



Advancements in Accelerator Operation

Automation and AI integration

S. Appel, O. Boine-Frankenheim, V. Isensee, N. Madysa, A. Oeftiger
GSI, Darmstadt, Germany

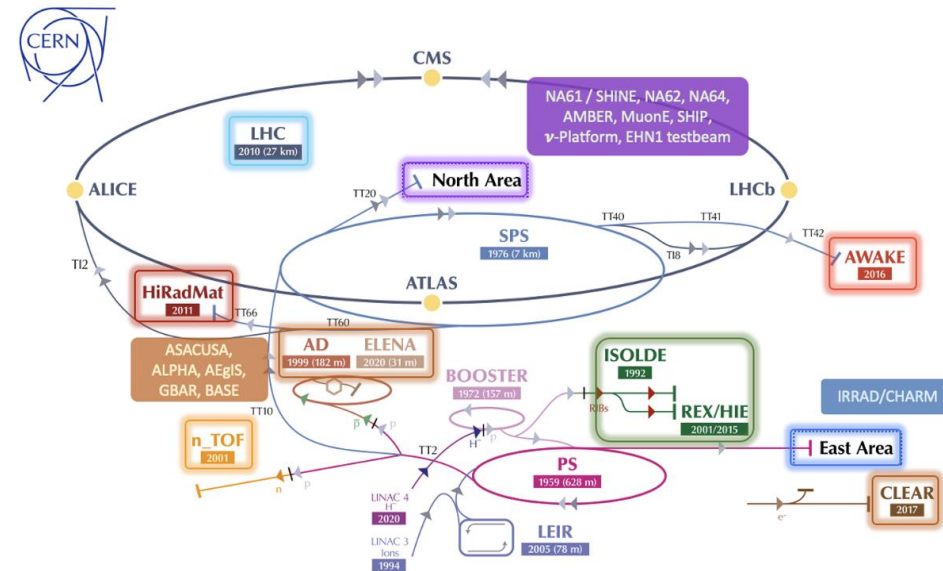
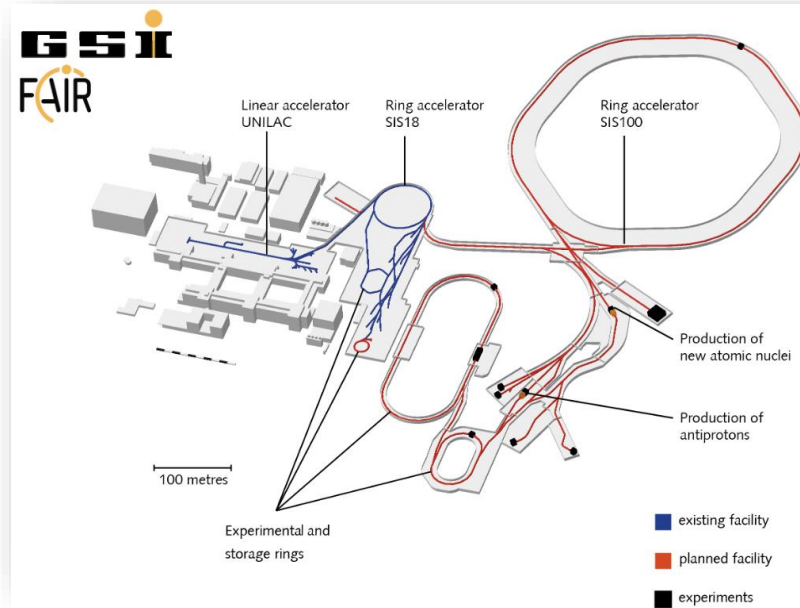
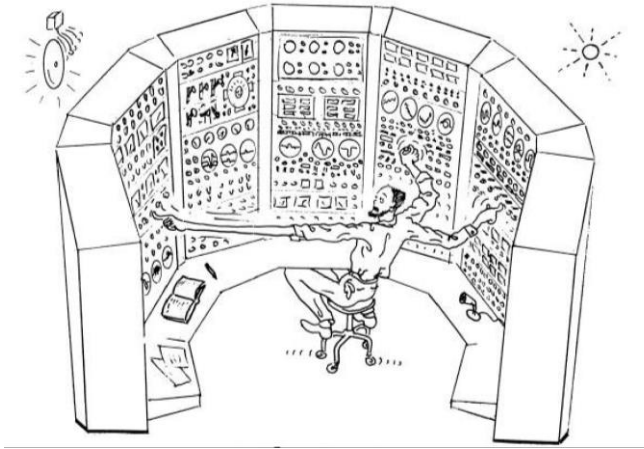
V. Kain, C. Roderick, M. Schenk, F. Velotti
CERN, Geneva, Switzerland

Beam operation challenges

Motivation

- **Machine availability & beam quality** are essential to reach **physics objectives**
parameter drifts, fault recovery & prediction, testing, ...
- Broad spectrum of **machine & beam types** with **multi-destination** operation
beam commissioning & preparation, hysteresis & eddy-currents, scheduling, ...

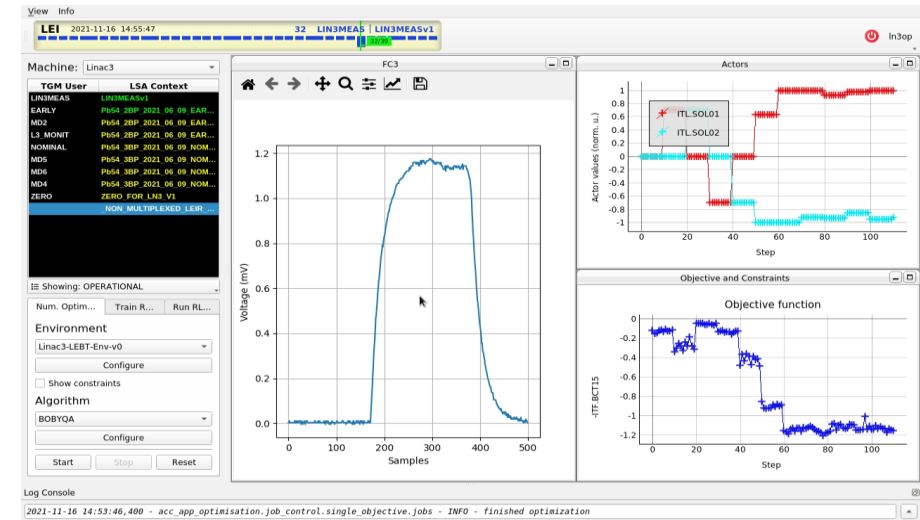
➔ **Exploit automation & technological advances (ML / AI) where possible**



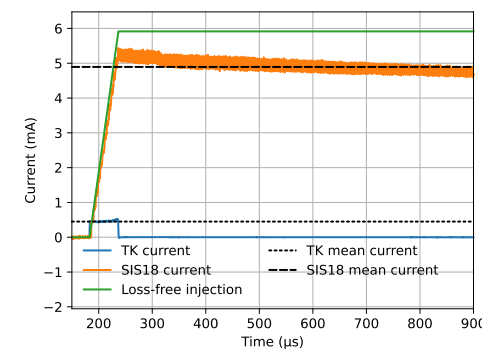
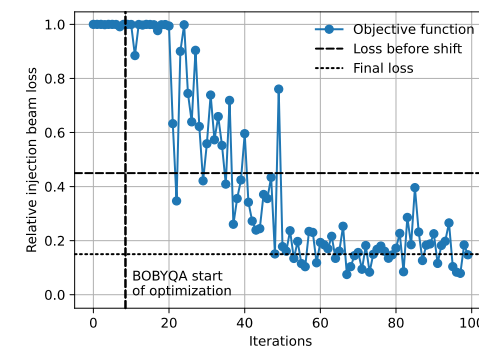
GeOFF Collaboration

History & scope

- Focus on **parameter optimization & drift compensation** here
- Address in **generic & flexible manner** → framework
- **Generic Optimization Framework & Frontend (GeOFF)**
 - **Python framework** to unify **different optimization approaches**
Classical Black-Box & Bayesian Optimization, Reinforcement Learning, Continuous Optimal Control
 - **Standardized interfaces, tools** for developers & docs
 - **GUI application** that wraps everything together
 - “Facilitate implementation of parameter optimization task with primary focus on problem itself”
- **Initiated and originally developed at CERN**
- **Since 2022 informal, yet effective collaboration with GSI**
focus on AI, optimization algorithm & tools development, knowledge sharing



Example: CERN Linac3



Example: GSI SIS18

GeOFF: status & plans

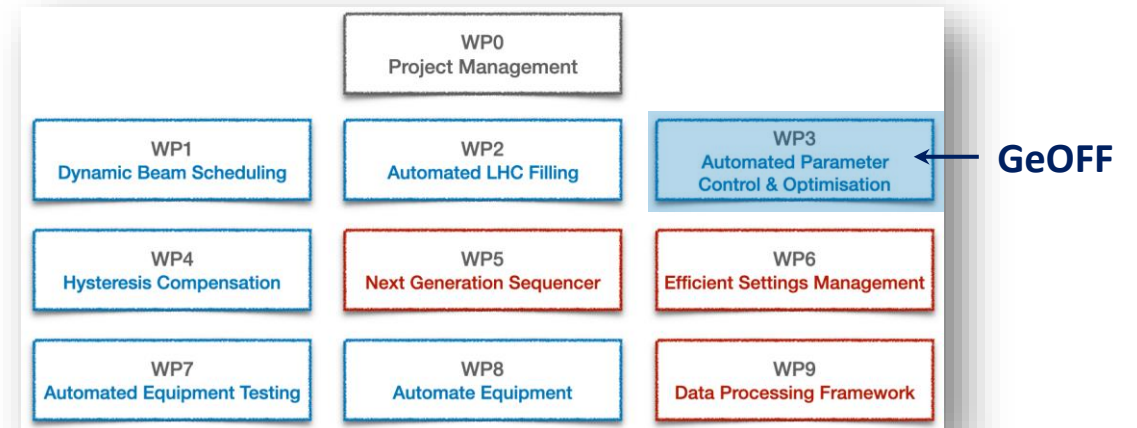
... at CERN & GSI/FAIR

GSI/FAIR

- **EURO-LABS** finances a scientific staff member for three years in the Accelerator Physics Group
- **Maintenance and co-development of GeOFF**
- Participation of several **Master / PhD students** from TU Darmstadt

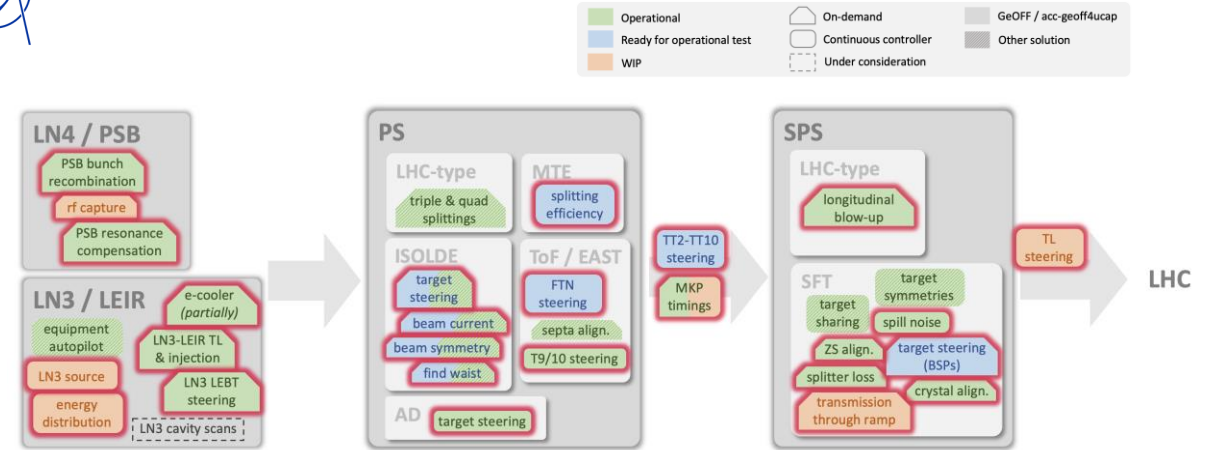
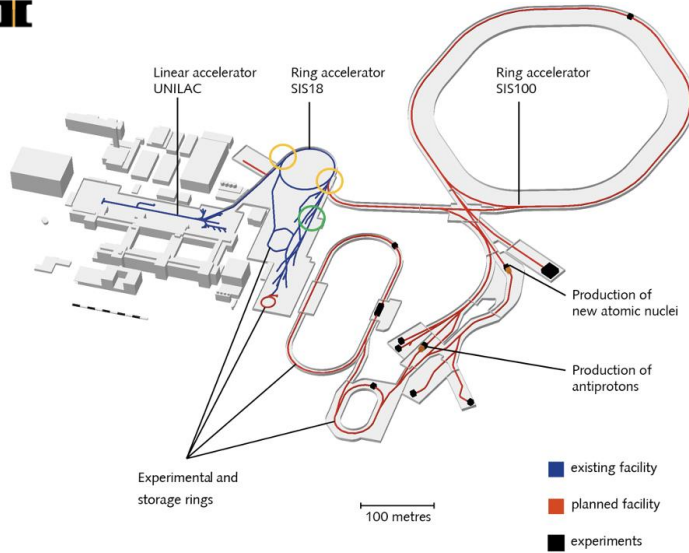
CERN

- **GeOFF one of core products** of DSB section in BE-CSS
 - Two staff part time for maintenance, improvements, and evolution
- **Efficient Particle Accelerators project (EPA)**
 - **Goal:** explore and exploit **automation & ML/AI** systematically **across complex**
 - **Approved** in autumn 2023 for a **5-year period**



GeOFF: status & plans

... at CERN & GSI/FAIR



- November 2023: **successful optimization** runs using GeOFF at **TK, SIS18 & FRS**
- Introduction of **Python Bridge** to access LSA & FESA via Python
- Investigation of safe deployment of **Python applications** in control room
topic for the FAIR Mini-MAC controls review

- **GeOFF** since LS2 **main optimization framework** in use *beam commissioning & day-to-day operation, further auto-pilots under development*
- **Trend from on-demand to continuous control**
Ported GeOFF concept to server: **UCAP*** infrastructure with **Python & GPU** support is key

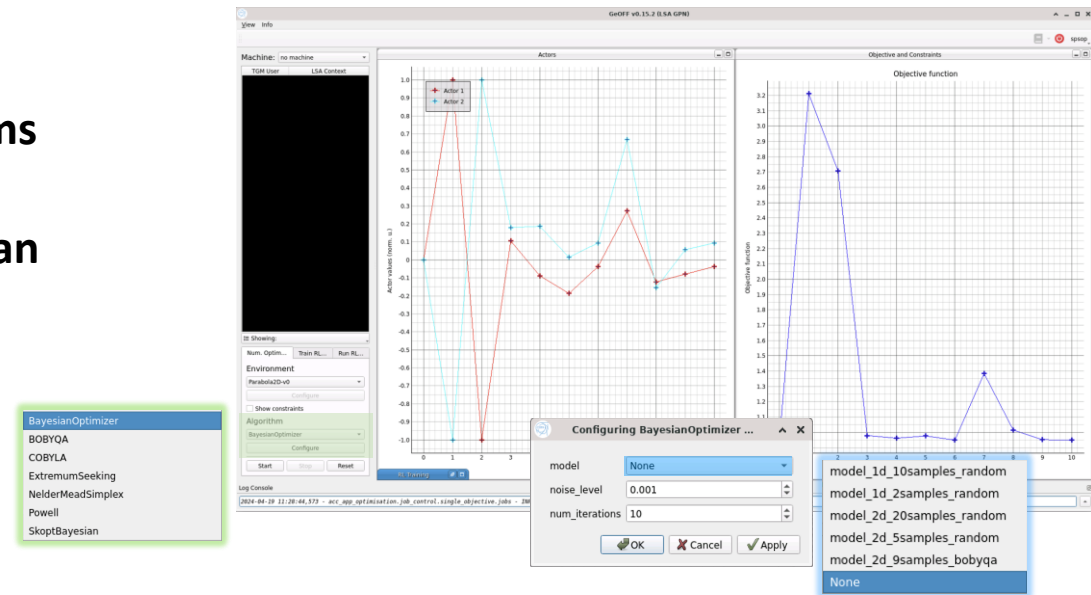
* *Unified Controls Acquisition and Processing: data processing pipelines on server*

GeOFF: recent developments

Custom algorithms, upgrades, and maintenance

- **Features & algorithms**

- Optimization tasks can have **custom configurable algorithms**
e.g.: model-based controller with prior knowledge
- **GSI**: preparing proof-of-concept of **Multi-Objective Bayesian Optimization (BO)**
- **CERN**: resonance compensation with **pre-conditioned BO**
ongoing tests at PSB



- **Upgrades and maintenance**

- Repayment of technical debt by **upgrading** dependencies, adjusting all interfaces and **fixing bugs**
 - GeOFF is heavily based on **OpenAI Gym**
 - OpenAI ceased development:
Farama Foundation took it over as **Gymnasium**
 - Many backwards-incompatible changes since then
- Update documentation

Create merge request Cancel

Commits 84 Pipelines 1 Changes 109

Showing 106 changed files with 12991 additions and 3155 deletions

GeOFF: next steps

Highest priority items and common interests

- Improve **Bayesian Optimization** (BO) support
 - CERN: Adaptive BO, BO with non-constant prior
 - GSI: Multi-Objective BO
- Improve **integration of Reinforcement Learning**
- Evolution of **GUI application**
 - CERN: distribute maintenance work between accelerators
 - GSI: use outside CERN is EURO-LABS requirement

Conclusions

- **GSI-CERN collaboration on GeOFF has been highly successful and will continue**
 - Labs are in **direct collaboration** and through **EU-projects**
 - **CERN** has a lot of experience in **automation and AI**
 - **GSI** is making progress in the field, and **offers valuable contributions in terms of algorithms**
e.g.: Multi-Objective Bayesian Optimization
 - Both labs are facing **similar control problems**
e.g.: resonance compensation, spill noise cancellation, drift compensation in general
- **GeOFF is a great example where GSI & CERN profit from common infrastructure and share expertise**
- **Strengthening collaboration** further is goal of the *Artificial Intelligence for Accelerators, User Communities and Associated Technologies project (ARTIFACT)**

**pending approval*

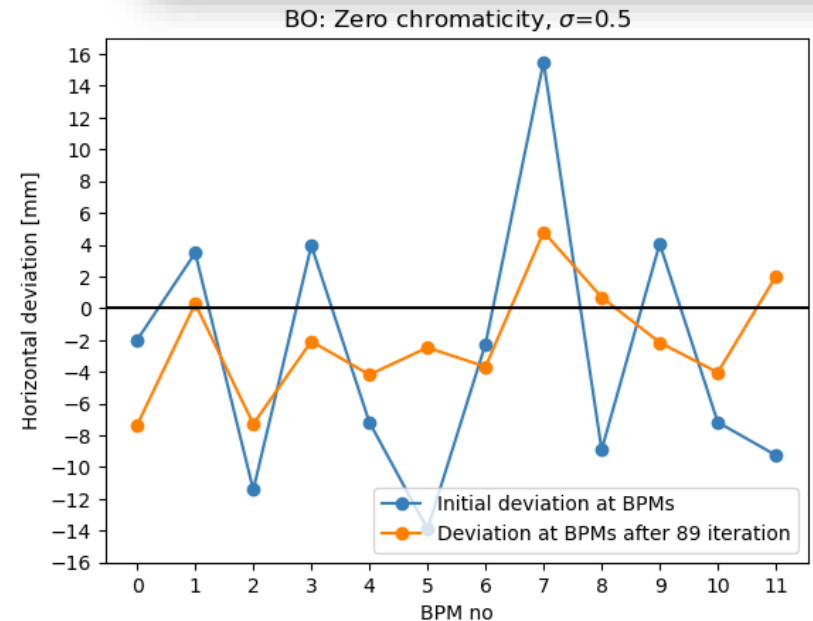
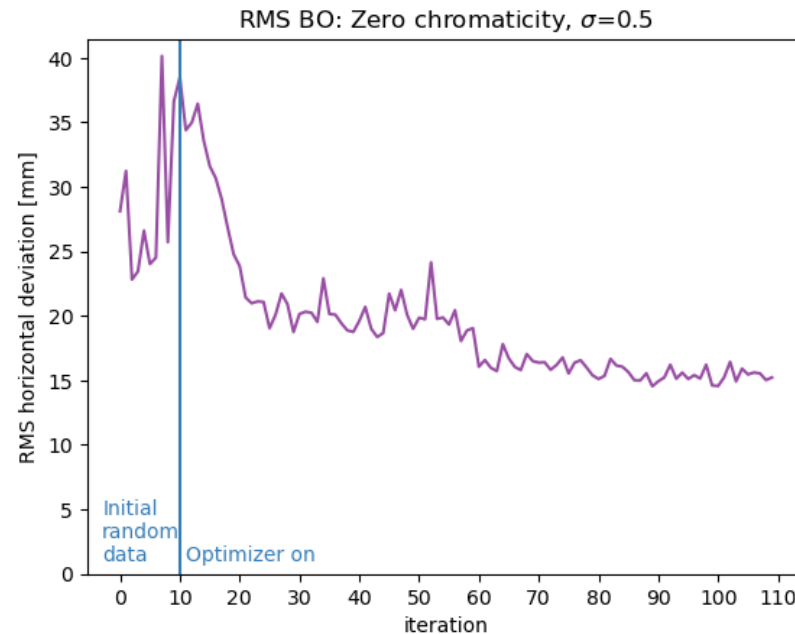
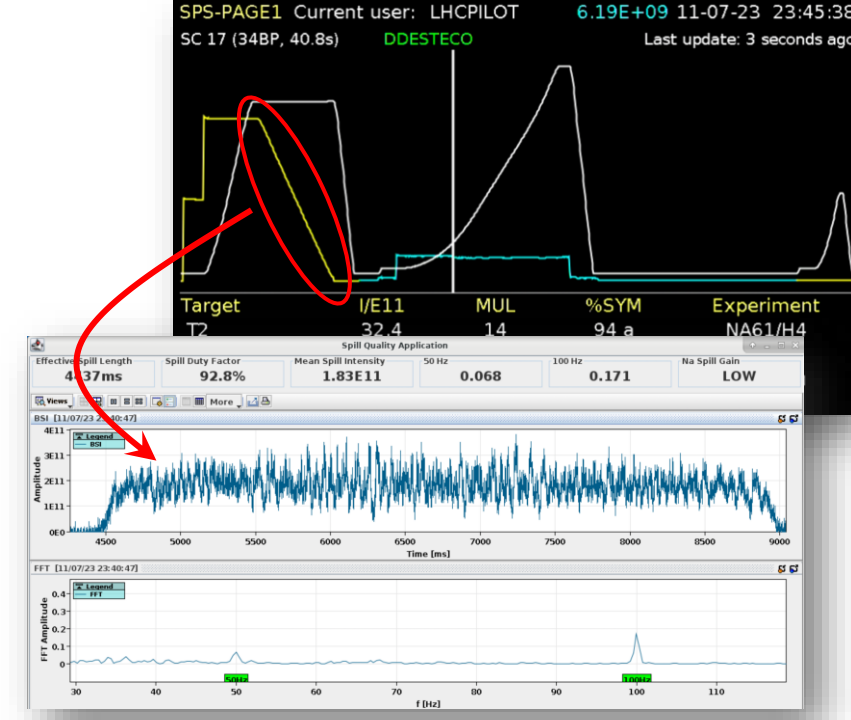
Thank you

Backup

Next Steps in GeOFF

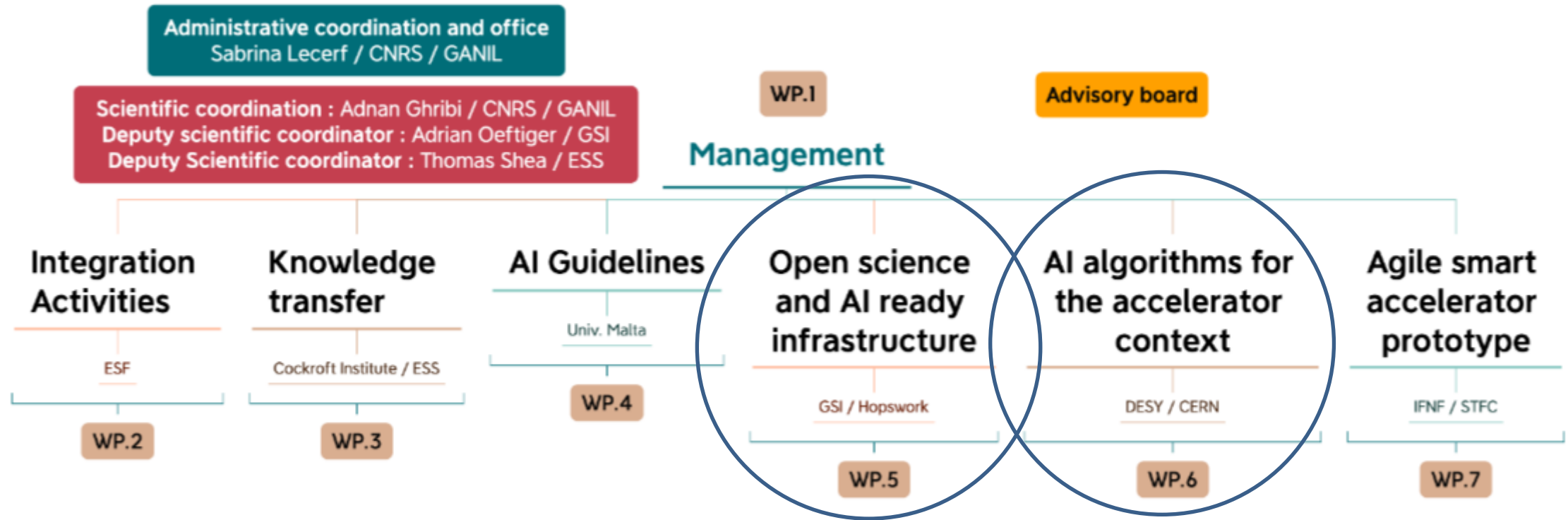
Highest Priority Items and Common Interests

- Improve **Bayesian Optimization** support
 - CERN: Adaptive Bayesian Control
 - GSI: Multi-Objective Bayesian Optimization
- Improve **integration of RL**
- Evolution of **GUI application**
 - CERN: distribute maintenance work between accelerators
 - GSI: use outside CERN is EURO-LABS requirement



ARTIFACT

Artificial Intelligence for Accelerators, User Communities and Associated Technologies



- 15 research infrastructures
- 10 M€ overall
- Time period: Jan 2025 – Dec 2028
- WP5/WP6 offer more opportunity for collaboration between CERN and GSI

WP5 Package Leader:
A. Mistry (GSI)

WP6 Deputy Leader:

V. Kain (CERN)

Subtask 6.4.4:

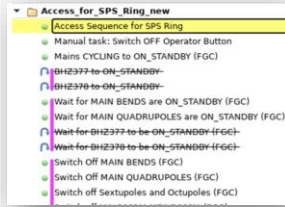
S. Appel (GSI)

Infrastructure

Frameworks & building blocks

Classical automation concepts

- **Sequencer:** programmatic execution of tasks
- High-level parameter models
- **AccTesting**



- **EPA:** sequencer 2.0, equipment testing, efficient settings management

Acc-Py

“accelerating Python”



- **Full integration of Python with control system**
- Online data acquisition, equipment access (set / get), app development, ...
- Python package index

UCAP

Unified Controls Acquisition & Processing



- **Virtual device service**
- Event-based, online **data transformations**

➔ **Further evolution with EPA**

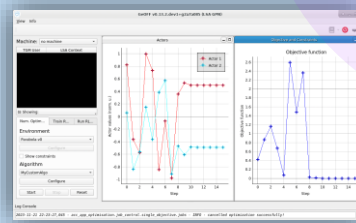
Enabling automation with AI / ML

Auto-pilots & optimizers

- **Facilitate** implementation of control problems
- **Exploit & expose features** of control architecture
- Maintain **uniformity** across complex

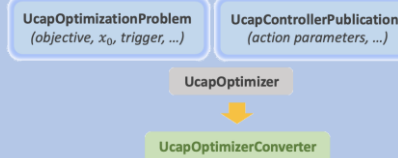
GeOFF

Generic Optimization Framework and Frontend



acc-geoff4ucap

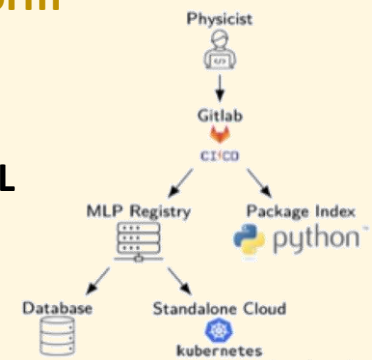
Framework for optimization & control via UCAP



Machine Learning Platform

Deployment & inference of (ML) models

- **Train, store & share ML models with VC**
- Language agnostic
- Available in control room



Infrastructure

UCAP & acc-geoff4ucap

UCAP

Framework & service to implement & run
online data processing pipelines

Acquire

- Subscribe to data sources
- Group data via EventBuilder

Transform

- Process incoming data
- Java or **Python**
- **GPU support**

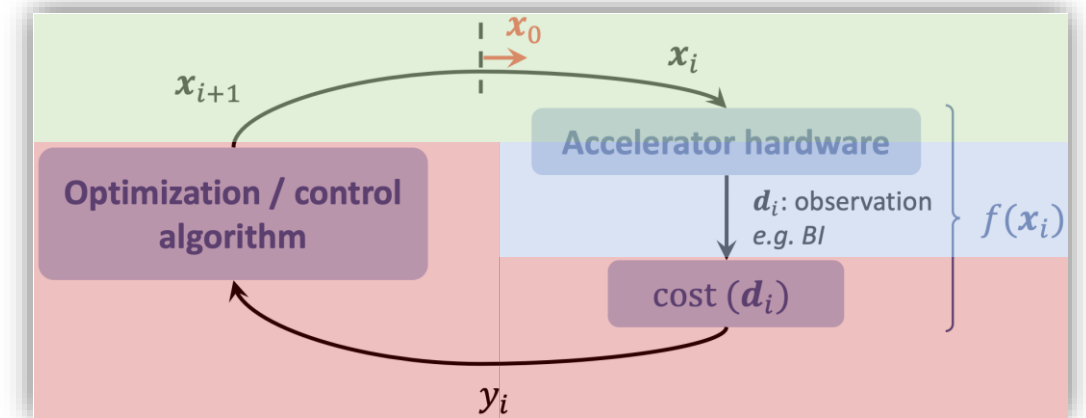
Publish

- Publish results
- Can be **hardware "sets"**

- UCAP pipelines can be **chained** and built into **hierarchies**
- Conceptually simple, and very **powerful**

acc-geoff4ucap

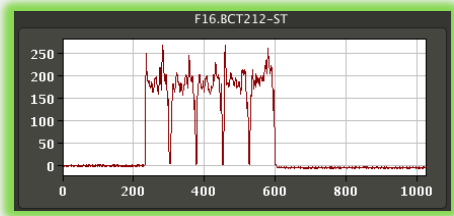
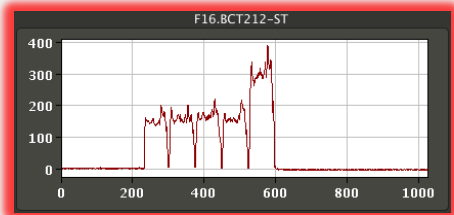
Use UCAP to implement the
optimization / control loop on server



Great infrastructure to run auto-pilots
continuous controllers or auto-launching optimizers

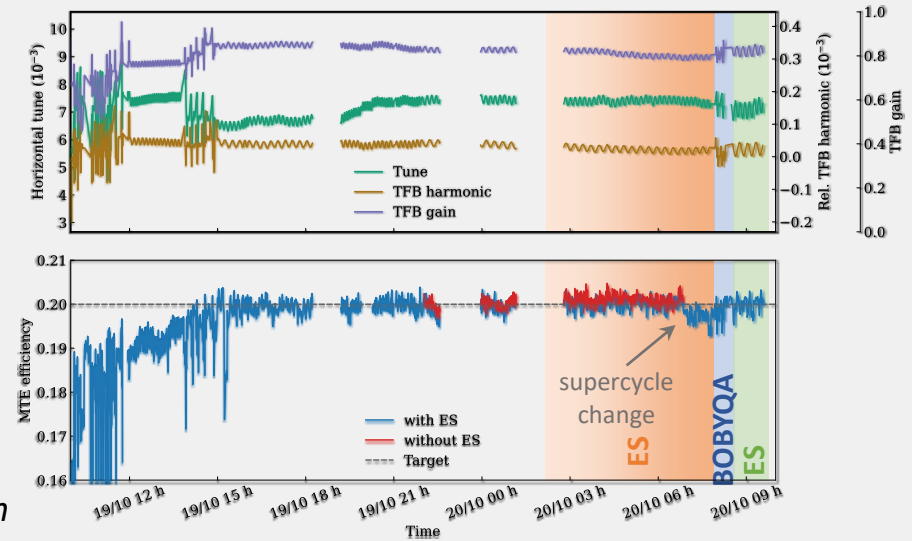
Status & results

Auto-pilots: a selection



PS Multi-Turn Extraction

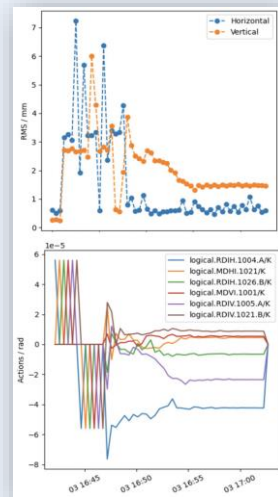
- **Automatic drift compensation**
- **Successfully tested** and tuned in MDs with controllers on **UCAP**
- **Hybrid agent:** continuous controller interleaved with optimizer when far off
- **Upcoming operational test**



A. Huschauer, M. Schenk, C. Uden

Trajectory steering framework using *acc-geoff4ucap*

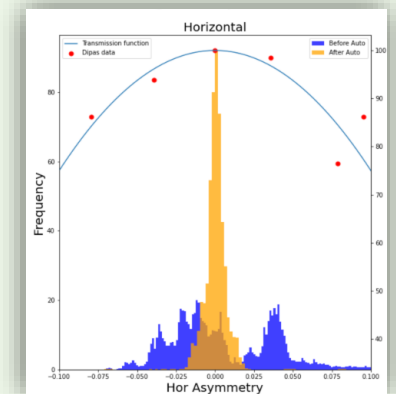
- **Versatile objective**
Beam position, beam loss, ...
- **Generic settings & actors**
- **Various algorithms**
incl. Micado / SVD
- **In 2024:** PS2SPS, SPS2LHC



G. Trad, F. Velotti

PS EAST: fixed target beam steering

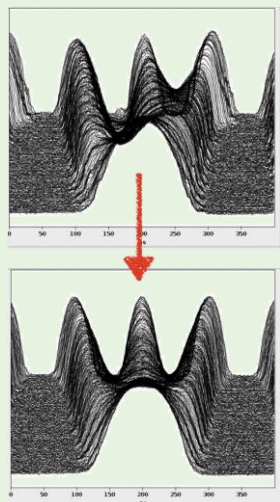
- **PID regulator on UCAP**
- **Simple & effective**
- **2024:** integrate with *acc-geoff4ucap*
- **Similar controller for TL**
towards AD



J. McCarthy

Status & results

Reinforcement learning: a selection



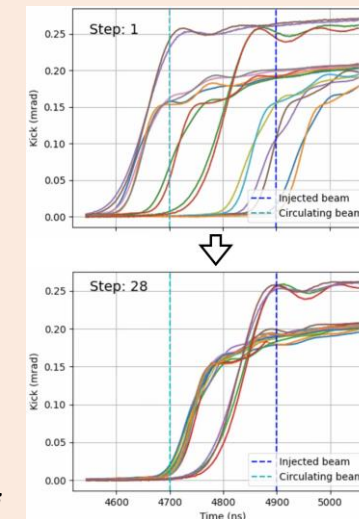
PS

- Correct RF **phase & voltage** for **uniform bunch splitting** (LHC beams)
- Successful **sim2real** & fully **operational**
- **Multi-agent (SAC) & CNN** for initial guess
- **Next: continuous** controller (UCAP)

A. Lasheen, J. Wulff

PS to SPS

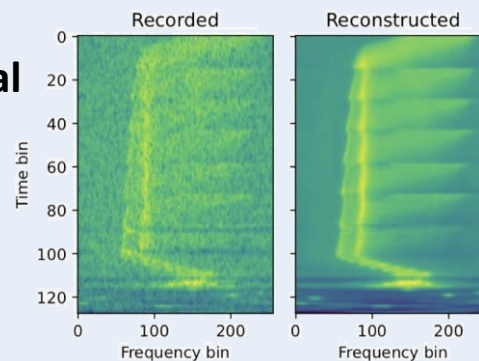
- Adjust **fine delays** of SPS **injection kicker**
- RL agent (PPO) trained on **data-driven dynamics model**
- Ready for **sim2real test**



M. Remta, F. Velotti

LINAC3 / LEIR

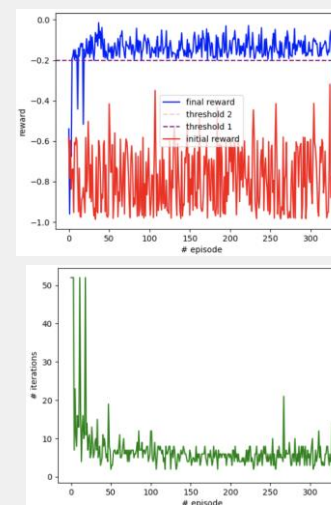
- **PhD project (B. Rodriguez):** control LINAC3 cavities for **optimal injection efficiency** into LEIR
- RL state based on **VAE-encoded Schottky spectra**
- Agent trained on **data-driven dynamics model**



V. Kain, N. Madysa

SPS

- **Steer DC beams** in TT20 TL using **split-foil secondary emission monitors**
- Works well in simulations, **with noise and varying emittances**
- Ready for **sim2real test**



N. Bruchon, V. Kain