

Introduction to Beam Instrumentation and Diagnostics Lecture I

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(based on previous lectures by Rhodri Jones)

Outline

- **Lecture I - today**
 - **Introduction**
 - **Beam position monitoring**
 - **Beam intensity monitoring**
 - **Beam loss monitoring**
- Lecture II - tomorrow
 - Transverse beam profile monitoring
 - Tune measurements
 - Coupling measurements
 - Chromaticity measurements
 - Diagnosing accelerator issues

Introduction

Beam instrumentation

- Instruments that observe the beam and its behaviour – “eyes” of the operators
 - Ultimate limit to quantify the performance of an accelerator
- Typical BI system architecture:

sensor → processing electronics → digitizer → processing software

discussed in these lectures

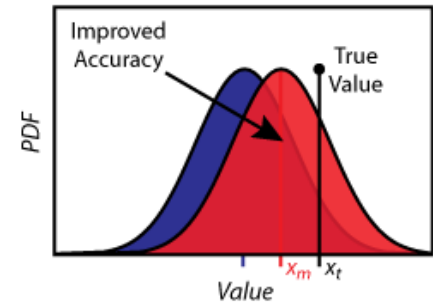
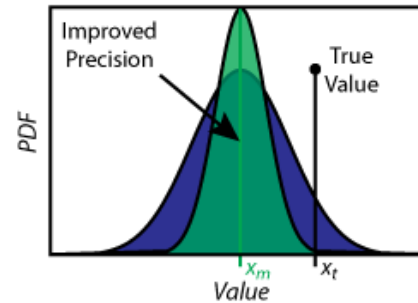
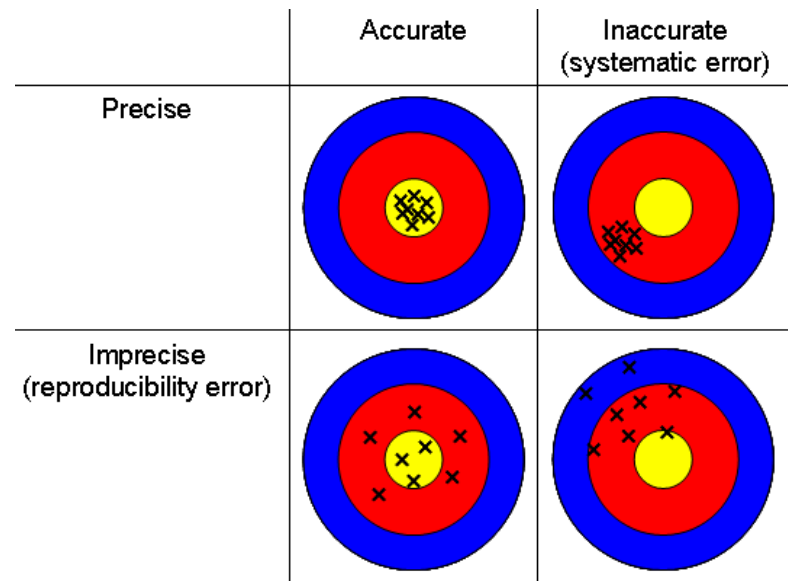
- BI expertise: applied and accelerator physics; mechanical, electronics, and software engineering
- BI system size: from 1 sensor / accelerator to 1000's sensors / accelerator
- Commonly measured beam parameters:
 - **Transverse beam position**: horizontal and vertical, all along and in specific places
 - **Beam intensity (and lifetime)**: bunch-by-bunch charge and total current
 - **Beam loss**: for protection and optimization
 - **Beam profiles**: transverse and longitudinal distribution of beam particles

Beam diagnostics

- Making use of beam instrumentation – extracting useful information from (a combination of) beam observables
- Examples of beam diagnostics:
 - **Daily operation of accelerators:** measurements and correction of beam orbit, tune, chromaticity...
 - **Understanding of accelerator limitations:** beam losses, instabilities, emittance growth...
 - **Improvement of accelerator performance:** luminosity, brilliance, feedbacks
 - **Detection of equipment faults:** aperture restrictions, magnet polarity inversion, wrong setting

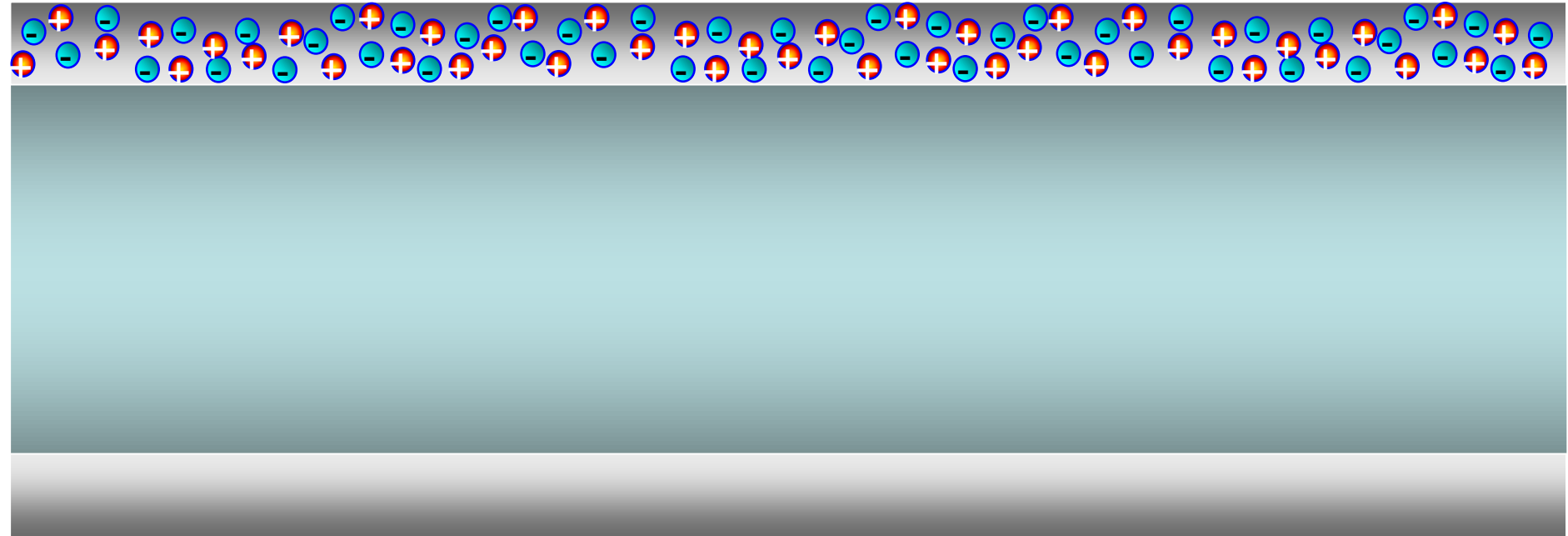
Measurement quality

- **Accuracy** – trueness
- **Precision** – reproducibility
- **Resolution** – smallest measurable change
- **Dynamic range** – ratio of the largest and smallest measurable signal
- **Timescale** – multi-turn full beam / turn-by-turn / bunch-by-bunch
- **Availability** – continuous / on-demand



Beam Position Monitors (BPMs)

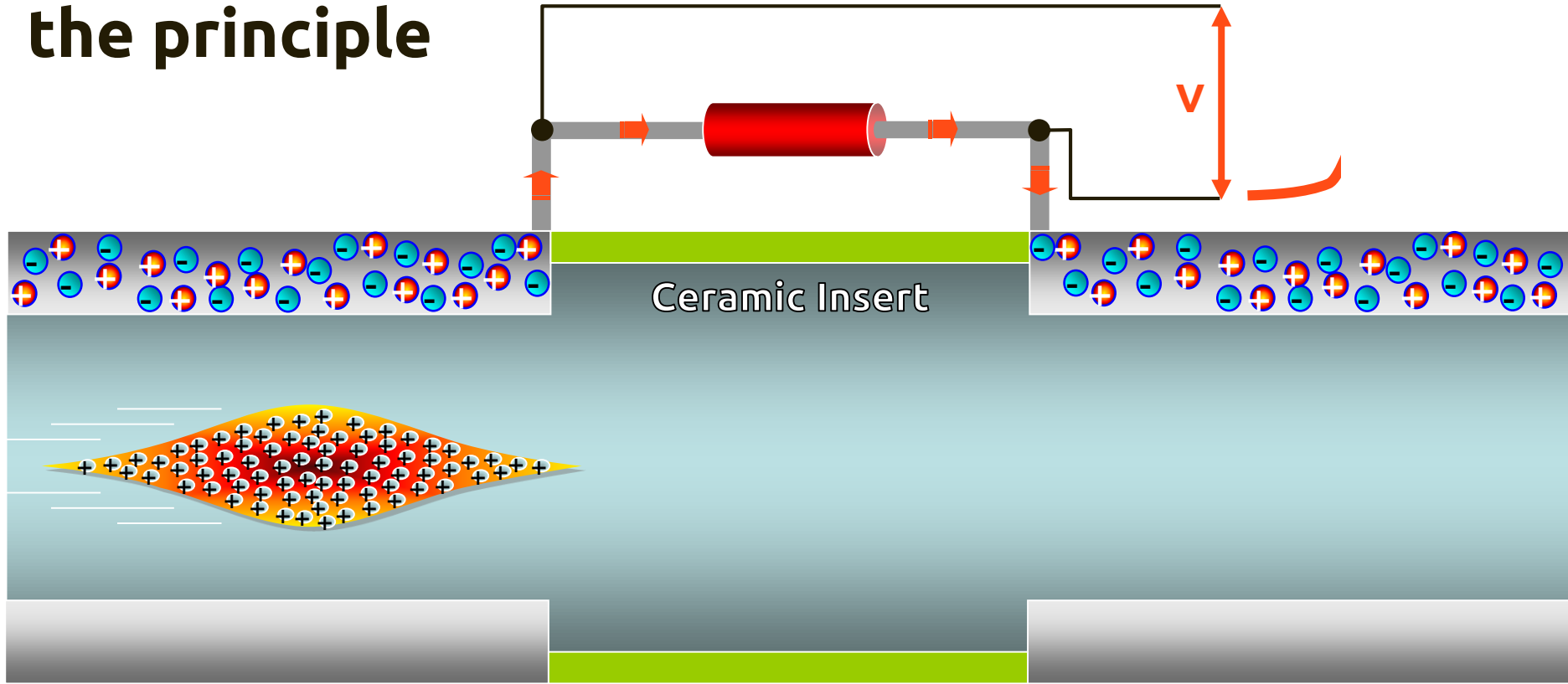
Beam image current



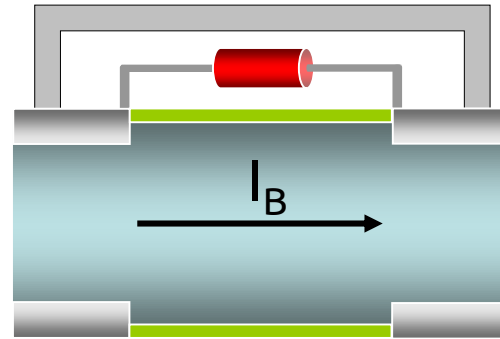
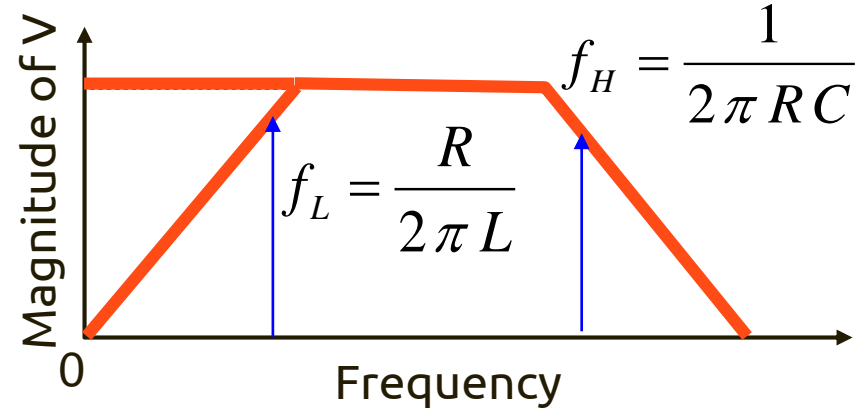
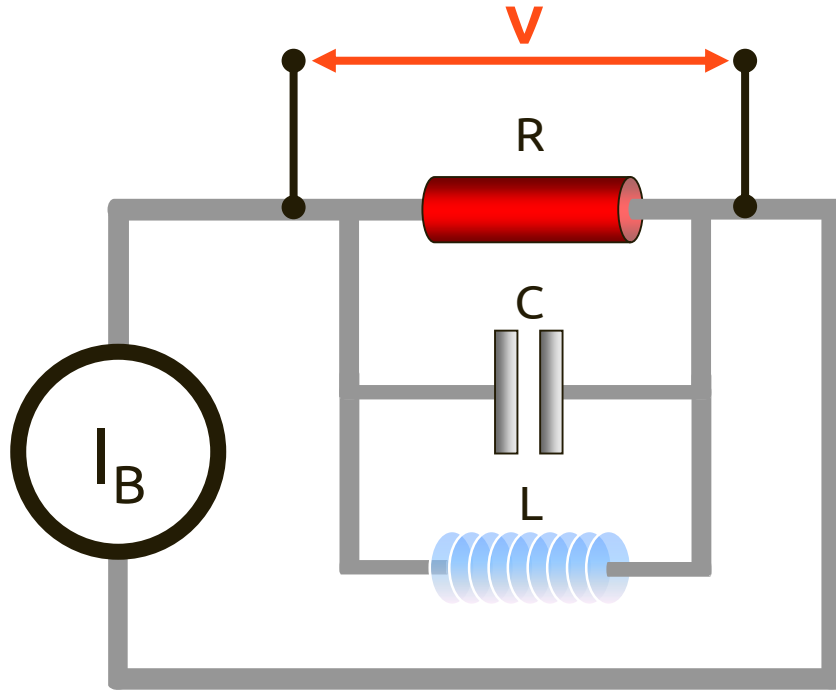
Beam image current properties

- Equal to the beam current (non-DC components) but with the opposite sign: $I_{\text{Image}} = -I_{\text{beam}}$
 - Good proxy for beam/bunch intensity measurements
- Current density around the vacuum chamber correlated to the transverse beam position
 - Good proxy for beam/bunch position measurements
- Same longitudinal charge distribution as the beam for highly-relativistic beams
 - Good proxy for longitudinal measurements
- Often referred to as the “wall current”

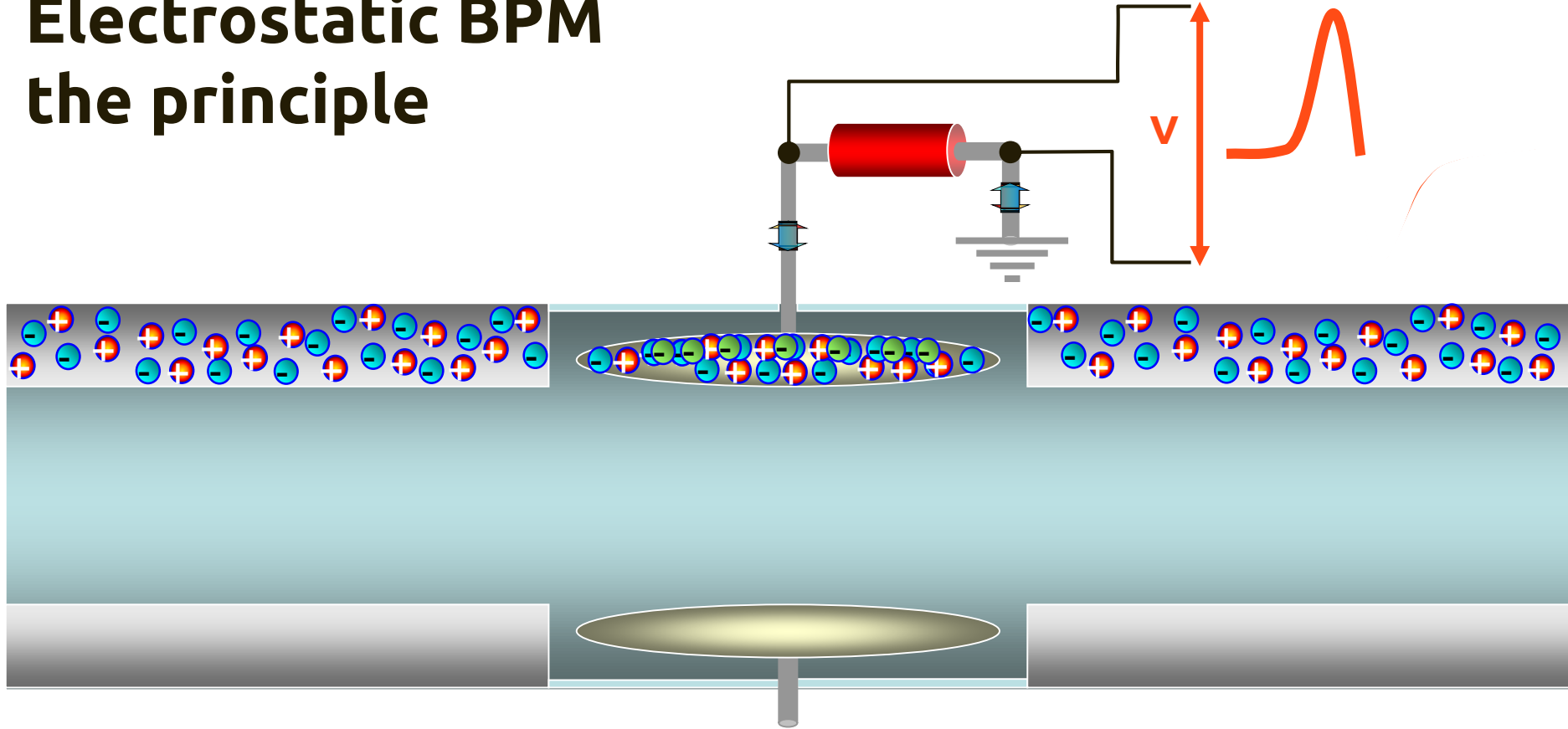
Wall Current Monitor the principle



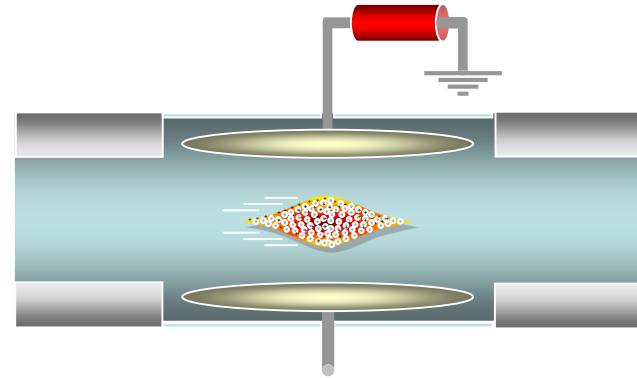
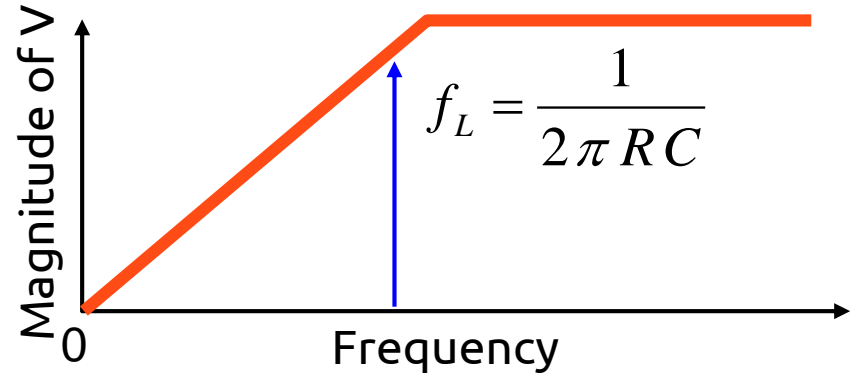
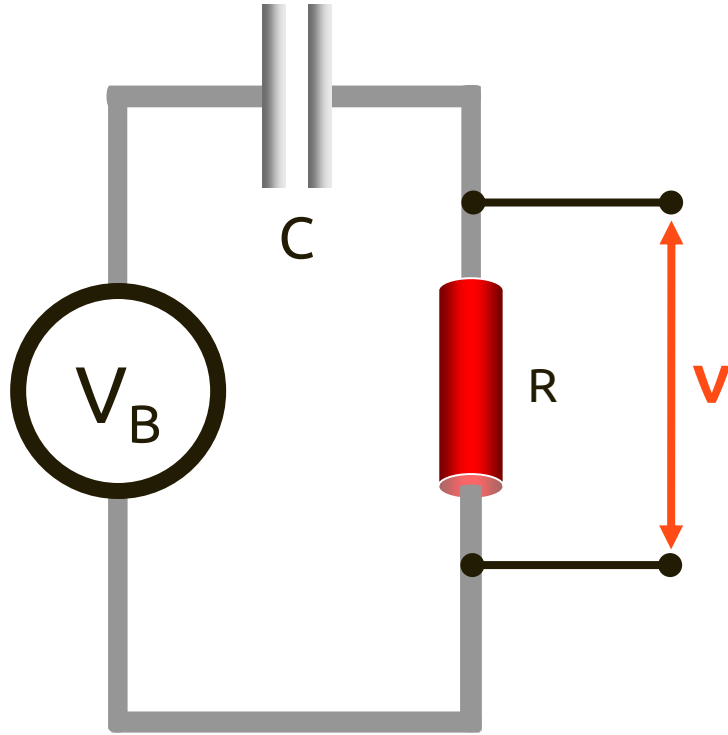
Wall Current Monitor – beam response



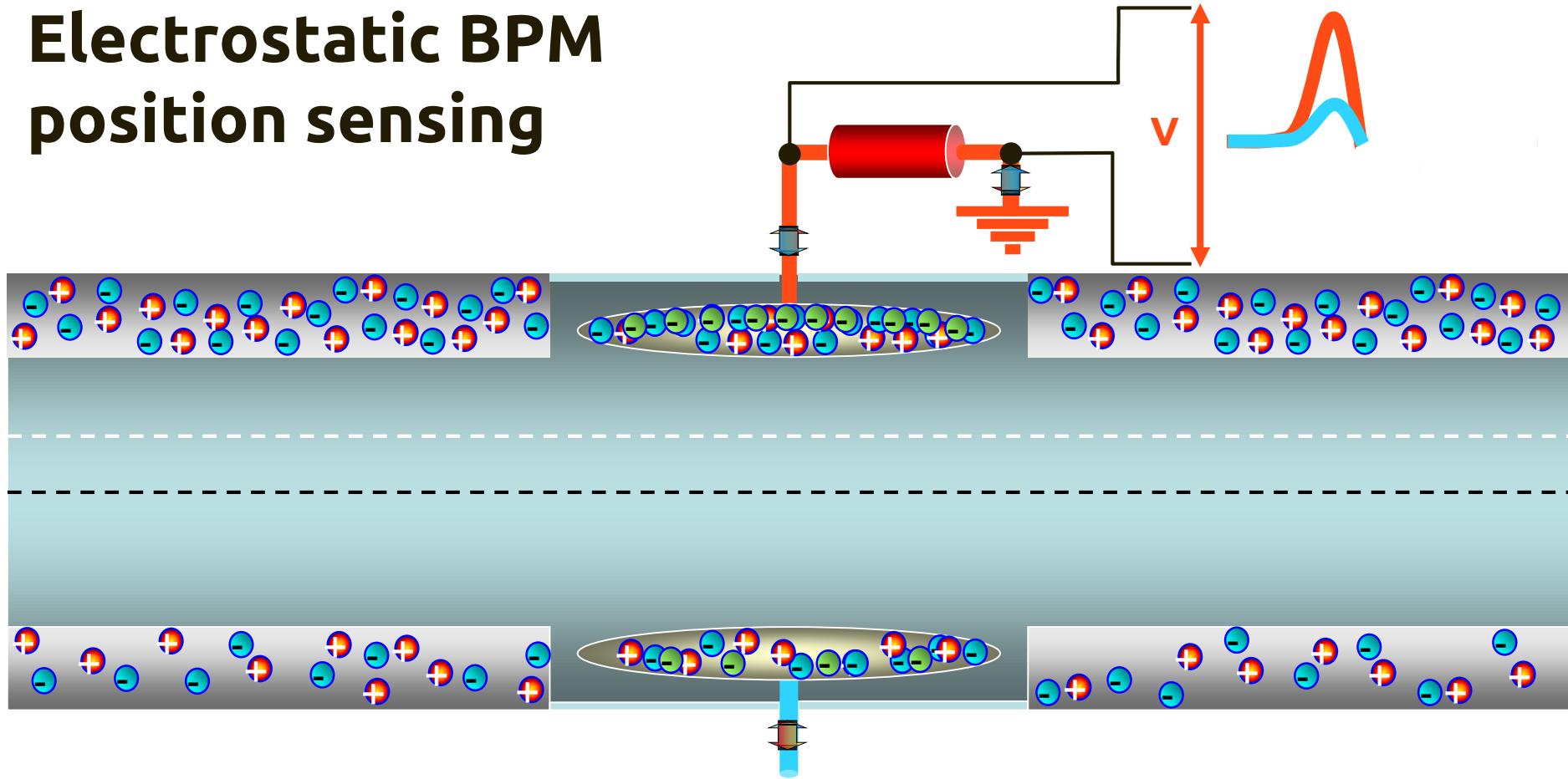
Electrostatic BPM the principle



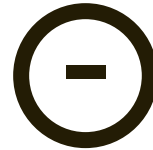
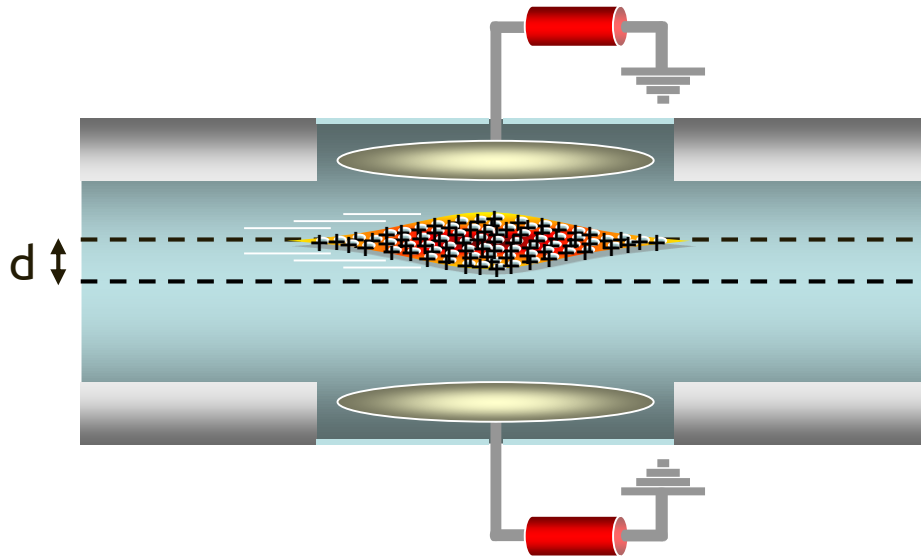
Electrostatic BPM – beam response



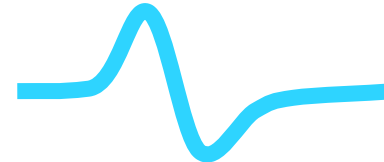
Electrostatic BPM position sensing



Electrostatic BPM – position sensing

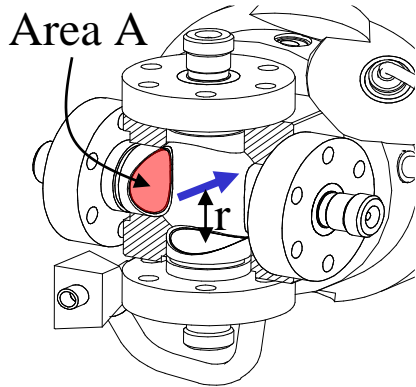


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Electrostatic BPM – button pick-up

- **Low cost** – most popular electrode type
- **Non-linear** – requires corrections for large beam displacements



C_e – button capacitance
 R_0 – load resistance

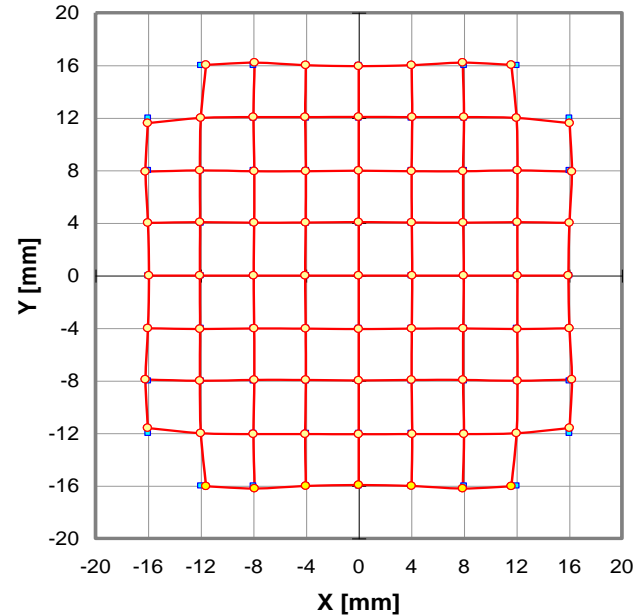
Transfer impedance

$$Z_{T(f \gg f_c)} = \frac{A}{(2\pi r) \times c \times C_e}$$

Low cut-off frequency

$$f_L = \frac{1}{2\pi R_0 C_e}$$

$$X = 2.30 \cdot 10^{-5} X_1^5 + 3.70 \cdot 10^{-5} X_1^3 + 1.035 X_1 + 7.53 \cdot 10^{-6} X_1^3 Y_1^2 + 1.53 \cdot 10^{-5} X_1 Y_1^4$$



Normalisation of BPM measurements

- Required to make measurement independent of beam / bunch intensity

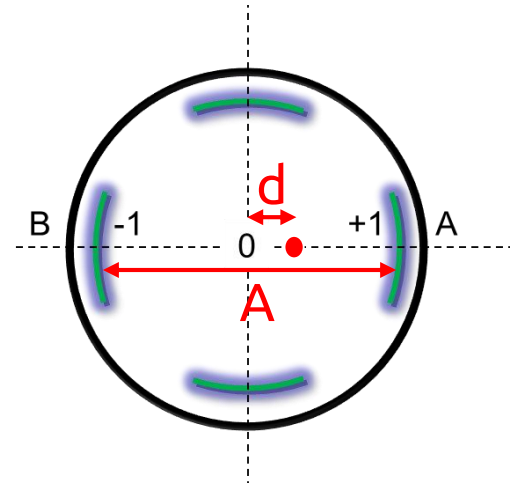
- $V_{BPM} \propto I_{beam} \cdot (1 + 4 \frac{d}{A} + \text{higher-order terms})$

- Three main methods:

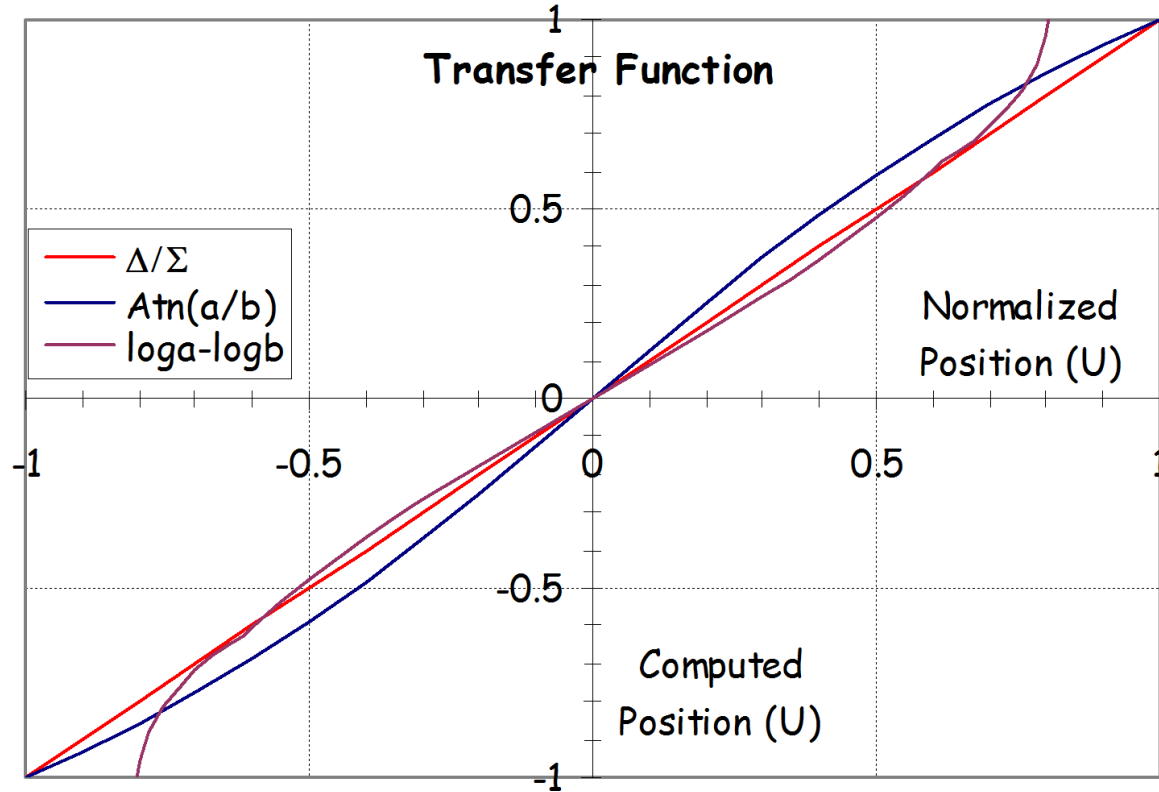
- **Phase:** $\text{ArcTan} \left(\frac{V_A}{V_B} \right) \approx \text{ArcTan} \left(2 \frac{d}{A} \right)$

- **Logarithm:** $\text{Log} \left(\frac{V_A}{V_B} \right) = \text{Log}(V_A) - \text{Log}(V_B) \approx \text{Log} \left(2 \frac{d}{A} \right)$

- **Difference / Sum:** $\frac{(V_A - V_B)}{(V_A + V_B)} = \frac{\Delta}{\Sigma} \approx 4 \frac{d}{A}$

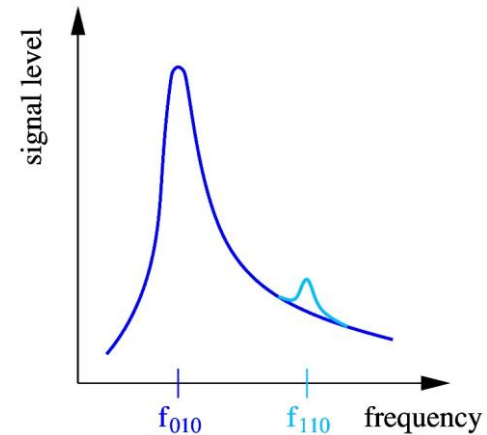
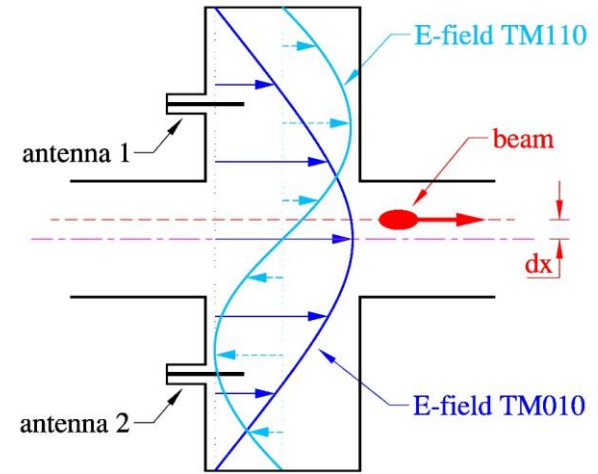


Normalisation of BPM measurements



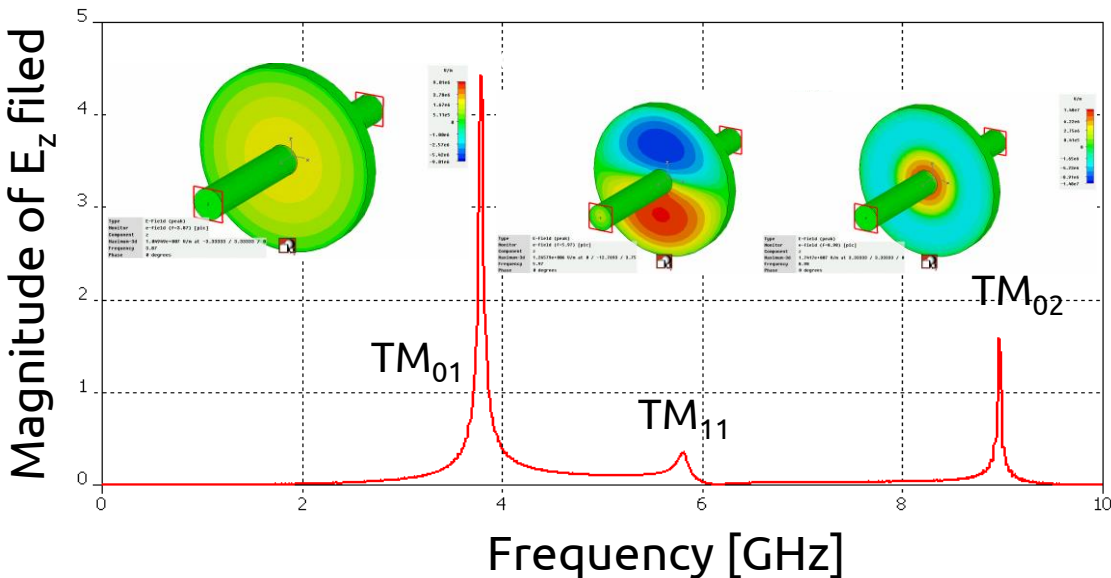
High-precision BPMs

- Standard BPM electrodes:
 $V_{BPM} \propto I_{beam} \cdot (1 + 4 \frac{d}{A} + \text{H.O.T.})$
 - Strong beam / bunch intensity component – difficult to suppress
 - Rather weak dependence on the beam position
- Another approach: **Cavity BPMs**
 - Separate the intensity component (TM010) and the position component (TM110) in the frequency domain
 - Intensity component still needed for normalisation
 - Not suitable for circular accelerators



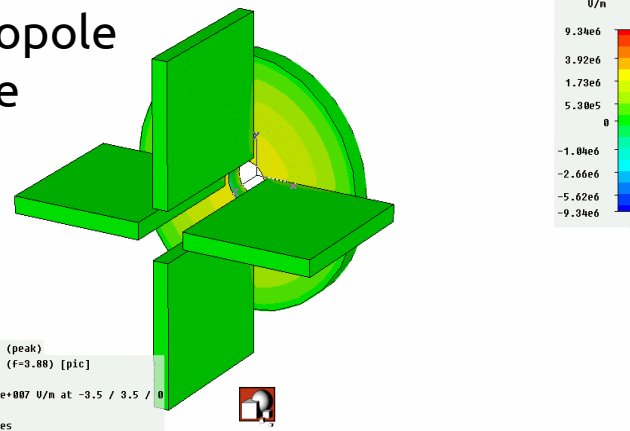
Cavity BPM

Use waveguides to couple out only the dipole mode and suppress the monopole mode

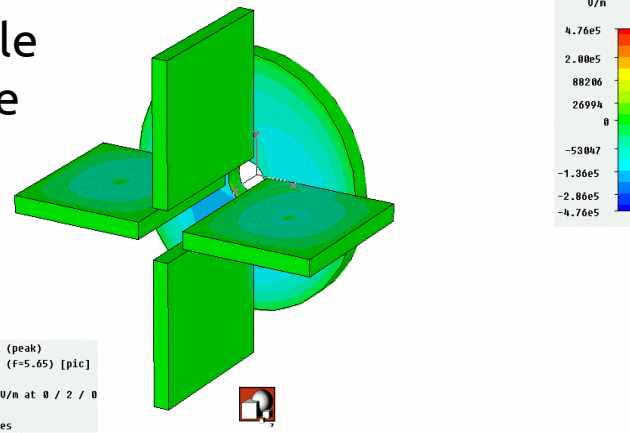


Courtesy of D. Lipka,
DESY, Hamburg

Monopole mode

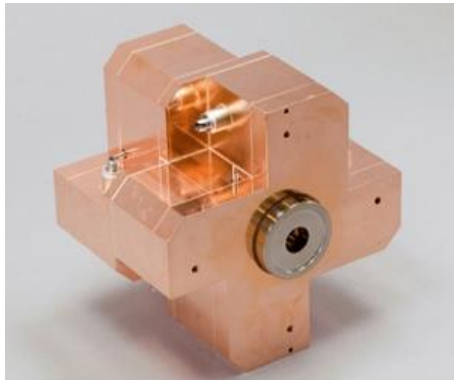


Dipole mode

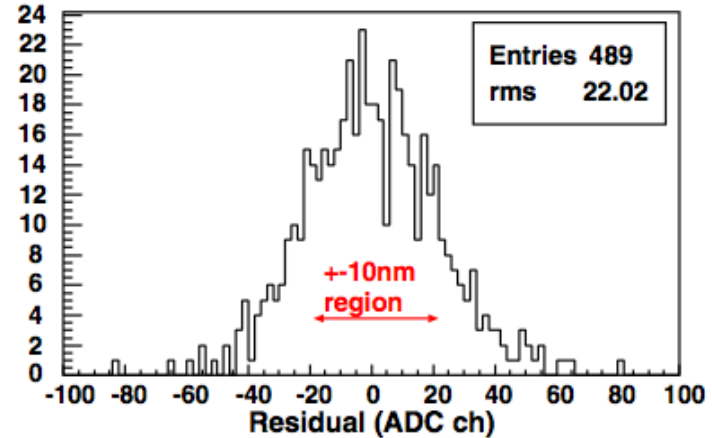
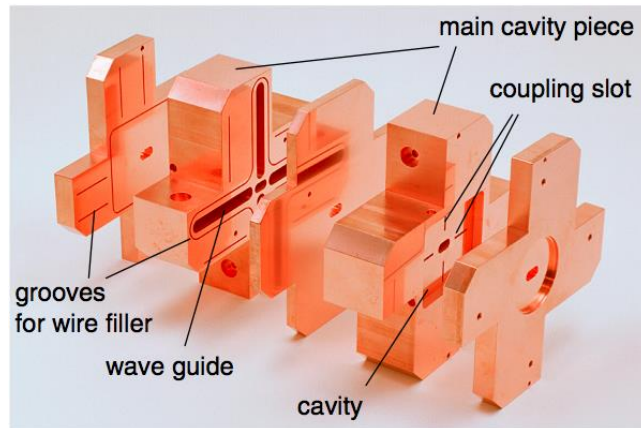


Prototype Cavity BPM for ILC Final Focus

- Required resolution of 2 nm in a 6×12 mm oval beam pipe
- Demonstrated with beam: astonishing resolution of **8.7 nm** at ATF2 (KEK, Japan)

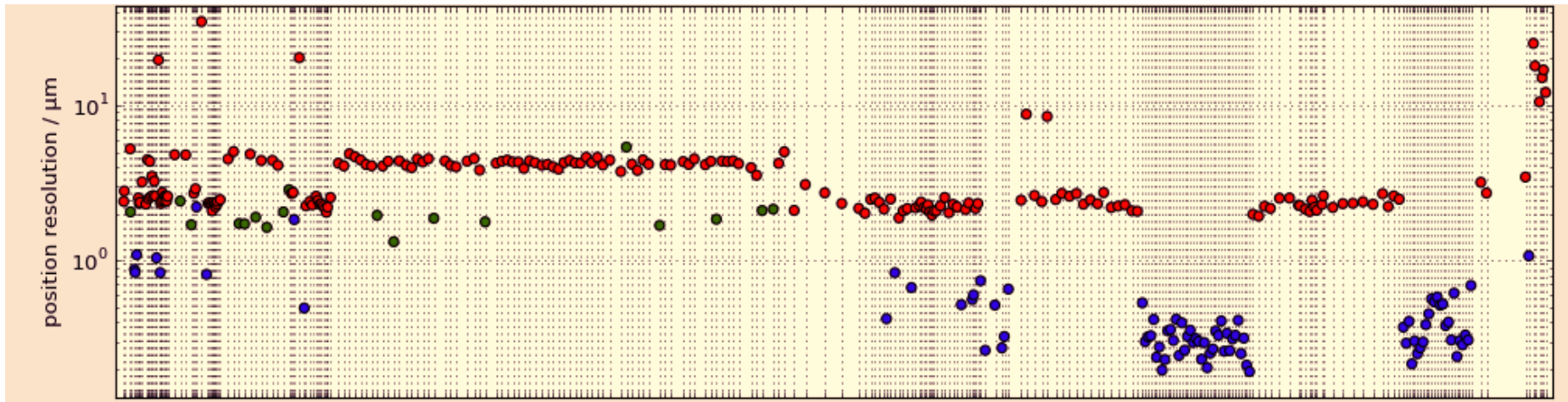
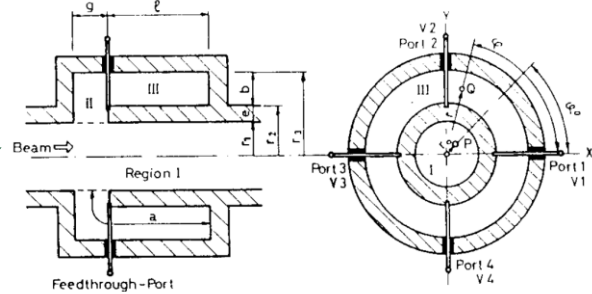


Courtesy of D. Lipka & Y. Honda

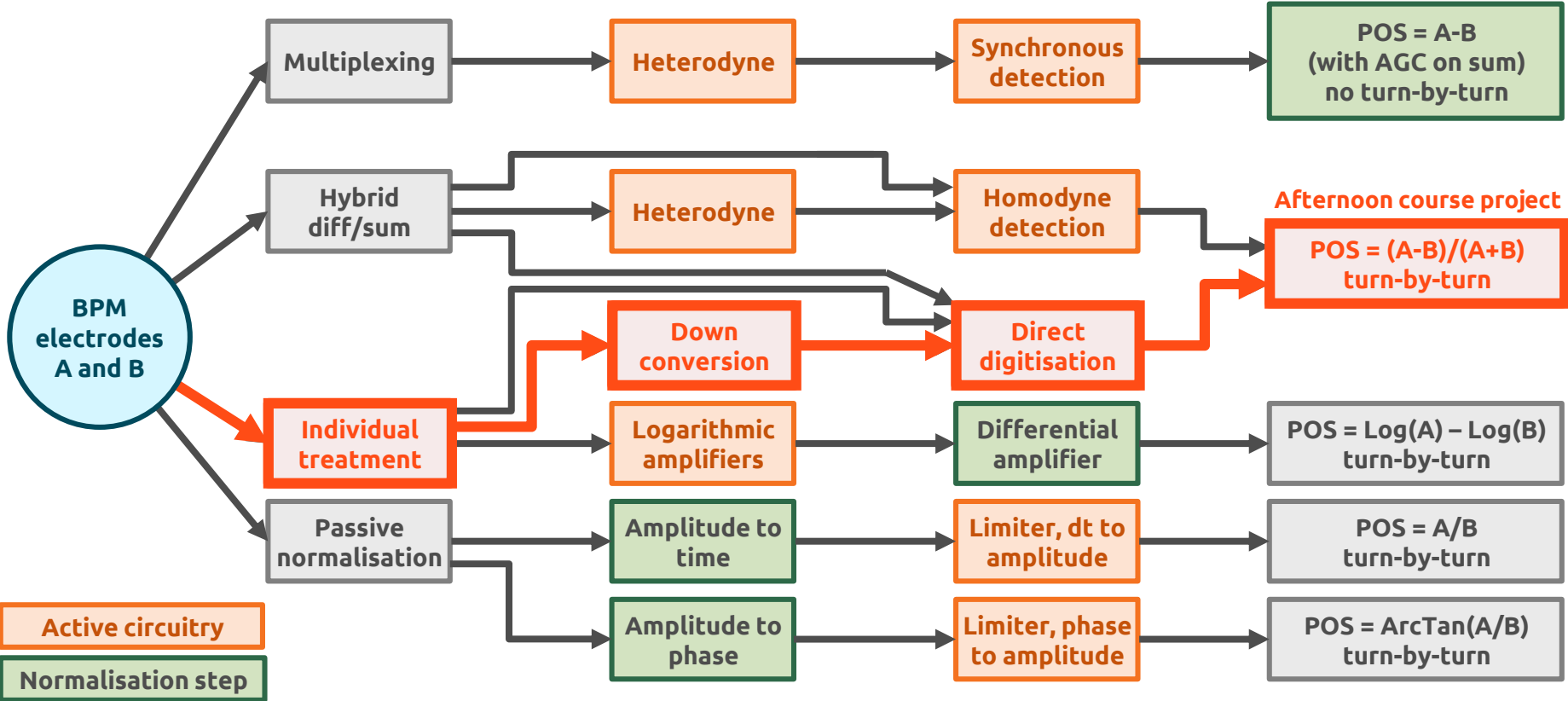


Electrostatic and cavity BPM – resolution comparison

- XFEL (Germany) results from 2017 beam commissioning:
 - **Red dots:** button BPMs (78 mm and 40.5 mm aperture)
 - **Green dots:** re-entrant cavity BPMs (78 mm aperture)
 - **Blue dots:** cavity BPMs (40.5 and 10 mm aperture)

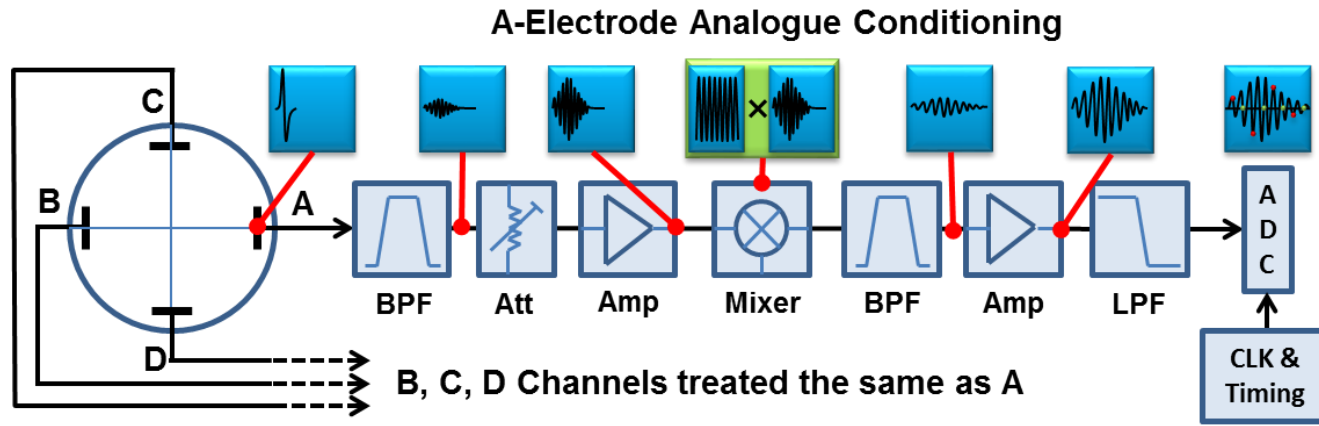


BPM data acquisition system families



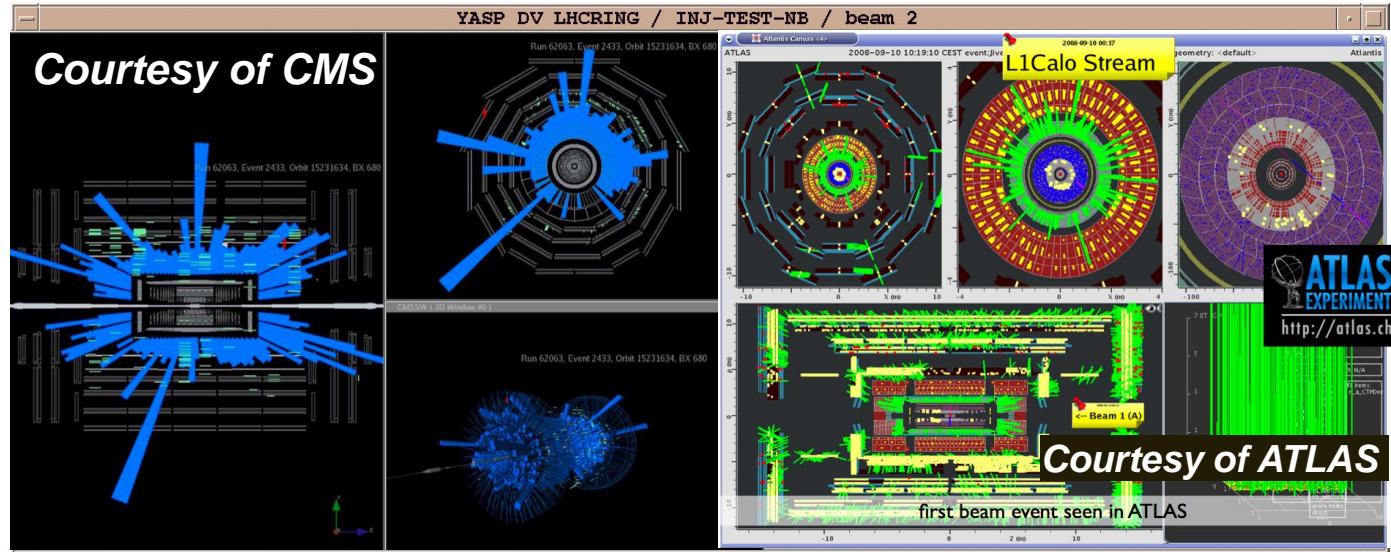
Modern BPM data acquisition system

- Each electrode treated individually
- Frequency-domain processing – telecommunications industry approach
- Requires good-resolution and fast-sampling analogue-to-digital converters
 - BPM signal down-conversion to match the ADC characteristics
- Minimal analogue circuitry – most processing done digitally

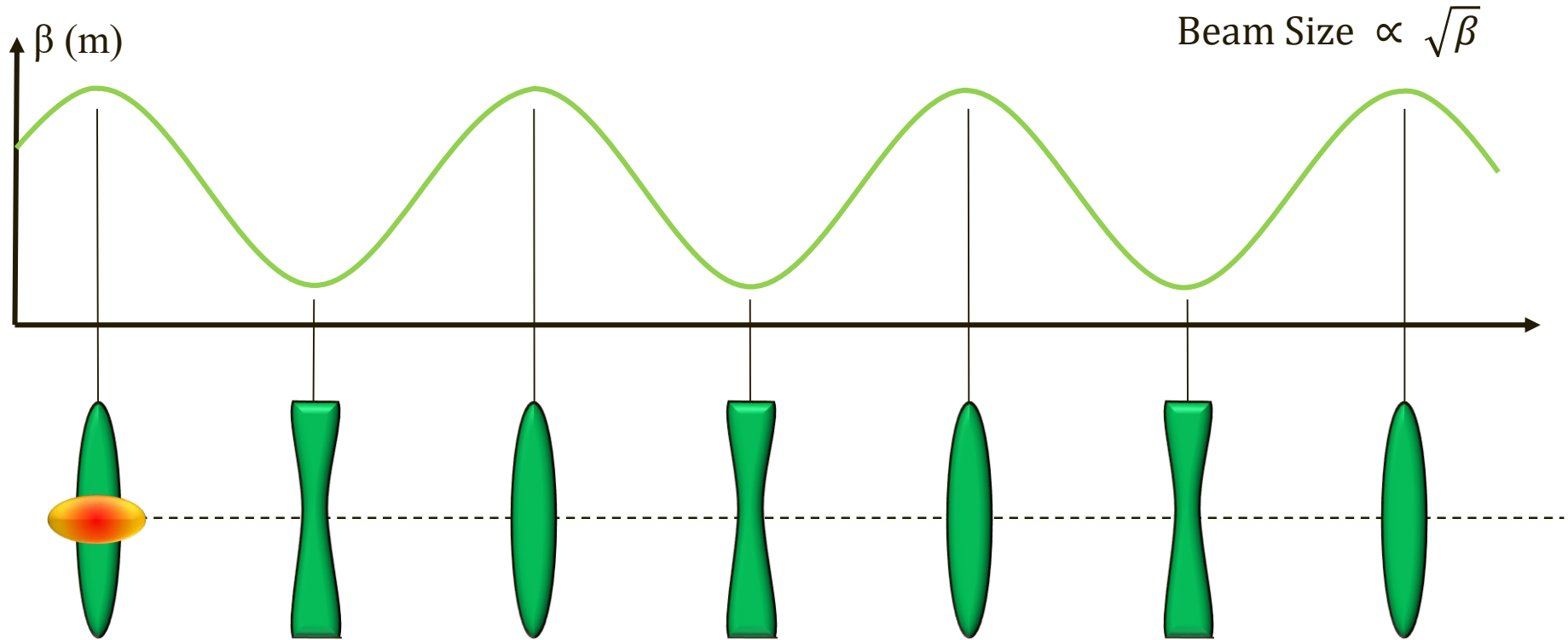


Initial accelerator commissioning using BPMs

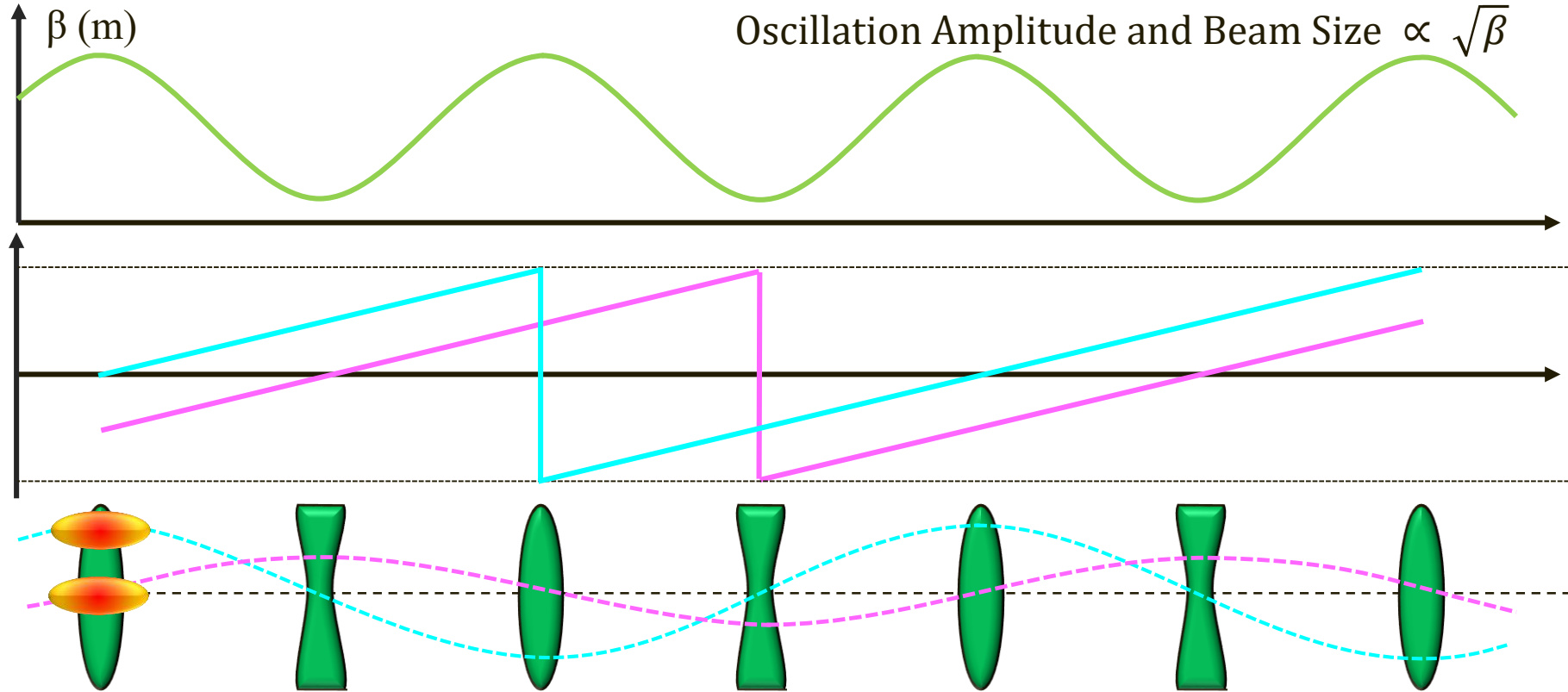
- Beam threading in the LHC
 - One beam at a time, ~1 hour per beam
 - Beam intercepted by the closest downstream collimator
 - Correct trajectory, open collimator, carry on



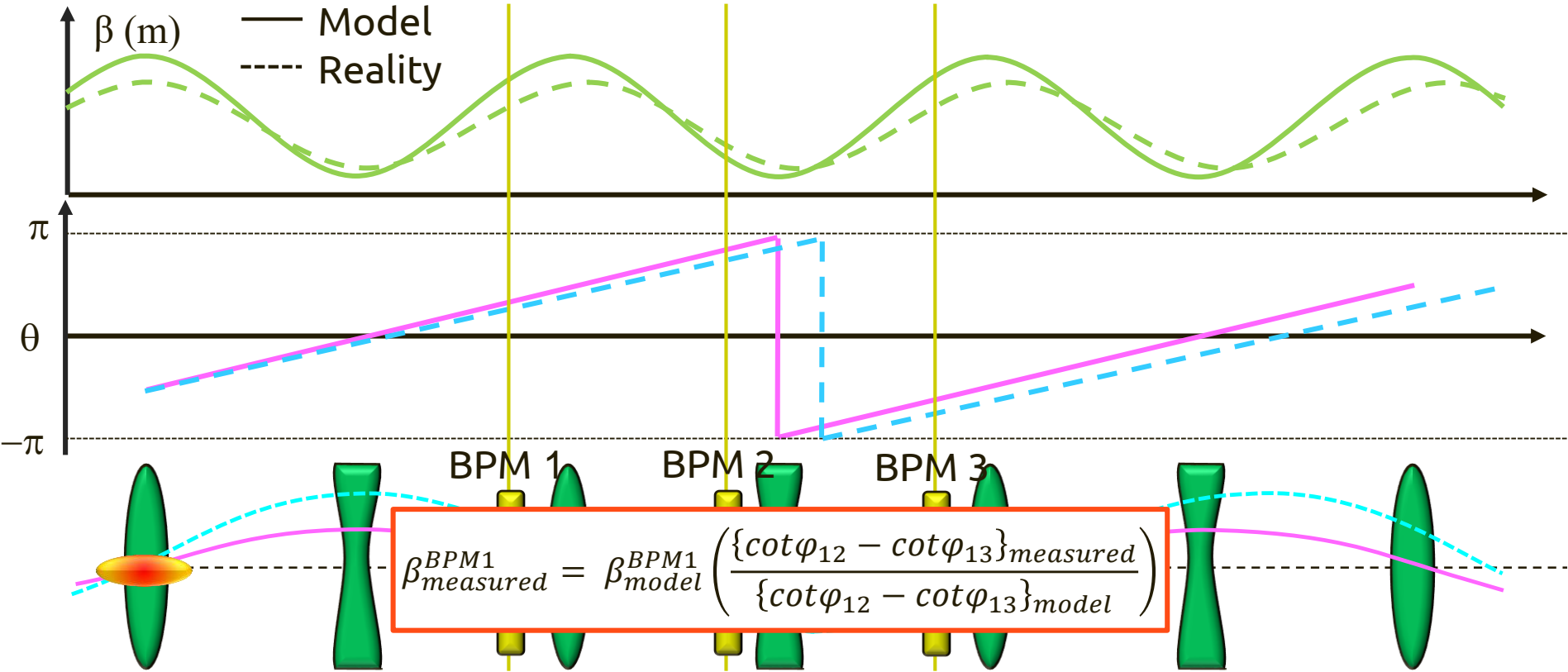
Accelerator beta function measurement with BPMs



Accelerator beta function measurement with BPMs

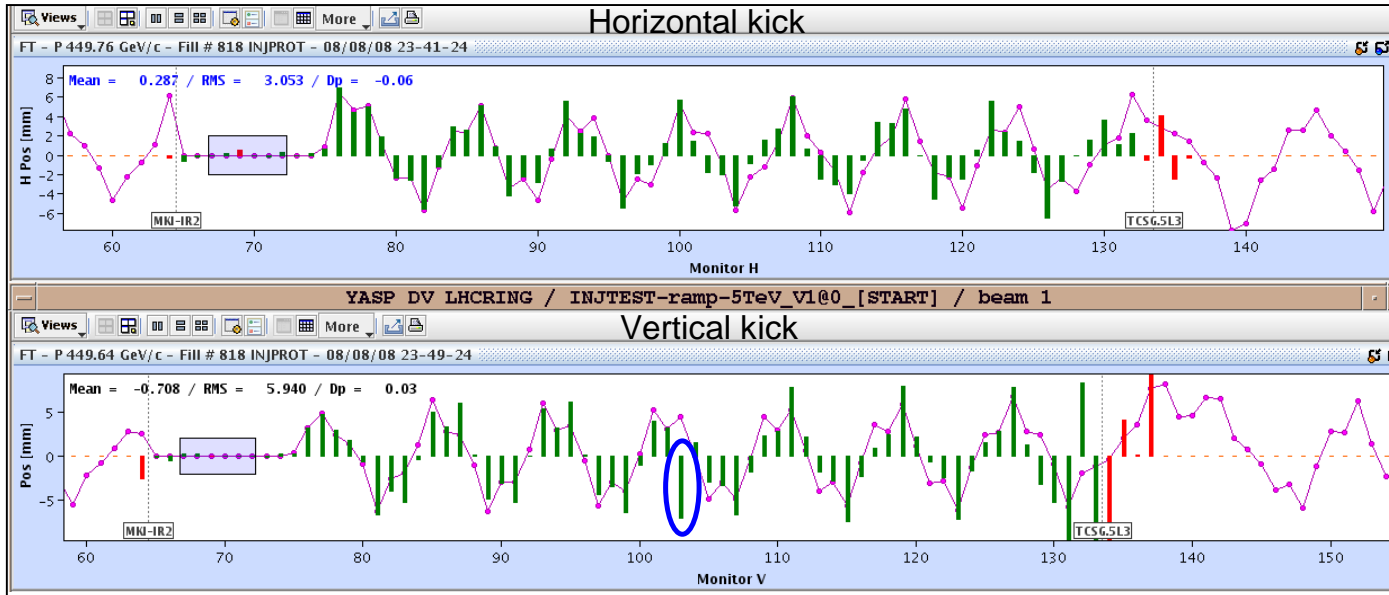


Accelerator beta function measurement with BPMs



Online analysis of BPM data

- Easy identification of polarity errors with 45° BPM sampling
- Quick indication of phase advance errors
- Verification of optics functions (e.g. injection matching)

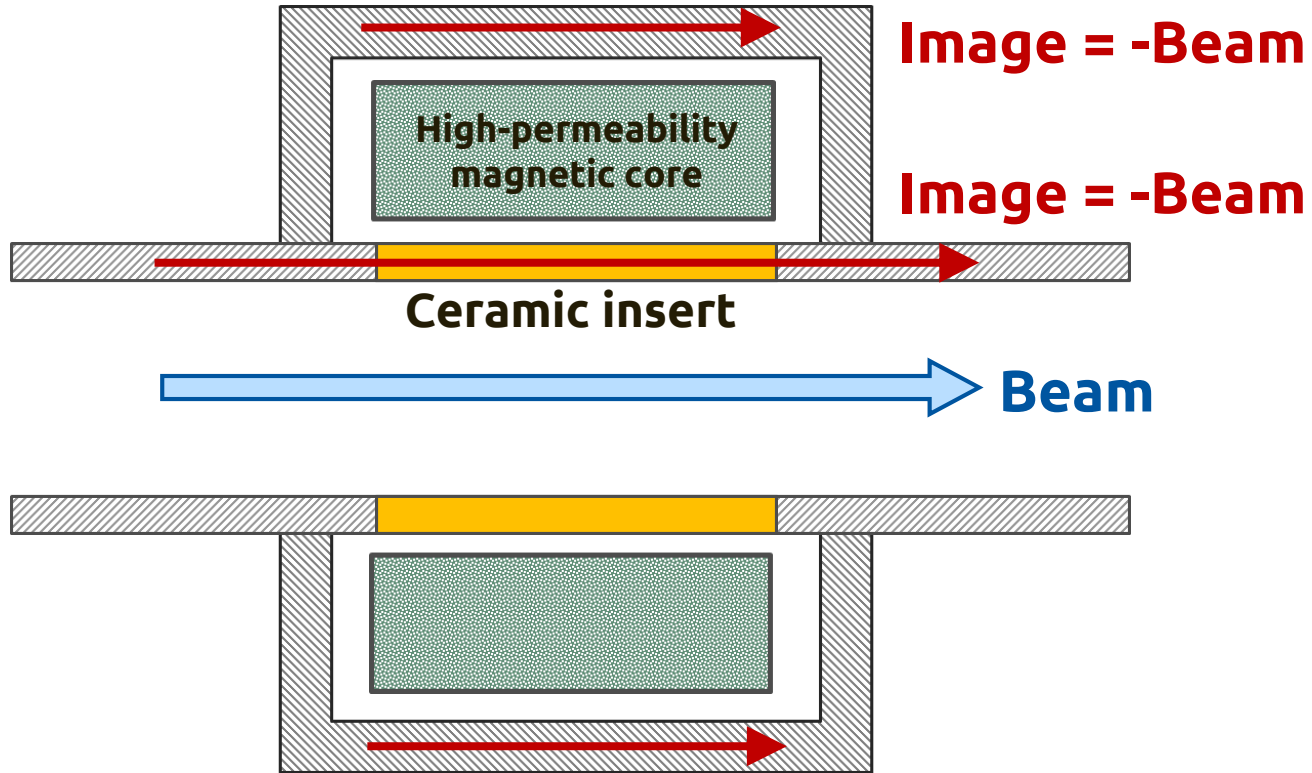


Optics phase error

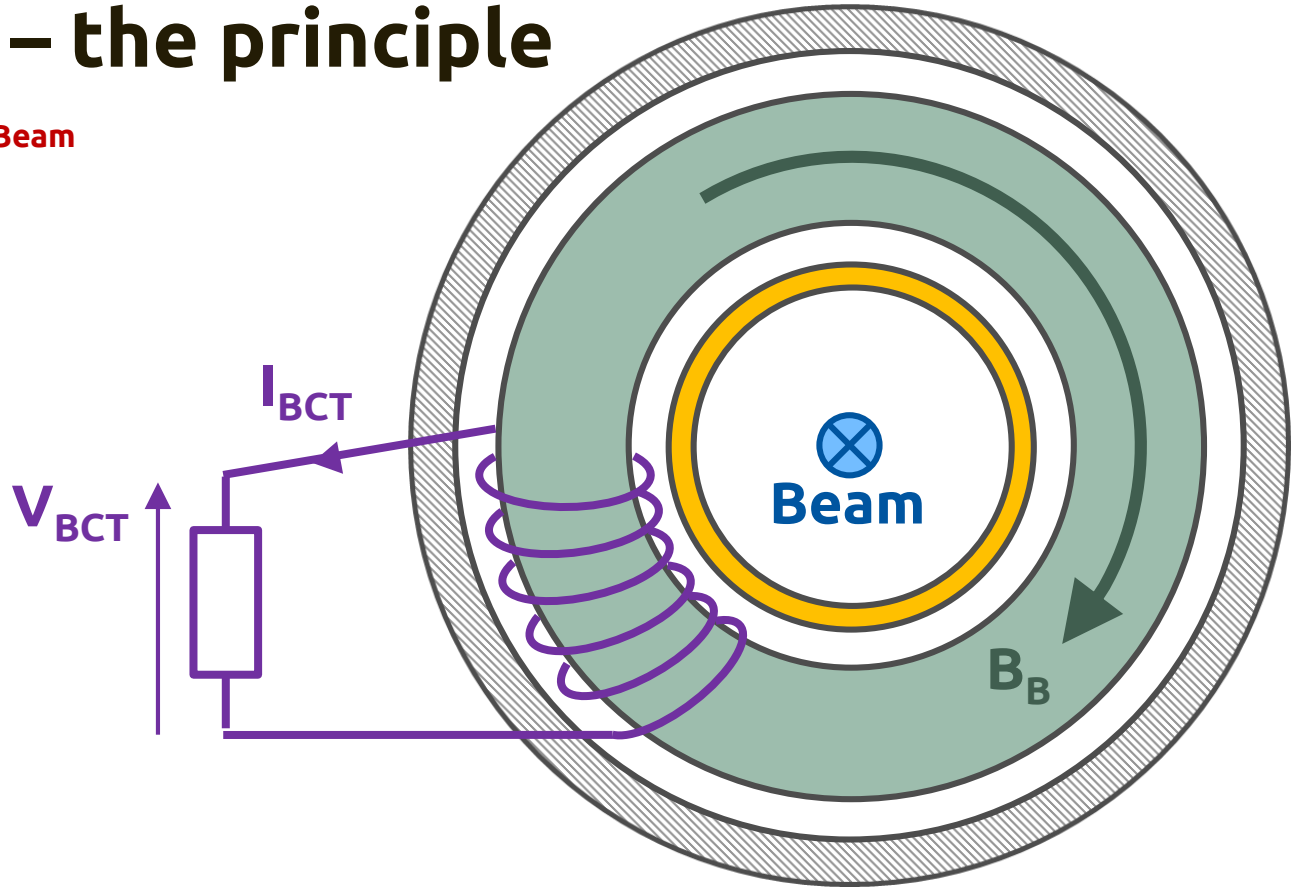
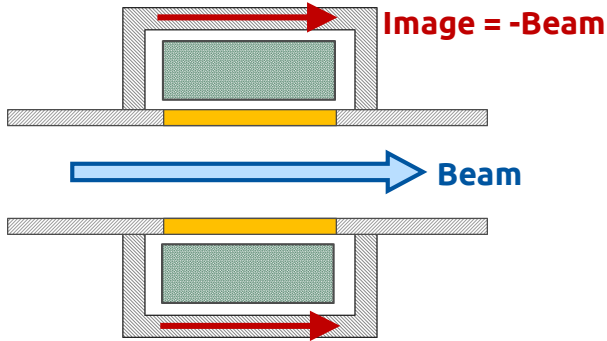
BPM polarity error

Beam Intensity Measurements with Beam Current Transformers (BCTs)

AC / Fast BCT – the principle

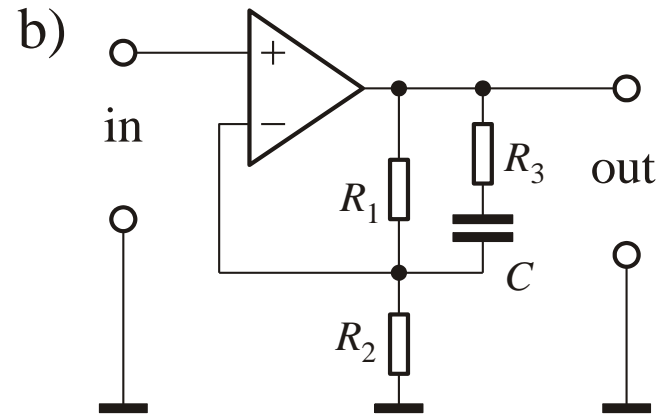
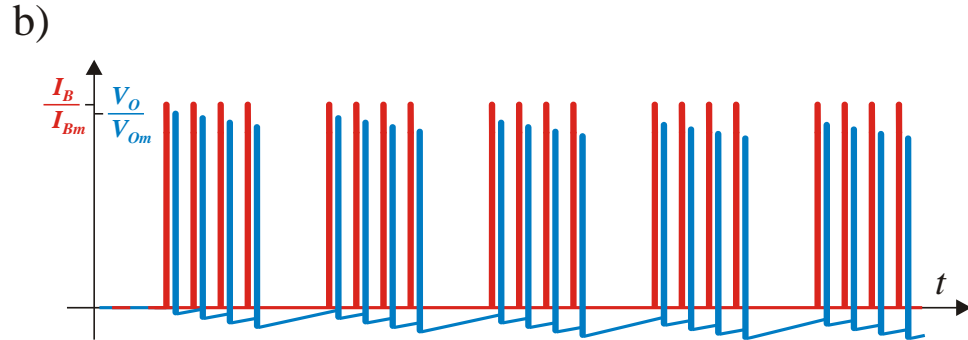
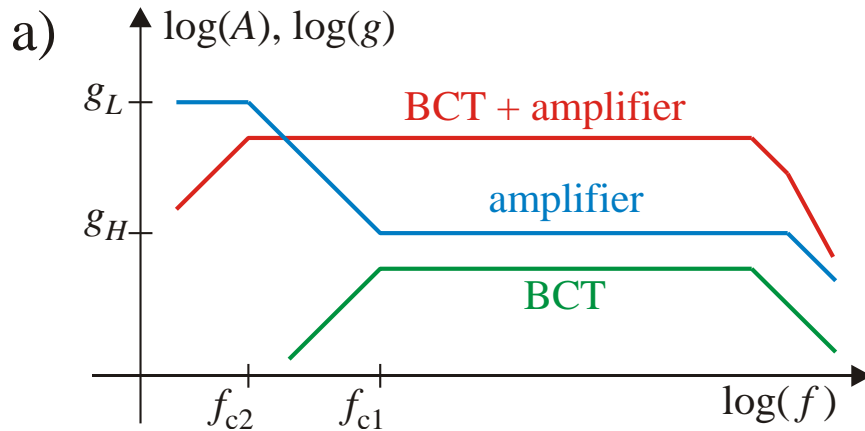


AC / Fast BCT – the principle



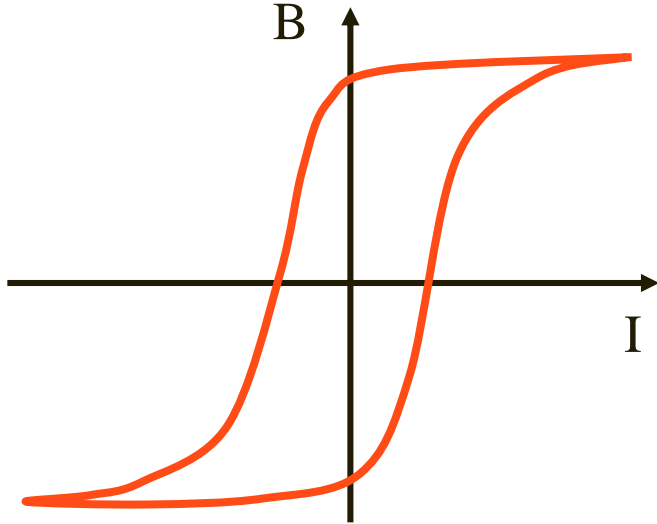
AC / Fast BCT – beam response

- **High-pass characteristics** – no low frequency signal components
- Impedance of secondary winding \propto frequency
- Baseline droop – analogue or digital restoration



DC BCT

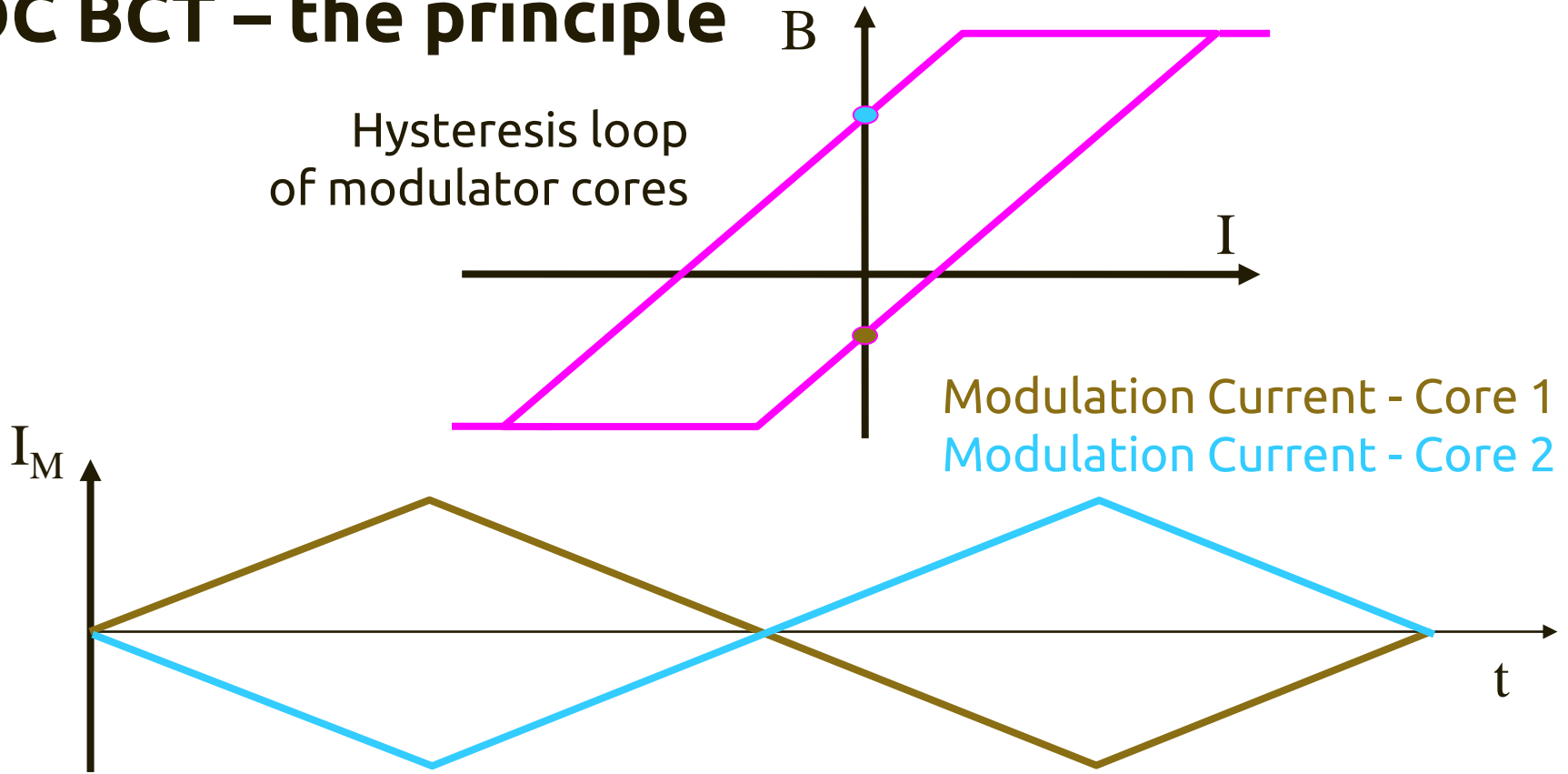
- AC BCTs cannot measure DC beam current (no di/dt)
- DC beam current measurement needed in storage rings
- **DC BCTs** – take advantage of non-linear magnetisation curve and use two identical cores magnetized in the opposite way



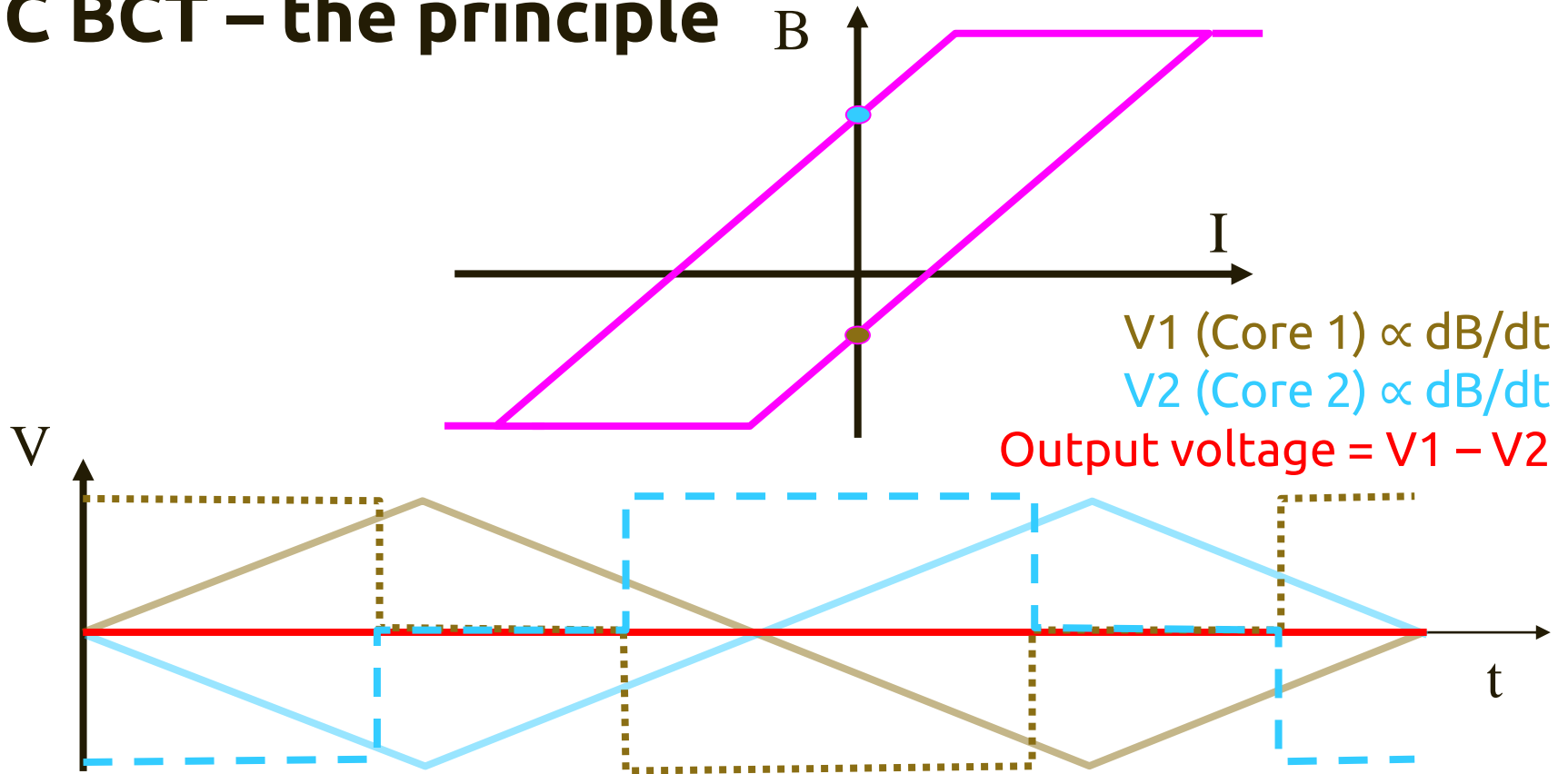
I – magnetizing current (i.e. beam current)

B – magnetic field in the core

DC BCT – the principle

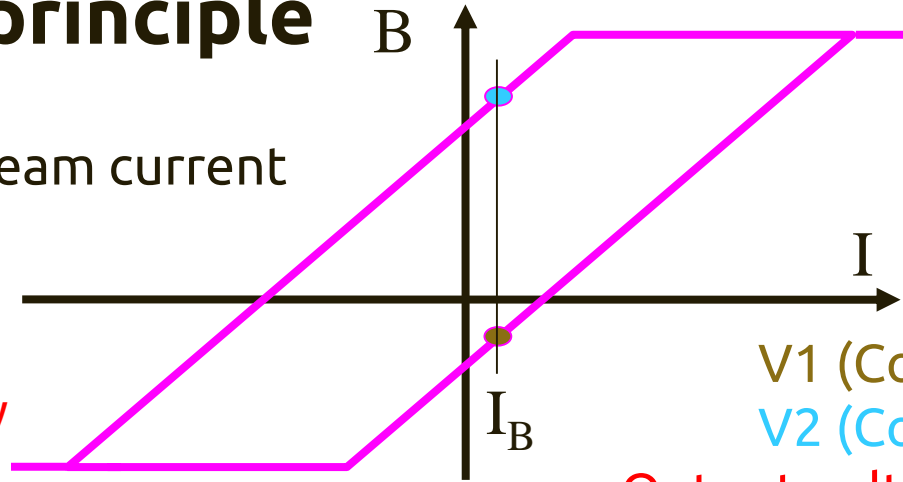


DC BCT – the principle



DC BCT – the principle

I_B = beam current

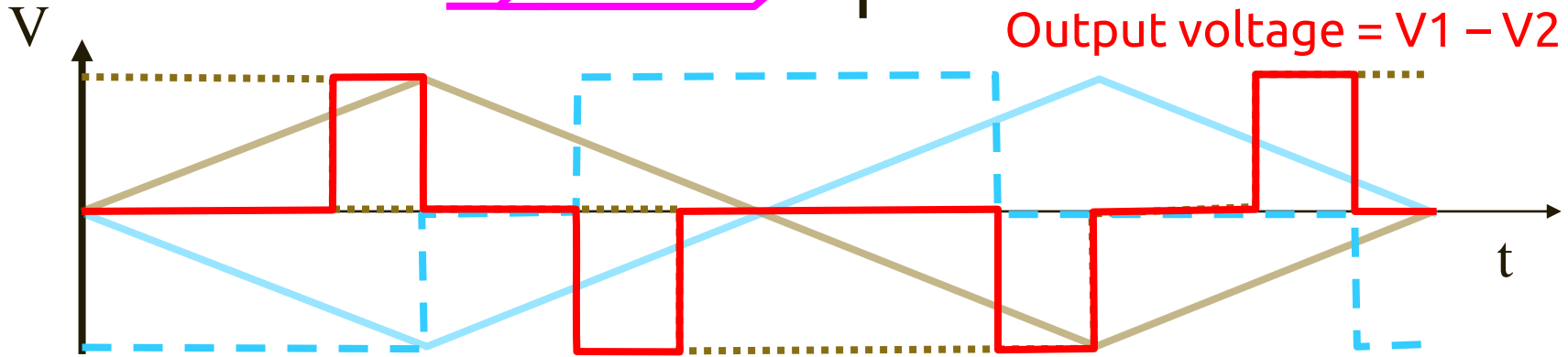


Output signal at twice the modulation frequency

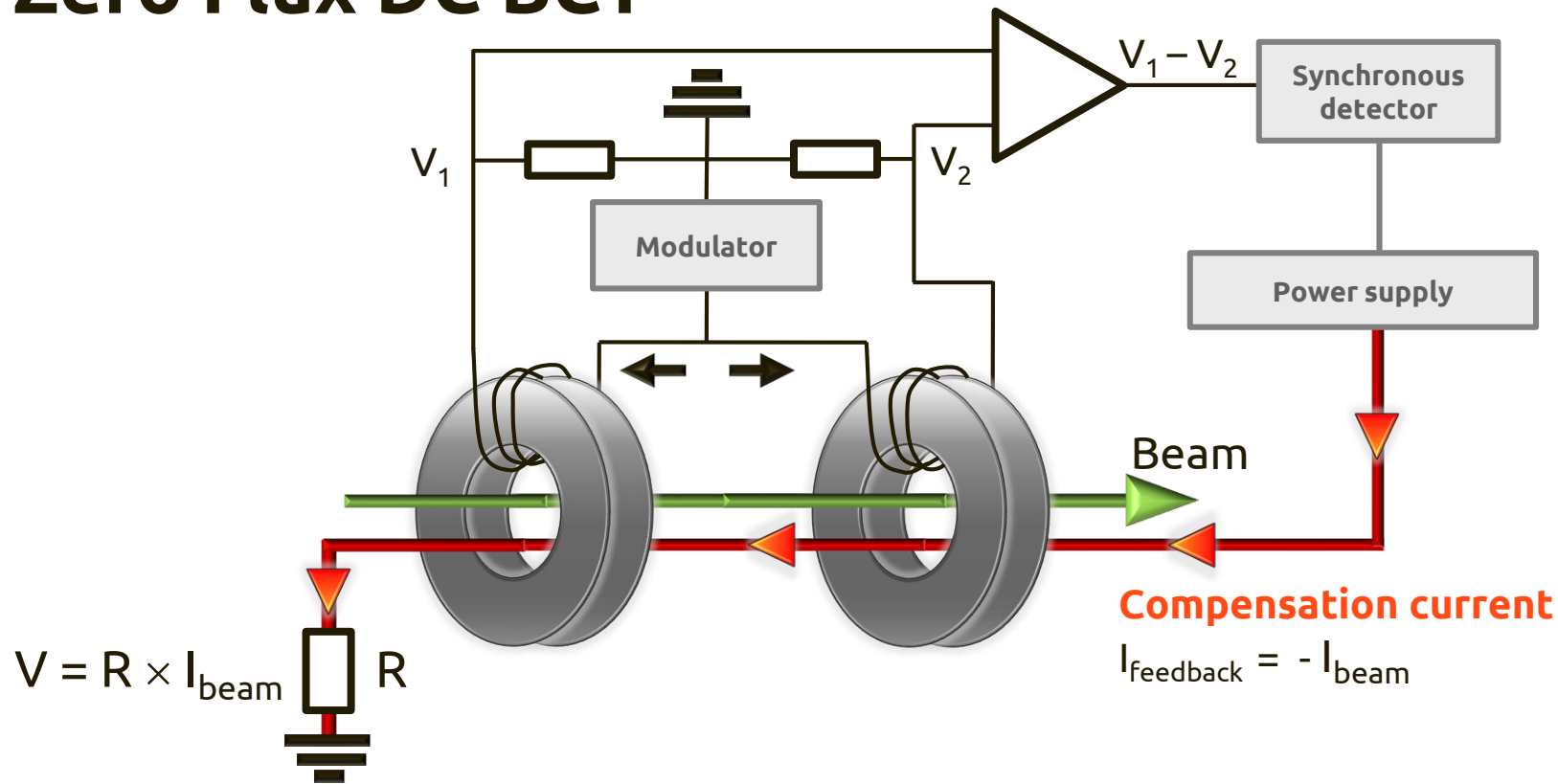
$V1$ (Core 1) $\propto dB/dt$

$V2$ (Core 2) $\propto dB/dt$

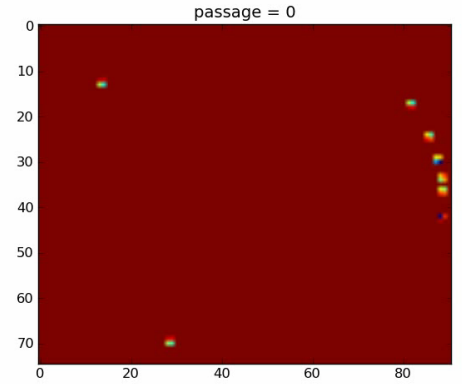
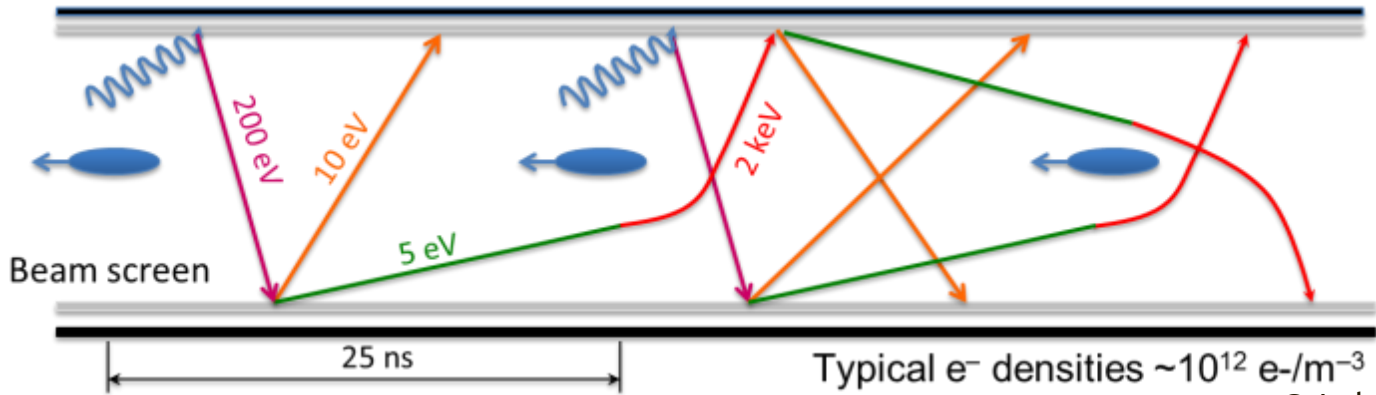
Output voltage = $V1 - V2$



Zero Flux DC BCT



LHC electron cloud diagnostics with BCTs

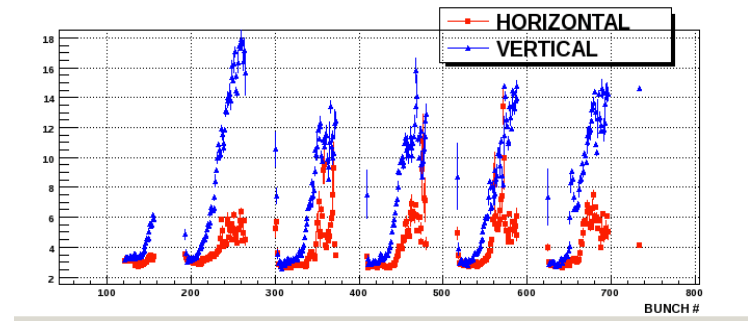
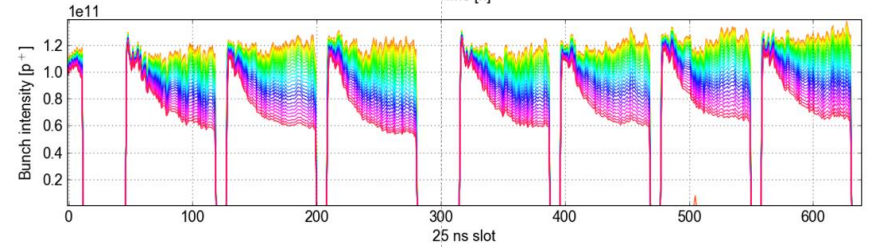
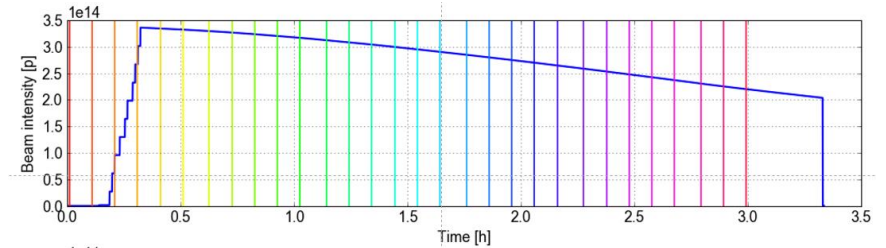


G. Iadarola, G. Rumolo, G. Arduini (CERN)

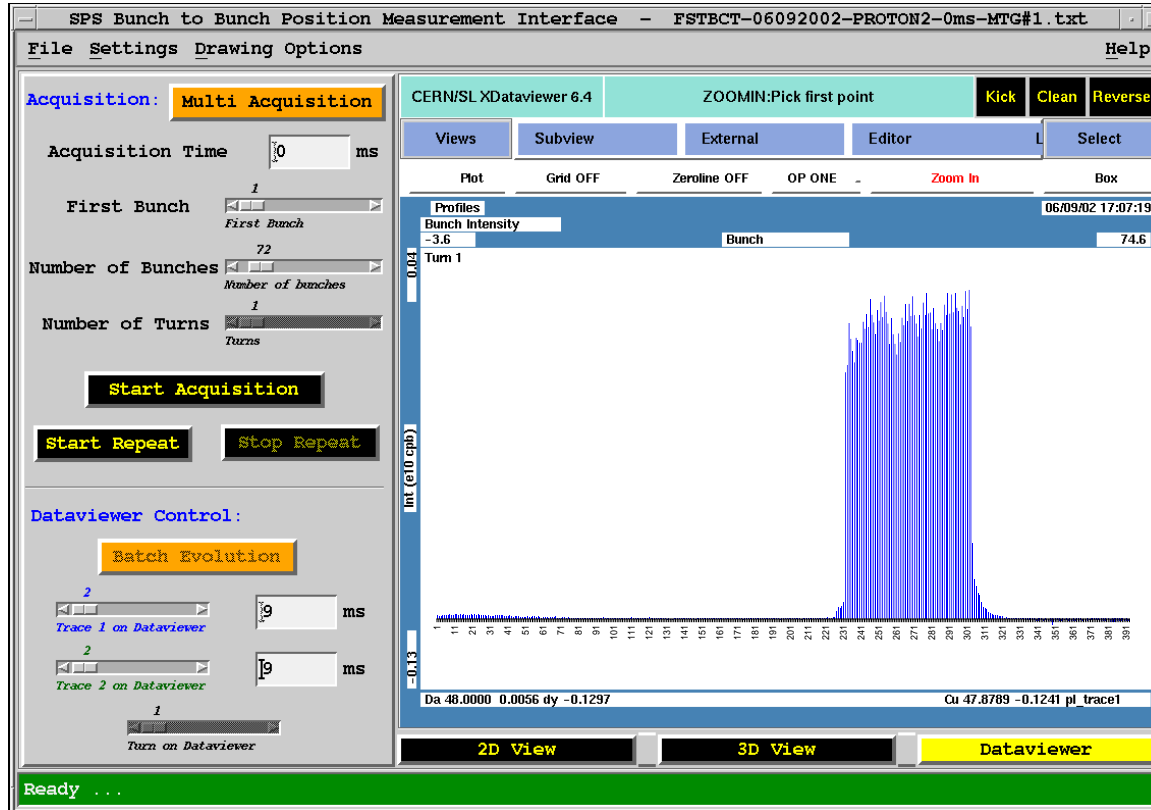
- Secondary Emission Yield (SEY) – emitted / impacting electrons
 - When SEY > threshold → multipacting (avalanche effect)
- Possible detrimental consequences:
 - Beam quality degradation: instabilities, emittance growth
 - Impact on the machine: vacuum degradation, background, heat load
- SEY can be reduced through electron bombardment (scrubbing)

LHC electron cloud diagnostics with BCTs

- Instabilities in tails of bunch trains \rightarrow increasing beam size \rightarrow beam losses
- Countermeasures:
 - Chromaticity
 - Transverse feedback
 - Beam scrubbing
- Diagnostics:
 - **Fast BCTs** – bunch-by-bunch intensity measurements
 - **Synchrotron Light Monitor** – bunch-by-bunch profile measurements



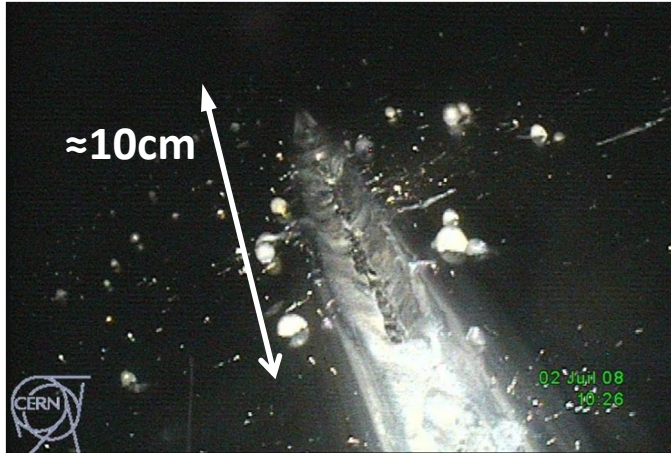
RF capture diagnostics with BCTs



Beam Loss Monitors (BLMs)

Beam Loss Monitoring

- Main functions of a BLM system:
 - Protect the accelerator from damage
 - Safely extract the beam to avoid superconducting magnet quenches
 - Provide diagnostics data to improve accelerator performance



2008 SPS incident: 2 MJ beam lost at 400 GeV

LHC beams and loss limits

Stored Energy

Beam 7 TeV	2 x 362 MJ
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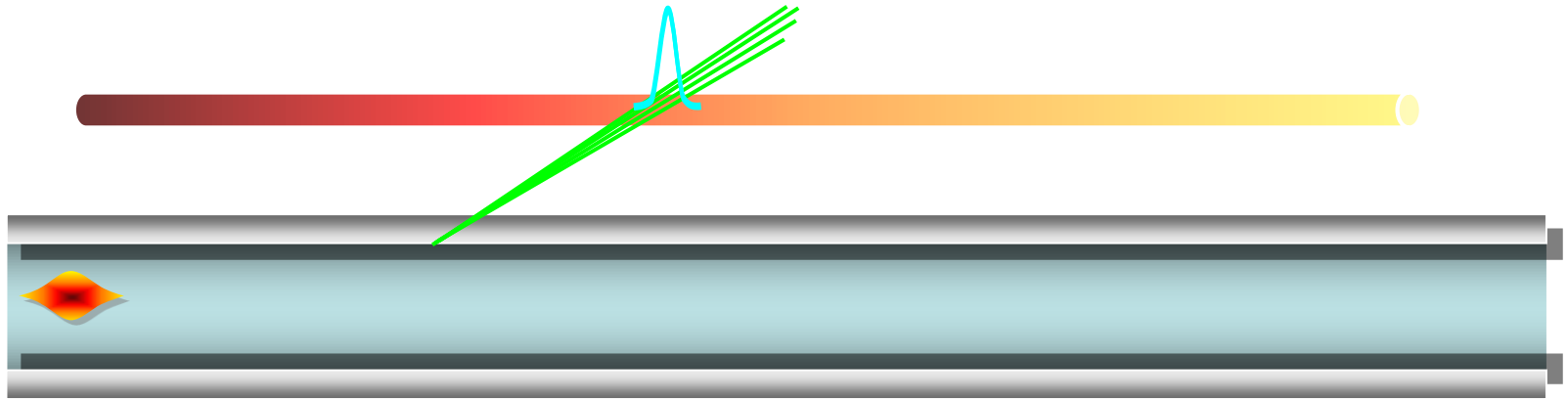
Quench and Damage at 7 TeV

Quench level	$\approx 1 \text{ mJ/cm}^3$
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Damage level	$\approx 1 \text{ J/cm}^3$
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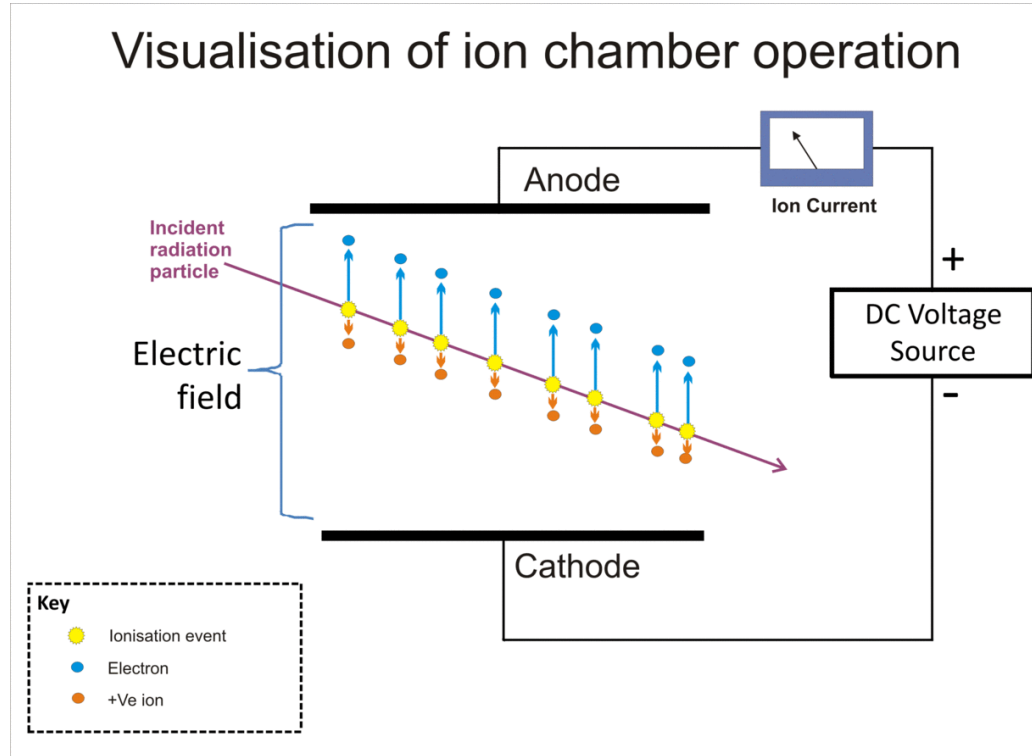
Long BLMs

- **Long ionisation chambers**
 - Several km long coaxial cables filled with gas
 - Detection of direct and reflected pulse – spacial resolution of several meters
 - Dynamic range of up to 10^4
- **Fibre optic BLMs**
 - Electric signals replaced by light generated via Cherenkov radiation



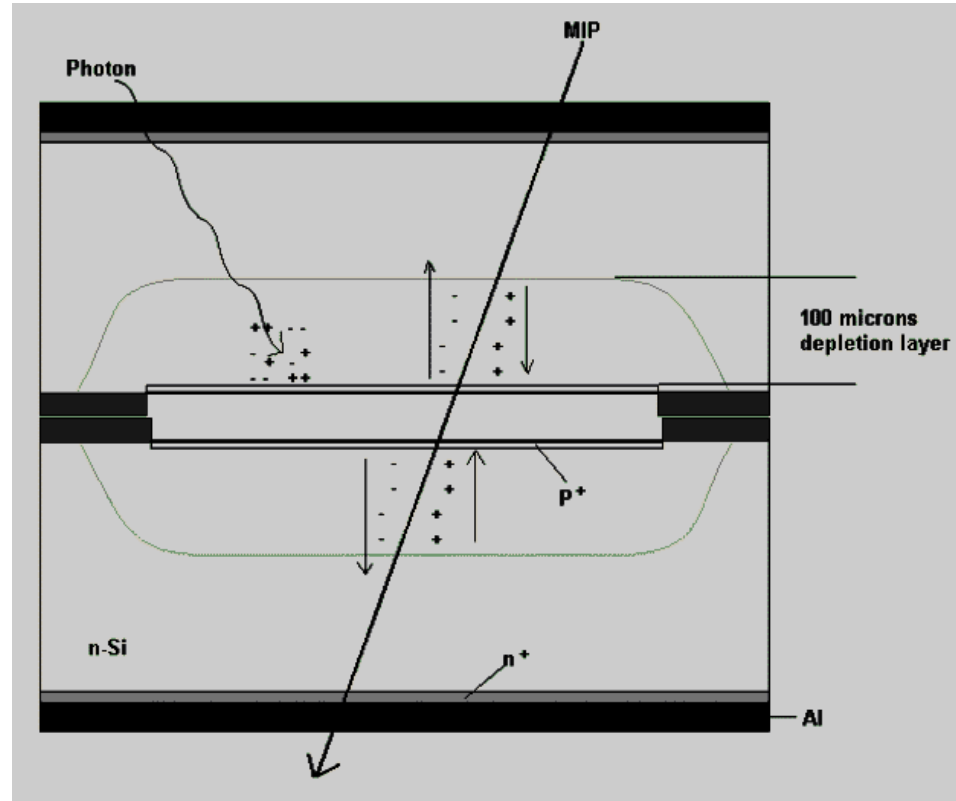
Ionisation chamber BLMs

- Formed by metal plates, filled with inert gas, high potential across the plates
- Electron-ion pair creation by high-energy particles = current on electrodes
- Dynamic range of $< 10^8$
- Slow response (μs) due to ion drift time
- Very radiation tolerant, long lifetime (20+ years)



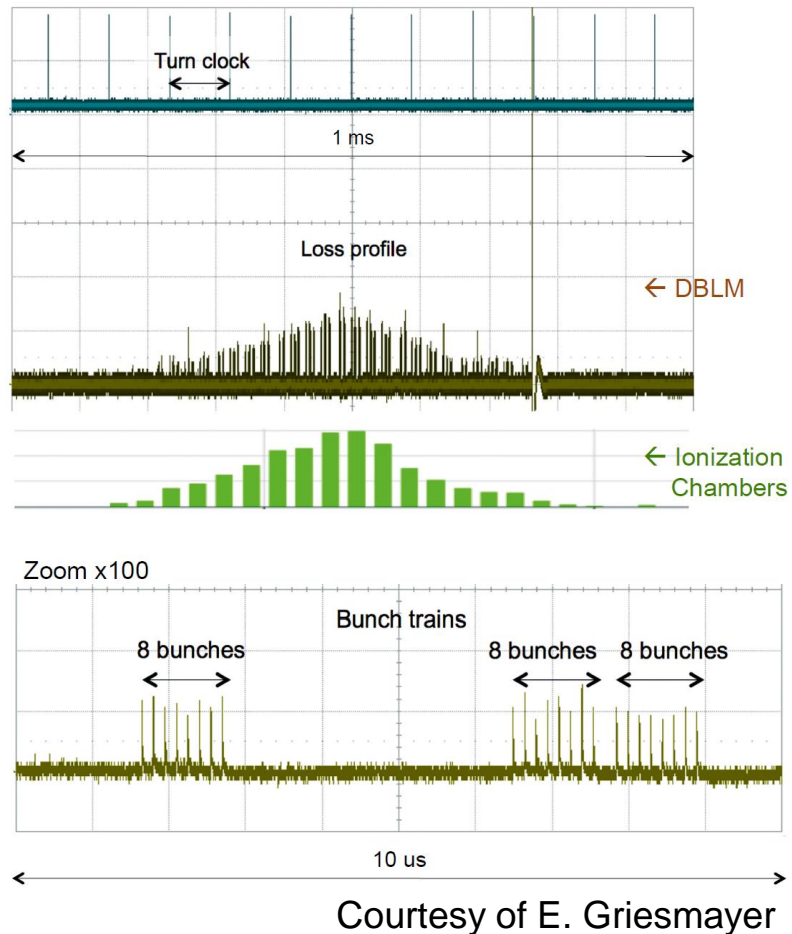
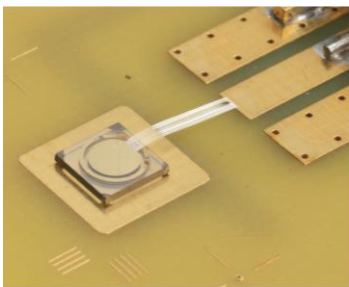
PIN photodiode BLMs

- Two reverse-biased PIN photodiodes mounted face-to-face
- Detect coincidence of ionising particles crossing both diodes
- Count rate proportional to beam loss – limited by integration time
- Can distinguish X-rays (low coincidence) and ionizing particles (high coincidence)
- Dynamic range up to 10^9



Diamond BLMs

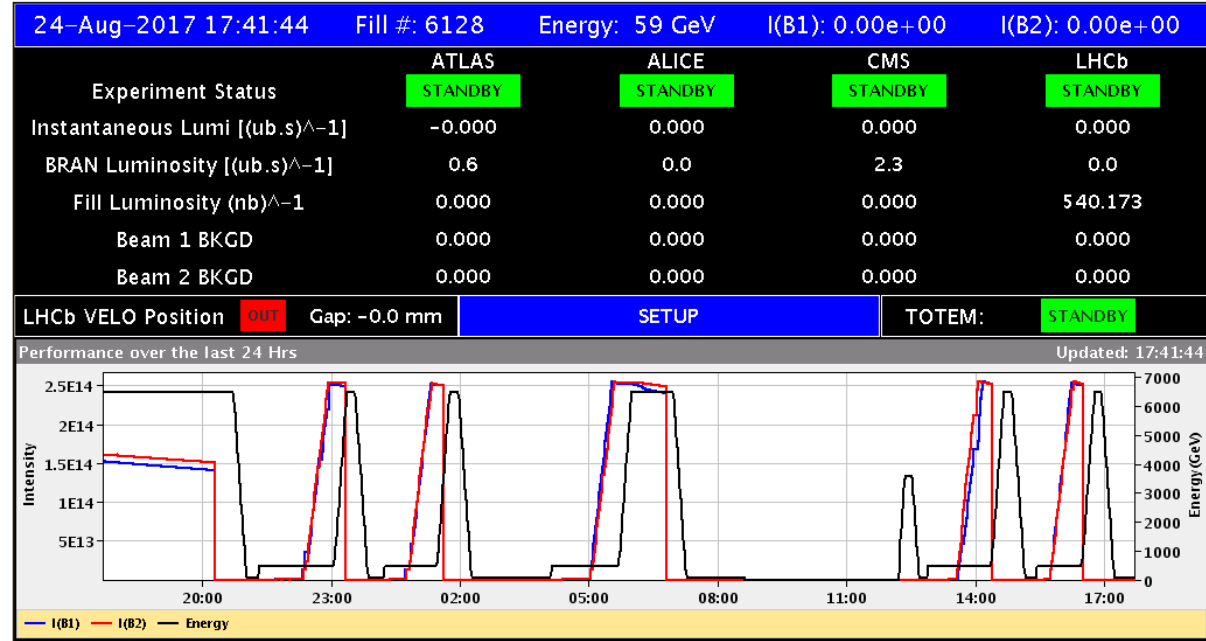
- pCVD diamond between two metal electrodes
- Ionizing particles crossing the diamond generate current flow between the electrodes
- Very fast response time (ns)
- Used in the LHC for bunch-by-bunch losses



Courtesy of E. Griesmayer

“LHC 16L2” diagnostics with BLMs – motive

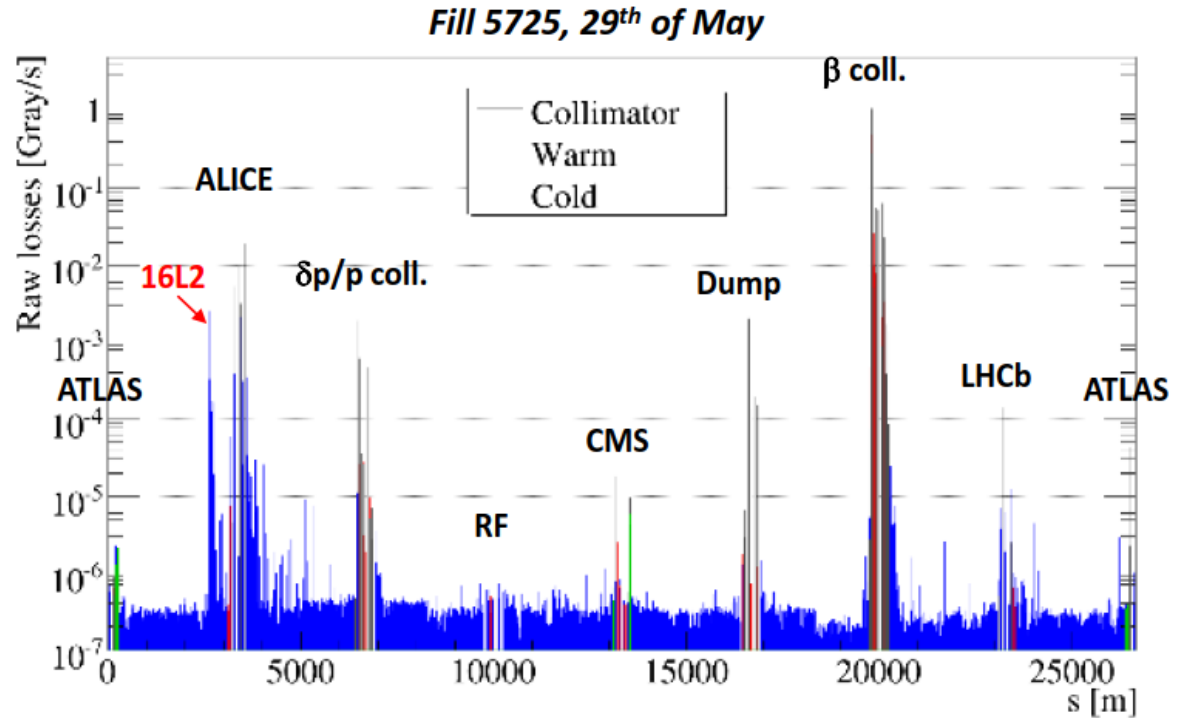
- Beam lost over and over again due to excessive losses
- Significant impact on the LHC availability in 2017



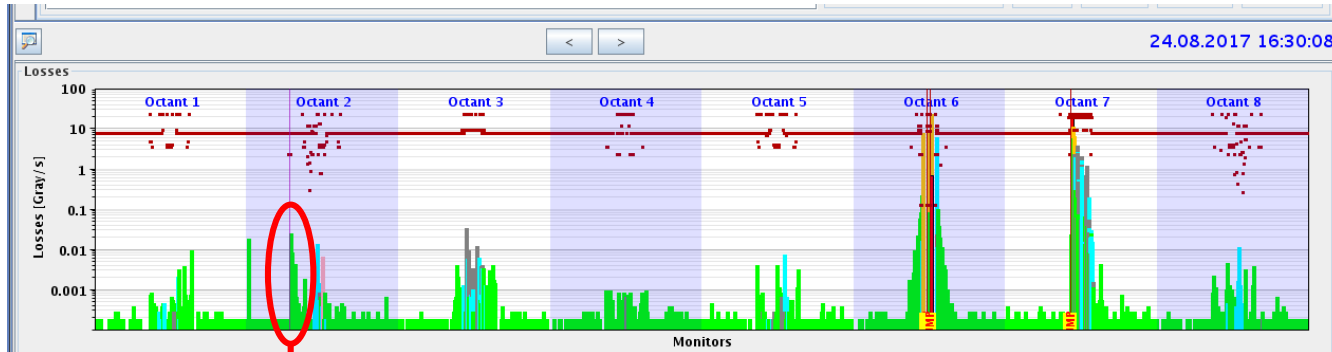
Dump	RF	Dump	Dump	Dump
#1	issue	#2	#3	#4
5.9TeV		7TeV	0.9TeV	0.8TeV

“LHC 16L2” diagnostics with BLMs – first event

- No aperture restriction seen after local measurements
- Clear signature of losses from both beams



“LHC 16L2” diagnostics with BLMs – loss evolution



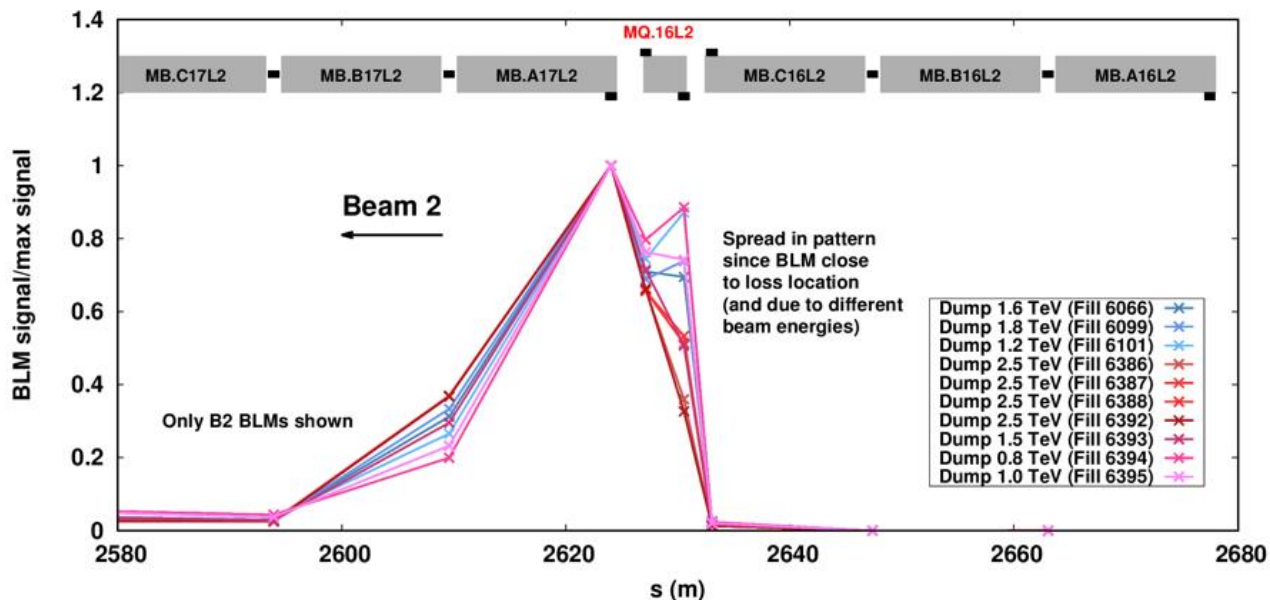
“LHC 16L2” diagnostics with BLMs – extra sensitivity

- How to quickly improve BLM sensitivity by a factor of 15



“LHC 16L2” diagnostics with BLMs – exact location

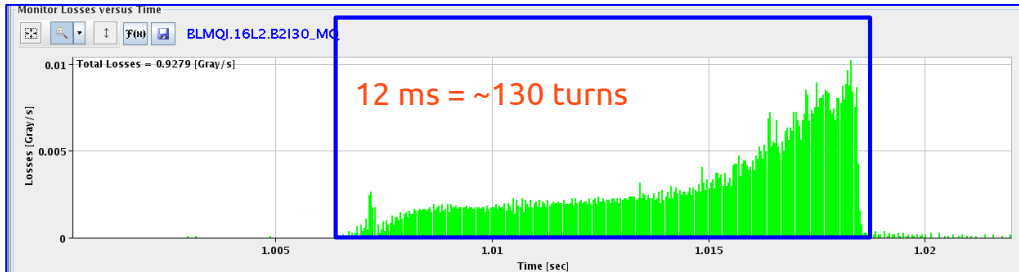
- BLM spatial patterns clearly indicate losses from one specific interconnection: quadrupole 16L2 (within 1 m)



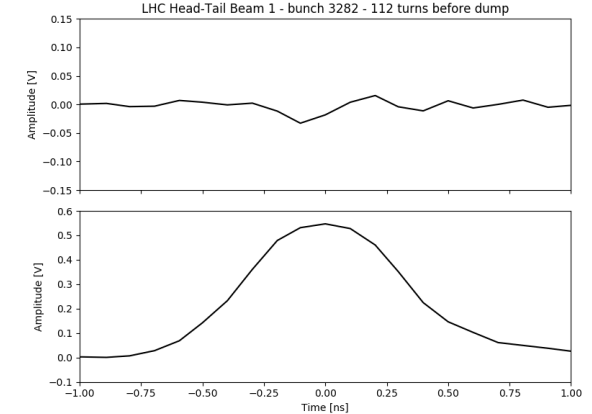
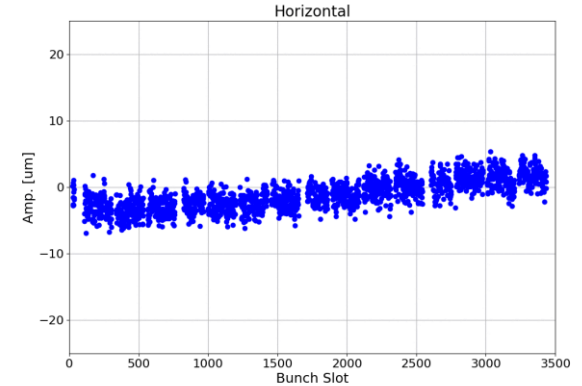
“LHC 16L2” diagnostics with BLMs – additional data

- Many dumps triggered by BLMs near primary collimators (far away from 16L2)
- Indication of a growing transverse instability

Losses at BLM

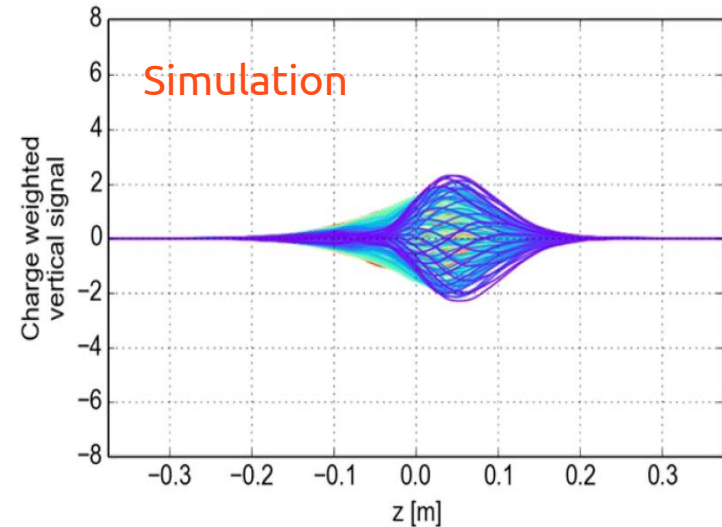
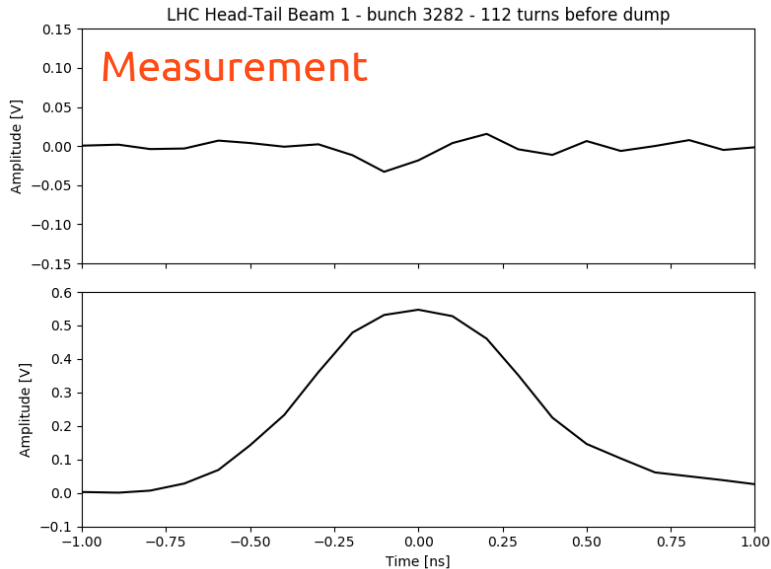


Fill: 6394, B2, Post Mortem, Turn before dump 100



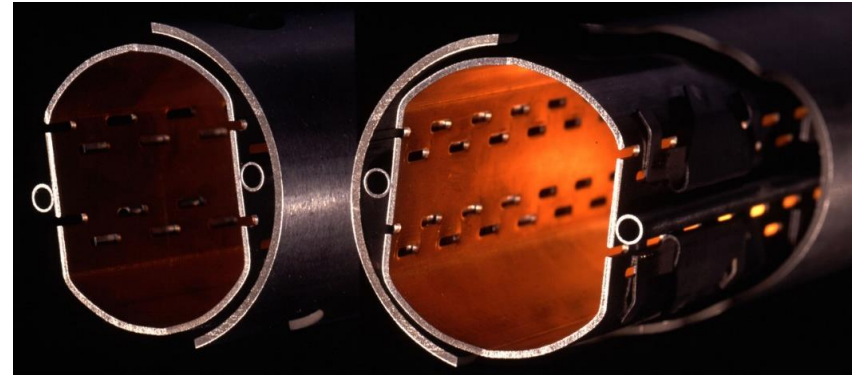
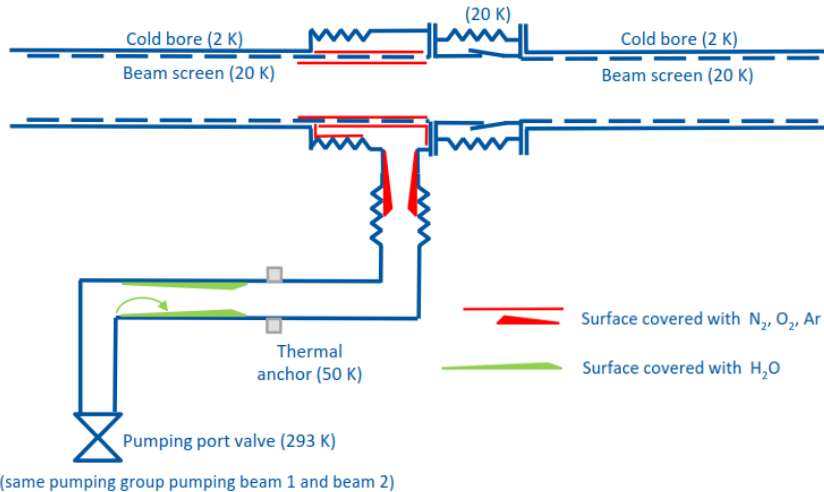
“LHC 16L2” diagnostics with BLMs – additional data

- Clear instability in the tail of the bunches
 - Simulations performed to recreate a similar instability
 - Required conditions: large density of electrons over a short distance – ionised gas cloud



“LHC 16L2” - conclusion

- Some air was trapped on beam screen and cold bore during vacuum pump down
 - Solid nitrogen and oxygen formed inside the beam vacuum
 - Particles fall into the beam and immediately vaporise locally rising pressure
 - Beam interactions produce an ionised gas cloud leading to losses and instabilities



Summary

- Focus of today: general introduction, BPMs, BCTs and BLMs
 - Principle of operation
 - Diagnostics use
- Tomorrow's subjects:
 - Transvers profile monitoring
 - Tune, coupling and chromaticity measurements and feedback
- For those following the BI afternoon course:
 - 3 sessions on beam signals and BPM design: 2 x simulation software + 1 x practical hands-on exercises
 - **Please install the BI simulation software on your laptop today!**
 - 3 sessions on profile measurements (transverse and longitudinal): hands-on experiments