

# Yukawa- and Higgs self-coupling corrections to di-Higgs production

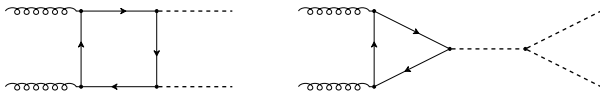
Higgs 2024, based on 2407.04653

G. Heinrich, S. Jones, M. Kerner, T. Stone, [A. Vestner](#) | November 5th, 2024

ITP - KIT, IPPP

# Why calculate higher orders to $gg \rightarrow HH$

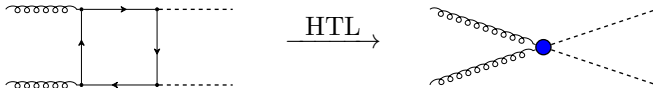
- LO is at one loop level
- Sensitivity to Higgs selfcoupling  $\lambda$



- Already calculated 1988 (Glover and van der Bij 1988)
- Match expected experimental uncertainty at (HL-)LHC, corrections impact the extracted constraints
- Sizeable effects on differential cross sections
- First full  $m_t$  dependent NLO QCD result from 2016 (Borowka, Greiner, et al. 2016), (Baglio, Campanario, et al. 2019)

- Approximation of higher orders (restricted to certain kinematic regions) with

- heavy top limit, (De Florian and Mazzitelli 2018; Florian, Grazzini, et al. 2016; Grigo, Hoff, and Steinhauser 2015)



- expansions in kinematic parameters (Davies, Herren, Mishima, and Steinhauser 2022)
- On the way to higher orders numerous combinations of these techniques are used, e.g. (Bagnaschi, Degrossi, and Gröber 2023; Grazzini, Heinrich, et al. 2018)
  - N<sup>3</sup>LO (Chen, Li, Shao, and Wang 2020a,b)
  - N<sup>3</sup>LO + N<sup>3</sup>LL (Ajath and Shao 2023)
- Reaching an uncertainty of  $\mathcal{O}(\%)$

- EW corrections are at a similar order of magnitude and distort the distributions
- Les Houches Wishlist > 2015

Wishlist	known $d\sigma$	desired $d\sigma$
2016	$N^2\text{LO}_{\text{HTL}}, \text{NLO}_{\text{QCD}}$	$N^2\text{LO}_{\text{HTL}} + \text{NLO}_{\text{QCD}} + \text{NLO}_{\text{EW}}$
2021	$N^3\text{LO}_{\text{HTL}} \otimes \text{NLO}_{\text{QCD}}$	$\text{NLO}_{\text{EW}}$

- Massive internal bosons
- Similar approximative methods can be employed, e.g. (Davies, Schönwald, Steinhauser, and Zhang 2023)
- Several partial results (Borowka, Duhr, et al. 2019; Davies, Mishima, et al. 2022; Mühlleitner, Schlenk, and Spira 2022)
- First full NLO EW result from 2023 (Bi, Huang, et al. 2023)

# Our higher order calculation toolchain

- 1 Produce contributing diagrams (QGRAF)
- 2 Project onto form factors (Mathematica)
- 3 Reduce the number of integrals (kira, Reduze, Ratracer)
- 4 Integrate the remaining master integrals (pySecDec)
- 5 Perform the Renormalization (blood, sweat and tears)
- 6 Crosschecks (DiffExp)
- 7 Put everything back together

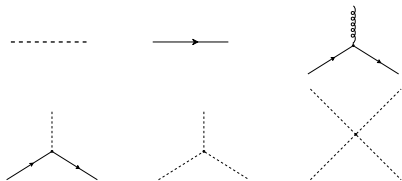
# The bare Lagrangian

- Gaugeless limit  $\Rightarrow$  Weak bosons decouple
- Unitary gauge  $\Rightarrow$  Goldstone bosons decouple

$$\mathcal{L} = -\frac{1}{4}G_{0,\mu\nu}G_0^{\mu\nu} + \frac{1}{2}(\partial_\mu H_0)^\dagger(\partial^\mu H_0) - \frac{m_{H,0}^2}{2}H_0^2 - \frac{m_{H,0}^2}{2v_0}H_0^3 - \frac{m_{H,0}^2}{8v_0^2}H_0^4$$

$$+ i\bar{t}_0\not{D}t_0 - m_{t,0}\bar{t}_0t_0 - \frac{m_{t,0}}{v_0}H_0\bar{t}_0t_0 + \text{constant}$$

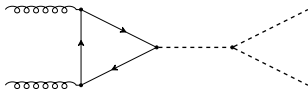
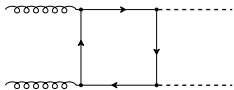
Yields Feynman rules for:



Reparametrized in terms of  $m_{H,0}$ ,  $m_{t,0}$  and  $v_0$ .

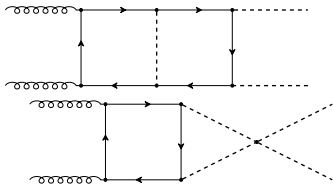
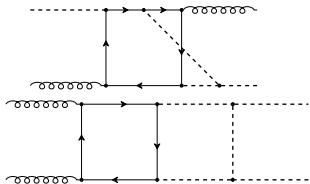
# Contributing Diagrams

LO



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NLO (examples)



Automated by the tool QGRAF. (Nogueira 1993)

# Splitting and Projecting

Each diagram is

- projected onto form factors  $F_i$  for two different tensor structures,
- sorted into classes, according to the occurring couplings

$$g_{t,0} \equiv \frac{m_{t,0}}{v_0} \quad g_{3,0} \equiv \frac{3m_{H,0}^2}{v_0} \quad g_{4,0} \equiv \frac{3m_{H,0}^2}{v_0^2},$$

- tagged as 1PI or 1PR contribution.

$$F_i|_{\text{NLO}} = g_{S,0}^2 \left( g_{3,0} g_{4,0} g_{t,0} F_{i,g_3 g_4 g_t} + g_{3,0}^3 g_{t,0} F_{i,g_3^3 g_t} + g_{4,0} g_{t,0}^2 F_{i,g_4 g_t^2} \right. \\ \left. + g_{3,0}^2 g_{t,0}^2 F_{i,g_3^2 g_t^2} + g_{3,0} g_{t,0}^3 F_{i,g_3 g_t^3} + g_{t,0}^4 F_{i,g_t^4} \right)$$

Type	$g_3 g_4 g_t$	$g_3^3 g_t$	$g_4 g_t^2$	$g_3^2 g_t^2$	$g_3 g_t^3$	$g_t^4$
1PI	0	0	3	6	24	60
1PR	12	6	1	6	24	26
Total	12	6	4	12	48	86



- Use integration by parts to relate different integrals to each other:

$$\int \prod_{\ell=1}^L d^D k_\ell \frac{d}{dk_i^\mu} [\eta^\mu \mathcal{I}(\vec{\eta})] = 0$$

- Choose a suitable basis of master integrals M.I.:
  - prefer dots over numerators
  - search for finite coefficients for top-level M.I. from non-planar sectors
  - avoid poles on diagonal elements of differential equation system
- Have obtained a fully symbolic reduction to M.I.s retaining dependence on  $s$ ,  $t$ ,  $m_t$  and  $m_H$  using `kira` with `ratracer` (Klappert, Lange, Maierhöfer, and Usovitsch 2021; Magerya 2022)

- 492 remaining M.I.s
- $d$ -factorizing integrals, i.e. dimensionality  $d$  and kinematics dependent parts are separated
- Still, too many mass scales to solve analytically
- Numerical evaluation using pySecDec (Heinrich, Jones, et al. 2024)
- Spurious poles at  $\mathcal{O}(\epsilon^{-4}, \epsilon^{-3}, \epsilon^{-2})$



- At higher orders the vev gets shifted.
- Fleischer-Jegerlehner tadpole scheme: (Fleischer and Jegerlehner 1981)

$$H + v \rightarrow H + v + \Delta v$$

- Require the tadpole diagrams  $T_H$  to vanish also at NLO through the tadpole counterterm

$$\delta T = -T_H$$

- Identify  $\delta T = -\Delta v m_H^2$
- This corresponds to a redistribution of tadpole contributions.

$$\mathcal{M}_{\text{ren}} = \mathcal{M}^{(0)}(m_t, m_H^2, v) + \mathcal{M}_{\delta X}^{(1)}(m_t, m_H^2, v) + \mathcal{M}^{(1)}(m_t, m_H^2, v) + \mathcal{O}(\delta X^2)$$

Introduce CTs:

$$H_0 = \sqrt{Z_H} H = \sqrt{1 + \delta_H} H$$

$$t_0 = \sqrt{Z_t} t = \sqrt{1 + \delta_t} t$$

$$m_{H,0}^2 = m_H^2 (1 + \delta m_H^2)$$

$$m_{t,0} = m_t (1 + \delta m_t)$$

$$v_0 + \Delta v = v (1 + \delta_v) + \Delta v$$



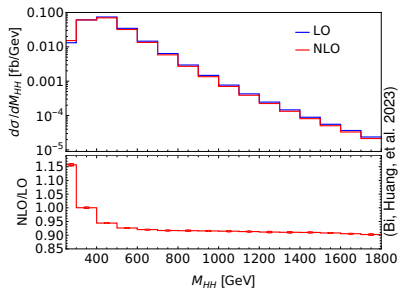
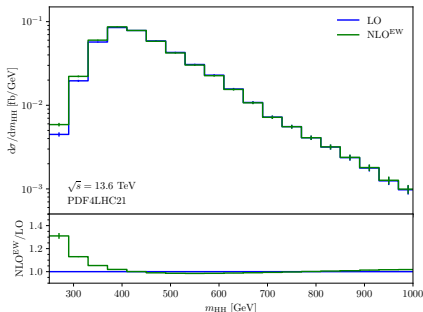
$$= -i3 \frac{m_H^2}{v} \left( \delta m_H^2 + \frac{3}{2} \delta_H - \delta_v - \frac{\delta T}{v m_H^2} \right)$$

etc.

- $\delta_H, \delta_t, \delta m_H^2, \delta m_t$  fixed through on-shell renormalization conditions
- $\delta_v$  fixed in  $G_\mu$  scheme according to (Biekötter, Pecjak, Scott, and Smith 2023)

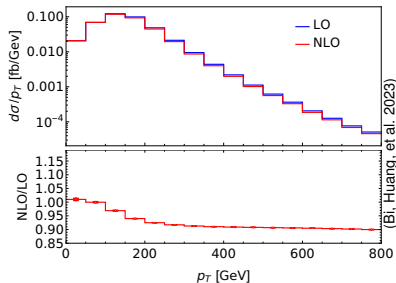
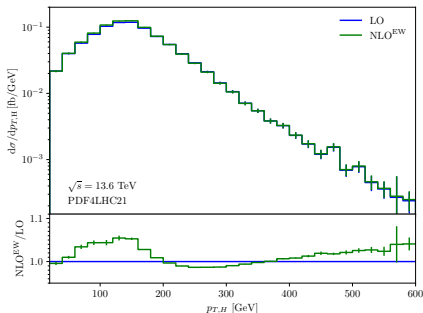
# The Cross Section

Corrections	Yukawa			Full EW (Bi, Huang, et al. 2023)
$\sqrt{s}$	13 TeV	13.6 TeV	14 TeV	14 TeV
LO [fb]	16.45	18.26	19.52	19.96
NLO <sup>EW</sup> [fb]	16.69	18.52	19.79	19.12
NLO <sup>EW</sup> /LO	1.01	1.01	1.01	0.958



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→ Considerable changes after including vector bosons!

# Conclusion

Where we are:

- Achieved fully symbolic reduction for the gaugeless sector
- Crosschecked with (Davies, Schönwald, Steihauser, and Zhang 2024)
- Found  $K = 1.01$
- Observations for invariant Higgs pair mass and transverse momentum distributions of the cross section
  - Quite large enhancement in low  $m_{HH}$  region
  - No Sudakov logs  $\Rightarrow$  tail of distributions only slightly changed
  - Dominant contributions from vector bosons

Where to go:

- Include the full EW corrections and cross-check the result of (Bi, Huang, et al. 2023)
- Investigate the effects of the bottom quark
- Implement an EFT framework

# Formfactors

Separate the matrix element into tensor structures and Form Factors

$$\mathcal{M}^{\mu\nu} = F_1 T_1^{\mu\nu} + F_2 T_2^{\mu\nu}$$

Form factors can be obtained by using projectors

$$\mathcal{P}_i^{\mu\nu} T_{j,\mu\nu} = \delta_{ij}$$

$$T_1^{\mu\nu} = g^{\mu\nu} - \frac{p_1^\nu p_2^\mu}{p_1 \cdot p_2}$$

$$T_2^{\mu\nu} = g^{\mu\nu} + \frac{m_H^2 p_1^\nu p_2^\mu}{p_T^2 p_1 \cdot p_2} - \frac{2p_1 \cdot p_3 p_2^\mu p_3^\nu}{p_T^2 p_1 \cdot p_2} - \frac{2p_2 \cdot p_3 p_1^\nu p_3^\mu}{p_T^2 p_1 \cdot p_2} + \frac{2p_3^\mu p_3^\nu}{p_T^2}$$

with

$$p_T = \sqrt{\frac{ut - m_H^4}{s}}$$



# Deriving the Tensor structure

General structure:

$$\begin{aligned}\mathcal{M}^{\mu\nu} = & a_{00}g^{\mu\nu} + a_{21}p_2^\mu p_1^\nu + a_{31}p_3^\mu p_1^\nu + a_{23}p_2^\mu p_3^\nu + a_{33}p_3^\mu p_3^\nu \\ & + a_{11}p_1^\mu p_1^\nu + a_{22}p_2^\mu p_2^\nu + a_{12}p_1^\mu p_2^\nu + a_{13}p_1^\mu p_3^\nu + a_{32}p_3^\mu p_2^\nu\end{aligned}$$

Further constraints from Ward identities:

$$\epsilon_{1,\mu}p_1^\mu = 0 \quad \epsilon_{2,\nu}p_2^\nu = 0$$

# Basic example of Sector Decomposition

$$\mathfrak{I} = \int_0^1 dx \int_0^1 dy x^{-1-a\epsilon} y^{-b\epsilon} (x + (1-x)y)^{-1}$$

Diverging for  $x \rightarrow 0$  and  $y \rightarrow 0$

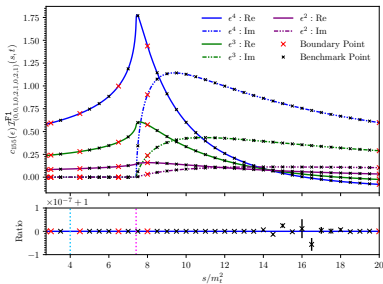
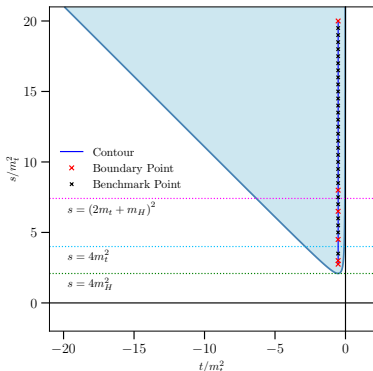
$$\mathfrak{I} = \int_0^1 dx \int_0^1 dy x^{-1-a\epsilon} y^{-b\epsilon} (x + (1-x)y)^{-1} [\Theta(x-y) + \Theta(y-x)]$$

Variable transformation  $y = xt$  and  $x = yt$

$$\begin{aligned} \mathfrak{I} &= \int_0^1 \frac{dx}{x^{1+(a+b)\epsilon}} \int_0^1 \frac{dt}{t^{b\epsilon} (1 + (1-x)t)} \\ &+ \int_0^1 \frac{dx}{y^{1+(a+b)\epsilon}} \int_0^1 \frac{dt}{t^{1+a\epsilon} (1 + (1-y)t)} \end{aligned}$$

Both limits  $x \rightarrow 0$  and  $y \rightarrow 0$  are independent


# Crosscheck with DiffExp




- Run contours in DiffExp between boundary points
- Check pySecDec vs DiffExp for benchmark points

# On-Shell Renormalization


$$0 = \left[ \Sigma_i(\hat{p}) \right]_{\not{p}=m_i} \qquad 0 = \left[ \frac{d}{d\not{p}} \Sigma_i(\not{p}) \right]_{\not{p}=m_i}$$




$$= -i \left[ (m_t - \not{p})\delta_t + m_t\delta m_t - \frac{m_t}{vm_H^2}\delta T \right]$$




$$= -i \left[ (m_H^2 - p^2)\delta_H + m_H^2\delta m_H^2 - 3\frac{\delta T}{v} \right]$$



$$= -i\frac{m_t}{v} \left( \delta m_t + \frac{\delta_H}{2} + \delta_t - \delta_v \right)$$



$$= -i3\frac{m_H^2}{v} \left( \delta m_H^2 + \frac{3}{2}\delta_H - \delta_v - \frac{\delta T}{vm_H^2} \right)$$



$$= -i3\frac{m_H^2}{v^2} (\delta m_H^2 + 2\delta_H - 2\delta_v)$$

# Tadpole Renormalization I



- At higher orders the vev gets shifted.
- Fleischer-Jegerlehner tadpole scheme: (Fleischer and Jegerlehner 1981)

$$H + v \rightarrow H + v + \Delta v$$

- Require the tadpole diagrams  $T_H$  to vanish also at NLO through the tadpole counterterm

$$\delta T = -T_H$$

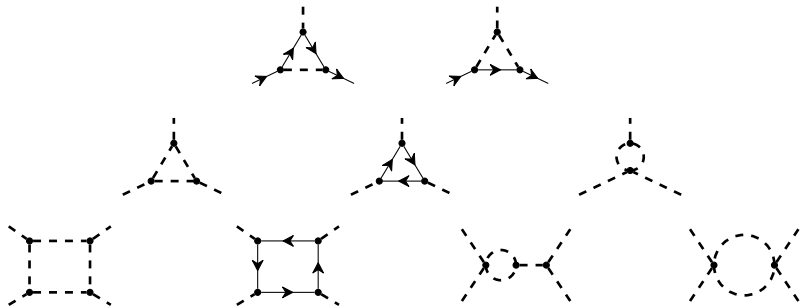
- Identify  $\delta T = -\Delta v m_H^2$
- This corresponds to a **redistribution of tadpole contributions**.

# Tadpole Renormalization II

$$\begin{aligned}
 \mathcal{L}_0 &= \frac{1}{2}(\partial_\mu H_0)^\dagger(\partial^\mu H_0) + \frac{\mu_0^2}{2}(v_0 + H_0)^2 + \frac{\lambda}{16}(v_0 + H_0)^4 \\
 &\quad + i\bar{t}_0 \not{D} t_0 - y_{t,0} \frac{v_0 + H_0}{\sqrt{2}} \bar{t}_0 t_0 - \frac{1}{4} \mathcal{G}_{0,\mu\nu} \mathcal{G}_0^{\mu\nu} \\
 &\rightarrow \frac{1}{2}(\partial_\mu H_0)^\dagger(\partial^\mu H_0) + \frac{\mu_0^2}{2}(v_0 + \Delta v + H_0)^2 + \frac{\lambda_0}{16}(v_0 + \Delta v + H_0)^4 \\
 &\quad + i\bar{t}_0 \not{D} t_0 - y_{t,0} \frac{v_0 + \Delta v + H_0}{\sqrt{2}} \bar{t}_0 t_0 - \frac{1}{4} \mathcal{G}_{0,\mu\nu} \mathcal{G}_0^{\mu\nu} \\
 &= \frac{1}{2}(\partial_\mu H_0)^\dagger(\partial^\mu H_0) + H_0 \left( \mu_0^2 v_0 + \frac{\lambda_0 v_0^3}{4} + \Delta v (\mu_0^2 + \frac{3}{4} \lambda_0 v_0^2) \right) \\
 &\quad + H_0^2 \left( \frac{\mu_0^2}{2} + \frac{3v_0^2 \lambda_0}{8} + \frac{3}{4} \lambda_0 v_0 \Delta v \right) + H_0^3 \left( \frac{\lambda_0 v_0}{4} + \Delta v \frac{\lambda_0}{4} \right) + H_0^4 \frac{\lambda_0}{16} \\
 &\quad + i\bar{t}_0 \not{D} t_0 - m_{t,0} \bar{t}_0 t_0 - \frac{m_{t,0}}{v_0} \Delta v \bar{t}_0 t_0 - \frac{m_{t,0}}{v_0} H_0 \bar{t}_0 t_0 - \frac{1}{4} \mathcal{G}_{0,\mu\nu} \mathcal{G}_0^{\mu\nu} + \dots
 \end{aligned}$$

# $\delta_V$ Counterterm

$$\delta_V|_{UV} = -\frac{3m_H^4 + 2m_H^2 m_t^2 N_c - 8m_t^4 N_c}{32\pi^2 m_H^2 v^2 \epsilon}$$



$$\delta_V|_{G_\mu} = \frac{1}{2^D \pi^{D/2}} \frac{1}{2v^2} \left( -\frac{m_H^2}{2} + N_c m_t^2 - 2N_c A_0(m_t^2) - 3A_0(m_H^2) + 8N_c \frac{m_t^2}{m_H^2} A_0(m_t^2) \right)$$