

## Foundations [1,2]

The **New Physics Learning Machine** is a methodology powered by machine learning to perform a likelihood-ratio goodness-of-fit test with data-driven hypotheses. The goal is to assess how well a reference model  $R$ , seen as a generator, fits a set of observations. A supervised classifier is trained on a *reference sample*

$$\mathcal{R} = \{x_i\}_{i=1}^{N_{\mathcal{R}}}, \quad x_i \sim p(x|R),$$

and a *data sample*

$$\mathcal{D} = \{x_i\}_{i=1}^{N_{\mathcal{D}}}, \quad x_i \sim p_{\text{true}}(x),$$

to approximate the true density ratio

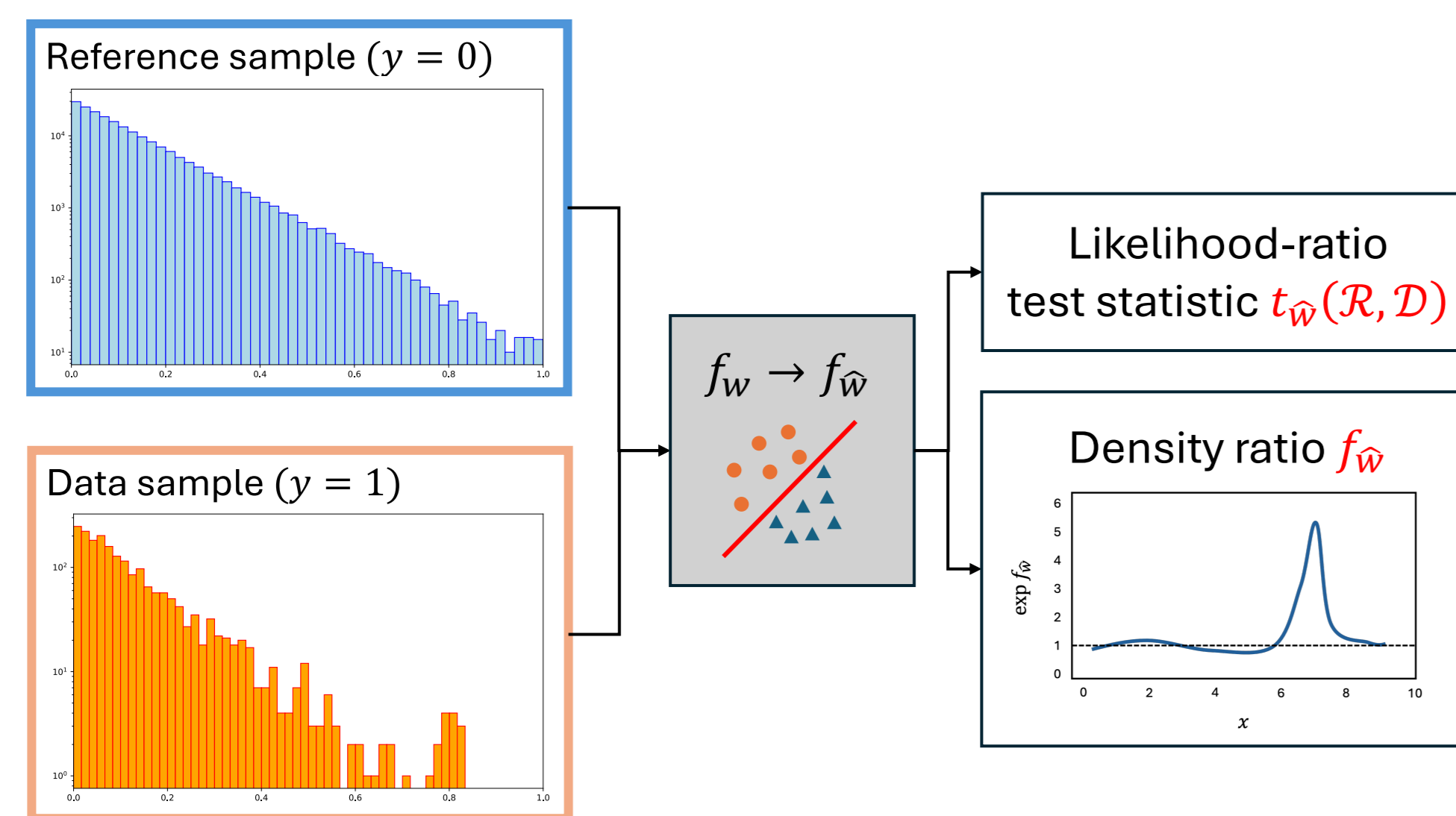
$$f_{\hat{w}}(x) \approx f^*(x) = \log \frac{p_{\text{true}}(x)}{p(x|R)}, \quad \hat{w} \text{ learned optimal parameters.}$$

Rather than using standard metrics such as accuracy, the model is evaluated in-sample with a metric derived from the (extended) likelihood-ratio

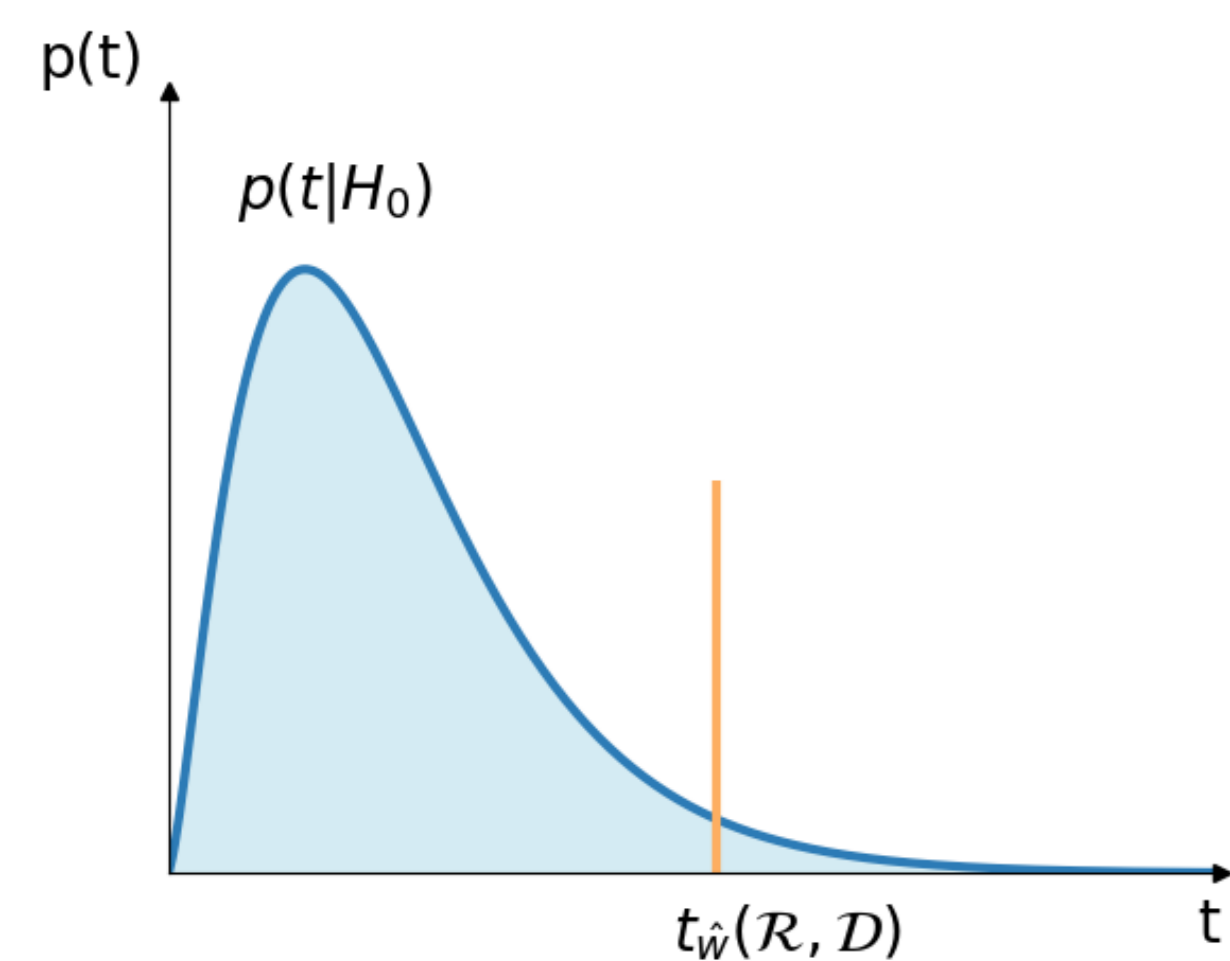
$$t_{\hat{w}}(\mathcal{R}, \mathcal{D}) = -2 \left[ \sum_{x \in \mathcal{R}} \frac{N(R)}{N_{\mathcal{R}}} (e^{f_{\hat{w}}(x)} - 1) - \sum_{x \in \mathcal{D}} f_{\hat{w}}(x) \right],$$

where  $N(R)$  is the expected number of events under the reference model.

The test is sensitive to both *distribution and normalisation shifts*.



The null hypothesis is estimated empirically by training and evaluating NPLM on the reference model against itself, to perform a goodness-of-fit test.



$$p_{\text{value}} = \int_{t_{\hat{w}}(\mathcal{R}, \mathcal{D})}^{\infty} dt p(t|H_0)$$

$$Z = \Phi^{-1}(1 - p_{\text{value}})$$

We focus on the implementation based on kernel methods and the Falcon library, highly performant while extremely efficient.<sup>[3]</sup> It is based on the (regularised) weighted logistic loss

$$\ell(y, f_w(x)) = \frac{N(R)}{N_{\mathcal{R}}} (1 - y) \log(1 + e^{f_w(x)}) + y \log(1 + e^{-f_w(x)}),$$

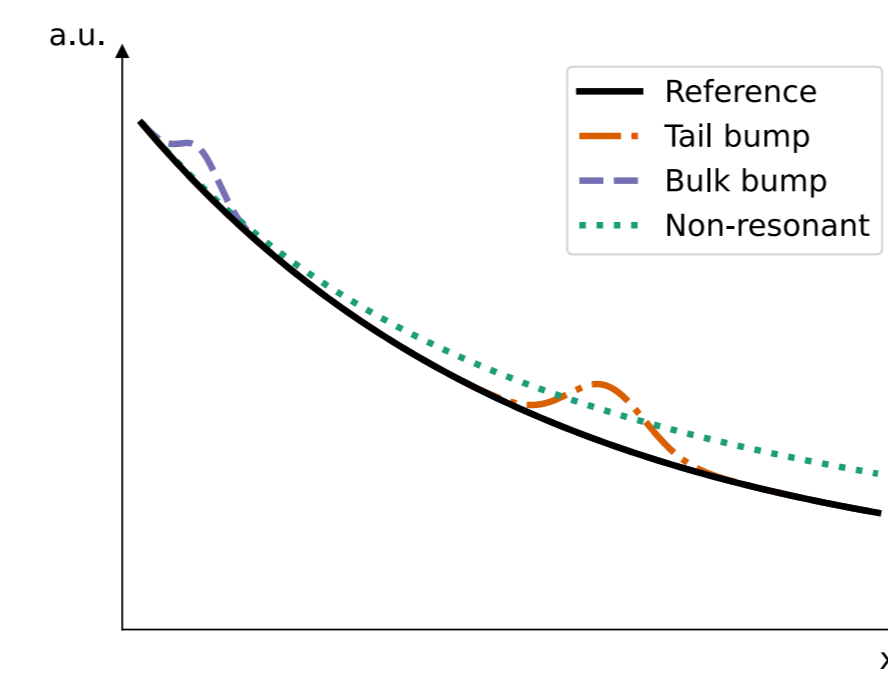
and considers functions of the following form

$$f_w(x) = \sum_{i=1}^N w_i k(x, x_i), \quad k(x, x') = \exp -\frac{\|x - x'\|^2}{2\sigma^2},$$

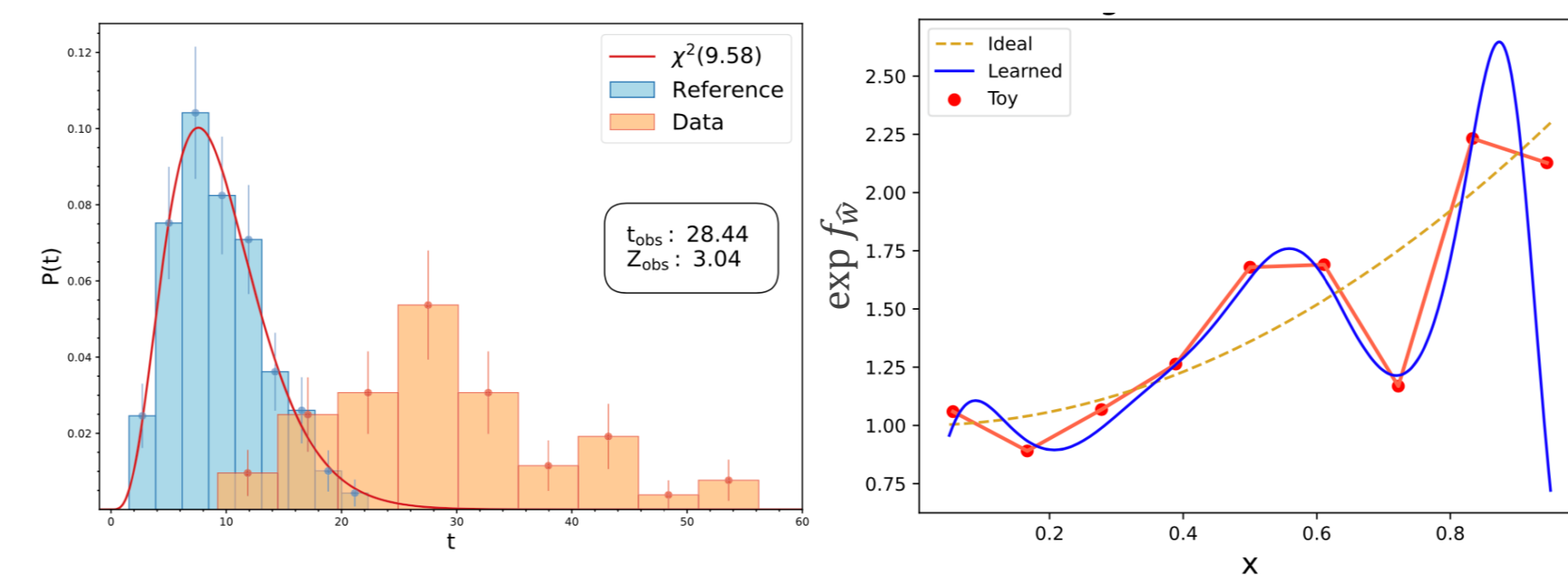
where  $\sigma$  is the width of the gaussian kernel, a hyperparameter.

## Signal-agnostic searches [2]

### 1D benchmark



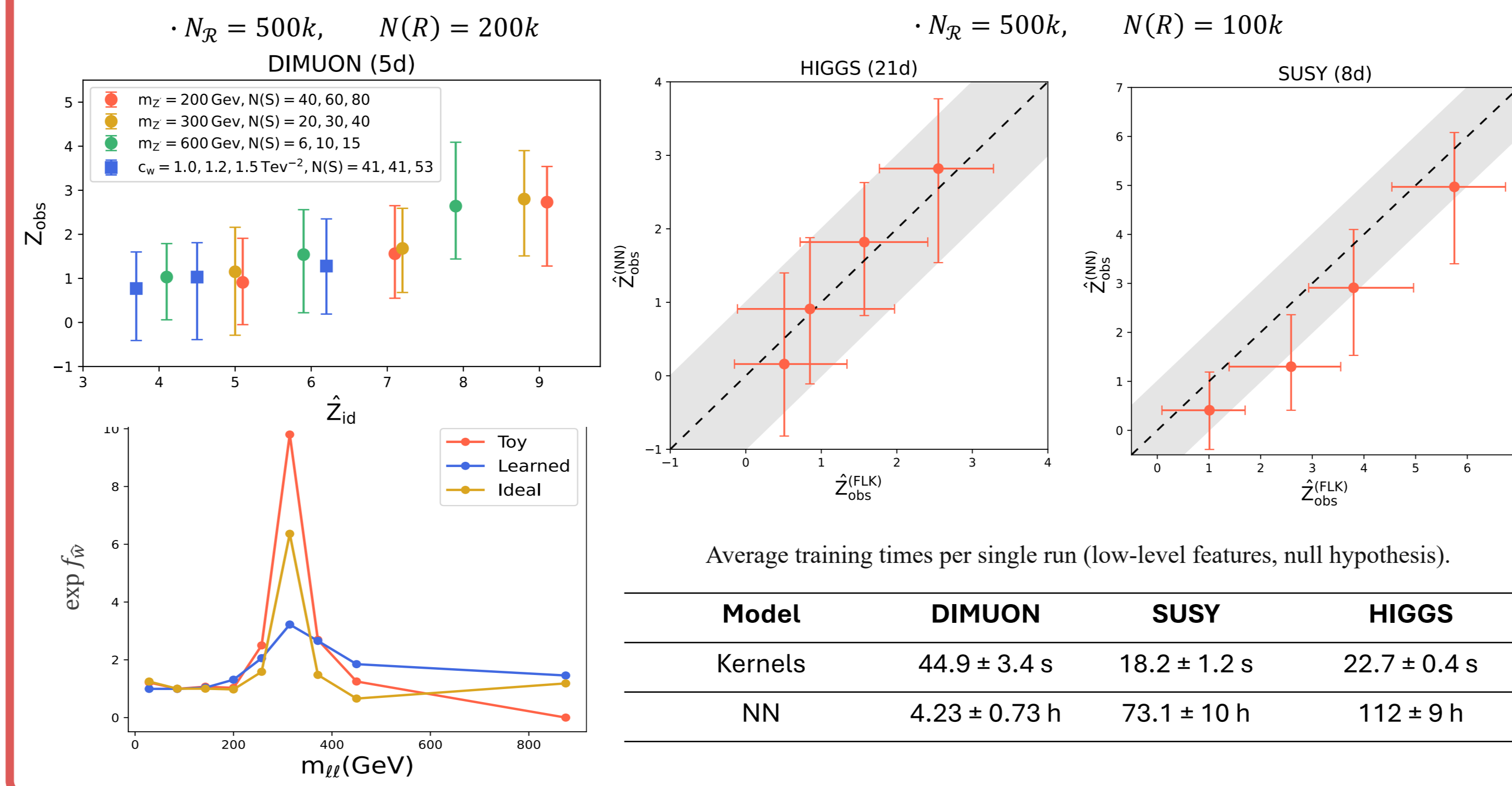
Distribution of the test statistic and signal reconstruction for the non-resonant signal.



- $N_{\mathcal{R}} = 200k$ ,  $N(R) = 2000$
- $N(S) = 10$  (tail), 90 (bulk/non-res)
- $\bar{t}_{\text{training}} \approx 2$  sec

	Median Z	Tail	Non-res	Bulk
$Z_{\text{id}}$	4.7	4.4	4.1	
$Z_{\text{obs}}$	2.4	3.0	2.8	

### Multivariate benchmarks

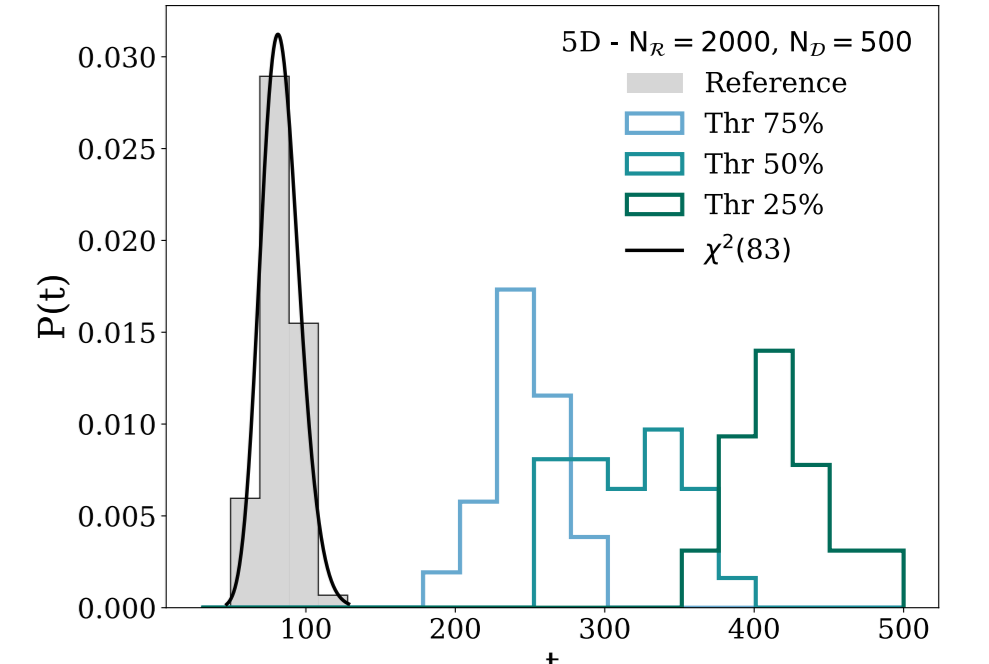
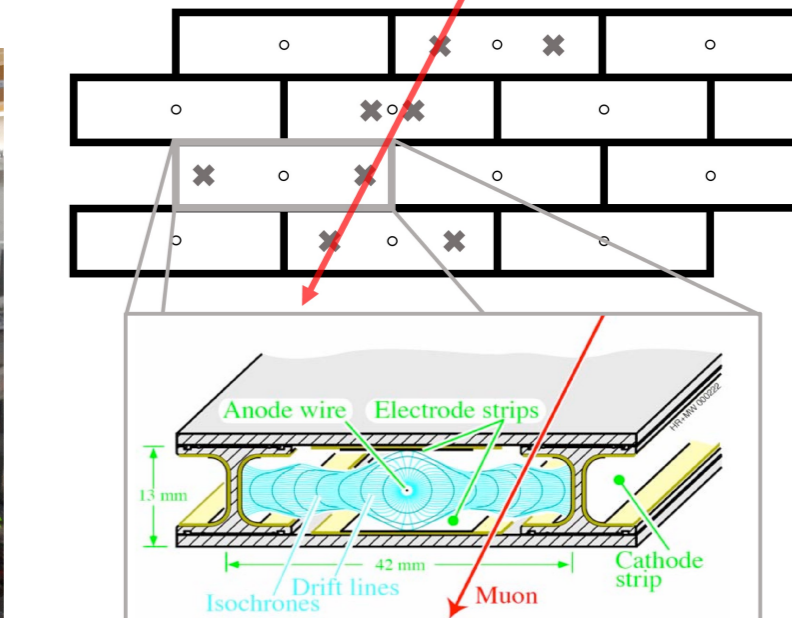


## Data Quality Monitoring [5]

NPLM for monitoring particle detectors in real-time.

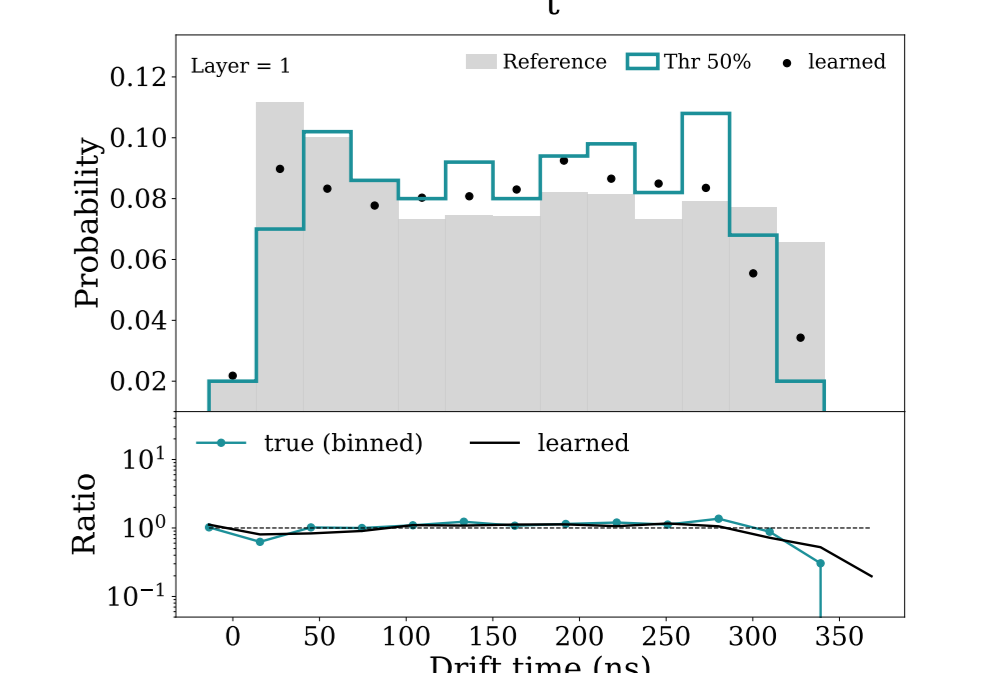
Reduced scale CSM drift tubes; features: 4 drift times + crossing angle;  $\bar{t}_{\text{training}} \approx 0.5$  sec;

anomalies: lowered cathodic voltages and front-end thresholds.



Anomaly	NPLM (5D)	KS ( $t_1$ )	KS ( $t_2$ )	KS ( $t_3$ )	KS ( $t_4$ )	KS ( $\phi$ )
Cathode 75%	$1.1 \times 10^{-6}$	0.50	0.41	0.43	0.40	0.42
Cathode 50%	$3.4 \times 10^{-4}$	0.47	0.27	0.47	0.37	0.41
Cathode 25%	0.0019	0.45	0.44	0.13	0.45	0.50
Threshold 75%	$< 10^{-7}$	0.23	0.14	0.16	0.14	0.48
Threshold 50%	$< 10^{-7}$	0.09	0.10	0.06	0.17	0.42
Threshold 25%	$< 10^{-7}$	0.11	0.07	0.04	0.11	0.66

Median  $p$ -values.



## Multiple testing [6]

Model selection can bias the test towards certain signal hypotheses. Multiple testing strategies can tame this effect for a more uniform response.

- min- $p$ :  $p_{\text{min}} = -\log \min_{1 \leq i \leq n} p_i$
- avg- $p$ :  $p_{\text{avg}} = -\frac{1}{n} \sum_{1 \leq i \leq n} p_i$
- prod- $p$ :  $p_{\text{prod}} = -\sum_{1 \leq i \leq n} \log p_i$
- smax- $t$ :  $t_{\text{smax}} = \log \frac{1}{n} \sum_{1 \leq i \leq n} e^{t_i}$

Different tests are characterized by different kernel widths.

N(S)	7	18	13	10	90
$\bar{x}_{\text{NP}}$	4	4	4	6.4	1.6
$\sigma_{\text{NP}}$	0.01	0.16	0.64	0.16	0.16

$\sigma = 0.01$	0.0028 ± 0.0008	0.0010 ± 0.0006	0.0005 ± 0.0004	0.0001 ± 0.0001	0.029 ± 0.004
$\sigma = 0.3$	<b>0.012 ± 0.002</b>	0.107 ± 0.007	0.008 ± 0.002	0.246 ± 0.009	0.65 ± 0.01
$\sigma = 0.7$	0.006 ± 0.001	<b>0.123 ± 0.007</b>	<b>0.011 ± 0.002</b>	<b>0.36 ± 0.01</b>	<b>0.70 ± 0.01</b>
$\sigma = 1.4$	0.004 ± 0.001	0.078 ± 0.006	<b>0.012 ± 0.002</b>	0.29 ± 0.01	0.54 ± 0.01
$\sigma = 4.5$	0.0023 ± 0.0007	0.020 ± 0.003	<b>0.011 ± 0.002</b>	0.098 ± 0.007	0.28 ± 0.01
$\sigma = 9.0$	0.0028 ± 0.0008	0.018 ± 0.003	<b>0.012 ± 0.002</b>	0.075 ± 0.006	0.24 ± 0.01
$\sigma = 2.3$	0.0023 ± 0.0007	0.044 ± 0.005	0.013 ± 0.002	0.028 ± 0.004	0.36 ± 0.01
min- $p$	<b>0.008 ± 0.001</b>	<b>0.103 ± 0.007</b>	0.007 ± 0.002	<b>0.32 ± 0.01</b>	<b>0.66 ± 0.01</b>
prod- $p$	0.005 ± 0.001	0.083 ± 0.006	<b>0.012 ± 0.002</b>	0.26 ± 0.01	0.65 ± 0.01
avg- $p$	0.006 ± 0.001	0.049 ± 0.005	0.011 ± 0.002	0.068 ± 0.006	0.50 ± 0.01
smax- $t$	0.0028 ± 0.0008	0.0010 ± 0.0006	0.0005 ± 0.0004	0.0001 ± 0.0001	0.029 ± 0.004

Table 1: EXPO 1D – probability of observing  $Z \geq 3$ .

test	Z' M = 180 GeV W = 0.02 GeV	Z' M = 300 GeV W = 15 GeV	Z' M = 600 GeV W = 30 GeV	EFT $c_w = 1.5 \times 10^{-6}$
$\sigma = 0.31$	0.007 ± 0.003	0.004 ± 0.002	0.0010 ± 0.0008	0.0010 ± 0.0008
$\sigma = 1.19$	<b>0.096 ± 0.009</b>	0.10 ± 0.01	0.006 ± 0.002	0.017 ± 0.004
$\sigma = 1.79$	0.065 ± 0.008	0.11 ± 0.01	0.012 ± 0.003	0.026 ± 0.005
$\sigma = 2.49$	0.036 ± 0.006	0.11 ± 0.01	0.027 ± 0.005	0.053 ± 0.007
$\sigma = 4.23$	0.037 ± 0.006	<b>0.13 ± 0.01</b>	<b>0.066 ± 0.008</b>	0.13 ± 0.01
$\sigma = 8.0$	0.023 ± 0.004	0.068 ± 0.008	0.056 ± 0.007	<b>0.22 ± 0.01</b>
$\sigma = 3.0$	0.031 ± 0.005	0.13 ± 0.01	0.044 ± 0.006	0.092 ± 0.009
min- $p$	0.065 ± 0.008	0.16 ± 0.01	<b>0.057 ± 0.007</b>	<b>0.23 ± 0.01</b>
prod- $p$	0.089 ± 0.009	<b>0.18 ± 0.01</b>	0.028 ± 0.005	0.083 ± 0.009
avg- $p$	<b>0.14 ± 0.01</b>	0.15 ± 0.01	0.035 ± 0.006	0.098 ± 0.009
smax- $t$	<b>0.017 ± 0.003</b>	0.004 ± 0.002	0.0010 ± 0.0008	0.0010 ± 0.0008

Table 3: MUMU 5D – Probability of observing  $Z \geq 3$ .

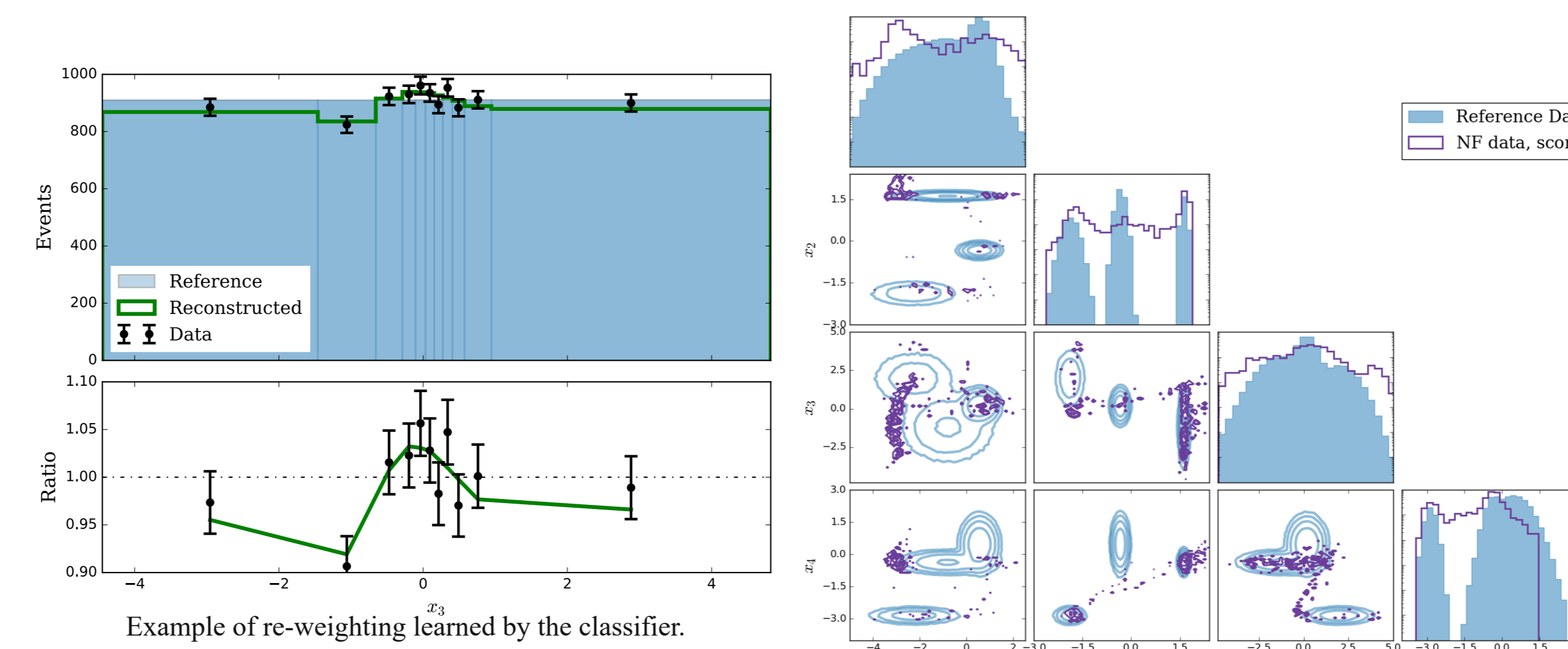
## Evaluation of generative models [4]

The efficiency of the kernel-based model opens the door to several applications.

- RealNVP on correlated mixtures of Gaussians.
- NPLM test :  $N_{\mathcal{R}}=100k$ ;  $N_{\mathcal{D}}=10k$ .

$N_{\text{tr}}$ \ $d$	4	8	12	16	20	30
100k	9.88 <sup>+1.22</sup> <sub>-1.29</sub>	8.88 <sup>+1.12</sup> <sub>-1.19</sub>	14.73 <sup>+1.23</sup> <sub>-0.94</sub>	16.81 <sup>+1.04</sup> <sub>-1.06</sub>	14.46 <sup>+1.09</sup> <sub>-0.84</sub>	14.97 <sup>+1.09</sup> <sub>-0.84</sub>
200k	4.79 <sup>+1.00</sup> <sub>-1.07</sub>	9.90 <sup>+0.94</sup> <sub>-1.05</sub>	9.56 <sup>+1.04</sup> <sub>-1.04</sub>	8.34 <sup>+0.96</sup> <sub>-1.09</sub>	6.45 <sup>+0.97</sup> <sub>-1.07</sub>	7.32 <sup>+0.90</sup> <sub>-0.81</sub>
500k	1.93 <sup>+1.02</sup> <sub>-0.99</sub>	3.01 <sup>+0.74</sup> <sub>-1.13</sub>	3.16 <sup>+1.10</sup> <sub>-1.02</sub>	5.05 <sup>+1.02</sup> <sub>-0.99</sub>	2.07 <sup>+0.81</sup> <sub>-0.97</sub>	3.06 <sup>+1.13</sup> <sub>-0.86</sub>

Median significance at varying dimensionality and number of training examples.



Using the classifier score to identify mismodeled correlations.