



# tinyML: the mWatts world

# GreenWaves Technologies

- Fabless semiconductor startup founded in 2014.
- We design and sell **extreme performance** processors for **energy constrained devices**
- 45 people, HQ in **Grenoble**, France
- Offices in **Bologna**, Italy, **Shanghai**, China, **Copenhagen**, Denmark. Global sales footprint.



Best hardware product  
Embedded World 2023



Embedded Technologies Award 2023  
Les Assises de l'Embarqué

## GAP8

In production since 2020  
one of the very first  
commercially available  
RISC-V processor and AI  
microcontroller



## GAP9

Second generation  
ultra-low power AI and  
DSP enabled  
Microcontroller



Gartner

COOL  
VENDOR  
2019

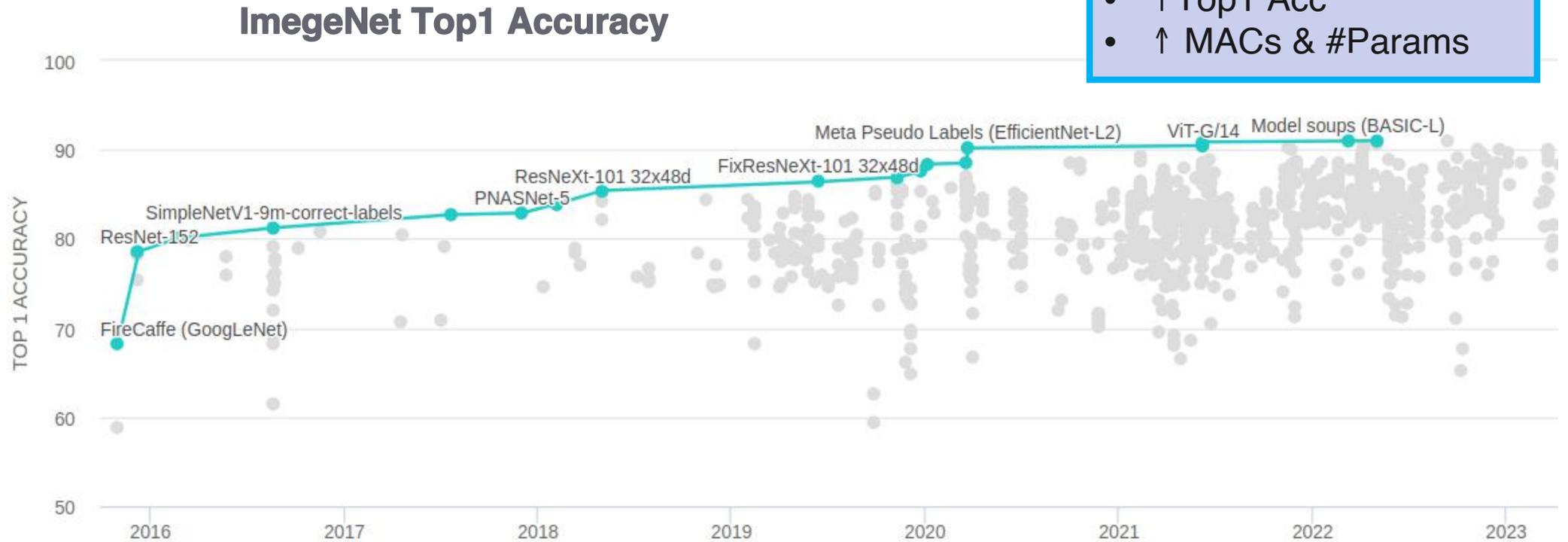
Cool Vendors in AI Semiconductors,  
Alan Priestley, Saniye Alaybeyi, April  
29, 2019.



# What is a “tinyML” workload?

**“Getting Better” trend**

- ↑ Top1 Acc
- ↑ MACs & #Params

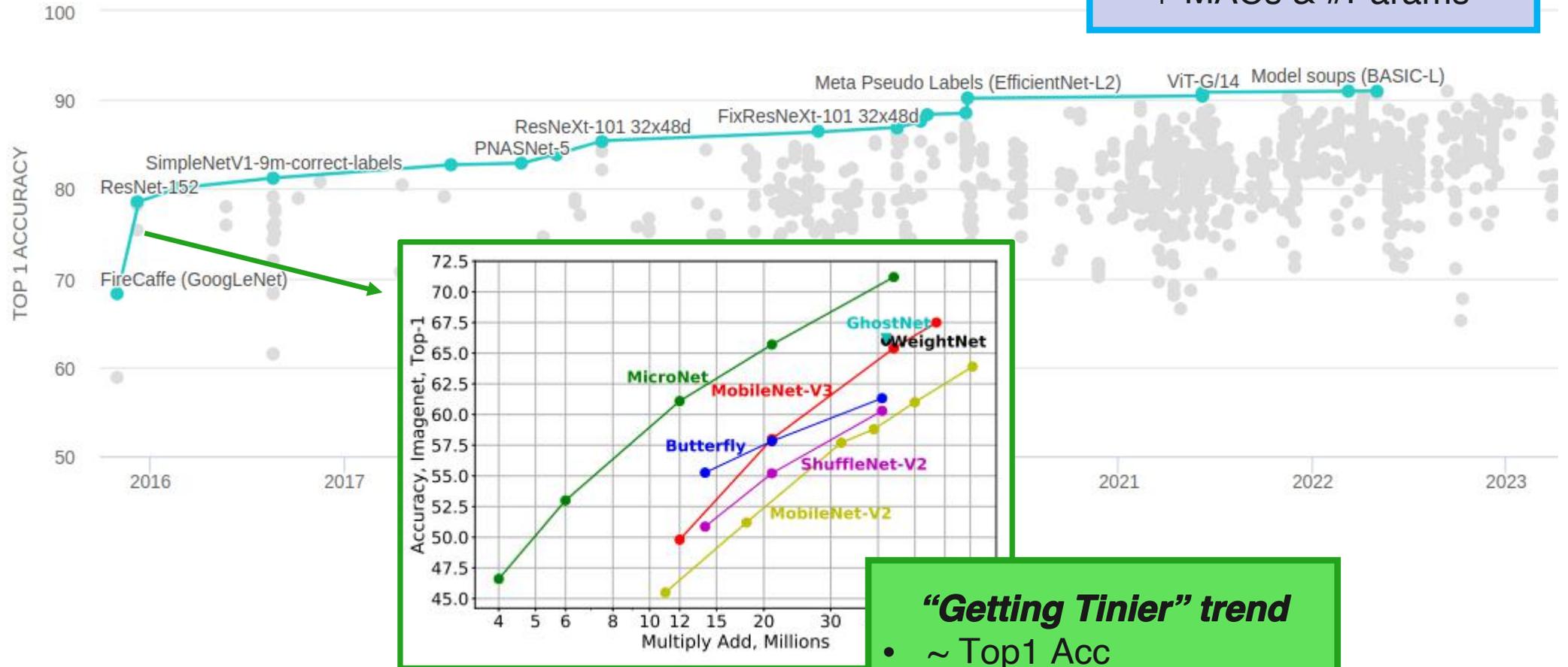


# What is a “tinyML” workload?

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ImageNet Top1 Accuracy



**“Getting Tinier” trend**

- ~ Top1 Acc
- ↓ MACs & #Params

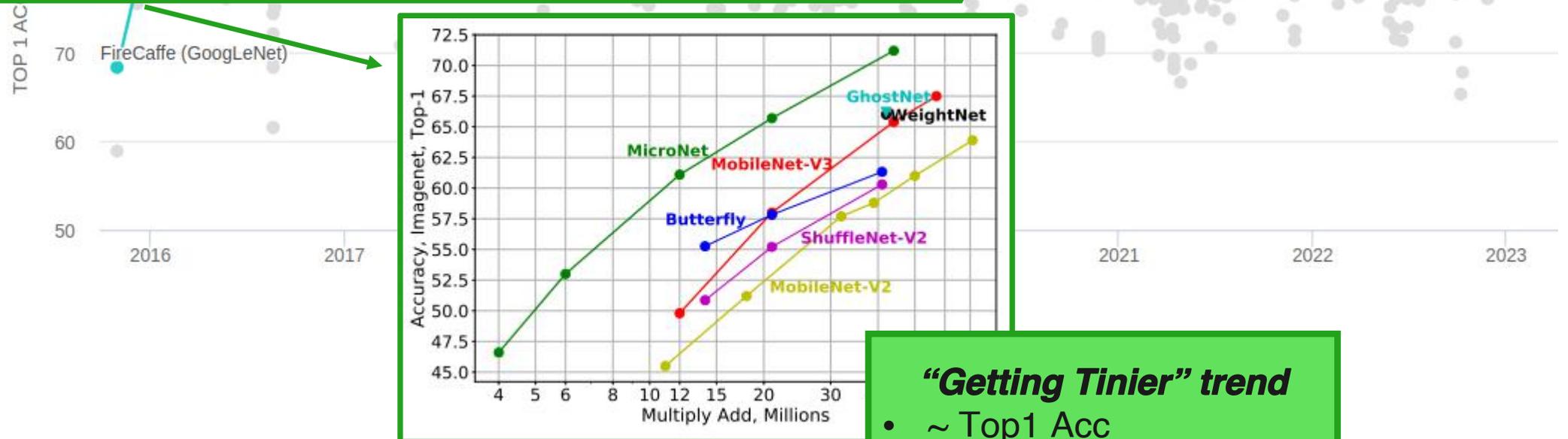
# What is a “tinyML” workload?

## Need:

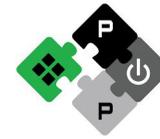
1. Flexibility (always-changing NN structures)
2. Performance
3. Energy efficiency

### “Getting Better” trend

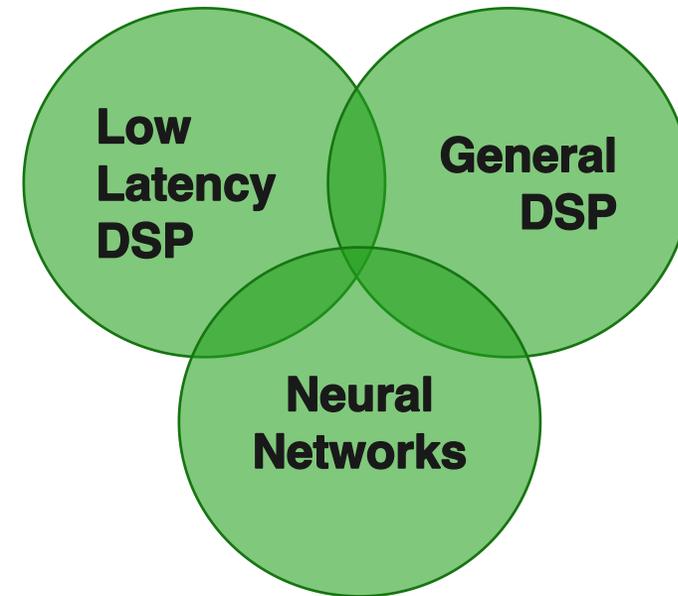
- ↑ Top1 Acc
- ↑ MACs & #Params



# Foundations of GAP

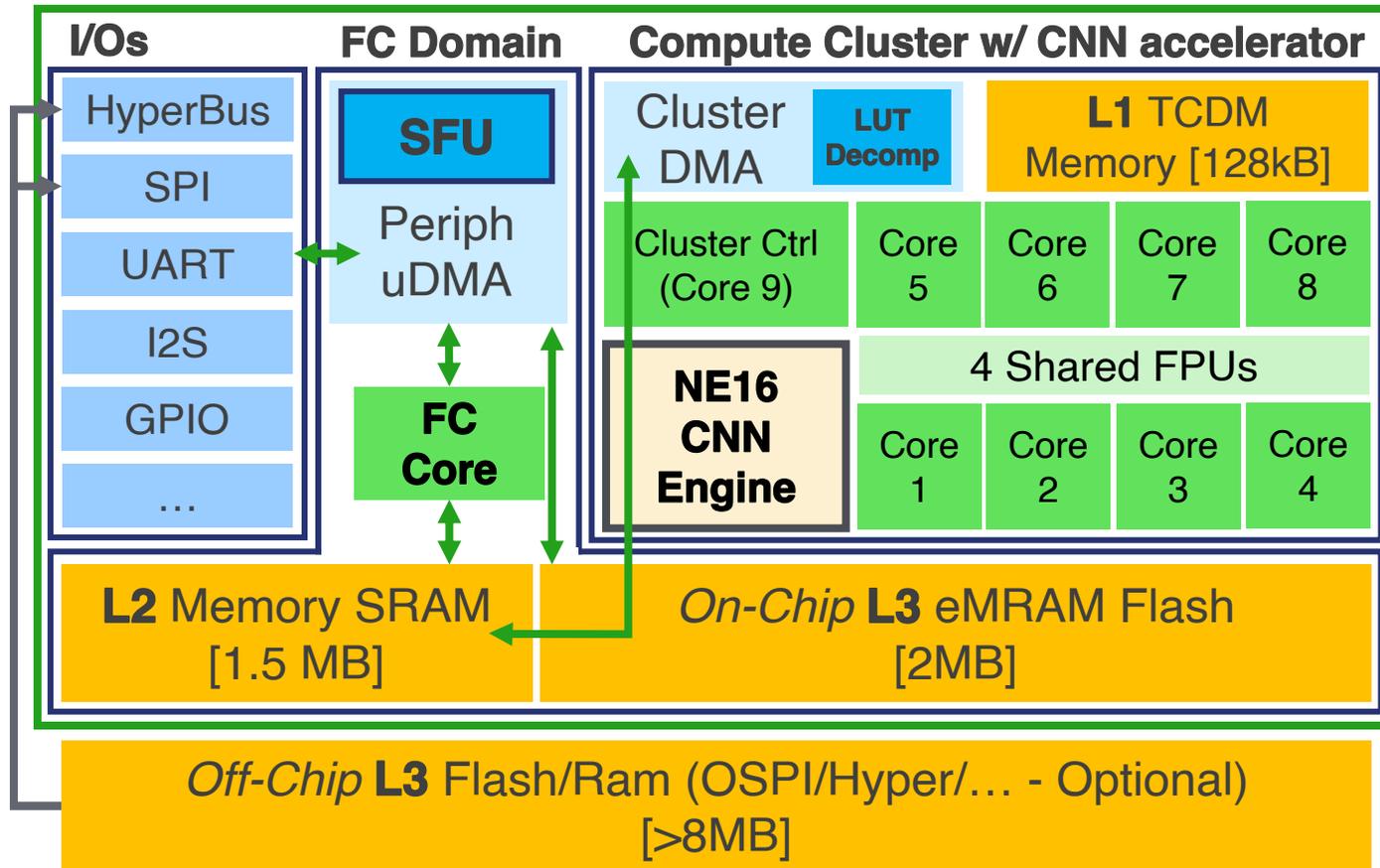


- Born from research groups:
  - **PULP** (Unibo & ETH Zurich)
  - **RISC-V**
- Push **Edge AI** to the limits
  - Specialized HW
  - Optimized SW
  - 10-100 GOPS @ <10mW always-on
- **Programmability**
  - RISC-V open source ISA
  - High level tools

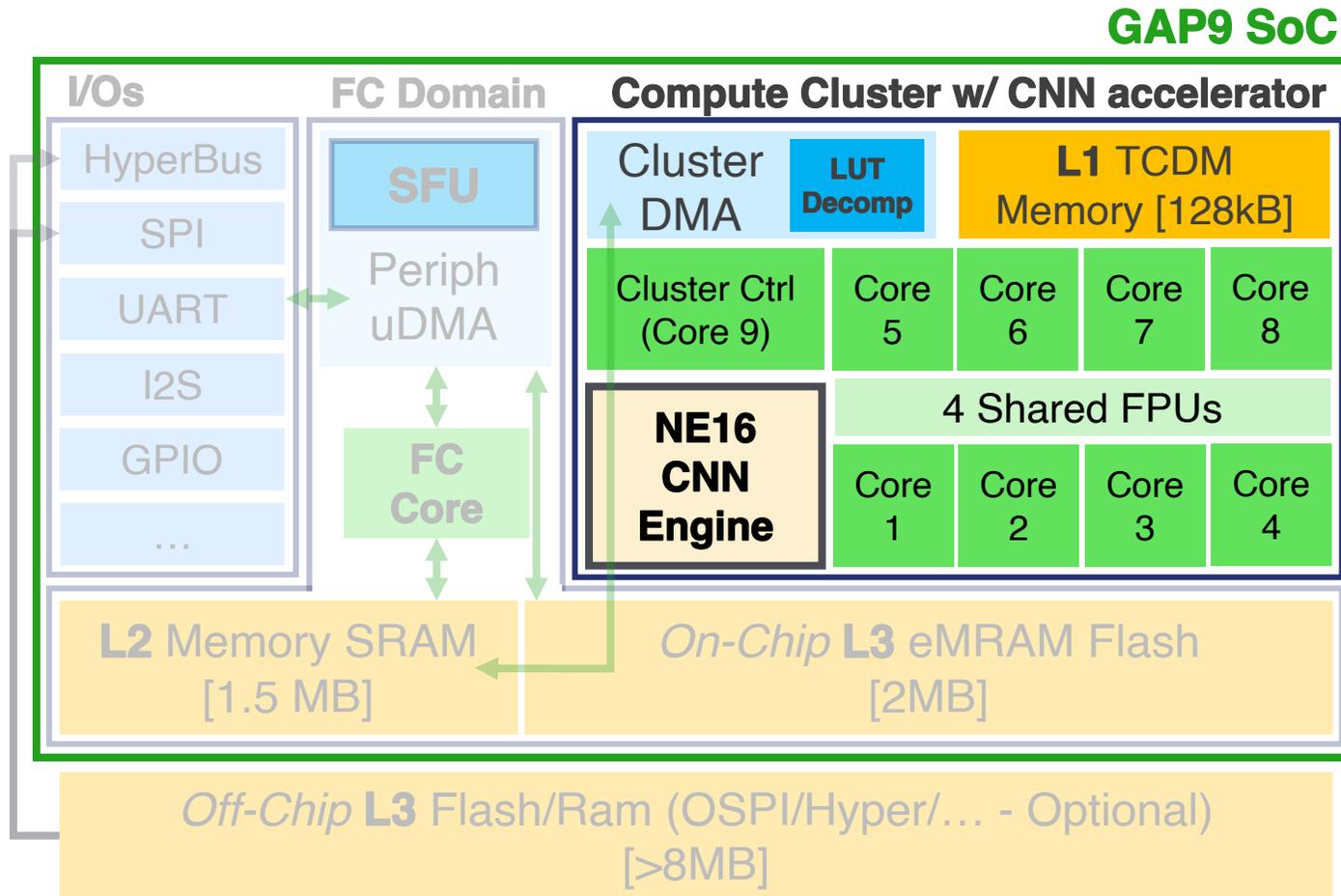


# GAP9 Architecture

## GAP9 SoC



# GAP9 Architecture

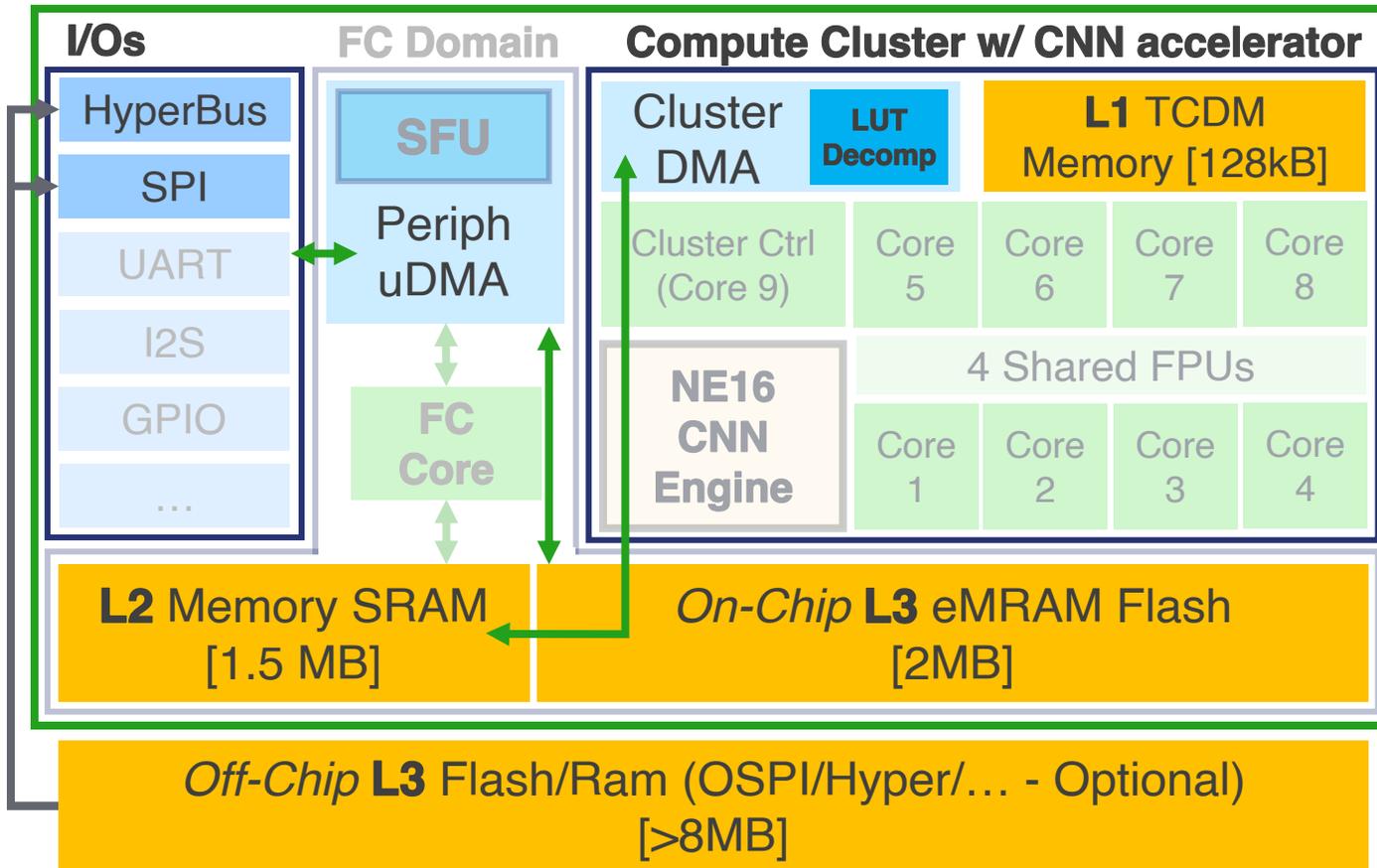


## Hierarchical Compute paradigm

- 4 independent frequency domains: **FC - I/Os - Cluster - SFU**
- *“Turn-on when you need”*

# GAP9 Architecture

## GAP9 SoC



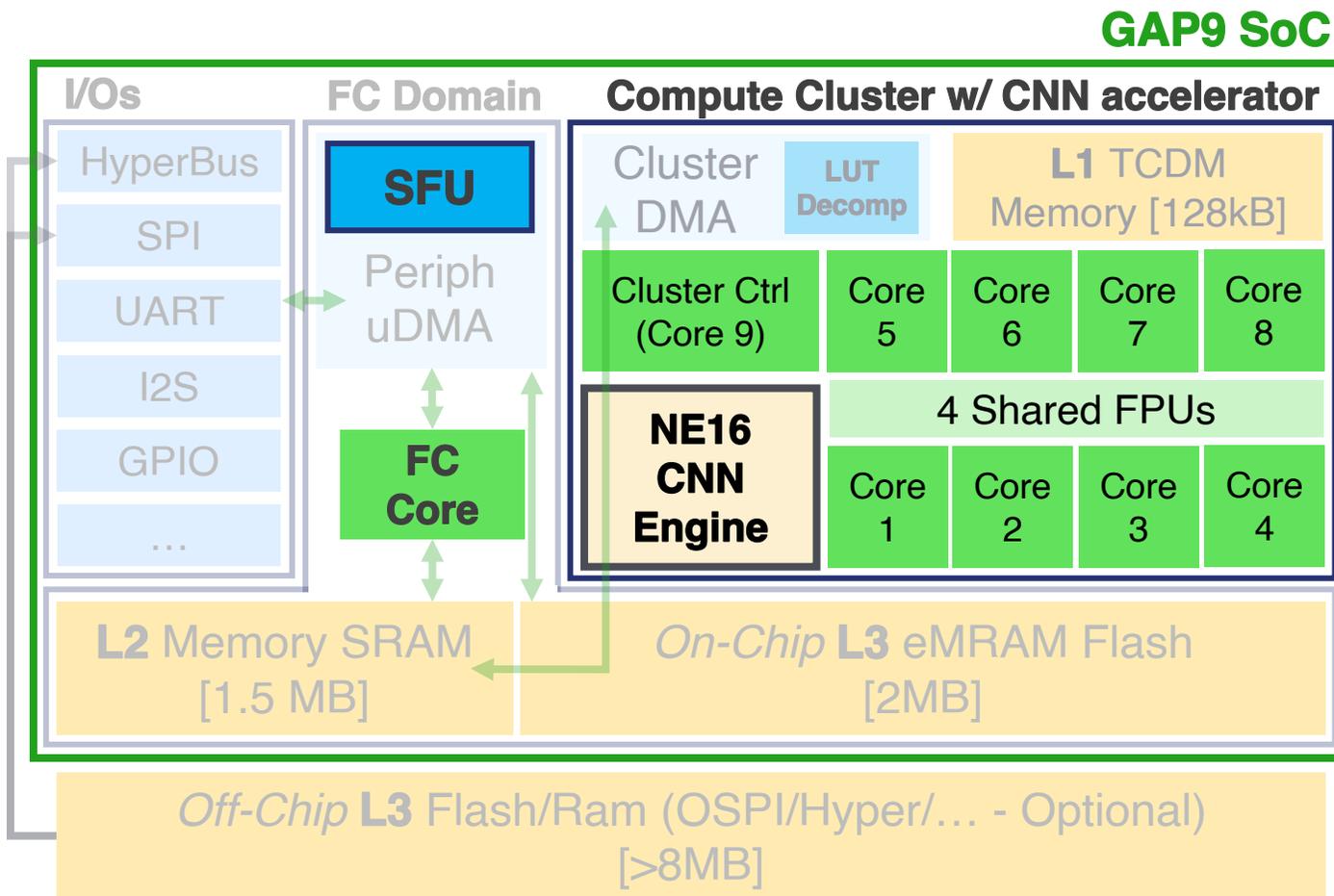
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### Hierarchical Memory Architecture (w/o D-Cache !!!)

- L1: 128kB – 1 Cyc/Access
- L2: 1.5MB – 10-100 Cyc/Access
- L3: >2MB – 100-1000 Cyc/Access
- DMA and uDMA for background copies+decompression

# GAP9 Architecture



## Hierarchical Compute paradigm

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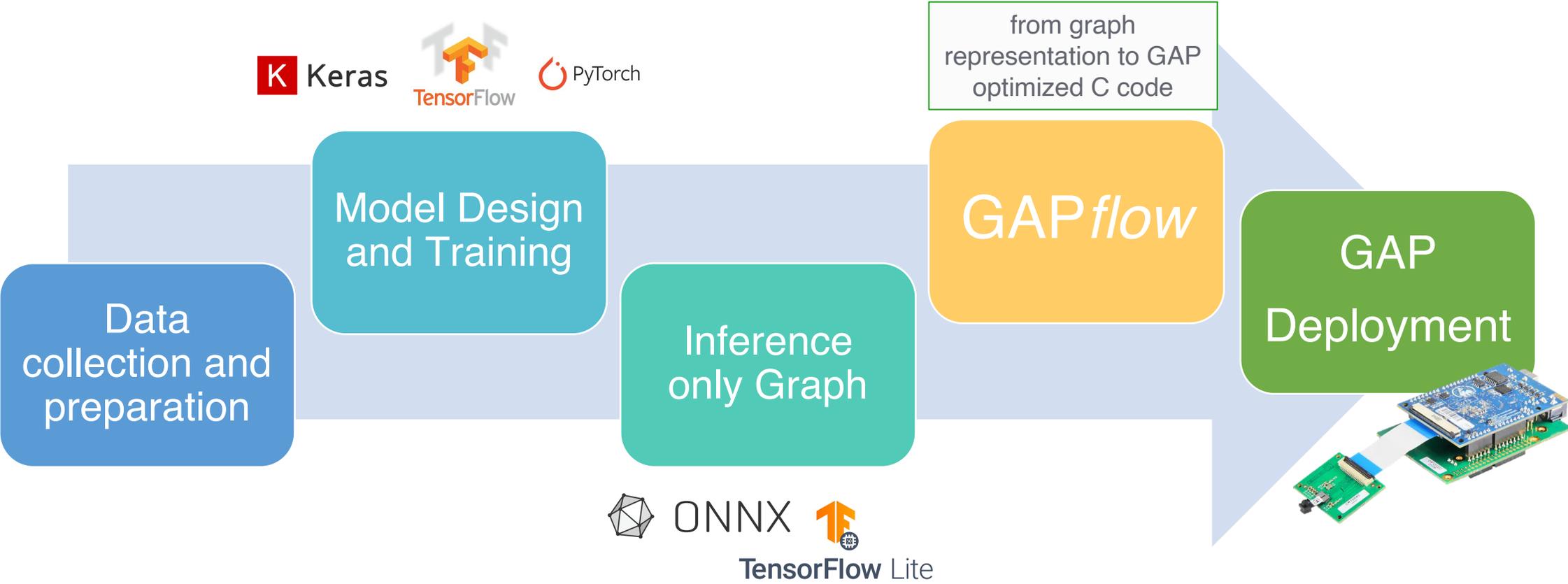
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## Heterogeneous Compute Units

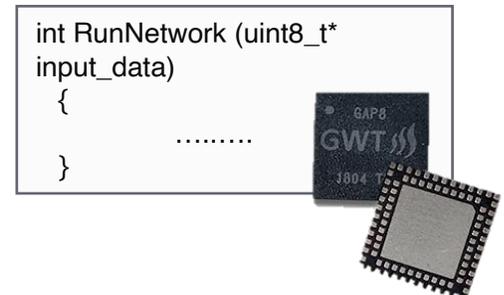
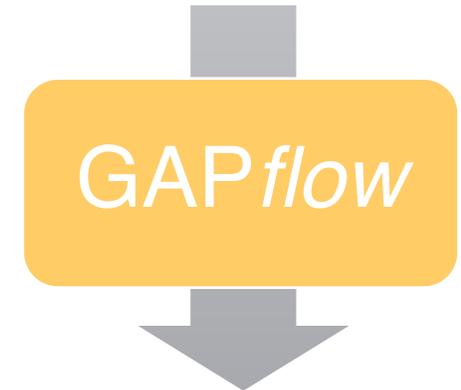
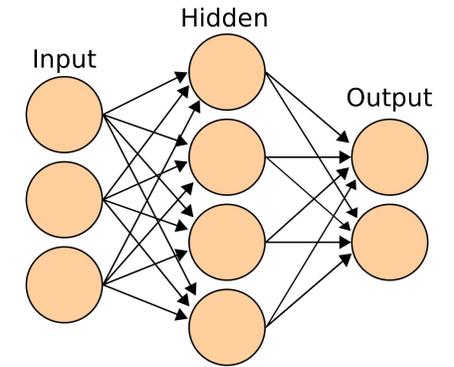
- 10 General Purpose RISC-V Cores
- 4 Shared FPUs (half/single precision)
- Conv/MatMul HW Accelerator (NE16)
- Low-Latency time-domain DSP Accelerator (SFU)

# GAPflow enables DNN inference on Parallel-Ultra Low Power GAP MCUs



# What is GAPflow?

**MAIN GOAL: turn complex DSP/NN computational graphs into optimized C code for GAP9**



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**MAIN GOAL: turn complex DSP/NN computational graphs into optimized C code for GAP9**

## GAP9 Graph Optimizations

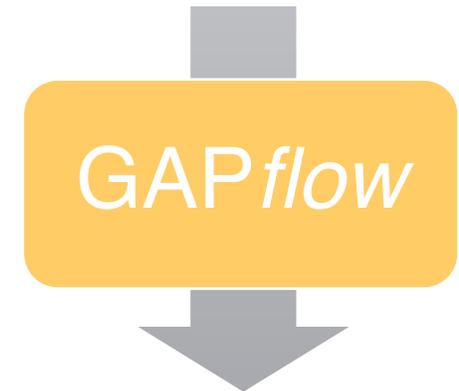
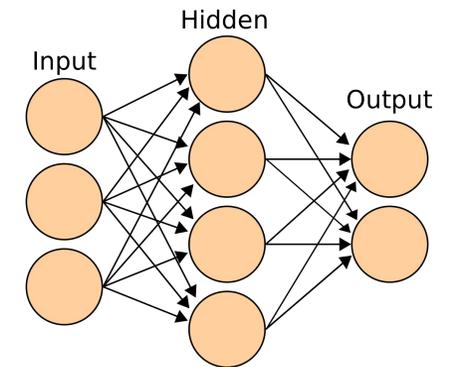
- **Static topology optimization** to minimize number of operations and memory overhead
- **Quantization:** reduce memory usage up to 16x and enable integer only arithmetic when performance is critical

## Validate the Solution

- Validate the numeric precision/accuracy of the deployable model in a user-friendly environment (python)

## Automatic C Code Generation

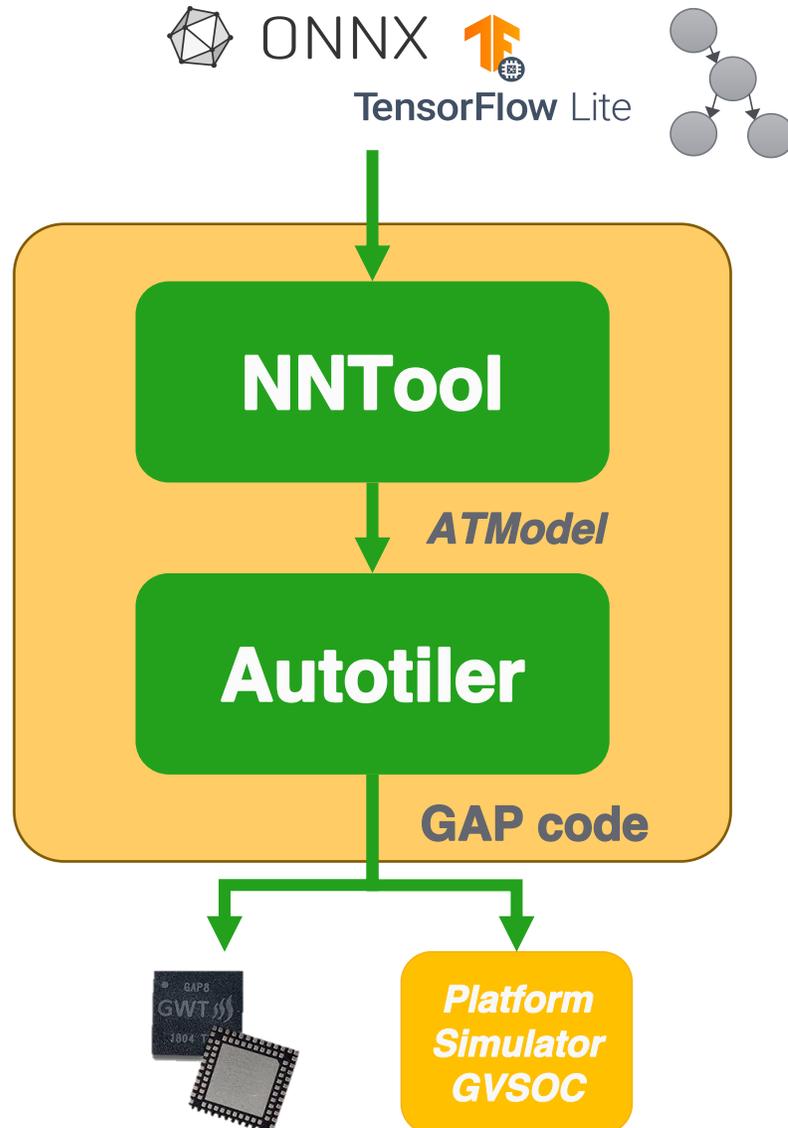
- Map the graph operations into the **Optimized SW library** of GAP9
- **Optimal Memory Management:** automating memory allocation and data transfers



```
int RunNetwork (uint8_t*  
input_data)  
{  
    .....  
}
```



# GAPflow: Overview



## NNTool

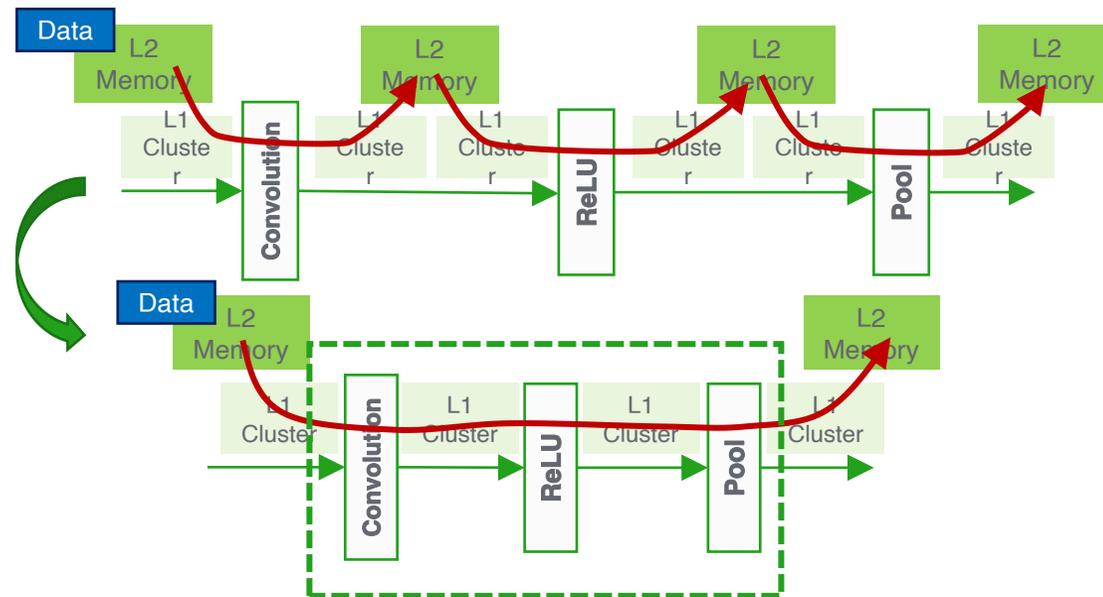
- **Static Topology optimizations** (node fusion)
- **Quantization** w/ calibration dataset (optional)
- **Validate** numerically the deployable solution
- Generates an IR of the graph (**ATModel**)

## Autotiler

- **Optimizes data movement** across the memory hierarchy
- Computes **optimal tiling sizes**
- Generates **GAP code** with double/triple-buffer mechanism using **optimized SW Library primitives**

# Topology Optimizations

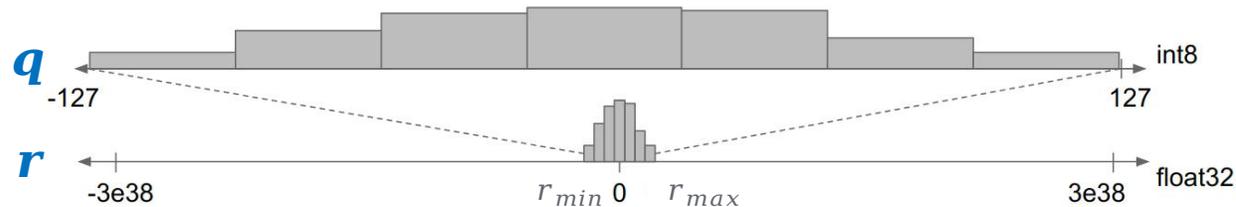
- **Remove** useless reshapes/transpose by moving them accross the graph
- **Layer Fusion:** known sequence of nodes merged together thanks to specialized hand-written backend SW
- **Expressions compiler:** fuses an arbitrary sequence of piecewise/broadcastable operations and dynamically generates GAP C code for it



# Quantization: Background

Any real tensor value is mapped into the 8-bit domain (INT8) through an affine transformation:

<https://arxiv.org/abs/1712.05877> (TFLite compliant)



$Z = 0$  if symmetric ranges  $r_{max} = -r_{min}$

$$r = S (q - Z)$$

$$\frac{r_{max} - r_{min}}{2^{nbits}}$$

## Convolution Operation

$X$  is a quantized value,  $x$  is a real value

$$y = \sum x \cdot w \longrightarrow S_y Y = \sum S_x X \cdot S_w W$$

Affine transformation

$$Y = \frac{S_x S_w}{S_y} \sum X \cdot W$$

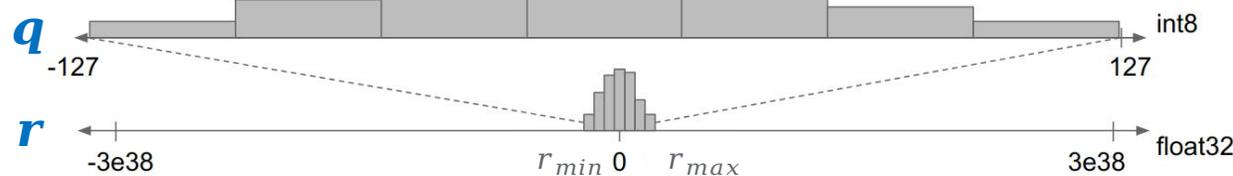
Integer only MACs

INT8

# Quantization: Background

- 4x memory reduction
- >4x speed up thanks to specialized HW
- But accuracy???

through an affine



$$r = S (q - Z)$$

$Z = 0$  if symmetric ranges  $r_{max} = -r_{min}$

$$\frac{r_{max} - r_{min}}{2^{nbits}}$$

## Convolution Operation

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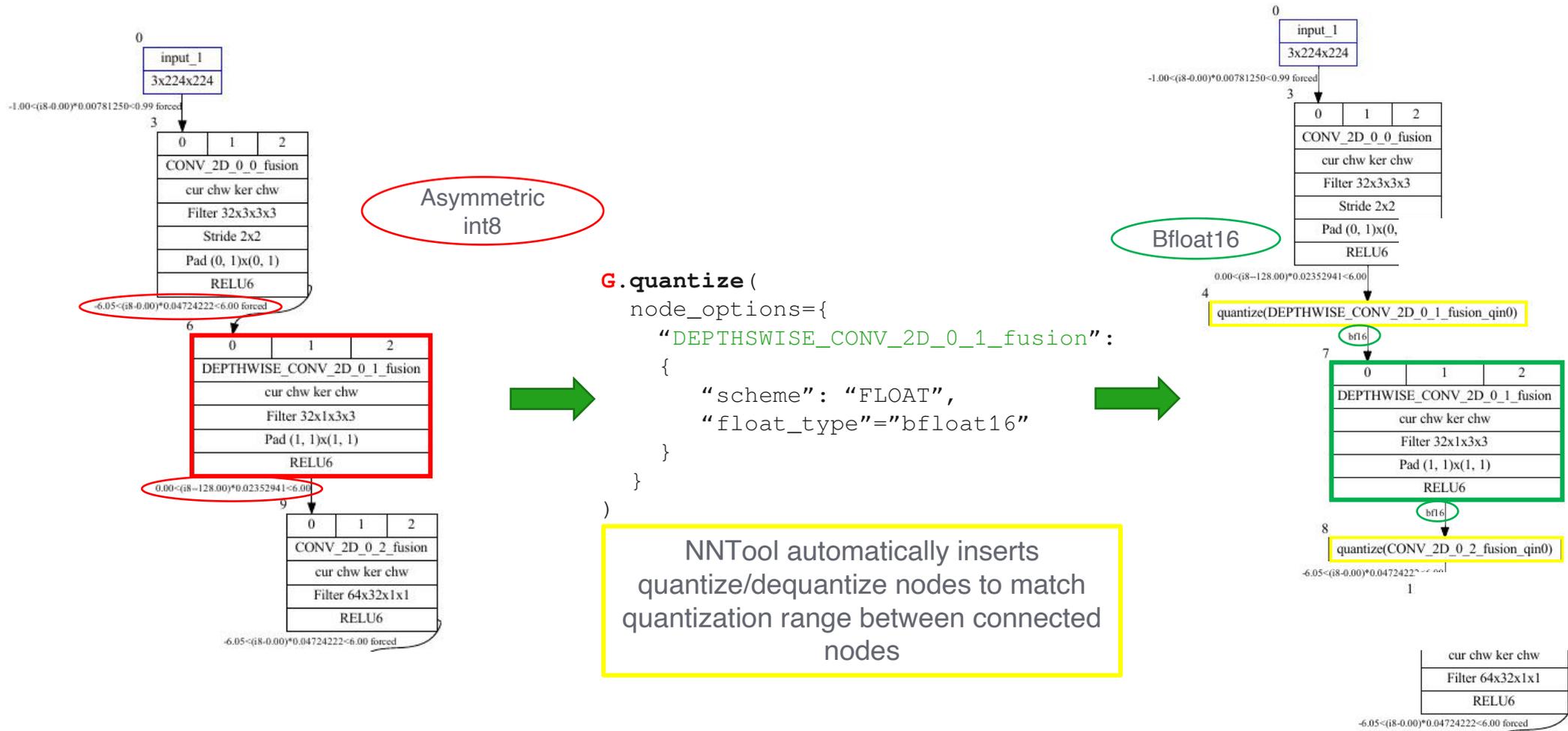
$$Y = \frac{S_x S_w}{S_y} \sum X \cdot W$$

Integer only MACs

INT8

# Mixed-Precision Quantization

GAP NNTool enables layer-wise selection of quantization scheme and number of bits



# Validation of the solution

- Check deployed model accuracy:

☹️ **On-device**: use directly the final platform to test the accuracy (**very slow**)

😊 **NNTool**: bit-accurate numpy backend, the user can test accuracy in a python environment without need of device (**fast**)

```
G = NNGraph.load_graph(file_path)
stats = G.collect_statistics(calibration_dataset)
G.quantize(stats, quantization_options)
G.adjust_order()
G.fusions("scaled_match_group")
# Ready for inference
acc1 = 0
for in_data, target in test_dataset:
    outq = G.execute(in_data, quantize=True)
    acc1 += np.argmax(outq[-1][0]) == target
```

**Prepare your model for deployment**  
(quantization+graph manipulation)

**Run inference and check results**

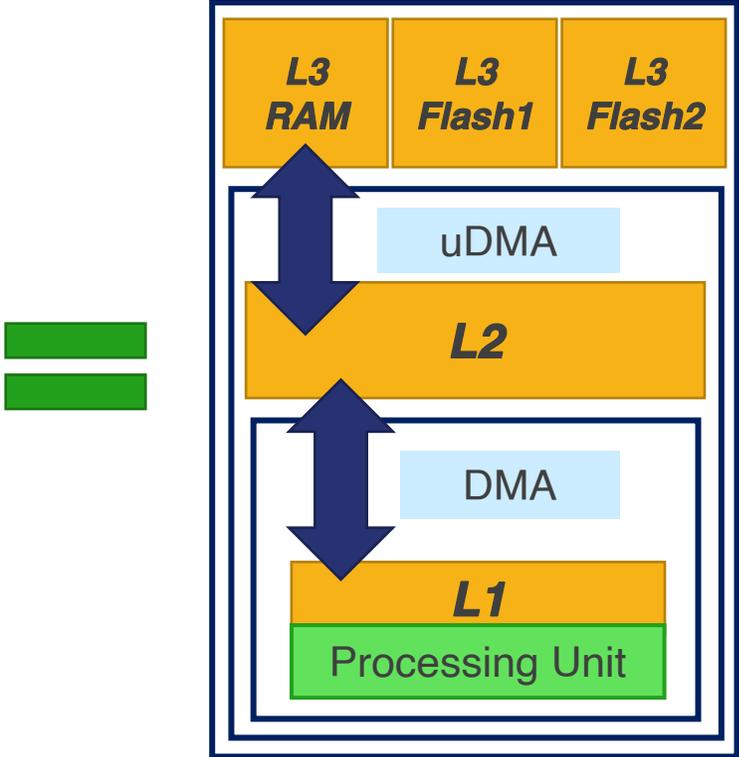
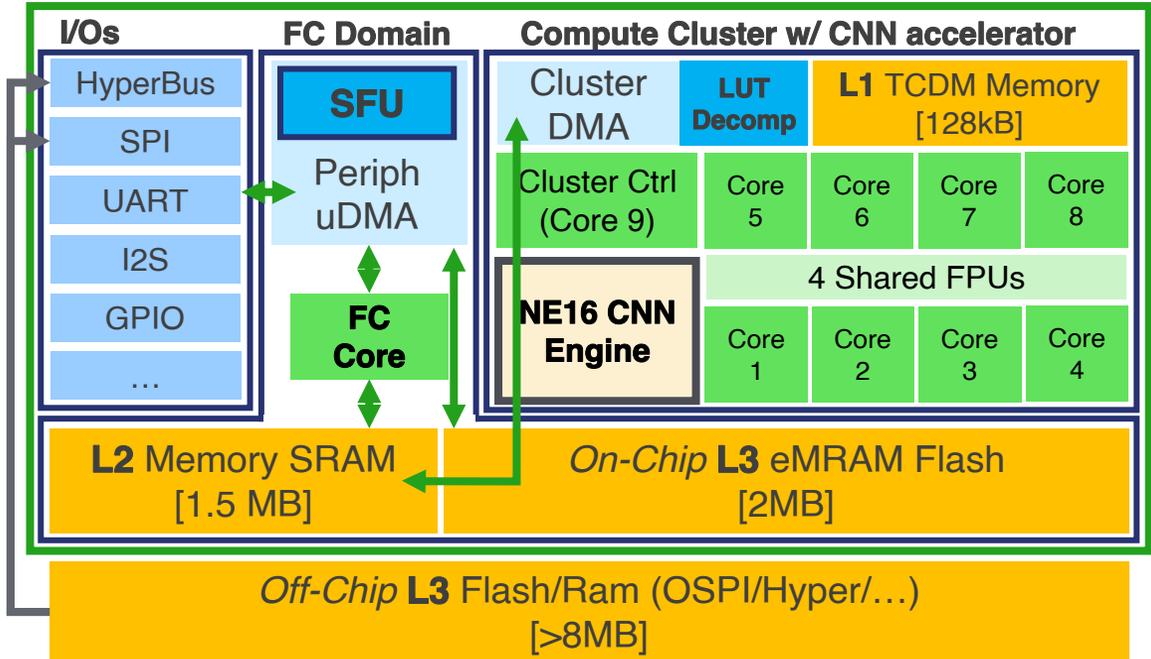
# GAP Autotiler

GAP does not have a data CACHE:

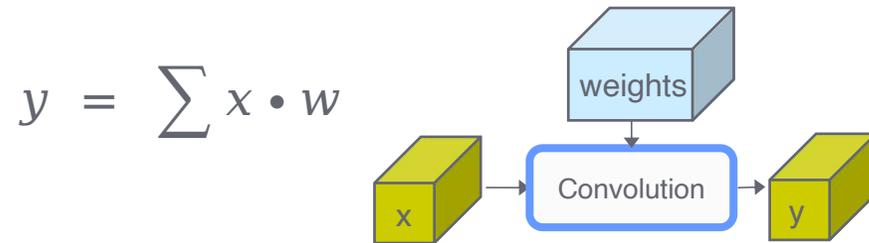
- Silicon Area
- Energy Efficiency
- NN/DSP algo have predictable data traffic



Generate C code for all data movement at compile time



# Autotiler User Kernel: NN Node to the GAP architecture



## Computation dataflow

Ahead of time

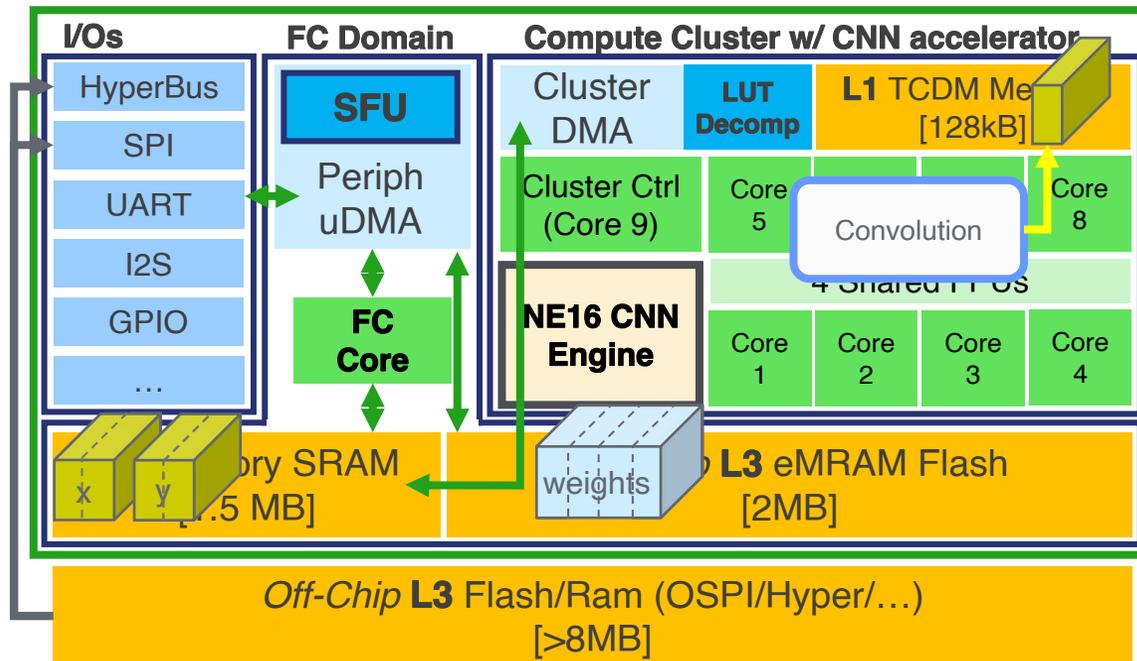
Store data (parameters & input vector) in L2 (or L3)

At run time, for any computational node:

Partition and Load data (parameters & input tensors) to L1

Run data-parallel/CNN Engine computation

Store data (output tensors) back in L2 (or L3)



```
static void Conv_Layer0
(
    signed char * In,      // input L2 vector
    signed char * Weights, // input L2 vector
    signed char * Bias,   // input L2 vector
    signed char * Out,    // output L2 vector
){
    //tile sizes of In, Weights, Bias computed offline
    //L1 buffer allocated to handle double buffering
    // two L1 memory buffers for double buffering

    DMA load first tiles to L1 memory buffer

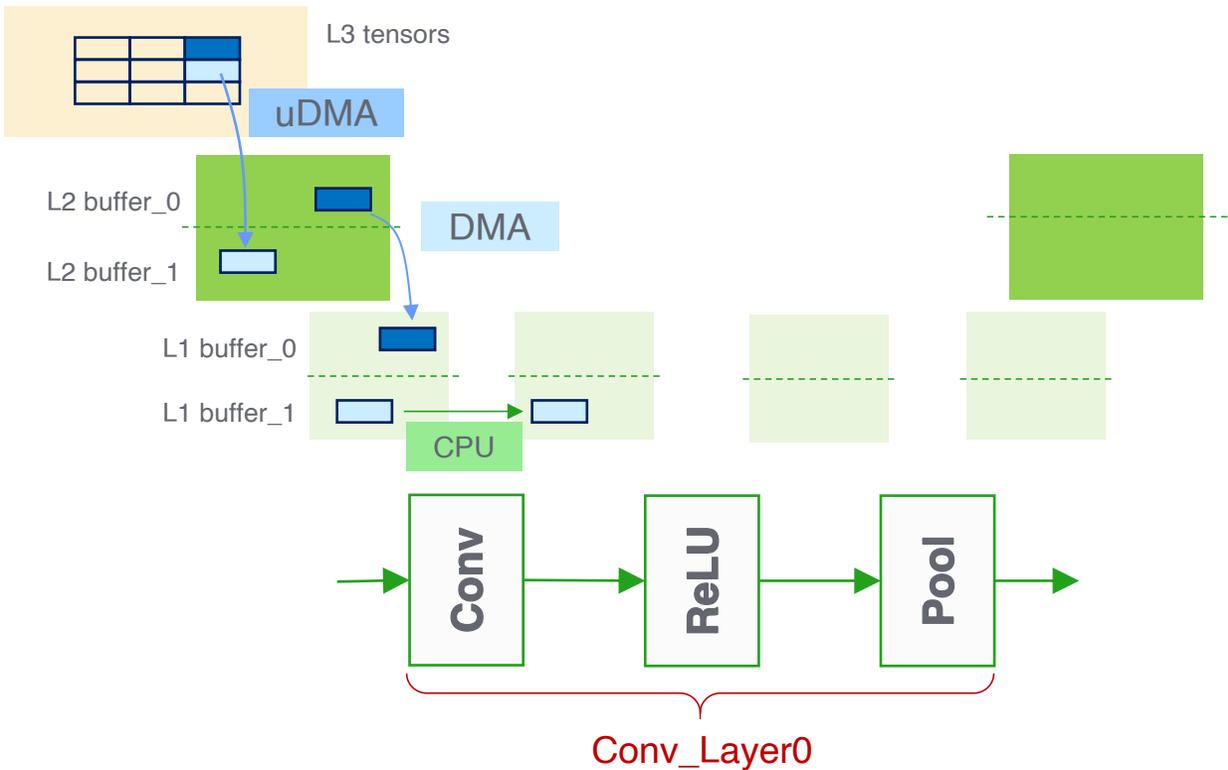
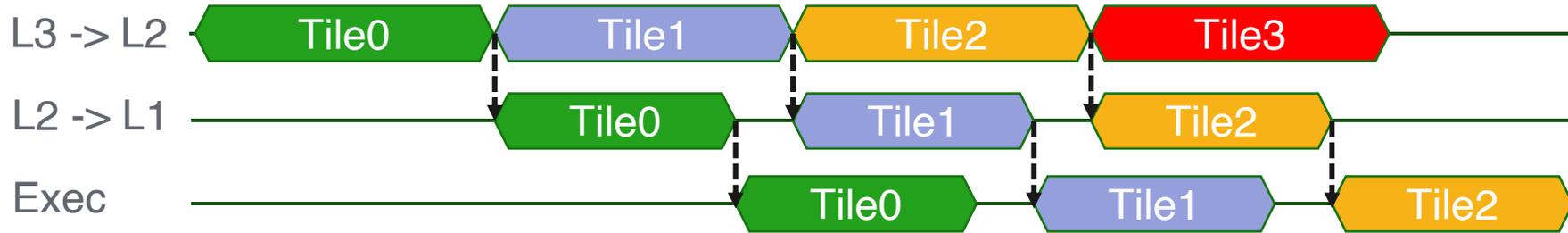
    for any tile of In, Weights, Bias tensors:

        DMA load next tiles to L1 memory buffer

        ParConv() on L1 tile
        ParReLU() on L1 tile
        ParPool() on L1 tile

        DMA write results (Out) to L2
}
```

# Mapping a NN Node to the GAP HW/SW architecture



```

static void Conv_Layer0
{
    signed char * In,      // input L3 vector
    signed char * Weights, // input L3 vector
    signed char * Bias,   // input L3 vector
    signed char * Out,    // output L3 vector
}{
    //tile sizes of In, Weights, Bias computed offline
    //L1 buffer allocated to handle double buffering
    // two L1 memory buffers for double buffering

    uDMA load first tiles to L2 memory buffer

    DMA load first tiles to L1 memory buffer

    for any tile of In, Weights, Bias tensors:

        uDMA load next next tiles to L2 memory buffer

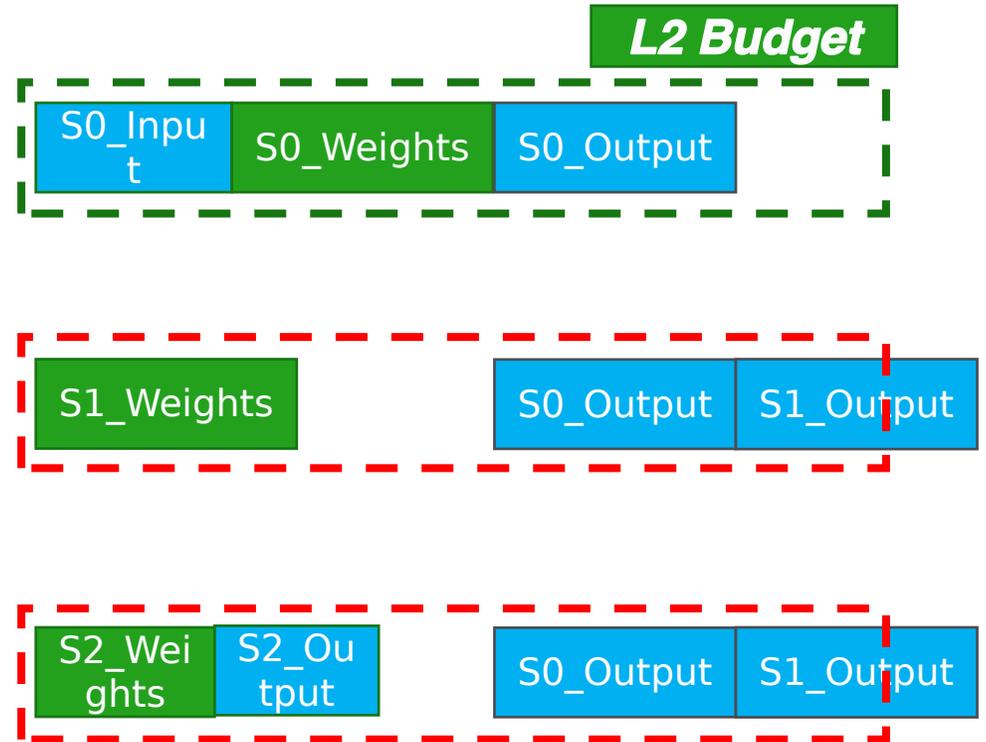
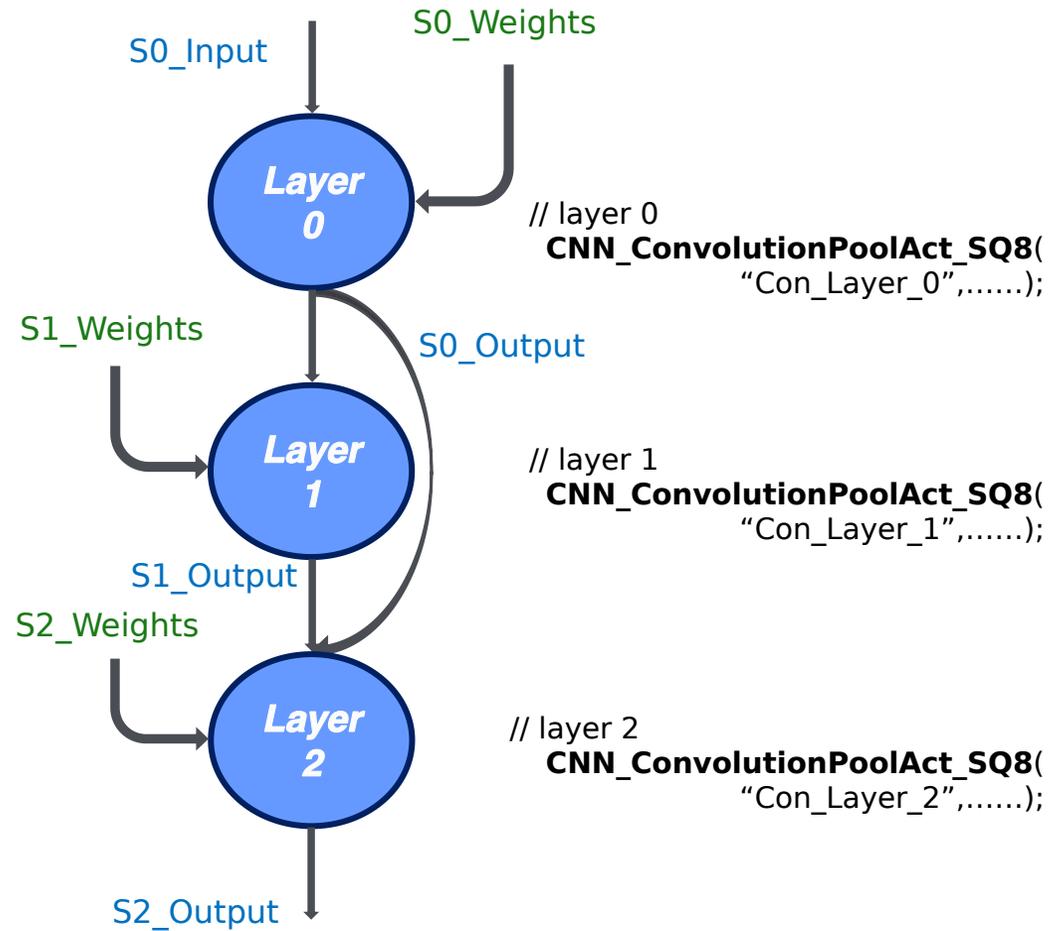
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        ParPool() on L1 tile

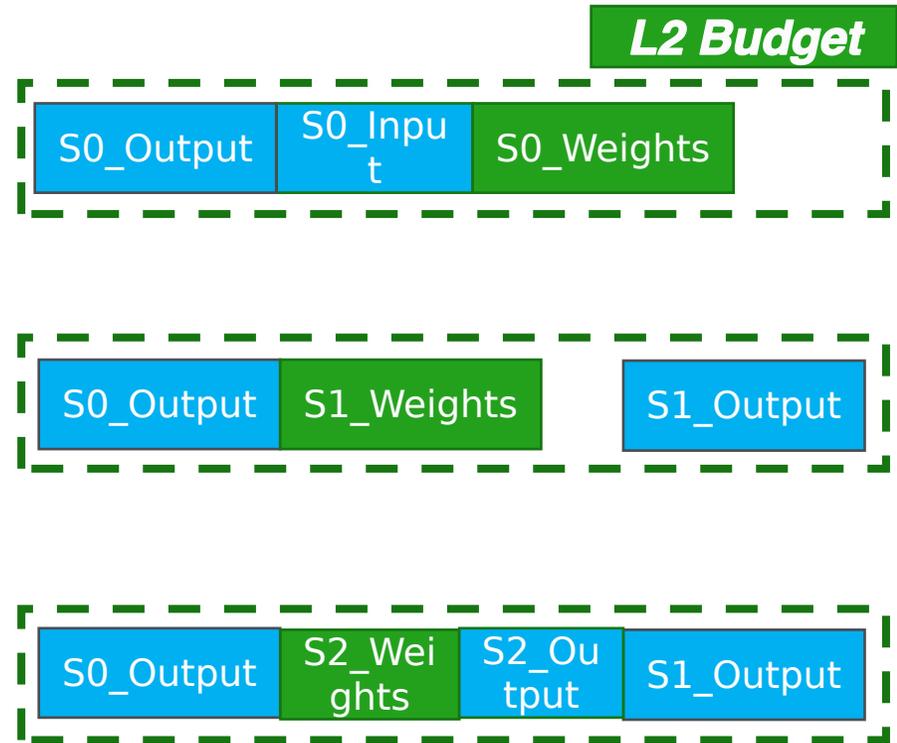
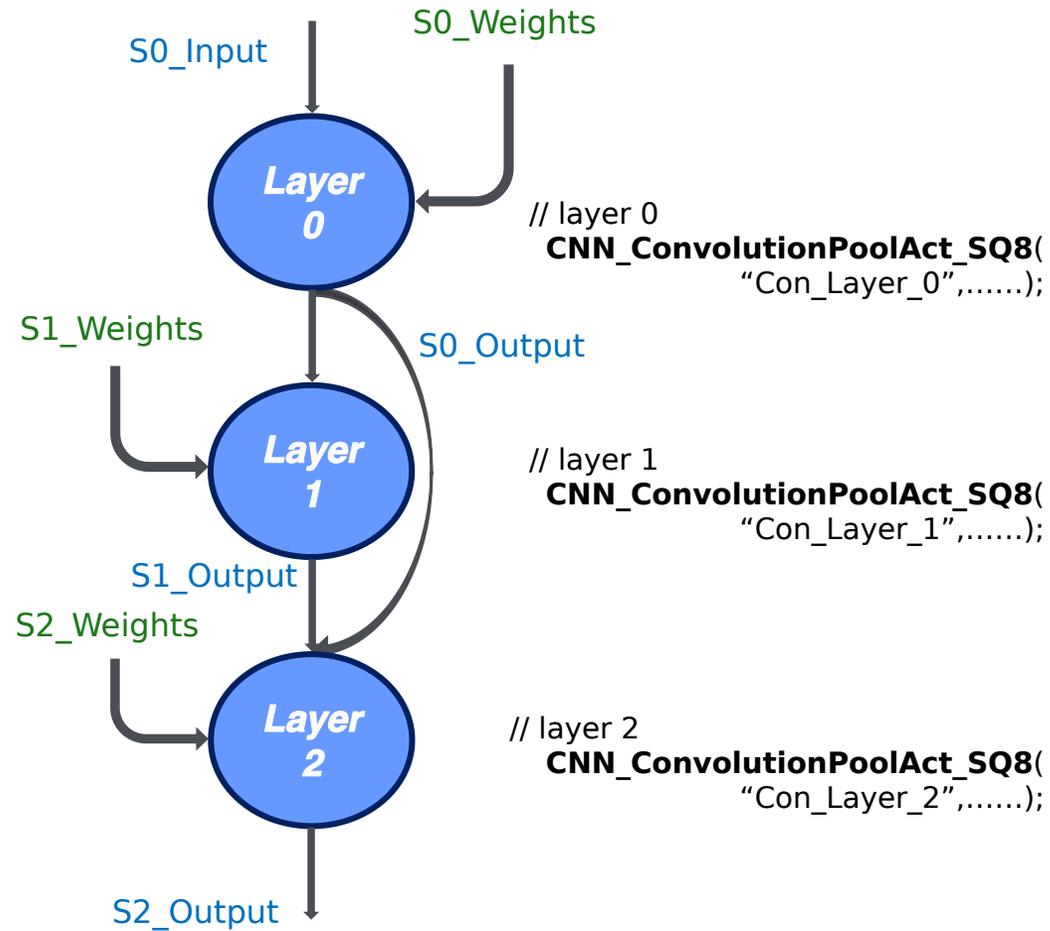
        DMA write results (Out) to L2

        uDMA write prev results to L3
}
    
```

# Autotiler Graph: Static allocation



# Autotiler Graph: Static allocation



# NN Benchmarks

	Network	# Params [M]	# MACs [M]	Latency @ 370MHz [ms]	GOPS/W @ 240MHz
Image and Audio classification and detection	MobileNet V1 224_1.0	4.27	568.9	45.89	485.38
	MobileNet V2 224_1.0	3.57	301.8	37.59	308.89
	ResNet18	11.71	1816.7	81.54	667.98
	SqueezeNet	1.25	843.4	46.14	685.49
	EfficientNetLite0	15.02	1352.9	182.92	320.10
	MCUNet	1.84	127.1	29.08	189.01
	SSD MobileNet V1 300_1.0	6.89	1258.1	93.59	504.79
	SSD MobileNet V2 300_1.0	6.17	775.8	86.11	338.02
	YamNet w/ Preprocessing	3.72	74.23	13.03	211.87
	YoloX Nano *	0.91	231.7	22.78	441.04
TinyMLPerf: Best in the market	TinyML - KWS: DSCNN	0.053	2.74	0.30	445.53
	TinyML - IC: ResNet8	0.098	12.58	0.57	978.99
	TinyML - AD: DeepAutoEncoder	0.277	0.27	0.11	151.26
	TinyML - VWW: MobileNet V1 0.25	0.333	7.72	1.05	399.28

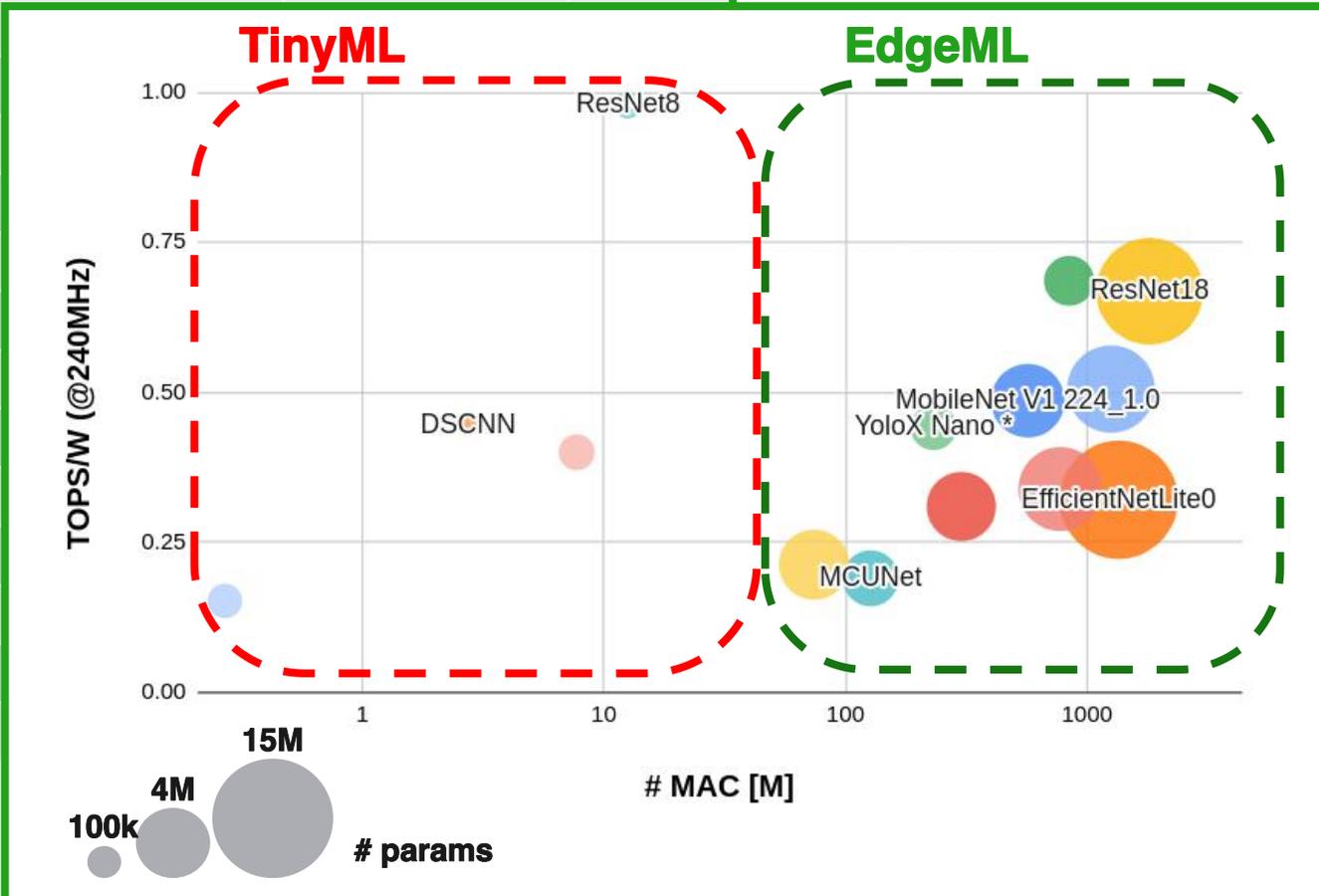
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Image and Audio classification and detection

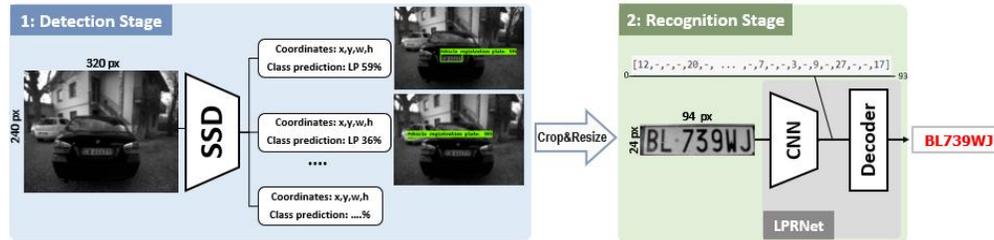
TinyMLPerf: Best in the market

>100GOPS/W across large range of NNs



# Enabling complex NN on energy constrained devices

## Multi NN – Licence Plate



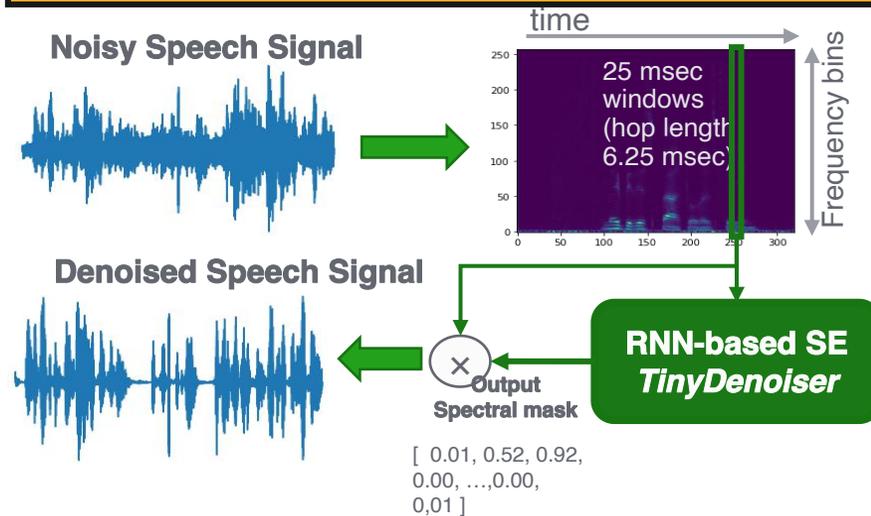
<https://ieeexplore.ieee.org/abstract/document/9401730>

## Smart glasses - object detection



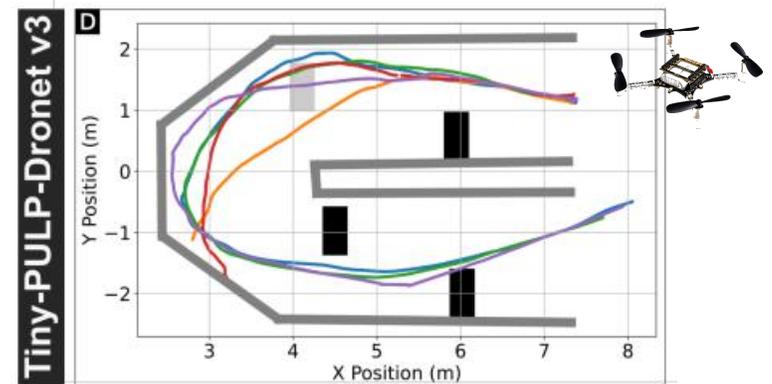
<https://arxiv.org/ftp/arxiv/papers/2311/2311.01057.pdf>

## DSP/NN Mixed-Precision – Denoiser



<https://arxiv.org/pdf/2210.07692>

## Nano drones autonomous navigation



<https://arxiv.org/pdf/2407.12675>

# Try yourself

- Contact us and get our evaluation kit board
- Tools and SW are mostly open-source:
  - <https://greenwaves-technologies.com/tools-and-software/>
  - [https://greenwaves-technologies.com/manuals\\_gap9/gap9\\_sdk\\_doc/html/](https://greenwaves-technologies.com/manuals_gap9/gap9_sdk_doc/html/)
- Lot of application and example to start your work  
(write us an email or sign in the website to access our SDK)



# Thank you!

# NN Benchmarks

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**>10GOPS** across large range of NNs

Image and Audio classification and detection

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SSD MobileNet V1 300_1.0
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