

OmniLearn: Facilitating All Jet Physics Tasks



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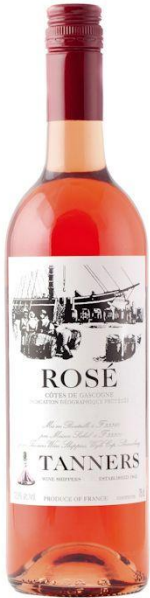
Foundational Models

- Foundational models are everywhere now
- In essence, these models are trained on large datasets and can be used for multiple tasks
- How does a **foundational model for science** look like?



BY ANTHROPIC

Data



Model

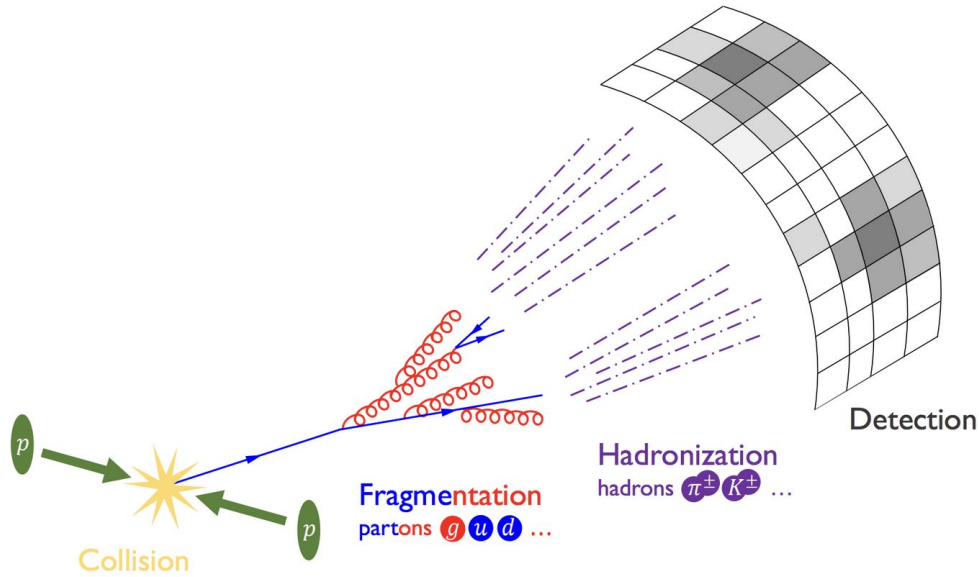


Learning





The Data

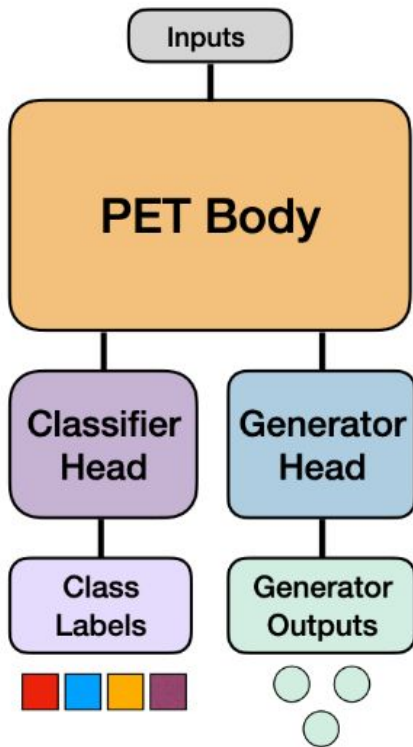


Jets are the most common signatures at the LHC

- Complicated signature: $O(10-100)$ particles are clustered in each jet
- Everywhere: Jets are used in almost any analysis at the LHC

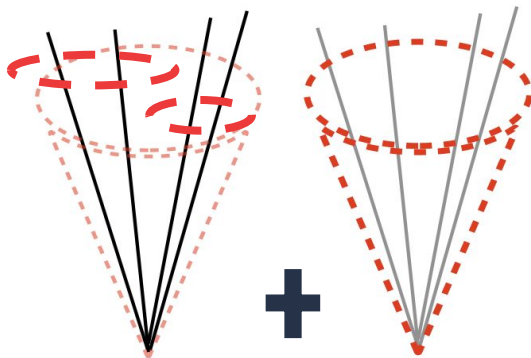


The Model



Point-Edge Transformer (PET)

- Combine local information with graphs
- Learn global information with Transformers:
3M parameters

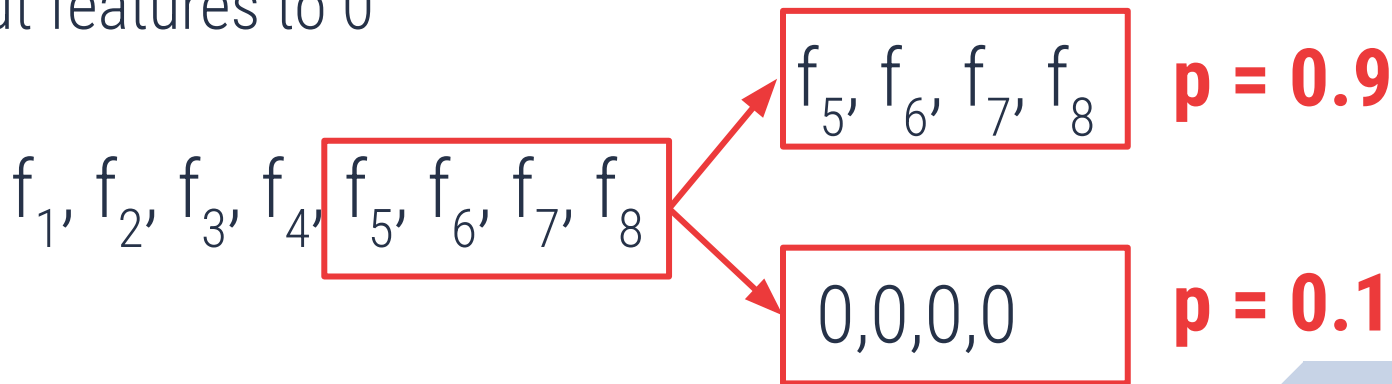




The Model

Not all datasets contain the same information:

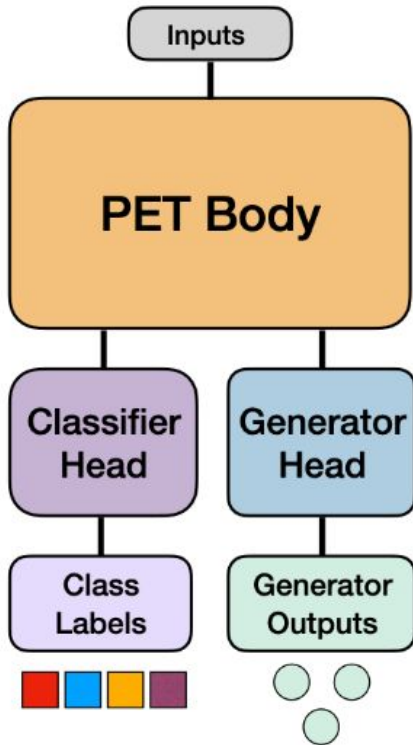
- Let the model learn with and without some features
- **Feature Dropout:** With fixed probability, set some of the input features to 0



More details at: <https://arxiv.org/abs/2404.16091>



The Learning



Couple the network with multiple experts:

- **Classify jets:** learns the difference in radiation between jet types
- **Generate jets:** implicitly learn the likelihood of jets for different particles
- **Multi-objective** loss



The Learning

$$\begin{aligned}\mathcal{L} &= \mathcal{L}_{\text{class}} + \mathcal{L}_{\text{gen}} + \mathcal{L}_{\text{class smear}} \\ &= \text{CE}(y, y_{\text{pred}}) + \|\mathbf{v} - \mathbf{v}_{\text{pred}}\|^2 + \alpha^2 \text{CE}(y, \hat{y}_{\text{pred}})\end{aligned}$$

Straightforward loss function:

- **Cross entropy** for each class
- Perturbed data prediction from the **diffusion loss**
- Classification over perturbed inputs: **data augmentation!**

More details at: <https://arxiv.org/abs/2404.16091>



Comparison Between Models

Language inspired models

- Data are tokenized
- Unsupervised and general pre-training
- Big models often required

OmniLearn

- Data are continuous
- HEP has one of the best simulators across all sciences: supervised pre-training
- Medium models that can fit on standard GPUs are still useful



JetClass dataset used for training

- 100M jets
- **10 different jet categories, AK8 jets simulated in pp collisions with Madgraph + Pythia8 with CMS Delphes detector simulation**

Use the pre-trained model as the starting point and fine-tune using different datasets



2 different jet categories, AK8 jets simulated in pp collisions with Madgraph + Pythia8 with ATLAS Delphes detector simulation

	Acc	AUC	$1/\epsilon_B$	
			$\epsilon_S = 0.5$	$\epsilon_S = 0.3$
ResNeXt-50 [38]	0.936	0.9837	302 ± 5	1147 ± 58
P-CNN [38]	0.930	0.9803	201 ± 4	759 ± 24
PFN [35]	-	0.9819	247 ± 3	888 ± 17
ParticleNet [38]	0.940	0.9858	397 ± 7	1615 ± 93
JEDI-net [37]	0.9300	0.9807	-	774.6
PCT [41]	0.940	0.9855	392 ± 11	1559 ± 98
LGN [79]	0.929	0.964	-	435 ± 95
rPCN [39]	-	0.9845	364 ± 9	1642 ± 93
LorentzNet [10]	0.942	0.9868	498 ± 18	2195 ± 173
PELICAN [80]	0.9425	0.9869	-	2289 ± 204
ParT [42]	0.940	0.9858	413 ± 16	1602 ± 81
ParT-f.t. [42]	0.944	0.9877	691 ± 15	2766 ± 130
Mixer(HDBSCAN) [81]	-	0.9859	416	-
PET Classifier	0.938	0.9848	340 ± 12	1318 ± 39
OMNILEARN	0.942	0.9872	568 ± 9	2647 ± 192

Better than all non-fine-tuned models and similar to PartT performance



2 different jet categories, **AK4 jets** simulated in pp collisions with ~~Madgraph + Pythia8 with CMS Delphes detector simulation~~

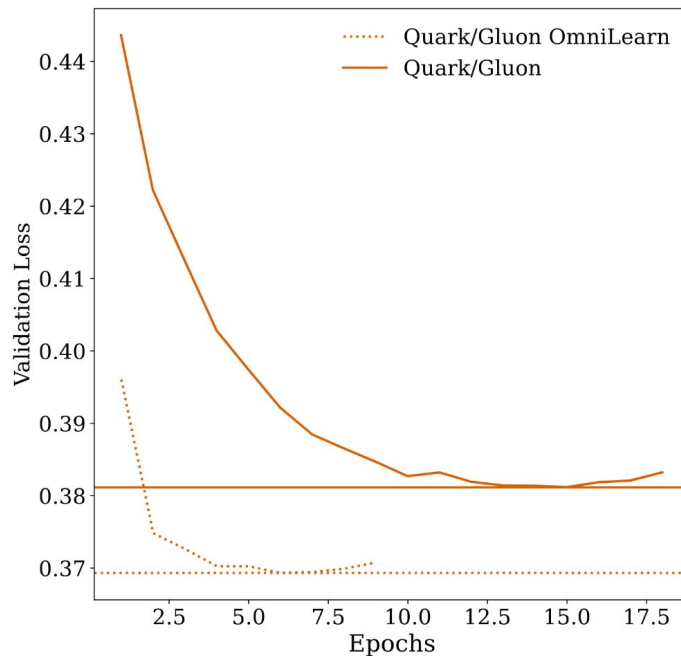
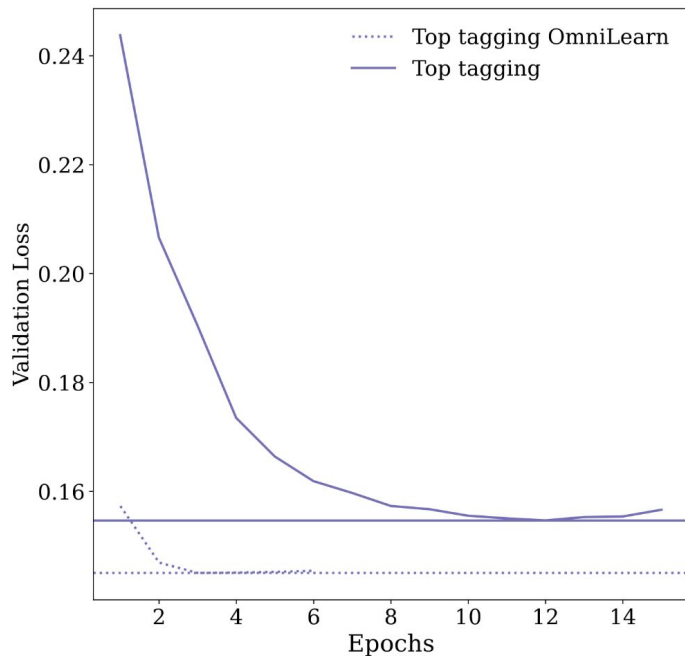
	Acc	AUC	$1/\epsilon_B$	
			$\epsilon_S = 0.5$	$\epsilon_S = 0.3$
P-CNN [38]	0.827	0.9002	34.7	91.0
PFN [35]	-	0.9005	34.7 ± 0.4	-
ParticleNet [38]	0.840	0.9116	39.8 ± 0.2	98.6 ± 1.3
rPCN [39]	-	0.9081	38.6 ± 0.5	-
ParT [42]	0.840	0.9121	41.3 ± 0.3	101.2 ± 1.1
ParT-f.t. [42]	0.843	0.9151	42.4 ± 0.2	107.9 ± 0.5
PET classifier	0.837	0.9110	39.92 ± 0.1	104.9 ± 1.5
OMNILEARN	0.844	0.9159	43.7 ± 0.3	107.7 ± 1.5

Better than all non-fine-tuned models and similar to PartT performance



Evaluation

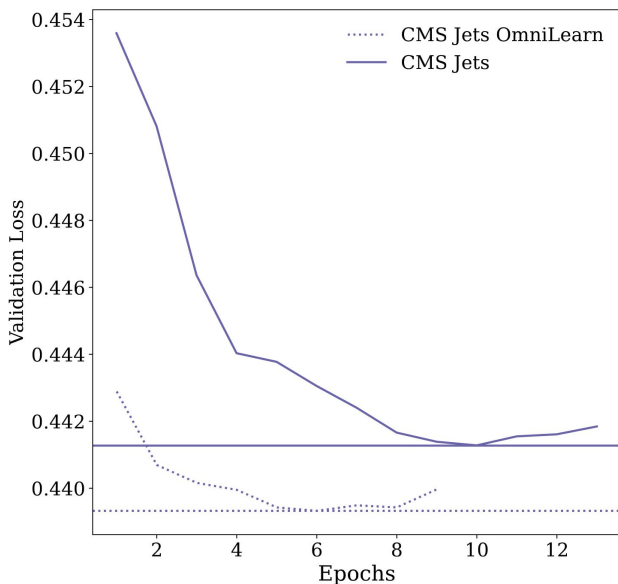
Evaluation datasets: 2



Faster training
and better
convergence



2 different jet categories, **AK5 jets** simulated in pp collisions with Pythia6 with **Geant4 Simulation + CMS Particle flow reconstruction**



	AUC	Acc	$1/\epsilon_B$	
			$\epsilon_S = 0.5$	$\epsilon_S = 0.8$
PET classifier	0.875	0.796	23.91 ± 0.07	4.770 ± 0.001
OMNILEARN	0.877	0.797	24.36 ± 0.01	4.836 ± 0.004



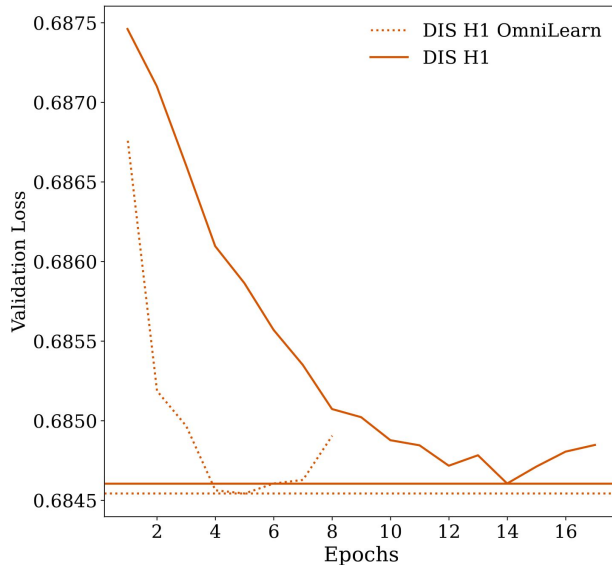
Evaluation



BERKELEY LAB

Evaluation datasets: 4

2 different jet categories, AK10 jets simulated in ep collisions with Rapgap with Geant3 Simulation + H1 Particle flow reconstruction



	AUC	Acc	$\frac{1/\epsilon_B}{\epsilon_S}$	
			$\epsilon_S = 0.1$	$\epsilon_S = 0.5$
PET classifier	0.5691	0.547	17.73 ± 0.04	2.467 ± 0.002
OMNILEARN	0.5695	0.547	17.78 ± 0.06	2.470 ± 0.003

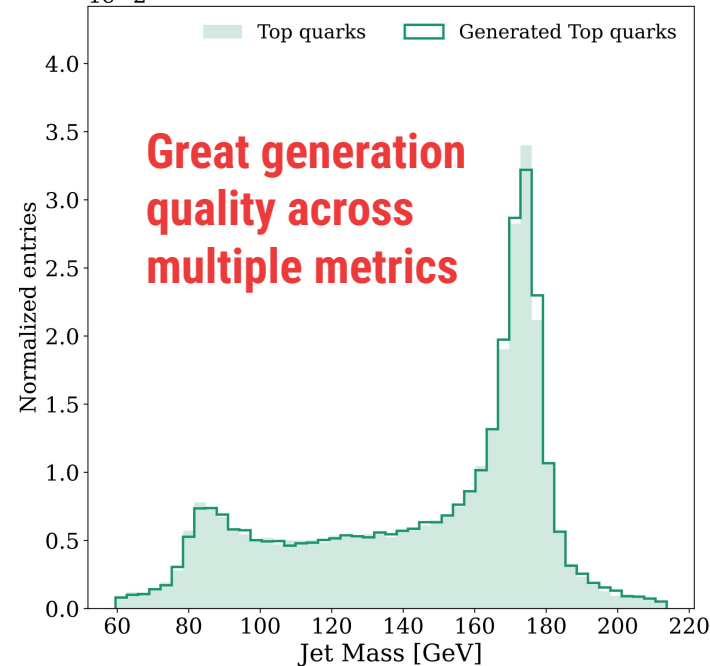


Jet Generation

Evaluation datasets: **6**

Jet class	Model	$W_1^{PM} (\times 10^{-3})$	$W_1^P (\times 10^{-3})$	$W_1^{PEFP} (\times 10^{-5})$	FPND	Cov↑	MMD
Gluon	FPCD [52]	0.36 ± 0.08	0.34 ± 0.09	0.47 ± 0.13	0.07	0.55	0.03
	FPCD 1 [52]	0.65 ± 0.11	0.34 ± 0.06	0.60 ± 0.09	0.11	0.55	0.03
	MP-GAN [44]	0.69 ± 0.07	1.8 ± 0.2	0.9 ± 0.6	0.20	0.54	0.037
	EPiC-GAN [45]	0.3 ± 0.1	1.6 ± 0.2	0.4 ± 0.2	1.01 ± 0.07	-	-
	PET generator	0.42 ± 0.10	0.36 ± 0.08	0.35 ± 0.08	0.04	0.55	0.03
	PET generator (Ideal)	0.36 ± 0.08	0.34 ± 0.09	0.47 ± 0.13	0.07	0.55	0.03
	OMNiLEARN	0.38 ± 0.08	0.33 ± 0.07	0.33 ± 0.09	0.02	0.55	0.03
	OMNiLEARN (Ideal)	0.33 ± 0.06	0.29 ± 0.08	0.30 ± 0.07	0.02	0.55	0.03
Light Quark	FPCD [52]	0.52 ± 0.07	0.27 ± 0.06	0.38 ± 0.11	0.08	0.49	0.02
	FPCD 1 [52]	0.59 ± 0.08	0.36 ± 0.08	0.50 ± 0.08	0.09	0.48	0.02
	MP-GAN [44]	0.6 ± 0.2	4.9 ± 0.5	0.7 ± 0.4	0.35	0.50	0.026
	EPiC-GAN [45]	0.5 ± 0.1	4.0 ± 0.4	0.8 ± 0.4	0.43 ± 0.03	-	-
	PET generator	0.39 ± 0.12	0.35 ± 0.06	0.24 ± 0.10	0.03	0.54	0.02
	PET generator (Ideal)	0.31 ± 0.08	0.38 ± 0.10	0.23 ± 0.07	0.03	0.53	0.02
	OMNiLEARN	0.24 ± 0.03	0.32 ± 0.07	0.24 ± 0.08	0.02	0.54	0.02
	OMNiLEARN (Ideal)	0.31 ± 0.08	0.30 ± 0.09	0.26 ± 0.08	0.01	0.54	0.02
Top Quark	FPCD [52]	0.51 ± 0.07	0.41 ± 0.12	1.25 ± 0.19	0.17	0.58	0.05
	FPCD 1 [52]	1.22 ± 0.09	0.46 ± 0.10	2.66 ± 0.26	0.56	0.57	0.05
	MP-GAN [44]	0.6 ± 0.2	2.3 ± 0.3	2 ± 1	0.37	0.57	0.071
	EPiC-GAN [45]	0.5 ± 0.1	2.1 ± 0.1	1.7 ± 0.3	0.31 ± 0.037	-	-
	PET generator	0.44 ± 0.03	0.29 ± 0.07	1.09 ± 0.23	0.07	0.58	0.05
	PET generator (Ideal)	0.41 ± 0.07	0.34 ± 0.08	1.22 ± 0.23	0.07	0.58	0.05
	OMNiLEARN	0.43 ± 0.06	0.30 ± 0.07	1.31 ± 0.18	0.04	0.58	0.05
	OMNiLEARN (Ideal)	0.36 ± 0.05	0.41 ± 0.08	1.02 ± 0.20	0.03	0.58	0.05
W Boson	FPCD [52]	0.26 ± 0.03	0.39 ± 0.08	0.15 ± 0.02	-	0.56	0.02
	FPCD 1 [52]	0.94 ± 0.06	0.42 ± 0.09	0.35 ± 0.03	-	0.56	0.02
	PET generator	0.17 ± 0.04	0.26 ± 0.05	0.11 ± 0.02	-	0.56	0.02
	PET generator (Ideal)	0.15 ± 0.02	0.31 ± 0.07	0.12 ± 0.03	-	0.57	0.02
	OMNiLEARN	0.19 ± 0.03	0.27 ± 0.07	0.10 ± 0.02	-	0.57	0.02
	OMNiLEARN (Ideal)	0.16 ± 0.06	0.28 ± 0.04	0.10 ± 0.02	-	0.57	0.02
Z Boson	FPCD [52]	0.21 ± 0.04	0.40 ± 0.13	0.18 ± 0.03	-	0.56	0.02
	FPCD 1 [52]	0.99 ± 0.05	0.35 ± 0.06	0.49 ± 0.03	-	0.56	0.02
	PET generator	0.22 ± 0.04	0.32 ± 0.07	0.20 ± 0.04	-	0.57	0.02
	PET generator (Ideal)	0.18 ± 0.10	0.30 ± 0.08	0.14 ± 0.02	-	0.56	0.02
	OMNiLEARN	0.19 ± 0.07	0.32 ± 0.09	0.12 ± 0.03	-	0.57	0.02
	OMNiLEARN (Ideal)	0.22 ± 0.05	0.27 ± 0.06	0.13 ± 0.02	-	0.57	0.02

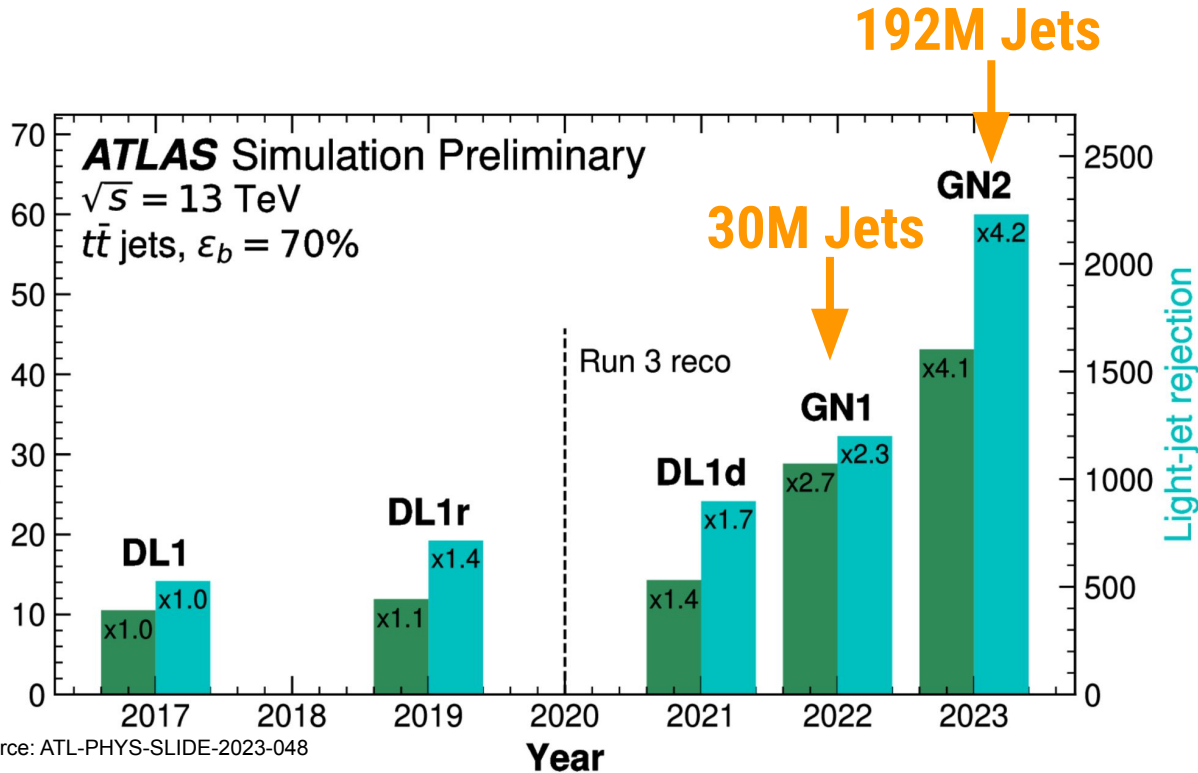
1e-2



“ Application Highlight



The Challenge



Pushing classification performance requires lots of data!



FastSim to FullSim

Evaluation datasets: 7

OmniLearn is trained on cheap Delphes simulations. Can we fine-tune to Run 2 **ATLAS** Full simulation + Reconstruction?

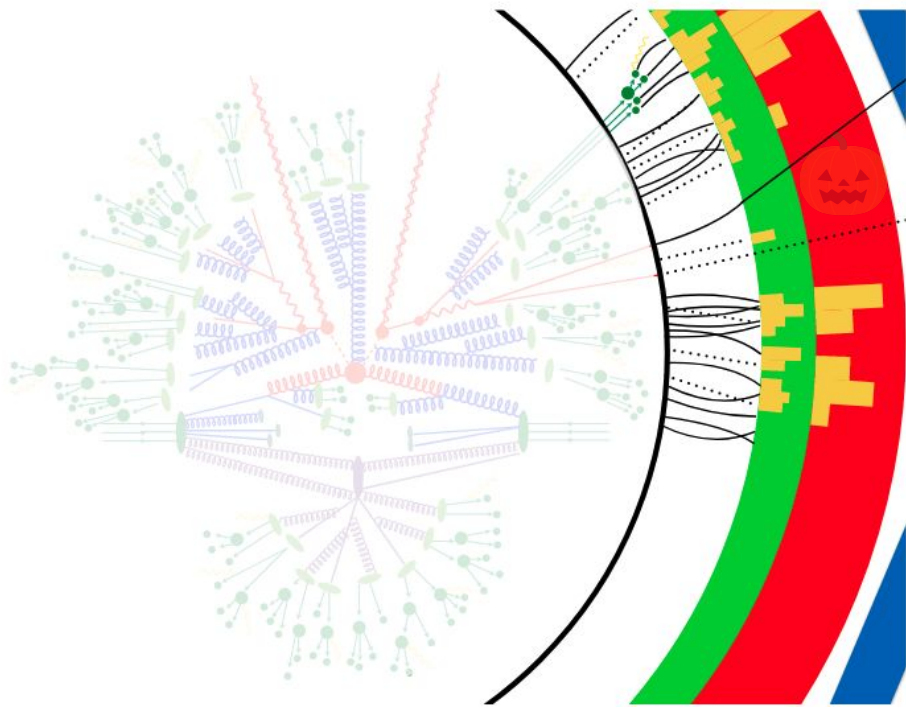
- Matches SOTA with **10%** of the data
- Improves on SOTA if all events are used

	AUC	Acc	$1/\epsilon_B$	
			$\epsilon_S = 0.5$	$\epsilon_S = 0.8$
ResNet 50	0.885	0.803	21.4	5.13
EFN	0.901	0.819	26.6	6.12
hIDNN	0.938	0.863	51.5	10.5
DNN	0.942	0.868	67.7	12.0
PFN	0.954	0.882	108.0	15.9
ParticleNet	0.961	0.894	153.7	20.4
PET classifier (4M)	0.959	0.890	146.5	19.4
OMNILEARN (4M)	0.961	0.894	172.1	20.8
PET classifier (40M)	0.964	0.898	201.4	23.6
OMNILEARN (40M)	0.965	0.899	207.30	24.10

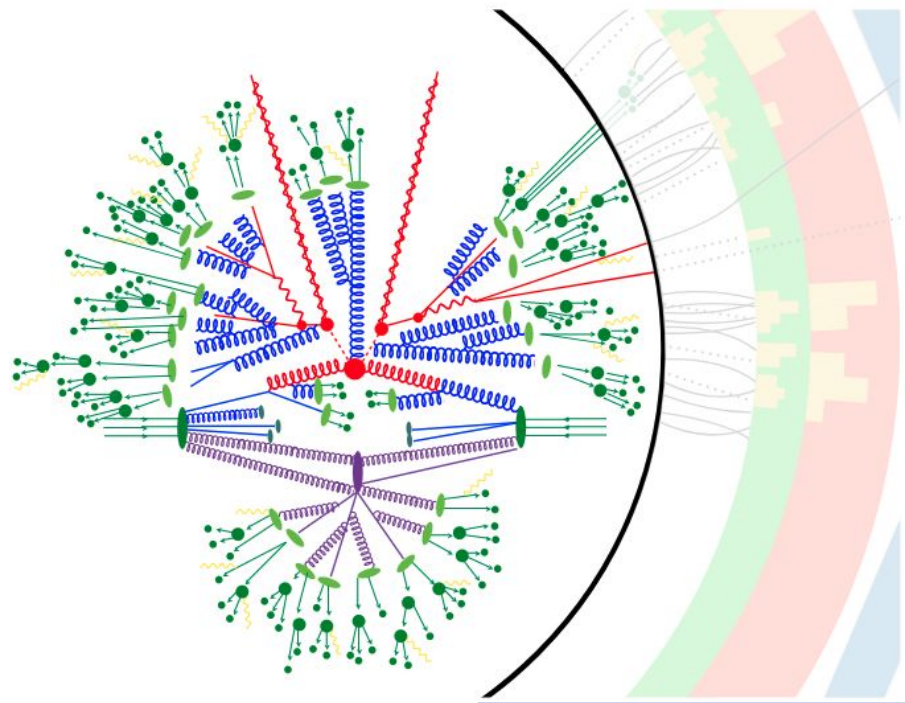


Unfolding

What we measure



What we want

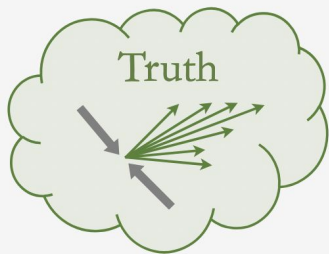
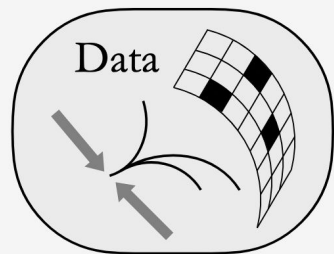




Detector-level

Particle-level

Natural



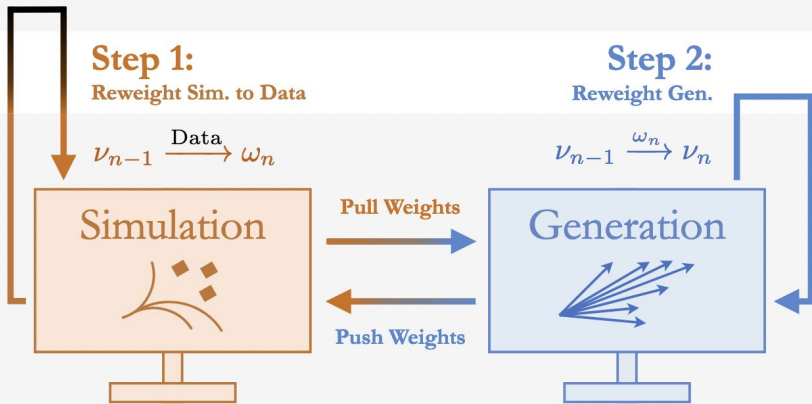
Step 1:
Reweight Sim. to Data

$$\nu_{n-1} \xrightarrow{\text{Data}} \omega_n$$

Step 2:
Reweight Gen.

$$\nu_{n-1} \xrightarrow{\omega_n} \nu_n$$

Synthetic



2-step iterative process

- **Step 1:** Reweight simulations to look like data
- **Step 2:** Convert learned weights into functions of particle level objects

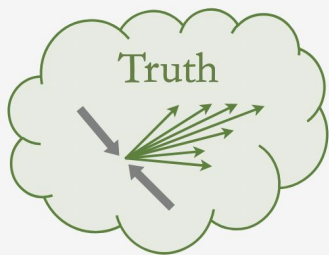
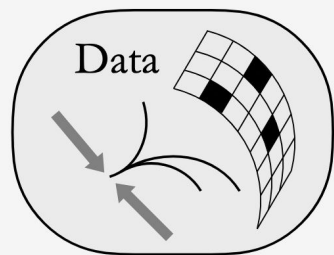
Learn a reweighting function between data and simulation



Detector-level

Particle-level

Natural



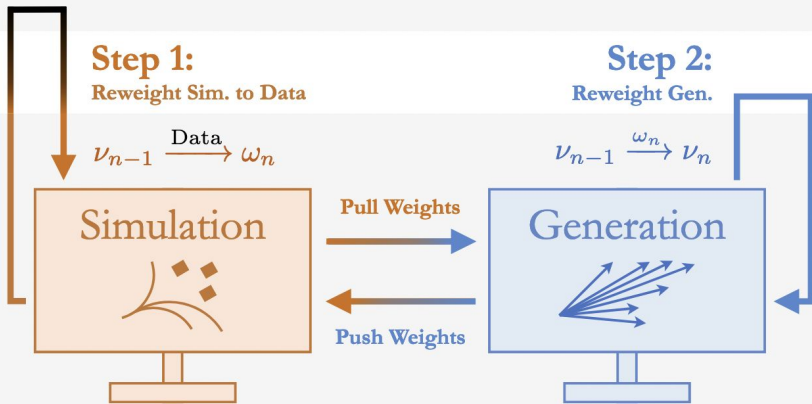
Step 1:
Reweight Sim. to Data

$$\nu_{n-1} \xrightarrow{\text{Data}} \omega_n$$

Step 2:
Reweight Gen.

$$\nu_{n-1} \xrightarrow{\omega_n} \nu_n$$

Synthetic



2-step iterative process

- **Step 1:** Reweight simulations to look like data
- **Step 2:** Convert learned weights into functions of particle level objects

Classification!

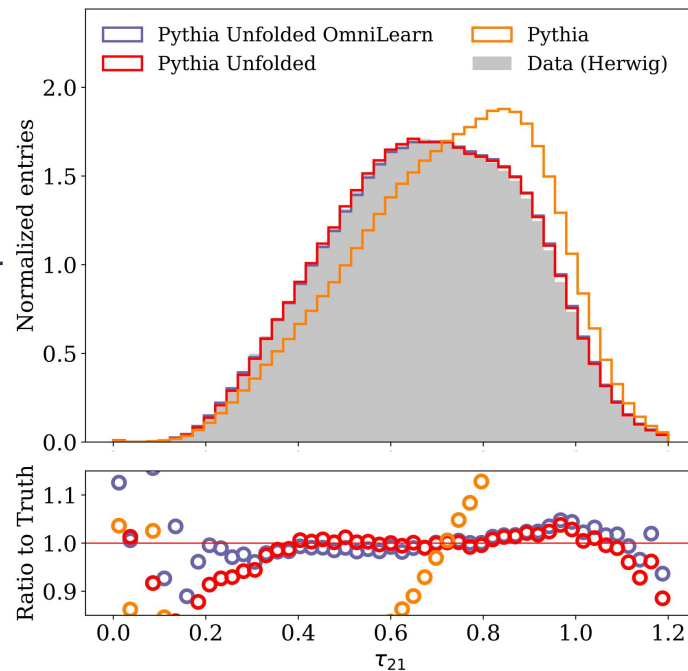


Unfolding

Evaluation datasets: 8

Unbinned Unfolding using the OmniFold workflow. More **precise** than traditional unfolding and more **efficient** than previous ML models. Ex: H1 trained thousands of networks

Metric	MULTIFOLD	UNIFOLD	IBU	OMNIFOLD		
				DeepSets	PET classifier	OMNILEARN
Jet mass	3.80	8.82	9.31	2.77	2.8±0.9	2.6±0.8
N	0.89	1.46	1.51	0.33	0.50±0.15	0.34±0.1
Jet Width	0.09	0.15	0.11	0.10	0.09±0.02	0.07±0.01
log ρ	0.37	0.59	0.71	0.35	0.23±0.07	0.14±0.03
τ ₂₁	0.26	1.11	1.10	0.53	0.13±0.03	0.05±0.01
z _g	0.15	0.59	0.37	0.68	0.19±0.03	0.21±0.04





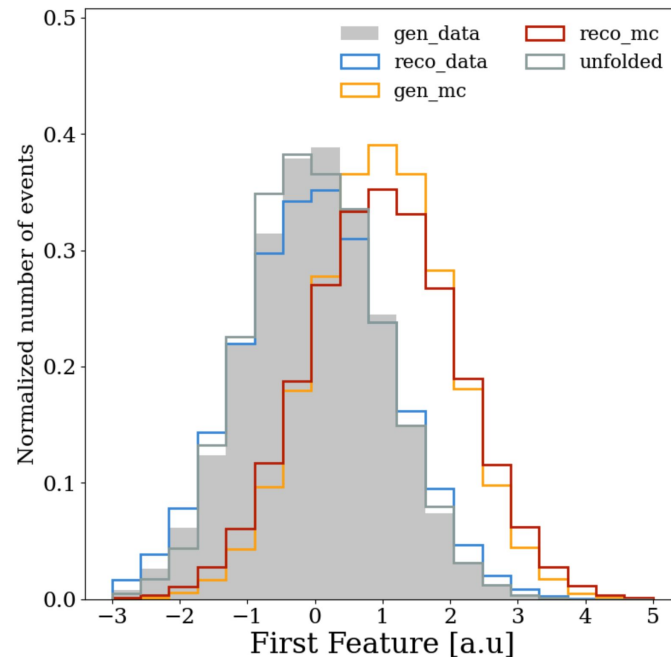
OmniFold

- OmniFold is also now available on pip:
 - ▶ **pip install omnifold**
 - ▶ GitHub repository:
<https://github.com/ViniciusMikuni/omnifold>
- ▶ **RooUnfold** implementation coming soon!

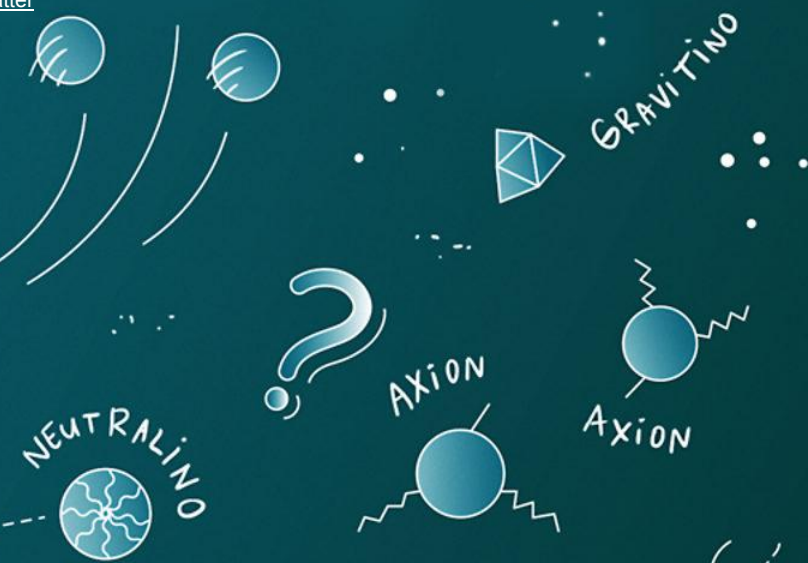
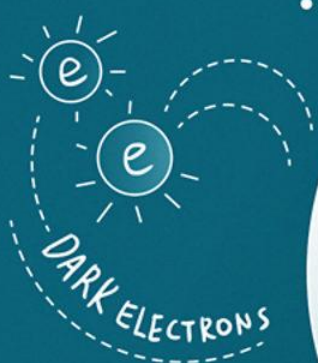
Let's now unfold!

```
In [10]: omnifold = MultiFold(  
         "Gaussian_test",  
         model1,  
         model2,  
         data,  
         mc,  
         batch_size = 1024,  
         niter = 5, #Number of Iterations  
         epochs=100,  
         weights_folder = 'weights',  
         verbose = True,  
         )
```

```
In [11]: omnifold.Preprocessing()  
         omnifold.Unfold()
```



DARK MATTER



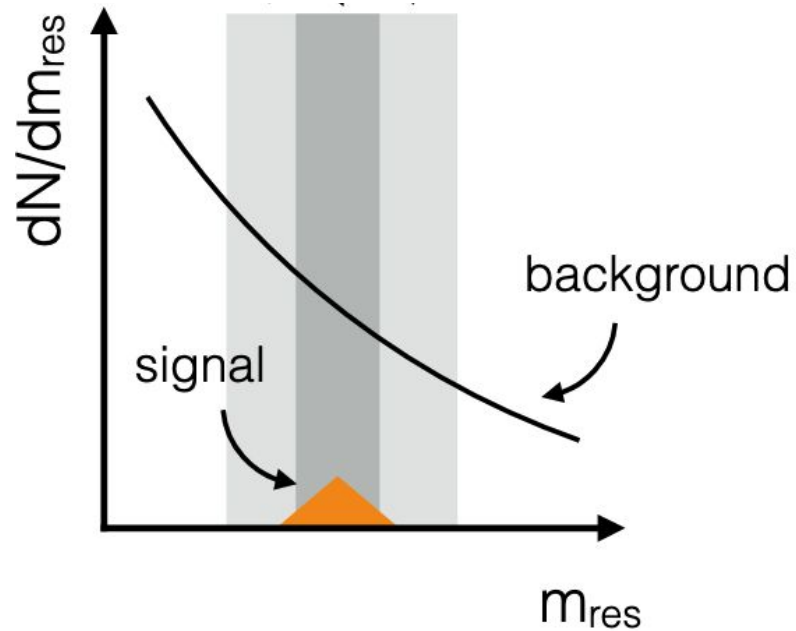


Anomaly Detection

Evaluation datasets: 9

Bump-hunting using ML:

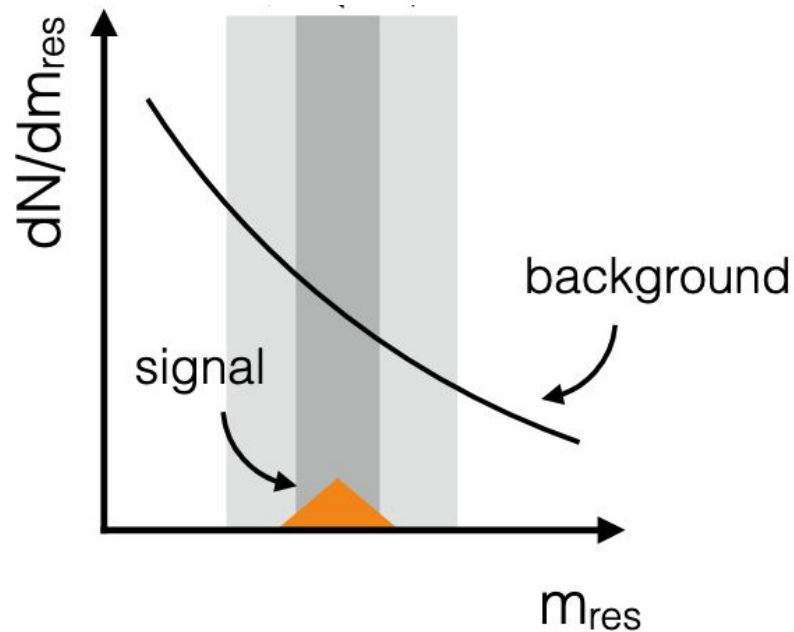
- Use the background in the sideband to estimate the background in the signal region
- Compare the estimated background with the data





Bump-hunting using ML:

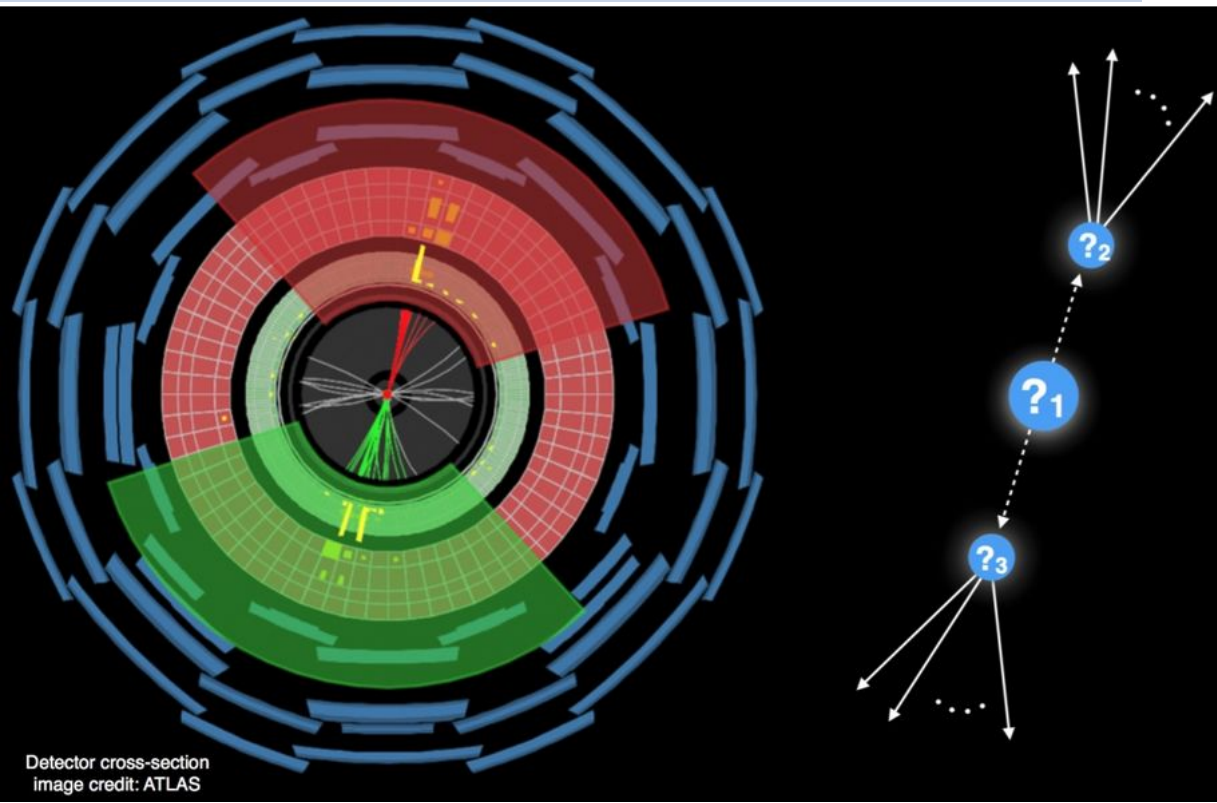
- **Generative Model**
- **Classifier**





LHCO dataset

Evaluation datasets: 9



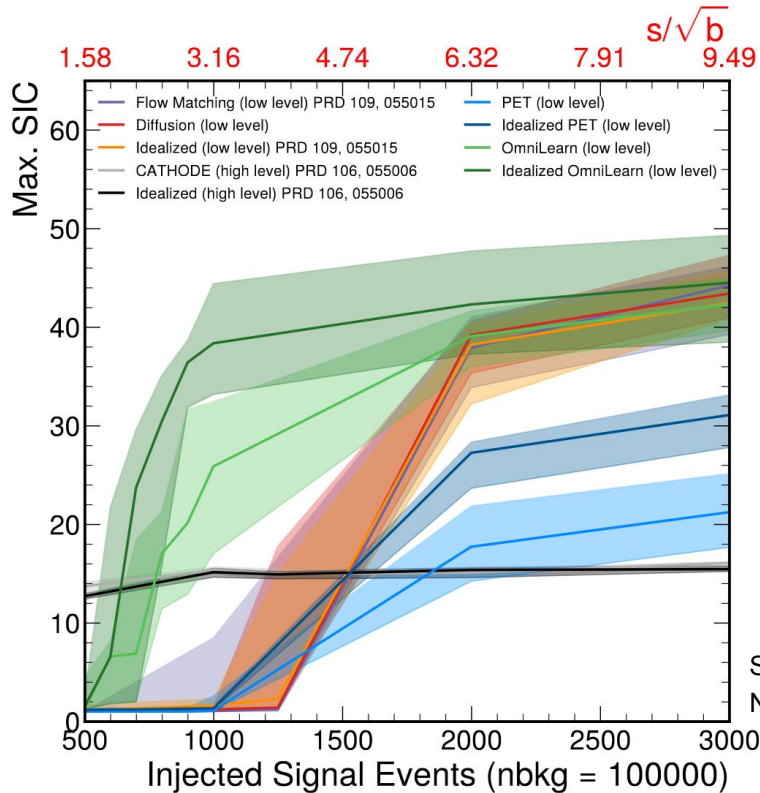
LHCO R&D dataset

- Resonant **dijet** final state: $A \rightarrow B(qq)C(qq)$ with $m_A, m_B, m_C = 3.5, 0.5, 0.1$ TeV



Anomaly Detection

Evaluation datasets: **9**



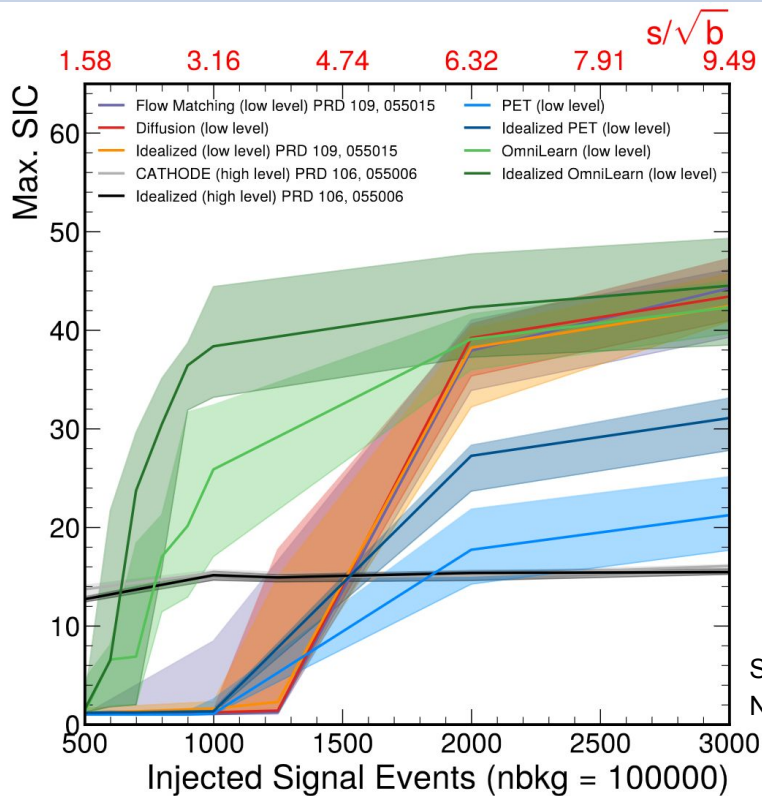
- **Generate** the full dijet system: $2 \times 279 \times 3 = 1674$ numbers to generate
 - **Classify** data from background
- SIC** = Significance Improvement Curve (TPR/sqrt(FPR) vs TPR) “By how much can I improve the significance of a particular signal given an initial significance.”

See also: E. Buhmann, C. Ewen, G. Kasieczka, **V. Mikuni**, B. Nachman, and D. Shih, Phys. Rev. D 109, 055015



Anomaly Detection

Evaluation datasets: 9



- **Generate** the full dijet system: $2 \times 279 \times 3 = 1674$ numbers to generate

- **Classify** data from background

Previous results were limited by the amount of data in the SR: Only sensitive to NP when

S/B > 3% $\sim 4\sigma$

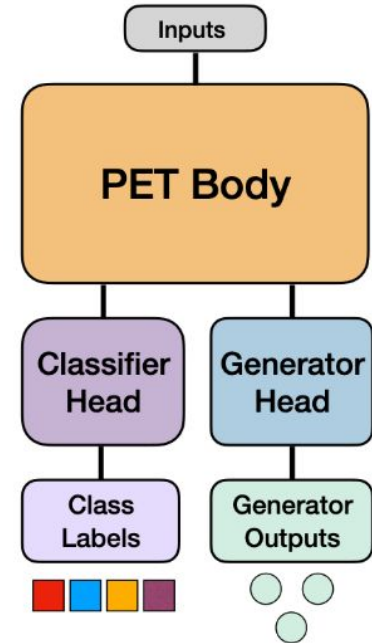
OmniLearn finds the NP with **S/B = 0.7% $\sim 2\sigma$**

See also: E. Buhmann, C. Ewen, G. Kasieczka, V. Mikuni, B. Nachman, and D. Shih, Phys. Rev. D 109, 055015



Conclusion

- **OmniLearn**: learn a general representation of jets
- Evaluation across **9 different downstream datasets**
- Evaluate the performance on **jet tagging, jet generation, unfolding**, and **anomaly detection**
- OmniLearn improves upon SOTA or/and converges quicker than models trained from scratch
- Magnify the statistical power of the data: **Not only Big Data benefits from AI**
- **Try it out yourself:**
<https://github.com/ViniciusMikuni/OmniLearn/> and check out the paper: [arXiv:2404.16091](https://arxiv.org/abs/2404.16091)





THANKS!

Any questions?

Backup



Comparison Between Models

Language inspired models

- Data are tokenized
- Unsupervised and general pre-training
- Big models often required

OmniLearn

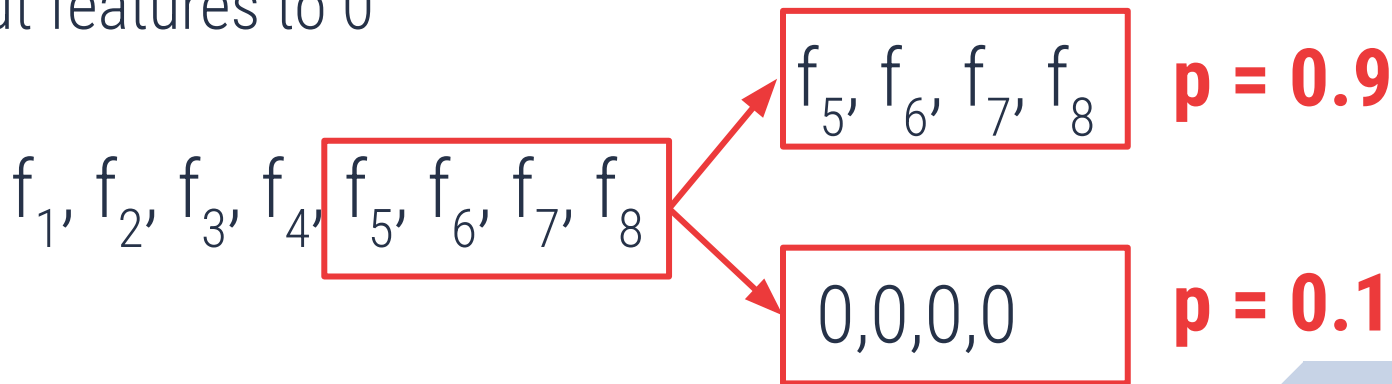
- Data are continuous
- HEP has one of the best simulators across all sciences: supervised pre-training
- Medium models that can fit on standard GPUs are still useful



Input Dropout

Not all datasets contain the same information:

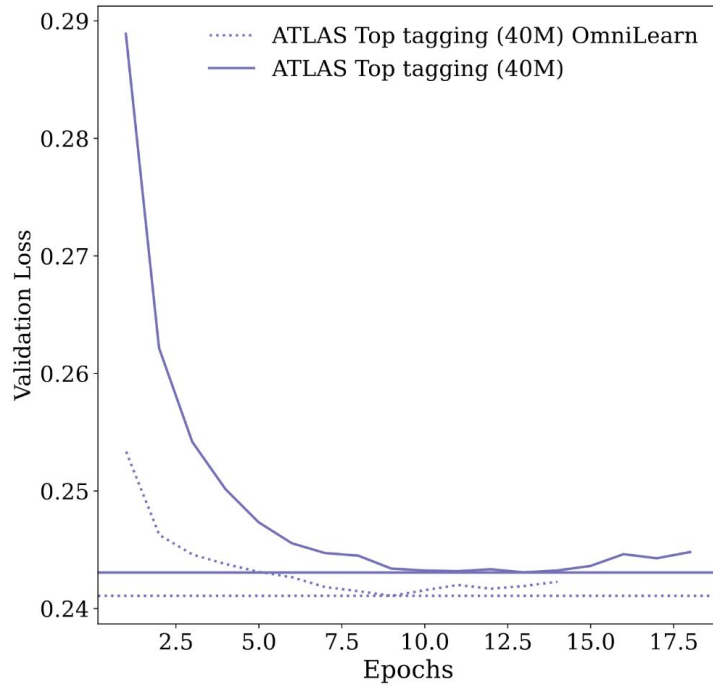
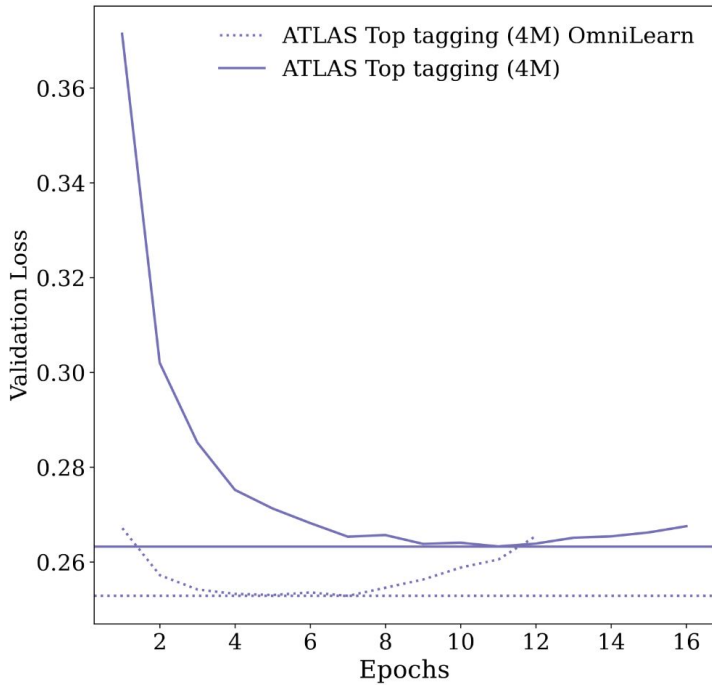
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More details at: <https://arxiv.org/abs/2404.16091>

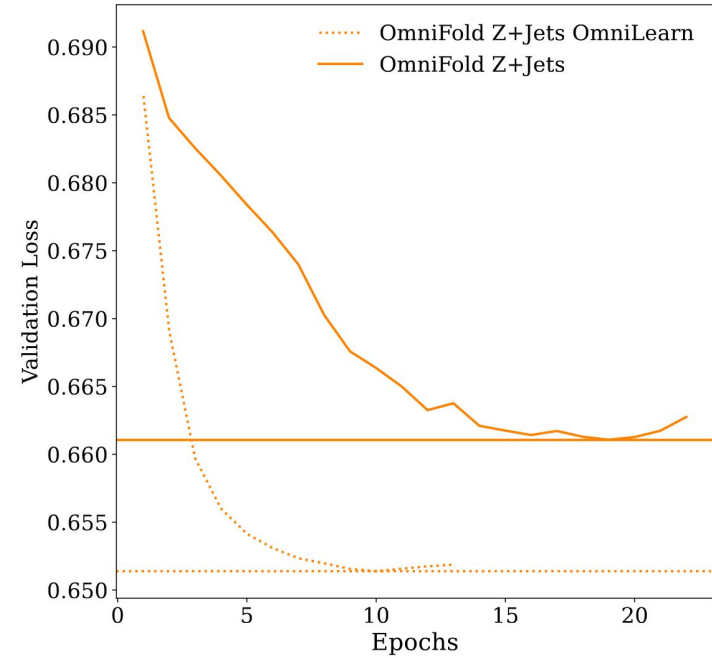
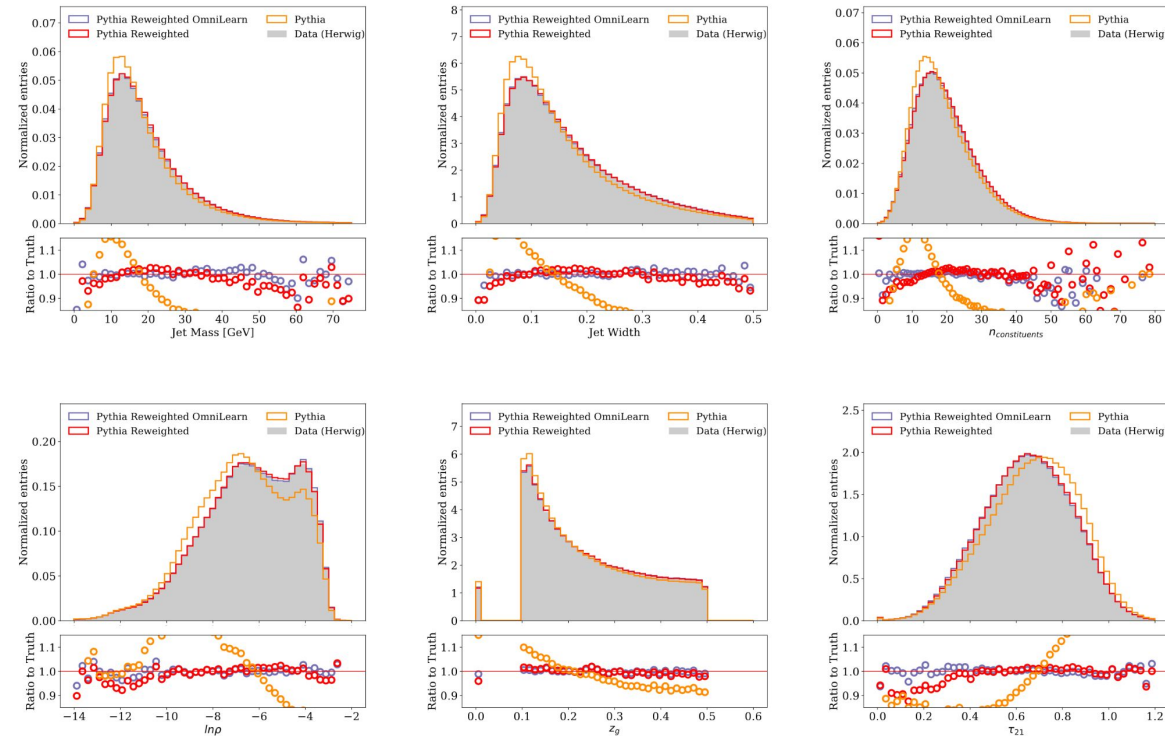


ATLAS Loss Curves



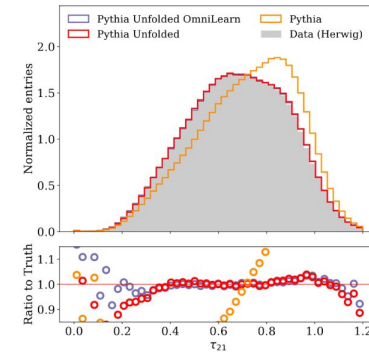
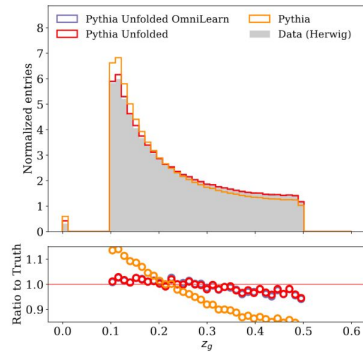
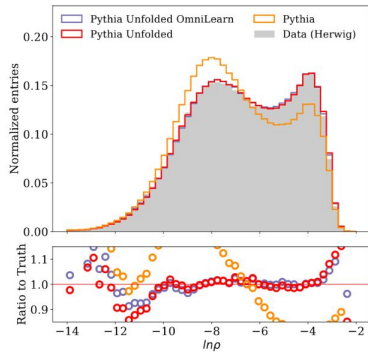
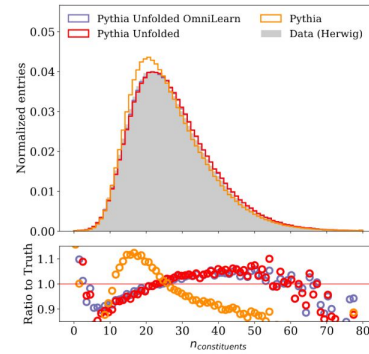
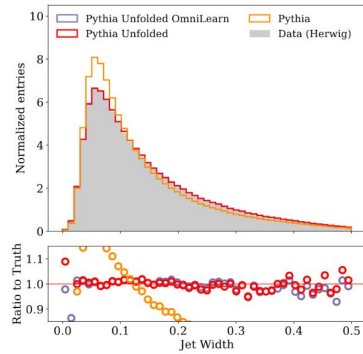
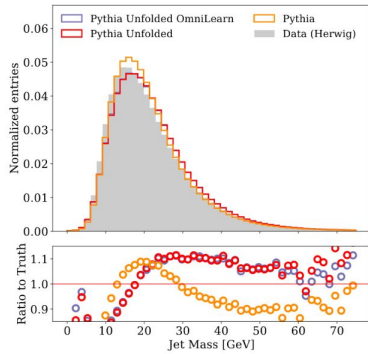


OmniLearn for reweighting



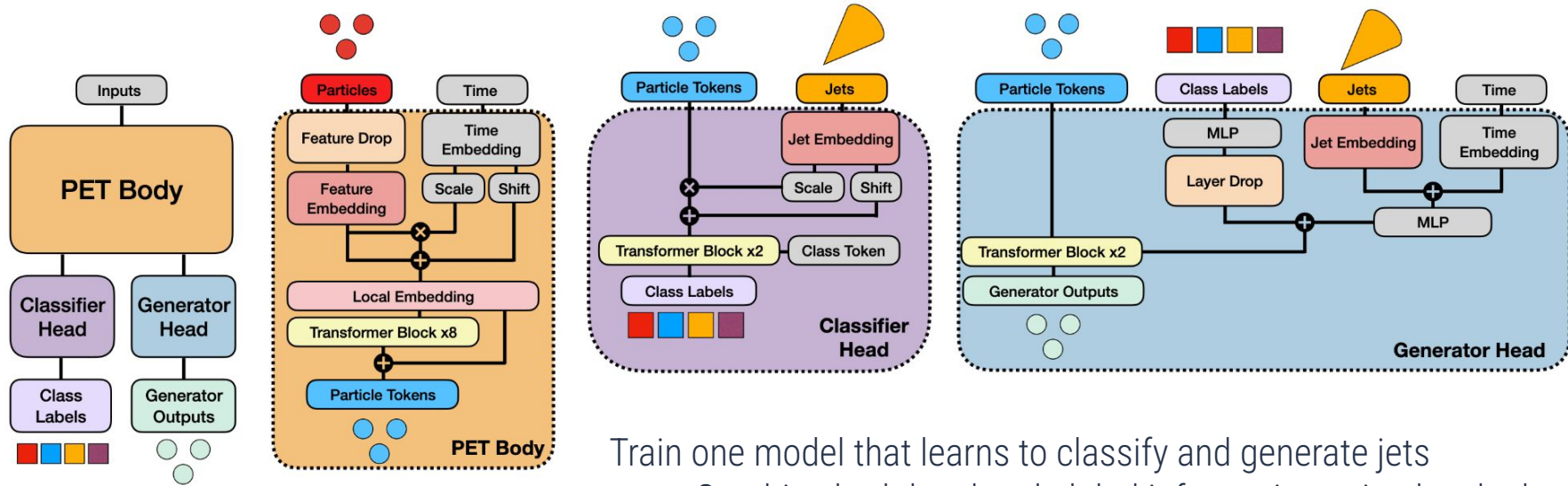


OmniLearn for Unfolding





PET



Train one model that learns to classify and generate jets

- Combine both local and global information using local edges and a transformer: **P**oint-**E**dge **T**ransformer



Diffusion Generative Models

Forward SDE (data \rightarrow noise)

$$\mathbf{x}(0) \longrightarrow dx = \mathbf{f}(\mathbf{x}, t)dt + g(t)d\mathbf{w} \longrightarrow \mathbf{x}(T)$$



score function

$$\mathbf{x}(0) \longleftarrow dx = [\mathbf{f}(\mathbf{x}, t) - g^2(t) \nabla_{\mathbf{x}} \log p_t(\mathbf{x})] dt + g(t)d\bar{\mathbf{w}} \longleftarrow \mathbf{x}(T)$$

Reverse SDE (noise \rightarrow data)

Source:

<https://yang-song.net/blog/2021/score/>



Loss function

$$\begin{aligned}\mathcal{L} &= \mathcal{L}_{\text{class}} + \mathcal{L}_{\text{gen}} + \mathcal{L}_{\text{class smear}} \\ &= \text{CE}(y, y_{\text{pred}}) + \|\mathbf{v} - \mathbf{v}_{\text{pred}}\|^2 + \alpha^2 \text{CE}(y, \hat{y}_{\text{pred}})\end{aligned}$$

Straightforward loss function:

- **Cross entropy** for each class
- Perturbed data prediction from the **diffusion loss**
- Classification over perturbed inputs: **data augmentation!**

More details at: <https://arxiv.org/abs/2404.16091>



Diffusion 101

Diffusion models are the go to for data generation

- Simple training: take data \mathbf{x} , perturb with a Gaussian of mean μ and std σ
- $\mathbf{x}' = \mu * \mathbf{x} + \sigma * \boldsymbol{\varepsilon}, \boldsymbol{\varepsilon} \sim \mathbf{N}(0,1)$
- Ask the network to predict the noise injected
- $\mathbf{L} = \|\mathbf{D}(\mathbf{x}') - \boldsymbol{\varepsilon}\|^2$

