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Optimisation of muon tomography scanners for border controls using TomOpt Zahraa Zaher on behalf of TomOpt Collaboration Center for Cosmology, Particle Physics and Phenomenology, UCLouvain (Belgium)

UCLouvain

Silent

Border

Muon Tomography: An Overview

- Primary cosmic ray protons interact with nuclei of Earth's upper atmosphere
- Secondary cosmic ray particles produced (π[±])

$$\blacktriangleright \pi^{\pm} \to \mu^{\pm} + \nu_{\mu}(\bar{\nu}_{\mu})$$



Muon Tomography: An Overview



scattering angle distribution $(\sigma_{\theta_0}) \rightarrow$ material identification (X_0)

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-Initial detector parameters: position, area -Passive volume (red) with true assigned voxel-wise X₀ Muons generation
Hits recorded in detector panels
Scattering model used to propagate muons in passive volume in short steps of *O*(1 *cm*)

TomOpt: Muon Scattering Tomography Optimisation





- Tracking of reco hits
- Point-of-closest-approach of incoming/outgoing tracks

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- Extended PoCA pdf \rightarrow PoCA prob per voxel
- Muon batch per voxel \rightarrow RMS of
- PoCA variables for each voxel
- Volume X_0 inference by inversion of approximated Eq.(1)



Backpropagation and parameter update

- Differential optimisation = minimisation of loss function $\mathcal{L}(a_n)$ where a_n : detector parameters
- $\mathcal{L}(a_n) = \text{inference error} + \text{constraints}$
- Gradient descent : $a_{n+1} = a_n \gamma \cdot \nabla \mathcal{L}(a_n)$



Industrial application: Fill height estimation of furnace ladle



- 1st TomOpt publication (Giles C Strong et al. 2024 Mach. Learn.: Sci. Technol. 5 035002)
- Molten metal transferred to furnace with ladle
- Slag formation prevents optical methods to estimate fill height of liquid metal
- ► Insufficient metal → partially filled moulds
- ► Too much metal → formation of scraps
- ► Fill level inference using ZPoCA

Application on cargo scanning (Dev)

- Silent Border project (https://silentborder.eu/): muon tomography scanners for border controls
- modular design: hodoscope containing detector panels





- hodoscope unit instead of panels
- Detector parameters: hodoscope position
- Panels are fixed inside hodoscopes

Inference method

- ► For cargo scanning, need to infer volume material → X₀ inference using weighted RMS of PoCA variables
- Volume X₀ prediction is 'good' for high-Z materials with low-Z background



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Inference method

- Volume X₀ prediction is 'good' for high-Z materials with low-Z background
- Systematic bias towards lower values



Fluctuations in MSE loss = $\frac{1}{n} \sum_{i=1}^{n} (true_{X_0} - pred_{X_0})^2$



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Binned clustering algorithm (BCA)

A binned clustering algorithm to detect high-Z material using cosmic muons (C Thomay et al. 2013 JINST 8 P10013)

For each voxel *k* in passive volume:

- Select n_{max} = 40 PoCA's with largest θ_{scatter}
- ► For *i*, *j* in voxel *k*:
 - Calculate $m_{ij} = \frac{||\overrightarrow{poca_i} - \overrightarrow{poca_j}||}{\theta_i \theta_i}$
 - Fill histogram with $ln(m_{ij})$
 - Take median of distribution
- ▶ Per voxel values → volume distribution



BCA weighted metric distributions



BCA predictions

- Passive volumes (with/without) U-blocks randomly generated
- Material is iron+beryllium+air blocks
- Uranium block randomly placed
- 100k muons generated



BCA predictions: no uranium block



BCA predictions: uranium block



Classification of BCA volume predictions

- 100 volumes randomly generated with equiprobability of containing uranium
- background materials: iron+air
- n_{muons} = 100,000 (resampling of muons that do not cross the volume)
- discriminator of each volume

 minimum of the
 distribution of
 median(weighted_{metric})
- powerful classification (AUC = 1)



Optimisation with BCA classification

- Binary-cross-entropy loss function
- target (truth) = 0 (no U) / 1 (U)
- discriminator passed to a sigmoid activation function



initial detector configuration upper hodoscope at x = y = 0(on other side of U-block)

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Optimisation with BCA classification



evolution of loss over 20 epochs (first 5 are warm-up epochs where hodoscope positions are not updated)



final detector configuration

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Optimisation (upper hodoscope above U-block)



upper hodoscope at x = y = 1.5m

Optimisation with BCA classification



evolution of loss over 20 epochs (first 5 are warm-up epochs where hodoscope positions are not updated)



final detector configuration (same as initial one)

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How to correct gradient behaviour?

Possible solution/ongoing study

- ► Extended PoCA pdf G(xyz, xyzunc) → per voxel probability of PoCA's
- For each voxel j:
 - All PoCA points are taken
 - PoCA weight = PoCA probability in voxel j \times muon efficiency
 - score of voxel is 'weighted median'
- $100k \text{ muons} \rightarrow 1000 \text{ muons}$ (comparable computation time)

BCA with Extended PoCA

Centered upper hodoscope



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BCA with Extended PoCA

Off-centered upper hodoscope



BCA with Extended PoCA

Off-centered upper hodoscope



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Conclusion

- TomOpt optimisation is inference-aware and fully-differentiable
- Studying different inference methods for better optimisation performance
- BCA classification shows good discrimination of U-lorry volumes
- Using extended PoCA pdf may improve gradient behaviour
- work in progress...

Thank you for your attention! Any questions?

Backup Slides



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