

# Statistics of generative models for the LHC



DALL-E

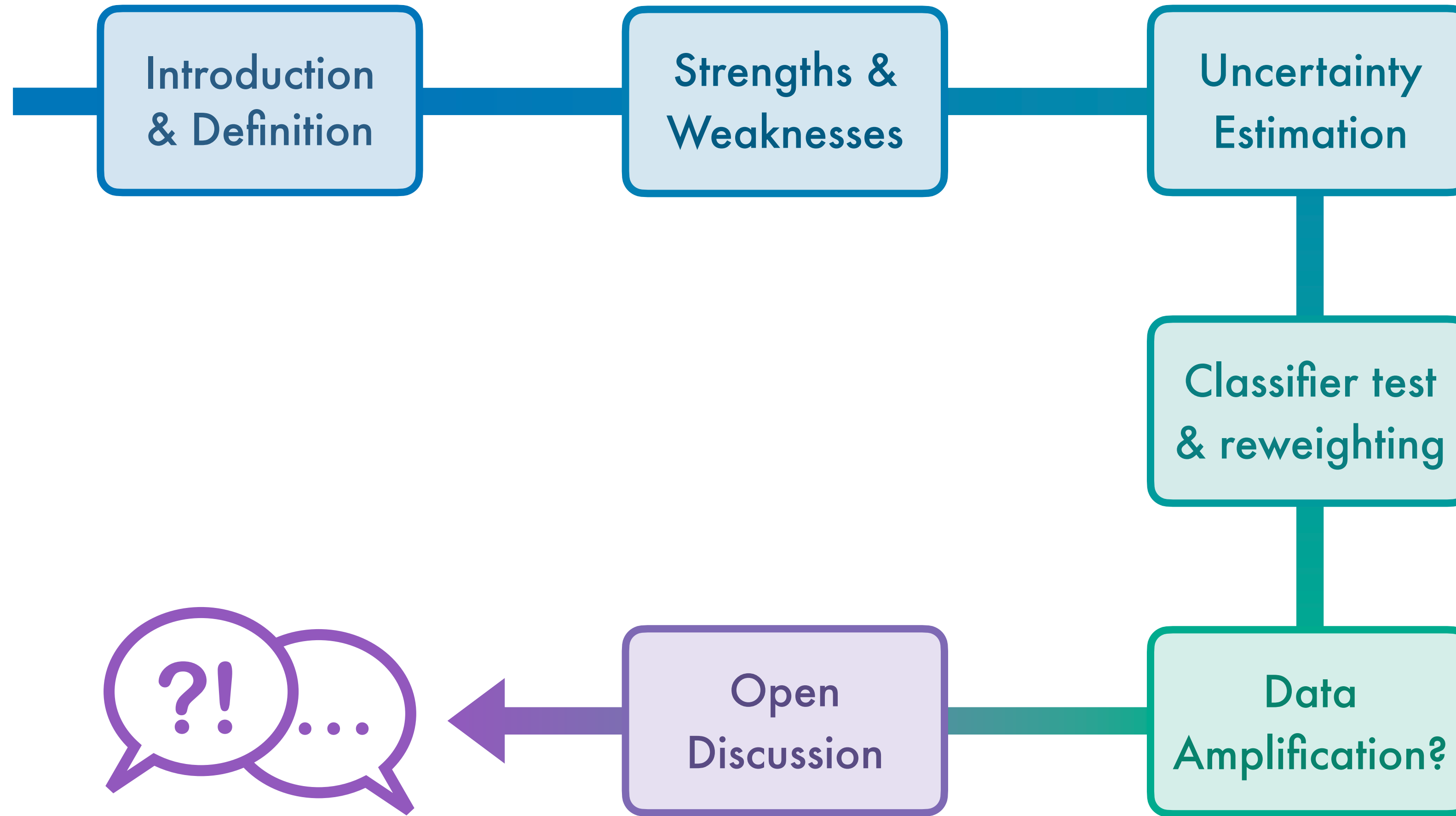


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DEGLI STUDI  
DI MILANO

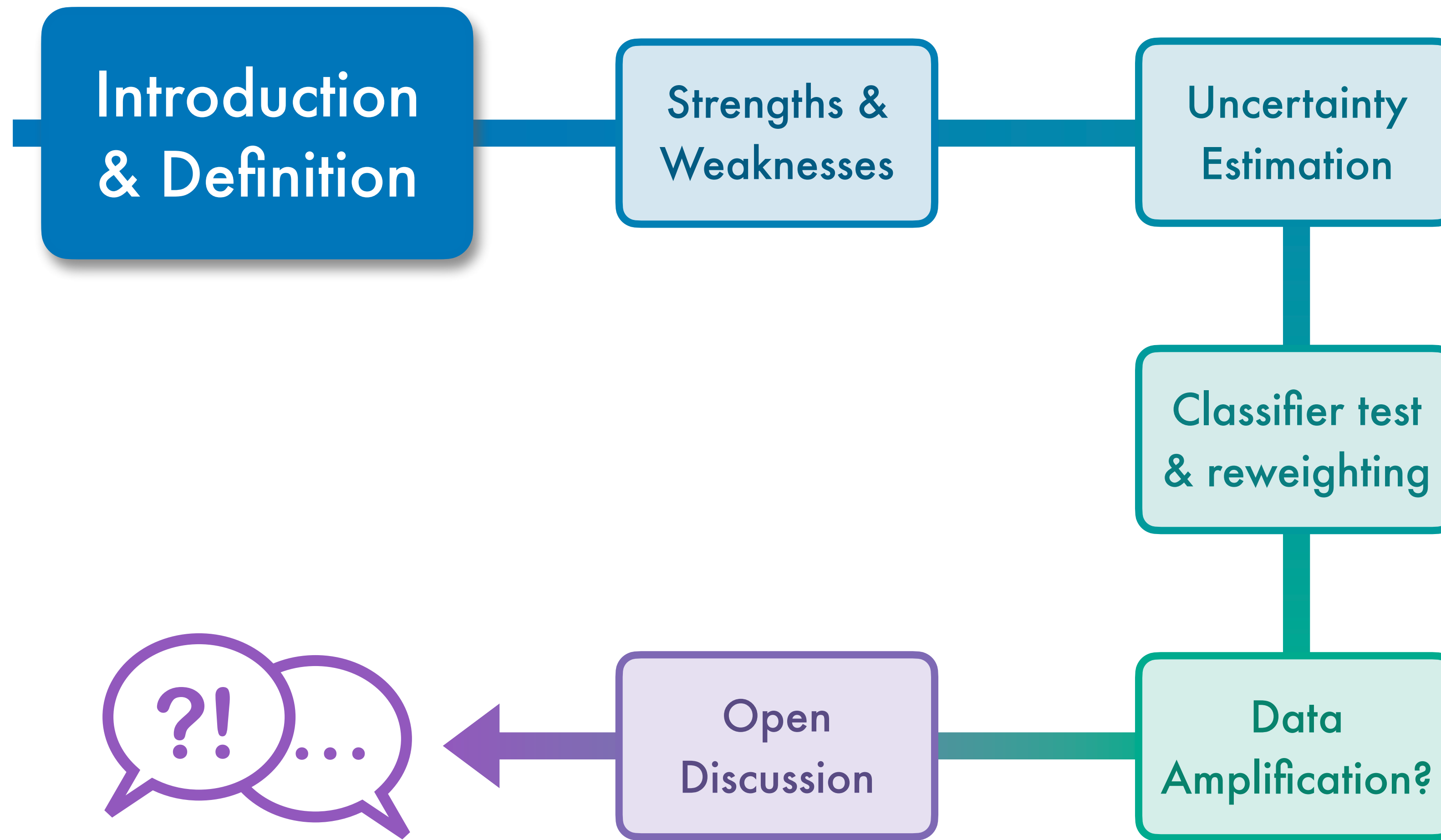
PHYSTAT — Statistics meets ML | Imperial College London

Ramon Winterhalder — UniMi

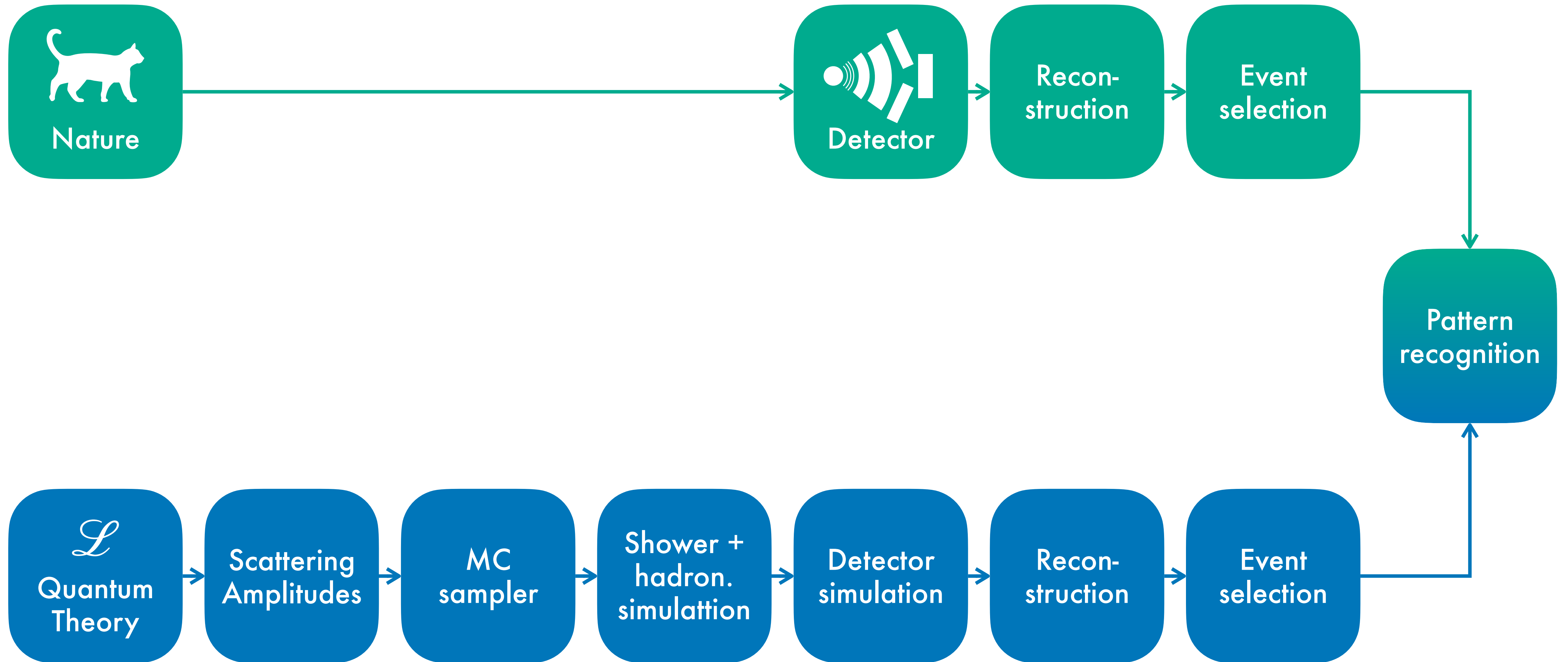
# Deep Generative Models



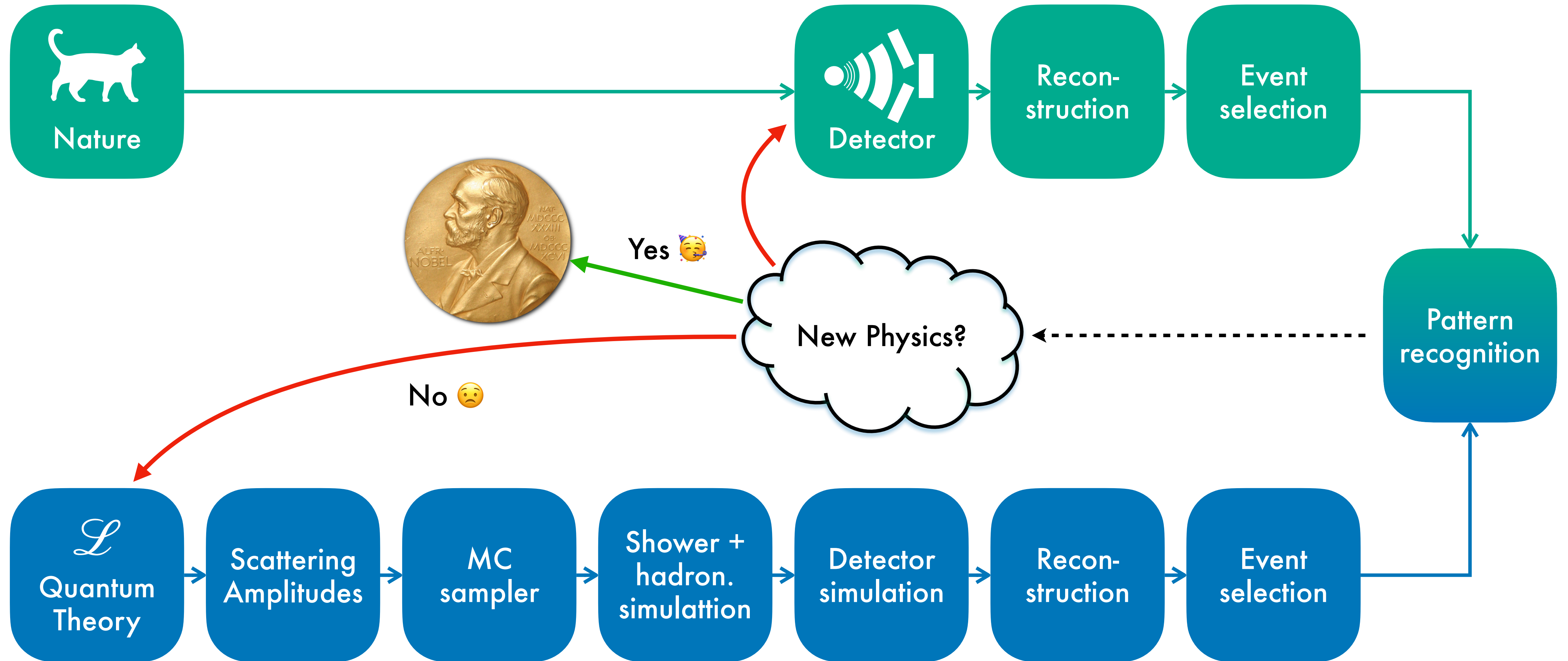
# Introduction & Definition



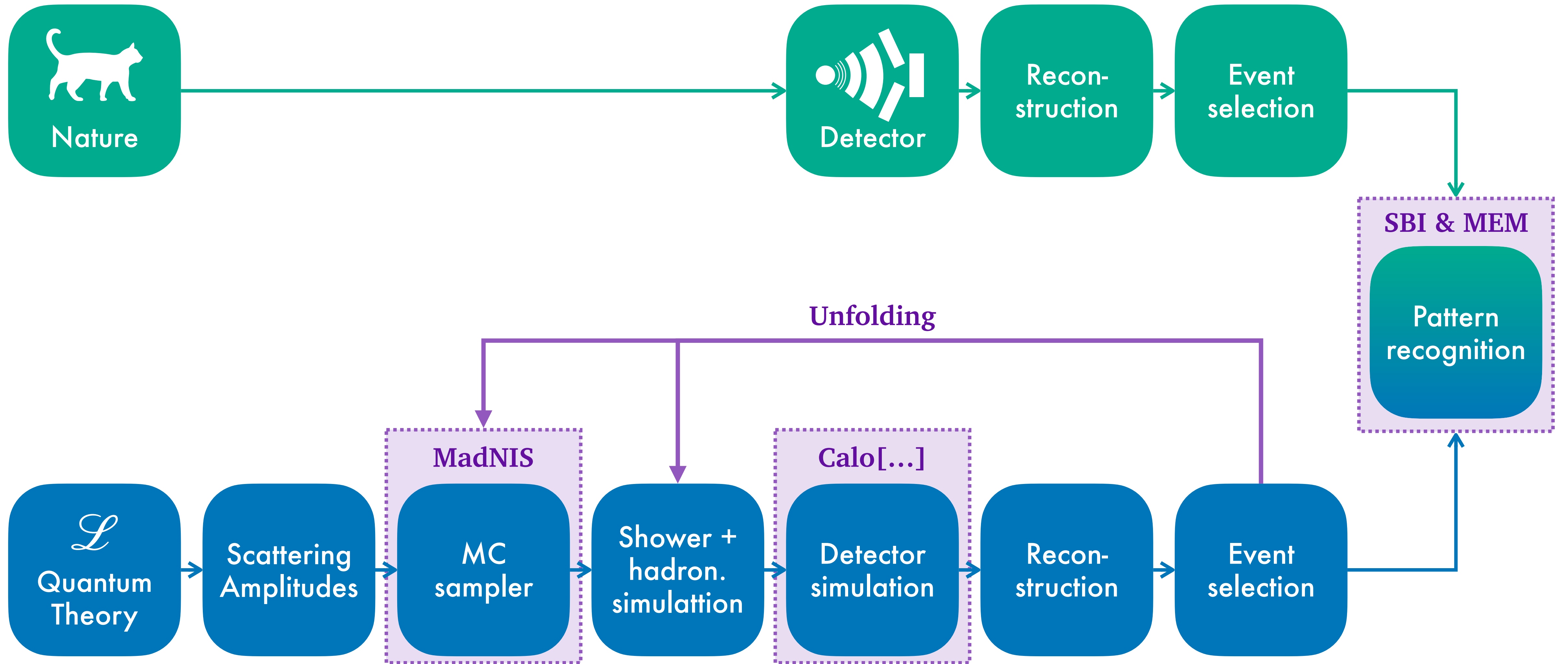
# LHC analysis (oversimplified)



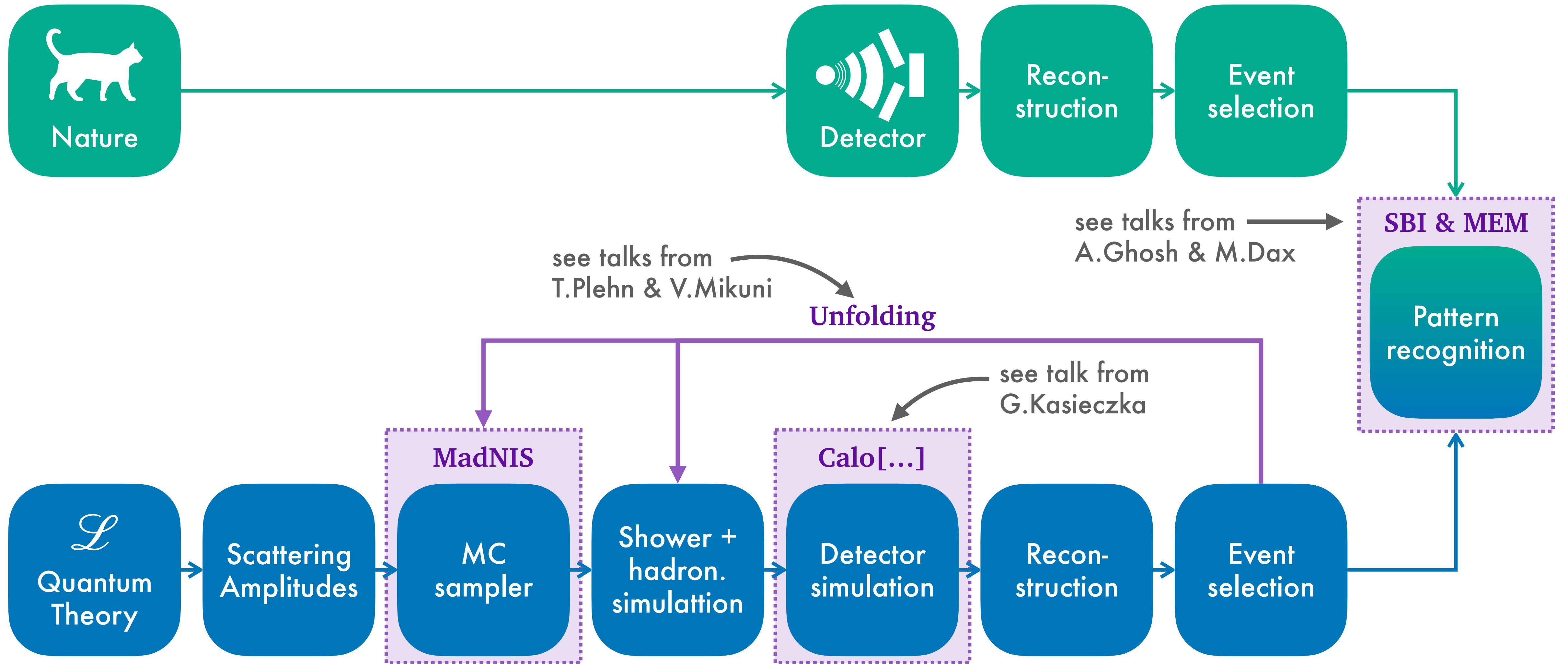
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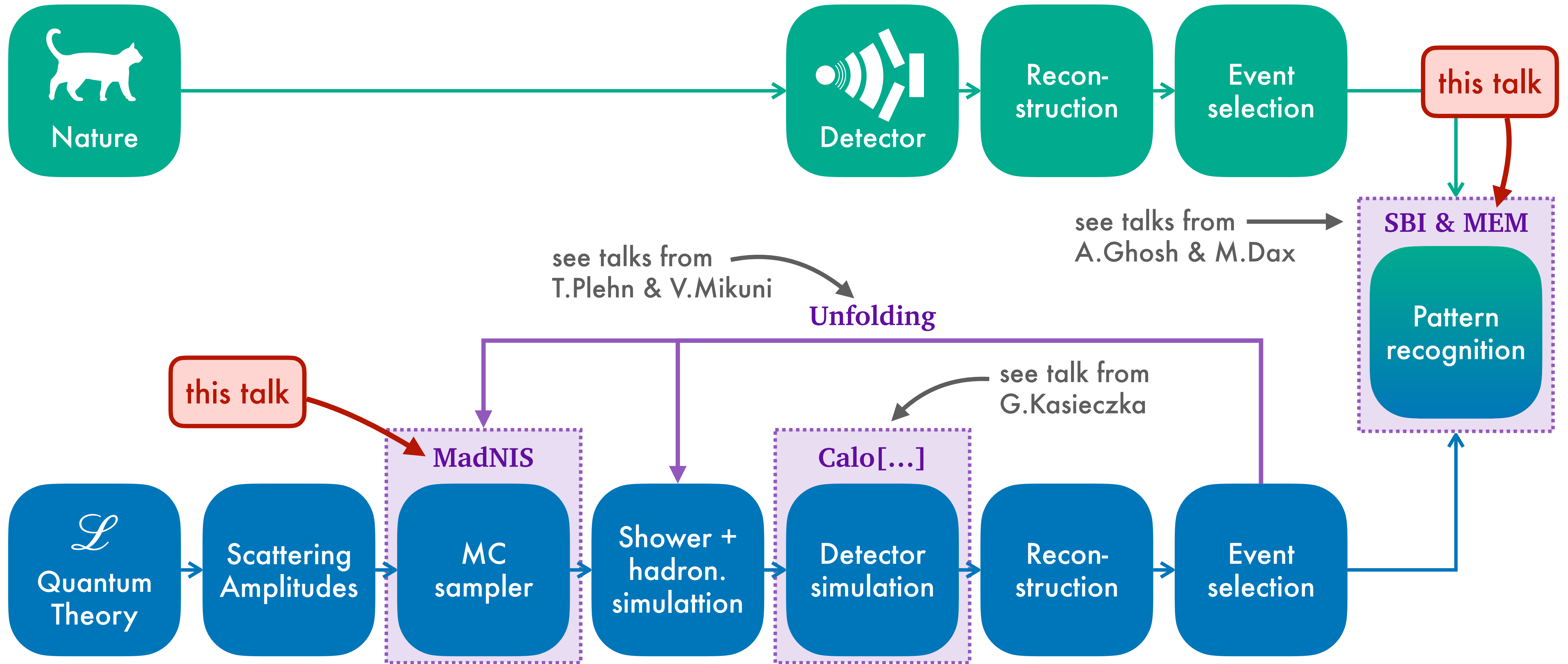
# LHC analysis + DGMs



# LHC analysis + DGMs



# LHC analysis + DGMs





# Deep Generative Models

## GAN



GAN Art (2018)  
→ sold for \$432,500

## Diffusion Models



State-of-the-art  
image generation

## Transformer



State-of-the-art  
text generation

# What is a Generative Model?



We have:  $p_{\text{truth}} \equiv p_{\text{data}}(x)$   $\longrightarrow$  We want to generate new samples  $x \sim p_{\omega}(x) \simeq p_{\text{data}}(x)$

The distribution  $p_{\text{truth}}$  is usually given as:

- **explicit** as function (e.g.  $d\sigma \propto$  differential cross-section)
- **implicit** via a set of training data  $\{x\} \sim p_{\text{data}}(x)$

In **particle physics**:

- Event generation
- Calorimeter simulation
- Unfolding
- MEM (transfer function)

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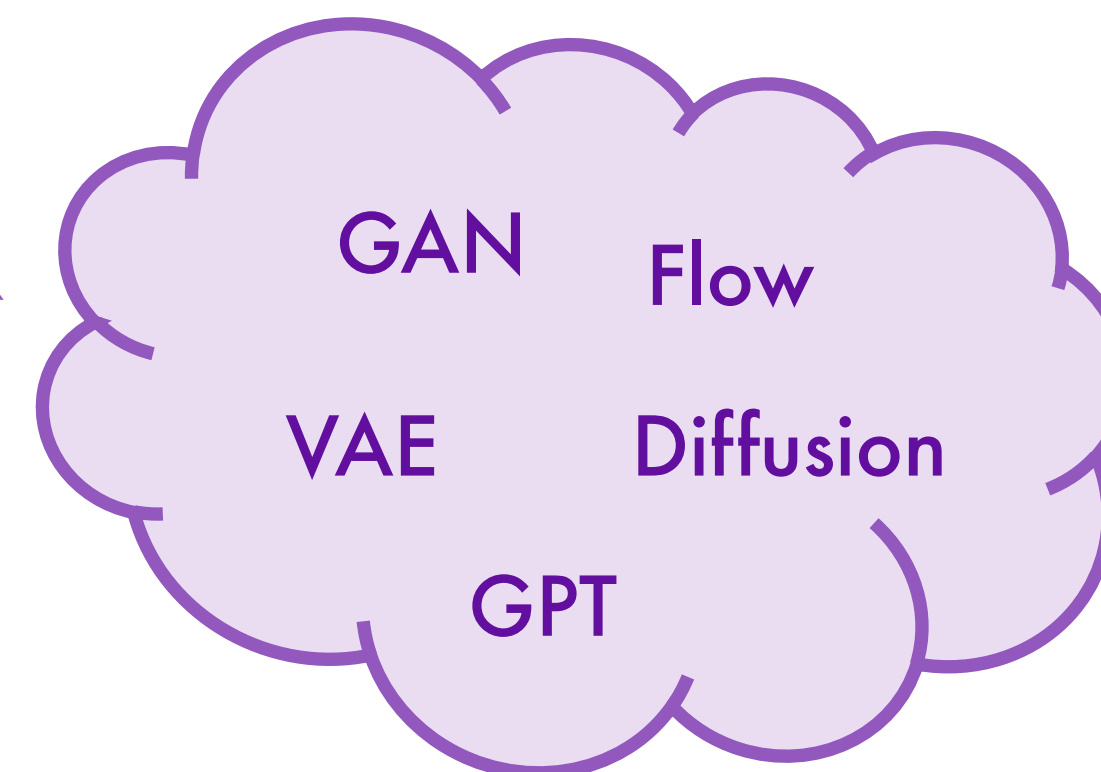
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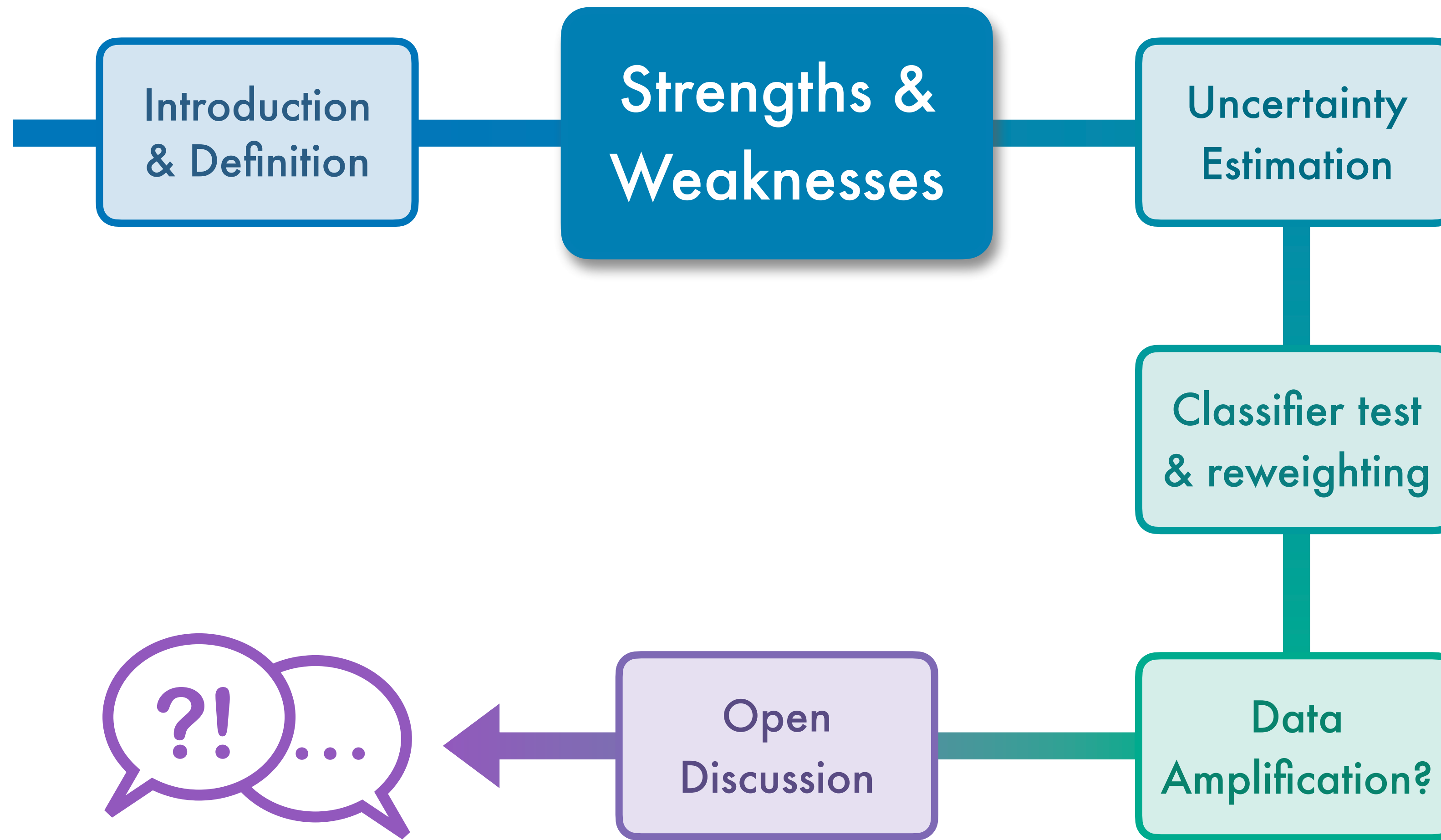
In **particle physics**:

- Event generation
- Calorimeter simulation
- Unfolding
- MEM (transfer function)

$\rightarrow$  **Multiple types** of generative models



# Strengths & Weaknesses of DGMs



# Deep generative models



$\beta$ -VAE

Hierarchical  
VAE

**Variational  
Autoencoder**

VQ-VAE

Diffusion Probabilistic  
Model

**Diffusion Model**

Score-matching  
Model

Conditional Flow  
Matching

Wasserstein GAN

**Generative  
Adversarial Network**

LS-GAN

Relativistic  
GAN

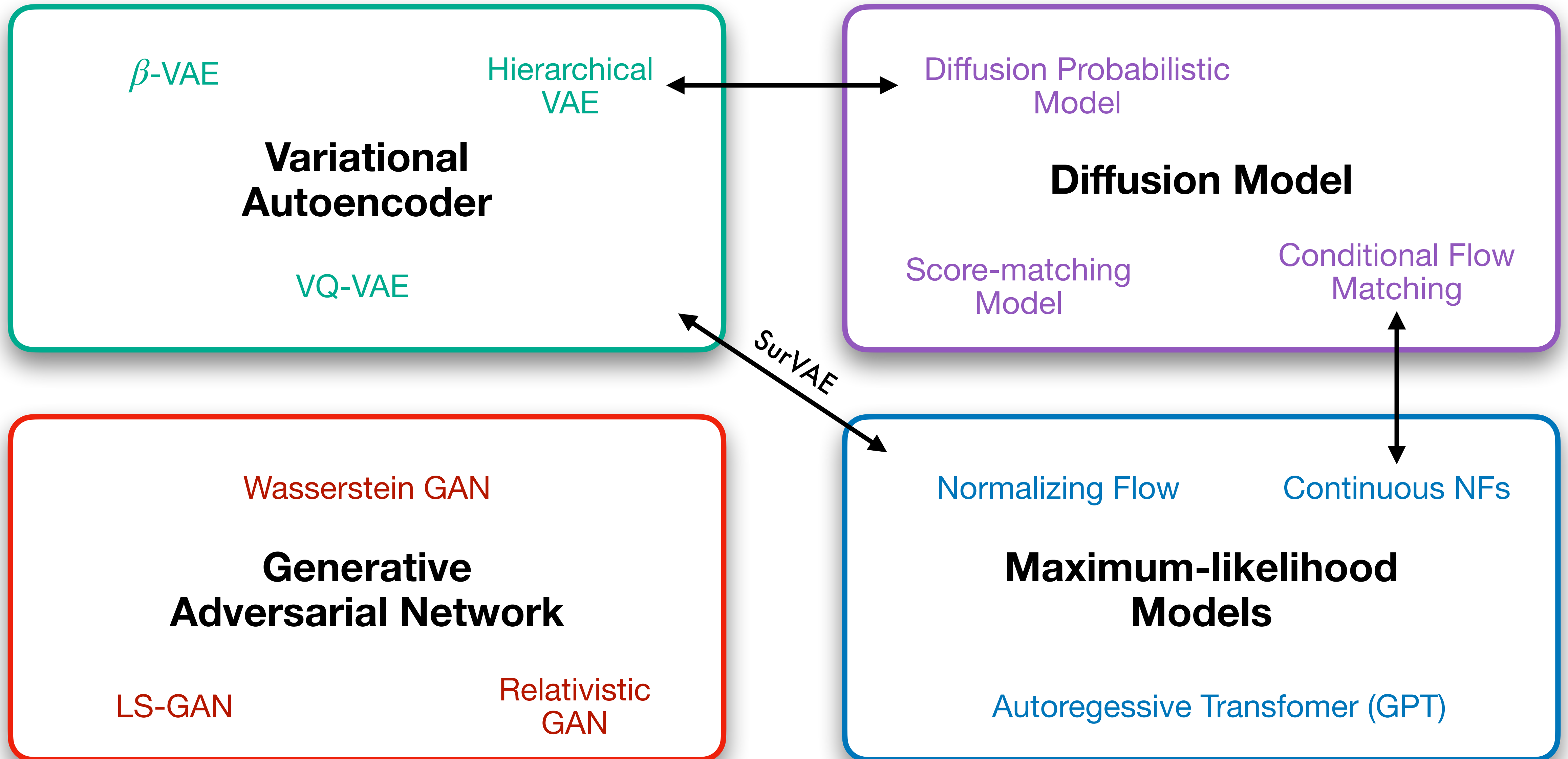
Normalizing Flow

Continuous NFs

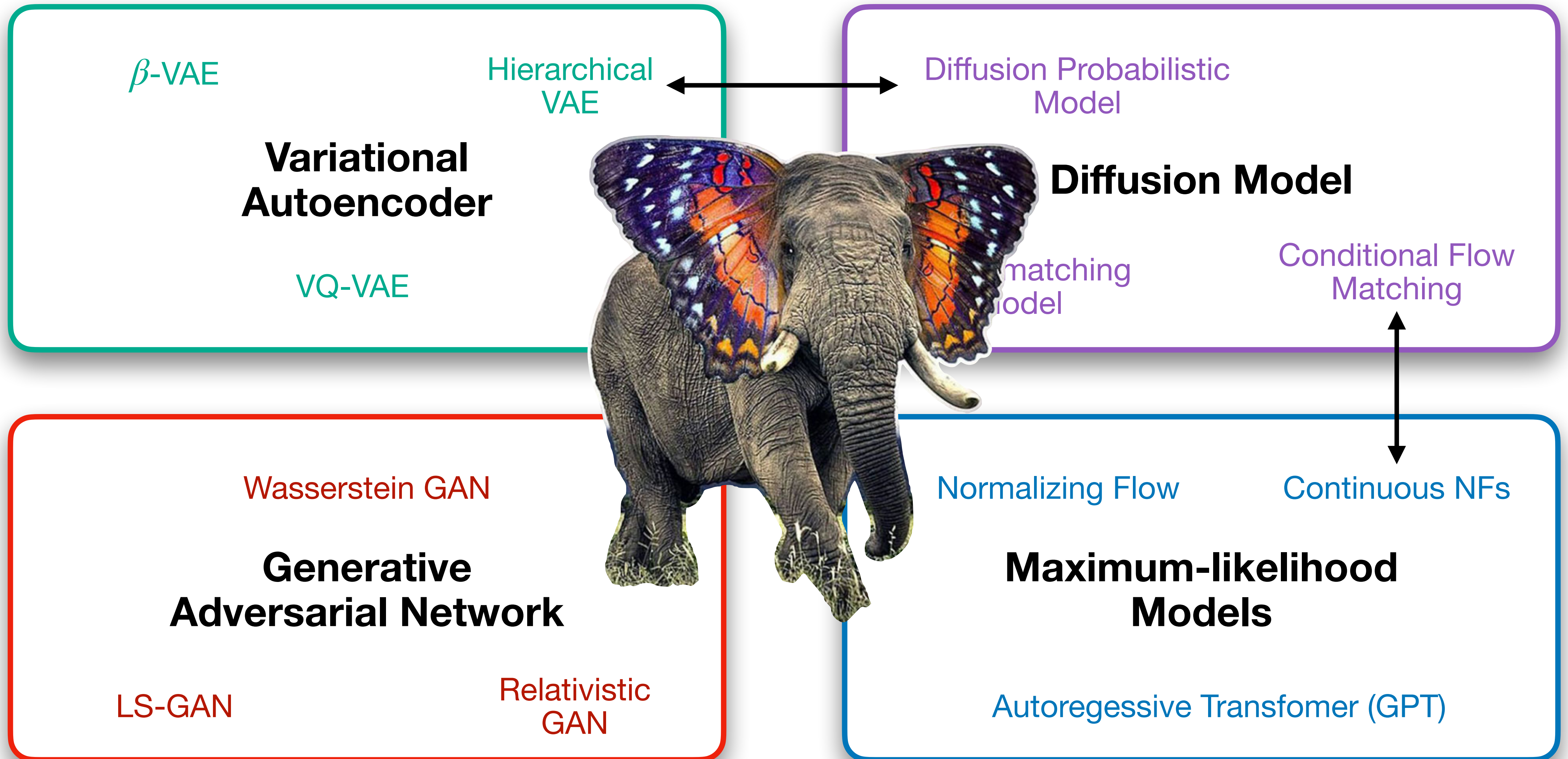
**Maximum-likelihood  
Models**

Autoregressive Transformer (GPT)

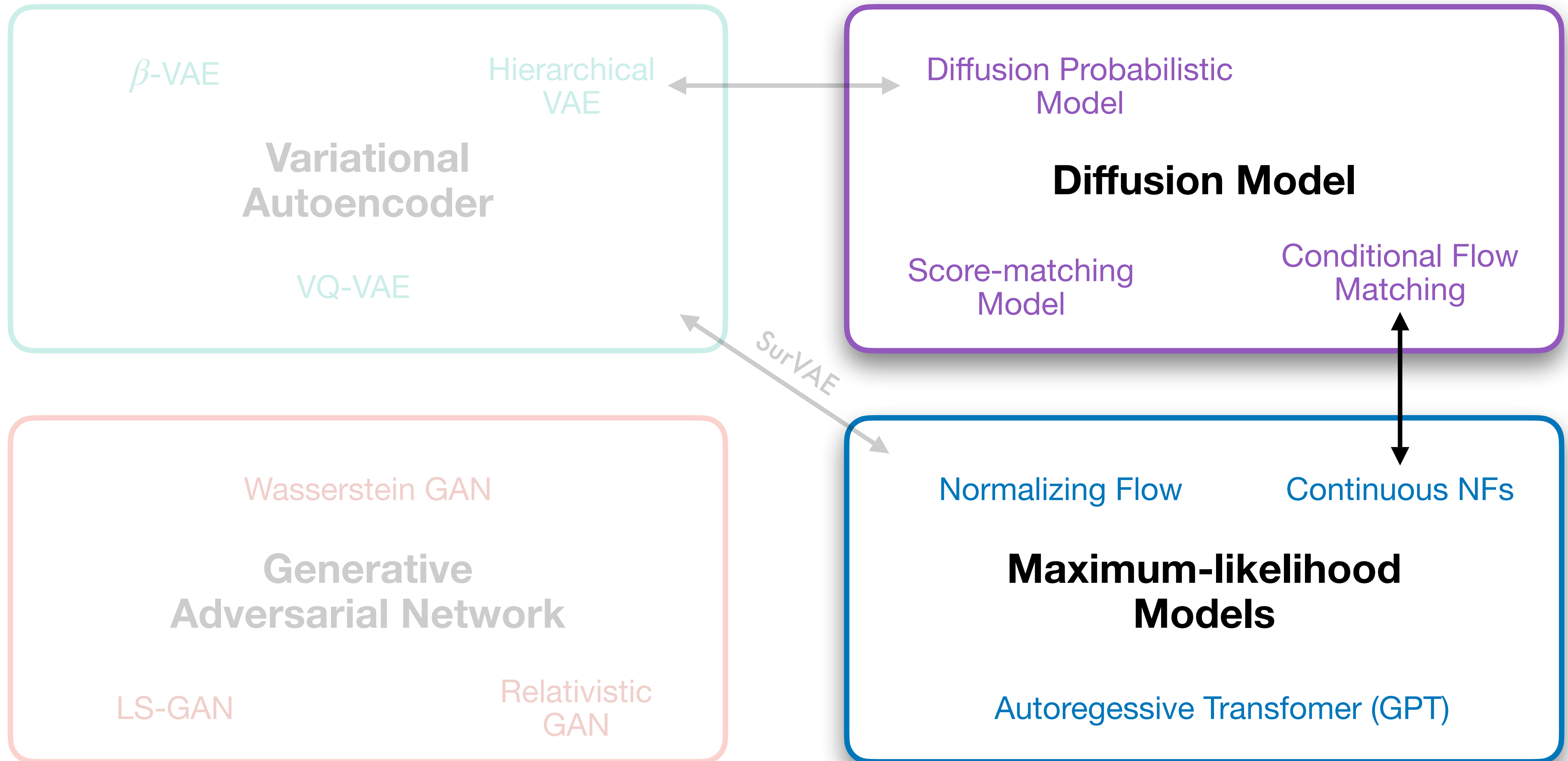
# Deep generative models



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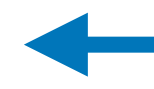
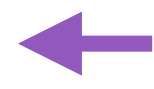


# Deep generative models

- ⊕ State-of-the-art in precision
- ⊕ Fast and stable training
- ⊖ Slow likelihood estimation

Application dependent

- ⊕ Fast training and evaluation
- ⊕ Tractable and fast likelihoods
- ⊖ Reduced flexibility and expressivity



Diffusion Probabilistic Model

**Diffusion Model**

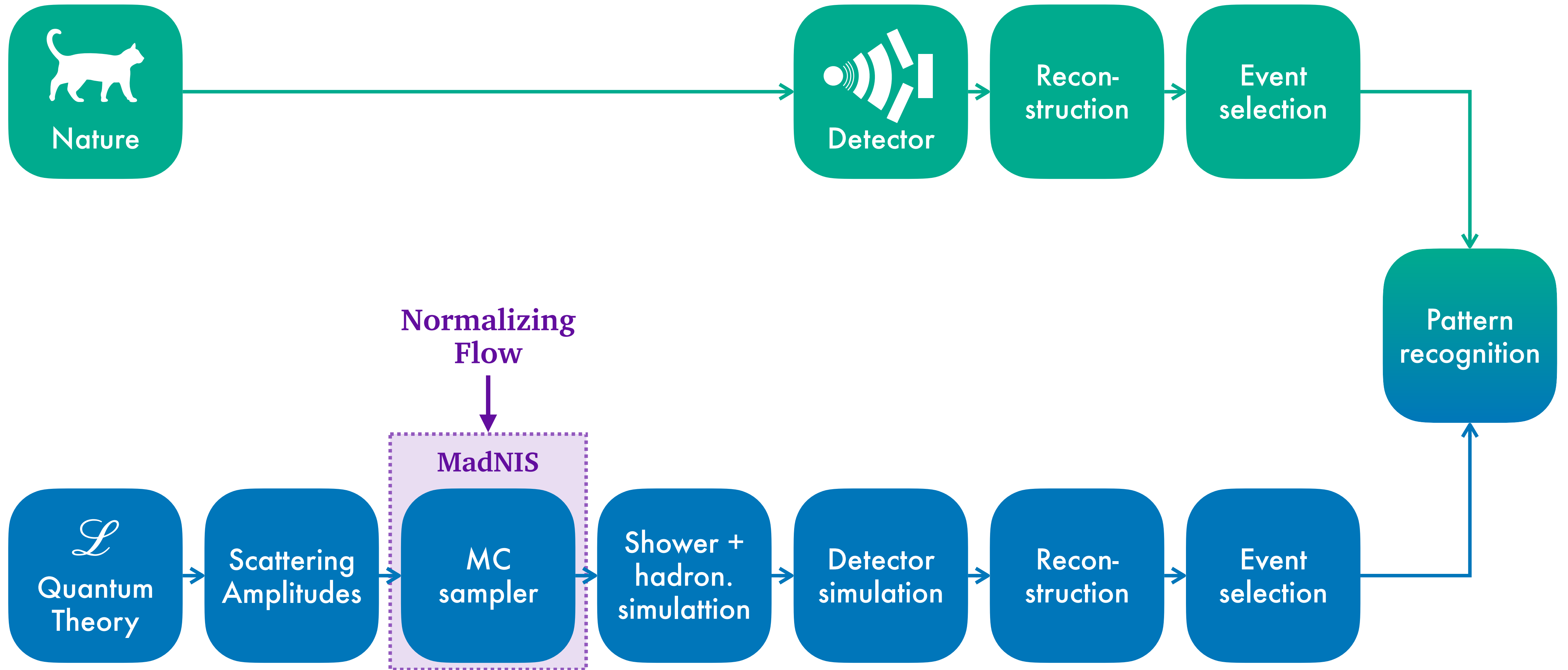
Score-matching Model      Conditional Flow Matching

Normalizing Flow      Continuous NFs

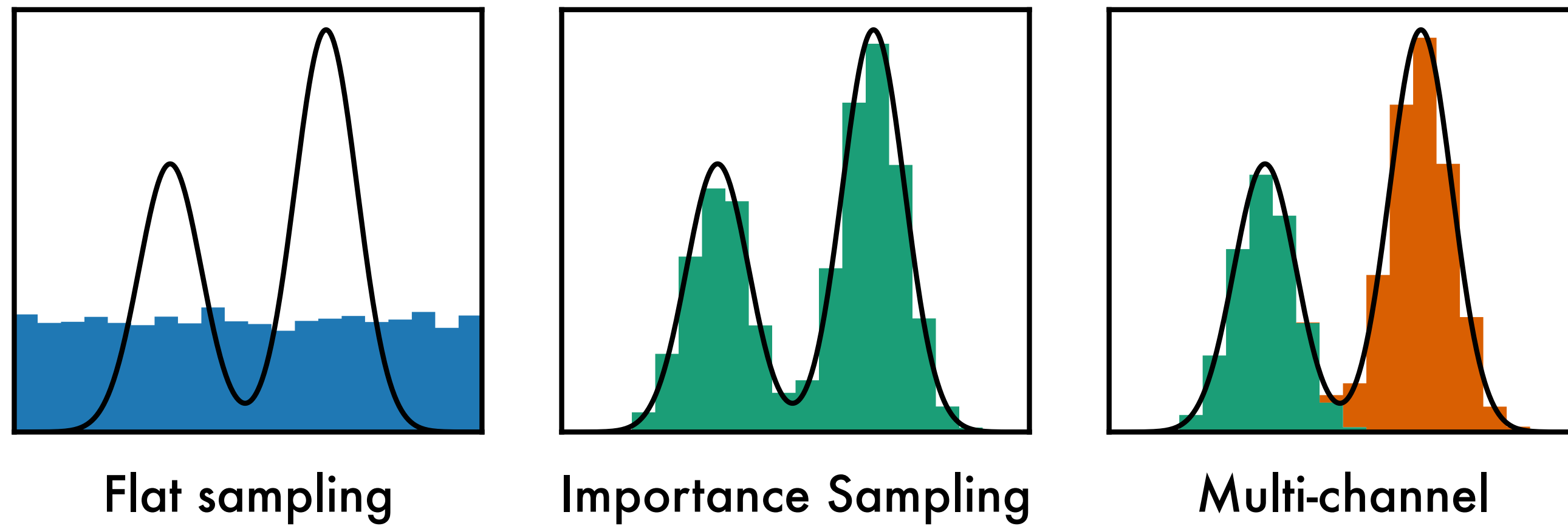
**Maximum-likelihood Models**

Autoregressive Transformer (GPT)

# LHC analysis + DGMs



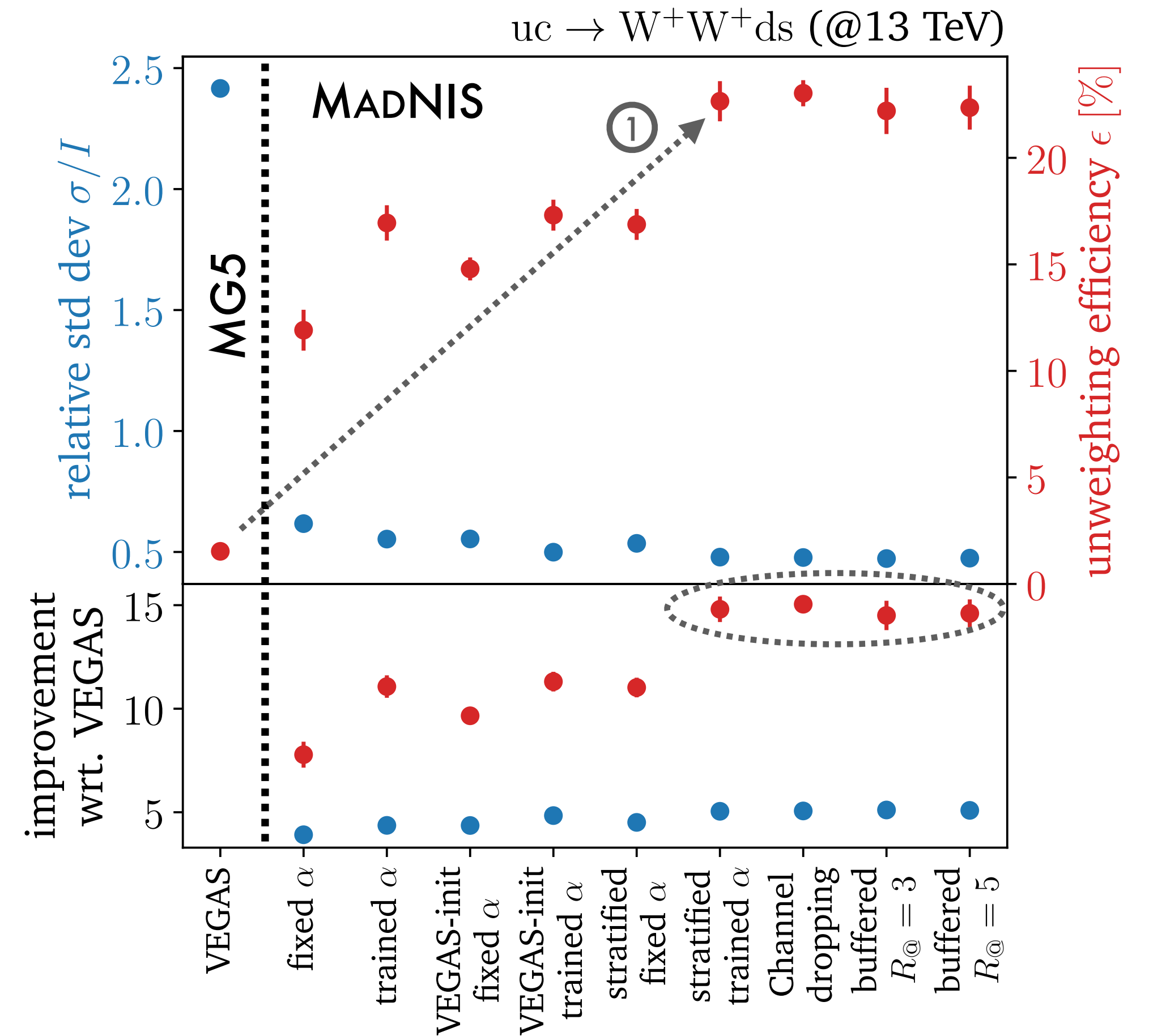
# MADNIS – Neural importance sampling



$$I = \sum_i \left\langle \alpha_i(x) \frac{f(x)}{g_i(x)} \right\rangle_{x \sim g_i(x)}$$

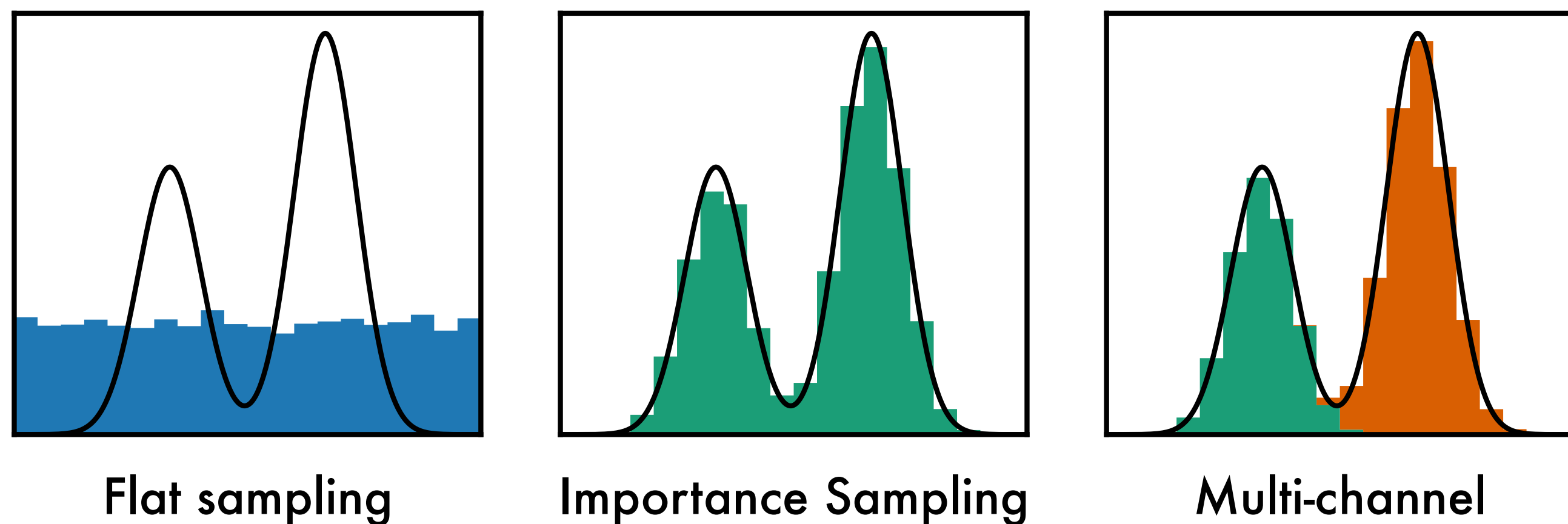
Parametrize with **NN**

Parametrize with **Normalizing Flow**



① excellent results with all features

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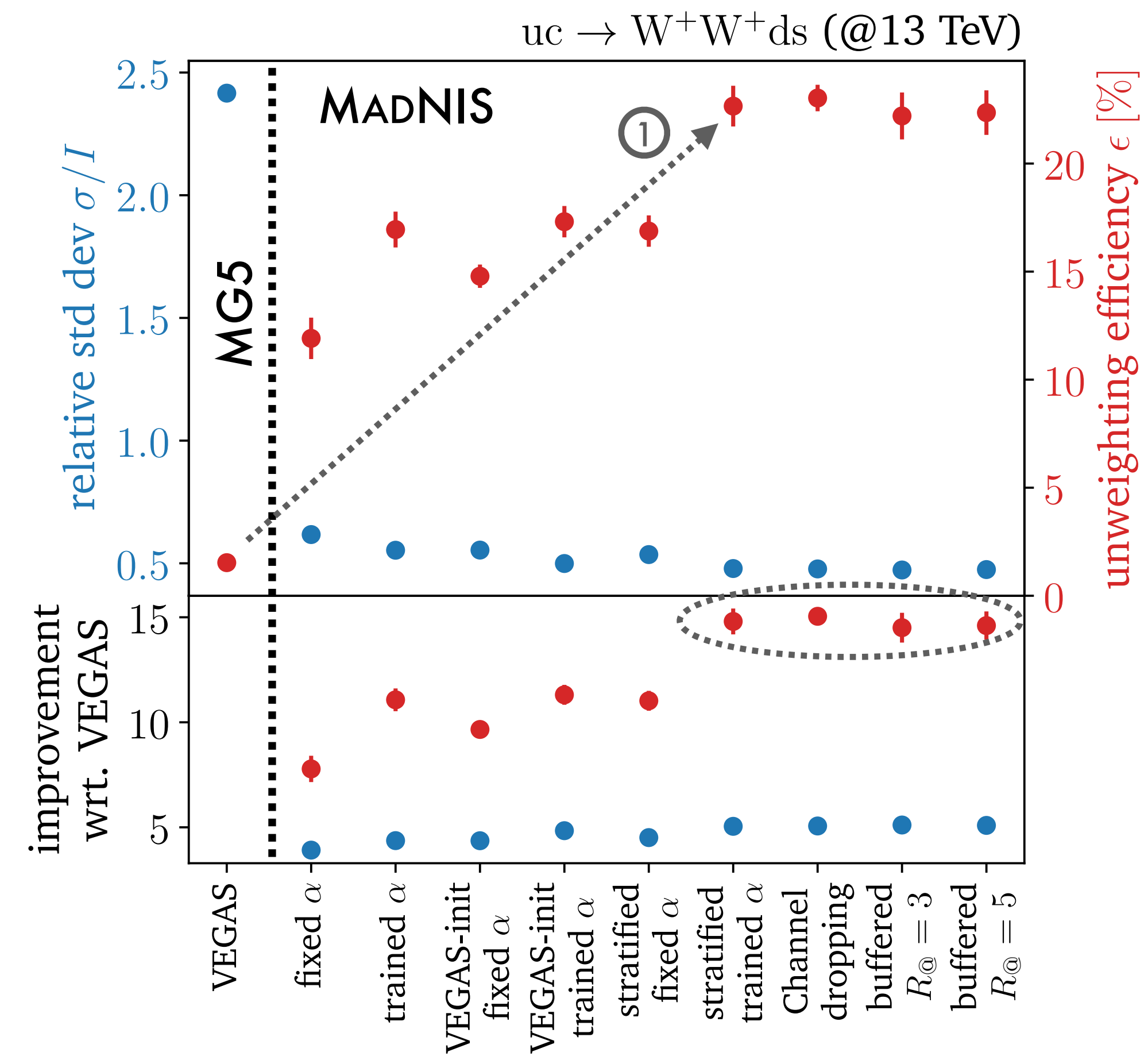


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Parametrize with **NN**

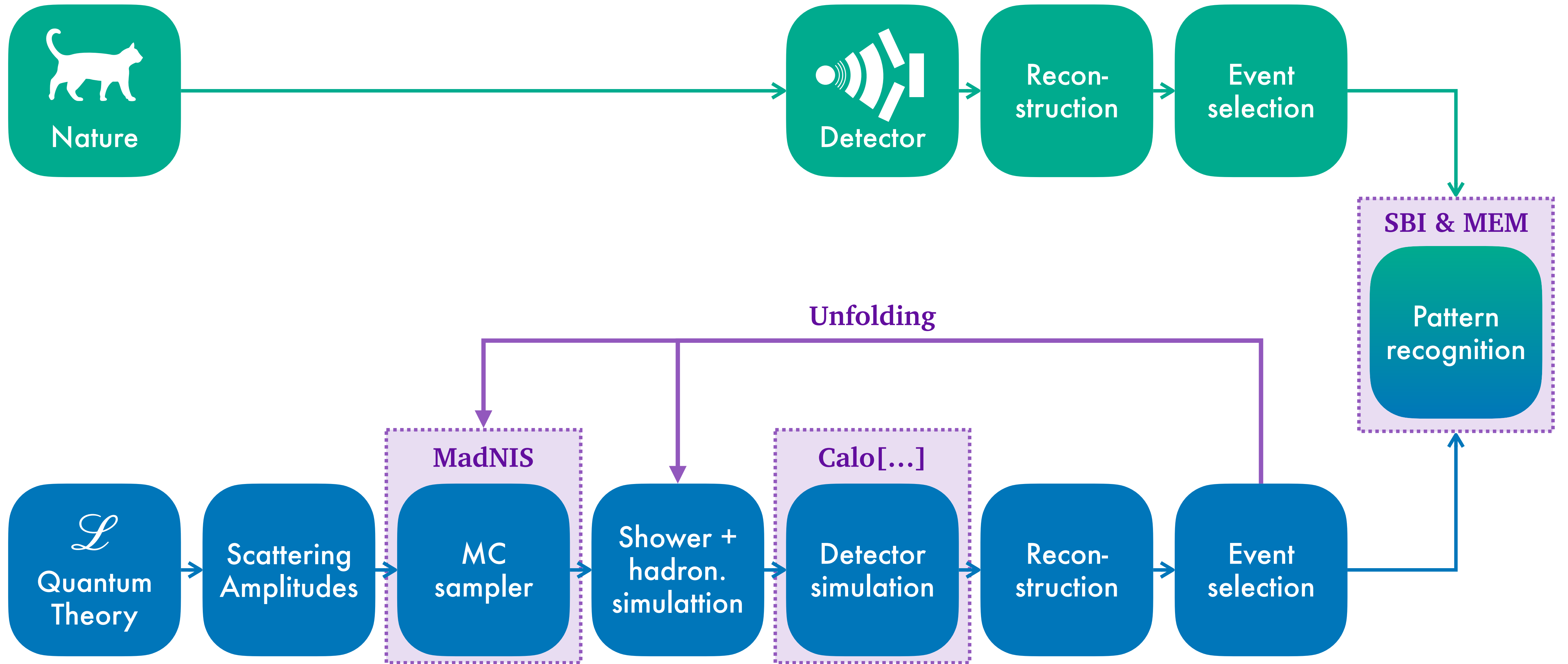
Parametrize with **Normalizing Flow**

← Fully differentiable version available

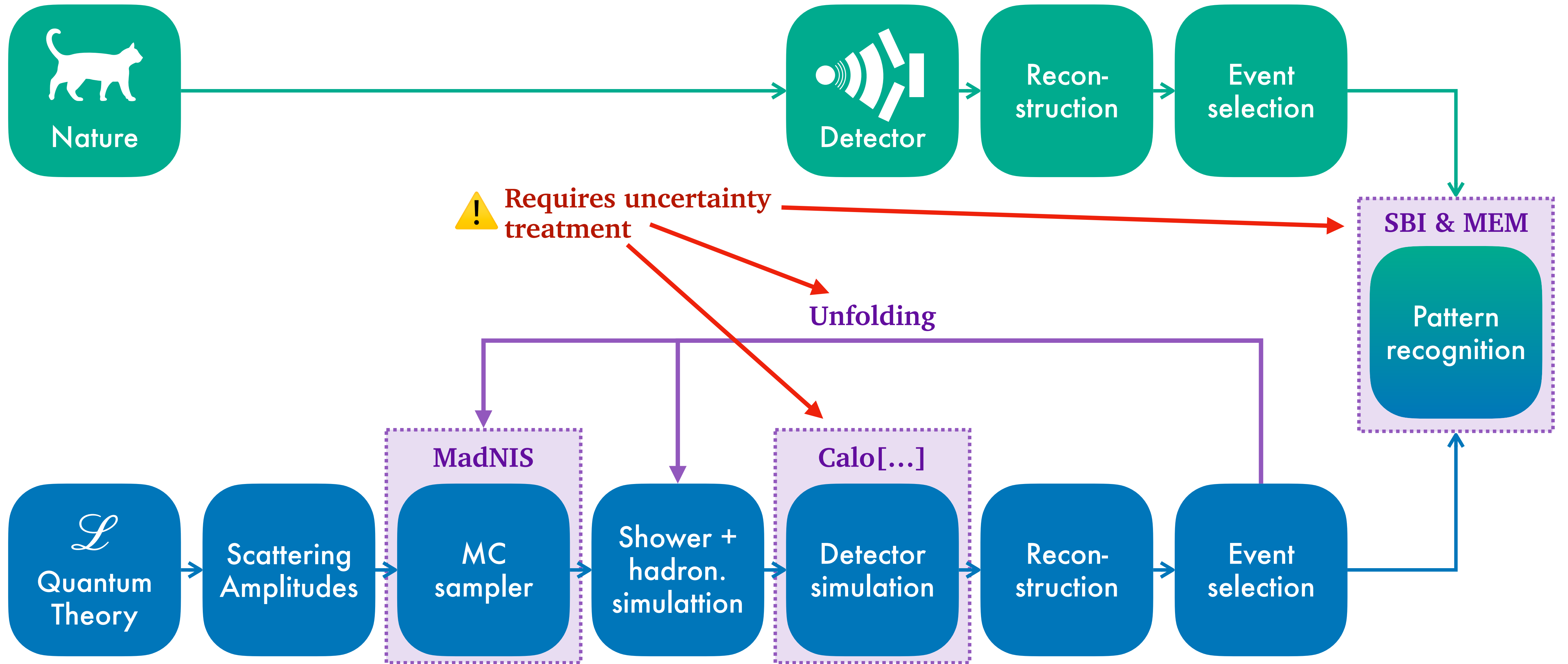


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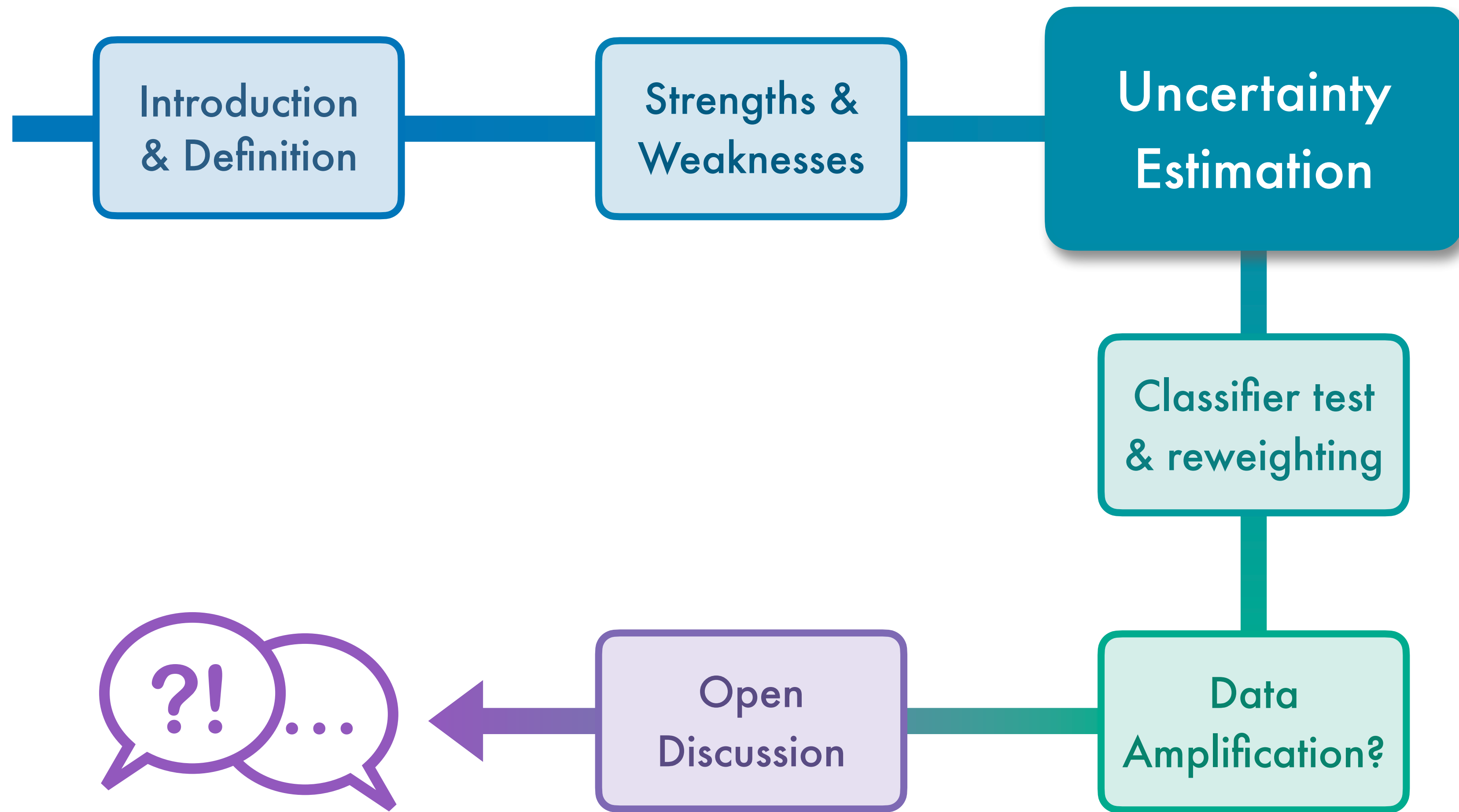
# LHC analysis + DGMs



# LHC analysis + DGMs



# Uncertainty Estimation



# What we have vs what we want

So far: NNs are deterministic  $\longrightarrow$  **fixed** input  $x$   $\longrightarrow$  **fixed** output  $y$

However, in **particle physics**:

$\rightarrow$  we are not only interested in **results**, but also in **errorbars**

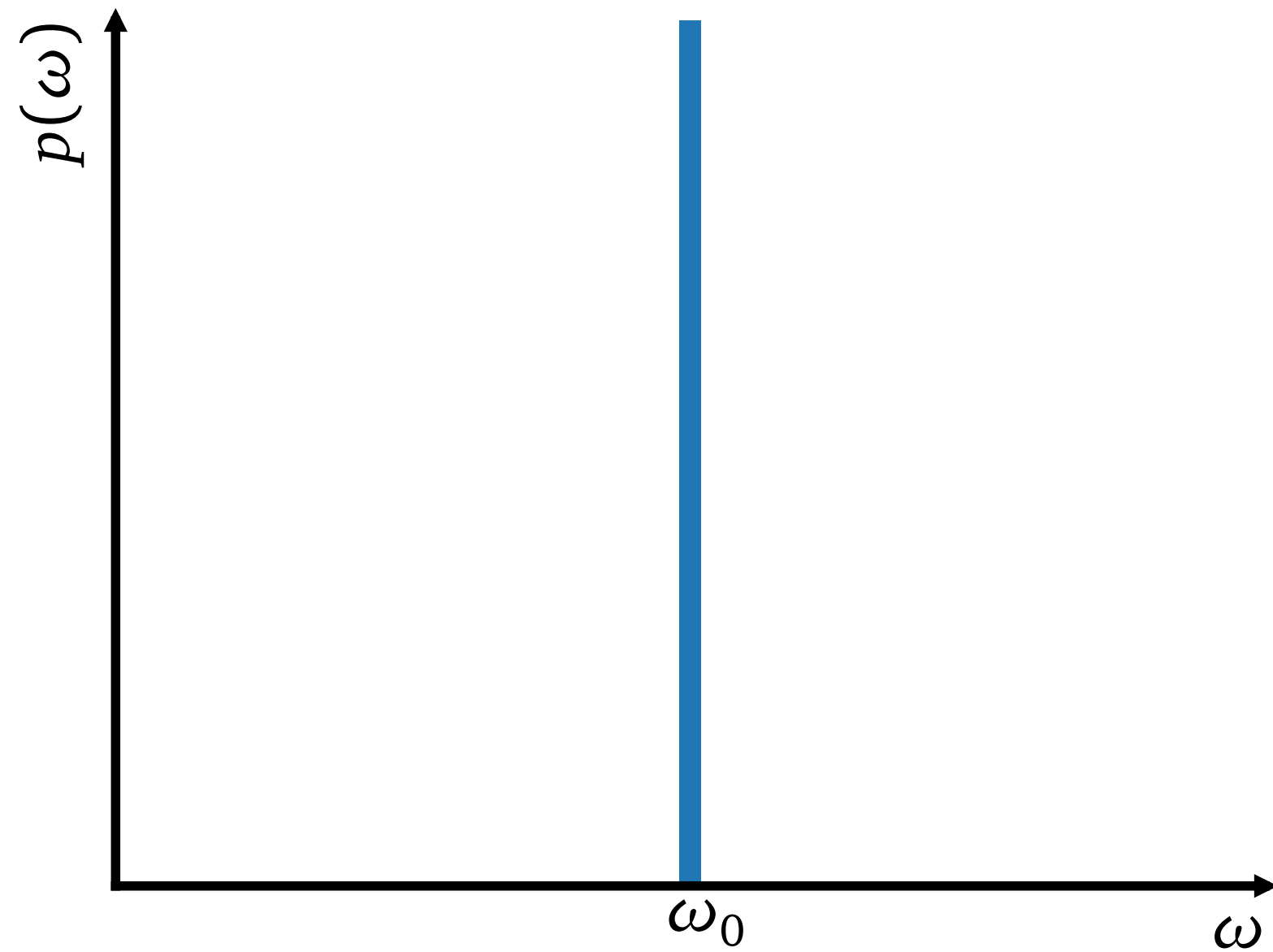
We need: **fixed** input  $x$   $\longrightarrow$  **probabilistic** output  $\langle y \rangle \pm \sigma_y$   $\longrightarrow$   $y \sim p(y|x)$

**How do we achieve this?**



# Bayesian neural networks

## Neural network

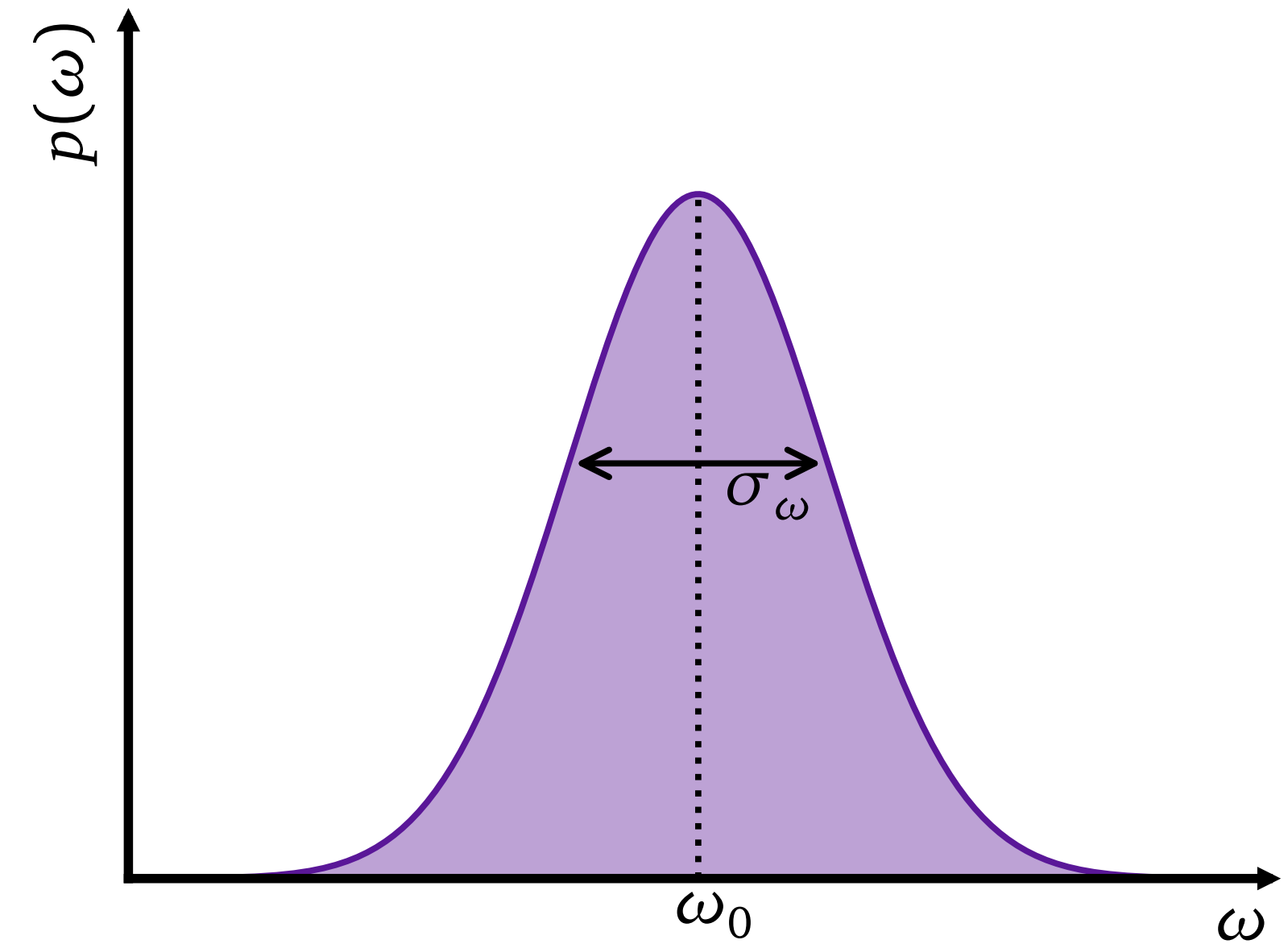


Network weights are deterministic

$$\omega = \omega_0$$



## Bayesian Neural network



Network weights are drawn from distribution

$$\omega \sim p(\omega)$$

# BNN loss function

- Predictive distribution in **DGMs**:

$$p(y|x) = \int d\omega p(y|\omega, x) p(\omega|x)$$

← Average over posterior

↑ DGM output

↘ Intractable ☹️

- Approximate posterior:

$$p(\omega|x) \simeq q_\alpha(\omega|x) \approx q_\alpha(\omega)$$

→ e.g. Gaussian with

$$\alpha = (\mu, \sigma)$$

# BNN loss function

- Predictive distribution in **DGMs**:  $p(y|x) = \int d\omega p(y|\omega, x) p(\omega|x)$ 
  - ← Average over posterior
  - ↑ DGM output
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- Approximate posterior:  $p(\omega|x) \simeq q_\alpha(\omega|x) \approx q_\alpha(\omega)$  → e.g. Gaussian with  $\alpha = (\mu, \sigma)$

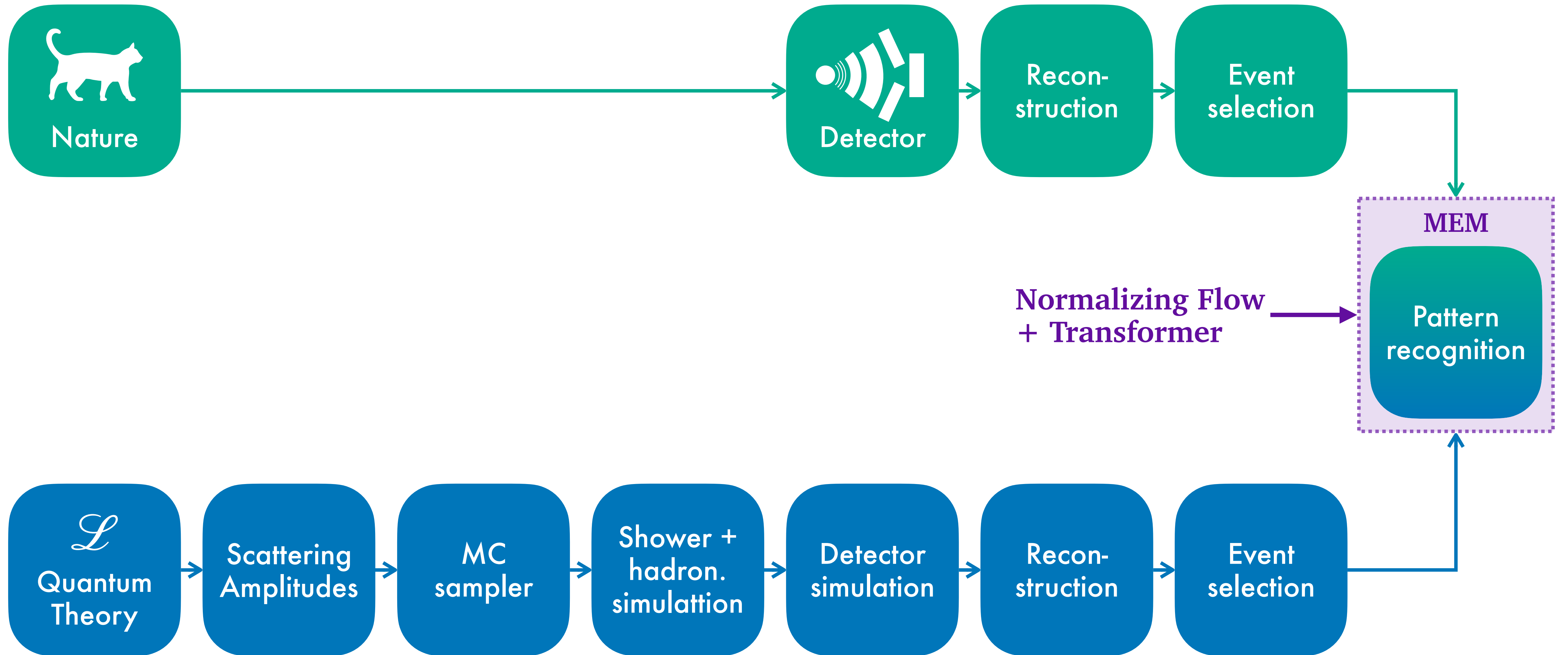
- Variational inference: find  $\alpha$  that minimizes  $\text{KL}(q_\alpha(x), p(\omega|x))$ 
  - ← Bayes' Theorem  $p(\omega|x) = \frac{p(x|\omega)p(\omega)}{p(x)}$

- BNN loss function

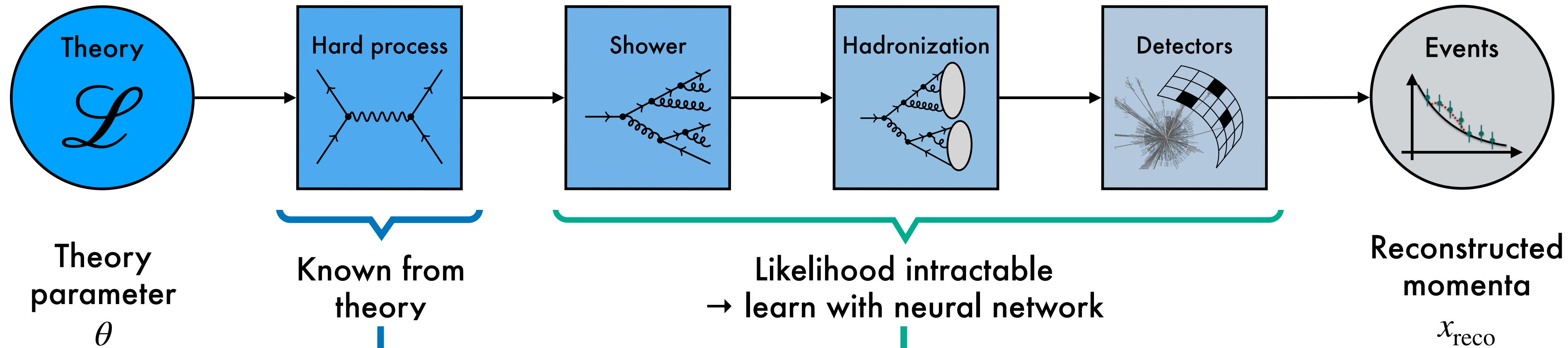
$$\mathcal{L}_{\text{BNN}} = - \underbrace{\langle \log p(x|\omega) \rangle_{q_\alpha(\omega)}}_1 + \underbrace{\text{KL}(q_\alpha(\omega), p(\omega))}_2$$

- ① Neg log-likelihood averaged over  $q_\alpha$
- ②  $q_\alpha$  should not deviate too much from prior!

# LHC analysis + DGMs



# Inference – Matrix element method



$$p(x_{\text{reco}} | \theta) = \int dx_{\text{hard}} p(x_{\text{hard}} | \theta) p(x_{\text{reco}} | x_{\text{hard}}) \epsilon(x_{\text{hard}})$$

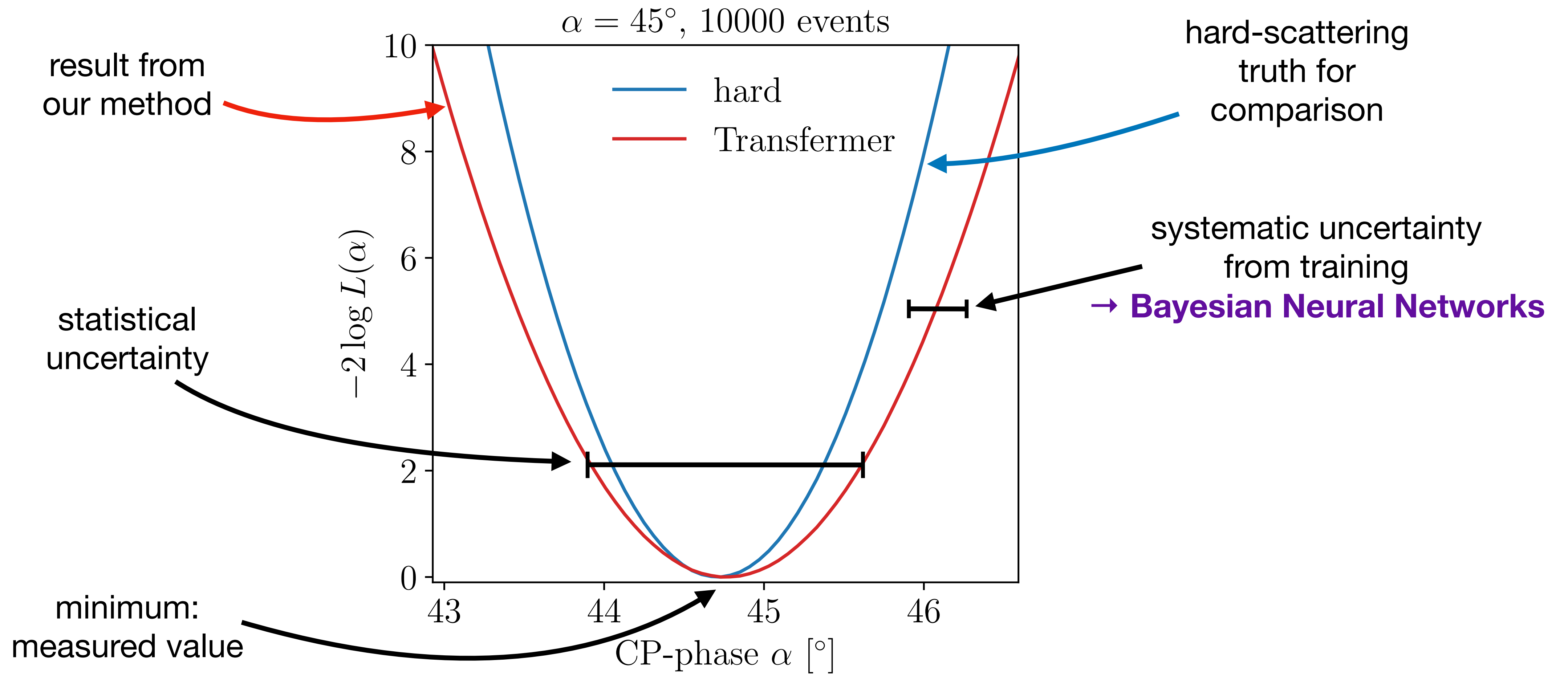
**Efficient MC integration**  
 importance sampling:  
**Normalizing Flow**  
 $x_{\text{hard}} \sim p(x_{\text{hard}} | x_{\text{reco}}, \theta)$

**Theory knowledge**  
 diff. cross-section  
 $\frac{1}{\sigma(\alpha)} \frac{d\sigma(\alpha)}{dx_{\text{hard}}}$

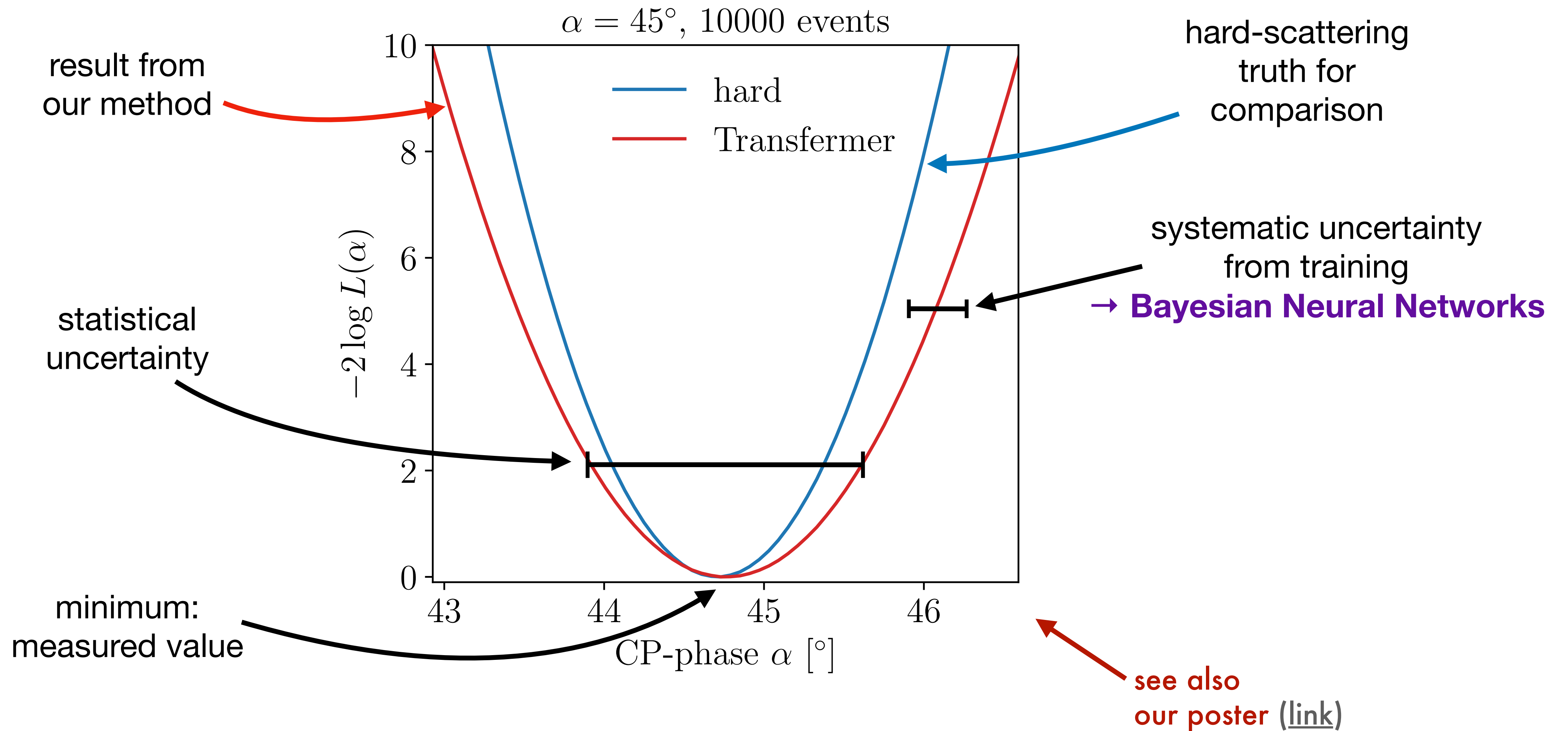
**Transfer function**  
 density estimation:  
**Normalizing Flow + Transformer**

**Acceptance function**  
 learn with simple  
**classifier network**

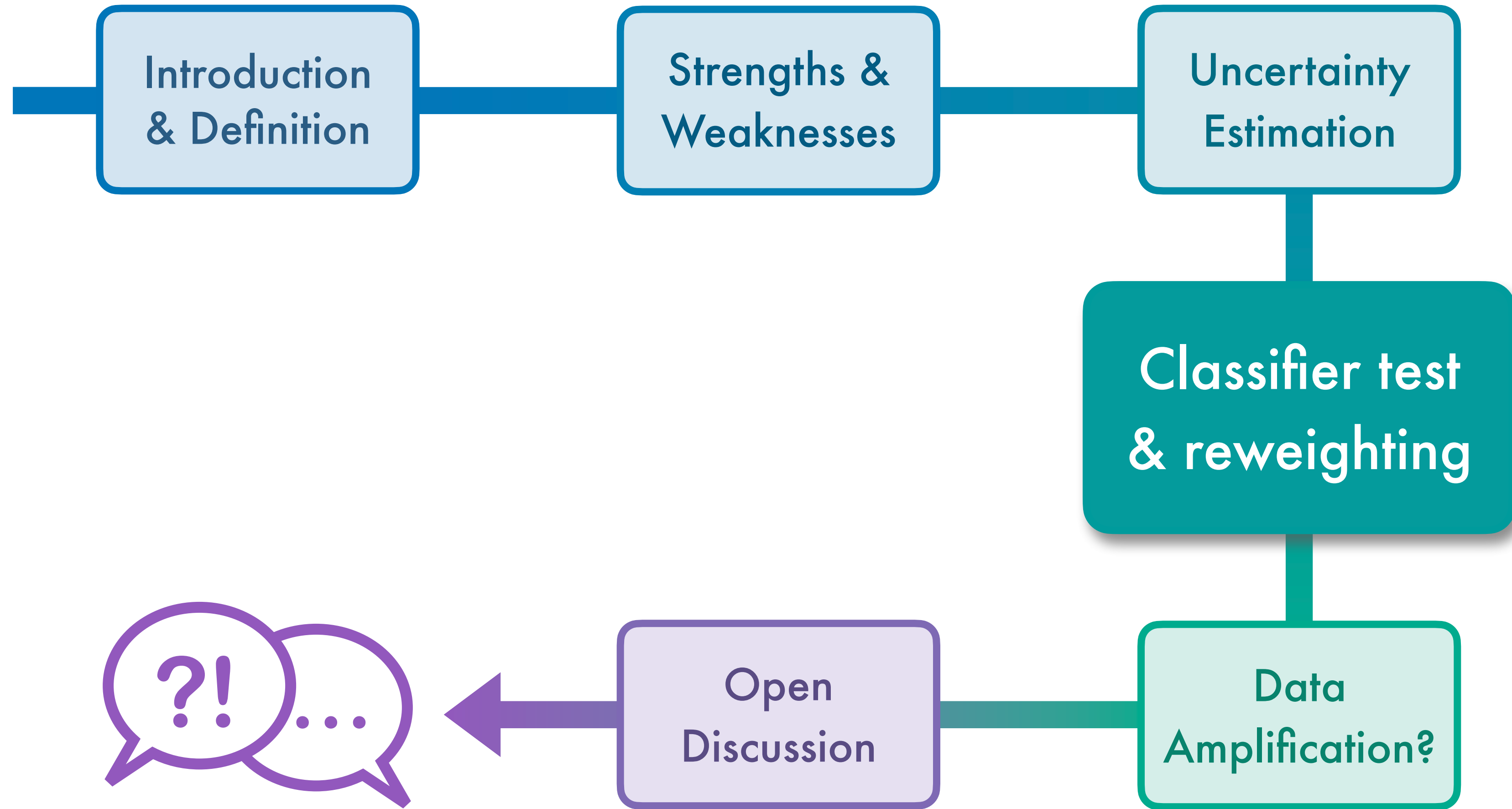
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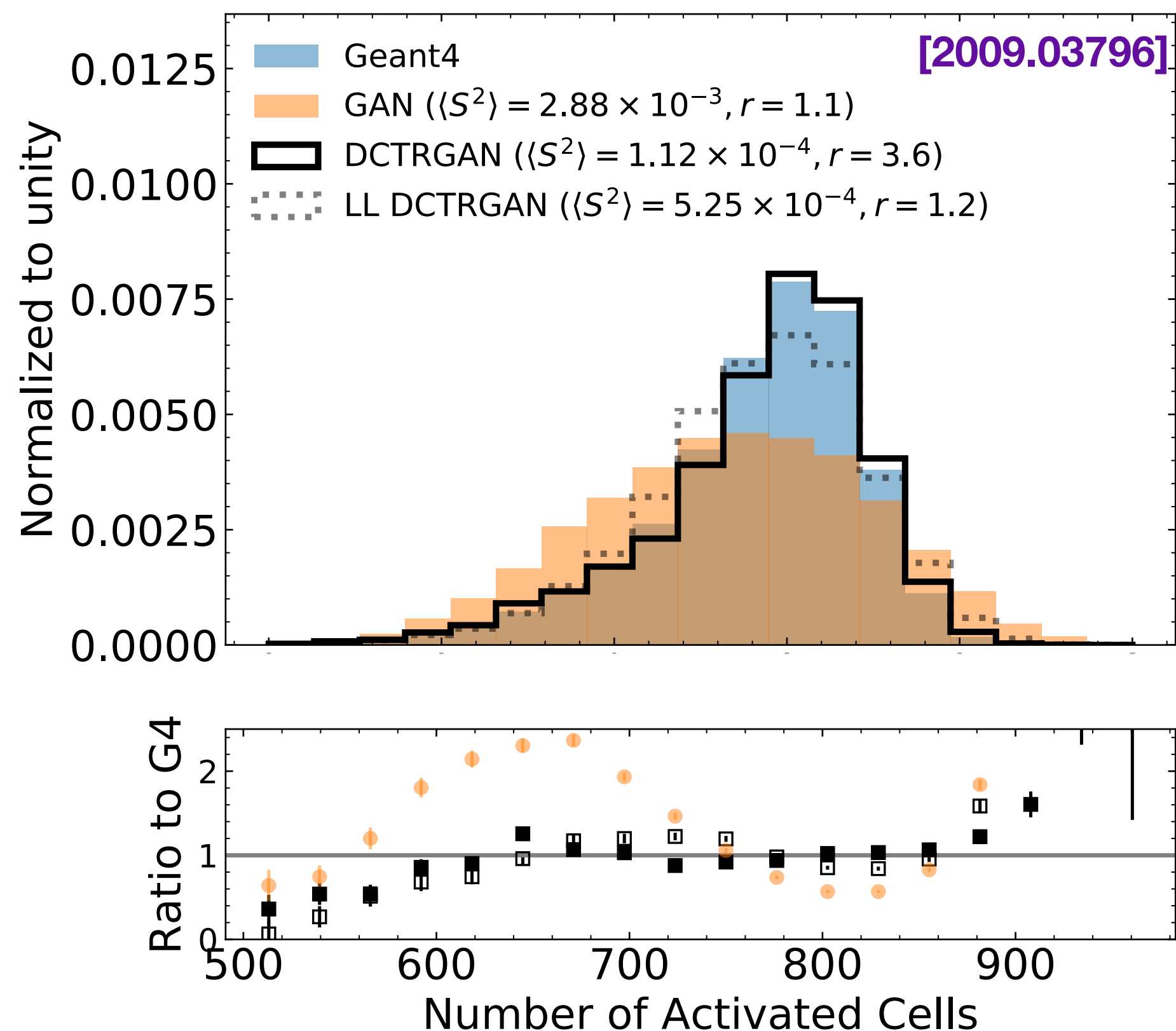
# Classifier test & reweighting





# Reweighting and refinement

## DCTRGAN



- ⊕ Additional classifier improves precision  
DCTRGAN [1907.08209, 2009.03796],  
LASER [2106.00792, 2305.07696]

## Classifier

If we have samples from **data** and **DGM...**

...an **optimal classifier** yields

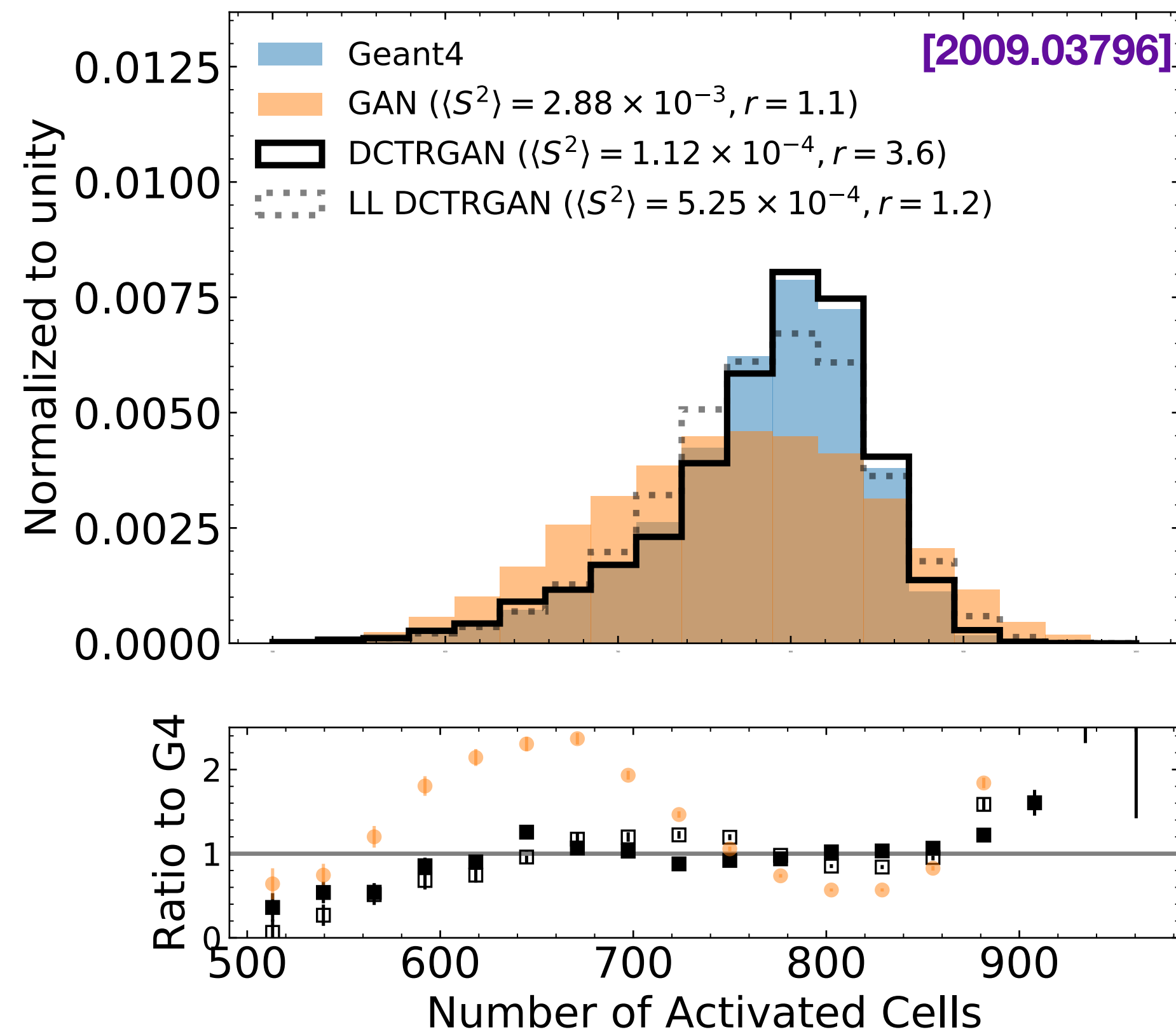
$$f(x) = \frac{p_{\text{data}}(x)}{p_{\text{data}}(x) + p_G(x)}$$

and defines weight

$$w(x) = \frac{p_{\text{data}}(x)}{p_G(x)} = \frac{f(x)}{1 - f(x)}$$

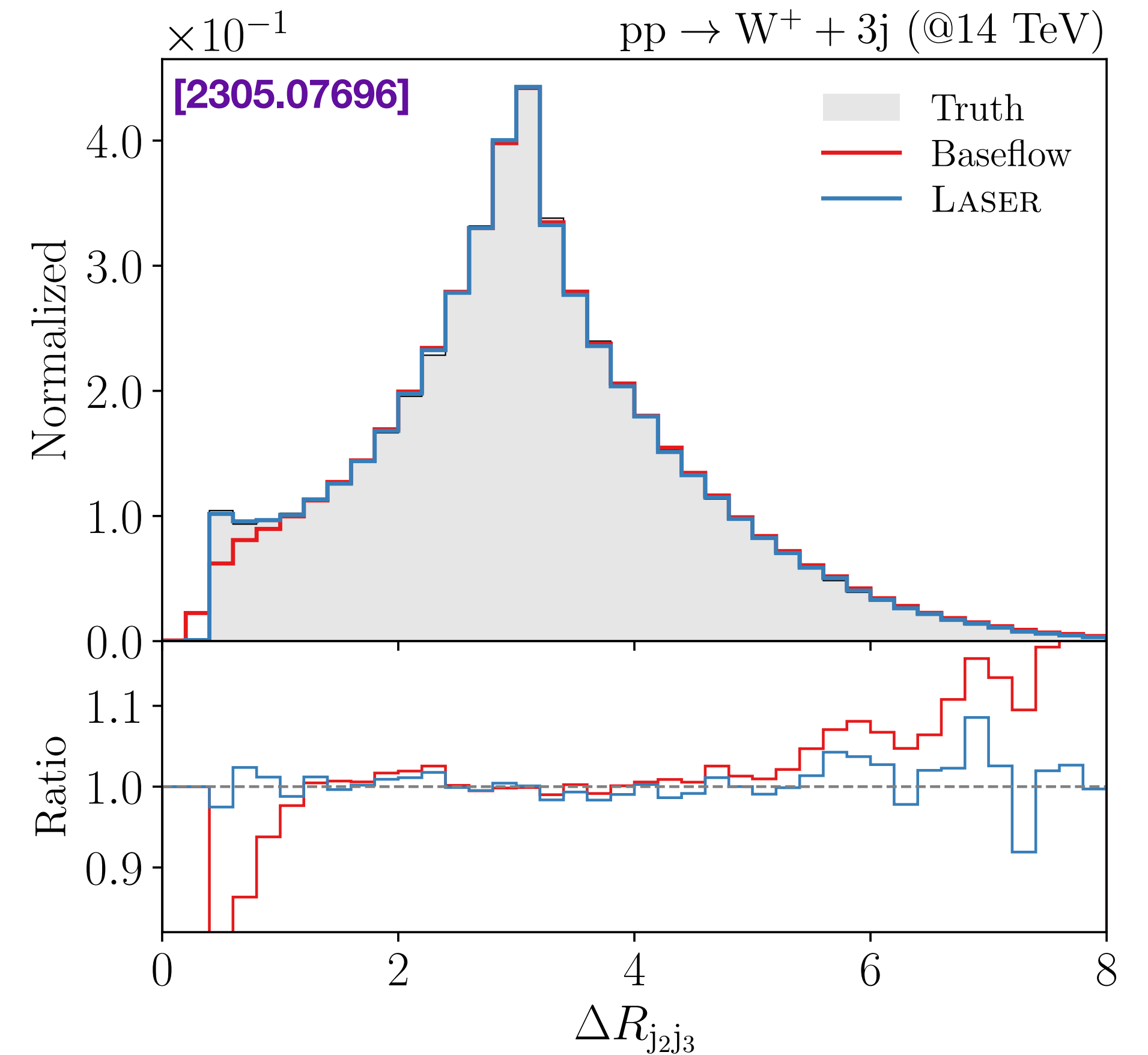
# Reweighting and refinement

## DCTRGAN



pull weights to  
latent space

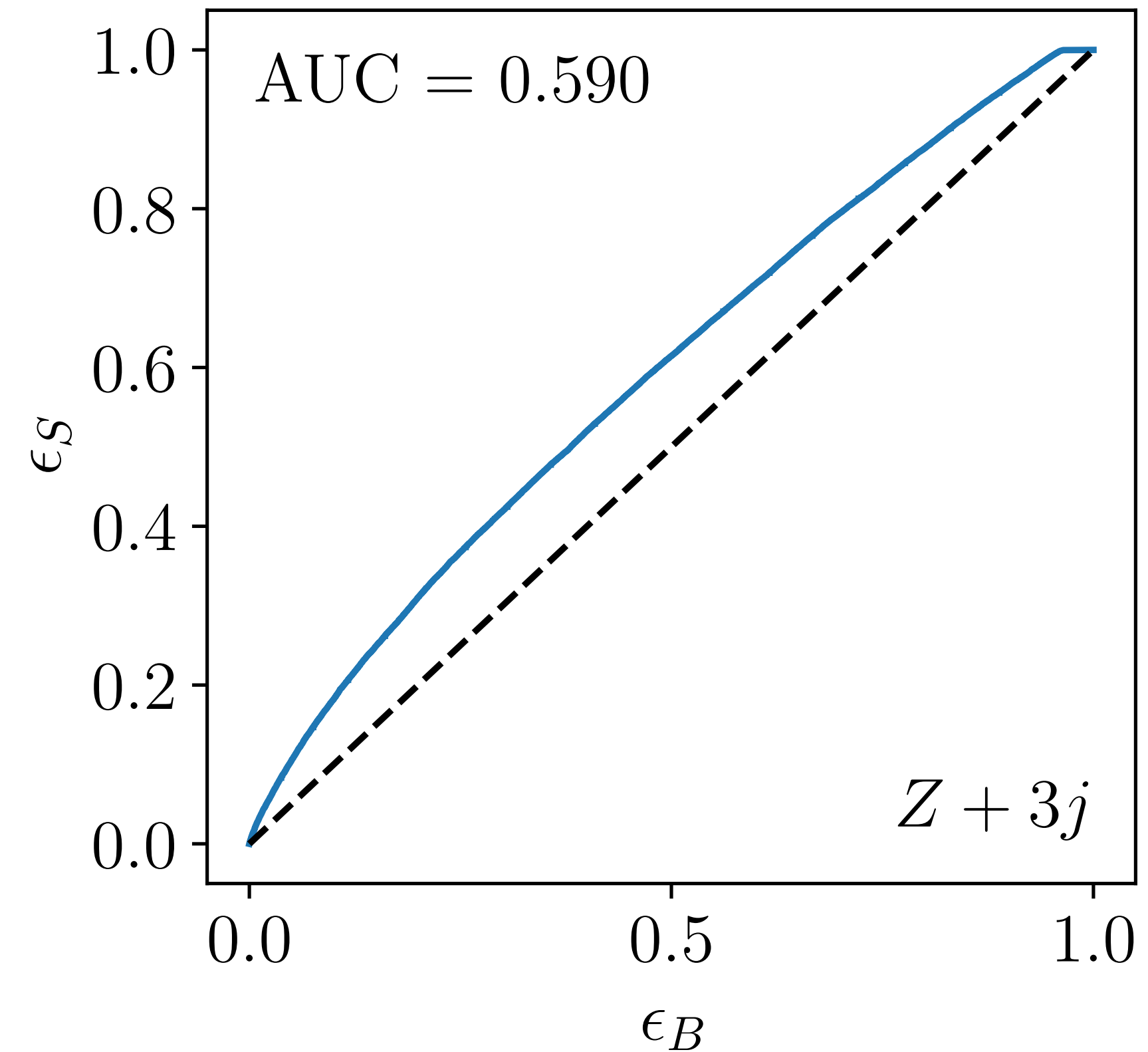
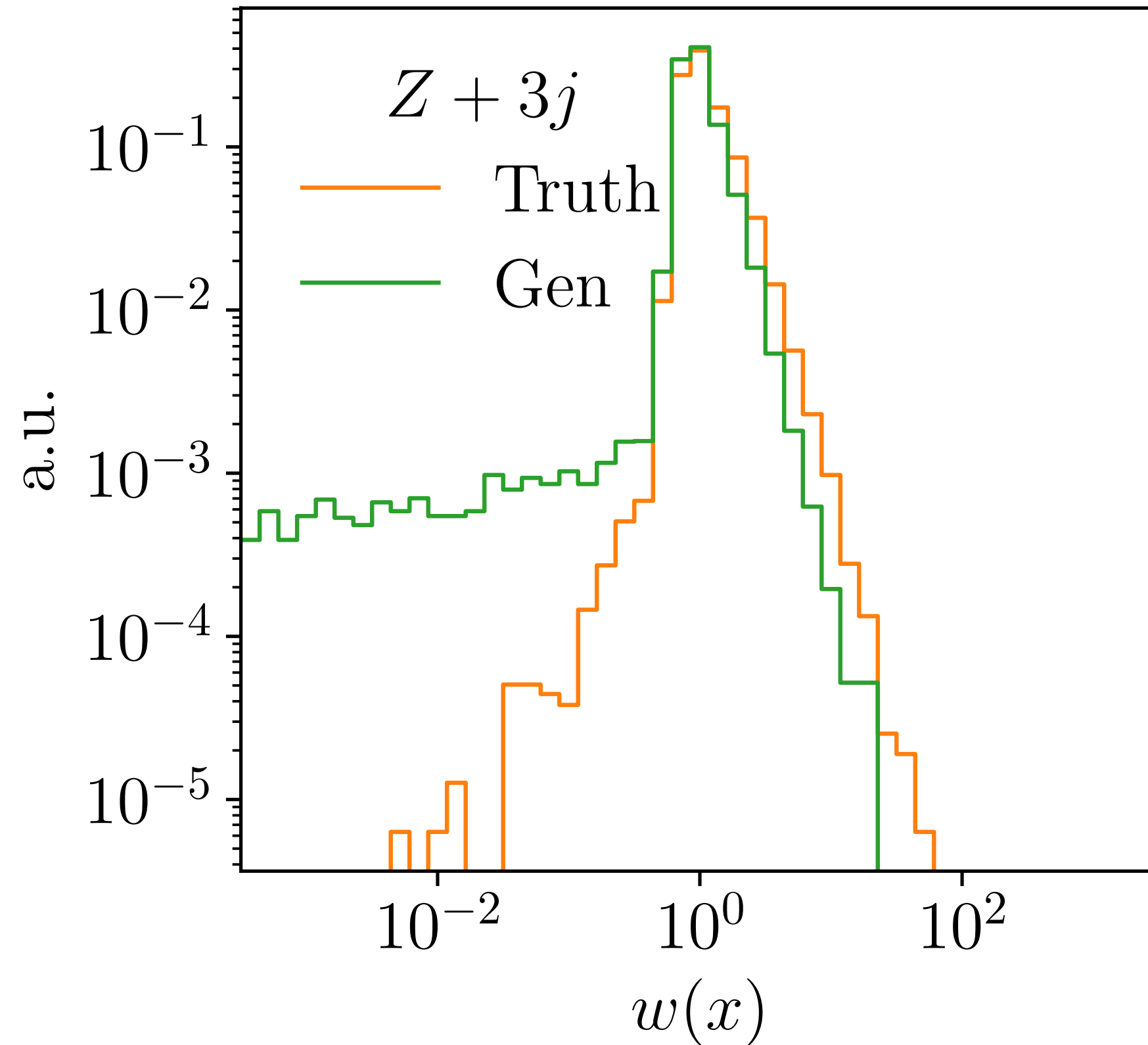
## LASER



⊕ Additional classifier improves precision  
DCTRGAN [1907.08209, 2009.03796],  
LASER [2106.00792, 2305.07696]

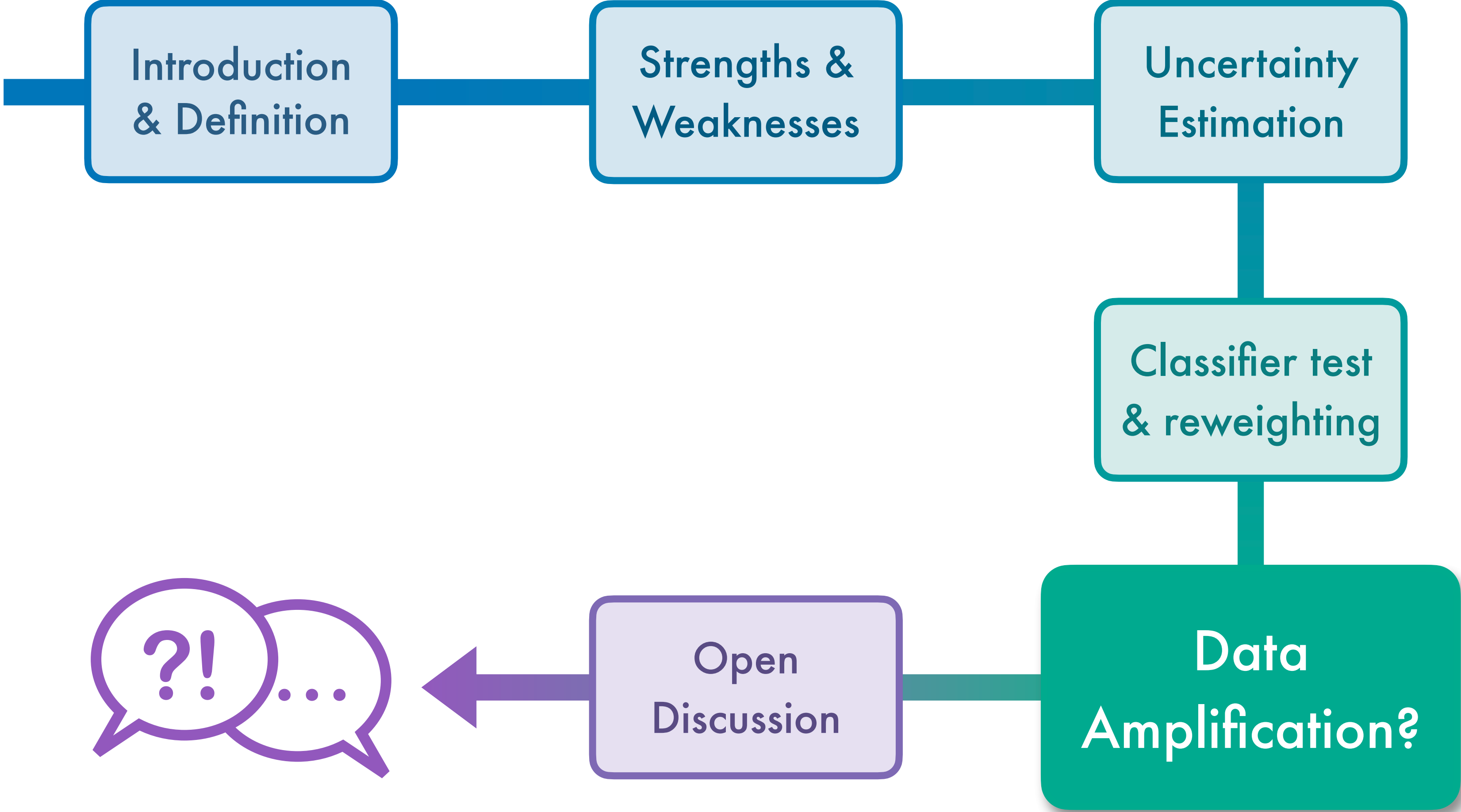
⊕ Laser gives unweighted events

# Classifier test



- classifier detects **subtle difference** between densities
- yields a **valuable test metric**

# Data Amplification



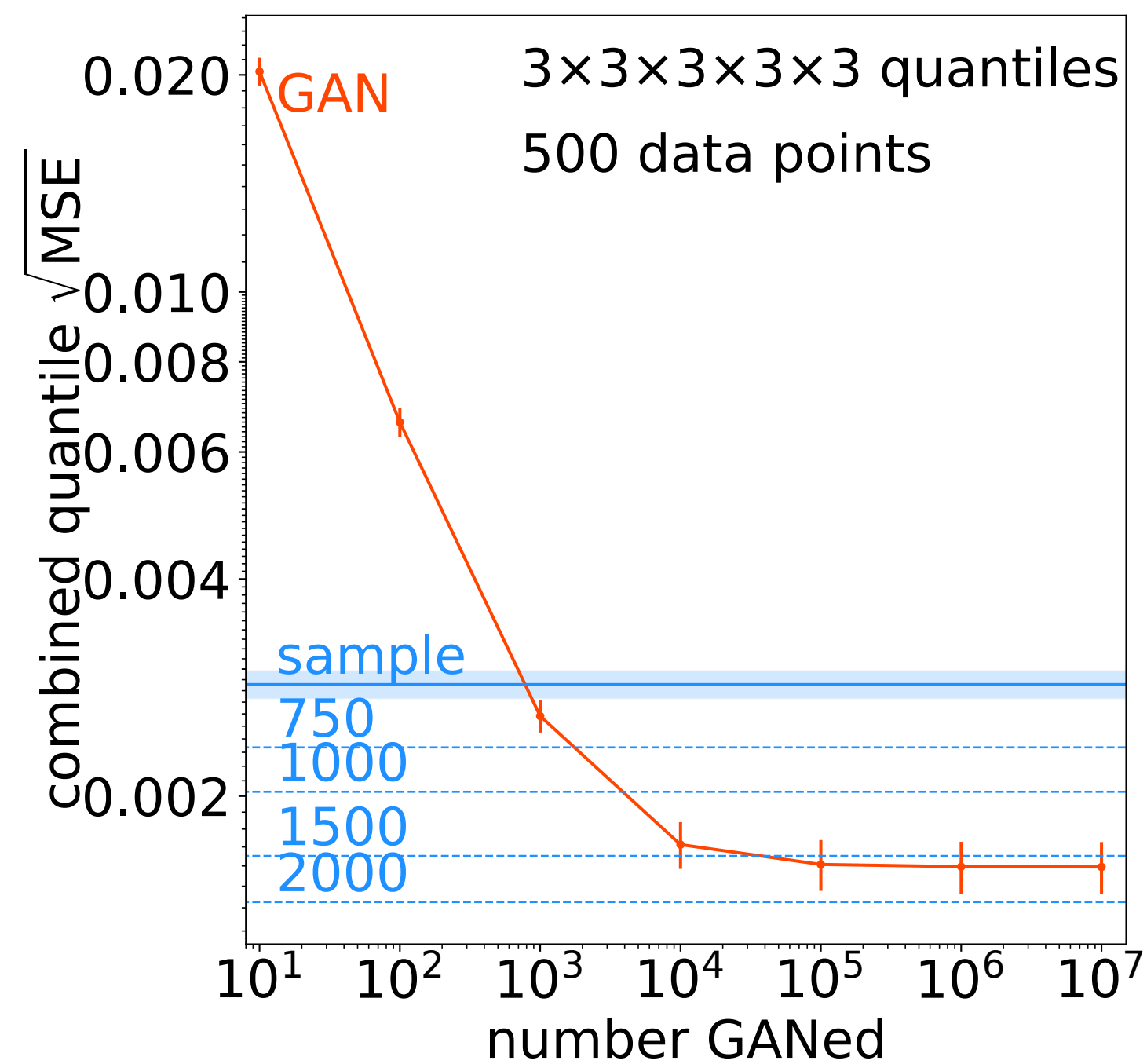
# Discussion Topic

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Given  $N$  training samples, how many more events  $N_g > N$  can the DGM generate that can effectively increase the statistics?

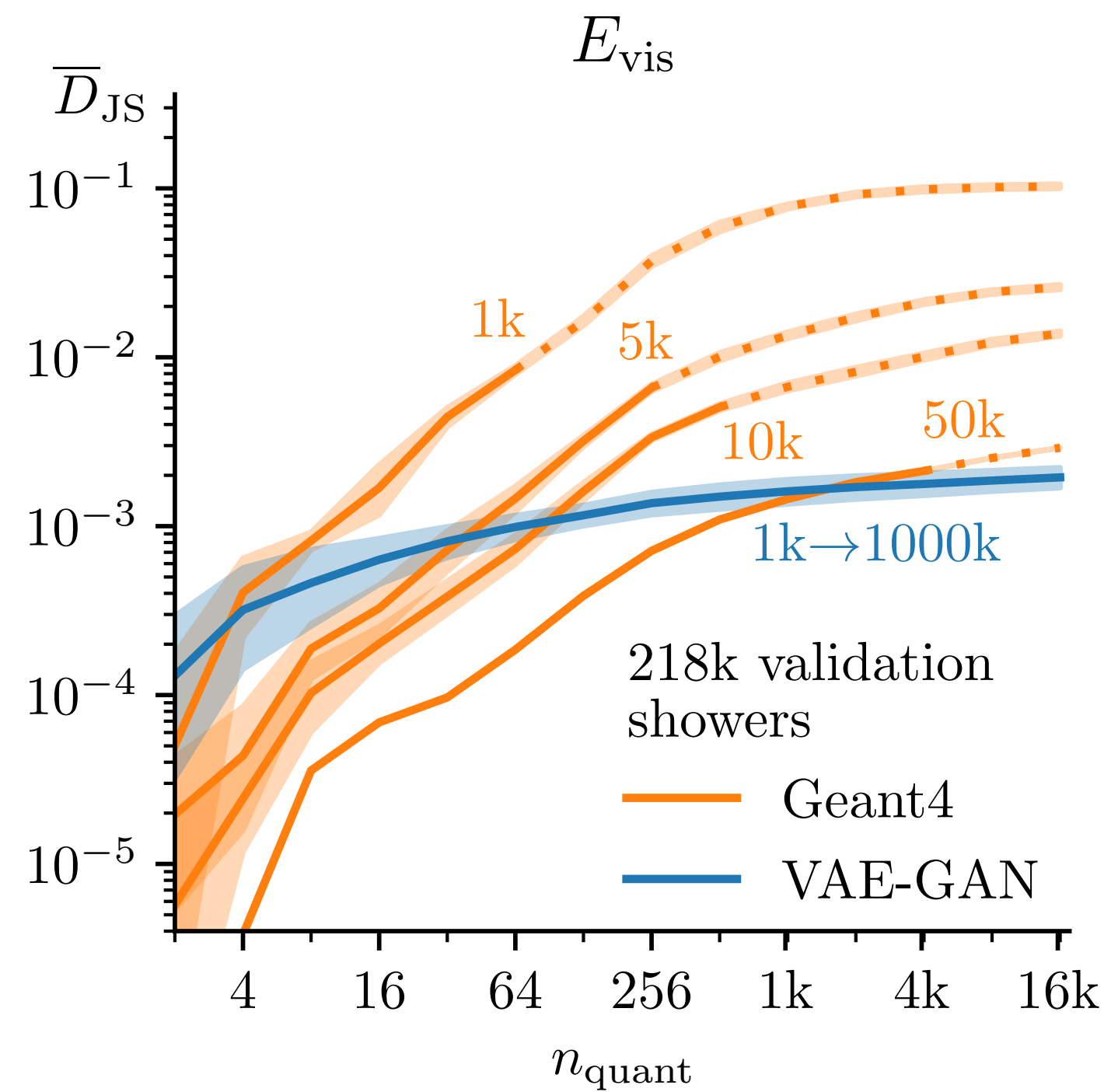
# GANplification

## 5D Gaussian



[2008.06545]

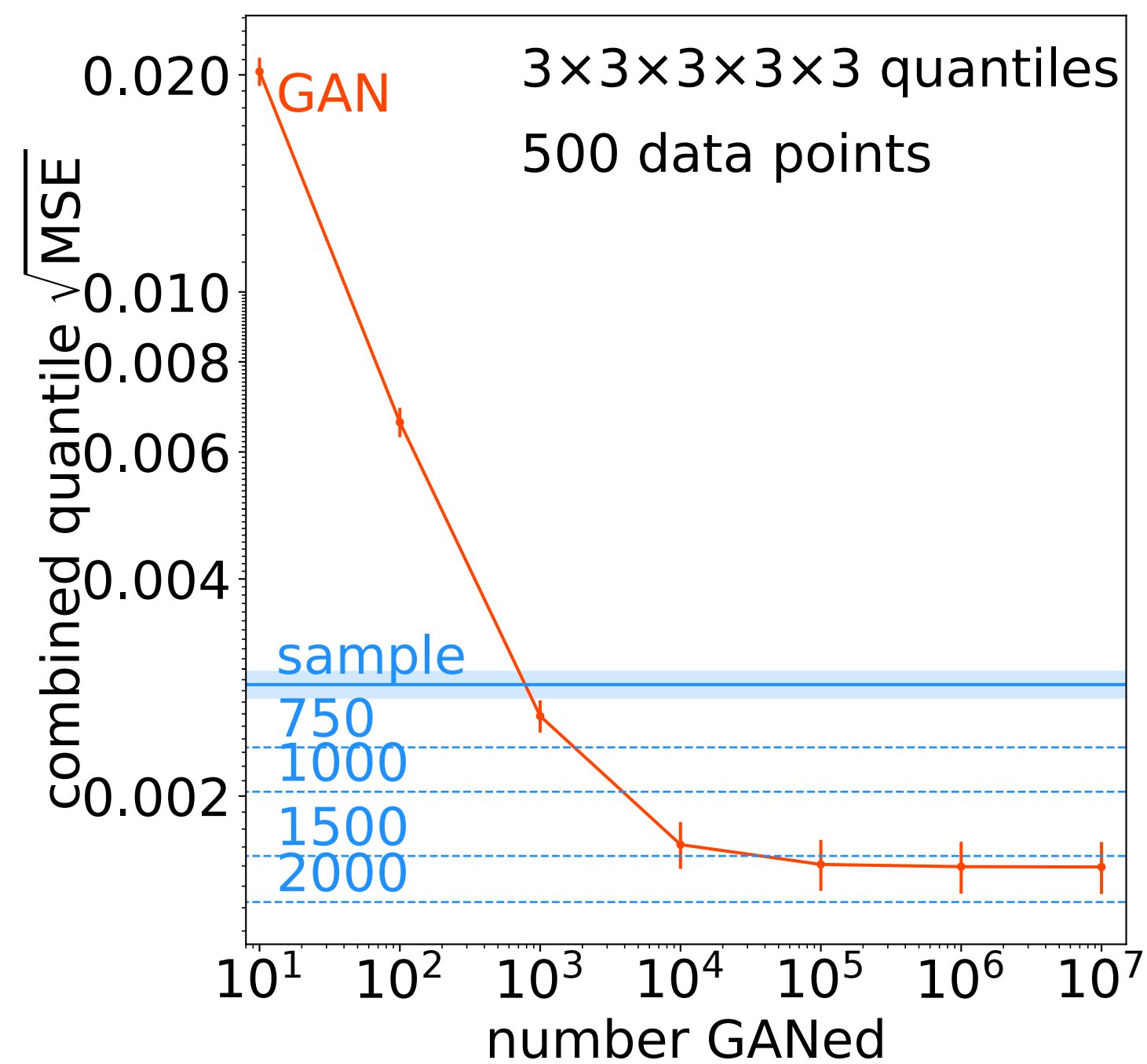
## Calorimeter Simulation



[2202.07352]

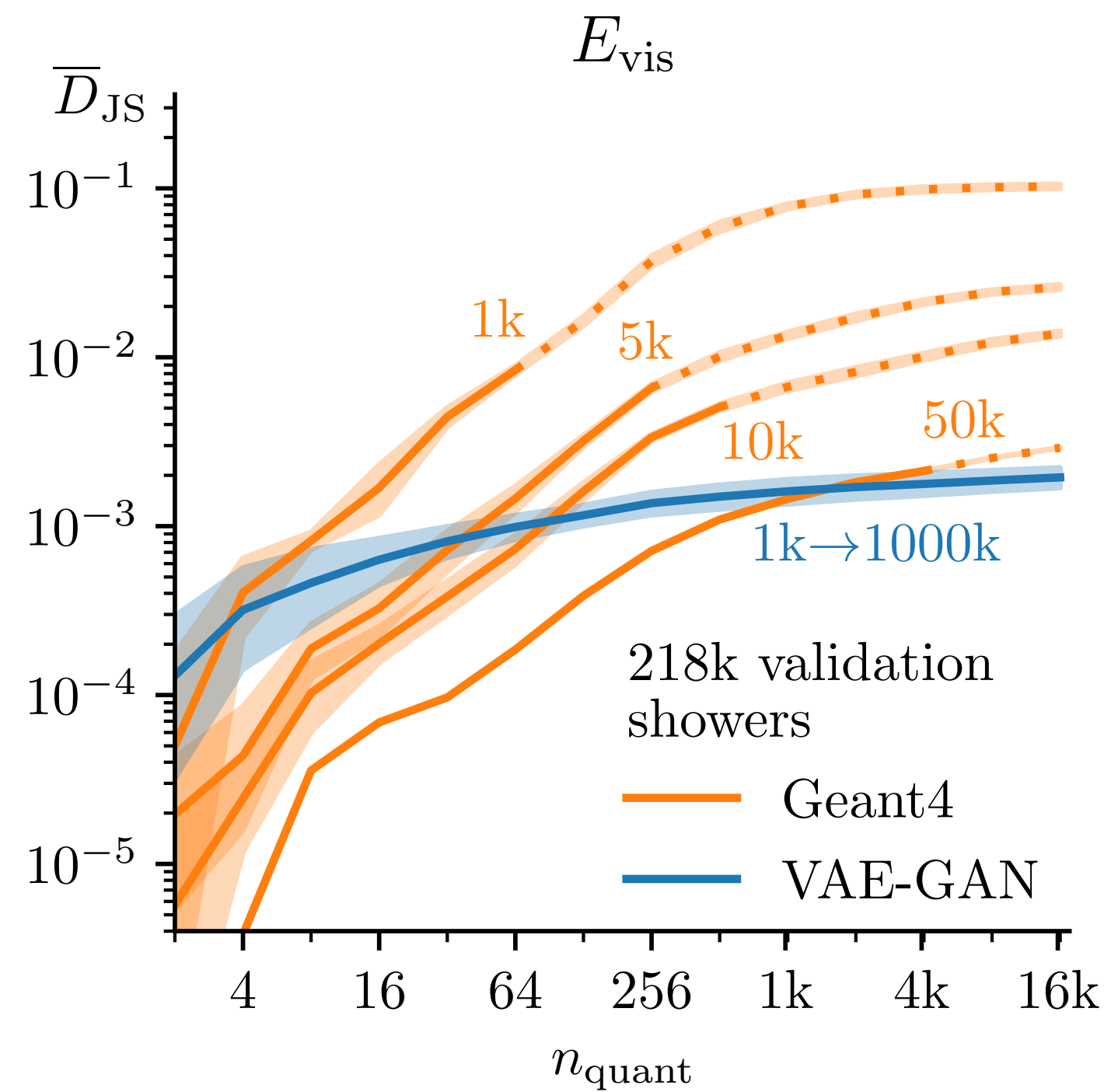
# GANplification

## 5D Gaussian



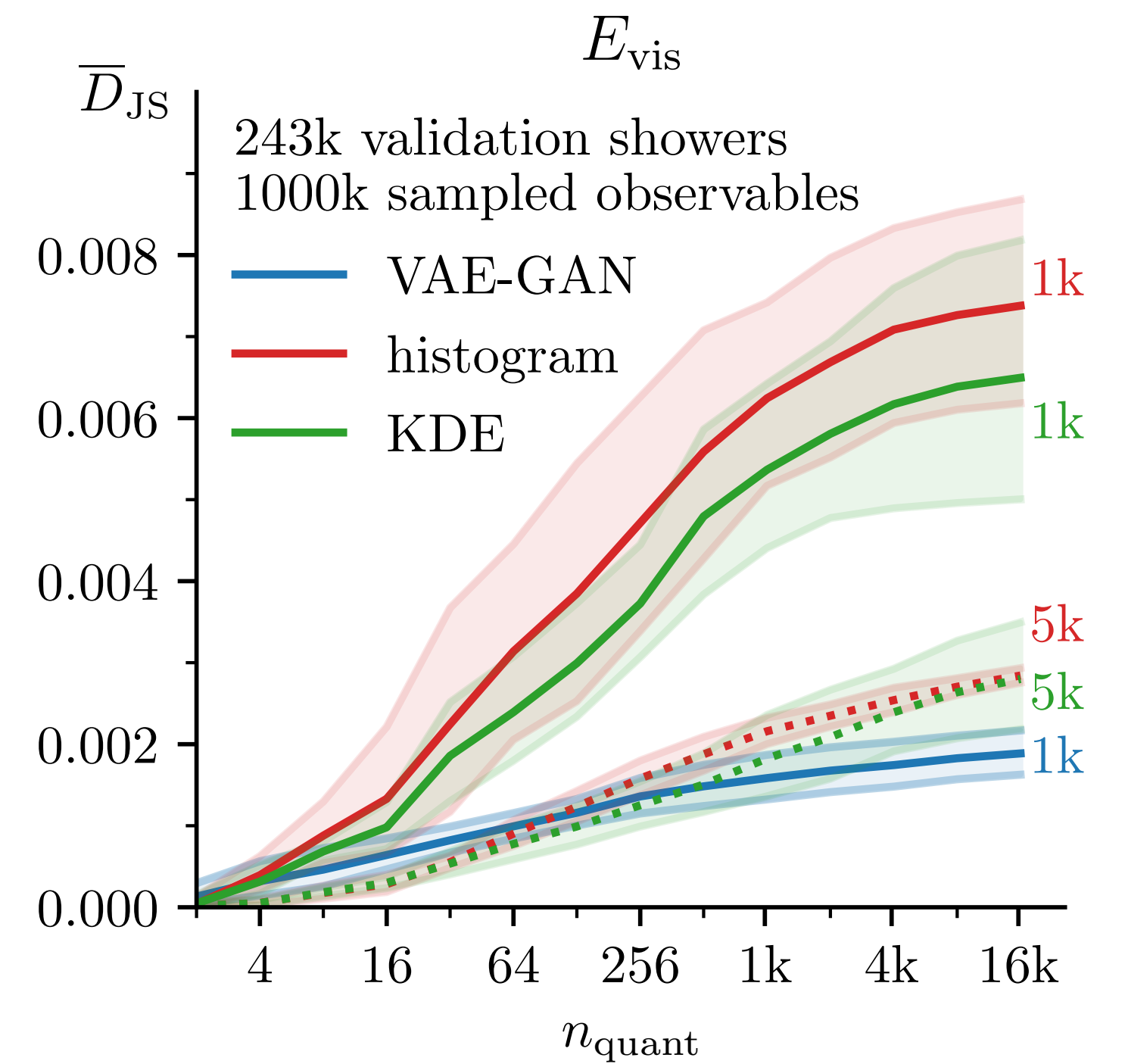
[2008.06545]

## Calorimeter Simulation



[2202.07352]

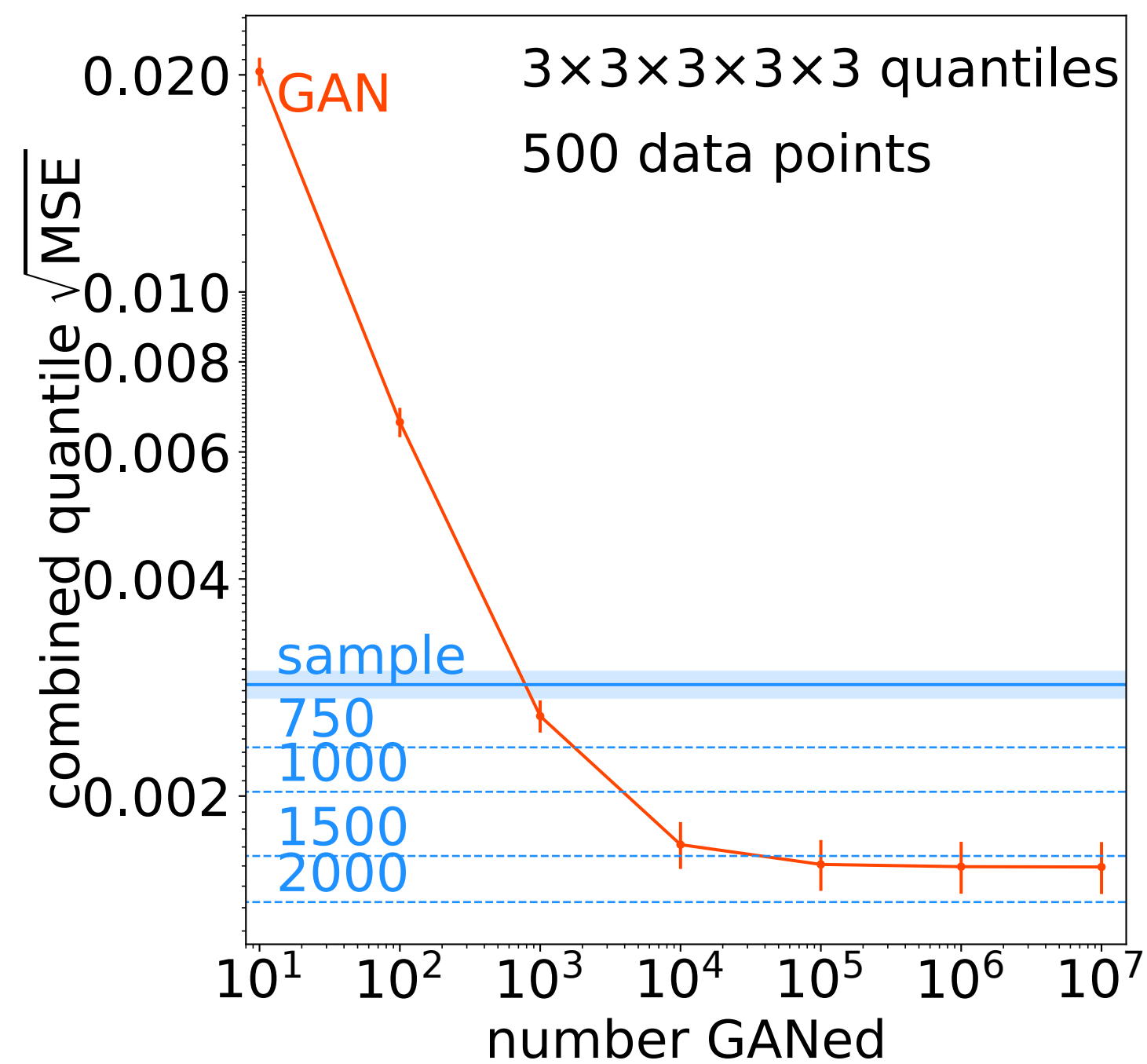
## Method Comparison



[2202.07352]

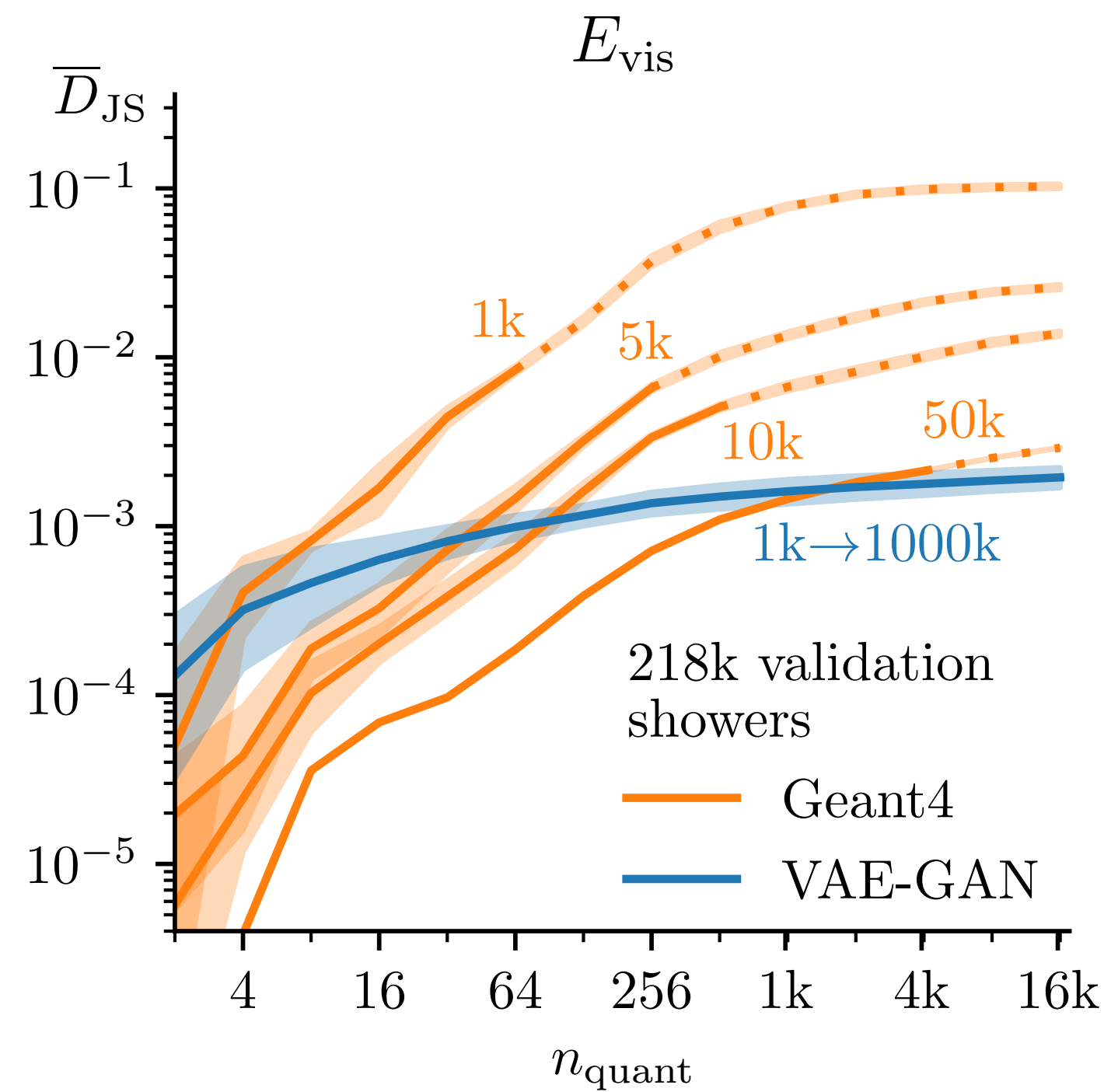
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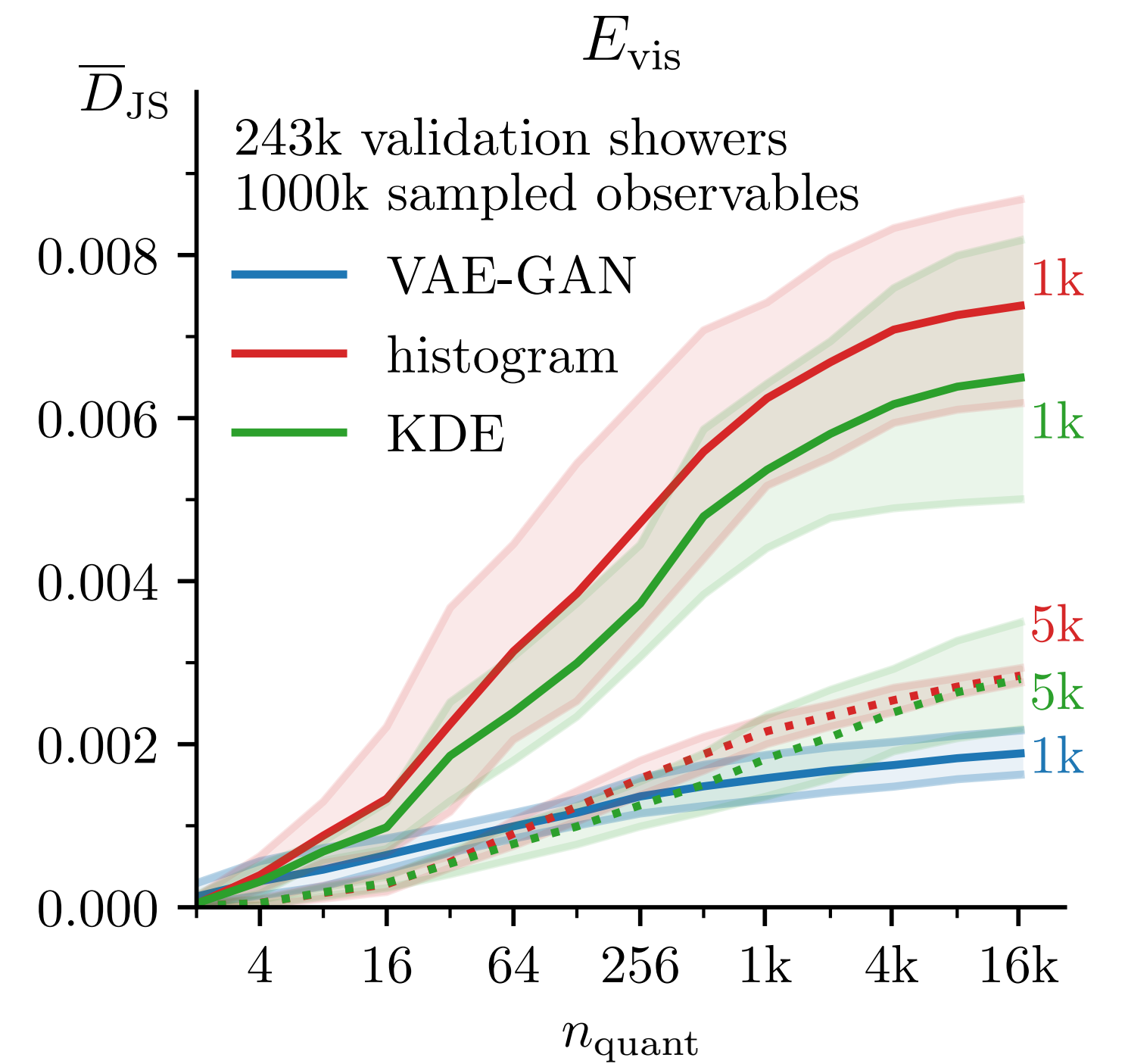
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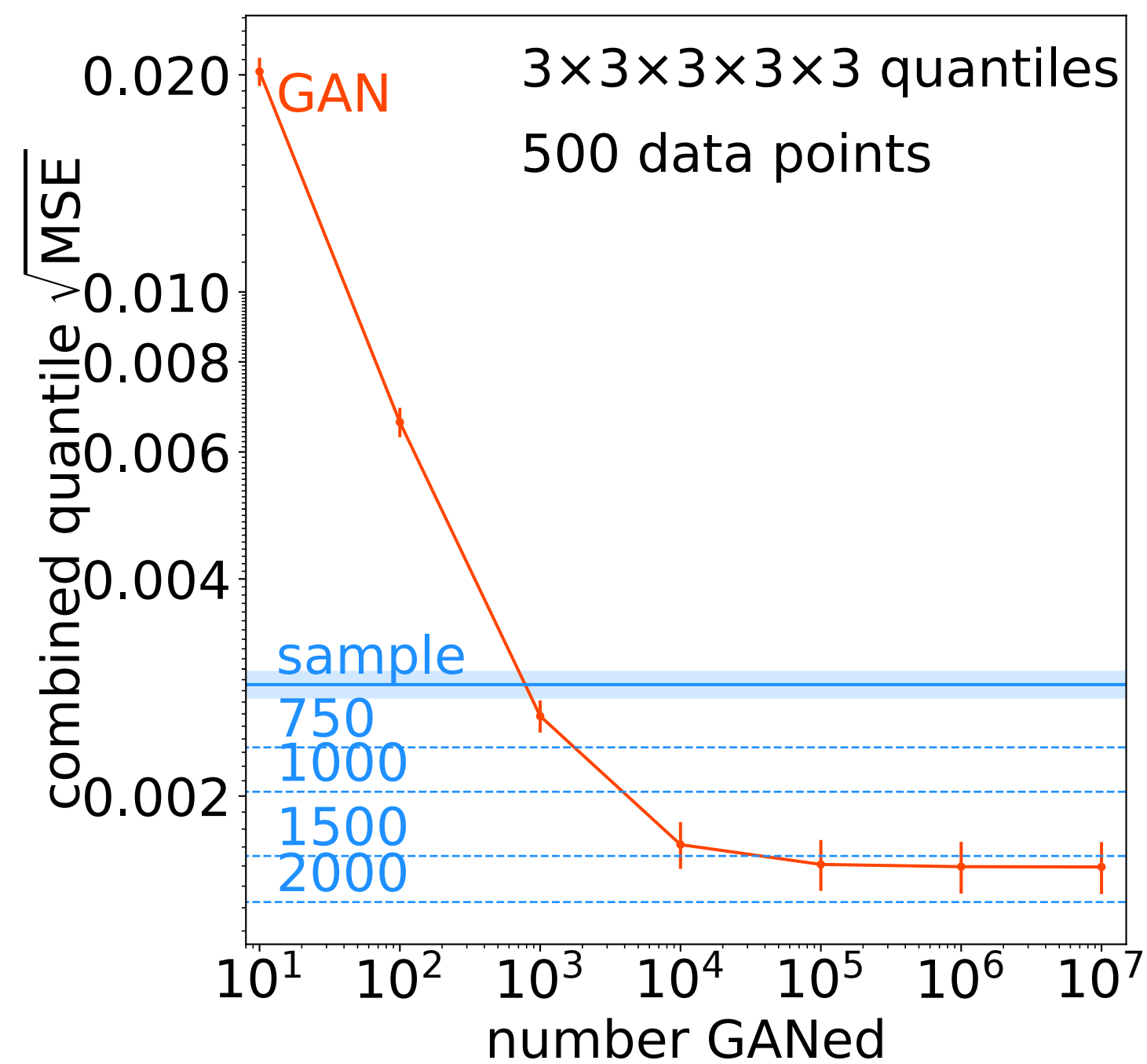
[2202.07352]

→ works for **different DGMs**



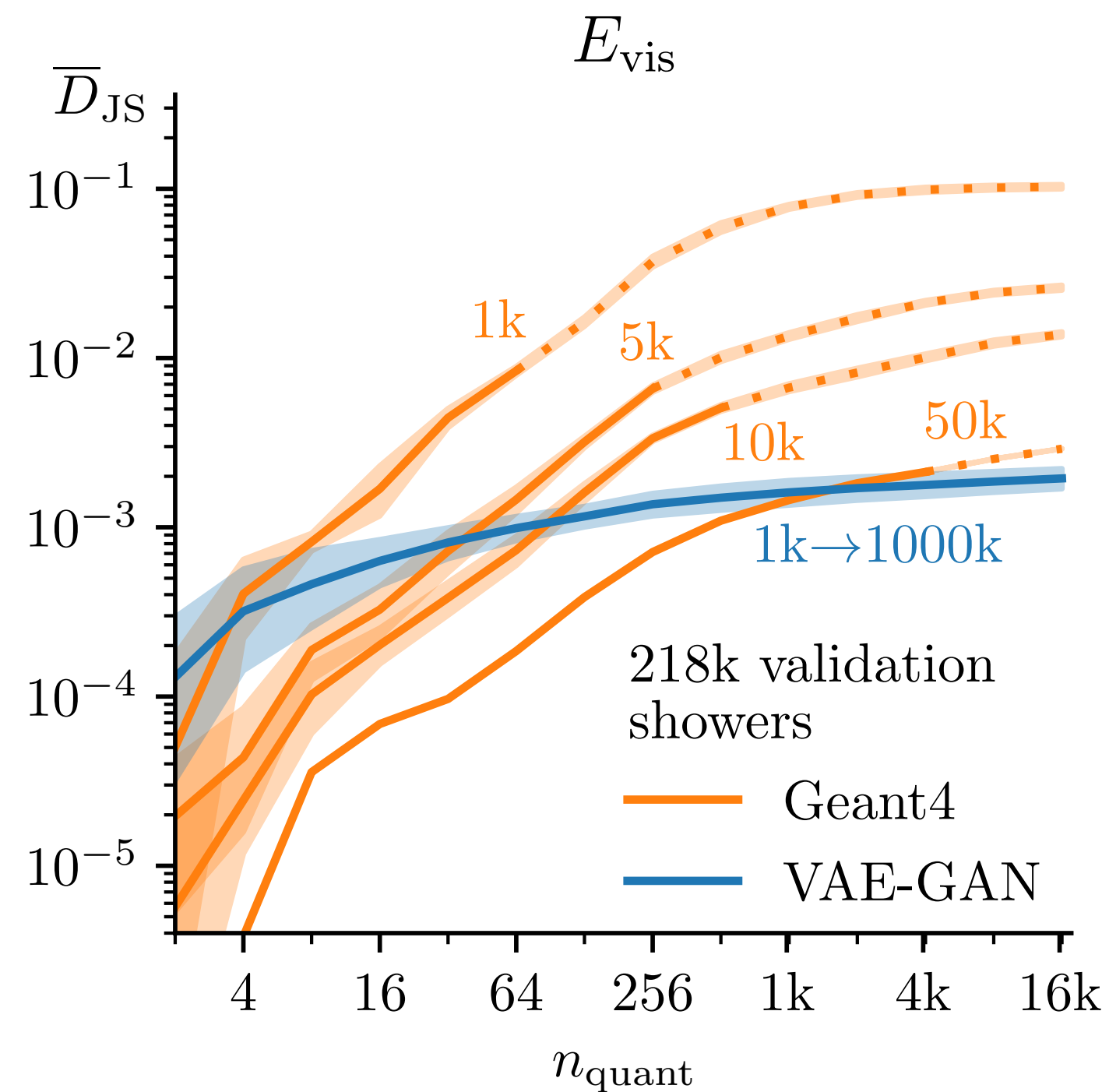
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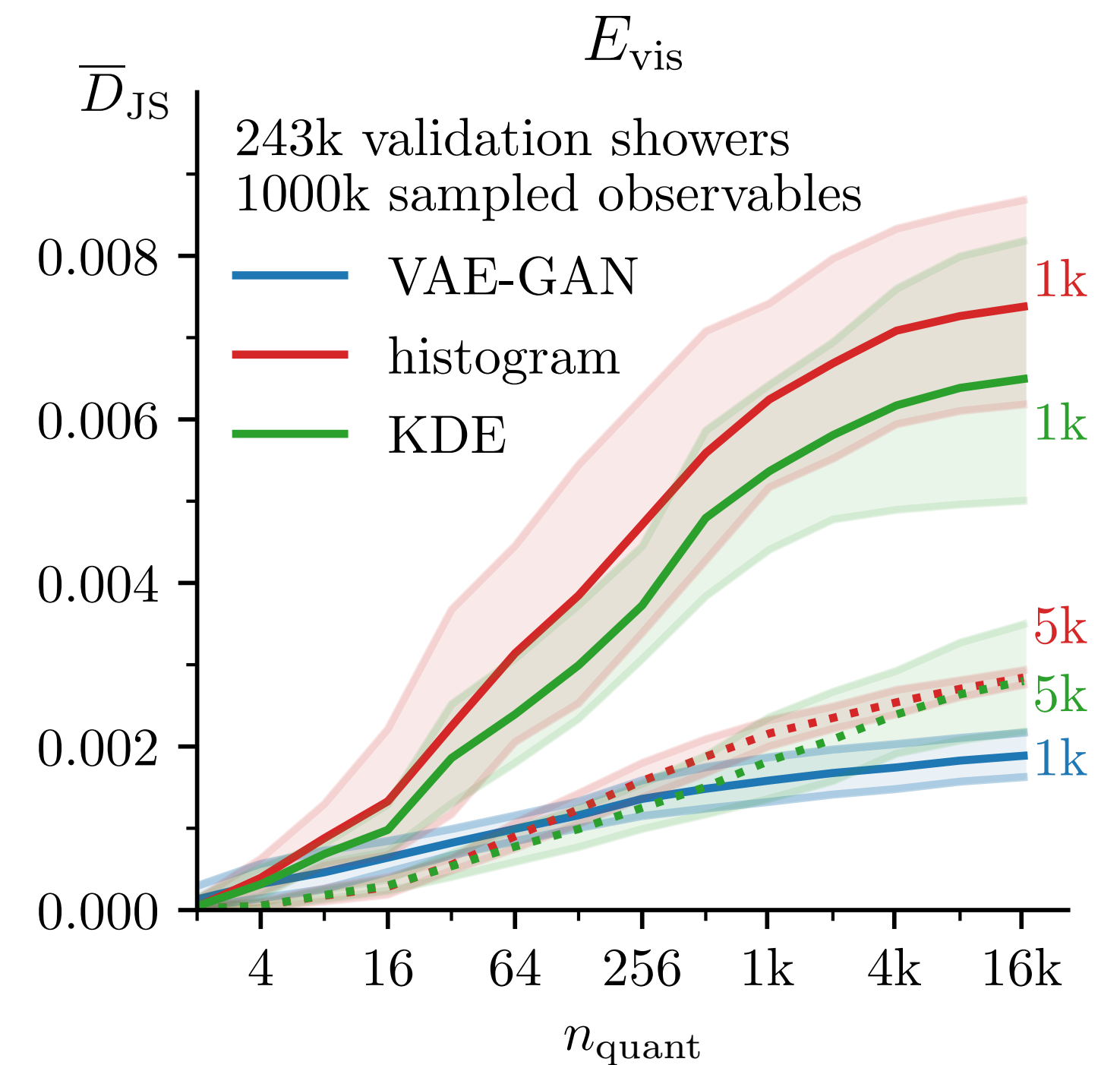
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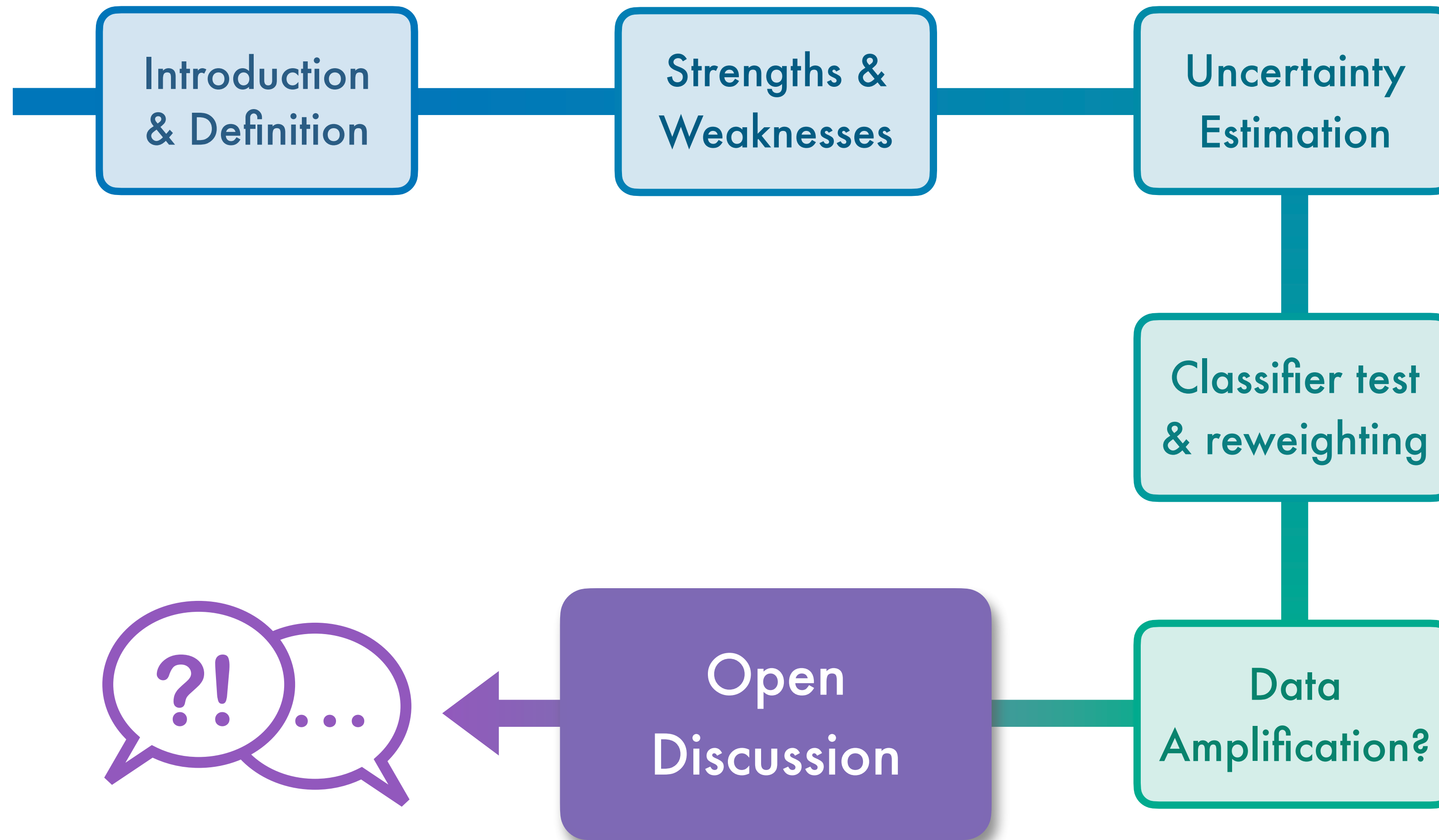


[2202.07352]

→ works for **different DGMs**

→ More details and link to BNNs, **see talk from G.Kasieczka and [2408.00838]**

# Deep Generative Models





# Open Discussion