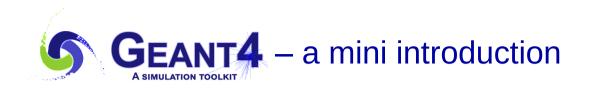
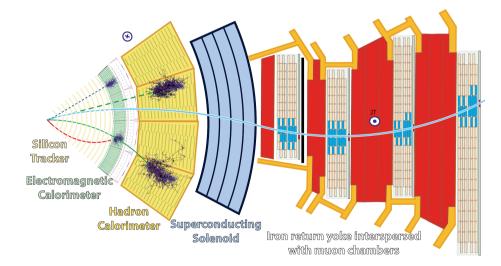
AdePT

accelerating GEANT4 applications on GPUs

Severin Diederichs on behalf of the AdePT team



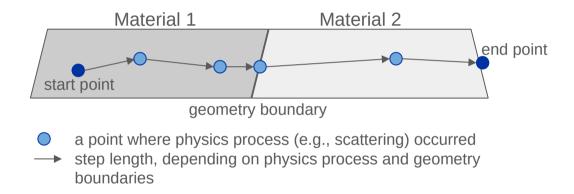
Monte-Carlo particle transport code. Backbone of detector simulation in HEP.



Also used in medical physics, space physics, accelerator physics, radiation protection...



Monte-Carlo particle transport code. Backbone of detector simulation in HEP.



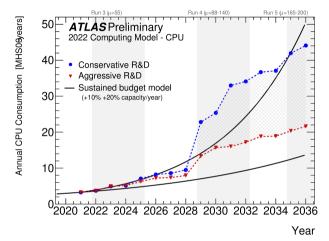
• Output: local energy deposition in detector

Detector does not change within a single run Particles do not interact with each other during transport (in detector)

Daunting evolution of required compute resources for the LHC

High-Lumi upgrade in 2028:

- higher statistics in simulations needed (more particles)
- simulations more expensive due to upgraded, finer detectors



Daunting evolution of required compute resources for the LHC

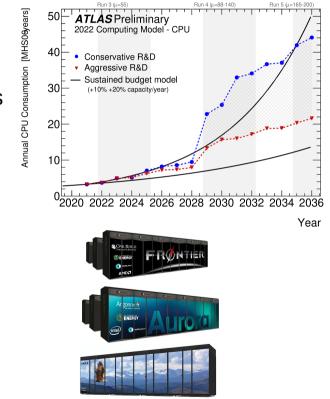
High-Lumi upgrade in 2028:

- higher statistics in simulations needed (more particles)
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Paradigm shift in supercomputing landscape:

17/20 of the top500 are GPU-based (NVIDIA, AMD, Intel)20/20 of the green500 are GPU-based

GEANT4 needs to be ported to GPU to keep up with current technology



A challenging, embarrassingly parallel problem

Huge amount of **divergence** between simulated particles due to **different geometry** and **different physics processes**

first approach: only port electromagnetic part to GPU (less complex physics, large fraction of compute time in LHC experiments)

A challenging, embarrassingly parallel problem

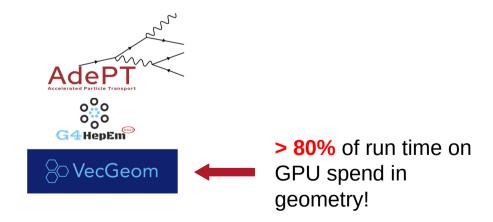
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Code structure:

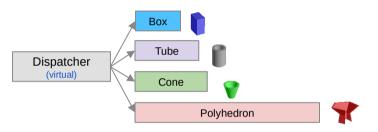
AdePT (track management etc)

- G4HepEm (electromagnetic physics)
- VecGeom (geometry)



Mitigating the Geometry bottleneck

Default solid model:

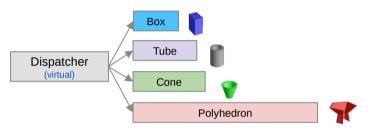


High divergence, recursive calls, virtual calls, high register usage

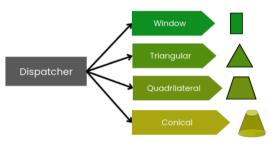
Not suited for GPUs!

Mitigating the Geometry bottleneck

Default solid model:



New surface model:



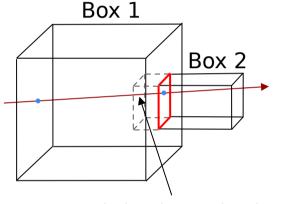
High divergence, recursive calls, virtual calls, high register usage

Not suited for GPUs!

Reduced divergence, no recursive calls, no virtual calls, simpler code

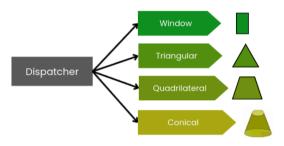
Better suited for GPUs

New model brings new challenges



Missing the overlapping entering surface leads to missing Box 2 entirely

New surface model:



Reduced divergence, no recursive calls, no virtual calls, simpler code

Better suited for GPUs

Conclusions

Despite being an embarrassingly parallel problem with millions of rays, this is an extremely challenging problem for GPUs due to code complexity, inevitable divergence, and poor memory access patterns.

Next steps:

- use of mixed precision to accelerate on GPU
- improve scheduling of tracks
- add portability:

AdePT, VecGeom, G4HepEm mostly header-based code + some CUDA

SYCL, Kokkos?