

The background of the slide is a vector field of black arrows. The arrows are arranged in a grid and their direction varies across the frame, generally pointing from the top-left towards the bottom-right, with some variations in angle and length. The background color is a gradient from light blue on the left to a darker cyan on the right.

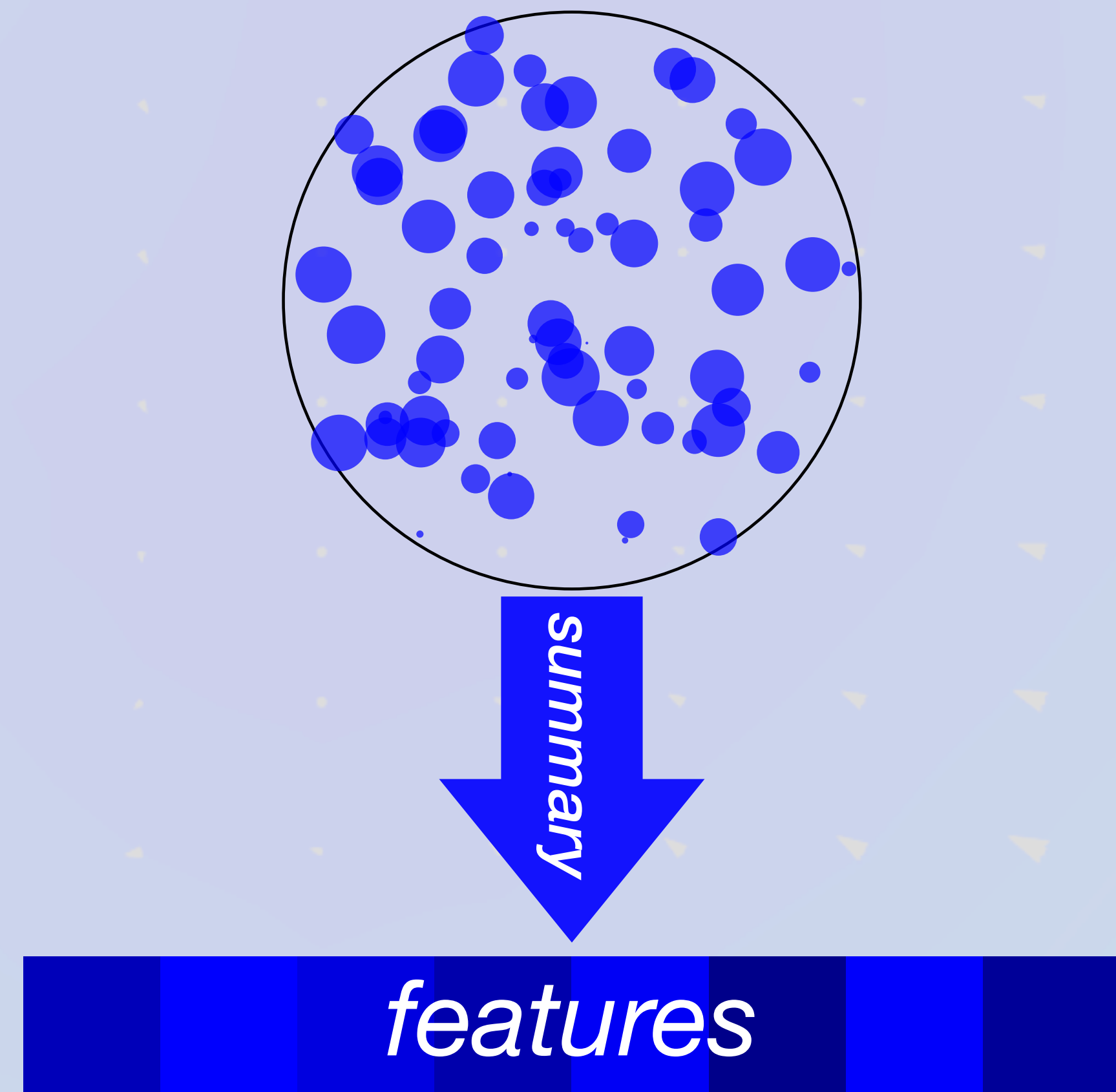
**a continuous calibration of
the ATLAS flavor-tagging classifiers
via optimal transportation maps**

Chris Pollard, Warwick
for the ATLAS collaboration

**incredible progress in recent
years...**

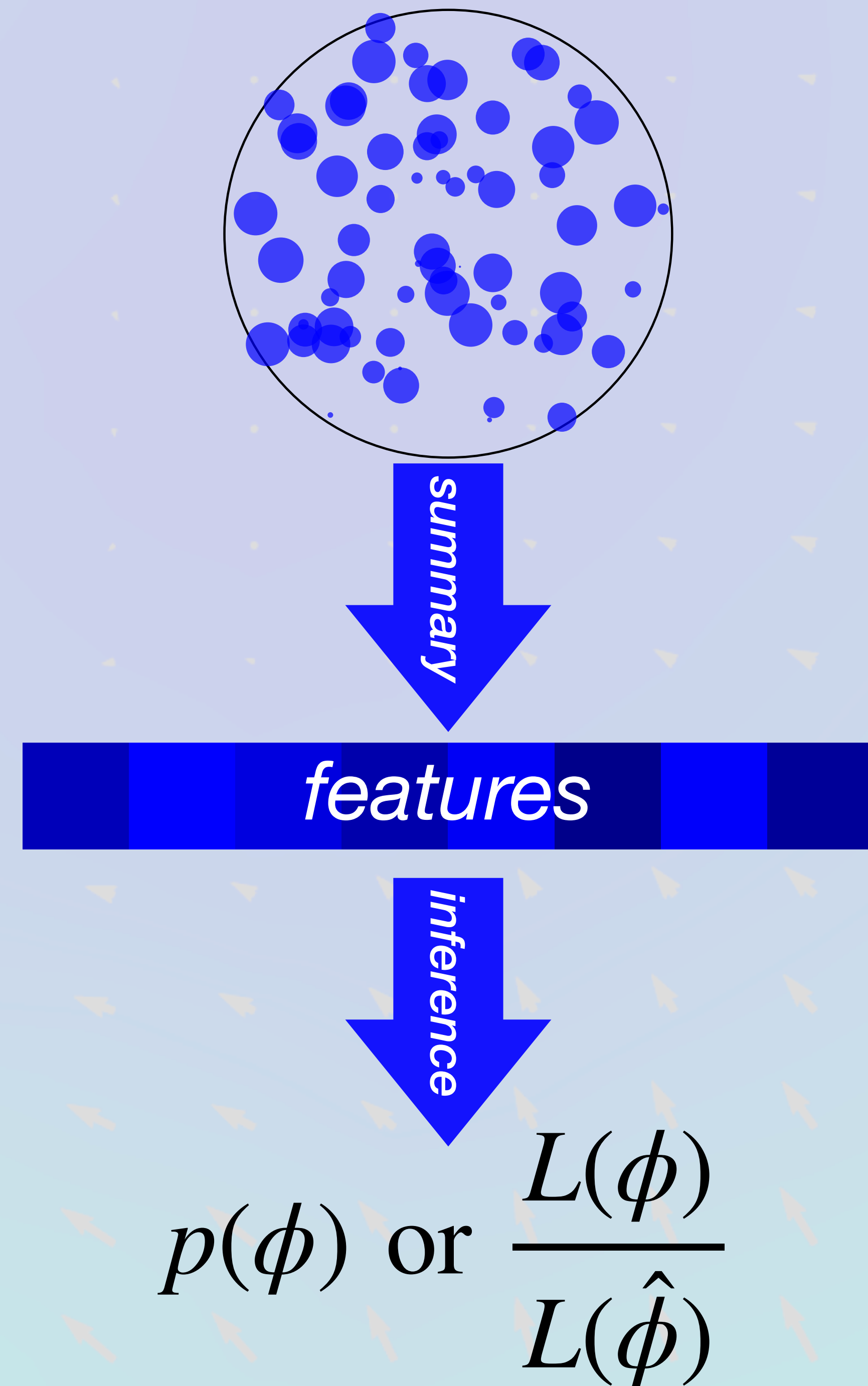
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- huge growth in constraining power of observed data



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correctness: we don't have a simulator that *adequately describes all details* of the data!

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indeed, this is perhaps the main “point” of constructing jets:

- we cannot correctly predict the details of QCD with arbitrary accuracy;
- *we can* predict the “large-scale structure” of the fragmentation of partons → jets.



*“large-scale structure”:
calculable features*

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- we can often *measure* the density over some informative features better than we can predict it.
- a *calibration region* may be used to measure said density and the simulation *corrected* based on this measurement.
- this is inherently a *mis-specification* problem, and one we're trying to learn how to solve generally!

we have a recipe for reweighting a density $p(\vec{x})$ (e.g. sim) to $q(\vec{x})$ (e.g. data):

● $w(x) \approx \exp D_p^q(\vec{x})$ for a data vs. simulation discriminator, $D_p^q(\vec{x})$.

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● for “reasonably behaved” \vec{x} , p , and q , at least one T exists.

● usually want to change the simulation *as little as possible*:

◆ i.e. find the \hat{T} that minimally (or “optimally”) morphs p into q ;

◆ this is an *optimal transport* (OT) problem.

we have been implicitly using OT for decades in HEP:

- correct a gaussian density \leftrightarrow alter μ, σ of simulated distribution.

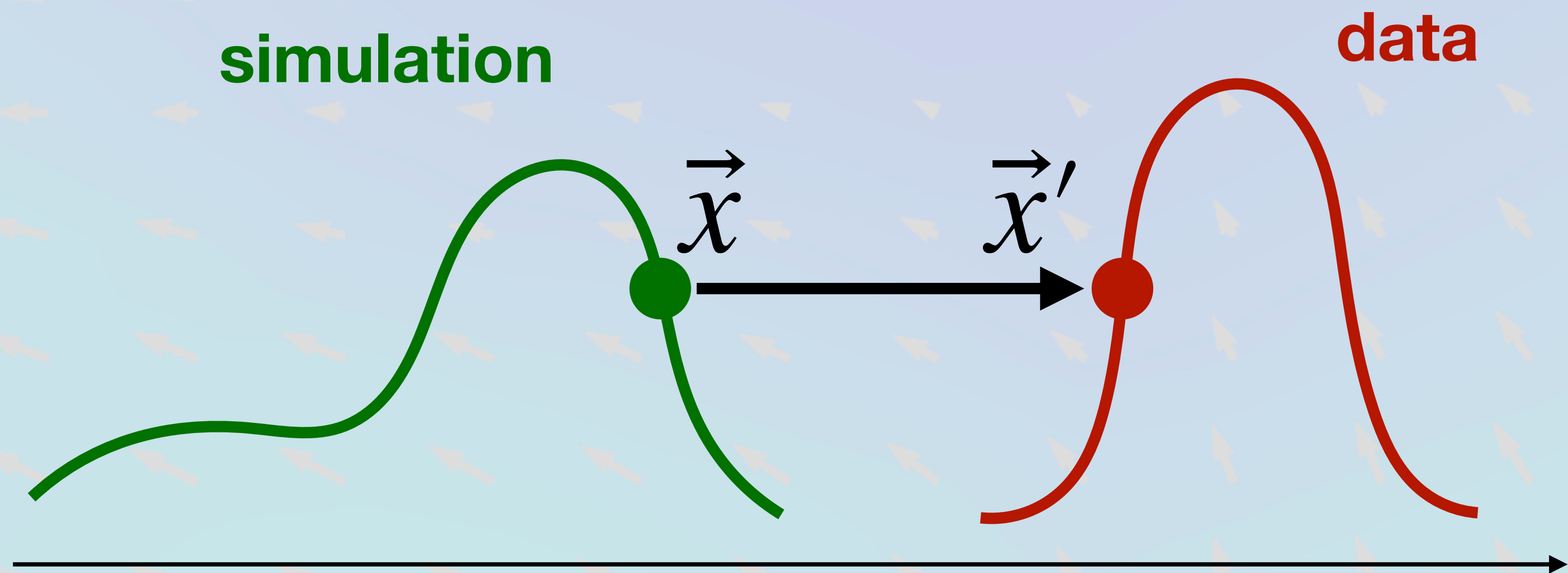
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neural OT generalizes this process.

- for euclidean spaces, the OT map is the gradient of some convex potential:

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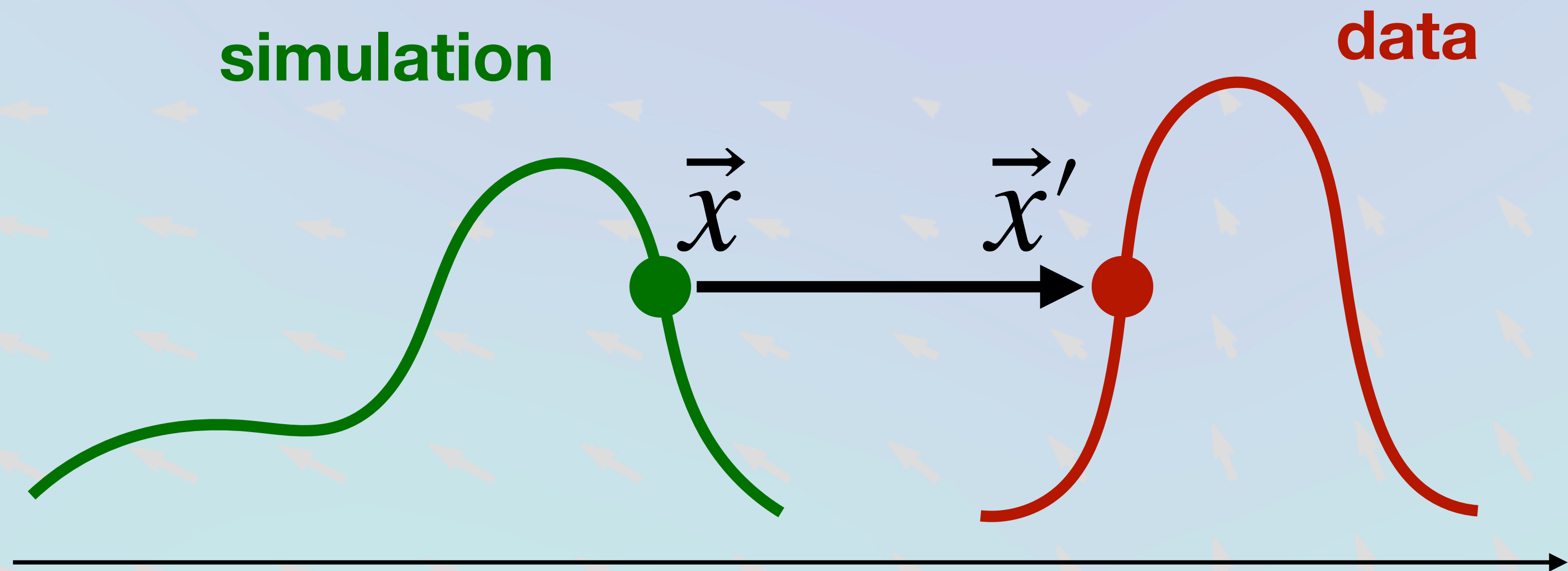
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- partially-convex neural networks learn ϕ_z and therefore \hat{T}_z :

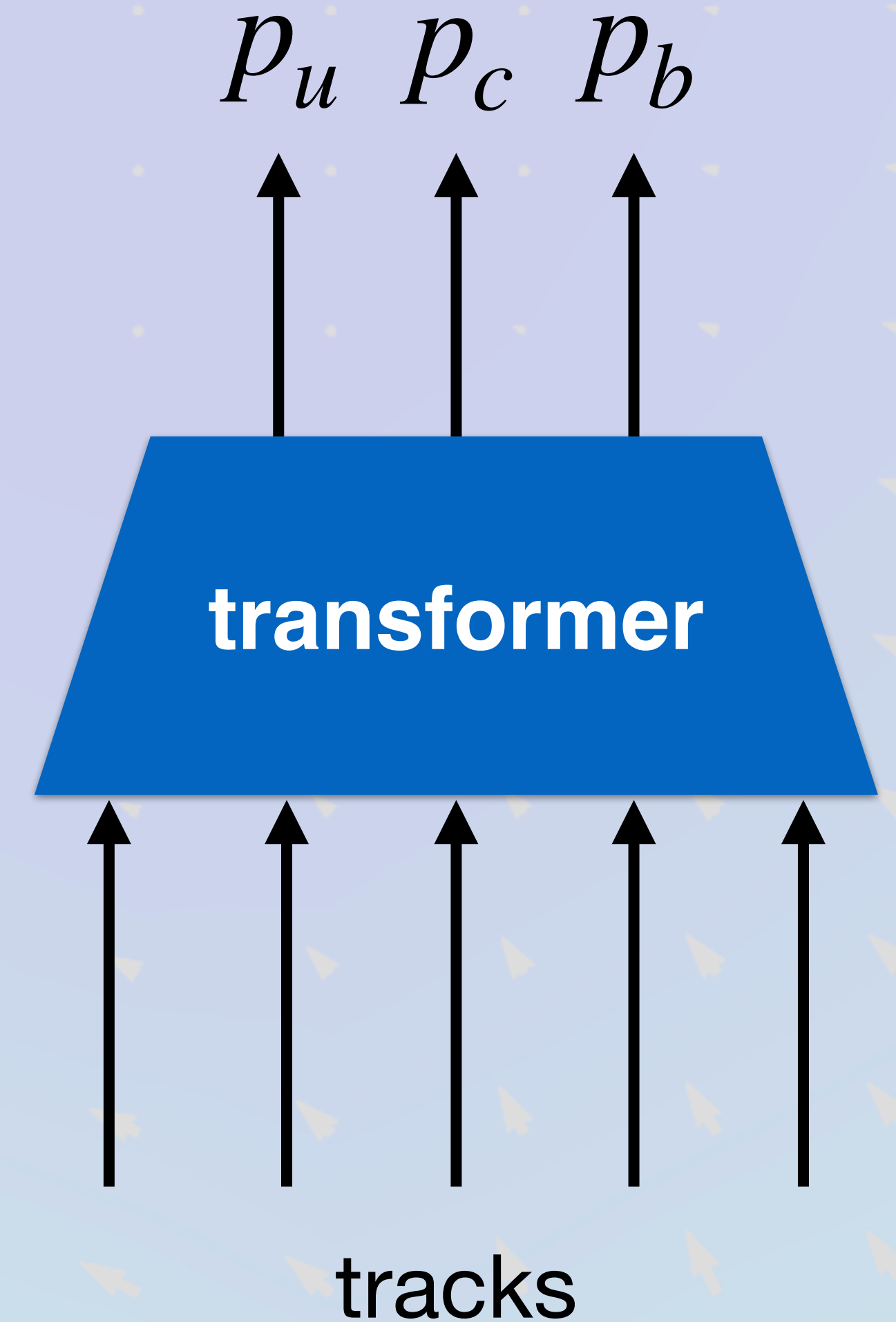
- ◆ the OT map is *conditional* on z .



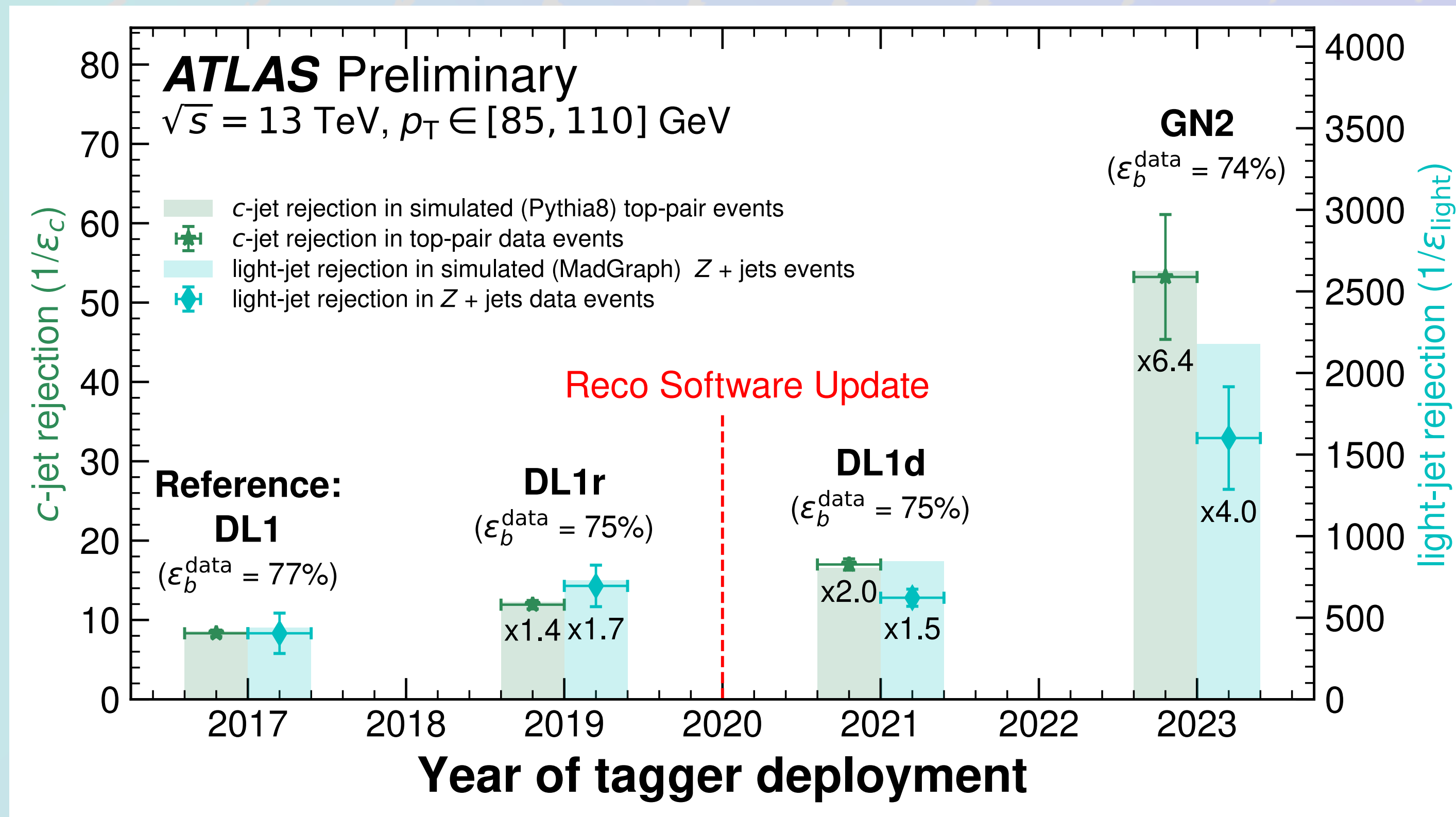
jet flavor-tagging is a classification problem:

- ATLAS's classifiers emit the probability of a jet to contain a b -hadron, c -hadron, or neither (p_b, p_c, p_u).
- modern algorithms are transformer-based:
 - ◆ charged-particle tracks as “point cloud” inputs.
 - ◆ see [Greta's overview](#) for more details
- historically, discriminant scores were calibrated in bins

$$D_b \equiv \log \frac{p_b}{f_c p_c + (1 - f_c) p_u}$$

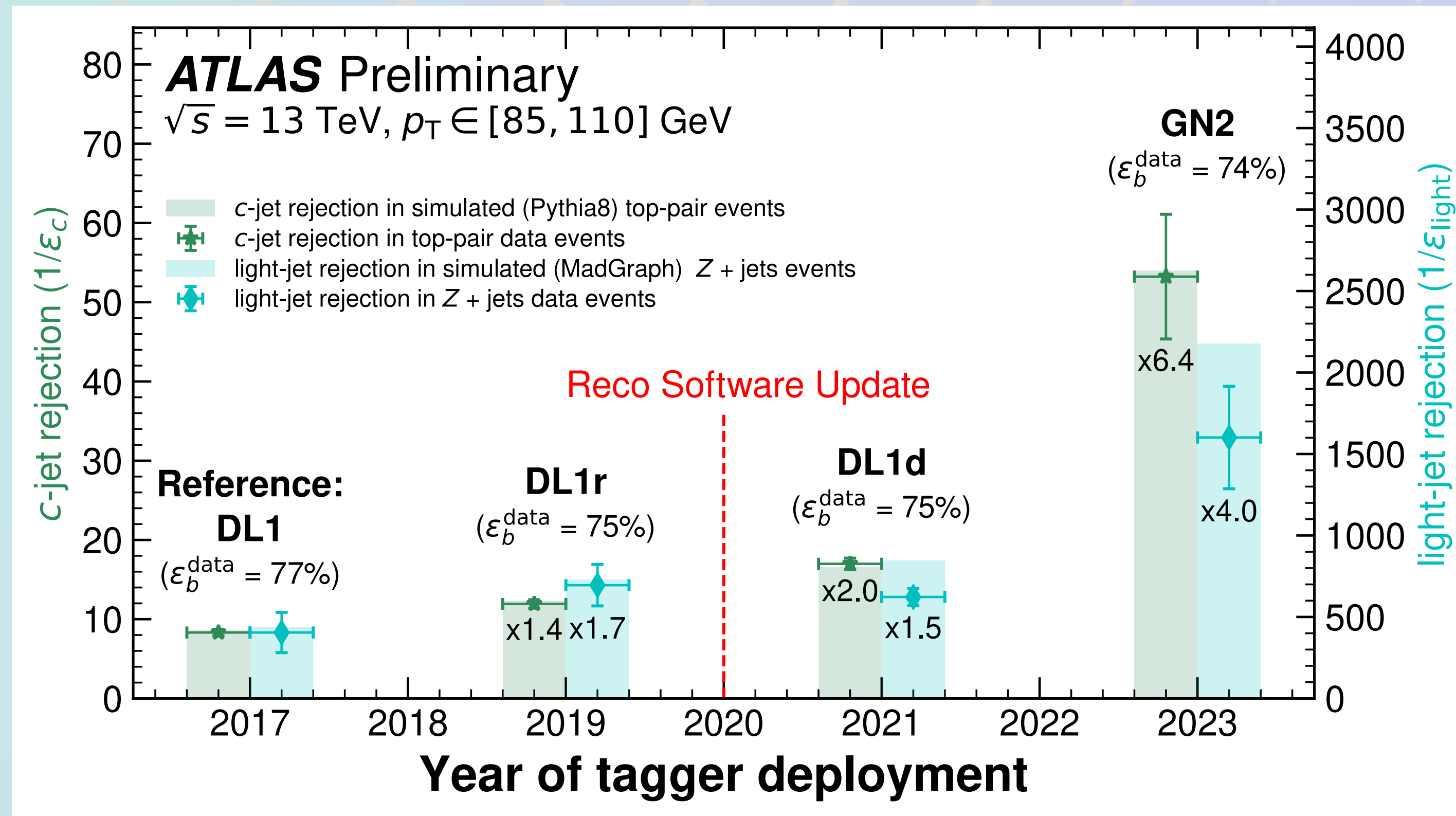


© transformer-based discriminators deliver incredible separating power



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◆ but some clear mismodeling in the simulation.

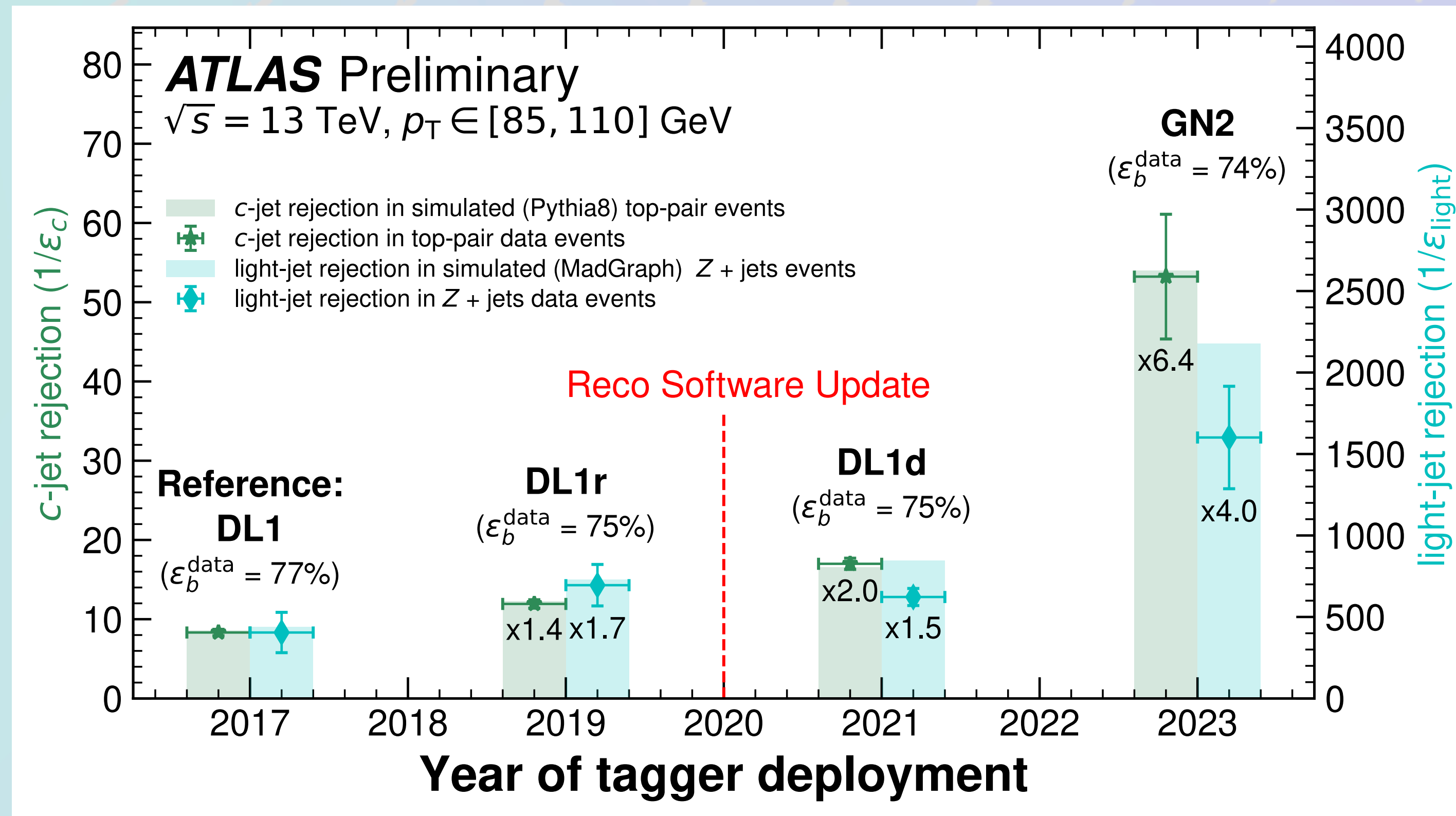


◎ transformer-based discriminators deliver incredible separating power

◆ but some clear mismodeling in the simulation.

◎ until now, we had no direct calibration for the jet flavor probabilities.

◆ to do so, we defined $q_i \equiv \text{logit } p_i$, treated \vec{q} as euclidean, and calibrated via OT.

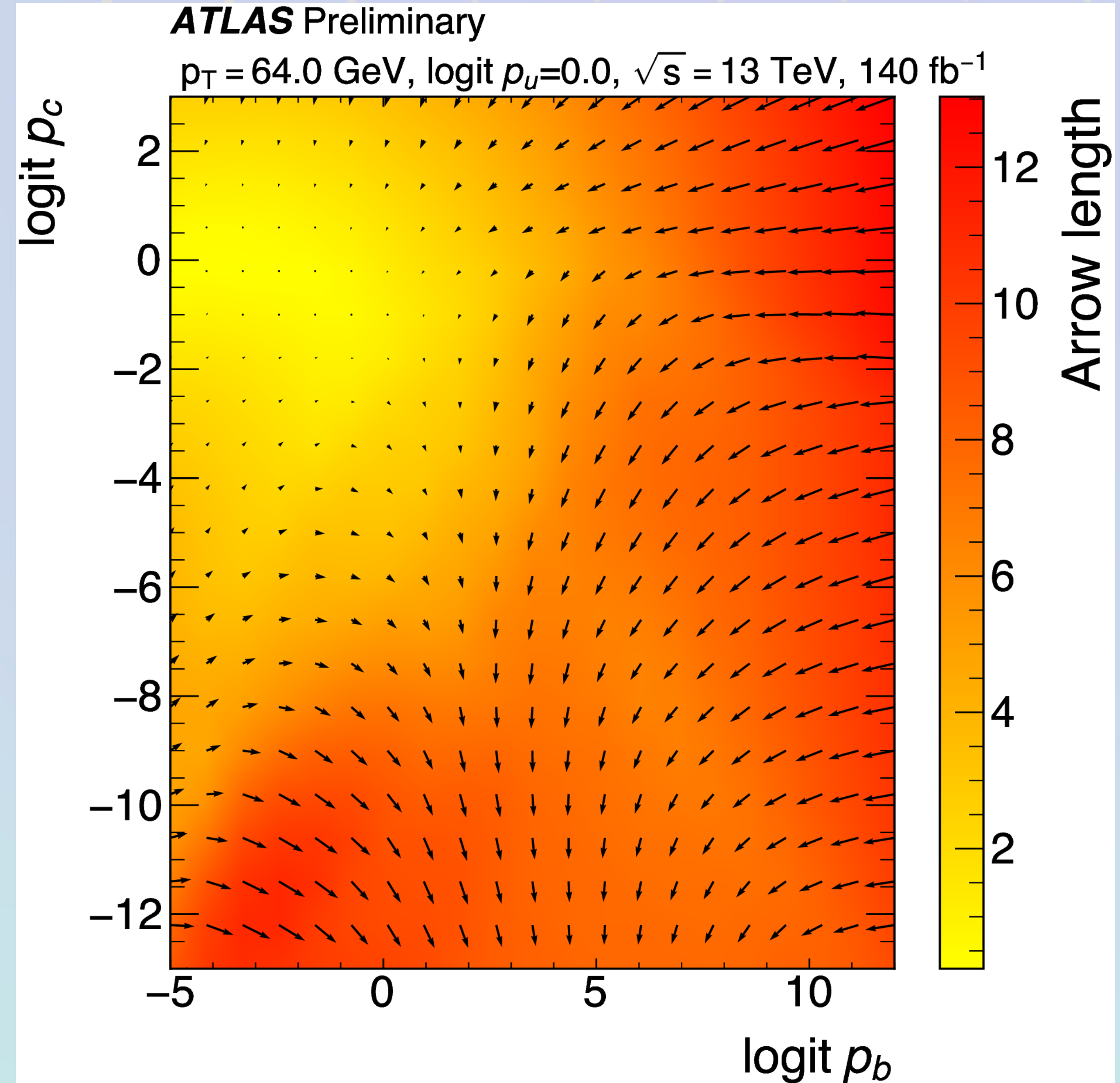


notation:

- $q_i \equiv \text{logit } p_i$: flav. class. scores
- $p'_{\text{sim}}(\vec{q}, p_T) \equiv p_{\text{sim}}(\vec{q} | p_T) p_{\text{data}}(p_T)$
- $\hat{T}_{\#} \equiv p_T$ -dependent OT map

results: light-flavor jets

- we obtain the full 3D OT maps in \vec{q} space s.t. $\hat{T}_{\#} p_{\text{sim}} \approx p_{\text{data}}$
 - derived as a function of jet p_T .
- here we show a 2D slice for $q_b \times q_c$ at fixed $q_u \times p_T$.

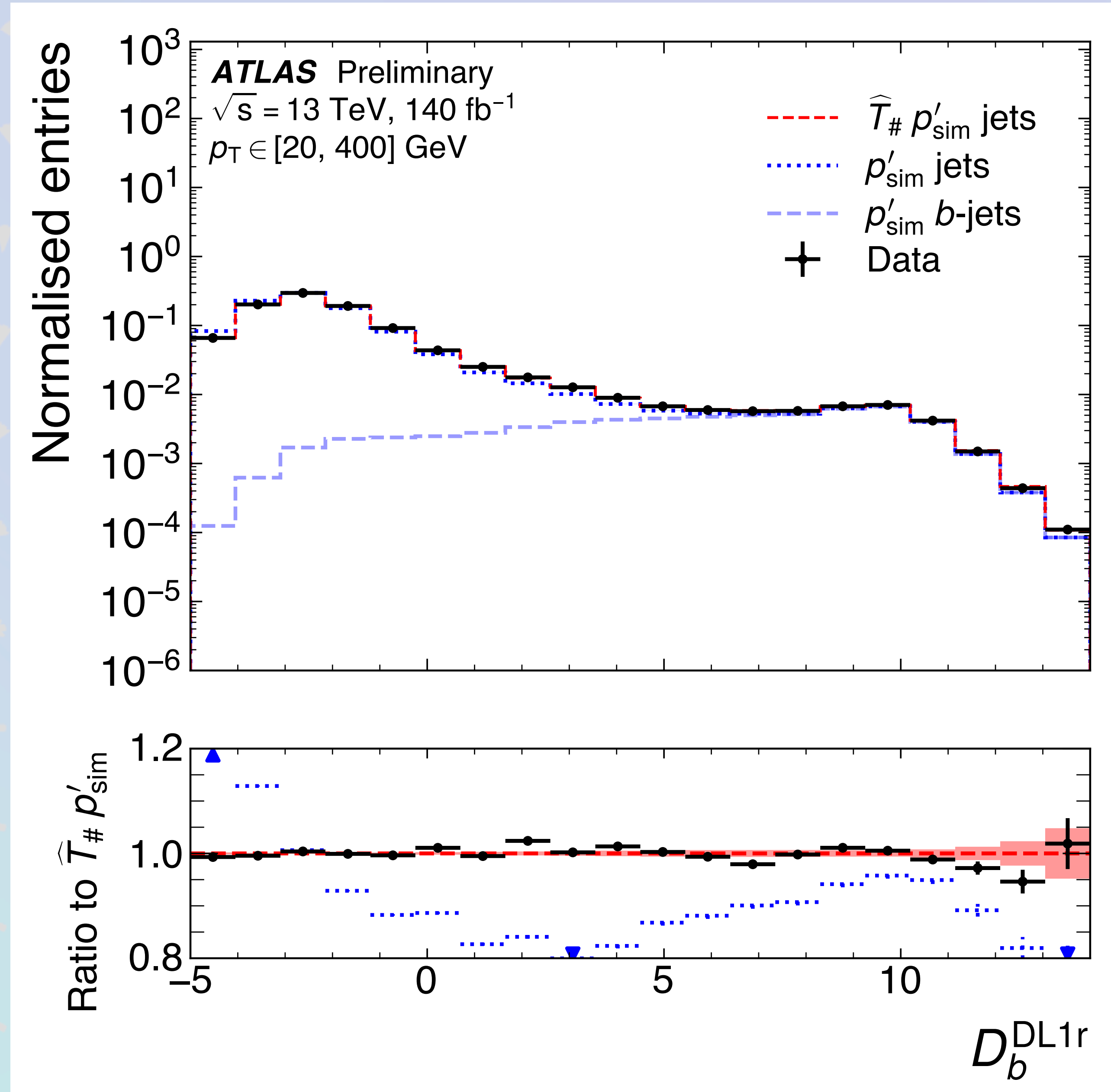


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the technology works!

- very good agreement after calibration, including for D_b .
- D_b was not a calibration target \rightarrow full space of p_i properly corrected.



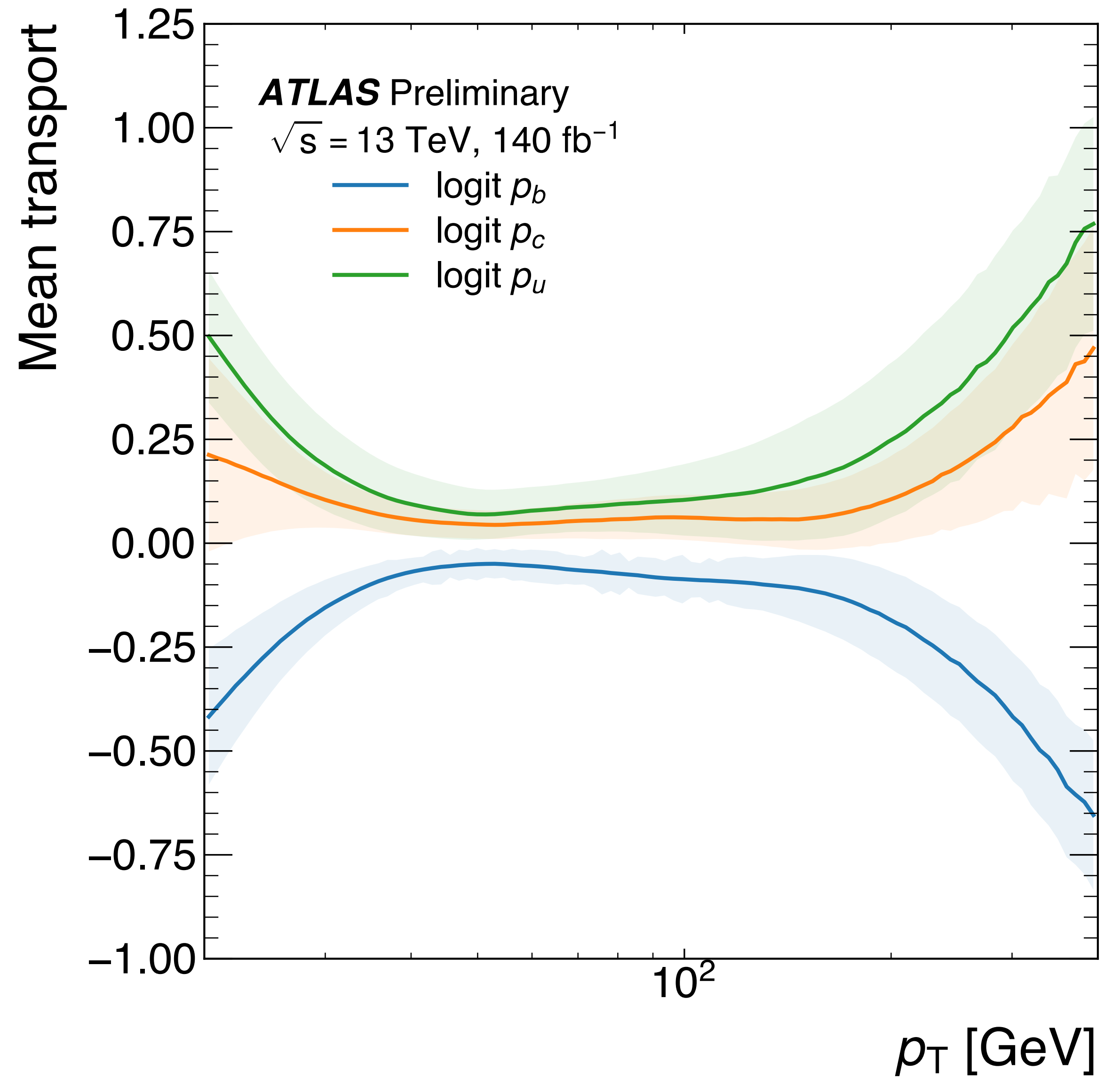
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⦿ for b -jets: $\hat{T} p_b < p_b$, while the reverse is true for p_c and p_u .

◆ the simulation overstates its classification power.

⦿ yields a very fine-grained understanding of mismodeling!

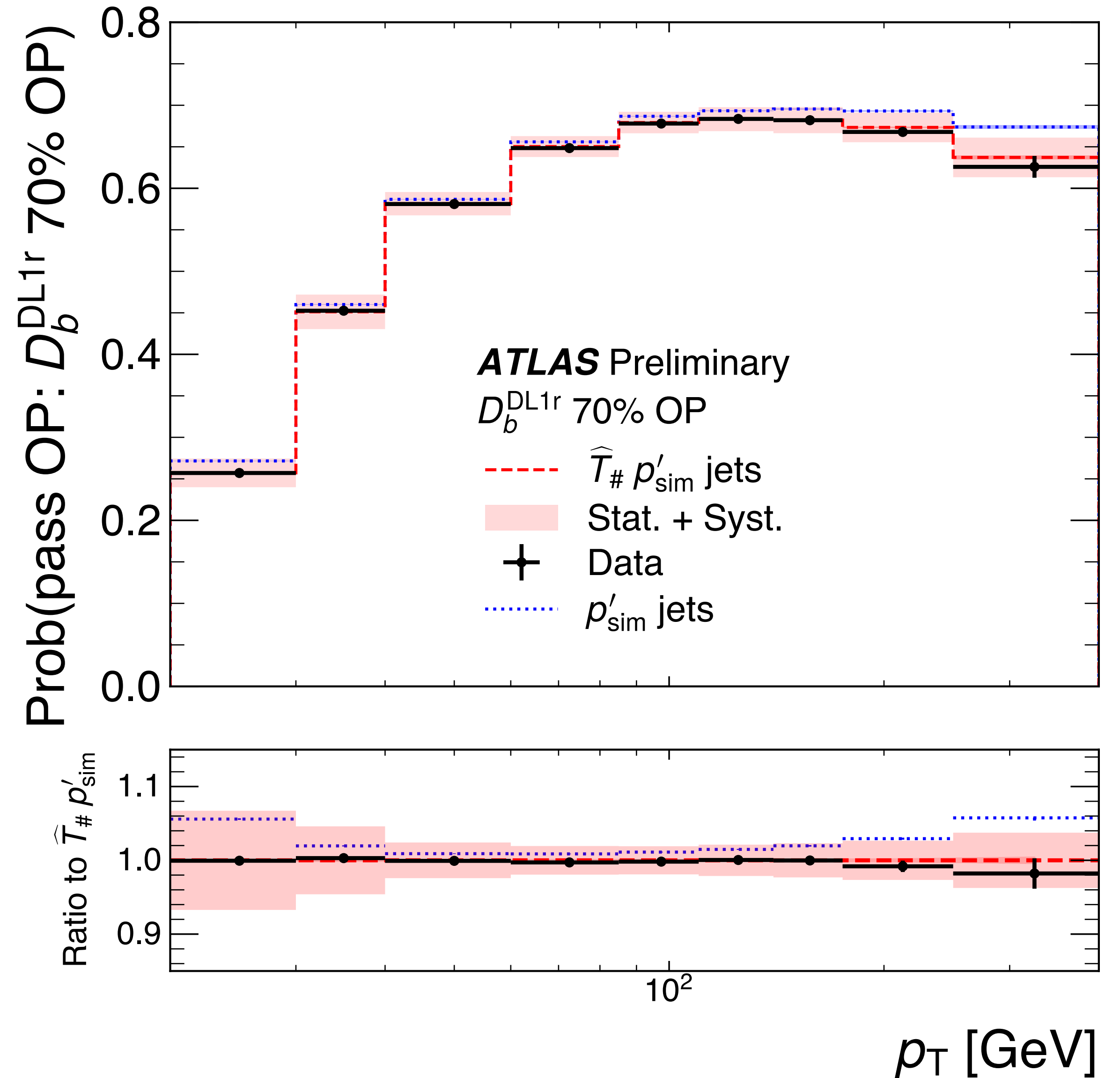


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conventional operating points are “automatically” corrected.

- e.g. this one used for measuring the $H \leftrightarrow b, t$ couplings.



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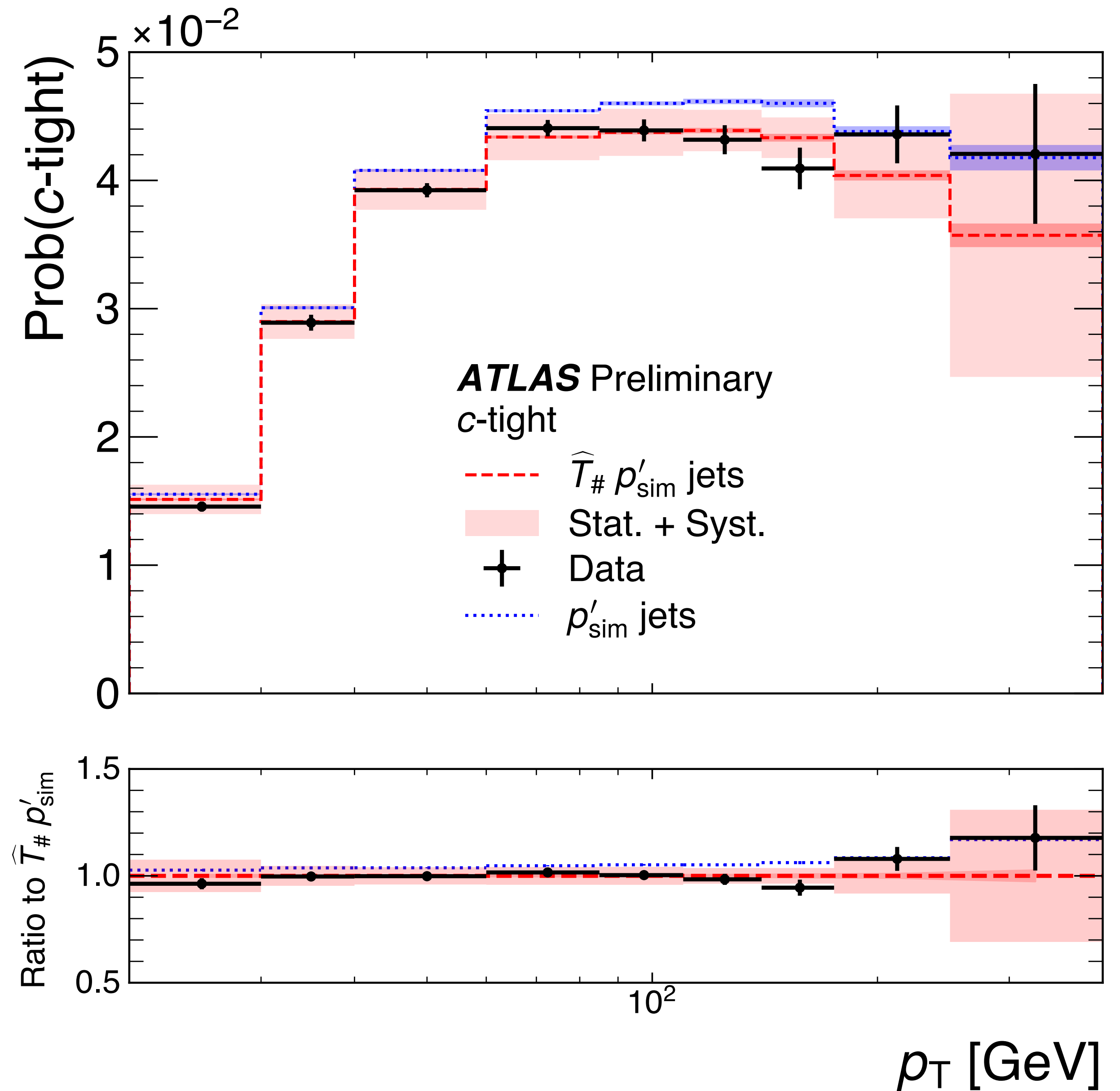
more general uses of flavor-tagging become possible.

◎ discriminator used to constrain

$H \leftrightarrow c$ couplings calibrated
“for free”.

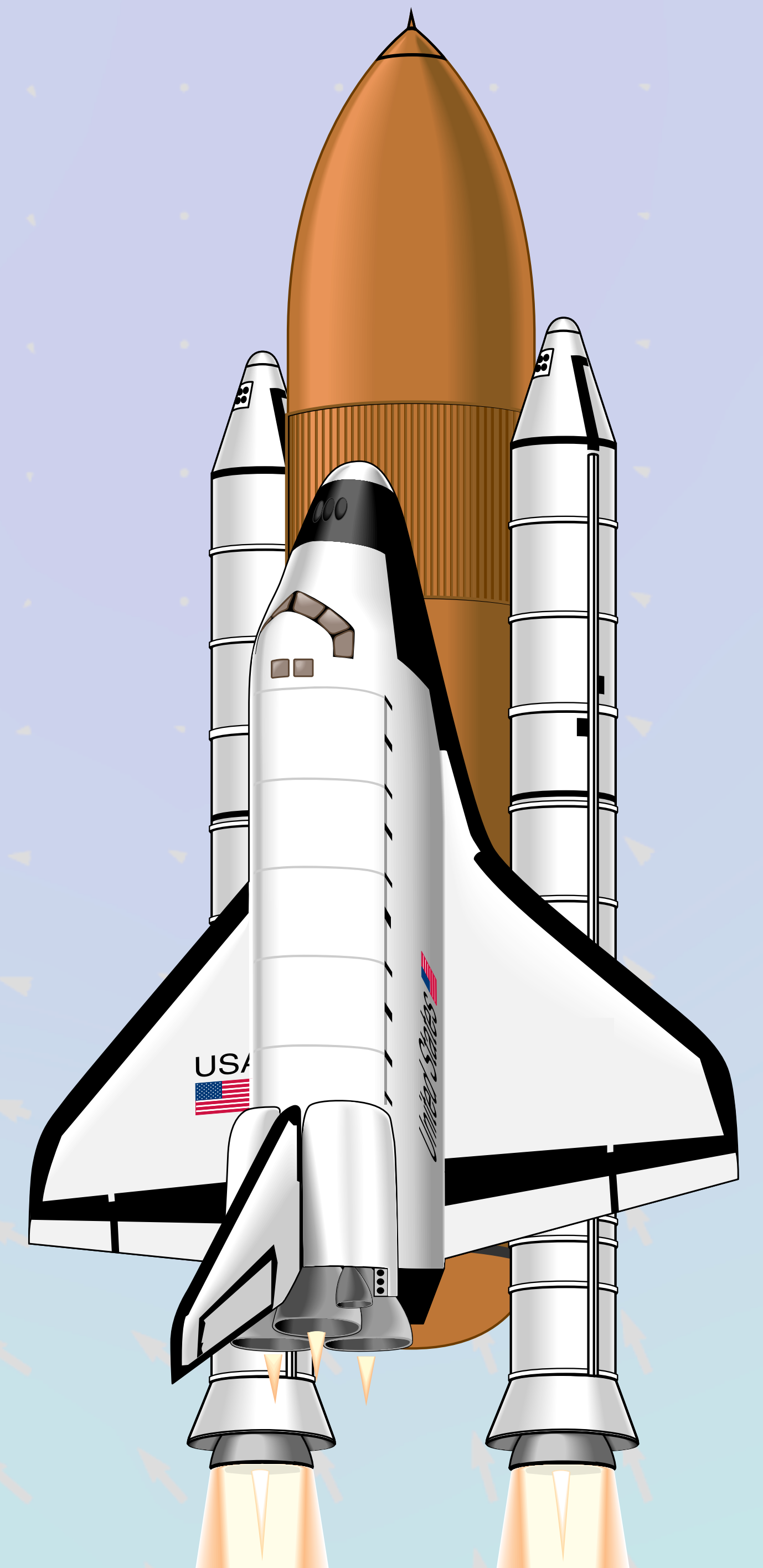
◎ only because the full 3D density

$\hat{T}_{\#} p_{\text{sim}}(\vec{q} | p_T)$ agrees with data.



the future

- here we've performed a first 3+1D continuous calibration via OT.
 - ◆ details and further background reading [[here](#)].
- the technique is *general*: it enables high-dimensional, transport-based calibrations.
- additional (informative) conditionals should result in more *universal* and *precise* calibrations,
 - ◆ allowing *richer* summary statistics for *better inference*.
- *we look forward to seeing what others can do with this technology!*





**thank you,
and happy calibrating!**