

# Unsupervised tagging of semivisible jets with normalized autoencoders in CMS

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# **ETH** zürich

19/06/2024

CHIPP 2024 annual meeting

- Hidden Valley [arXiv:hep-ph/0604261] with new particles and forces form the dark sector
- Strongly coupled dark sector
  - $\twoheadrightarrow$  New confining SU(N) force, dark QCD, and dark quarks
  - $\rightarrow$  Dark hadronic showers and jets
  - → Experimental signature: semivisible jets (SVJs) [arXiv:1503.00009, arXiv:1707.05326]
- Portal between the standard model (SM) and dark sectors via a mediator particle





### Anomaly detection to search for SVJs



- → Different jet substructure due to double hadronization
- → Experimental signatures of SVJs very model-dependent
- → Large parameter space to cover



The details of the shower in the dark sector depend on many unknown parameters, e.g.:

- Number of colors and flavors in the dark sector
- Masses of the dark hadrons

 $\rightarrow$  Use anomaly detection to identify SVJs as anomalies

### CMS detector

- The CMS detector is composed of different subdetectors allowing to identify and measure the properties of photons, electrons, muons and hadrons
- SM decay products of SM jets and SVJs can be reconstructed, and clustered into jets
- $\rightarrow$  Exploit the different jet substructure of SVJs compared to SM jets to tag them





CMS.

### Backgrounds



#### SVJ experimental signature:

Missing transverse momentum  $(\not\!\!\!E_{\rm T})$  aligned with a jet

### QCD multijet

- Artificial missing transverse energy  $\not\!\!E_{\rm T}$  aligned with jet from jet energy mismeasurement
- Autoencoder-based anomaly detection proved to work well against QCD jets [arXiv:2112.02864]

### $t\bar{t} + jets$

- More challenging for anomaly detection



SM hadrons Stable dark hadrons



• AEs are trained to minimize the reconstruction error (e.g. MSE) between input and output:

$$L(x) = ||g(f(x)) - x||$$

- → Aim: that examples out of the training distribution, i.e. anomalies, have a higher reconstruction error
- → Trained on SM data, AEs can perform signal-agnostic searches for new physics [arXiv:1808.08979, arXiv:1808.08992]
- $\rightarrow$  Will use interchangeably:
  - "training" and "background"
  - "anomaly" and "signal"
  - AE network is a fully connected NN with jet substructure input features (see backup slides 19-21)





## The problem of out-of-distribution (OOD) reconstruction





Working principle of the Wasserstein Normalized Autoencoder



Ensure that the low reconstruction error probability distribution matches that of the training data

• Define a probability distribution  $p_{\theta}$  so that regions with low reco error  $E_{\theta}$  have high probability

$$p_{\theta}(x) = \frac{1}{\Omega_{\theta}} \exp\left(-E_{\theta}(x)\right)$$

- Minimize the distance between the training and  $p_{\theta}$  probability distributions
  - Sample from  $p_{\theta}$  via MCMC  $\rightarrow$  "Negative samples"
  - Wasserstein distance between training and negative samples<sup>1</sup>



<sup>1</sup>First developments on Normalized Autoencoders in arXiv:2105.05735 and arXiv:2206.14225) with different loss function resulting in several failure modes, see backup slides 23-26

### Wasserstein Normalized Autoencoder: Performance

CMS

- Direct (anti-)correlation between Wasserstein distance and AUC!
- Fully signal-agnostic training procedure: training until minimal Wasserstein distance is achieved
- Drastic improvement over standard AEs!







# Epoch 1





# Epoch 40





# Epoch 500



### A more natural representation: graphs



- Reconstructed jets are unordered sets of particles
- Can naturally be represented as graphs!



$$X_{1} \qquad X_{2} \qquad X_{3} \qquad X = (x_{0}, ..., x_{N}) \qquad \rightarrow \text{ Node features}$$

$$X_{1} \qquad X_{2} \qquad X_{3} \qquad X = (x_{0}, ..., x_{N}) \qquad \rightarrow \text{ Node features}$$

$$A = \begin{bmatrix} 1 & \dots & x_{0,N} \\ \vdots & \ddots & \vdots \\ a_{N,0} & \dots & 1 \end{bmatrix} \qquad \rightarrow \text{ Adjacency matrix}$$

а.

### Towards normalized graph autoencoder

- Need to sample from  $p_{\theta}$  in a graph space!
- Can run an MCMC on graphs:

$$X_n = X_{n-1} - \alpha \nabla E_\theta(X_{n-1}, A_{n-1}) + \beta \sigma_X$$

$$A_n = A_{n-1} - \gamma \nabla E_\theta(X_{n-1}, A_{n-1}) + \delta \sigma_A$$



→ Extends normalized autoencoders to graph networks!





- Signal-agnostic searches for new physics in HEP can be implemented by learning a score that depends on the probability density of the SM data
- Standard AEs are prone to out-of-distribution reconstruction because they are free to minimize the reconstruction error outside the training phase space
- Normalized AEs propose a mechanism to ensure that the learned probability distribution matches that of the training data
- Wasserstein Normalized AEs is an improvement over Normalized AEs, based on the Wasserstein distance to minimize the distance between the AE probability distribution and that of the training data
- The Normalized AE paradigm can be extended to graph networks



# Backup



# Analysis

# Normalized autoencoder (theory)

# • Normalized autoencoder (in practice)

- Dark quarks hadronize in the dark sector
- A fraction of dark hadrons promptly decays to SM quarks which hadronize in the SM sector
- $\bullet$  Remaining dark hadrons are stable and invisible  $\implies$  DM candidates
- → Production of semivisible jets (SVJ) [arXiv:1503.00009, arXiv:1707.05326]
- $\rightarrow$  Different jet substructure due to double hadronization



SM hadrons Stable dark hadrons





### *t*-channel production of SVJ



3 production mechanisms:

q

q

- Direct production: Production of dark quarks without resonance
- Associated production: Production of the mediator associated with a dark quark

 $y_D$ 

 $u_{L}$ 

(a) Direct production

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• Pair production: Production of a pair of mediators



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• Direct production



• Associated production



• Pair production



sull is the mediator  $\Phi$ , gv11 is a dark quark

### Model parameters

Model parameters:

- $m_{\Phi}$ : Mass of the mediator
- $m_{\rm D}$ : Mass of the dark hadrons  $(\pi_{\rm D}, \rho_{\rm D})$ 
  - Same for all dark hadrons
- $y_{\rm D}$ : Yukawa coupling between SM and dark quarks



- $r_{inv}$ : Jet invisible fraction
  - Effective parameter in the simulation Branching ratio DM  $\to q\bar{q}$

 $r_{\rm inv} = \left\langle \frac{\text{Number of stable dark hadrons}}{\text{Number of dark hadrons}} \right\rangle$ 



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### Backgrounds



### **SVJ experimental signature**: $\not\!\!E_T$ aligned with jets!

### QCD multijet

- Artificial missing transverse energy  ${\not\!\!E}_{\rm T}$  aligned with jet from jet energy mismeasurement
- Large cross-section

### $t\bar{t} + jets$

- Large jet from boosted t

### Z + jets

### W + jets

- $W \rightarrow l \nu$  with lost/not reconstructed lepton or hadronic decay of  $\tau$
- Genuine  ${\not\!\! E}_{\rm T}$  from neutrino





# Analysis

# • Normalized autoencoder (theory)

# • Normalized autoencoder (in practice)

#### Energy-based models (EMBs)

- CMS
- EBMs are models where the probability is defined through the Boltzmann distribution
- Let  $\theta$  denote the model parameters
- The model probability  $p_{\theta}$  is defined from the energy  $E_{\theta}$

$$p_{\theta}(x) = \frac{1}{\Omega_{\theta}} \exp\left(-E_{\theta}(x)/T\right)$$
(1)

where the normalization constant  $\Omega_{\theta}$  is

$$\Omega_{\theta} = \int \exp\left(-E_{\theta}(x)/T\right) dx \tag{2}$$

• The EBM loss for a training example x is the negative log-likelihood:

$$L_{\theta}(x) = -\log p_{\theta}(x) = E_{\theta}(x)/T + \log \Omega_{\theta}$$
(3)

• The gradient of the EBM loss is thus:

$$\nabla_{\theta} L_{\theta}(x) = \nabla_{\theta} E_{\theta}(x) - \mathbb{E}_{x' \sim p_{\theta}} \left[ \nabla_{\theta} E_{\theta}(x') \right]$$
(4)

 $\bullet\,$  The expectation value over the training dataset, with probability  $p_{\rm data}$  is:

$$\mathbb{E}_{x \sim p_{\text{data}}} \left[ \nabla_{\theta} L_{\theta}(x) \right] = \mathbb{E}_{x \sim p_{\text{data}}} \left[ \nabla_{\theta} E_{\theta}(x) \right] - \mathbb{E}_{x' \sim p_{\theta}} \left[ \nabla_{\theta} E_{\theta}(x') \right]$$
(5)

## Normalized Autoencoder (NAE) paradigm

- Ensure that the low reconstruction error probability distribution matches that of training data
- → Need a way to sample from the low reco error probability, independent of the training dataset
- The network probability distribution  $p_{\theta}$  is constructed from the reco error  $E_{\theta}$  via the Boltzmann distribution<sup>1</sup>:

$$p_{\theta}(x) = \frac{1}{\Omega_{\theta}} \exp\left(-E_{\theta}(x)\right)$$



- Low reco error probability distribution sampled via Langevin Markov Chain Monte Carlo  $(MCMC)^2$  to obtain "negative examples" and compute their reconstruction error  $E_-$
- The positive energy  $E_+$  is the reconstruction error of the training ("positive") examples
- The loss is designed to learn  $p_{\theta} = p_{\text{data}}$ :

$$\mathbb{E}_{x \sim p_{\text{data}}} \left[ L_{\theta}(x) \right] = \mathbb{E}_{x \sim p_{\text{data}}} \left[ E_{\theta}(x) \right] - \mathbb{E}_{x' \sim p_{\theta}} \left[ E_{\theta}(x') \right]$$
positive energy  $E_{\pm}$  negative energy  $E_{\pm}$ 



 $<sup>^1\,\</sup>mathrm{More}$  on Energy Based Models in backup slide 9

<sup>&</sup>lt;sup>2</sup>More on MCMC in backup slide 13



Loss

$$\mathbb{E}_{x \sim p_{\text{data}}} \left[ L_{\theta}(x) \right] = \mathbb{E}_{x \sim p_{\text{data}}} \left[ E_{\theta}(x) \right] - \mathbb{E}_{x' \sim p_{\theta}} \left[ E_{\theta}(x') \right]$$

positive energy  $E_+$  negative energy  $E_-$ 

#### Positive energy

- Simply the reconstruction error over the training dataset
- Take examples from training dataset and compute the reconstruction error!

#### Negative energy

- Reconstruction error of the "negative samples" x' from the probability distribution  $p_{\theta}$
- Need to sample from the model to get the "negative samples"
- $\rightarrow$  Monte Carlo Markov Chain (MCMC) employed

#### MCMC

- Start from an initial point  $x'_0$
- Run n Langevin MCMC steps:

$$\begin{aligned} x_{i+1}' &= x_i' - \lambda_i \nabla_x E_{\theta}(x_i') + \sigma_i \epsilon \qquad \epsilon \sim \mathcal{N}\left(\mathbf{0}, \boldsymbol{I}\right) \\ \text{drift} \quad \text{diffusion} \end{aligned}$$

• Repeat with several points  $x_0^{\prime(j)}$ , the negative samples are the  $x_n^{\prime(j)}$ 

### Wasserstein Normalized Autoencoder (WNAE) paradigm

CMS

- Ensure that the low reconstruction error probability distribution matches that of the training data
- → Need to sample from the low reco error probability distribution, independent from the training dataset
- The network probability distribution  $p_{\theta}$  is constructed from the reco error  $E_{\theta}$  via the Boltzmann distribution<sup>1</sup>:

$$p_{\theta}(x) = \frac{1}{\Omega_{\theta}} \exp\left(-E_{\theta}(x)\right)$$



- $\bullet$ Low reco error probability distribution sampled via Langevin Markov Chain Monte Carlo $(\rm MCMC)^2$ to obtain "negative examples" ^3
- The loss is the Wasserstein distance (a.k.a. Energy Mover's Distance) between negative examples and training examples to learn  $p_{\theta} = p_{\text{data}}$ :

$$L_{\theta}(x) = \inf_{\gamma \in \Pi(\underline{p_{\text{data}}}, p_{\theta})} \mathbb{E}_{(x, x') \sim \gamma}[\|x - x'\|]$$

• The WNAE learns the probability distribution of the training data

 $^{2}$ More on MCMC in backup slide 13

 $<sup>^{1}</sup>$ More on Energy Based Models in backup slide 9

- Let p be a probability distribution on  $\mathbb{R}^d$
- Consider  $x_0$  a random initial set of n points in  $\mathbb{R}^d$
- With the update rule:

$$x_{t+1} = x_t + \lambda \nabla \log (p(x_t)) + \sqrt{2 \cdot \lambda} \cdot \epsilon_t$$

where  $\epsilon_t$  is a sample of n points drawn from a multivariate normal distribution on  $\mathbb{R}^d$ 

- Let  $\rho_t$  denote the probability distribution of  $x_t$
- In the limit  $t \to \infty$ ,  $\rho_t$  approaches a stationary distribution  $\rho_{\infty}$ , and  $\rho_{\infty} = p$







$$x_{i+1}' = x_i' - \lambda \nabla_x E_\theta(x_i') + \sigma \epsilon \qquad \epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

• A theoretically motivated choice<sup>1</sup> for the MCMC hyper-parameters is:

$$2 \cdot \lambda = \sigma^2$$

- The MCMC is run on every batch: in practice, for training in a reasonable amount of time, the MCMC is rather short
- To speed up the convergence of the MCMC, the temperature T is introduced:

$$x'_{i+1} = x'_i - \frac{\lambda}{T} \nabla_x E_{\theta}(x'_i) + \sigma \epsilon \qquad \epsilon \sim \mathcal{N}(\mathbf{0}, I)$$

- Tweaking the gradient step size can be seen as adjusting the temperature T: the strength of the gradient term is increased for T < 1
- The parameter space where  $\sigma$  and T are set independently, with T<1 and  $\lambda=\sigma^2/2$  is in theory a good region



<sup>&</sup>lt;sup>1</sup>For an infinitely long chain, see backup slide 13

### MCMC initialization:

- In theory, MCMC convergence independent on the initial point
- However, in practice with short chain, initialization is crucial

Several commonly used initialization algorithms of the MCMC:

- Contrastive Divergence<sup>1</sup> (CD)
- Persistent CD<sup>2</sup> (PCD)

### $CD^3$

- Initial distribution from training data
- Re-initialization after each parameter update (*i.e.* epoch)

### $PCD^4$

- Random initial distribution for first MCMC
- The model changes only slightly during parameter update
- Thus, for subsequent chains, initialize chain at the state in which it ended for the previous model
- Possibility to randomly re-initialize a small fraction of the samples

<sup>1</sup> Neural Comput 2002; 14 (8)	<sup>3</sup> Illustration in backup	p slide <mark>16</mark>
<sup>2</sup> PCD paper	<sup>4</sup> Illustration in backup	p slide 17
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Example of a failure mode of CD: High Training data probability mode far from training data distribution: distribution is not sampled Step N Initial distribution Step 1 Step 2 Chain i  $-E_{\theta_i}$ . . . Model parameter Initial distribution Step 1 Step 2 Step N update Chain i+1  $-E_{\theta_{i+1}}$ . . .

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# Analysis

# Normalized autoencoder (theory)

# • Normalized autoencoder (in practice)











- Input features used for the training on top jets at pre-selection level
- Leading two jets
- Truth-tagged SVJ only for signals





Input features Using AK8 jets because SVJ are expected to be wide

Jet width	Axis major axis minor
N-pronginess	
Other	$p_{\rm T}^{\rm D},  {\rm EFP1}$ log(softdrop mass)

#### Architecture

Fully connected neural net Hidden layers: 10, 10, 6, 10, 10

#### Number of events

$m_{\Phi}$ [GeV]	1000	1500	2000		3000	4000	OCD	tŦ		
$r_{\rm inv}$	0.3	0.3	0.1	0.5	0.3	0.7	0.3	0.3		
Number of events	23k	25k	23k	18k	16k	11k	14k	14k	83k	23k

#### Number of AK8 jets

Background jets	Leading 2 jets	
Signal jets	Only SVJ in leading 2 jets	

#### Hyper-parameters

Hyper-parameter	Value
Batch size	256
Reconstruction loss	MSE
Activation	ReLU
Output encoder/	Lincor
decoder activation	Linear
Optimizer	Adam
Learning rate	1e-5
Dropout	0.
MCMC	PCD
Sampling phase space	[-3, 3] hypercube

#### Train/validation/test splitting

0.7/0.15/0.15

### Failure modes of NAEs



Observed two failure modes when training a NAE:

- Negative energy difference: the loss function can be < 0
  - $\rightarrow p_{\theta} = p_{\text{data}} \implies L = 0$
  - $\rightarrow L \neq 0 \implies p_{\theta} \neq p_{\text{data}}$  !
  - → Incentive to learn  $p_{\theta} \neq p_{\text{data}}$  as it has lower loss (L < 0) than  $p_{\theta} = p_{\text{data}}$  (L = 0)

#### • Divergence of energies





Modified default loss function, compared to arXiv:2105.05735, to:

- discourage the network to converge to negative energy difference configurations
- prevent the divergence of the energies

$$L = \log\left(\cosh\left(E_{+} - E_{-}\right)\right)$$



- $\rightarrow$  Signal SVJ reconstruction is efficiently suppressed!
- $\rightarrow$  How to define stopping condition in a fully signal-agnostic way?

Wasserstein distance: signal-agnostic metric for optimal performance







- The Wasserstein ditance (a.k.a. Energy Mover's Distance, EMD) between the training and negative samples is a measure of the distance between the background and NN probabilities directly in the input feature space
- Always observing a "collapse": the energy difference stays zero but background and NN probabilities differentiate







#### Illustration before collapse:

- Background (positive) and NN (negative) probability distributions match
- → Low EMD and low energy difference between negative and positive probability distributions
- $\rightarrow$  Anomalies have large reco error

#### Illustration after collapse:

- Large discrepancy between background and NN probability distributions
- → Large EMD but low energy difference between negative and positive probability distributions
- → Anomalies are not distinguishable from background

CMS

- Can visualize negative samples as 1D histograms in the feature space!
- $C_2^{\beta=0.5}$  negative samples distribution is wider and offset after the collapse

