad (A - \bar{A}) \quad (A$$

The boundary term corresponds precisely the R-boundary term [Arvanitakis, Cole, SD, Thompson]

$$S_{\text{bdy}} = c \int_{\partial M} \langle A, \bar{A} \rangle - \frac{1}{2} \langle \bar{A} - A, \mathcal{R}(\bar{A} - A) \rangle$$

where the R-matrix is the Drinfel'd-Jimbo R-matrix for

$$\mathcal{R}L_0 = 0, \qquad \mathcal{R}L_{\pm} = \pm L_{\pm}$$

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Higher spin AdS<sub>3</sub> gravity also admits Chern-Simons formulation

$$S_{\text{grav}} = S_{\text{CS}}[A] - S_{\text{CS}}[\bar{A}] + S_{\text{bdy}} \quad \text{with connections for} \\ \text{the algebra } \mathfrak{sl}(N, \mathbb{R}) \\ \text{with spin fields} \quad \phi_{\mu_1 \dots \mu_{s-1} \mu_s} \sim \text{Tr} \left( e_{(\mu} \dots e_{\mu_{s-1}} e_{\mu_s)} \right)$$

 $\rightarrow$  what type of BC does the R-boundary term give rise to?

$$S_{\text{bdy}} = c \int_{\partial M} \langle A, \bar{A} \rangle - \frac{1}{2} \langle \bar{A} - A, \mathcal{R}(\bar{A} - A) \rangle$$

with the Drinfel'd-Jimbo matrix  $\mathcal{R}H_i = 0$ ,  $\mathcal{R}E_{\alpha} = +c E_{\alpha}$ ,  $\mathcal{R}E_{-\alpha} = -c E_{-\alpha}$ 

to be continued....

#### $\rightarrow$ Summary

Constructed topological boundary conditions in non-Abelian Chern-Simons

- ► Led to a subclass: R-defects
- Looked into their fusion
- Application to AdS<sub>3</sub>-gravity

 $\rightarrow$  What's next ?

- ► Can we identify the surface defect for Poisson-Lie T-duality ?
- Does the R-defect boundary make sense in higher spin 3d gravity
- SymTFT description ?

#### Thank you for you attention !