

Davide Valsecchi (ETH Zurich) - CMS Johannes Michael Wagner (University of California Berkeley) - ATLAS





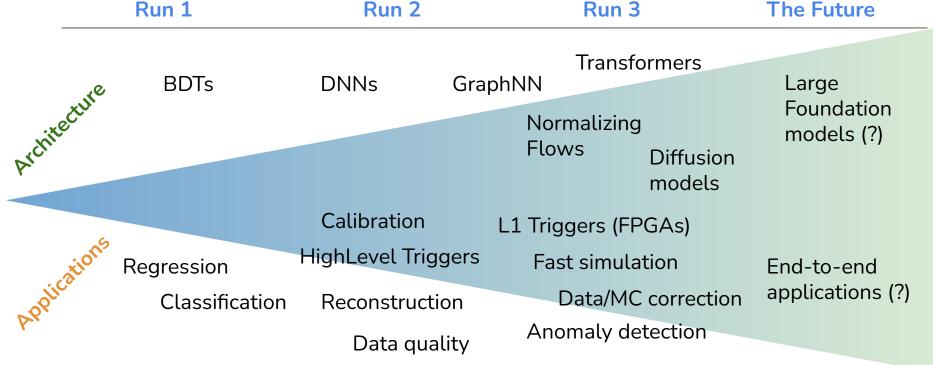


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ML in Higgs 2024

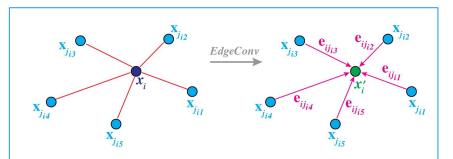
08-11-2024

ML expanding toolbox \rightarrow many interesting applications in HEP beyond Sig vs Bkg





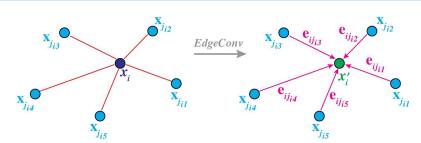
ML architecture depends on the data structure and task



Graph Networks: encode the relation between (unordered) objects. Extract information both about the full graph and the single objects or edges. arxiv1812.08434



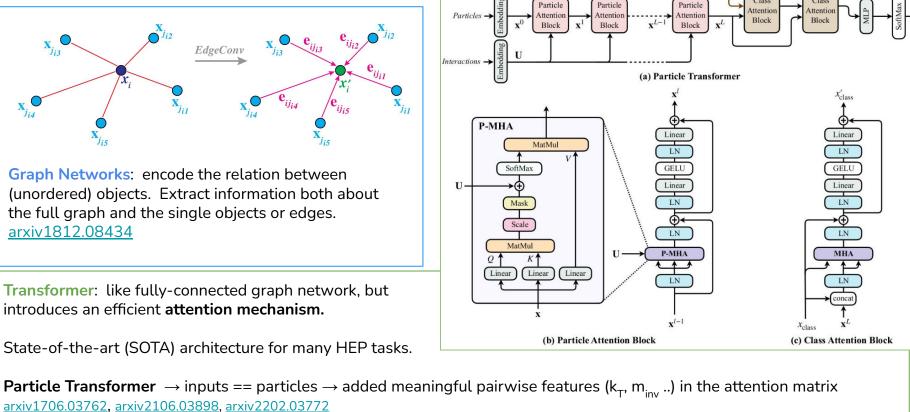
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Graph Networks: encode the relation between (unordered) objects. Extract information both about the full graph and the single objects or edges. arxiv1812.08434

Transformer: like fully-connected graph network, but introduces an efficient attention mechanism.

State-of-the-art (SOTA) architecture for many HEP tasks.



L blocks

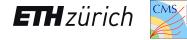
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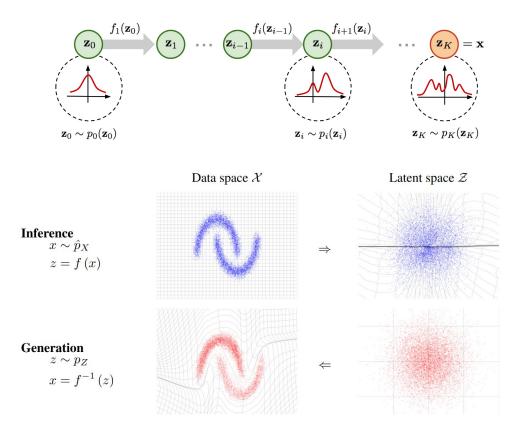
ETH zürich

Class

Class



ML architecture depends on the data structure and task



Probabilistic ML architectures: Normalizing Flows <u>arxiv1908.09257</u>

 \rightarrow Used to model complex p.d.f. with a sequence of simple invertible transformations from a simple base p.d.f. (gaussians)

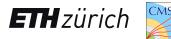
\rightarrow both density estimation and sample generation

Many natural applications in HEP:

- fast simulation: CMS FlashSim <u>CMS-DP-2024-080</u>
- calibration (<u>CMS-PAS-HIG-23-014</u>, <u>ATLAS-CONF-2024-014</u>)
- importance sampling <u>CMS-DPS-2023-085v2</u>

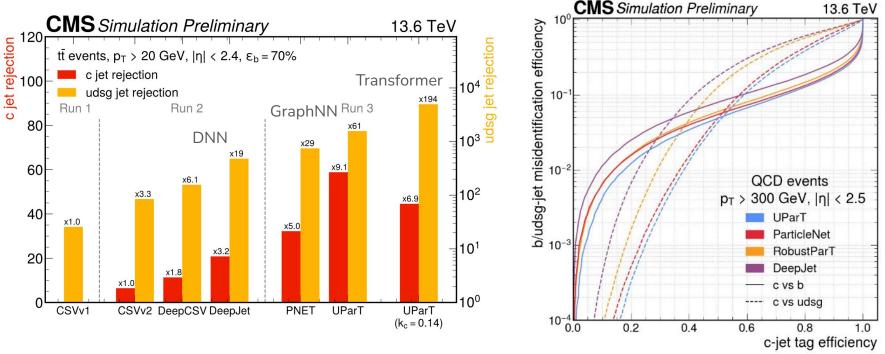
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A unified approach to Jet Tagging



Evolution of taggers \rightarrow From **DNN** to **GraphNN** (ParticleNet) to **Transformer** (UnifiedParT)

- Many improvements all included in the new state-of-the-art tagger CMS-DP-2024-066
- "Unified" tagger \rightarrow **UParT**: new Run3 best model



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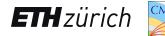
ML in Higgs 2024

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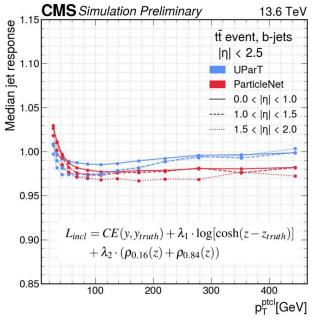
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UParT: robust training and jet calibration

CMS-DP-2024-066



- Training includes also jet \textbf{p}_{T} regression and resolution estimation



UPart has a better jet response, especially at high eta

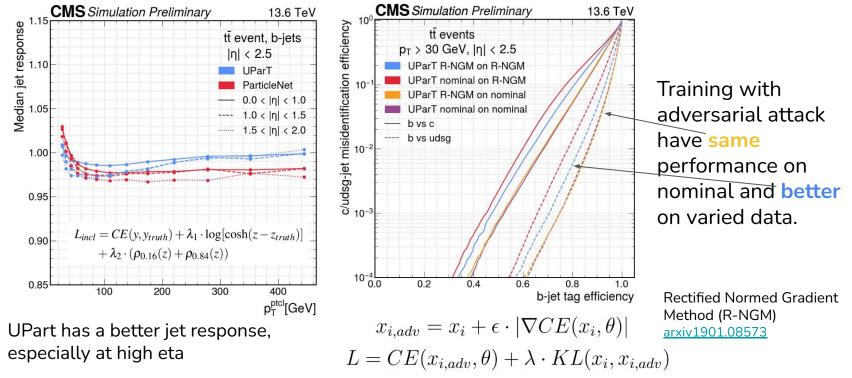
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UParT: robust training and jet calibration





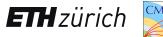
- Training includes also jet p_T regression and resolution estimation
- Trained with adversarial attack for data/MC robustness



Train the model on distorted inputs to become less sensitive to feature changes

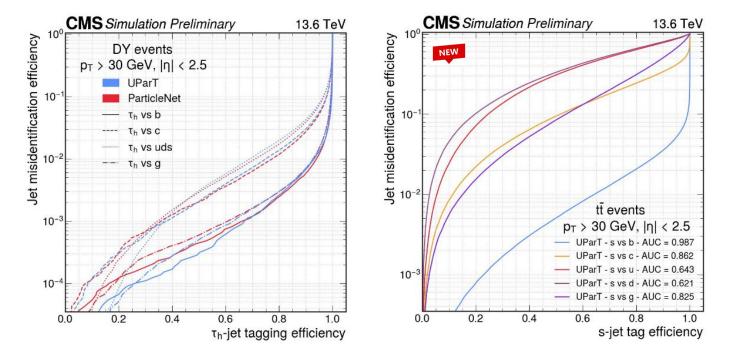
UParT: s-tagging and tau-tagging

CMS-DP-2024-066



UPart includes classes for hadronic taus, and strange jets.

- made possible by new tuning of CMS pileup removal algorithm CMS-DP-2024-043
- low-efficiency s-tagger: first time in CMS



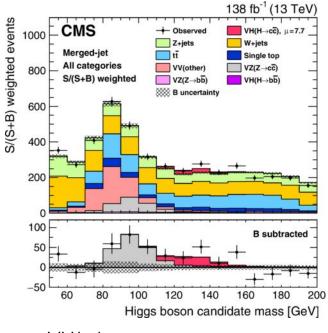
Boosted Jet taggers



ParticleNet is very powerful also for searching for resonances in AK8 jets.

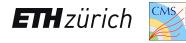
- Implemented in Run2 for boosted X(bb) and X(cc) tagging
- significant improvements in the performance of VH(cc) PhysRevLett.131.061801 and HH(4b)

PhysRevLett.131.041803 searches (see <u>talk</u> from Raffaele)



VH(cc) <u>PhysRevLett.131.061801</u>

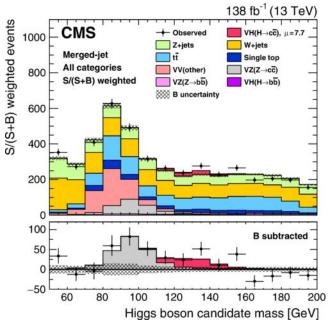
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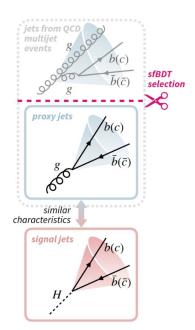


VH(cc) PhysRevLett.131.061801

3 calibration methods documented in <u>BTV-22-001</u>

Using ML for calibration: **sfBDT**

- Select g→bb/cc jets in QCD that are more similar to X→bb/cc decays
- Inputs: N-subjettines, track and SV information



Boosted Jet taggers

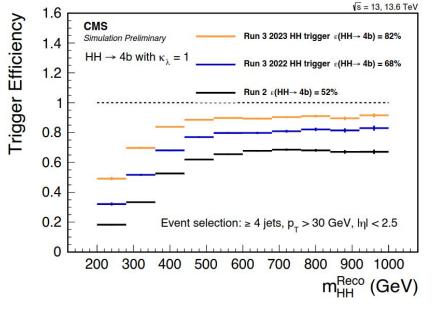
Many improvements for Run3: <u>CMS-DP-2024-055</u>

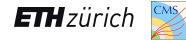
- added boosted $H(\tau\tau)$ decays
- Simultaneous train classification and regression tasks in single network
- Improve mass decorrelation by sampling more granularly the mX range: no mass sculpting on background <u>CMS-DP-2021-017</u>

From Run3 using ParticleNet-MD in **scouting trigger**s to enhance the acceptance of analysis looking at final state with boosted hadronic resonances.

More info in M. Stamenkovic <u>talk</u> at FTAG workshop

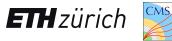
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<u>CMS-DP-2023-050</u>

Multi-prong ParT tagger

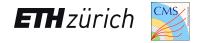


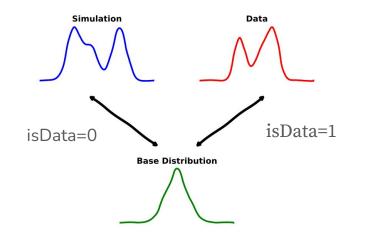
Exploring an extension of PartT to multi-prong decays in AK8 jets \rightarrow **GloParT**

- developed for HH \rightarrow VV \rightarrow 4b analysis <u>CMS-PAS-HIG-23-012</u>
- including: top-tagging (3 prong), $X \rightarrow VV$ with hadronic and leptonic decays, taus etc.
- same mass decorrelation strategy by using flat mass signal samples vs QCD
 → learn only substructure

Challenge: calibration with multi-prong decays

Figure 4: Full set of training jet classes for GloParT.





Problem: correct MC mis-modeling of complex IDs or regressions depending on many observables.

Normalizing Flows (NF) can be used to build an "optimal transport" correction:

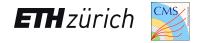
 \rightarrow train a NF to bring data and MC p.d.f.s to a common base distribution (gaussian)

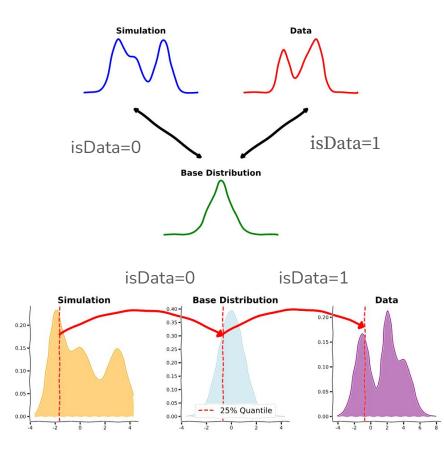
 \rightarrow use the resulting transformations to morph MC into data

 \rightarrow the transformation can be made conditional on other observables

Demonstrated method on toy data: One Flow to correct them all <u>arxiv2403.18582</u>

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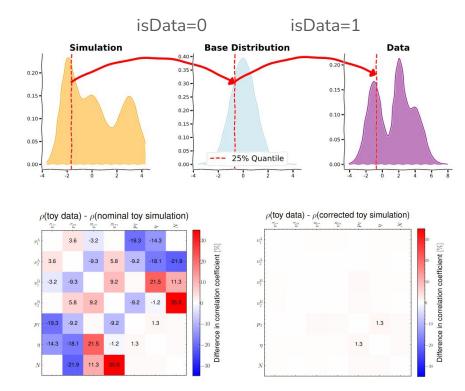
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Demonstrated method on toy data: One Flow to correct them all <u>arxiv2403.18582</u>





Correct both 1D distributions and (also complex) correlations

Problem: correct MC mis-modeling of complex IDs or regressions depending on many observables.

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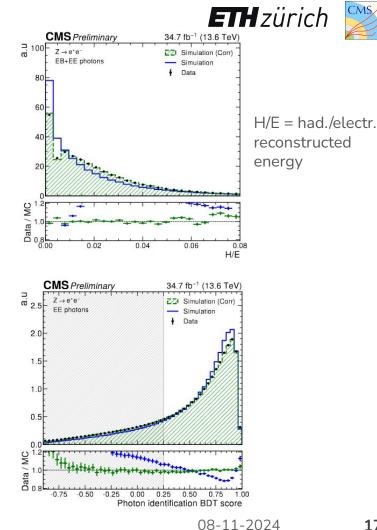
Demonstrated method on toy data: One Flow to correct them all <u>arxiv2403.18582</u>

 $H \rightarrow \gamma \gamma$ inclusive and differential XS at 13.6 TeV (Run3 2022 data) CMS-PAS-HIG-23-014

Photon ID inputs: shower shapes, isolation variables, H/E, per-photon energy resolution estimate σ_{r}

Mismodeling Photon ID \rightarrow mismodeling of the per-event diphoton inv-mass resolution $\sigma_{_{\rm M}} \rightarrow$ affects analysis categorization \rightarrow large uncertainty

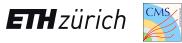
- In Run2 used a chain of BDT to correct shower shape and isolation variables
- in Run3 used the **Normalizing Flow** technique to correct shower shape, isolation and σ_{F} , conditionally by η , φ , pT of the photon and ρ (energy density from PU)
 - Simpler model and even more powerful correction: ~1-2% residual data/MC discrepancy checked in $Z \rightarrow \mu\mu\gamma$ events



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ML in Higgs 2024

ML for EFT



We can exploit the EFT quadratic expansion to build optimal classifiers to measure SMEFT operators effects.

$$p(\boldsymbol{x}|\boldsymbol{\theta}) = \int p(\boldsymbol{x}, \boldsymbol{z}) d\boldsymbol{z} = \int p(\boldsymbol{x}|\boldsymbol{z}) p(\boldsymbol{z}|\boldsymbol{\theta}) d\boldsymbol{z},$$

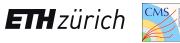
the full likelihood is intractable at detector level (x). MELA method attacks this with transfer functions

likelihood ratio

$$R(\boldsymbol{x}|\boldsymbol{\theta},\boldsymbol{\theta}_0) = \frac{\mathrm{d}\sigma_{\boldsymbol{\theta}}(\boldsymbol{x})/\mathrm{d}\boldsymbol{x}}{\mathrm{d}\sigma_{\boldsymbol{\theta}_0}(\boldsymbol{x})/\mathrm{d}\boldsymbol{x}} = \frac{\sigma(\boldsymbol{\theta})\,p(\boldsymbol{x}|\boldsymbol{\theta})}{\sigma(\boldsymbol{\theta}_0)\,p(\boldsymbol{x}|\boldsymbol{\theta}_0)} \longrightarrow r(\boldsymbol{x},\boldsymbol{z}|\boldsymbol{\theta},\boldsymbol{\theta}_0) \equiv \frac{p(\boldsymbol{x},\boldsymbol{z}|\boldsymbol{\theta})}{p(\boldsymbol{x},\boldsymbol{z}|\boldsymbol{\theta}_0)} = \frac{p(\boldsymbol{z}|\boldsymbol{\theta})}{p(\boldsymbol{z}|\boldsymbol{\theta}_0)} \overset{\text{join had}}{\underset{\text{factor}}{\mathrm{factor}}}$$

oint likelihood ratio: reco, nadronization, showering factors cancel

ML for EFT



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$$L = \sum_{\boldsymbol{\theta}\in\mathcal{B}} \int \mathrm{d}\boldsymbol{x}\,\mathrm{d}\mathbf{z}\,p(\boldsymbol{x},\boldsymbol{z}|\mathrm{SM})\left(r(\boldsymbol{x},\boldsymbol{z}|\boldsymbol{\theta})\hat{f}(\boldsymbol{x};\boldsymbol{\theta})^{2} + (1-\hat{f}(\boldsymbol{x};\boldsymbol{\theta}))^{2}\right) \longrightarrow f(\boldsymbol{x};\boldsymbol{\theta}) = \frac{1}{1+\hat{R}(\boldsymbol{x};\boldsymbol{\theta})}$$

We can use a ML model to approximate $f(X,\theta)$ with a regression \to optimal likelihood ratio for each θ point in the Wilson space

$$R(x|\theta,\theta_0) = 1 + \sum_{a} (\theta - \theta_0)_a R_a(x) + \sum_{a,b} \frac{1}{2} (\theta - \theta_0)_a (\theta - \theta_0)_b R_{ab}(x)$$

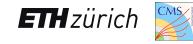
polynomial expansion: model each term with BDTs or NNs

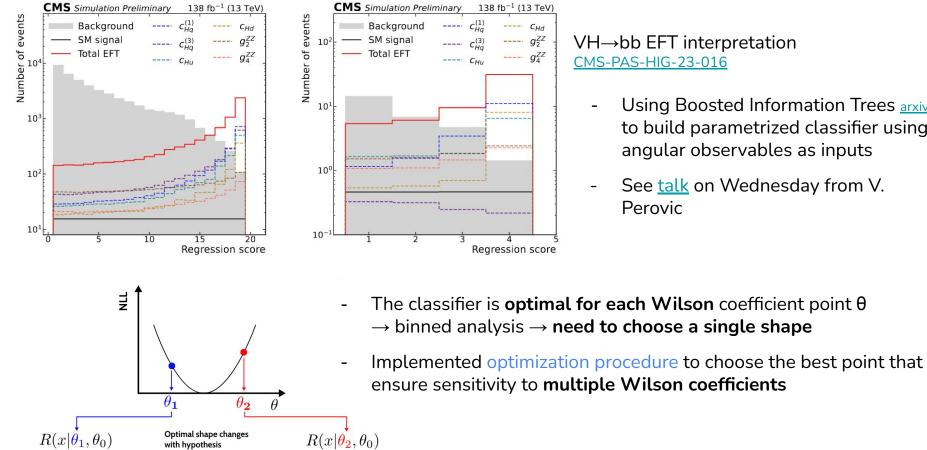
 $\left| \begin{array}{c} \bar{q} \\ q \end{array} \right| \left| \begin{array}{c} \bar{q} \\ + \\ \frac{\theta}{\Lambda^2} \\ t \\ q \end{array} \right| \left| \begin{array}{c} \bar{q} \\ + \\ \frac{\theta}{\Lambda^2} \\ t \\ \end{array} \right|^2$

More details in Learning EFT with Tree boosting arxvi2205.12976, MadMiner: 1907.10621

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Boosted Information Trees for EFT fits

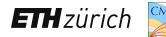




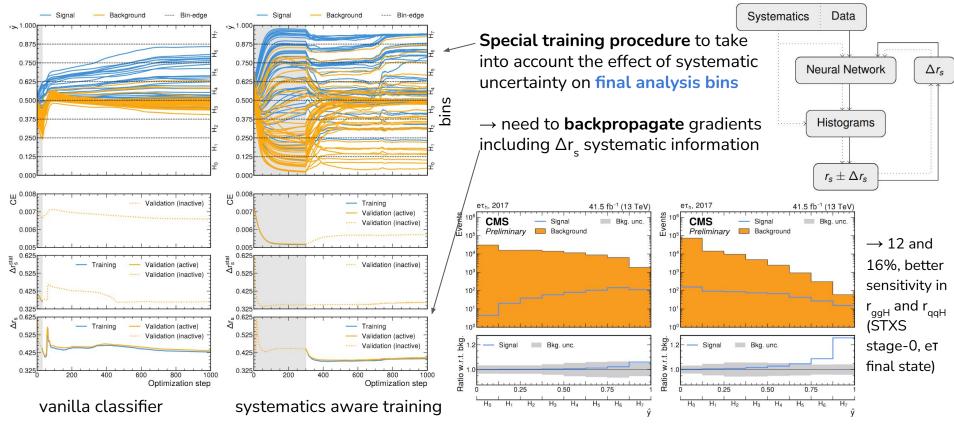
$VH \rightarrow bb EFT$ interpretation CMS-PAS-HIG-23-016

- Using Boosted Information Trees arxiv to build parametrized classifier using angular observables as inputs
- See <u>talk</u> on Wednesday from V. Perovic

Systematic-aware NN trainings



Development of systematic-aware NN trainings for binned-likelihood-analyses at the LHC <u>CMS-PAS-MLG-23-005</u>



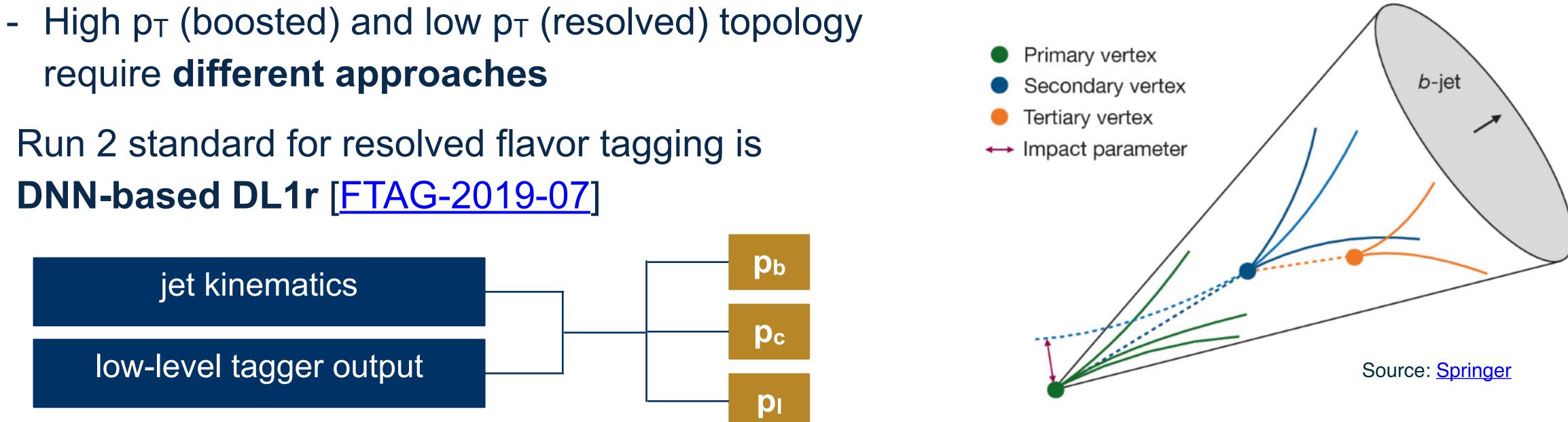
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ML in Higgs 2024

08-11-2024



- Many Higgs measurements rely on powerful jet flavor tagging algorithms
 - require different approaches
- Run 2 standard for resolved flavor tagging is **DNN-based DL1r** [<u>FTAG-2019-07</u>]



- Low level taggers consist of IP and SV fitting algorithms plus track-based RNN
- classify physics of large-R jets as H(bb), Top or QCD
- Move to DNN-based flavor tagging plays significant role in all sensitivity improvements highlighted today

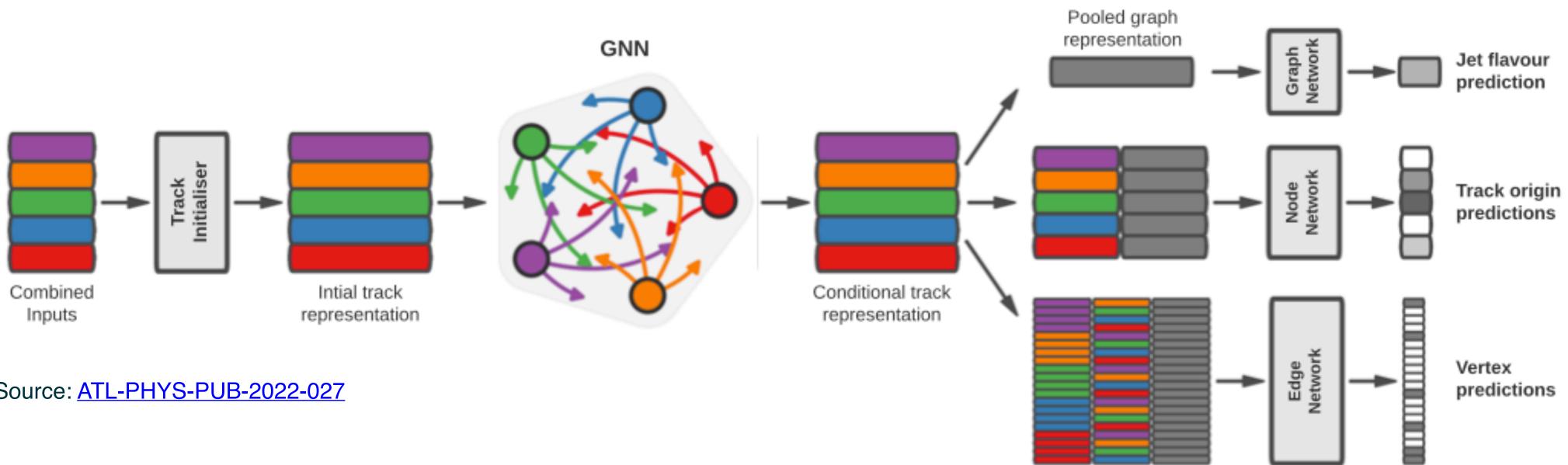
Flavor tagging: run 2 improvements



• Separate DNN-based algorithm in boosted regime uses DL1r scores on VR track jets to



- Run 3 FTAG in ATLAS based on transformer encoder with tracks as inputs
 - Attention mechanism allows for incorporating correlations between features from **different tracks** (kinematics, IPs, lower-level tracking information)
- Jet flavor classification task aided by additional physics-inspired auxiliary training objectives
- Shared structure for GN1/GN2 [PHYS-PUB-2022-027] in resolved and GN2X [PHYS-PUB-2023-021] in boosted



Source: ATL-PHYS-PUB-2022-027

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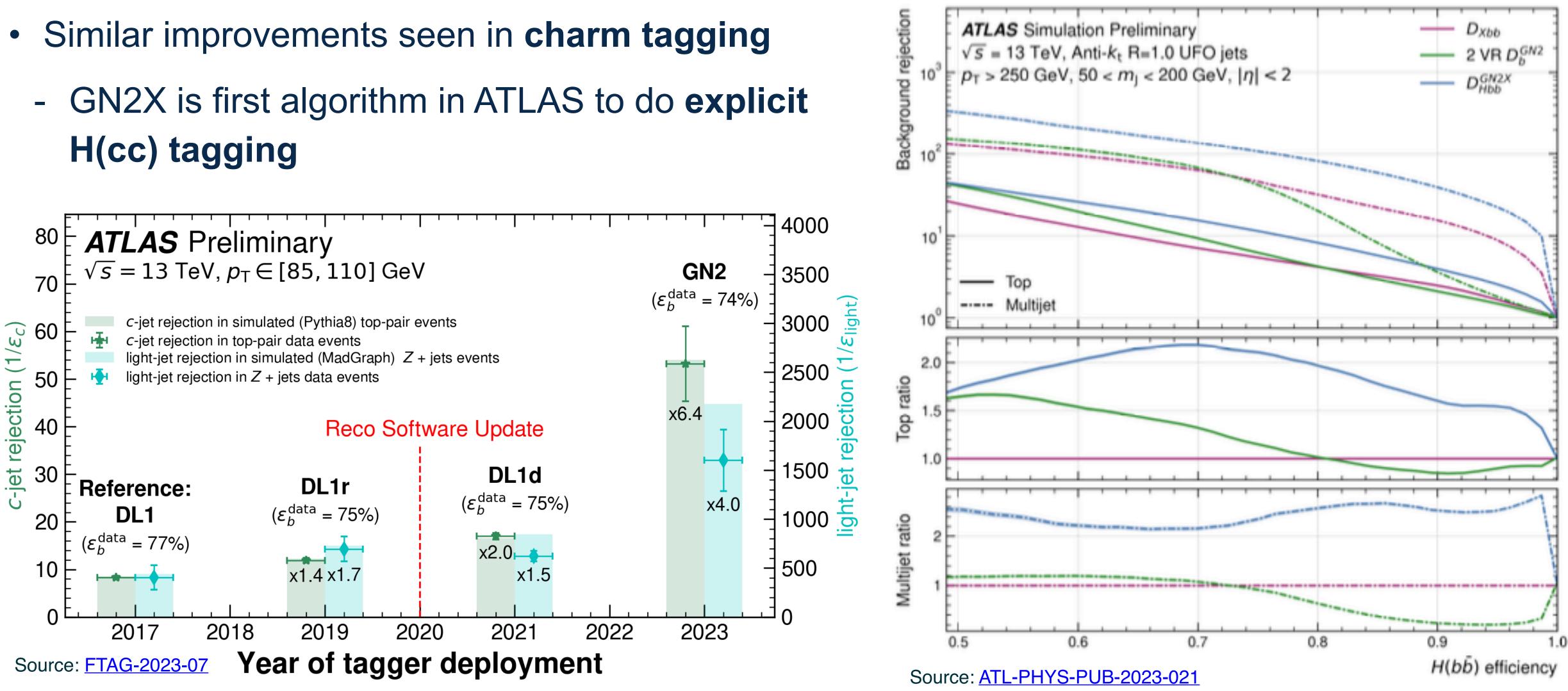








- and **2/3-times for H(bb) tagging** with GN2X
- - H(cc) tagging



Flavor tagging: performance comparisons



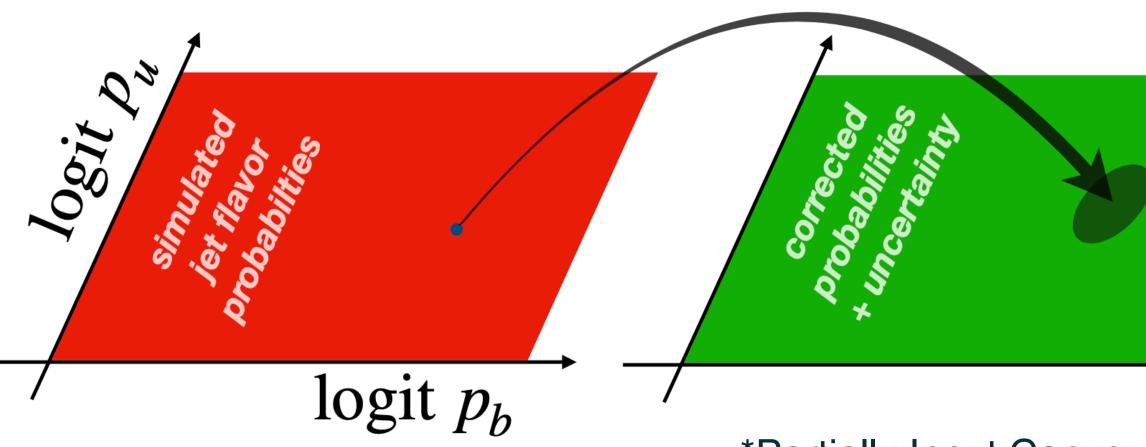
Up to 4-times increased background rejection for bottom tagging with GN2 compared to DL1r







- FTAG algorithms require individual calibrations based on choice of discriminant
 - New method uses optimal transport maps to calibrate (pb, pc, pu) continuously
- Idea is to derive p_T dependent mapping T_{p_T} which matches data performance and minimally alters the simulation (via euclidian distance metric) 0.8
 - Mapping is gradient of scalar complex function \rightarrow use PICNN* to approximate
- Method tested [CONF-2024-014] on b-jets in leptonic $t\bar{t}$ decays with **good closure** across the board

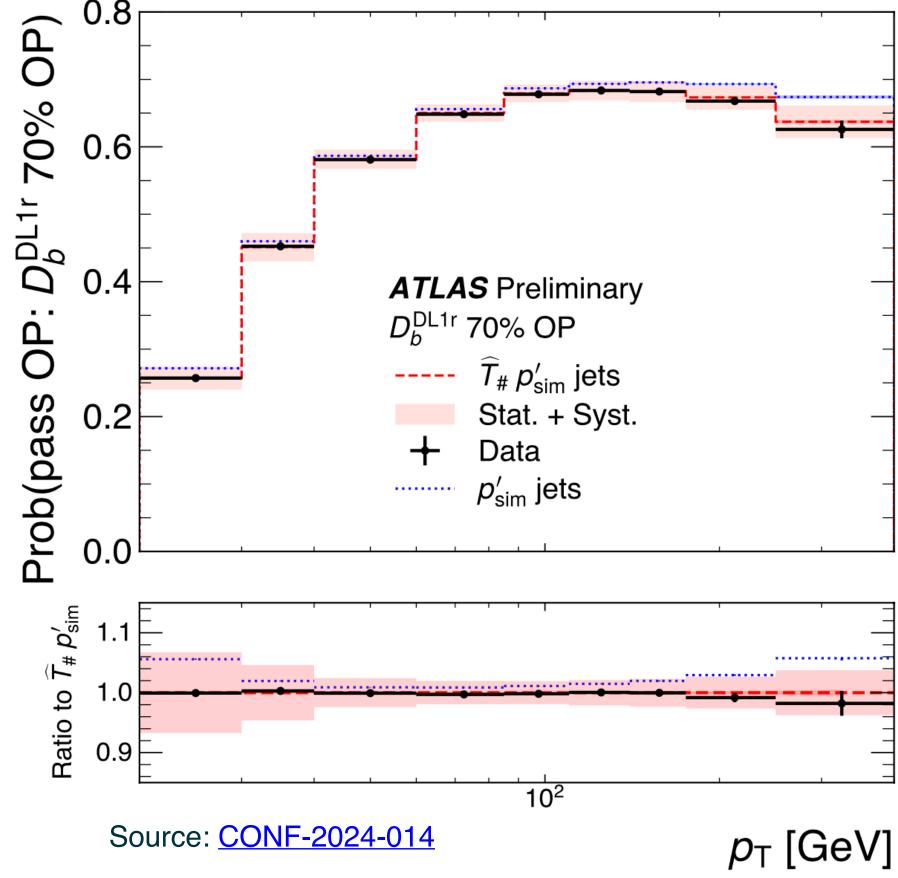


*Partially Input Convex Neural Network

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Flavor tagging: calibration via optimal transport





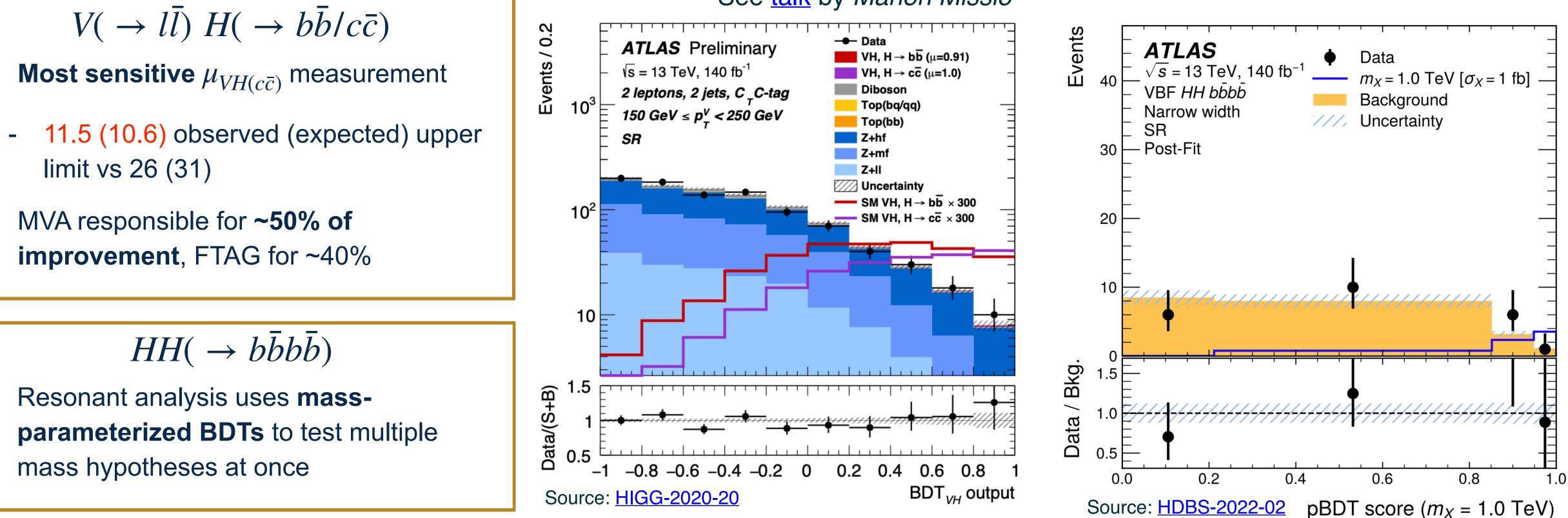


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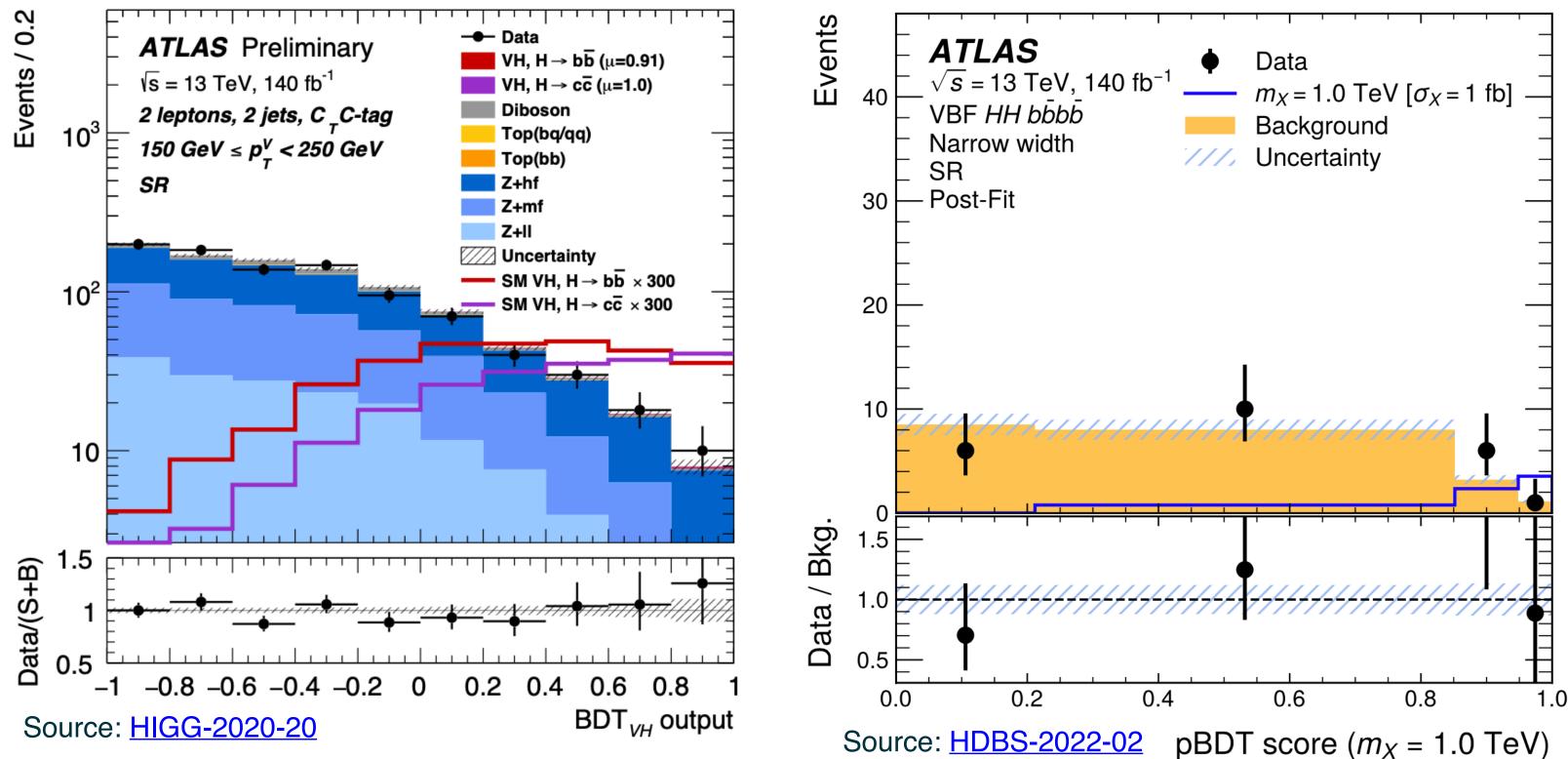




- Fitting BDT/DNN derived multi-variate discriminants gives increased S/B separation compared to single-variable based (i.e. m_H) fits
- boosted VBF $HH(\rightarrow bbbb)$ [HDBS-2022-02] analyses



$$HH(\rightarrow b\bar{b}b\bar{b})$$

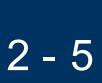




• MVA techniques bring notable improvements to $V(\rightarrow ll) H(\rightarrow bb/c\bar{c}) [HIGG-2020-20]$ and

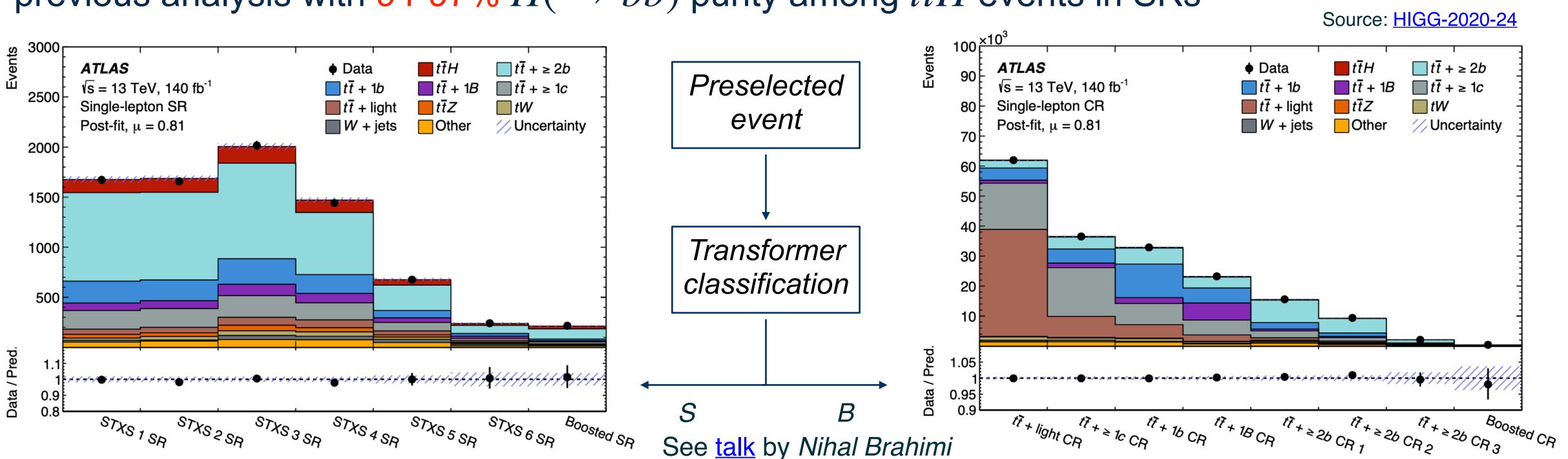
See talk by Marion Missio







- New $t\bar{t}H(\rightarrow bb)$ result [HIGG-2020-24] categorizes events with two Transformer-based neural networks from jet, lepton and MET input information
 - One splits events between signal and 5 $t\bar{t}$ +jets background categories, other identifies **Higgs candidate** p_T in signal events
- Main factor in improved $t\bar{t}H$ significance of 4.6 (5.4) observed (expected) vs 1.0 (2.7) in previous analysis with 94-97% $H(\rightarrow b\bar{b})$ purity among $t\bar{t}H$ events in SRs

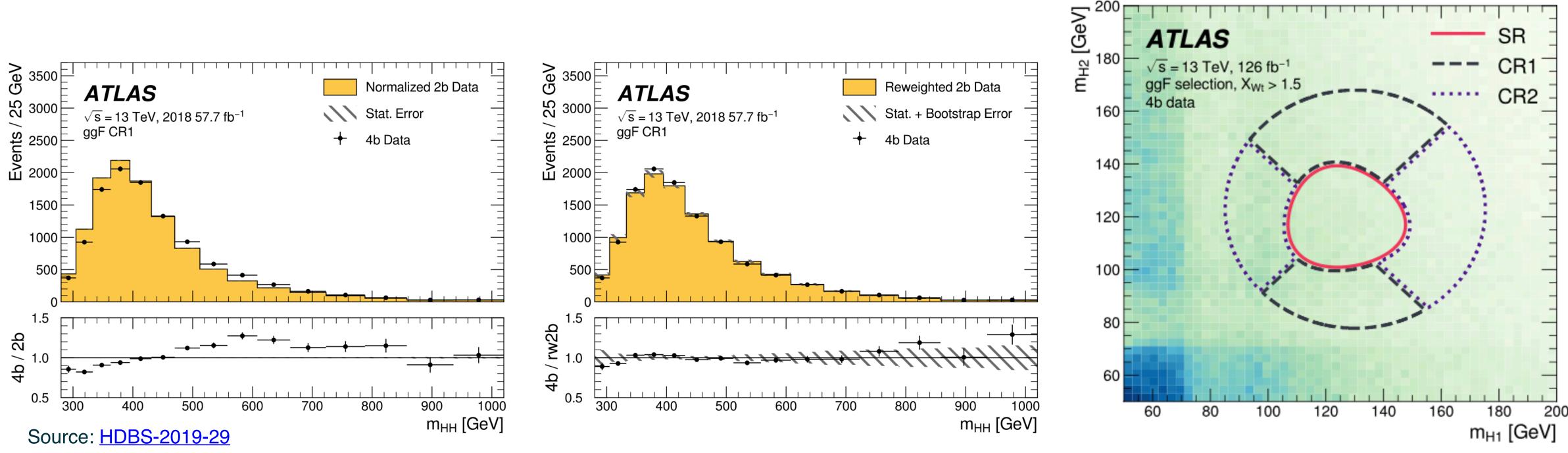








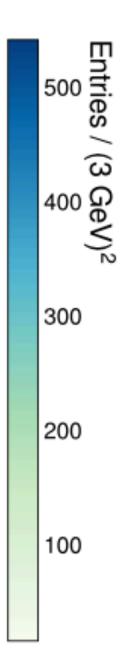
- estimate dominant (~90%) multi-jet background based on data
 - Background in SR modeled based on 2 b-tag events with kinematic differences accounted for by reweighting function (2b \rightarrow 4b) learned in CRs
- Improved modeling of correlations in kinematic variables leads to better mHH modeling, contributing to 30% improvement over lumi scaling





• ggF and VBF $HH(\rightarrow bbbb)$ result [HDBS-2019-29] uses DNN for density ratio estimation to reweighting function







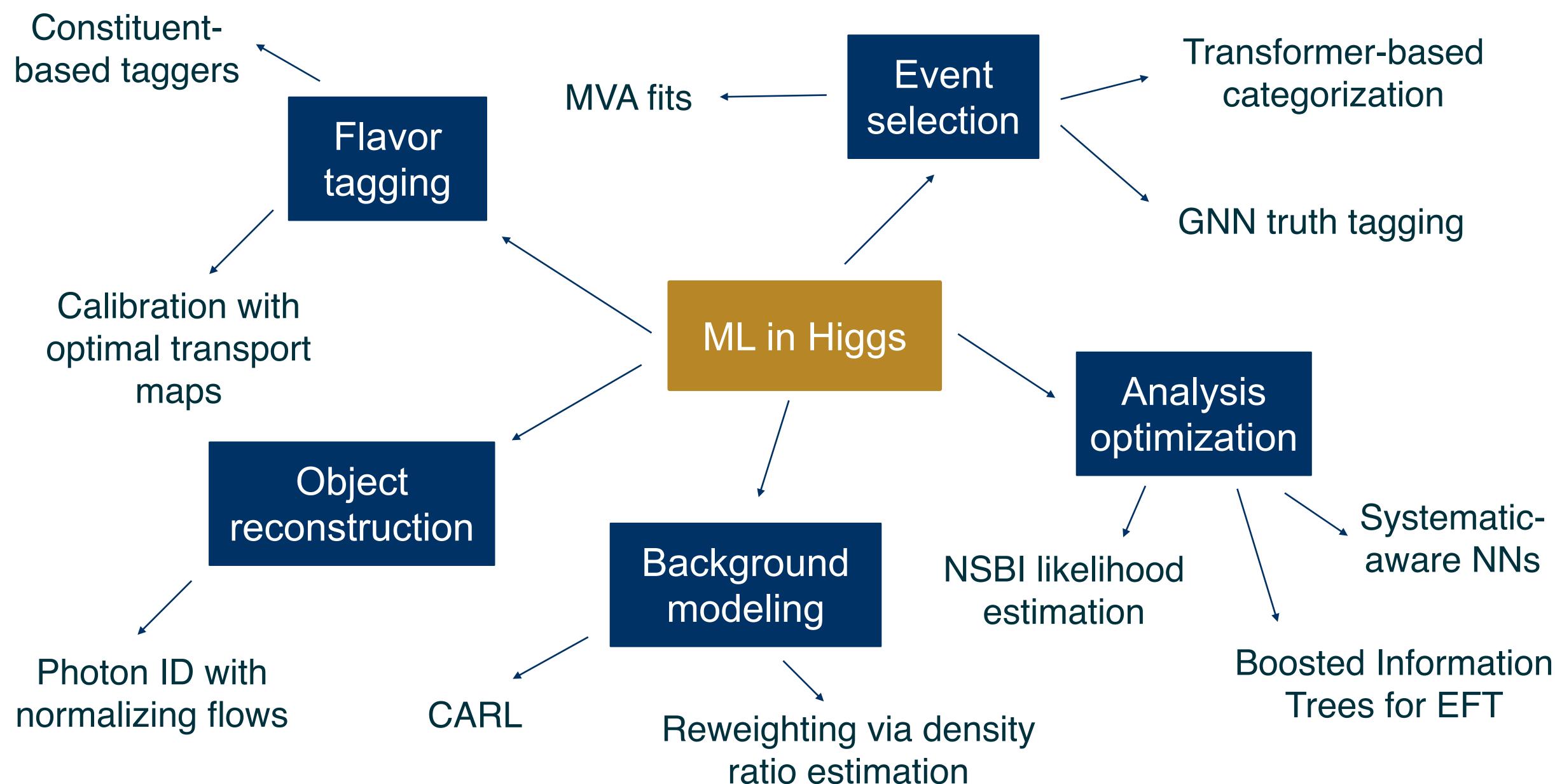


- MC-MC shape uncertainties derived via Calibrated Likelihood Ratio Estimator (CARL) in $V(\rightarrow l\bar{l}) H(\rightarrow b\bar{b}/c\bar{c})$ [CONF-2024-010]
 - DNN trained on **nominal and alternative MC** to distinguish the two
 - Output weights used to **reweight nominal** \rightarrow better statistics than alternative
- Neural simulation-based inference (NSBI) used to estimate likelihood ratios from unbinned events by learning a reweighting of one hypothesis to another [CONF-2024-015]
 - See <u>talk</u> by Jay Sandesara
- Weighted event selection via GNN-based "truth tagging" in $V(\rightarrow ll) H(\rightarrow bb/c\bar{c})$ [<u>CONF-2024-010</u>]
 - GNN trained on MC to predict probability that event passes given FTAG selection - All MC events kept and weighted, improving background modeling via increased statistics







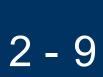


Today's highlights











- Machine learning is now a mainstay of Higgs physics in ATLAS and CMS
- Evolution characterized by larger and more complex models working with lower-level inputs
 - **Physics-inspired techniques** are gaining a lot of traction
 - Gradual increase in training statistics often still lead to performance gains
- Use of ML has expanded greatly beyond just object reconstruction and event selection
- Future holds many interesting possibilities as we move towards HL-LHC
 - On the horizon: global particle flow, physics foundation models, ML for unfolding, ...

Lots of exciting ML-related improvements to look forward to in run 3!









This material is based upon work supported by the National Science Foundation Graduate Research Fellowship under Grant No. DGE 2146752. Any opinion, findings, and conclusions or recommendations expressed in this material are those of the authors(s) and do not necessarily reflect the views of the National Science Foundation.

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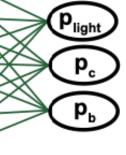
Backup



Input	Variable	Description	SVKine	JFKine	DL1	DL1r		
Kinematics	p_{T}	Jet $p_{\rm T}$	\checkmark	\checkmark	\checkmark	\checkmark		
Kinematics	η	Jet $ \eta $	\checkmark	\checkmark	\checkmark	\checkmark		
	$\log(P_{\rm b}/P_{\rm light})$	Likelihood ratio of the <i>b</i> -jet to light-flavour jet hypotheses			\checkmark	\checkmark		
IP2D, IP3D	$\log(P_{\rm b}/P_{\rm c})$	Likelihood ratio of the <i>b</i> -jet to <i>c</i> -jet hypotheses			\checkmark	\checkmark		
	$\log(P_{\rm c}/P_{\rm light})$	Likelihood ratio of the <i>c</i> -jet to light-flavour jet hypotheses			\checkmark	\checkmark		
	P _b	<i>b</i> -jet probability				\checkmark		
RNNIP	P _c	<i>c</i> -jet probability				\checkmark		
	P _{light}	light-flavour jet probability				\checkmark		
	m(SV)	Invariant mass of tracks at the secondary vertex assuming pion	\checkmark		\checkmark	\checkmark		
		mass						_
	$f_E(SV)$	Jet energy fraction of the tracks associated with the secondary	\checkmark		\checkmark	\checkmark		
SW1		vertex						Unrolled RNN
SV1	$N_{\text{TrkAtVtx}}(\text{SV})$	Number of tracks used in the secondary vertex	\checkmark		\checkmark	\checkmark		
	$N_{2\mathrm{TrkVtx}}(\mathrm{SV})$	Number of two-track vertex candidates	\checkmark		\checkmark	\checkmark		$\bigcirc \bullet \bullet$
	$L_{xy}(SV)$	Transverse distance between the primary and secondary vertices	\checkmark		\checkmark	\checkmark	×	
	$L_{xyz}(SV)$	Distance between the primary and secondary vertices	\checkmark		\checkmark	\checkmark		
	$S_{xyz}(SV)$	Distance between the primary and secondary vertices divided by	\checkmark		\checkmark	\checkmark		
		its uncertainty						Fully
	$\Delta R(\vec{p}_{\text{jet}}, \vec{p}_{\text{vtx}})(\text{SV})$	ΔR between the jet axis and the direction of the secondary vertex	\checkmark		\checkmark	\checkmark		
	J	relative to the primary vertex.						s s
	m(JF)	Invariant mass of tracks from displaced vertices		\checkmark	\checkmark	\checkmark		
	$f_E(JF)$	Jet energy fraction of the tracks associated with the displaced		\checkmark	\checkmark	\checkmark	s _{d0}	
		vertices					S.	
1	$\Delta R(\vec{p}_{jet}, \vec{p}_{vtx})$ (JF)	ΔR between the jet axis and the vectorial sum of momenta of all		\checkmark	\checkmark	\checkmark	-20	Track 1 ↓ Track 2 ↓ Track 3 ↓
JetFitter	j j j j j j j j j j j j j j j j j j j	tracks attached to displaced vertices					P _T ^{frac}	
	$S_{xyz}(JF)$	Significance of the average distance between PV and displaced		\checkmark	\checkmark	\checkmark	Δ R	
		vertices					hits	
	N _{TrkAtVtx} (JF)	Number of tracks from multi-prong displaced vertices		\checkmark	\checkmark	\checkmark		ordered by s _{a0} Jet
	$N_{2\mathrm{TrkVtx}}(\mathrm{JF})$	Number of two-track vertex candidates (prior to decay chain fit)		\checkmark	\checkmark	\checkmark		
	$N_{1-\text{trk vertices}}(\text{JF})$	Number of single-prong displaced vertices		\checkmark	\checkmark	\checkmark		Source: <u>FTAG-2019-07</u>
	$N_{\geq 2-\text{trk vertices}}(\text{JF})$	Number of multi-prong displaced vertices		\checkmark	\checkmark	\checkmark		000106. <u>1 170-2013-01</u>
	$L_{xyz}(2^{\rm nd})(\rm JF)$	Distance of 2 nd vertex from PV		\checkmark	\checkmark	\checkmark		
	$L_{xy}(2^{\rm nd})(\rm JF)$	Transverse displacement of the 2 nd vertex		\checkmark	\checkmark	\checkmark		
	$m_{\rm Trk}(2^{\rm nd})({\rm JF})$	Invariant mass of tracks associated with the 2 nd vertex		\checkmark	\checkmark	\checkmark		
	$E(2^{nd})(JF)$	Energy of the tracks associated with the 2 nd vertex						
	$f_E(2^{\rm nd})({\rm JF})$	Jet energy fraction of the tracks associated with the 2^{nd} vertex						
	$N_{\text{TrkAtVtx}}(2^{\text{nd}})(\text{JF})$	Number of tracks associated with the 2^{nd} vertex						
	min, max, avg (and) (IF)							
	$\eta_{\rm trk}^{\rm min, max, avg}(2^{\rm nd})({\rm JF})$	Min., max. and avg. pseudorapidity of tracks at the 2 nd vertex		✓	✓	✓		

DL1r details





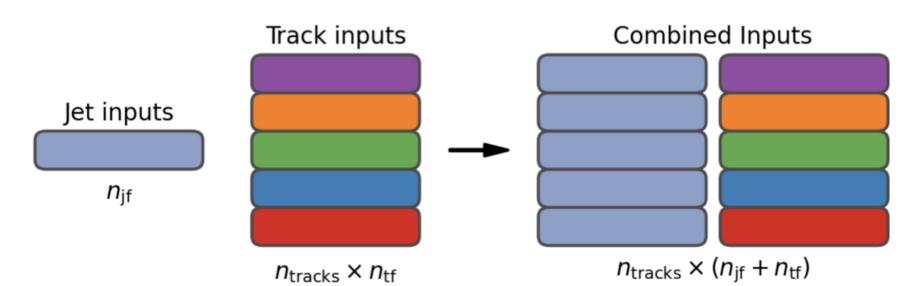




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GN1/GN2 model details

Jet Input	Description
p_{T}	Jet transverse momentum
η	Signed jet pseudorapidity
Track Input	Description
q/p	Track charge divided by momentum (measure of curvature)
$\mathrm{d}\eta$	Pseudorapidity of the track, relative to the jet η
$\mathrm{d}\phi$	Azimuthal angle of the track, relative to the jet ϕ
d_0	Closest distance from the track to the PV in the longitudinal plane
$z_0 \sin \theta$	Closest distance from the track to the PV in the transverse plane
$\sigma(q/p)$	Uncertainty on q/p
$\sigma(heta)$	Uncertainty on track polar angle θ
$\sigma(\phi)$	Uncertainty on track azimuthal angle ϕ
$s(d_0)$	Lifetime signed transverse IP significance
$s(z_0)$	Lifetime signed longitudinal IP significance
nPixHits	Number of pixel hits
nSCTHits	Number of SCT hits
nIBLHits	Number of IBL hits
nBLHits	Number of B-layer hits
nIBLShared	Number of shared IBL hits
nIBLSplit	Number of split IBL hits
nPixShared	Number of shared pixel hits
nPixSplit	Number of split pixel hits
nSCTShared	Number of shared SCT hits
nPixHoles	Number of pixel holes
nSCTHoles	Number of SCT holes
leptonID	Indicates if track was used in the reconstruction of an electron or muon (only for GN1



Johannes Wagner



Source: ATL-PHYS-PUB-2022-027

Truth (Origin	Description
Pileup		From a <i>pp</i> collision other than the primary interaction
Fake		Created from the hits of multiple particles
Primary	7	Does not originate from any secondary decay
fromB		From the decay of a <i>b</i> -hadron
fromBC		From a <i>c</i> -hadron decay, which itself is from the decay of a <i>b</i> -hadron
fromC		From the decay of a <i>c</i> -hadron
OtherSe	econdary	From other secondary interactions and decays

Track origin classification labels

GN1/GN2 input features

GN1 vs GN2 differences

Source: FTAG-2023-01

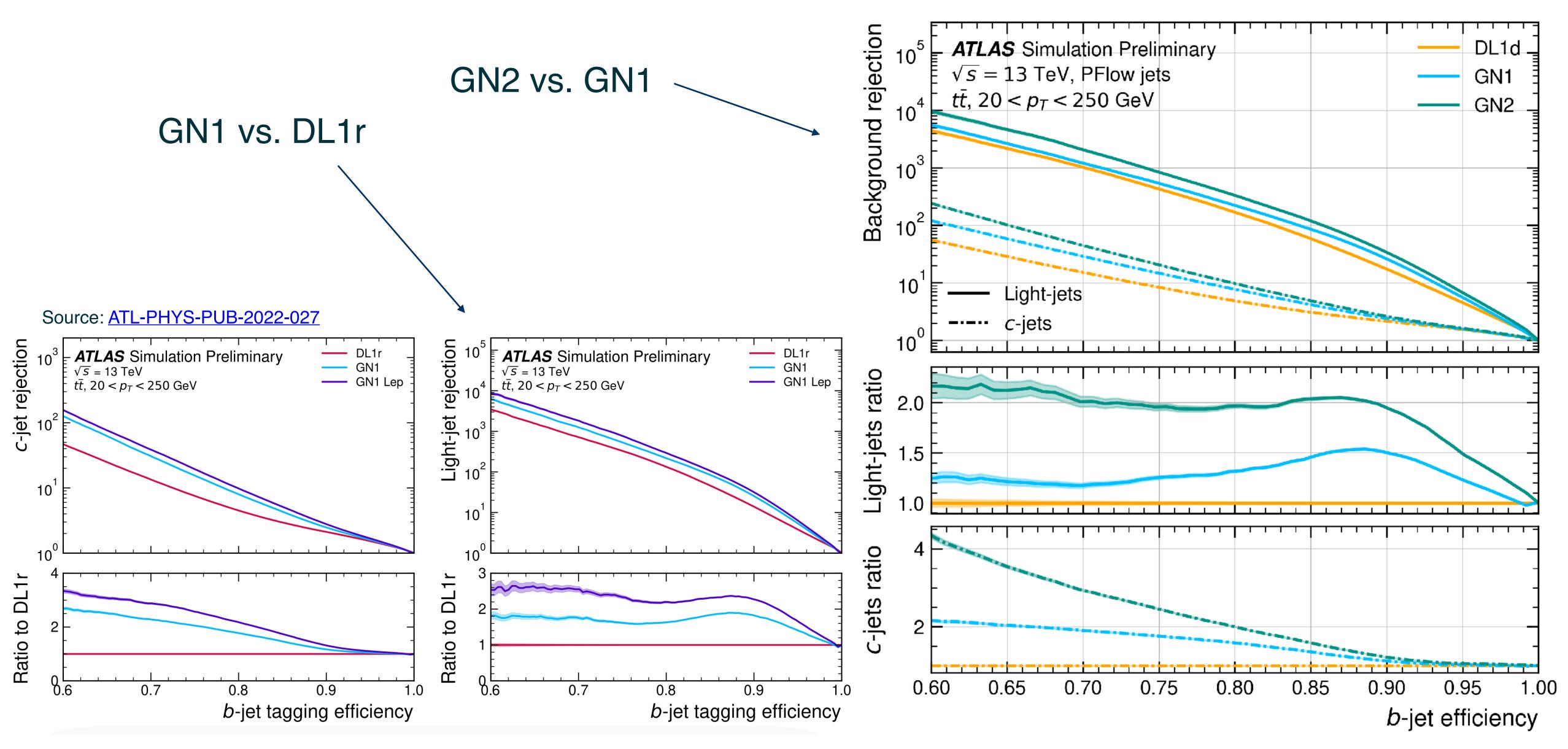
	Туре	Name	GN1	GN2
1 Lep)	Hyperparameter	Trainable parameters	0.8M	$1.5\mathrm{M}$
	Hyperparameter	Learning rate	1e-3	OneCycle LRS (max LR 4ϵ
	Hyperparameter	GNN Layers	3	6
	Hyperparameter	Attention Heads	2	8
	Hyperparameter	Embed. dim	128	192
	Architectural	Attention type	GATv2	${\it ScaledDotProduct}$
	Architectural	Dense update	No	Yes $(\dim 256)$
	Architectural	Separate value projection	No	Yes
	Architectural	LayerNorm + Dropout	No	Yes
	Inputs	Num. training jets	30M	$192\mathrm{M}$



4e - 5)

2 - 14



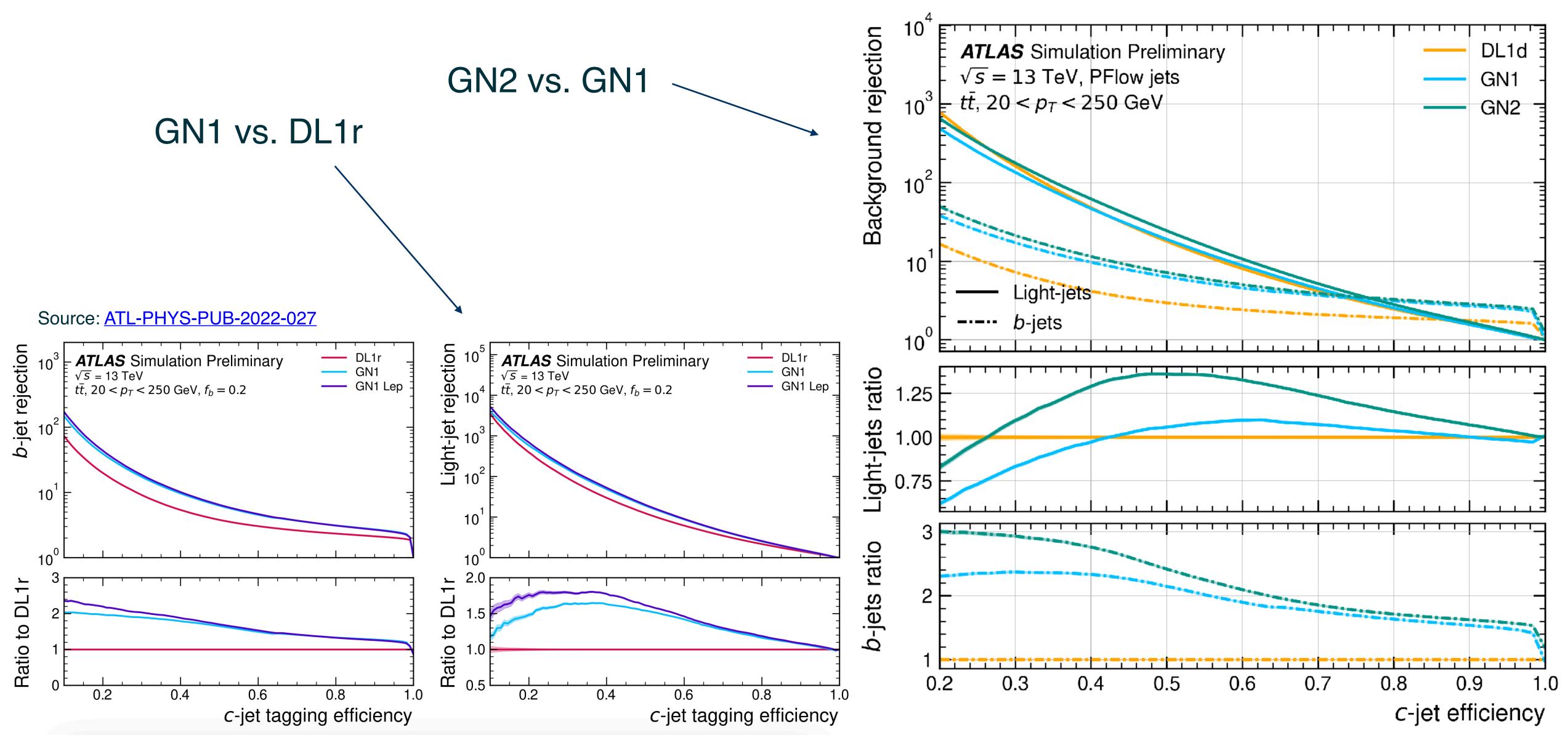




Source: FTAG-2023-01









Source: FTAG-2023-01



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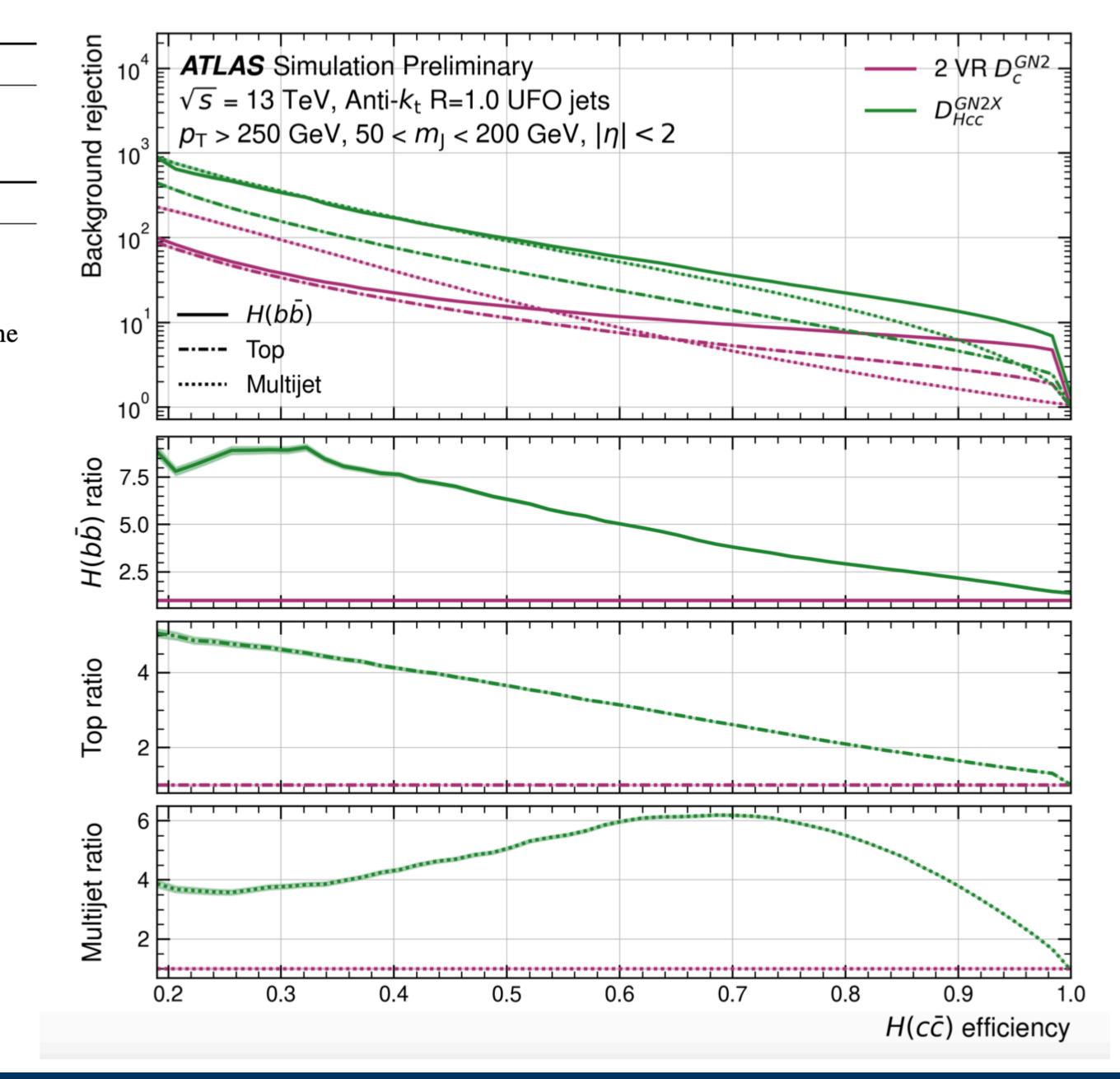
GN2X inputs and H(cc)-tagging performance

Jet Input	Description
<i>p</i> _T	Large- <i>R</i> jet transverse momentum
η	Signed large-R jet pseudorapidity
mass	Large-R jet mass
Track Input	Description
q/p	Track charge divided by momentum (measure of curvature)
$\mathrm{d}\eta$	Pseudorapidity of track relative to the large-R jet η
$\mathrm{d}\phi$	Azimuthal angle of the track, relative to the large-R jet ϕ
d_0	Closest distance from track to primary vertex (PV) in the transverse plane
$z_0 \sin \theta$	Closest distance from track to PV in the longitudinal plane
$\sigma(q/p)$	Uncertainty on q/p
$\sigma(heta)$	Uncertainty on track polar angle θ
$\sigma(\phi)$	Uncertainty on track azimuthal angle ϕ
$s(d_0)$	Lifetime signed transverse IP significance
$s(z_0\sin\theta)$	Lifetime signed longitudinal IP significance
nPixHits	Number of pixel hits
nSCTHits	Number of SCT hits
nIBLHits	Number of IBL hits
nBLHits	Number of B-layer hits
nIBLShared	Number of shared IBL hits
nIBLSplit	Number of split IBL hits
nPixShared	Number of shared pixel hits
nPixSplit	Number of split pixel hits
nSCTShared	Number of shared SCT hits

Source: ATL-PHYS-PUB-2023-021

GN2X input features









- loss (maximize f, minimize g)

$$\mathcal{L}(f,g) = \frac{1}{N_{\text{data}}} \sum_{\vec{q}, p_{\text{T}} \sim p_{\text{data}}} f(\vec{q}, p_{\text{T}}) + \frac{1}{N_{\text{sim}}} \sum_{\vec{q}, p_{\text{T}} \sim p'_{\text{sim}}} \vec{q} \cdot \vec{\nabla} g(\vec{q}, p_{\text{T}}) - f(\vec{\nabla} g(\vec{q}, p_{\text{T}}), p_{\text{T}})$$

- $p'_{sim}(\vec{q}, p_{T}) \equiv (f_{sig}(p_{T})p_{sig}(\vec{q}|p_{T}) + (1 f_{sig}(p_{T}))p_{bkg}(\vec{q}|p_{T})) p_{data}(p_{T})$
- normalizing flows)

Optimal transport calibration method



Optimal transport maps **derived for** $q_i = \text{logit } p_i$ where $\text{logit } p_i = \log \frac{p_i}{1 - p_i}$ - Defined by $\hat{T}_{p_T} = \arg \inf_{T_{p_T}} \int_{\vec{q} \in \vec{Q}} c(\vec{q}, T_{p_T} \vec{q}) p_{\text{sim}}(\vec{q}|p_T) d\vec{q}$; s.t. $(T_{p_T})_{\#} p_{\text{sim}}(\vec{q}|p_T) \approx p_{\text{data}}(\vec{q}|p_T)$ with distance metric $c^2(\vec{x}, \vec{y}) = (\vec{x} - \vec{y})^2$ (unique solution)

Partially Input Convex Neural Networks (PICNNs) used to approximate optimal mapping with

- Input data for simulation sampled from **pT corrected distribution** (equal in data and MC)

- Requires understanding of **b-jet fractions** (i.e. $f_{sig}(p_T)$ derived via neural density estimation) and flavor probability distribution components (i.e. $p_{sig}(\vec{q}|p_T)$ derived via conditional

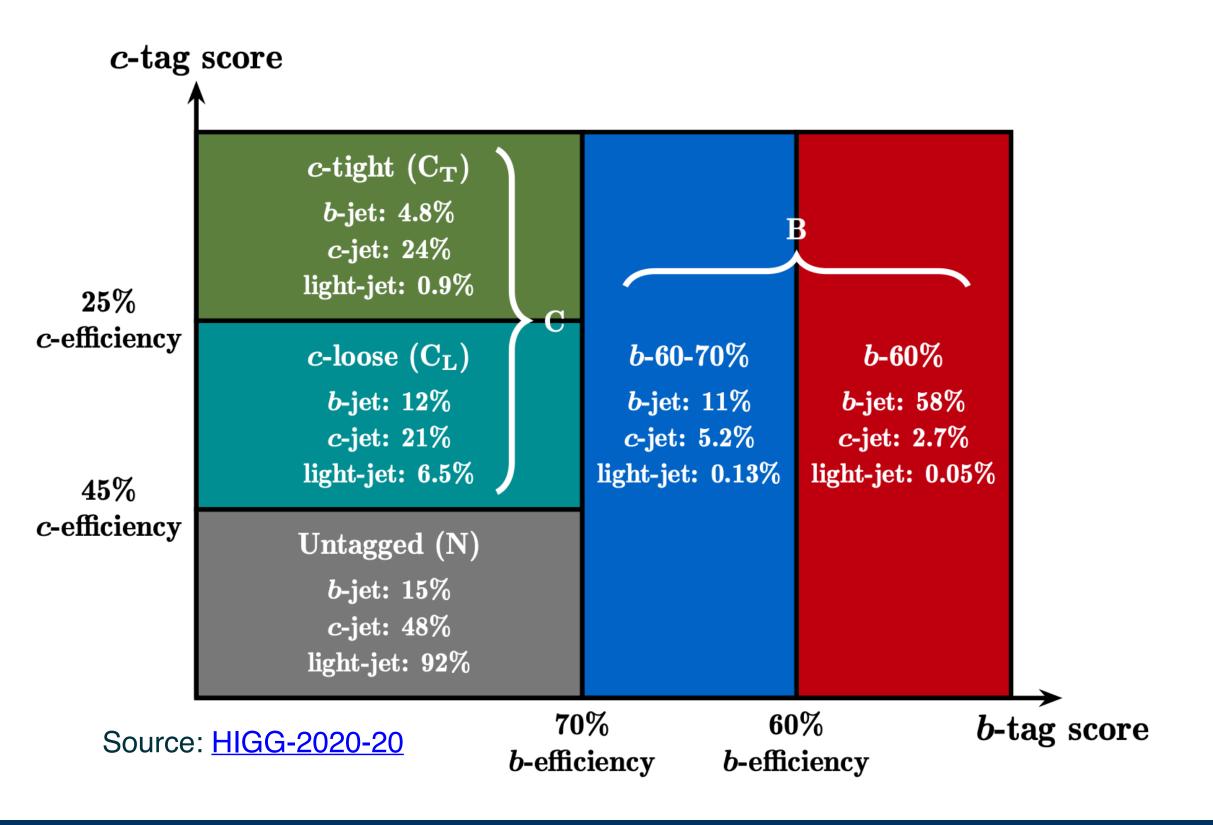


2 - 18





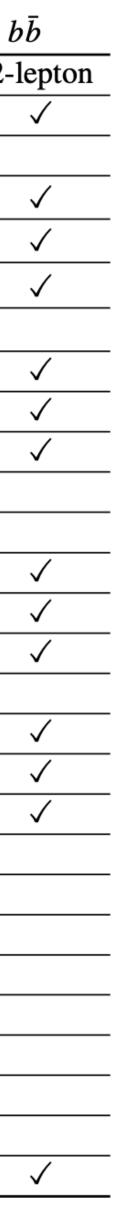
- **3 sets of BDTs**: BTD_{VH}, BDT_{VZ}, BDT_{CRLow}
 - BDT for VZ used in cross check analysis measuring VZ(bb/cc)
 - CRLow BDT applied in low- ΔR CR to separate V+jets from Top background



$V(\rightarrow l\bar{l}) H(\rightarrow b\bar{b}/c\bar{c})$ MVA and FTAG



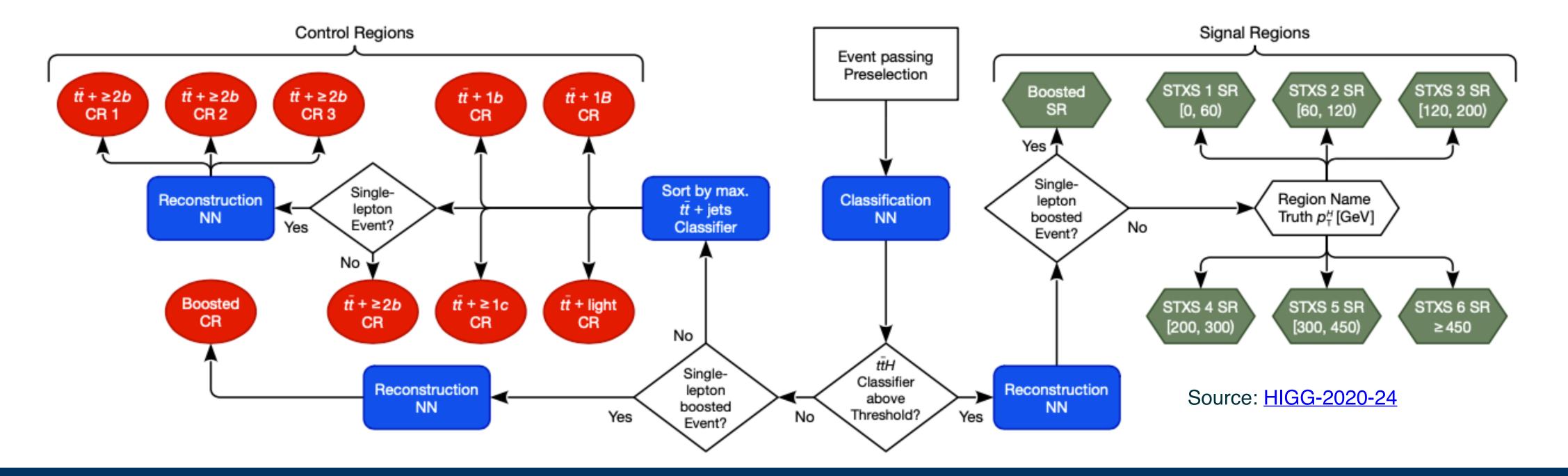
	Resolve	d <i>VH</i> , <i>H</i> –	$\rightarrow b\bar{b}, c\bar{c}$	Boost	ed VH, H	$\rightarrow b\bar{b}$
Variable	0-lepton	1-lepton	2-lepton	0-lepton	1-lepton	2-le
m _H	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	``
$m_{j_1 j_2 j_3}$	\checkmark	\checkmark	\checkmark			
$p_{\mathrm{T}}^{j_1}$	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	``
$p_{\mathrm{T}}^{j_2}$	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	``
$p_{\mathrm{T}}^{\mathbf{j}_3}$				\checkmark	\checkmark	``
$\sum p_{\mathrm{T}}^{j_i}, i > 2$	\checkmark	\checkmark	\checkmark			
$\operatorname{bin}_{D_{\mathrm{DL1r}}}(j_1)$	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	``
$bin_{D_{\text{DL1r}}}(j_2)$	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	``
p_{T}^{V}	$\equiv E_{\rm T}^{\rm miss}$	\checkmark	\checkmark	$\equiv E_{\rm T}^{\rm miss}$	\checkmark	``
$E_{\mathrm{T}}^{\mathrm{miss}}$	\checkmark	\checkmark		\checkmark	\checkmark	
$E_{\rm T}^{\rm miss}/\sqrt{S_{\rm T}}$			\checkmark			
$ \Delta \phi(V, H) $	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	``
$ \Delta y(\boldsymbol{V}, \boldsymbol{H}) $		\checkmark	\checkmark		\checkmark	``
$\Delta R(\boldsymbol{j_1}, \boldsymbol{j_2})$	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	``
$\min[\Delta R(j_i, j_1 \text{ or } j_2)], i > 2$	\checkmark	\checkmark				
N(track-jets in J)				\checkmark	\checkmark	``
N(add. small-R jets)				\checkmark	\checkmark	``
colour ring				\checkmark	\checkmark	``
$ \Delta\eta(\boldsymbol{j_1}, \boldsymbol{j_2}) $	\checkmark					
$H_{\rm T}$ + $E_{\rm T}^{\rm miss}$	\checkmark					
m_{T}^W		\checkmark				
m _{top}		\checkmark				
$\min[\Delta \phi(\ell, j_1 \text{ or } j_2)]$		\checkmark				
p_{T}^{ℓ}					\checkmark	
$(p_{\rm T}^{\ell} - E_{\rm T}^{\rm miss})/p_{\rm T}^{V}$					\checkmark	
$m_{\ell\ell}$			\checkmark			
$\cos \theta^*(\ell^-, V)$			\checkmark			`







- hadron), $t\bar{t} + \geq 1c$ (no b-jets, but at least 1 c-jet) and $t\bar{t} + light$ (all others)
- features (p_x, p_y, p_z, p_T, E, m, η , ϕ , sin(ϕ), cos(ϕ))
- Also includes DL1r score for jets and charge plus electron/muon index for leptons





• $t\bar{t} + jets$ background is split into 5 categories based on jets not from $t\bar{t}$ decay: $t\bar{t} + \geq 2b$ (2) or more b-jets), $t\bar{t} + 1B$ (1 b-jet with 2 matched hadrons), $t\bar{t} + 1b$ (1 b-jet with 1 matched

Transformer model is trained with jet, electron, muon and missing transverse momentum









DNN trained for density ratio estimation via loss function given by

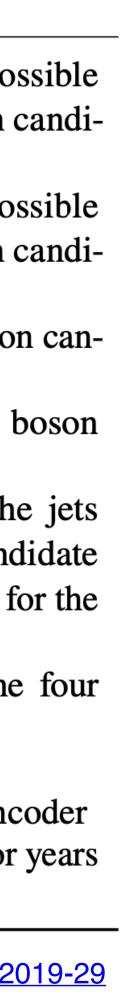
$$\mathcal{L}(w(\vec{x})) = \int d\vec{x} \left[\sqrt{w(\vec{x})} p_{2b}(\vec{x}) + \frac{1}{\sqrt{w(\vec{x})}} p_{4b}(\vec{x}) \right]$$

- Minimized by ratio of PDFs of 4b and 2b samples $w(\vec{x}) = \frac{p_{4b}(\vec{x})}{p_{2b}(\vec{x})}$ 2. 3
- Separate trainings for ggF and VBF (+ each data-taking year in ggF)
- Trainings are performed before splitting events by $|\Delta \eta_{HH}|$ and X_{HH}
 - Variables found insensitive to kinematic reweighting



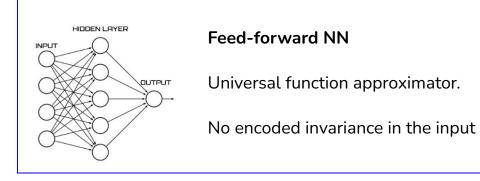
<u>Neural network inputs</u>

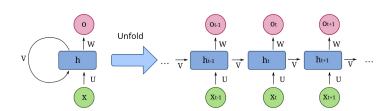
	•
ggF	VBF
1. $log(p_T)$ of the 2 nd leading Higgs boson candidate jet	1. Maximum dijet mass from the pos pairings of the four Higgs boson of
2. $\log(p_T)$ of the 4 th leading Higgs boson candidate jet	date jets 2. Minimum dijet mass from the pos
3. $log(\Delta R)$ between the closest two Higgs boson candidate jets	pairings of the four Higgs boson of date jets
4. $log(\Delta R)$ between the other two Higgs boson candidate jets	3. Energy of the leading Higgs boson didate
5. Average absolute η value of the Higgs boson candidate jets	4. Energy of the subleading Higgs b candidate
 6. log(p_T) of the di-Higgs system 7. Δ<i>R</i> between the two Higgs boson candidates 	5. Second-smallest ΔR between the in the leading Higgs boson cand (from the three possible pairings for leading Higgs condidate)
8. $\Delta \phi$ between jets in the leading Higgs boson candidate	$\begin{array}{c c} & \text{leading Higgs candidate} \\ & 6. & \text{Average absolute } \eta \text{ value of the} \end{array}$
9. $\Delta \phi$ between jets in the subleading Higgs boson candidate	Higgs boson candidate jets 7. $log(X_{Wt})$
10. $log(X_{Wt})$ 11. Number of jets in the event 12. Trigger class index as one-hot encoder	 8. Trigger class index as one-hot enc 9. Year index as one-hot encoder (for inclusive training)
	Source: HDBS-20



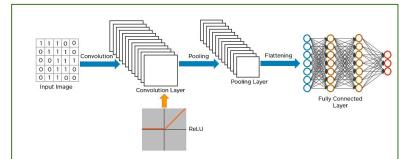


ML architecture: depends on the structure of the data and the target task





Recurrent NN: used for sequences, can encode casualty, Inefficient for long sequences



ETH zürich

Convolutional NN: used for images, inefficient for sparse data. Encodes input invariance by translation

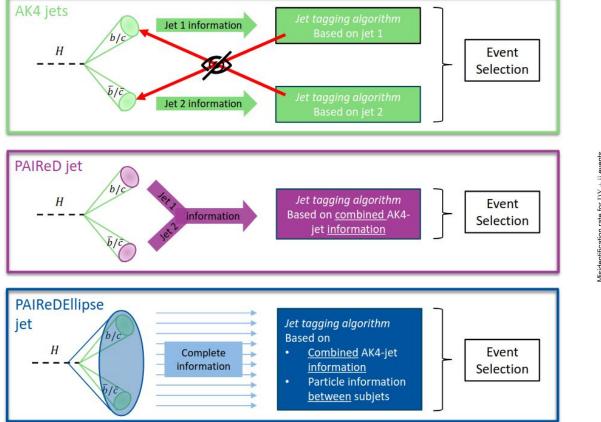
Have a look at the Living Review of Machine Learning for Particle Physics for an updated list of ML in HEP applications

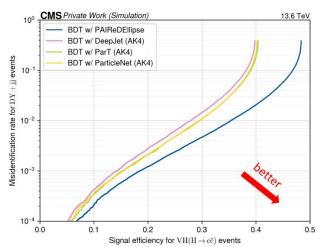
PAIRed-jet classifier

ETH zürich

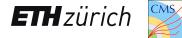


[arXiv:2311.11011 [hep-ex]; accepted by JHEP]





Generative ML for MEM



Computing the Matrix Element Method for ttH(bb) using Normalizing Flows and transformers for optimal sampling and *P*(*Reco*/*Gen*) transfer functions

