

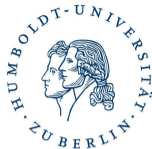
# Derivative-based Optimization for Applications in Physics

Andrea Walther  
Institut für Mathematik  
Humboldt-Universität zu Berlin and ZIB

Keynote Lecture  
4th MODE Workshop on Differentiable Programming for Experimental Design  
September 24, 2024

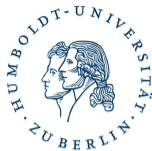
Berlin Mathematics Research Center

**MATH+**



# Outline

- 1 Calculation of Derivatives
- 2 Introduction to Algorithmic Differentiation
  - Forward Mode of AD
  - Backpropagation aka Reverse Mode AD
- 3 Applications in Physics
  - Identification of Parameters for Piezoceramics
  - Optimization for Nano-optics
  - Sensitivities Near Exceptional Points
- 4 Conclusion

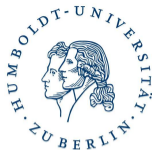


## Where are Derivatives Needed?

- Optimization:

unbounded:  $\min f(x), \quad f : \mathbb{R}^n \rightarrow \mathbb{R}$

bounded:  $\min f(x), \quad f : \mathbb{R}^n \rightarrow \mathbb{R}, \quad c(x) = 0, \quad c : \mathbb{R}^n \rightarrow \mathbb{R}^m, \quad h(x) \leq 0, \quad h : \mathbb{R}^n \rightarrow \mathbb{R}^l$



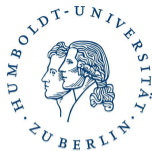
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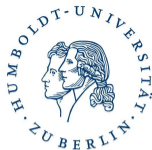
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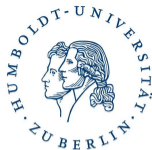
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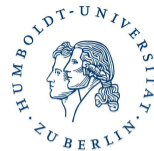
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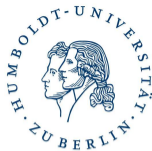
- Real-time control

- ML, e.g., Stochastic Gradient Descent, Adam, ...  
target functions quite often nonsmooth!

# Frequent Situation





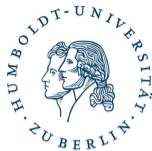


# Computing Derivatives

## Given:

Description of functional relation as

- formula  $y = F(x)$   $\Rightarrow$  explicit expression  $y' = F'(x)$
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## Task:

Computation of derivatives taking

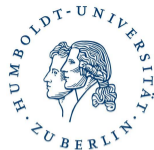
- requirements on exactness
- computational effort

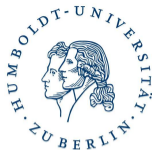
into account

# Algorithmic Differentiation (AD)

aka Automatic Differentiation

= Differentiation of computer programs implementing  $F : \mathbb{R}^n \mapsto \mathbb{R}^m$





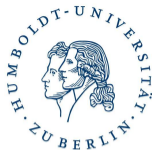
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- Quantitative dependence information (local):
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  - Error and condition number estimates . . .
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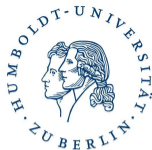
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# Algorithmic Differentiation (AD)

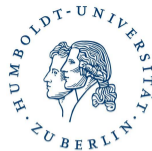
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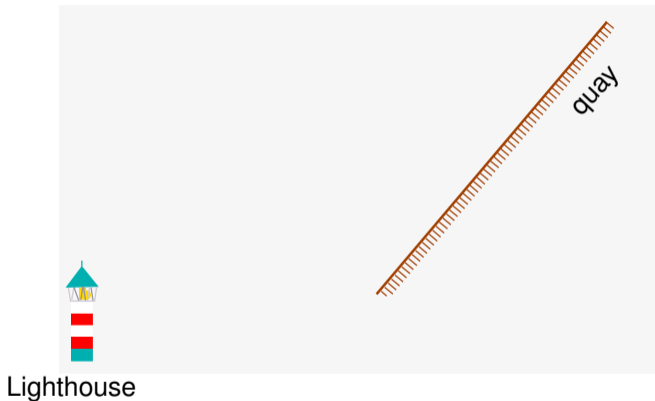
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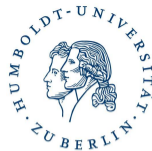
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Assumption:  $F$  differentiable in a neighbourhood of current argument  $x$

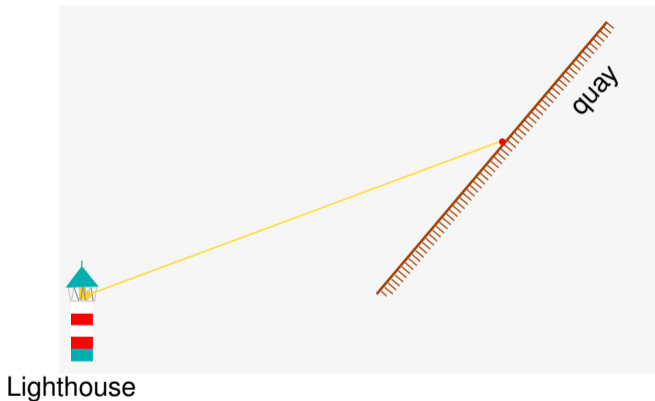


# The “Hello-World”-Example of AD

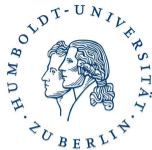




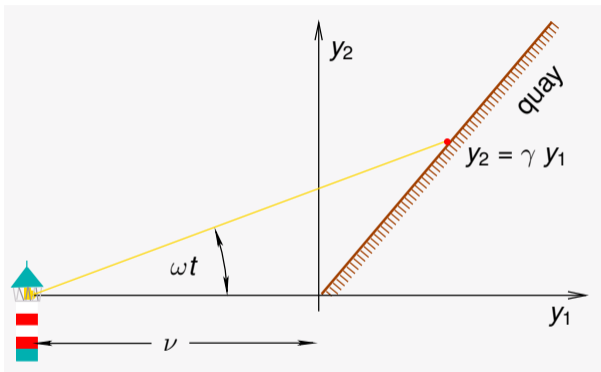
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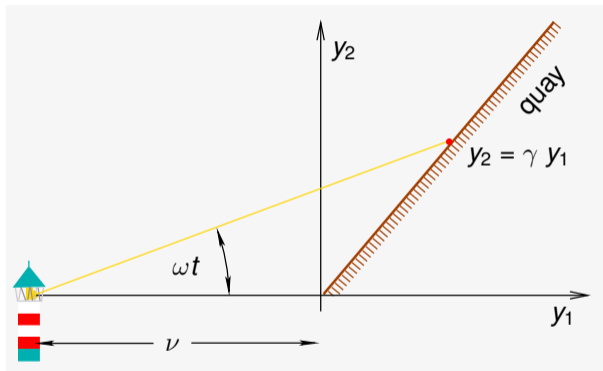


## The “Hello-World”-Example of AD



Lighthouse

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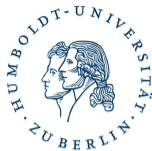


Lighthouse

$$y_1 = \frac{\nu \tan(\omega t)}{\gamma - \tan(\omega t)}$$

and

$$y_2 = \frac{\gamma \nu \tan(\omega t)}{\gamma - \tan(\omega t)}$$



## Evaluation Procedure (Lighthouse)

$$y_1 = \frac{\nu \tan(\omega t)}{\gamma - \tan(\omega t)}$$

$$y_2 = \frac{\gamma \nu \tan(\omega t)}{\gamma - \tan(\omega t)}$$

 $\Rightarrow$ 

$$V_{-3} = X_1 = \nu$$

$$V_{-2} = X_2 = \gamma$$

$$V_{-1} = X_3 = \omega$$

$$V_0 = X_4 = t$$

$$V_1 = V_{-1} * V_0 \equiv \varphi_1(V_{-1}, V_0)$$

$$V_2 = \tan(V_1) \equiv \varphi_2(V_1)$$

$$V_3 = V_{-2} - V_2 \equiv \varphi_3(V_{-2}, V_2)$$

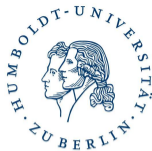
$$V_4 = V_{-3} * V_2 \equiv \varphi_4(V_{-3}, V_2)$$

$$V_5 = V_4 / V_3 \equiv \varphi_5(V_4, V_3)$$

$$V_6 = V_5 * V_{-2} \equiv \varphi_6(V_5, V_{-2})$$

$$y_1 = V_5$$

$$y_2 = V_6$$

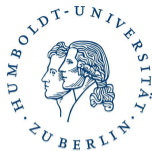


# Function Evaluation in ML

Typical function evaluation (deep neural net):

Propagation of one data point:

$$\begin{aligned}x &= x^{(1)} \rightarrow \tilde{x}^{(1)} = W^{(1)}x^{(1)} + b^{(1)} && \rightarrow x^{(2)} = \rho(\tilde{x}^{(1)}) \\ &\rightarrow \tilde{x}^{(2)} = W^{(2)}x^{(2)} + b^{(2)} && \rightarrow x^{(3)} = \rho(\tilde{x}^{(2)}) \\ &\rightarrow \dots \\ &\rightarrow y = W^{(k)}x^{(k)} + b^{(k)}\end{aligned}$$



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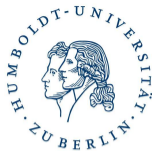
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Empirical risk, loss function, ...

$$f(x_{1 \leq i \leq M}) = \frac{1}{M} \sum_{i=1}^M l(y_i(x_i), y_i^{NN})$$



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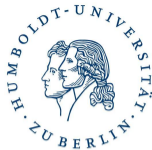
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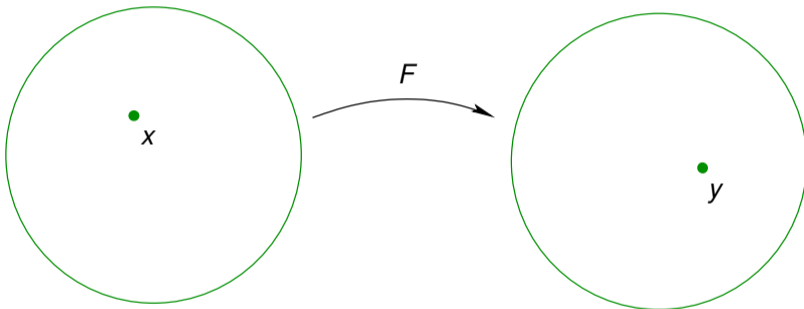
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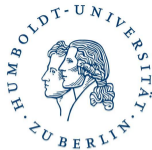
Stochastic gradient descent requires

$$\nabla_{W^1, b^1, \dots, W^k, b^k} l(y_i(x_i), y_i^{NN})$$

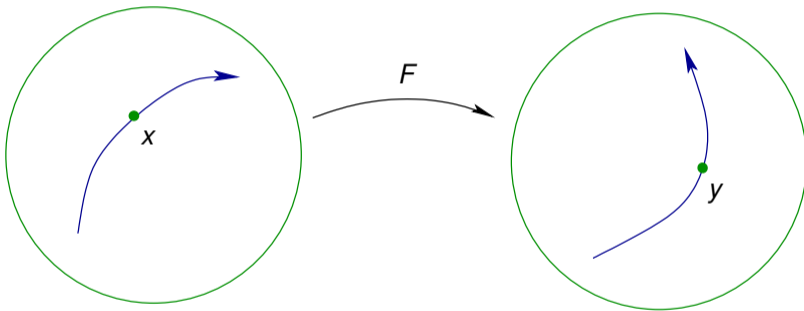


# Forward mode AD = Tangents/Sensitivities

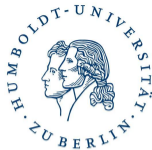




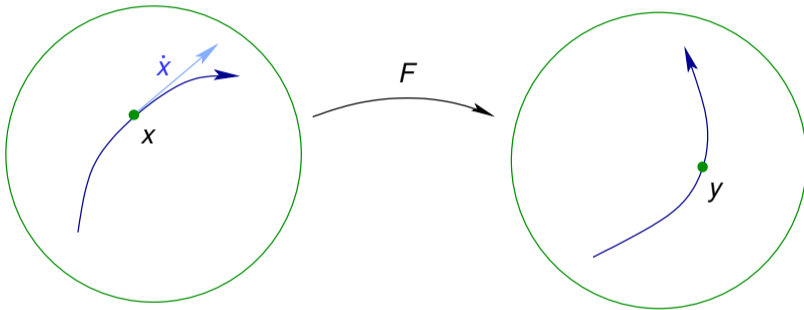
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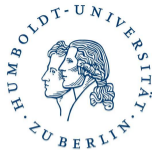




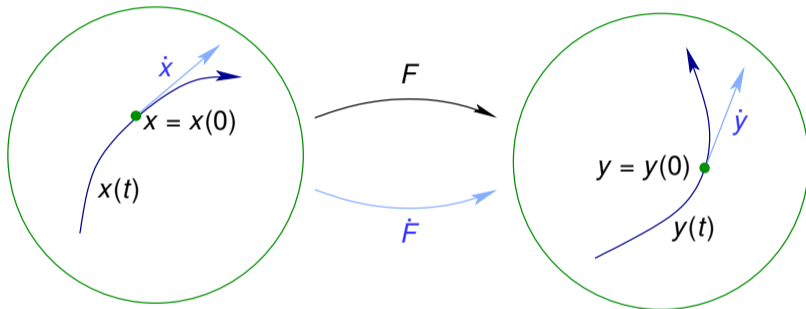


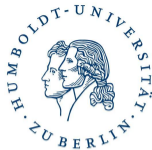
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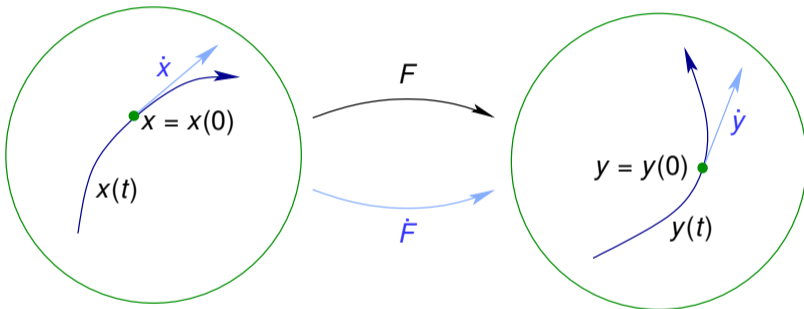


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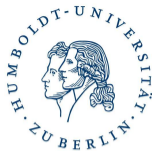




# Forward mode AD = Tangents/Sensitivities



$$\dot{y}(t) = \frac{\partial}{\partial t} F(x(t)) = F'(x(t)) \dot{x}(t) \equiv \dot{F}(x, \dot{x})$$



## Forward Mode (Lighthouse)

$$V_{-3} = X_1 = \nu$$

$$V_{-2} = X_2 = \gamma$$

$$V_{-1} = X_3 = \omega$$

$$V_0 = X_4 = t$$

---


$$V_1 = V_{-1} * V_0$$

$$V_2 = \tan(V_1)$$

$$V_3 = V_{-2} - V_2$$

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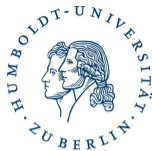
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---


$$y_1 = V_5$$

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 v_0 & = x_4 = t & \dot{v}_0 & = \dot{x}_4
 \end{array}$$


---

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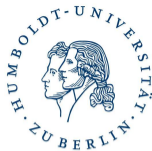
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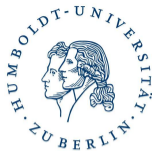
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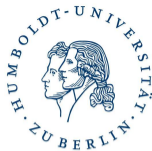
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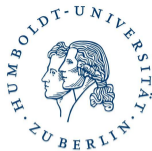
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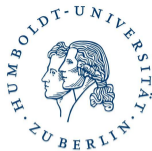
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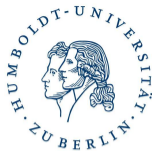
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$V_5 = V_4 / V_3$	
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$y_1 = V_5$	
$y_2 = V_6$	



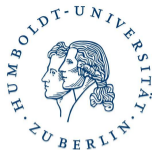
## Forward Mode (Lighthouse)

$V_{-3} = X_1 = \nu$	$\dot{V}_{-3} = \dot{X}_1$
$V_{-2} = X_2 = \gamma$	$\dot{V}_{-2} = \dot{X}_2$
$V_{-1} = X_3 = \omega$	$\dot{V}_{-1} = \dot{X}_3$
$V_0 = X_4 = t$	$\dot{V}_0 = \dot{X}_4$
$V_1 = V_{-1} * V_0$	$\dot{V}_1 = \dot{V}_{-1} * V_0 + V_{-1} * \dot{V}_0$
$V_2 = \tan(V_1)$	$\dot{V}_2 = \dot{V}_1 / \cos(V_1)^2$
$V_3 = V_{-2} - V_2$	$\dot{V}_3 = \dot{V}_{-2} - \dot{V}_2$
$V_4 = V_{-3} * V_2$	$\dot{V}_4 = \dot{V}_{-3} * V_2 + V_{-3} * \dot{V}_2$
$V_5 = V_4 / V_3$	$\dot{V}_5 = (\dot{V}_4 - \dot{V}_3 * V_5) * (1 / V_3)$
$V_6 = V_5 * V_{-2}$	
$y_1 = V_5$	
$y_2 = V_6$	



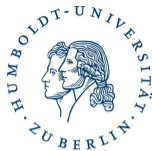
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$V_0 = X_4 = t$	$\dot{V}_0 = \dot{X}_4$
$V_1 = V_{-1} * V_0$	$\dot{V}_1 = \dot{V}_{-1} * V_0 + V_{-1} * \dot{V}_0$
$V_2 = \tan(V_1)$	$\dot{V}_2 = \dot{V}_1 / \cos(V_1)^2$
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$V_4 = V_{-3} * V_2$	$\dot{V}_4 = \dot{V}_{-3} * V_2 + V_{-3} * \dot{V}_2$
$V_5 = V_4 / V_3$	$\dot{V}_5 = (\dot{V}_4 - \dot{V}_3 * V_5) * (1 / V_3)$
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$y_1 = V_5$	
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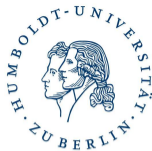
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$V_4 = V_{-3} * V_2$	$\dot{V}_4 = \dot{V}_{-3} * V_2 + V_{-3} * \dot{V}_2$
$V_5 = V_4 / V_3$	$\dot{V}_5 = (\dot{V}_4 - \dot{V}_3 * V_5) * (1 / V_3)$
$V_6 = V_5 * V_{-2}$	$\dot{V}_6 = \dot{V}_5 * V_{-2} + V_5 * \dot{V}_{-2}$
$y_1 = V_5$	$\dot{y}_1 = \dot{V}_5$
$y_2 = V_6$	$\dot{y}_2 = \dot{V}_6$



## Complexity (Forward Mode)

tang	$c$	$\pm$	$*$	$\psi$
MOVES	1 + 1	3 + 3	3 + 3	2 + 2
ADDS	0	1 + 1	0 + 1	0 + 0
MULTS	0	0	1 + 2	0 + 1
NLOPS	0	0	0	1 + 1



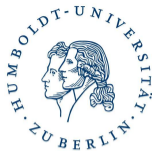
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MULTS	0	0	1 + 2	0 + 1
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$$\text{OPS}(F'(x)\dot{x}) \leq c \text{ OPS}(F(x))$$

with  $c \in [2, 5/2]$  platform dependent

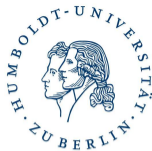


# Forward Mode AD for ML

Typical function evaluation (deep neural net):

$$x = x^{(1)} \rightarrow \tilde{x}^{(1)} = W^{(1)}x^{(1)} + b^{(1)} \rightarrow x^{(2)} = \rho(\tilde{x}^{(1)}) \dots \rightarrow y = W^{(k)}x^{(k)} + b^{(k)}$$

Attention: Optimization variables  $W$  and  $b$   $\Rightarrow$  AD computes  $\dot{W}$  and  $\dot{b}$ !



## Forward Mode AD for ML

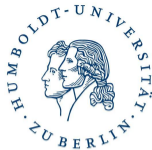
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Attention: Optimization variables  $W$  and  $b$   $\Rightarrow$  AD computes  $\dot{W}$  and  $\dot{b}$ !

$$\begin{aligned} x = x^{(1)} \rightarrow \tilde{x}^{(1)} = W^{(1)}x^{(1)} + b^{(1)} &\rightarrow x^{(2)} = \rho(\tilde{x}^{(1)}) \\ \dot{\tilde{x}}^{(1)} = \dot{W}^{(1)}x^{(1)} + \dot{b}^{(1)} &\rightarrow \dot{x}^{(2)} = \rho'(\tilde{x}^{(1)})\dot{\tilde{x}}^{(1)} \end{aligned}$$





## Forward Mode AD for ML

Typical function evaluation (deep neural net):

$$x = x^{(1)} \rightarrow \tilde{x}^{(1)} = W^{(1)}x^{(1)} + b^{(1)} \rightarrow x^{(2)} = \rho(\tilde{x}^{(1)}) \dots \rightarrow y = W^{(k)}x^{(k)} + b^{(k)}$$

Attention: Optimization variables  $W$  and  $b \Rightarrow$  AD computes  $\dot{W}$  and  $\dot{b}$ !

$$x = x^{(1)} \rightarrow \tilde{x}^{(1)} = W^{(1)}x^{(1)} + b^{(1)} \rightarrow x^{(2)} = \rho(\tilde{x}^{(1)})$$

$$\dot{\tilde{x}}^{(1)} = \dot{W}^{(1)}x^{(1)} + \dot{b}^{(1)} \rightarrow \dot{x}^{(2)} = \rho'(\tilde{x}^{(1)})\dot{\tilde{x}}^{(1)}$$

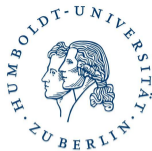
$$\rightarrow \tilde{x}^{(2)} = W^{(2)}x^{(2)} + b^{(2)} \rightarrow x^{(3)} = \rho(\tilde{x}^{(2)})$$

$$\dot{\tilde{x}}^{(2)} = \dot{W}^{(2)}x^{(2)} + W^{(2)}\dot{x}^{(2)} + \dot{b}^{(2)} \rightarrow \dot{x}^{(3)} = \rho'(\tilde{x}^{(2)})\dot{\tilde{x}}^{(2)}$$

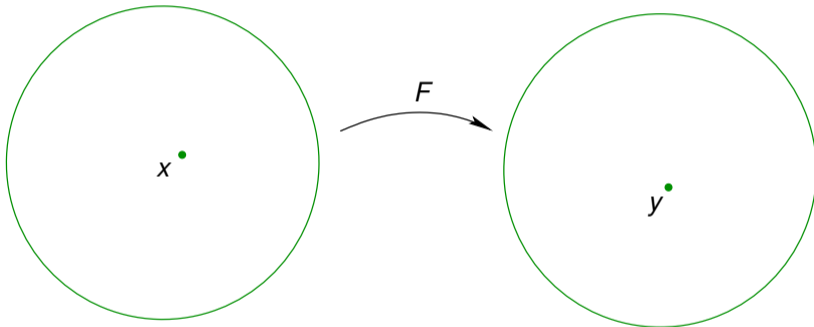
$\rightarrow \dots$

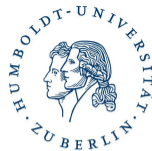
$$\rightarrow y = W^{(k)}x^{(k)} + b^{(k)}$$

$$\rightarrow \dot{y} = \dot{W}^{(k)}x^{(k)} + W^{(k)}\dot{x}^{(k)} + \dot{b}^{(k)}$$

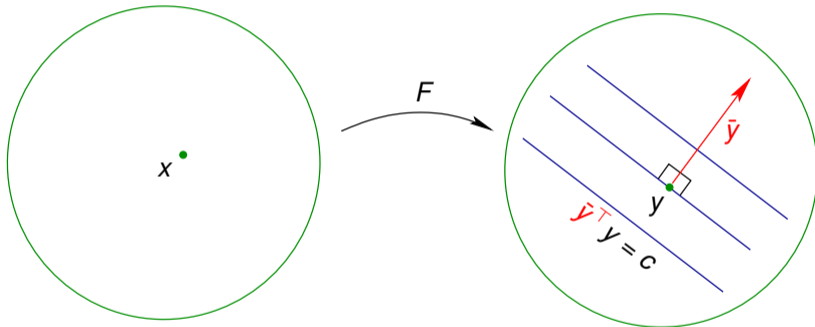


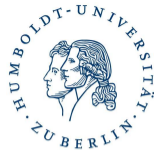
# Reverse Mode AD = Discrete Adjoint



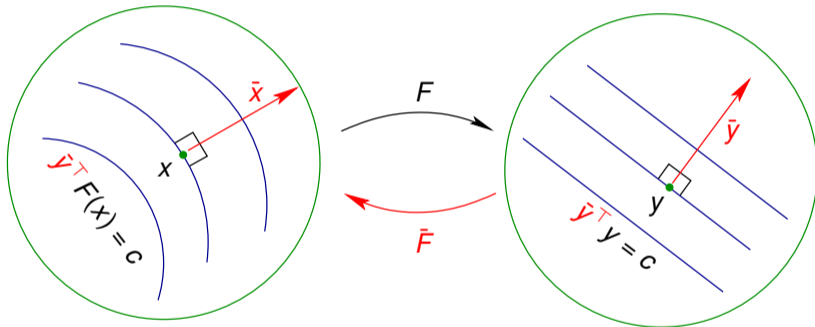


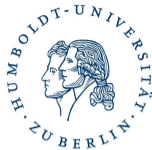
# Reverse Mode AD = Discrete Adjoint



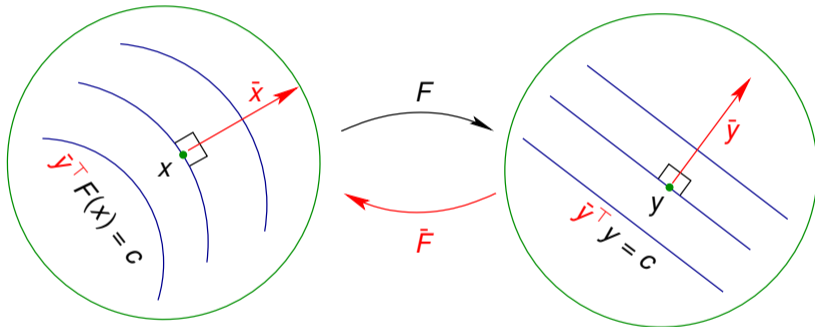


# Reverse Mode AD = Discrete Adjoint

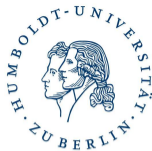




# Reverse Mode AD = Discrete Adjoint



$$\bar{x} \equiv \bar{y}^T F'(x) = \nabla_x \langle \bar{y}^T F(x) \rangle \equiv \bar{F}(x, \bar{y})$$



## Reverse Mode (Lighthouse)

$$V_{-3} = X_1; \quad V_{-2} = X_2; \quad V_{-1} = X_3; \quad V_0 = X_4;$$

$$V_1 = V_{-1} * V_0;$$

$$V_2 = \tan(V_1);$$

$$V_3 = V_{-2} - V_2;$$

$$V_4 = V_{-3} * V_2;$$

$$V_5 = V_4 / V_3;$$

$$V_6 = V_5 * V_{-2};$$

$$y_1 = V_5; \quad y_2 = V_6;$$

$$\bar{V}_5 = \bar{y}_1; \quad \bar{V}_6 = \bar{y}_2;$$

$$\bar{V}_5 += \bar{V}_6 * V_{-2}; \quad \bar{V}_{-2} += \bar{V}_6 * V_5;$$

$$\bar{V}_4 += \bar{V}_5 / V_3; \quad \bar{V}_3 -= \bar{V}_5 * V_5 / V_3;$$

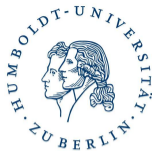
$$\bar{V}_{-3} += \bar{V}_4 * V_2; \quad \bar{V}_2 += \bar{V}_4 * V_{-3};$$

$$\bar{V}_{-2} += \bar{V}_3; \quad \bar{V}_2 -= \bar{V}_3;$$

$$\bar{V}_1 += \bar{V}_2 / \cos^2(V_1);$$

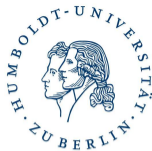
$$\bar{V}_{-1} += \bar{V}_1 * V_0; \quad \bar{V}_0 += \bar{V}_1 * V_{-1};$$

$$\bar{X}_4 = \bar{V}_0; \quad \bar{X}_3 = \bar{V}_{-1}; \quad \bar{X}_2 = \bar{V}_{-2}; \quad \bar{X}_1 = \bar{V}_{-3};$$



## Complexity (Reverse Mode)

grad	$c$	$\pm$	$*$	$\psi$
MOVES	1 + 1	3 + 6	3 + 8	2 + 5
ADDS	0	1 + 2	0 + 2	0 + 1
MULTS	0	0	1 + 2	0 + 1
NLOPS	0	0	0	1 + 1



## Complexity (Reverse Mode)

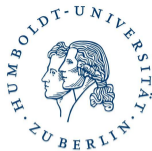
grad	$c$	$\pm$	$*$	$\psi$
MOVES	1 + 1	3 + 6	3 + 8	2 + 5
ADDS	0	1 + 2	0 + 2	0 + 1
MULTS	0	0	1 + 2	0 + 1
NLOPS	0	0	0	1 + 1



$$\text{OPS}(\bar{y}^\top F'(x)) \leq c \text{OPS}(F(x)), \quad \text{MEM}(\bar{y}^\top F'(x)) \sim \text{OPS}(F(x))$$

with  $c \in [3, 4]$  platform dependent





## Complexity (Reverse Mode)

grad	$c$	$\pm$	$*$	$\psi$
MOVES	1 + 1	3 + 6	3 + 8	2 + 5
ADDS	0	1 + 2	0 + 2	0 + 1
MULTS	0	0	1 + 2	0 + 1
NLOPS	0	0	0	1 + 1

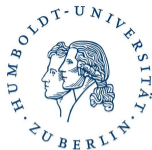


$$\text{OPS}(\bar{y}^\top F'(x)) \leq c \text{OPS}(F(x)), \quad \text{MEM}(\bar{y}^\top F'(x)) \sim \text{OPS}(F(x))$$

with  $c \in [3, 4]$  platform dependent

### Remarks:

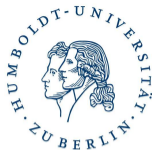
- Cost for gradient calculation independent of  $n$
- Memory requirement may cause problem!  $\Rightarrow$  Checkpointing



## Reverse Mode AD for ML

Typical function evaluation (deep neural net):

$$\begin{aligned}x &= x^{(1)} \rightarrow \tilde{x}^{(1)} = W^{(1)}x^{(1)} + b^{(1)} && \rightarrow x^{(2)} = \rho(\tilde{x}^{(1)}) \\ &\rightarrow \tilde{x}^{(2)} = W^{(2)}x^{(2)} + b^{(2)} && \rightarrow x^{(3)} = \rho(\tilde{x}^{(2)}) \\ &\rightarrow \dots \\ &\rightarrow y = W^{(k)}x^{(k)} + b^{(k)}\end{aligned}$$



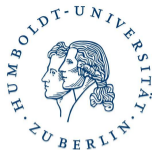
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 &\rightarrow \tilde{x}^{(2)} = W^{(2)}x^{(2)} + b^{(2)} && \rightarrow x^{(3)} = \rho(\tilde{x}^{(2)}) \\
 &\rightarrow \dots \\
 &\rightarrow y = W^{(k)}x^{(k)} + b^{(k)}
 \end{aligned}$$

With  $\bar{y} = 1$  one obtains

$$\bar{W}^{(k)} = [x^{(k)}], \quad \bar{x}^{(k)} = W^{(k)}, \quad \bar{b}^{(k)} = \mathbb{1}, \dots$$



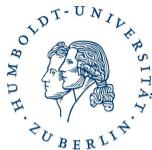
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Typical function evaluation (deep neural net):

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 &\rightarrow \dots \\
 &\rightarrow y = W^{(k)}x^{(k)} + b^{(k)}
 \end{aligned}$$

With  $\bar{y} = 1$  one obtains

$$\begin{aligned}
 \bar{W}^{(k)} &= [x^{(k)}], & \bar{x}^{(k)} &= W^{(k)}, & \bar{b}^{(k)} &= \mathbb{1} & , \dots \\
 \bar{\tilde{x}}^{(2)} &= \rho'(x^{(2)}) * \bar{x}^{(3)}, & \bar{W}^{(2)} &= x^{(2)} * \bar{\tilde{x}}^{(2)}, & \bar{x}^{(2)} &= W^{(2)} * \bar{\tilde{x}}^{(2)}, & \bar{b}^{(2)} &= \bar{\tilde{x}}^{(2)} \\
 \bar{\tilde{x}}^{(1)} &= \rho'(x^{(1)}) * \bar{x}^{(2)}, & \bar{W}^{(1)} &= x^{(1)} * \bar{\tilde{x}}^{(1)}, & \bar{x}^{(1)} &= W^{(1)} * \bar{\tilde{x}}^{(1)}, & \bar{b}^{(1)} &= \bar{\tilde{x}}^{(1)}
 \end{aligned}$$



## Reverse Mode AD for ML

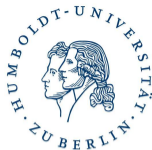
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 &\rightarrow \tilde{x}^{(2)} = W^{(2)}x^{(2)} + b^{(2)} && \rightarrow x^{(3)} = \rho(\tilde{x}^{(2)}) \\
 &\rightarrow \dots \\
 &\rightarrow y = W^{(k)}x^{(k)} + b^{(k)}
 \end{aligned}$$

With  $\bar{y} = 1$  one obtains

$$\begin{aligned}
 \bar{W}^{(k)} &= [x^{(k)}], & \bar{x}^{(k)} &= W^{(k)}, & \bar{b}^{(k)} &= \mathbb{1} & , \dots \\
 \bar{\tilde{x}}^{(2)} &= \rho'(x^{(2)}) * \bar{x}^{(3)}, & \bar{W}^{(2)} &= x^{(2)} * \bar{\tilde{x}}^{(2)}, & \bar{x}^{(2)} &= W^{(2)} * \bar{\tilde{x}}^{(2)}, & \bar{b}^{(2)} &= \bar{\tilde{x}}^{(2)} \\
 \bar{\tilde{x}}^{(1)} &= \rho'(x^{(1)}) * \bar{x}^{(2)}, & \bar{W}^{(1)} &= x^{(1)} * \bar{\tilde{x}}^{(1)}, & \bar{x}^{(1)} &= W^{(1)} * \bar{\tilde{x}}^{(1)}, & \bar{b}^{(1)} &= \bar{\tilde{x}}^{(1)}
 \end{aligned}$$

very simple to implement!

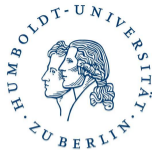


# Historical Development of AD

J. Nolan	1953	→	J. M. Thames et al.	1975	→
L. M. Beda et al.	1959	→	D. D. Warner	1975	→
A. Gibbons	1960	→			
J. W. Hanson et al.	1962	→	J. Joss	1980	→
R. E. Wengert	1964	→			
R. D. Wilkins	1964	→			
G. Wanner	1965	→	L. B. Rall	1980	→
R. Bellman et al.	1965	→			
Y. F. Chang	1967	→	R. Kalaba et al.	1983	→
D. Barton et al.	1971	→			
R. E. Pugh	1972	→			
			L. C. W. Dixon et al.	1986	→
			...		

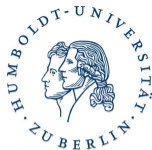
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A. Gibbons	1960	→	W. Miller	1975	←
J. W. Hanson et al.	1962	→	J. Joss	1980	→
R. E. Wengert	1964	→	G. Kedem	1980	←
R. D. Wilkins	1964	→	B. Speelpenning	1980	←
G. Wanner	1965	→	L. B. Rall	1980	→
R. Bellman et al.	1965	→	W. Baur, V. Strassen	1983	←
Y. F. Chang	1967	→	R. Kalaba et al.	1983	→
S. Linnainma	1970	←	M. Iri et al.	1984	←
D. Barton et al.	1971	→	K. W. Kim et al.	1984	←
G. M. Ostrowski	1971	←	J. W. Sawyer	1984	←
R. E. Pugh	1972	→			
W. Stacey	1973	←	L. C. W. Dixon et al.	1986	→
P. Werbos	1974	←	...		

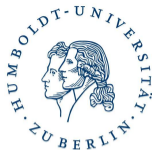


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S. Linnainma	1970	←	M. Iri et al.	1984	←
D. Barton et al.	1971	→	K. W. Kim et al.	1984	←
G. M. Ostrowski	1971	←	J. W. Sawyer	1984	←
R. E. Pugh	1972	→	E. M. Oblow et al.	1985	↔
W. Stacey	1973	←	L. C. W. Dixon et al.	1986	→
P. Werbos	1974	←	...		



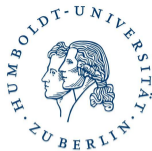




## Historical Development of AD

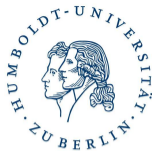
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D. Barton et al.	1971	→	K. W. Kim et al.	1984	←
G. M. Ostrowski	1971	←	J. W. Sawyer	1984	←
R. E. Pugh	1972	→	E. M. Oblow et al.	1985	↔
W. Stacey	1973	←	L. C. W. Dixon et al.	1986	→
P. Verbos	1974	←	...		

Rumelhart et al. (1986) made backpropagation famous for neural nets



# Overview AD Theory and Tools

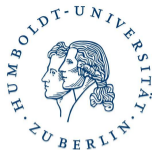
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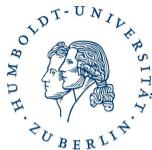
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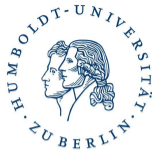
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= discrete analogon to sensitivity equation



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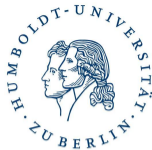


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= discrete analogon to adjoint equation

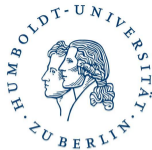


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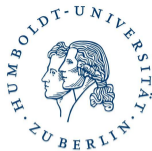
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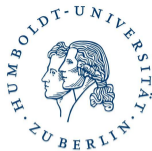
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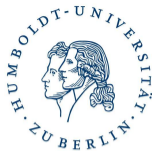
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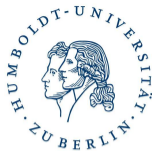
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(Griewank, Walther 2008), (Naumann 2012), [www.autodiff.org](http://www.autodiff.org)



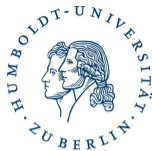
# Automatic Differentiation by OverLoading in C++

- ADOL-C version 2.7, available at COIN-OR since 2009, open source (GPL or ECL)
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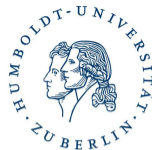
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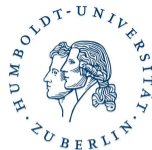
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- current developments
  - Julia interface ADOLC.jl
  - exploitation of fixed-point structure for second-order derivatives
  - generalized derivatives for nonsmooth functions



# Piezoelectricity

Fundamental properties:

- Transformation of **mechanical energy** into **electrical energy**
- Transformation of **electrical energy** into **mechanical energy**



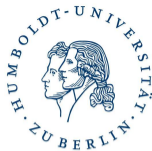
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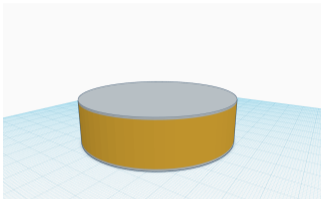
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Used in wide range of applications:  
Pressure Sensors, Ultrasonic Cleaning,  
Ultrasound Imaging, Piezoelectric Speakers,  
Electronic Toothbrushes, Instrument Pickups,  
Microphones, Piezoelectric Igniters,  
Electricity Generation, Tennis Racquets, ...



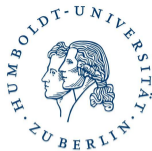
## The Considered Setting



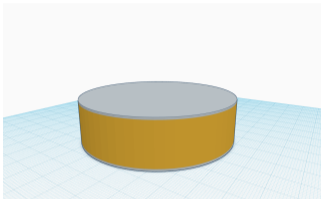
<https://www.piceramic.de/de/produkte/piezokeramische-baelemente/scheiben-staebe-und-zyllinder/piezoelektrische-scheiben-1206710/>

- Piezoceramics come in many shapes and sizes  
here: disk shaped ceramics (very popular, cheap(er) simulation)





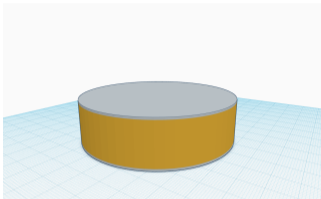
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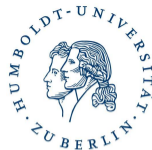
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Cooperation with Measurement Engineering Group, Prof. Henning, Univ Paderborn

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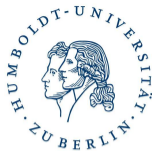
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- Here: Consider only small loads  $\Rightarrow$  Disregard thermal effects  
Nonlinear effects  $\Rightarrow$  DFG research group NEPTUN



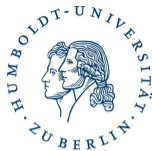
## Inverse Problem - State of the Art

- Sensitivity too small for some parameter  
(using conventional methods or data provided by manufacturer)  
Up to 20% error not uncommon



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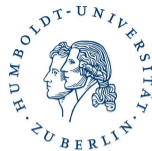
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⇒ Leads to inconsistent datasets
  - Use additional measurements of surface displacement  
⇒ Very expensive and still low sensitivity
  - Low sensitivity parameters are excluded from parameter identification



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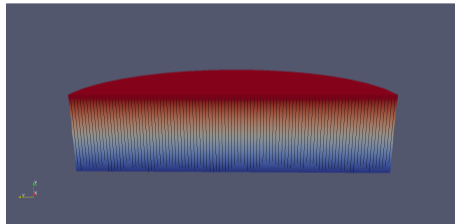
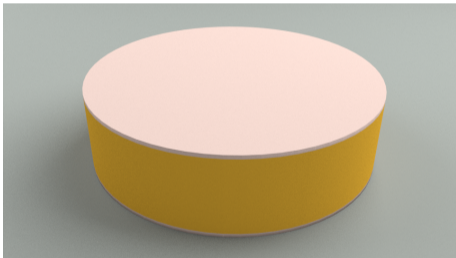
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**Goal:** Identify all parameters using a single piezoceramic and impedance measurements

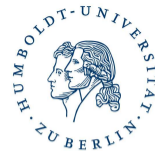


# AD-enabled Optimization of the Electrodes

Fully covering electrodes

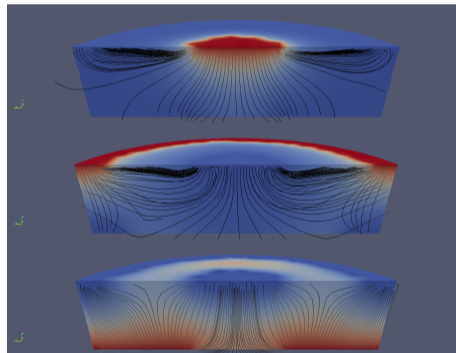
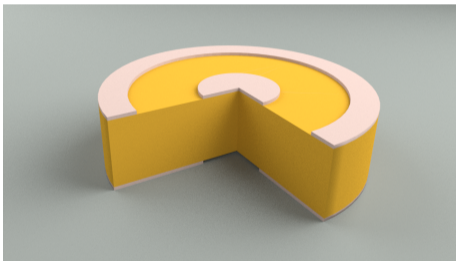


Thanks to B. Jurgelucks

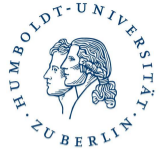


# AD-enabled Optimization of the Electrodes

## Triple-ring electrodes



Thanks to B. Jurgelucks



# Real Measurements

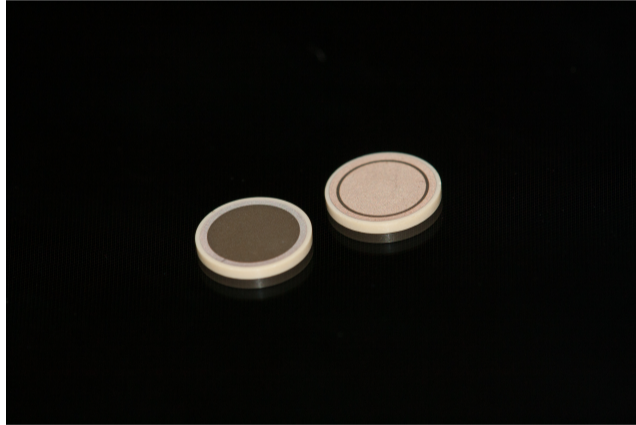
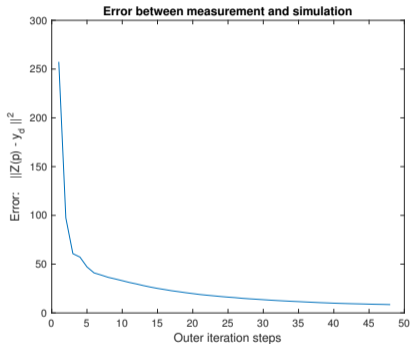
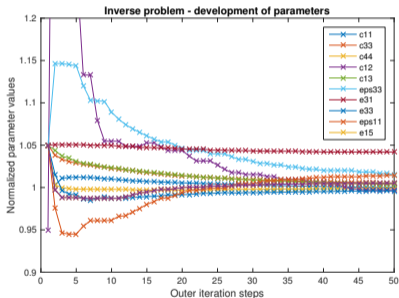


Photo by S. Olfert

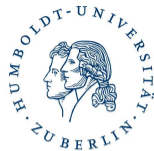




# Appropriate Version of AD-enabled Gauss-Newton Method



- None of the 10 (!) parameters diverges
- To the best of our knowledge this has not been possible with only one piezoceramic

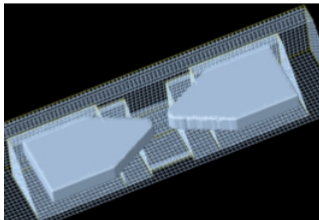


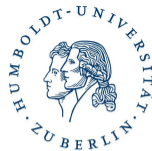
# Optical Nano-Structures

**State of the art:** Nano-structures are used to confine light

Simple example: Bow-tie antenna

- metallic nano structure
- two triangles and gap
- Size: 100 nm ( $< \lambda_{\text{light}}$ !)
- intensity enhancement in gap





# Possible Configurations

Simple setting:

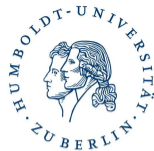
- different structure



- “simple” excitation



- pure metal
- extremely short dephasing



## Possible Configurations

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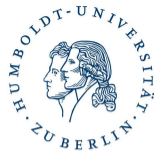


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Advanced setting:

- fixed structure





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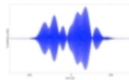
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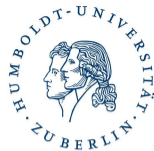
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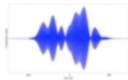
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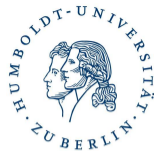
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- add resonances in semiconductors



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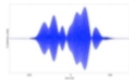
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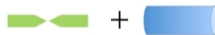
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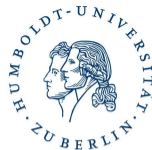


- sophisticated excitation



- add resonances in semiconductors
- longer dephasing





# Test Case: Quantum Wire

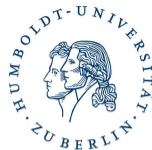
Cooperation with T. Meier, M. Reichelt, Dep. Physik, Uni Paderborn

Generic configuration:



← adaptable light puls  $E(t)$

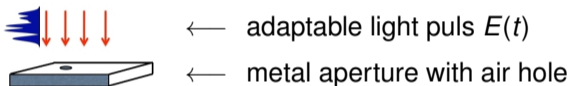


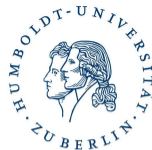


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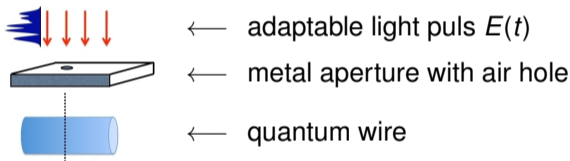


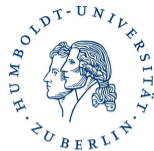


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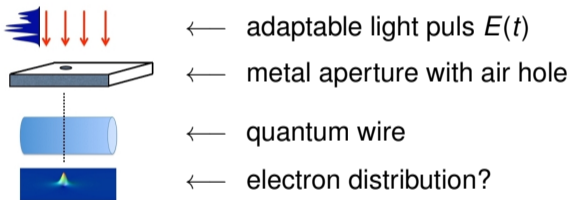




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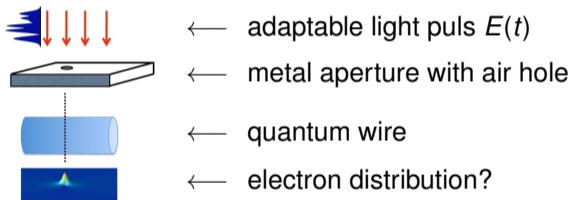
Generic configuration:



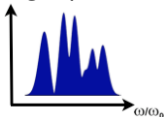
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Generic configuration:



Light puls:

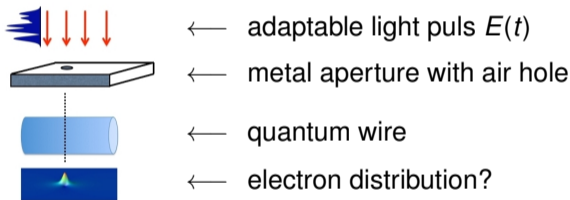


$$\text{with } E(t) = \sum A_i \exp\left(-\left(\frac{t-t_i}{\delta t_i}\right)^2\right) \cos(\omega_i t + \phi_i)$$

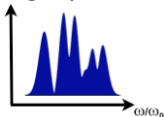
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Cooperation with T. Meier, M. Reichelt, Dep. Physik, Uni Paderborn

Generic configuration:

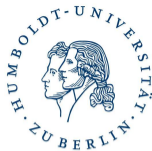


Light puls:



$$\text{with } E(t) = \sum A_i \exp\left(-\left(\frac{t-t_i}{\delta t_i}\right)^2\right) \cos(\omega_i t + \phi_i)$$

Parameter:  $A_i, \phi_i, \omega_i, t_i \Rightarrow$  up to 120!

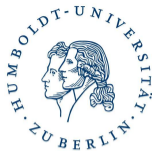


## Mathematical Formulation

**State equation:**

$$\begin{aligned}\frac{\partial}{\partial t} \rho &= \frac{i}{\hbar}(\epsilon_0 - \epsilon_1)\rho + \frac{i}{\hbar} \mathbf{E}(t) \cdot \mathbf{d} (n_0 - n_1) \\ \frac{\partial}{\partial t} n_0 &= \frac{2}{\hbar} \text{Im} [\mathbf{E}(t) \cdot \mathbf{d} \rho^*] \\ \frac{\partial}{\partial t} n_1 &= -\frac{2}{\hbar} \text{Im} [\mathbf{E}(t) \cdot \mathbf{d} \rho^*] \\ 1 &= n_1 + n_0\end{aligned}$$

⇒ Three complex-valued coupled differential equations  
 $\rho$ ,  $n_0$  and  $n_1$  distributed in space.



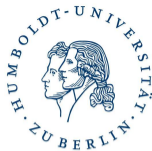
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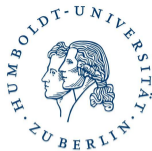
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= Maximize emitted radiation

$$I_{rad} = |\omega^2 P(\omega)|^2 = |\omega^2 2 \text{Re}(d p)|^2$$



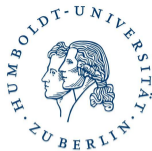


## Function Evaluation of $I_{rad}(f(g(x)))$

$x[] \leftarrow (\text{phase}[], \text{amplitude}[], \text{width}[], \text{point}[])$

```
for time=0 to Tfinal do
  if (time >= Tobs && time < Tobs+dt)
    eval_time_step1(x,int_tar)
  else
    eval_time_step2(x,int_tar)
  end if
end for
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eval\_target(int\_tar,fitness)



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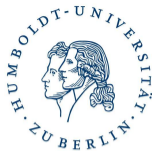
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# independents  $\in \{20, 60, 120\}$

$\Rightarrow$  Reverse mode!



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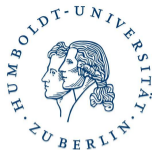
scenarios:

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$\Rightarrow$  Reverse mode!

# time steps  $\in \{16000, 32000, 160000\}$

$\Rightarrow$  Checkpointing!



# Quantum Wire: Optimization

**So far:** Genetic algorithms

**Now:** L-BFGS and efficient gradient computation

- ADOL-C coupled with hand-coded adjoints
- Checkpointing (160 000 time steps!!)

⇒  $\text{TIME}(\text{gradient})/\text{TIME}(\text{target function}) < 7$  despite of checkpointing!

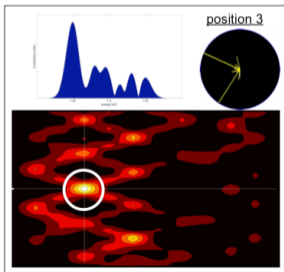
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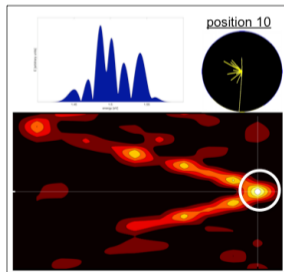


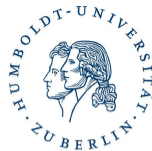
excite

- at **same** position
- at **same** time
- with **same** energy

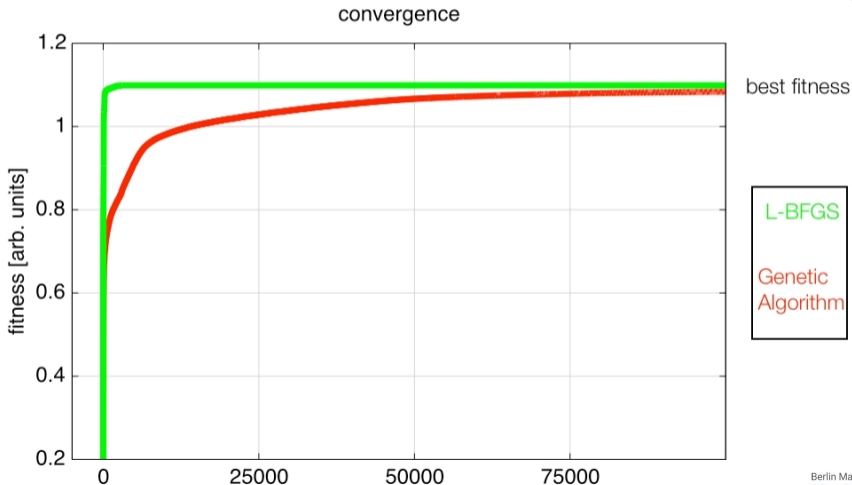
optimize

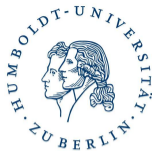
- for **same**  $t_{\text{opt}}$
- **different** positions





# Quantum Wire: Comparison



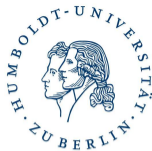


# Photonic Nano-Resonators

Joint work with F. Binkowski, J. Kullig, F. Betz, L. Zschiedrich, J. Wiersig, S. Burger

Applications:

- probing single molecules with ultrahigh sensitivity
- designing nanoantennas with a tailored directivity
- large spontaneous emission rate or realizing efficient single-photon sources



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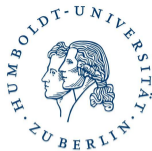
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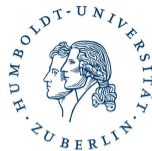
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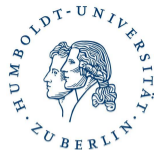
Further aspects:

- computed by solving the source-free Maxwell's equations
- sensitivities of resonances are of interest for
  - better understanding of the underlying physical effects
  - an efficient optimization of corresponding photonic devices



# Behaviour of Sensitivities at EPs

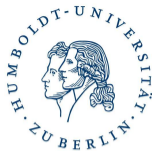
Exceptional points: spectral degeneracies  
(eigenfrequencies and eigenmodes coalesce)



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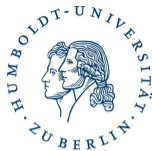
- parametric fine-tuning is needed to achieve such non-Hermitian degeneracies  
⇒ exceptional points (EPs)



# Behaviour of Sensitivities at EPs

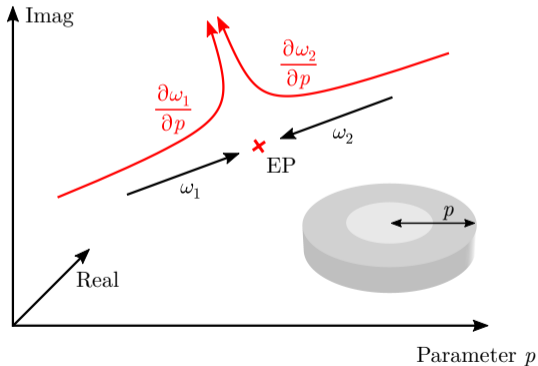
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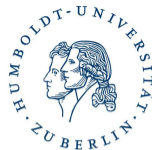
- parametric fine-tuning is needed to achieve such non-Hermitian degeneracies  
⇒ exceptional points (EPs)
- EPs have been connected to many interesting effects including
  - ultra-sensitive sensors
  - control of light transport
  - electromagnetically induced transparency
  - optical amplifiers, . . .



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Exceptional points: spectral degeneracies  
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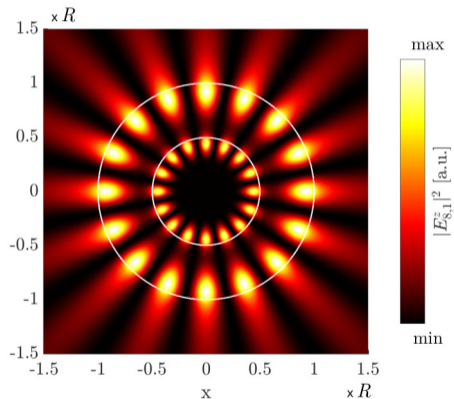
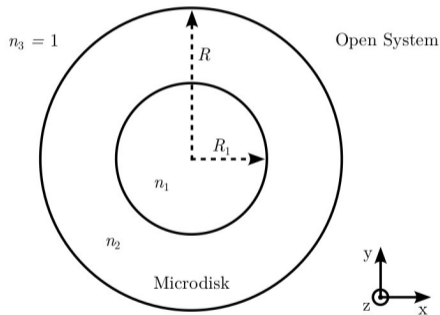




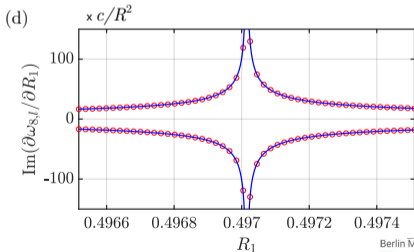
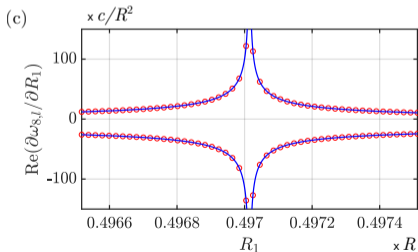
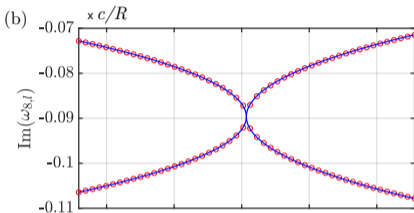
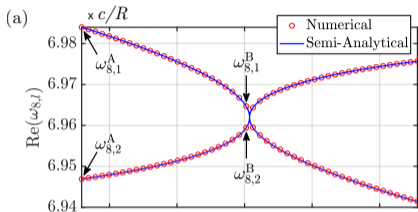
## Calculation of EPs and Their Sensitivities

- RPExpand  
Software for Riesz projection expansion of resonance phenomena  
by F. Betz, F. Binkowski, S. Burger
- JCMSuite  
part of JCMWave (commercial software)  
based on FEM combined with efficient contour-integral method  
implements own AD approach

# The Considered Setting

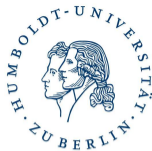


# Eigenfrequencies and Their Sensitivities

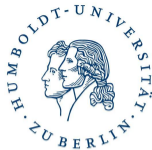




# Conclusions



- Basics of Algorithmic Differentiation
  - Efficient evaluation of derivatives with working accuracy
  - Theory for basic modes complete, advanced AD?
  - Various tools/implementations available



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  - Various tools/implementations available
- Structure exploitation indispensable
- AD for applications in physics:
  - parameter identification for piezoceramics<sup>1</sup>
  - optimized excitation of nano antenna<sup>2</sup>
  - sensitivities of exceptional points of nano-resonators<sup>3</sup>

<sup>1</sup> e.g., L. Claes et al.: Inverse procedure for measuring piezoelectric material parameters using a single multi-electrode sample. J. Sensors and Sensor Systems 12 (1) (2023)

<sup>2</sup> e.g., M. Reichelt, A. Walther, T. Meier: Tailoring the high-harmonic emission in two-level systems and semiconductors by pulse shaping. JOSA B 29 (2) (2012)

<sup>3</sup> F. Binkowski, J. Kullig, F. Betz, L. Zschiedrich, A. Walther, J. Wiersig, S. Burger: Computing eigenfrequency sensitivities near exceptional points, Phys. Rev. Research 6 (2) (2024)