Dynamical Instabilities in the Generalized SU(2) Proca Theory: Challenges for Cosmic Acceleration

# Santiago García-Serna

**GRECO** 

Facultad de Ciencias Naturales y Exactas Universidad del Valle



## Generalized SU(2) Proca Theories

$$
S \equiv \int dx^4 \sqrt{-g} \left( \mathcal{L}_{EH} + \mathcal{L}_{YM} + \sum_{i=1}^2 \chi_i \mathcal{L}_2^i + \sum_{i=3}^7 \frac{\chi_i}{m_P^2} \mathcal{L}_2^i + \sum_{i=1}^6 \frac{\alpha_i}{m_P^2} \mathcal{L}_{4,2}^i + \mathcal{L}_m + \mathcal{L}_r \right)
$$

$$
\mathcal{L}_{EH} \equiv \frac{m_P^2}{2} R, \quad \mathcal{L}_{YM} \equiv -\frac{1}{4} F_{\mu\nu}^a F_{a}^{\mu\nu}, \quad \mathcal{L}_{2}^1 \equiv (B^a \cdot B_a) (B^b \cdot B_b),
$$
\n
$$
\mathcal{L}_{2}^2 \equiv (B^a \cdot B^b) (B_a \cdot B_b), \quad \mathcal{L}_{2}^3 \equiv A_a^{\mu\nu} A^{\rho}{}_{\nu}{}^a B^b_{\mu} B_{\rho b}, \quad \mathcal{L}_{2}^4 \equiv A_a^{\mu\nu} A^{\rho}{}_{\nu}{}^b B_{\mu b} B^a_{\rho},
$$
\n
$$
\mathcal{L}_{2}^5 \equiv A_a^{\mu\nu} A^{\rho}{}_{\nu}{}^b B^a_{\mu} B_{\rho b}, \quad \mathcal{L}_{2}^6 \equiv A_a^{\mu\nu} A^a_{\mu\nu} (B_b \cdot B^b), \quad \mathcal{L}_{2}^7 \equiv A_a^{\mu\nu} A^b_{\mu\nu} (B^a \cdot B_b),
$$
\n
$$
\mathcal{L}_{4,2}^1 \equiv (B_b \cdot B^b) [S^{\mu a}_{\mu} S^{\nu}_{\nu a} - S^{\mu a}_{\nu} S^{\nu}_{\mu a}] + 2 (B_a \cdot B_b) [S^{\mu a}_{\mu} S^{\nu b}_{\nu} - S^{\mu a}_{\nu} S^{\nu b}_{\mu}],
$$
\n
$$
\mathcal{L}_{4,2}^2 \equiv A^a_{\mu\nu} S^{\mu b}_{\sigma} B^{\nu}_{a} B^{\sigma}_{b} - A^a_{\mu\nu} S^{\mu b}_{\sigma} B^{\nu}_{b} B^{\sigma}_{a} + A^a_{\mu\nu} S^{\rho b}_{\rho} B^{\mu}_{a} B^{\nu}_{b},
$$
\n
$$
\mathcal{L}_{4,2}^3 \equiv B^{\mu a} R^{\alpha}{}_{\sigma\rho\mu} B_{\alpha a} B^{\rho b} B^{\sigma}_b + \frac{3}{4} (B_b \cdot B^b) (B^a \cdot B_a) R,
$$
\n
$$
\mathcal{L}_{4,2}^4 \equiv \left[ (B_b \cdot B^b) (B^a \cdot B_a) + 2 (B_a \cdot B_b) (B^a \cdot B^b) \right] R
$$

$$
\alpha_2 = 2\alpha_3,\n\alpha_6 = -20\alpha_1 + 6\alpha_3 - 3\alpha_5,\n\chi_3 = 0,\n\alpha_4 = -2\alpha_1 + \frac{7}{20}\alpha_3,\n\alpha_5 = -\frac{20\alpha_1 - 14\alpha_3}{3},\n\chi_7 = 5\alpha_1 + \alpha_3 - \frac{\chi_4}{2} - 3\chi_6,
$$

### isor perturbations:

nt-Roll Inflation in the Generalized SU(2) Proca Theory

rnica (Santander Industrial U.), L. Gabriel Gomez (Santiago de Chile U.), Andres A. Navarro (Santo Tomas U.), odriguez (Santander Industrial U. and Antonio Narino U.)

We consider the FLRW background  $ds^2 = -dt^2 + a^2(t)\delta_{ij}dx^i dx^j$ , and the configuration for the vector field  $B_{0a}(t) = 0$ ,  $B_{ia}(t) = a(t)\psi(t)\delta_{ia}$  and  $\hat{g} \equiv \sqrt{\tilde{g}^2 - 6\chi_1 - 2\chi_2}$ .

# Considering the tensor perturbations and other simplifications

## Tensor Perturbations

$$
\alpha_2 = 2\alpha_3,
$$
  
\n
$$
\alpha_6 = -20\alpha_1 + 6\alpha_3 - 3\alpha_5,
$$
  
\n
$$
\chi_3 = 0,
$$
  
\n
$$
\alpha_4 = -2\alpha_1 + \frac{7}{20}\alpha_3,
$$
  
\n
$$
\alpha_5 = -\frac{20\alpha_1 - 14\alpha_3}{3},
$$
  
\n
$$
\chi_7 = 5\alpha_1 + \alpha_3 - \frac{\chi_4}{2} - 3\chi_6,
$$

## Useful definitions

$$
\alpha_3 \to \frac{-c_1 + c_2 + 20\alpha_1}{20}, \quad \chi_5 \to \frac{c_1 + 9c_2 - 20\alpha_1}{10}
$$

The Equation of Motion

$$
m_{\rm P}^2 G_{\mu\nu} = T_{\mu\nu}^{(B)} + T_{\mu\nu}^{(m)},
$$

$$
3m_{\rm P}^2H^2 = \rho_B + \rho_m,
$$
  

$$
-2m_{\rm P}^2\dot{H} = p_B + \rho_B + \rho_m,
$$

## Where the density and the pressure are

## The EQAM and the field is

$$
0 = \ddot{\psi} + 3H\dot{\psi} + \psi \left(2H^2 + \dot{H} - 6c_2 \frac{\dot{\psi}^2}{m_P^2}\right) \frac{\chi_4}{m_P^2} \left(\mathcal{L}_2^4 - \frac{\mathcal{L}_2^7}{2}\right) + 2\psi^3 \left[\hat{g}^2 + 3\left(c_1 - 2c_2\right) \frac{H^2}{m_P^2} + \left(c_1 - 4c_2\right) \frac{\dot{H}}{m_P^2}\right] \left[\frac{2 - \frac{20}{3} \mathcal{L}_{4,2}^5 + 5\mathcal{L}_2^7}{3} - 6c_2 \frac{\psi^2}{m_P^2} \left(\ddot{\psi} + 3H\dot{\psi}\right).
$$

$$
\rho_B \equiv (\dot{\psi} + H\psi)^2 \left[ \frac{3}{2} - 9c_2 \frac{\psi^2}{m_P^2} \right] + \frac{3}{2} \hat{g}^2 \psi^4 \n+ 6H(c_1 - c_2) \frac{\psi^3 \dot{\psi}}{m_P^2}, \np_B \equiv (\dot{\psi} + H\psi)^2 \left[ \frac{1}{2} + 3c_2 \frac{\psi^2}{m_P^2} \right] + \frac{1}{2} \hat{g}^2 \psi^4 \n+ 6 \frac{\psi^2}{m_P^2} (c_2 - c_1) \left\{ \dot{\psi}^2 - \psi^2 \left( H^2 + \frac{\dot{H}}{3} \right) + \frac{1}{3} \psi \ddot{\psi} \right\},
$$

## Dynamical system approach

$$
\text{Dynamical variables} \quad x \equiv \frac{\psi}{\sqrt{2}m_{\text{P}}H}, \quad y \equiv \frac{\psi}{\sqrt{2}m_{\text{P}}}, \quad z \equiv \sqrt{\frac{\hat{g}}{2m_{\text{P}}H}}\psi. \quad \hat{g} \equiv \sqrt{\tilde{g}^2 - 6\chi_1 - 2\chi_2}. \quad p \equiv \frac{\ddot{\psi}}{m_{\text{P}}H}, \quad \epsilon \equiv -\frac{\dot{H}}{H^2}
$$

### The EOM

$$
1 = (x+y)^2(1 - 12c_2y^2) + 8(c_1 - c_2)xy^3 + 2z^4,
$$
  
\n
$$
\epsilon = 2 + 12c_1y^4 - 4y^3(c_1 - c_2)\left(\frac{p}{\sqrt{2}} + \epsilon y\right) - 4(c_1 - 7c_2)xy^3 - 12(c_1 - 2c_2)x^2y^2,
$$
  
\n
$$
\frac{p}{\sqrt{2}} = 2y^2\left(2x(4c_1 - 7c_2) + 3\sqrt{2}c_2p\right) + \frac{2(x^2 - 1)}{y} + y\left(\epsilon - 12c_2x^2\right) + x + 4y^3(c_1\epsilon - 3c_1 - 4c_2\epsilon).
$$

## Dynamical system

$$
x' = \frac{p}{\sqrt{2}} + x\epsilon, \quad y' = x
$$

We neglect the matter contribution in order to study the epochs where the universe experiments accelerated expansion.

# Fixed points and stability



# Cosmological viability of the fixed points



$$
c_1 \le 0 \quad \wedge \quad c_2 > \frac{c_1}{2} + \sqrt{-\frac{c_1}{24}}.
$$

$$
\frac{\partial B}{\partial \beta} = 3\hat{g}^2 \left(\frac{y}{z}\right)^4 \left[ y^2 - 12c_2y^4 + x^2 \left(1 - 12c_2y^2\right) + 2x \left[ y + 4(c_1 - 4c_2)y^3 \right] + 2z^4 \right].
$$

 $\begin{array}{cc} \n & c_1 \n \end{array}$ 

- At the fixed point  $A_+$ , the density  $\rho_B$  becomes negative.
- At the fixed points  $\overline{B}_+$  and  $C_+$  the density  $\rho_B$  goes to infinity.

# Pseudo stationary states or nullclines

• The straight lines and constant roll condition.

$$
y = \beta x, \quad \ddot{\psi} = \frac{H}{\beta} \dot{\psi} \qquad \qquad \lim_{x \to \infty} \left( \frac{1}{\beta} - \frac{x'}{x} \right) = 0
$$

When we consider the limit of the x and y large we got the equation on  $\beta$ 

$$
0=\left(-\frac{4}{3}+\frac{7}{3}\frac{c_2}{c_1}\right)+\left(-\frac{37}{9}+\frac{8}{9}\frac{c_1}{c_2}+\frac{56}{9}\frac{c_2}{c_1}\right)\beta+\left(\frac{4}{3}-\frac{2}{3}\frac{c_1}{c_2}+\frac{7}{3}\frac{c_2}{c_1}\right)\beta^2+\beta^3.
$$

such that the slopes of the straight lines are

$$
\beta_0 = \frac{4}{3} - \frac{7}{3} \frac{c_2}{c_1},
$$
\n
$$
\beta_{\pm} = -\frac{4}{3} + \frac{c_1}{3c_2} \pm \frac{\sqrt{(c_1 - c_2)(c_1 - 7c_2)}}{3c_2},
$$
\n
$$
w_B = -1
$$
\n
$$
w_B = -\frac{23}{9} + \frac{8}{9} \frac{c_1}{c_2} \pm \frac{8}{9c_2} \sqrt{(c_1 - c_2)(c_1 - 7c_2)}.
$$



## Pseudo stationary states or nullclines



 $' = 0$  when  $y \rightarrow 0$ , we find the pseudo fixed points  $U_{+} = {\pm 1, 0}$ 

• The stability of this points are describing by the eigensystem

$$
U_{+}: \quad \lambda_{1}^{+} = -\frac{1}{2}y, \quad \lambda_{2}^{+} = 3 + \frac{4}{y},
$$

$$
\nu_{1}^{+} = \{0, 1\}, \quad \nu_{2}^{+} = \left\{3 + \frac{4}{y}, 1\right\},\
$$

$$
U_{-}: \quad \lambda_1^{-} = 3 - \frac{4}{y}, \quad \lambda_2^{-} = \frac{1}{2}y,
$$

$$
\nu_1^{-} = \left\{3 - \frac{4}{y}, 1\right\}, \quad \nu_2^{-} = \{0, 1\}.
$$

 $\mathcal{X}% _{M_{1},M_{2}}^{\alpha,\beta}(\varepsilon)=\mathcal{X}_{M_{1},M_{2}}^{\alpha,\beta}(\varepsilon)$  $x_i = 5 \times 10^9$ ,  $y_i = 10^{10}$ ,  $c_1 = 0.0206$ ,  $c_2 = 0.0366$ .

## Instabilities in the central zone



# Instabilities in the central zone



