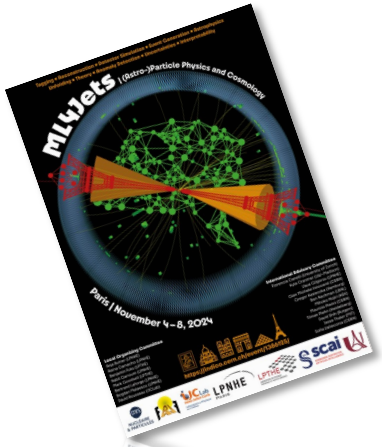


OMNIFOLD-HI

Advanced ML Unfolding for Heavy-Ion Data

Alexandre Falcão*
Adam Takacs

*alexandre.falcao@uib.no

Nov. 7th, 2024

UNIVERSITY OF BERGEN

Recipe to measure a jet observable

detector

event-by-event

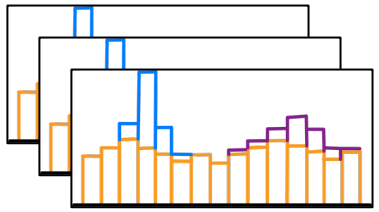
backgroud subtraction

statistics

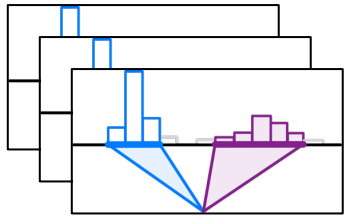
unfolding

theory

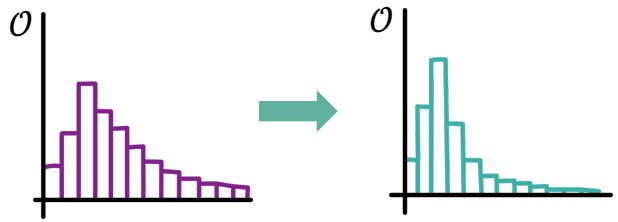
event measurement



event-by-event background subtraction

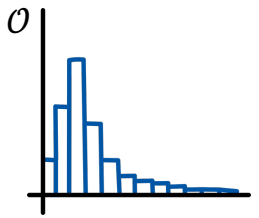


unfolding of detector effects



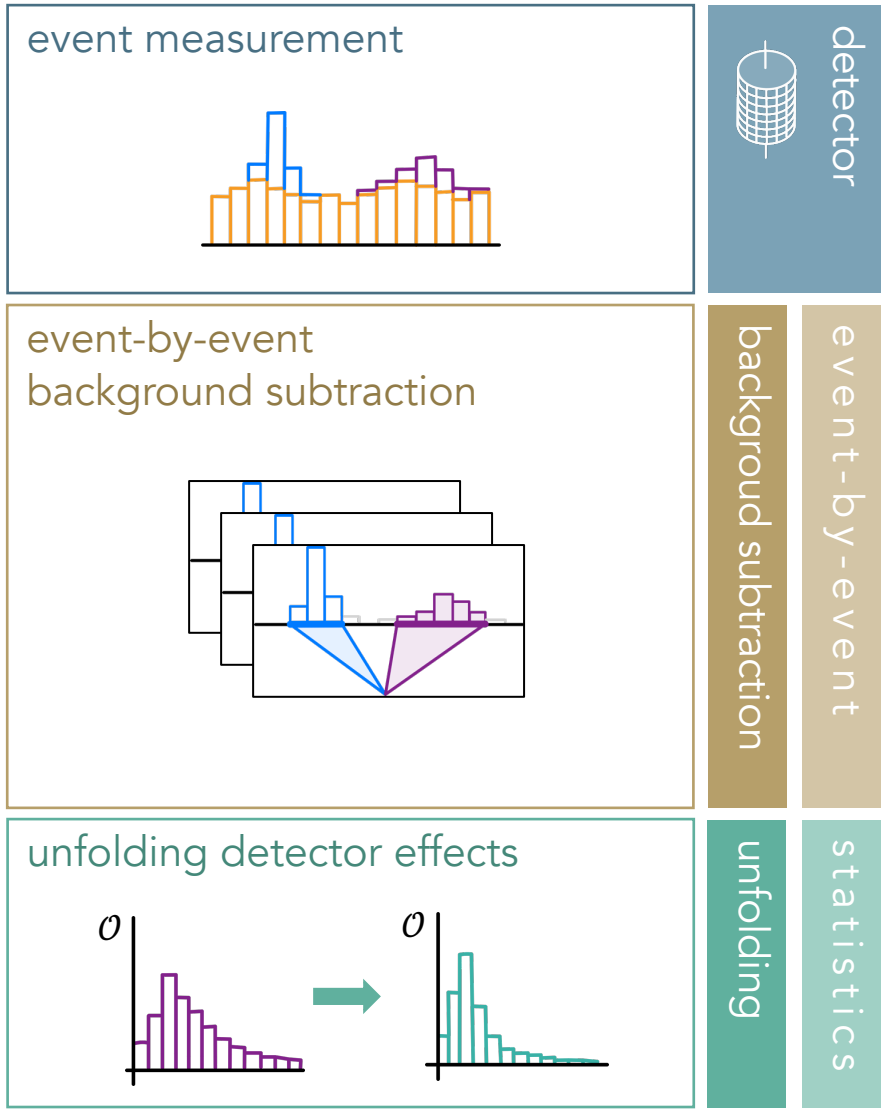
vs.

theoretical model

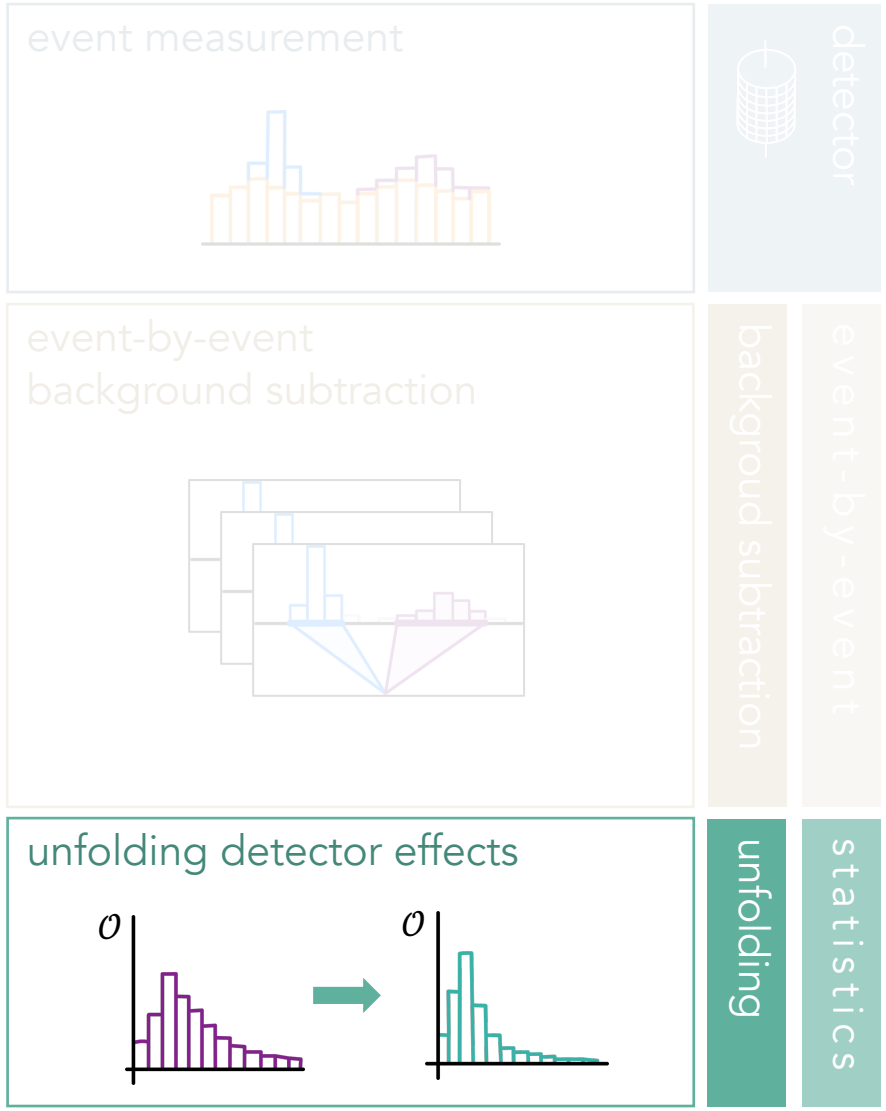


comparison with theoretical models and other experiments

Recipe to measure a jet observable



Traditional unfolding



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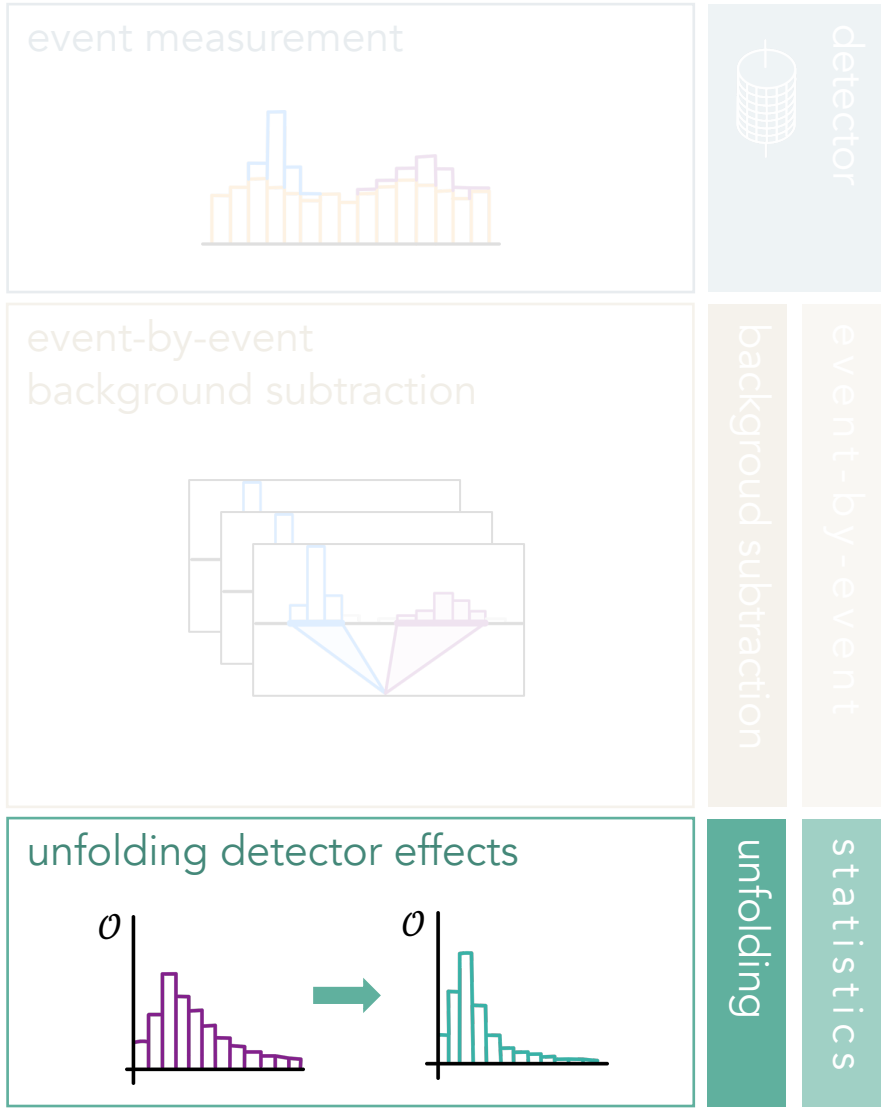
- limited resolution
- inefficiency
- distortion or smearing

A: Statistical proceadure to deconvolute detector effects from observables via detector simulation



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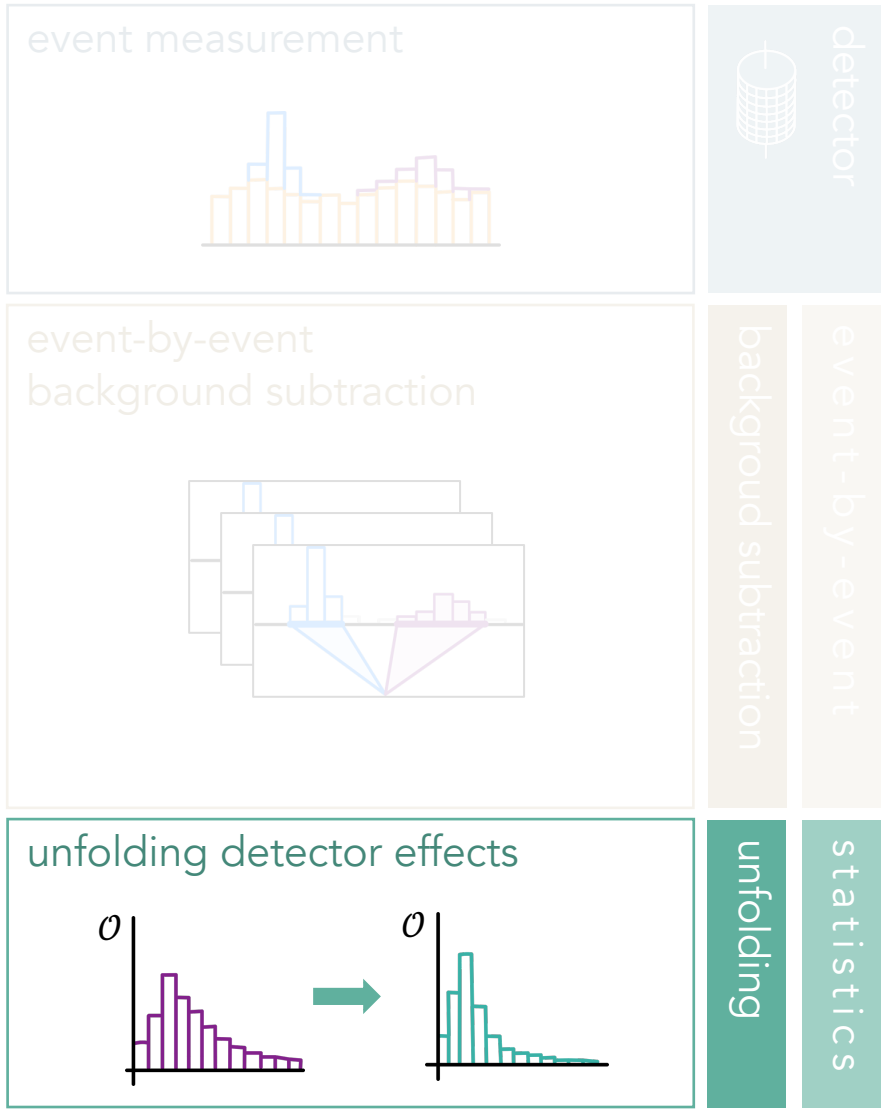
Binned porcedure:

- Iterative Bayesian Unfolding (IBU)

Unbinned procedure (with ML):

- density-based models: GAN's; VAE's; NF's
- classifier-based models: OmniFold



Background subtraction

1. jet clustering
2. background subtraction

jet-by-jet

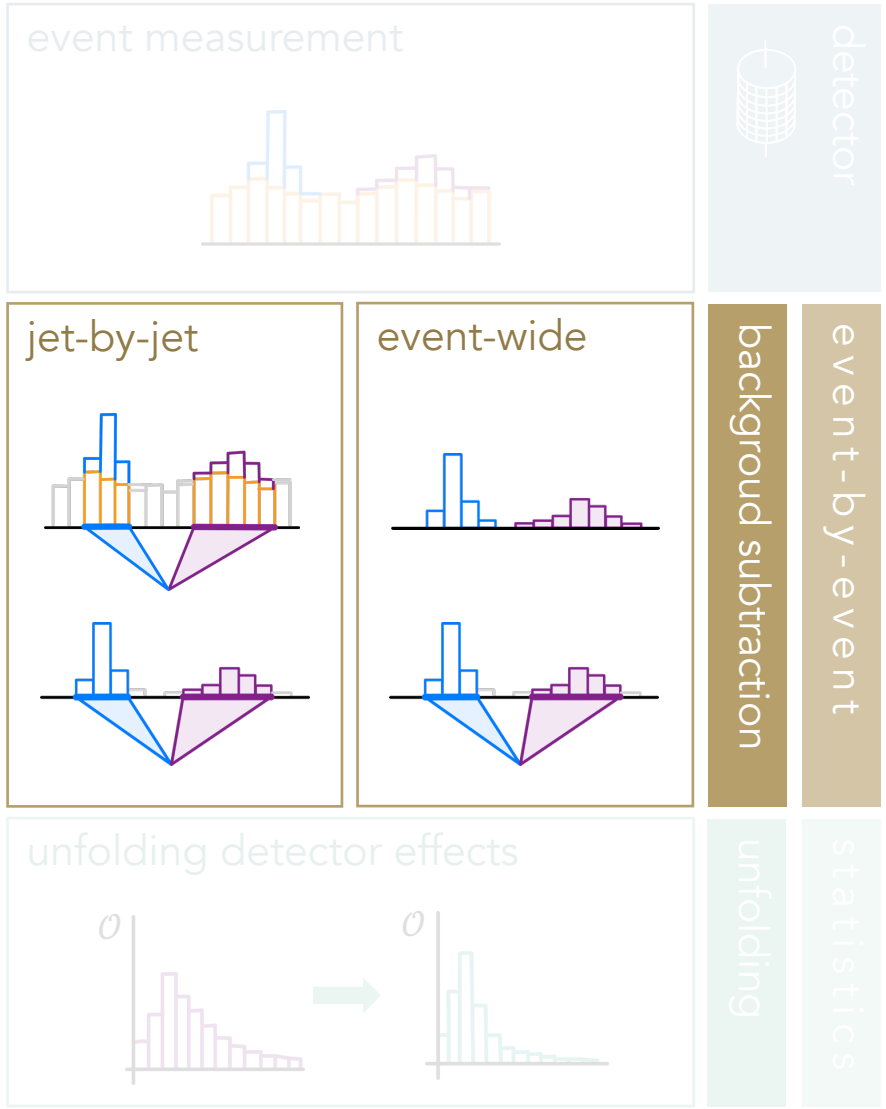
OR

1. background subtraction
2. jet clustering

event-wide

(better for jet substructure)

e.g.: area subtraction; CS; ICS



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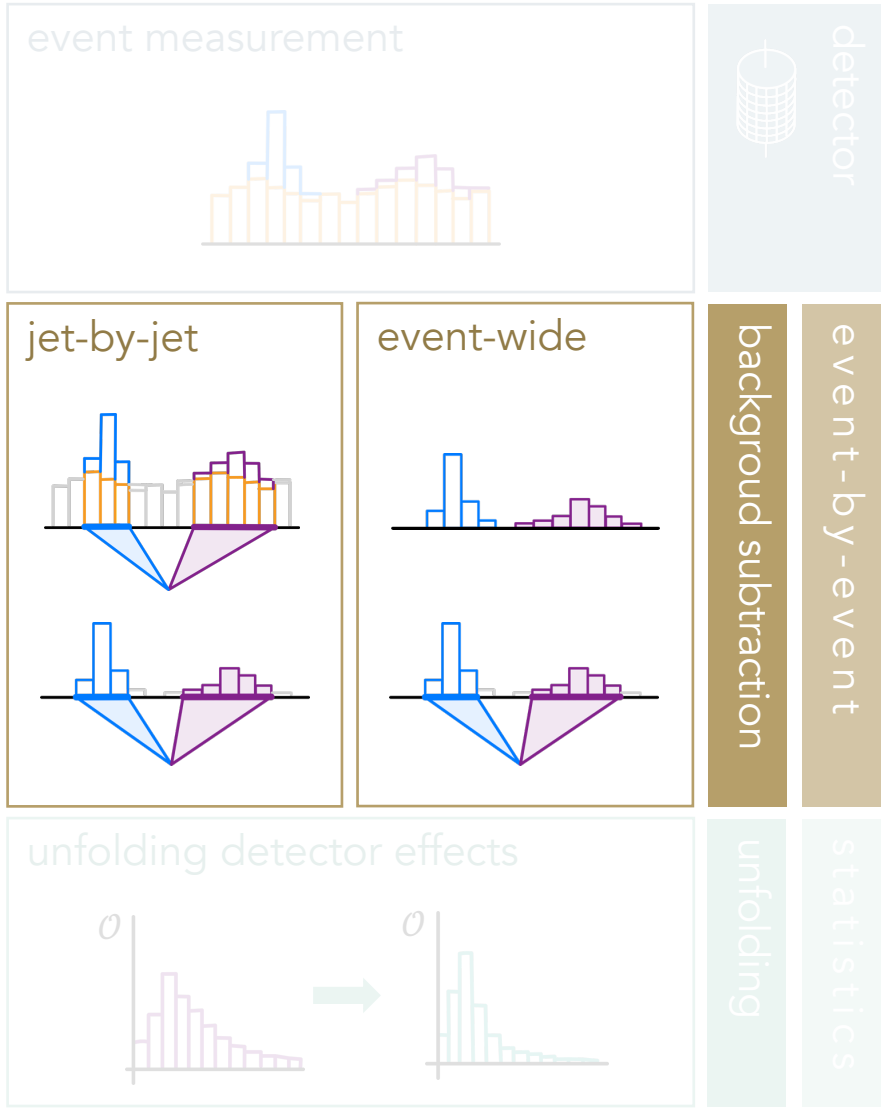
Main sources of background:

- **pp:** pileup
- **HI:** underlying event (UE)



The Underlying Event in HI

In HI, complex UE from quark-gluon plasma (QGP):
(formation + hydrodynamical evolution)

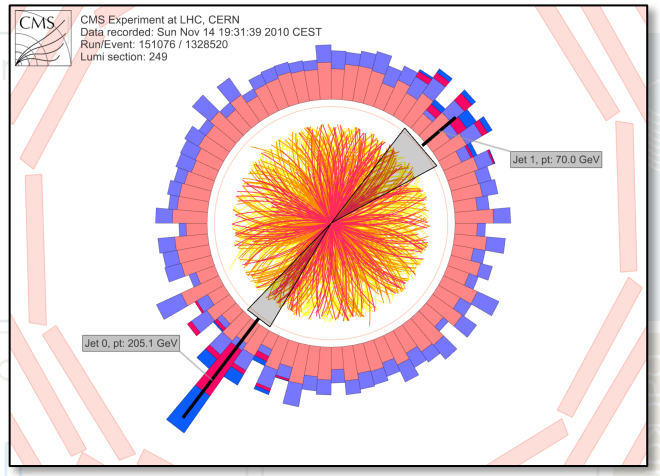
high-multiplicity thermal component

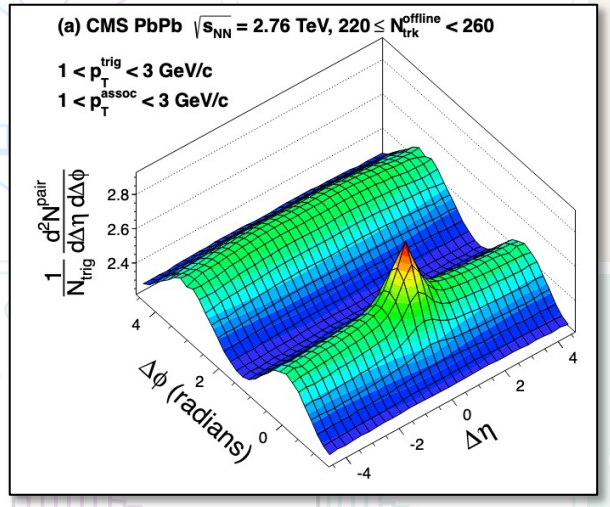
collective flow effects ($v_2, v_3, v_4, \ldots$)

initial state fluctuations

interaction jet ↔ QGP

- jet quenching ⟺ UE modifies jet p_T and internal structure
- jet medium response modifies UE





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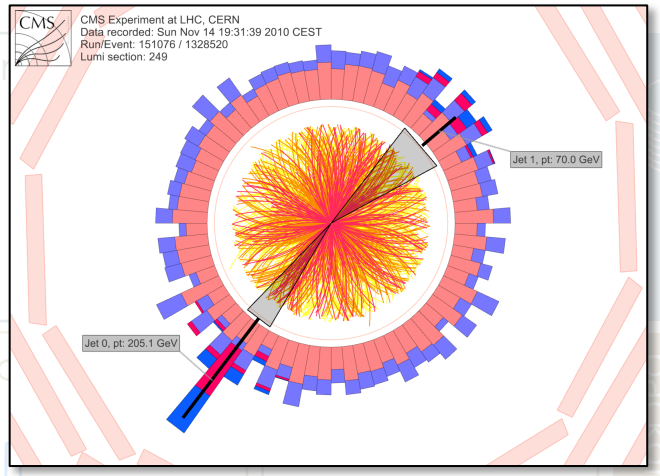
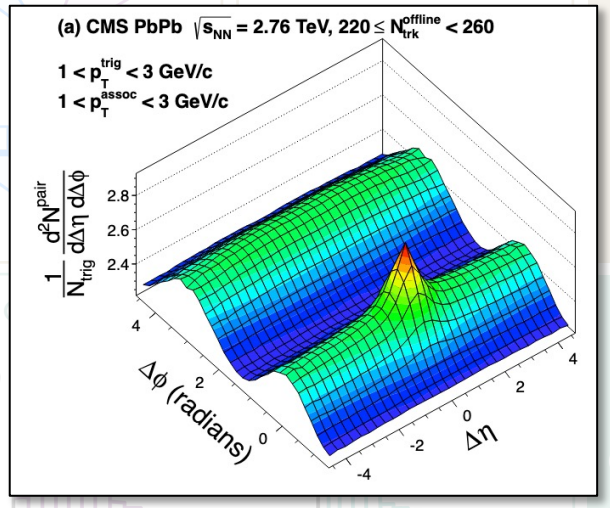
Underlying event *cannot* be separated from the hard event!
(UE is *not* additive)

⇓

HI background is *ill-defined*





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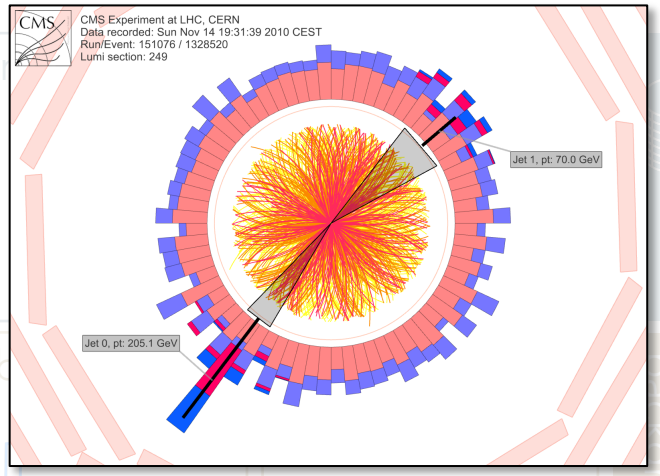

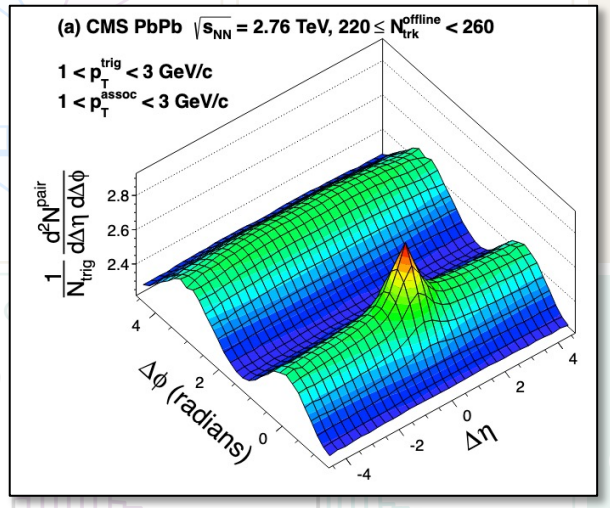

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consensus: everyone uses the same subtraction method
e.g.: ICS; jet grooming

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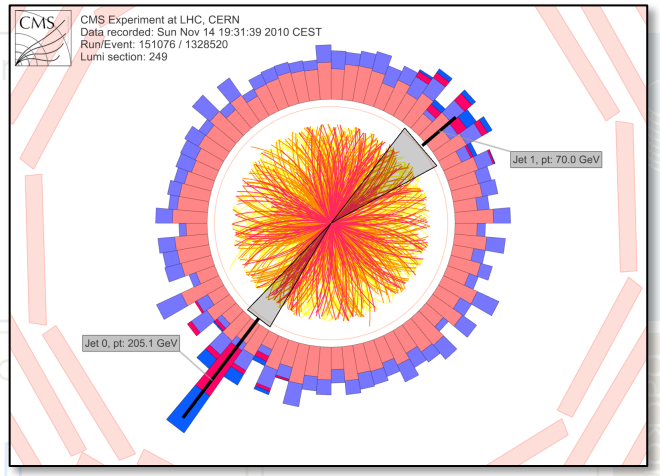

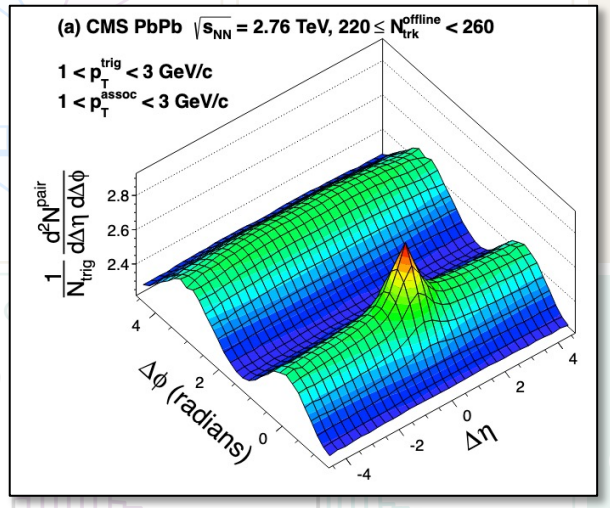

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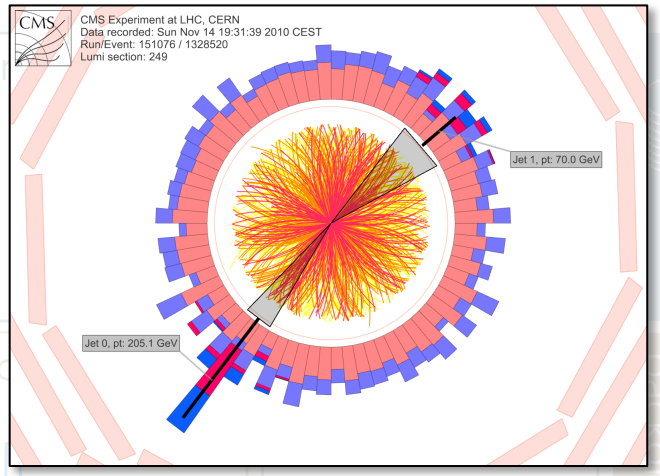
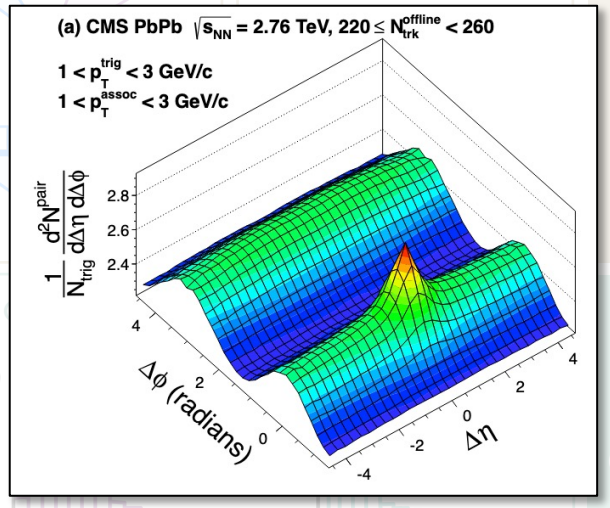




How to deal with it?

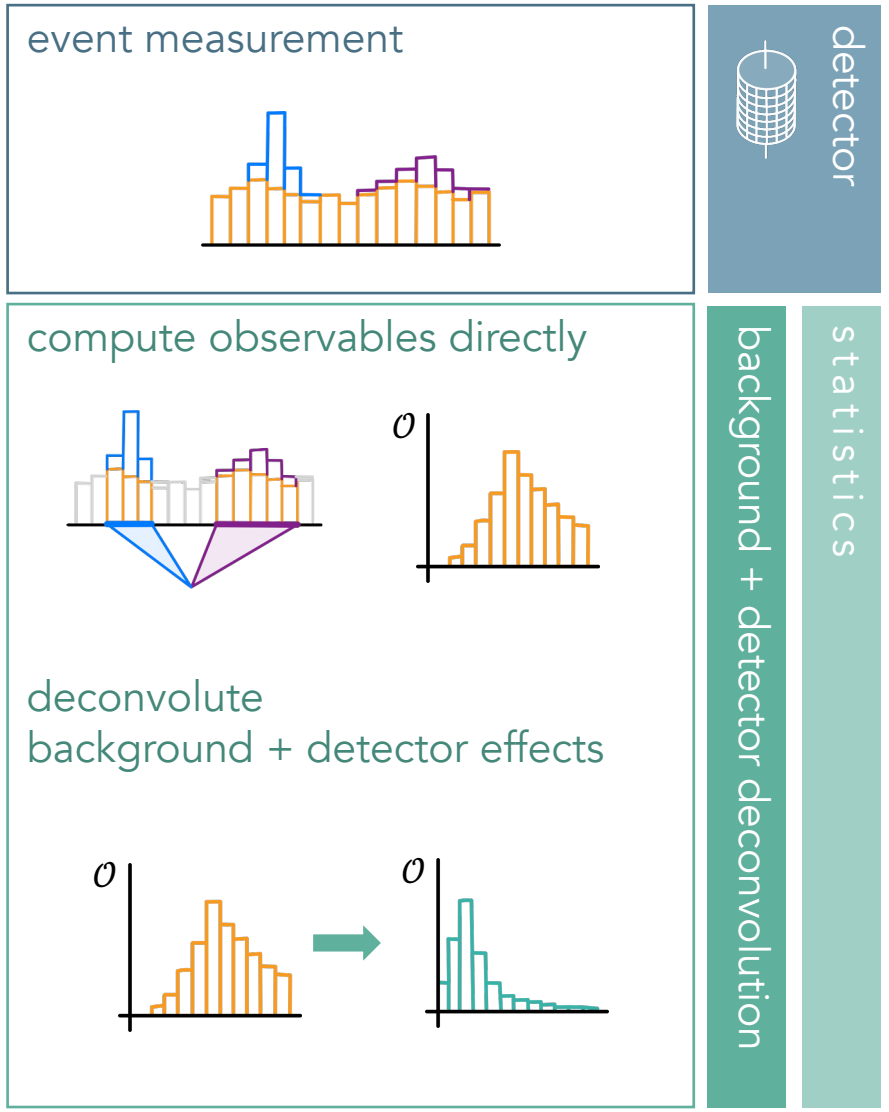
consensus: everyone uses the same subtraction method
e.g.: ICS; jet grooming → adds subtraction uncertainty

Is there as simpler way?

Background + detector deconvolution

We extend the unfolding of detector effects to include background effects

- combine deconvolution of background and detector effects on observable
- background is defined by simulation needed for deconvolution
- choice of background to deconvolute eliminates subtraction uncertainty



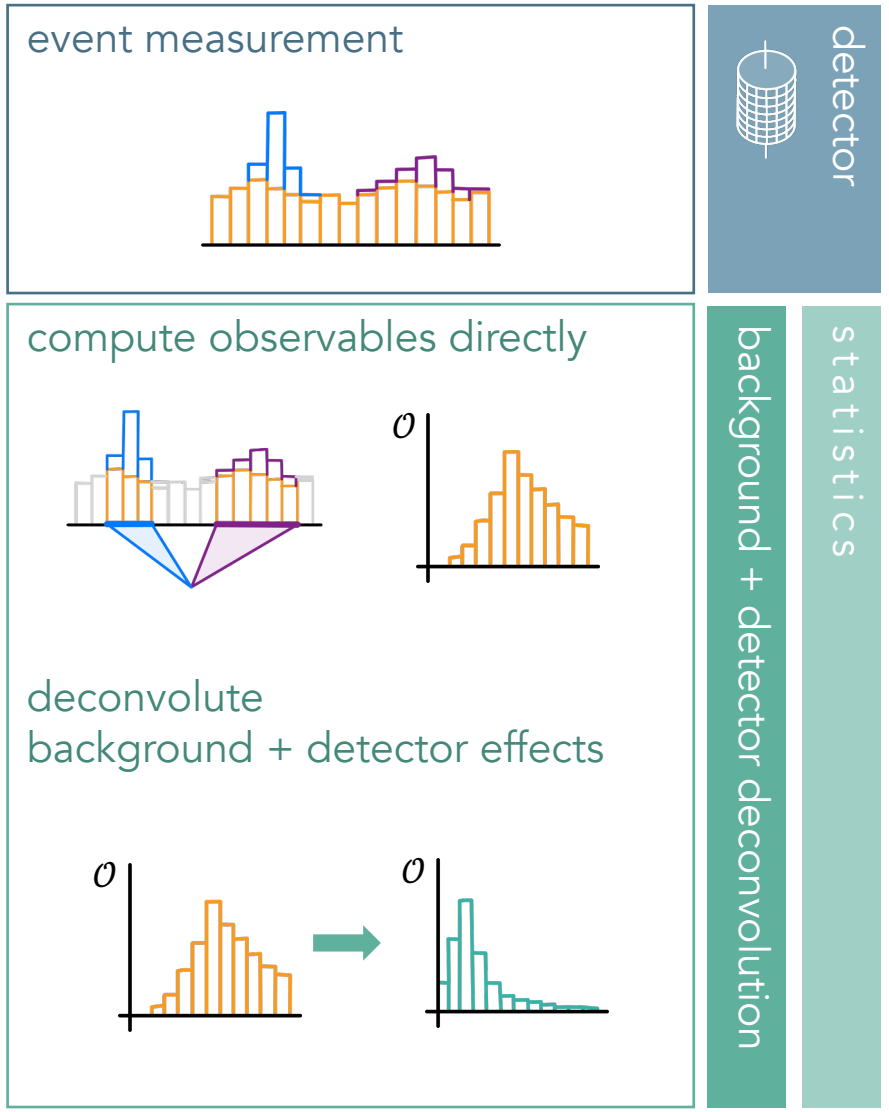
Background + detector deconvolution

We extend the unfolding of detector effects to include background effects

- combine deconvolution of background and detector effects on observable
- background is defined by simulation needed for deconvolution
- choice of background to deconvolute eliminates subtraction uncertainty
- possible to use unfolding statistical procedures:

Binned:
- Iterative Bayesian Unfolding (IBU)

Unbinned (with ML):
- OmniFold



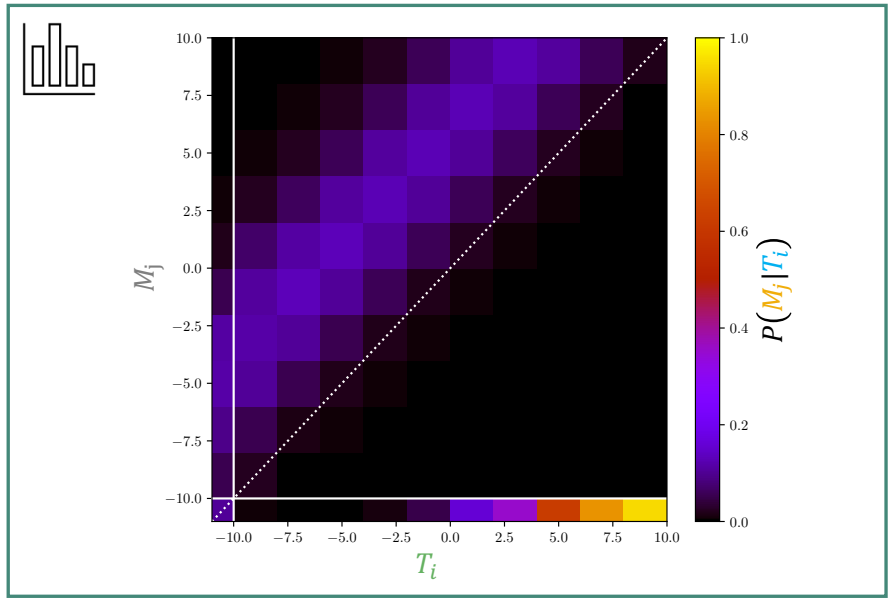
Unfolding procedures

IBU:
[arXiv:1010.0632]

$$x(T_i) = \sum_j P(T_i|M_j) \cdot x(M_j)$$

- $x(T_i)$: true bin counts
- $P(T_i|M_j)$: response matrix
- $x(M_j)$: measured bin counts

from Monte Carlo + simualtion



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IBU:

[arXiv:1010.0632]

$$x(T_i) = \sum_j P(T_i|M_j) \cdot x(M_j)$$

response matrix

true bin counts

measured bin counts

OmniFold:

[arXiv:1911.09107, arXiv:2105.04448]

$$x(t) = \int \mathrm{d}m \; p(t|m) \cdot x(m)$$

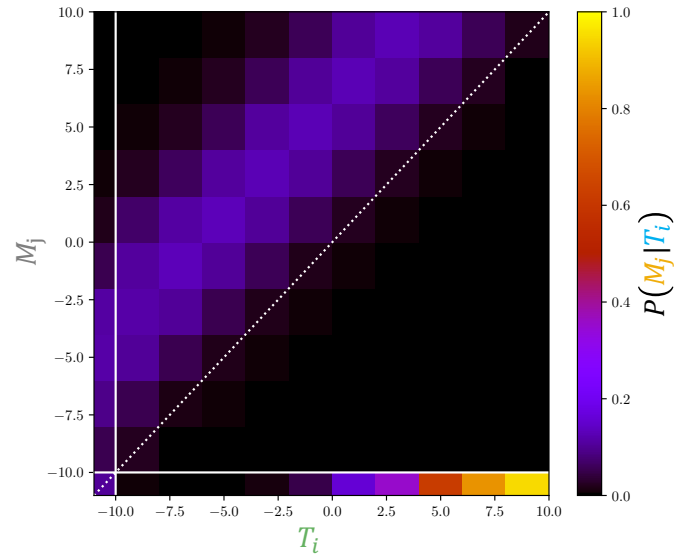
"response matrix" over event space

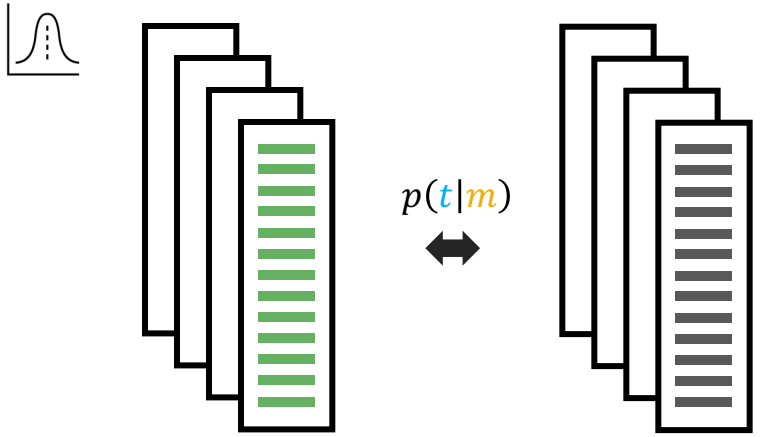
true event distribution

measured event distribution

- easy to extend to higher dimensions (up to whole event unfolding!)

from Monte Carlo + simualtion





OmniFold-HI

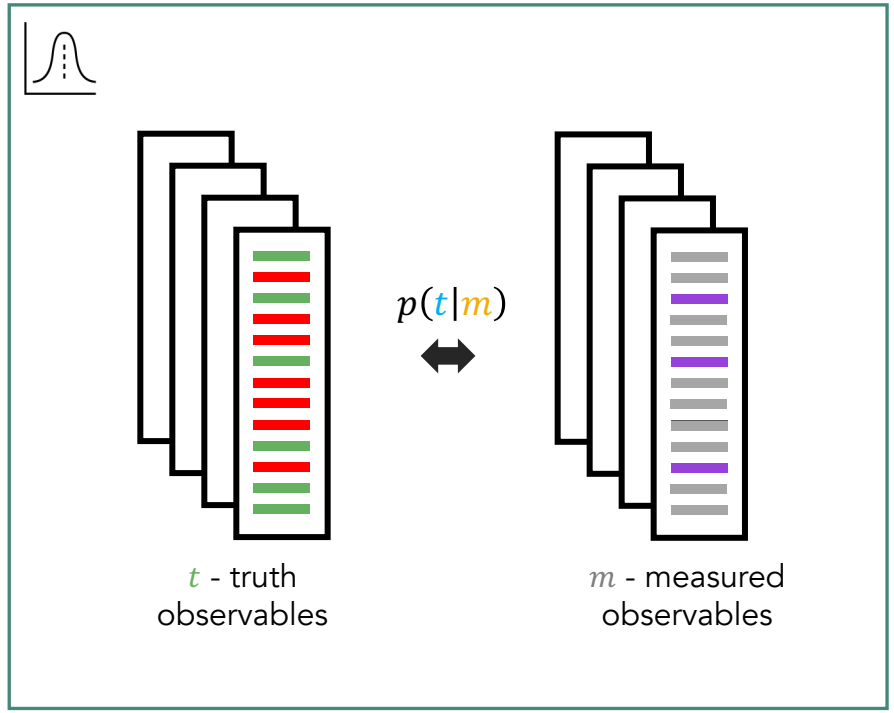
We introduce **OmniFold-HI:**

= Same as OmniFold

\+ Acceptance and efficiency formalized
(rigurous proof of OmniFold from IBU)

\+ Correct estimation of **fake** and **trash** events
(important for fake jets from UE)

\+ Deconvolution of uncertainty



Acceptance: T trash event - true event that are not measured
Efficiency: F fake event - measured event without truth origin

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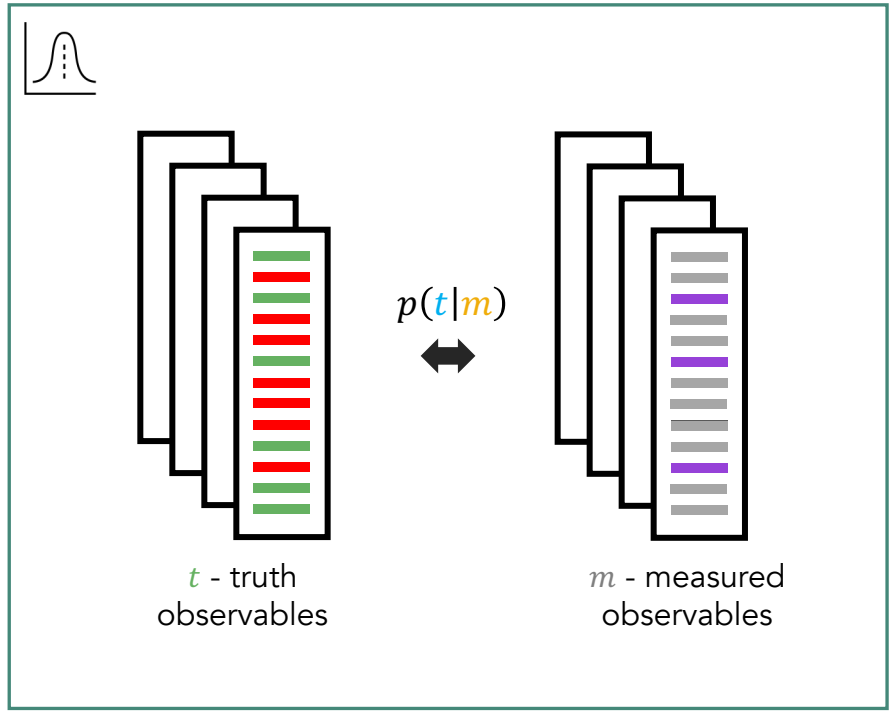
! algorithm tailored for background deconvolution
but useful for traditional detector unfolding !



(**Acceptance:** T trash event - true event that are not measured
Efficiency: F fake event - measured event without truth origin)

Setup

Data: (no real truth data available…)

Truth: Herwig7

Measured: Herwig7 + background + Delphes

detector simulation

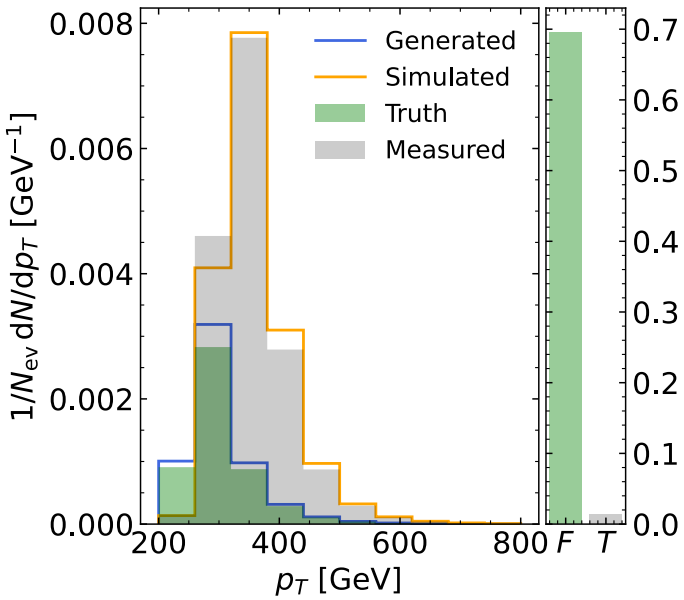
MC for deconvolution procedure:

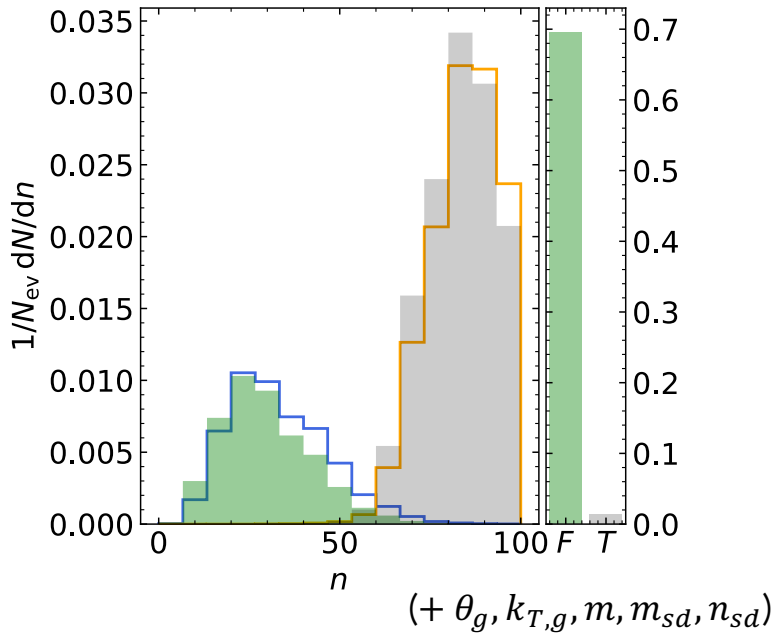
Generated: Pythia8

Simulated: Pythia8 + background + Delphes

Background:

- Thermal background:
  multiplicity = 7000
  $\langle p_T \rangle$ = 1.2 GeV





Truth/Measured: Herwig7 + thermal bkg. + Delphes
Smeared/Generated: Pythia8 + thermal bkg. + Delphes

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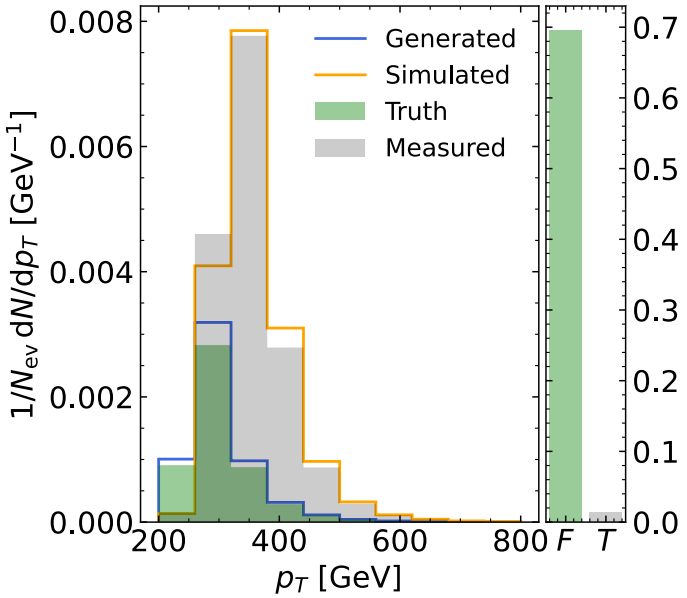
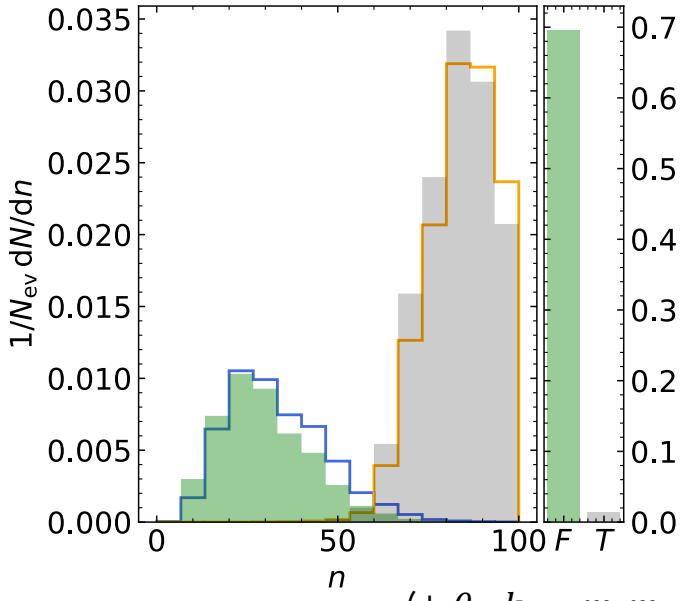
Goal:

deconvolute *chosen background* effects together with detector effects





$(+\ \theta_g, k_{T,g}, m, m_{sd}, n_{sd})$

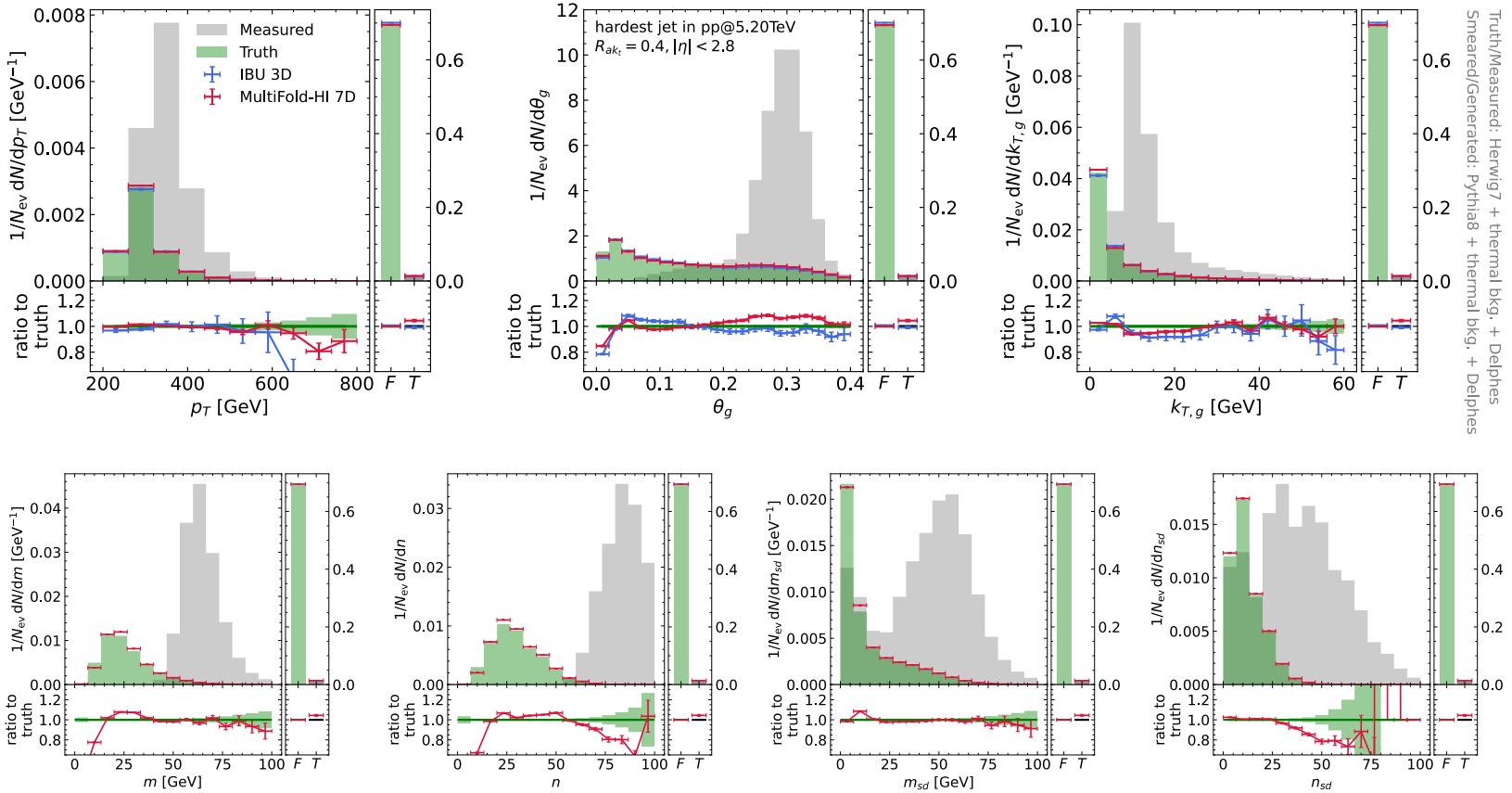
Truth/Measured: Herwig7 + thermal bkg. + Delphes
Smeared/Generated: Pythia8 + thermal bkg. + Delphes

Results: Background + Detector deconvolution

7D deconvolution:

7 observables deconvoluted together

(too computionaly expensive for IBU)



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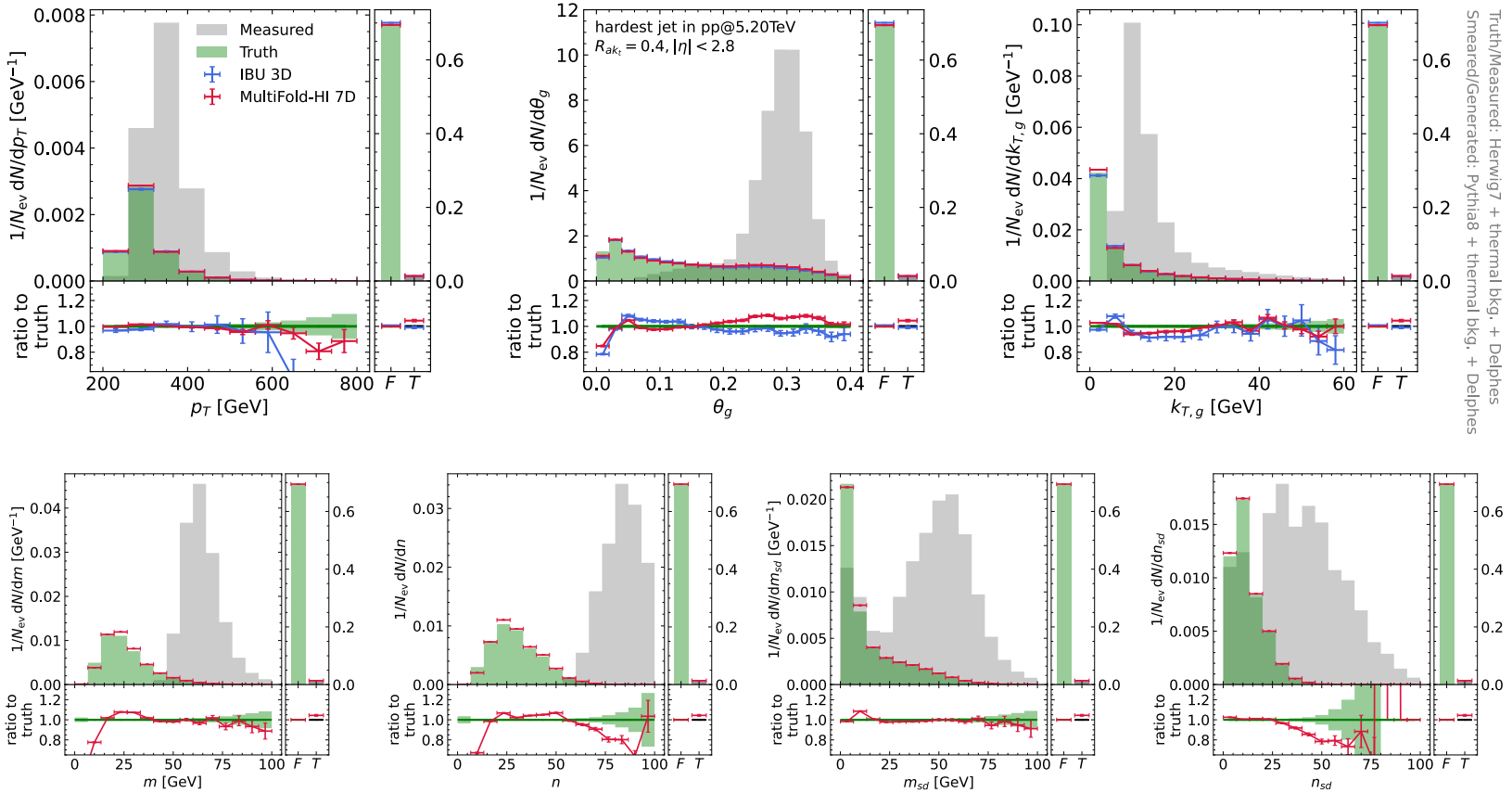
- Both unfolding techniques succeed at deconvoluting background effects
- OmniFold-HI scales easily with deconvolution dimension



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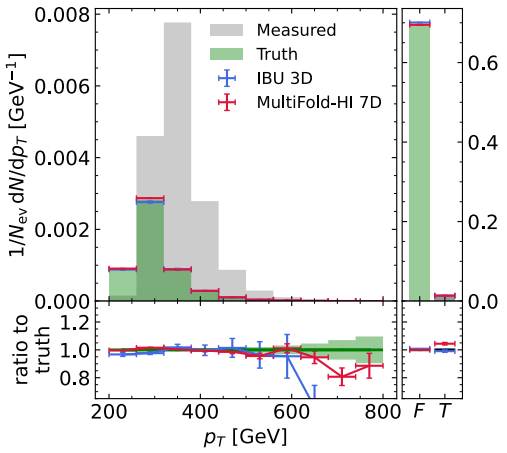
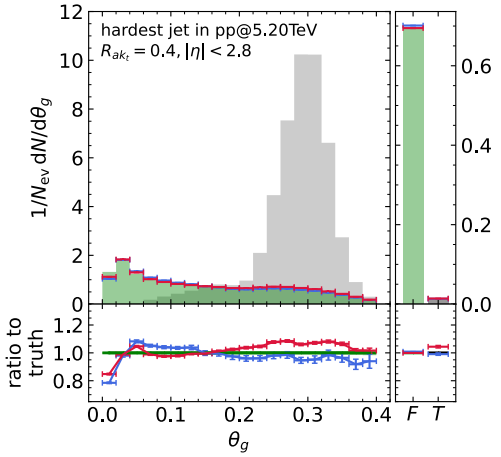
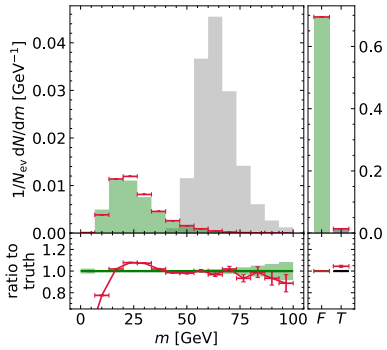
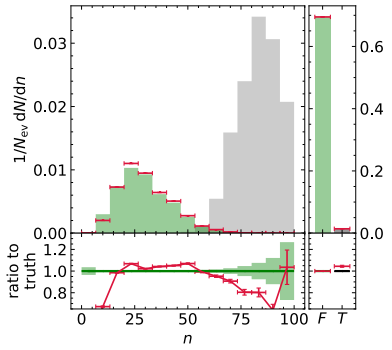
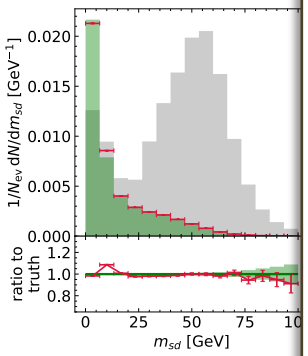
- OmniFold-HI outperformes original OmniFold in fake and trash estimation

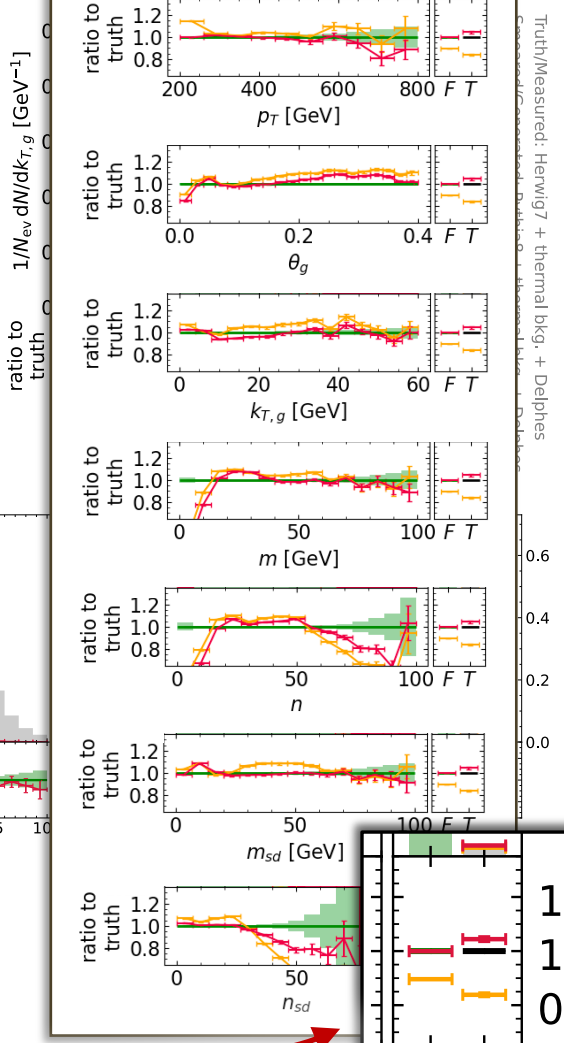












Summary

- Experimental measurement of jet observables
  - background subtraction + detector unfolding
- Background is ill-defined in HI collisions
- Deconvolution of background effects can be combined with detector unfolding
- Unfolding techniques can be used:
  - IBU
  - OmniFold-HI
    (upgrade to OmniFold + formal approach to acceptance and efficiency)

Next steps

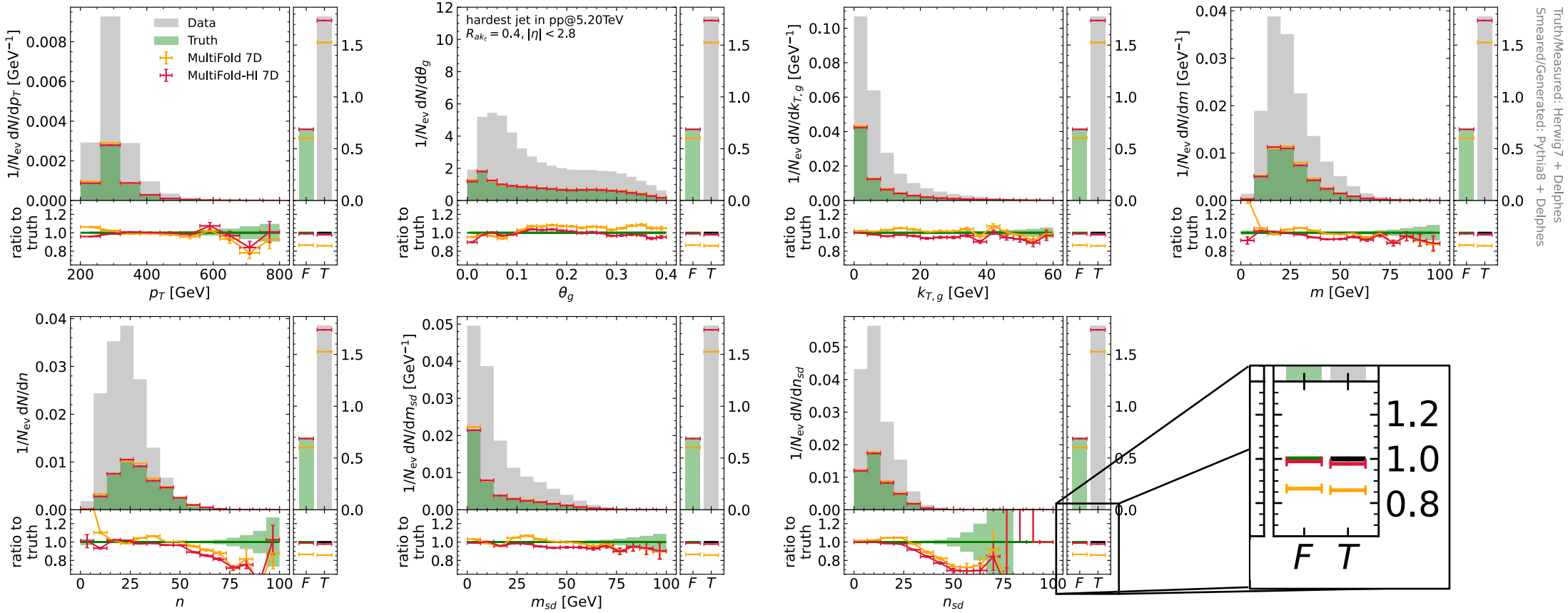
- Better HI simulation to study use in real data
  - hydrodynamic background + jet quenching
- Increase number of observables
- Study use of deconvolution after subtraction

BACKUP

OmniFold vs. OmniFold-HI

(**MultiFold** n**D:** n-dimentional OmniFold
UniFold: one-dimentional OmniFold)

Unfolding detector effects only

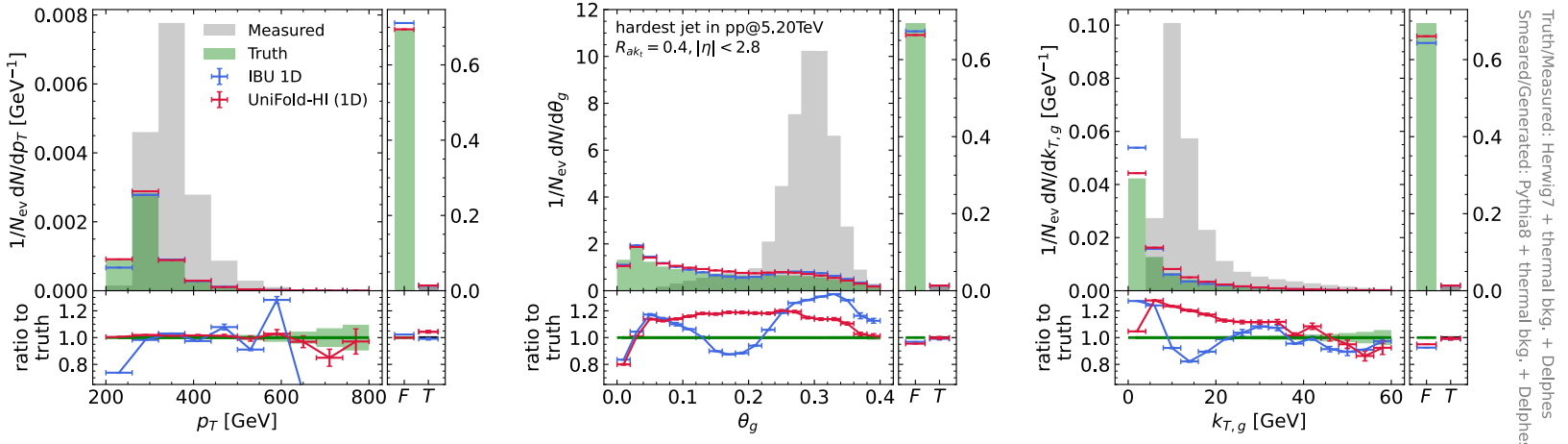


Results: Background + Detector deconvolution

(**UniFold:** one-dimentional OmniFold
MultiFold nD: n-dimentional OmniFold)

1D deconvolution:

3 observables deconvoluted independently



Vs.

3D deconvolution:

3 observables deconvoluted together

- better performance
- agreement between procedures