

1st Accelerators Technology Sector Workshop

Engineering Design Tools and Processes
Project Management Methodologies and Tools

Chair: Mike Lamont

Interconnecting knowledge, experience, methods,
people & data to foster learning & collaboration



ATS
Accelerators and
Technology Sector

Developing digital twins for accelerator magnets

Melvin Liebsch

- on behalf of the TE-MS-C-TM section -



ATS
Accelerators and
Technology Sector



Agenda

Learning from data through the lens of models is a way to exploit structure in an otherwise intractable problem [6]

- The digital twin of the accelerator magnet
- Hybrid modeling (Newton to Kepler)
 - Calibrated models
 - Delta models
 - Machine learning models
- Integration in the life cycle management
- Conclusion



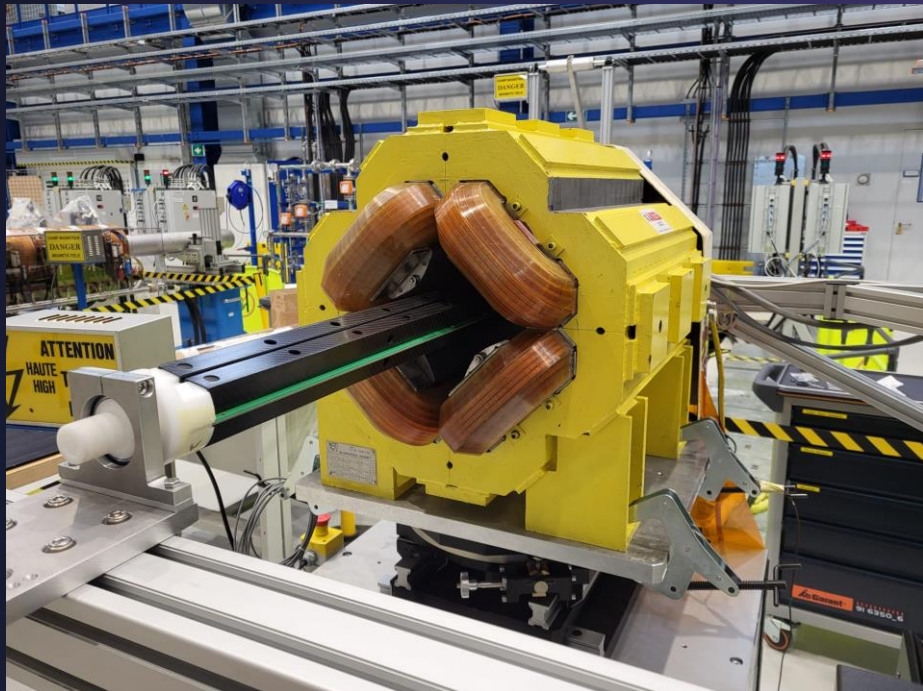
Agenda

Learning from data through the lens of models is a way to exploit structure in an otherwise intractable problem [6]

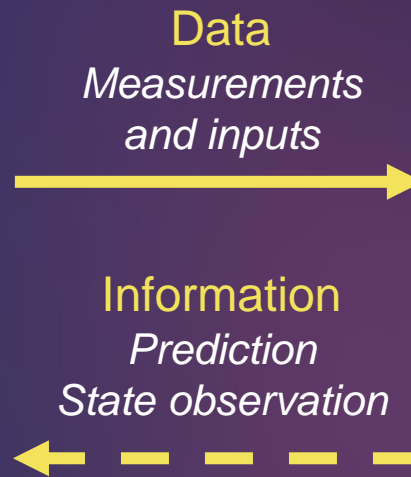
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The digital twin [1]

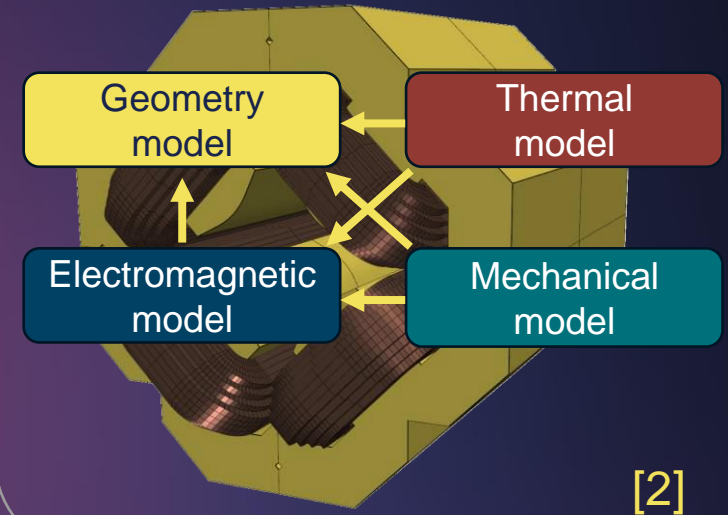
Physical object
a.k.a. accelerator magnet



Communication
channel



Digital representation
a.k.a. numerical system model

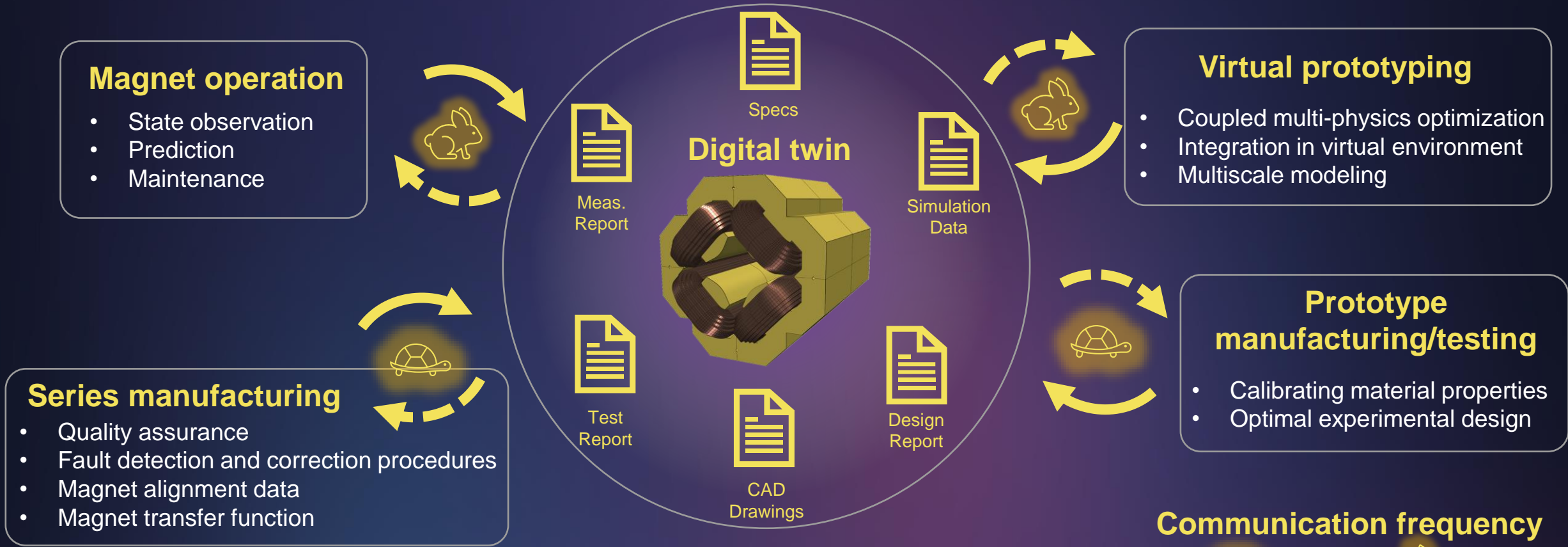


→ **The digital twin requires multi-physical modeling**

[1] Piascik, R., et al., *Technology Area 12: Materials, Structures, Mechanical Systems, and Manufacturing Road Map*. 2010, NASA Office of Chief Technologist.

[2] M. Maciejewski, B. Auchmann, D. M. Araujo, G. Vallone, J. Leuthold and J. Smajic, "Model-Based System Engineering Framework for Superconducting Accelerator Magnet Design," in *IEEE Transactions on Applied Superconductivity*, vol. 33, no. 5, pp. 1-5, Aug. 2023, Art no. 4003105, doi: 10.1109/TASC.2023.3249647

Accelerator magnet life cycle



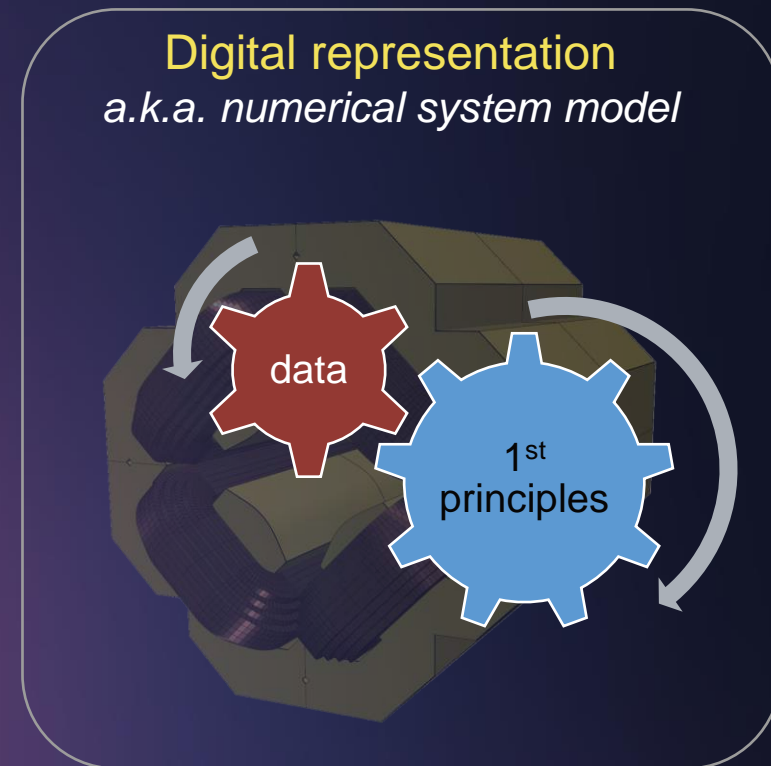
Product life cycle

→ Principles of systems modeling
 → Document based information exchange
 → Communication frequency depends on the application
 → Data management services → EMB, EMB-based, NORMA, PLM

Development life cycle

Challenges

- **Complex (non-linear) dynamic system**
 - Interplay of iron saturation, hysteresis and eddy currents
 - Superconductor magnetization
 - Temperature effects
- **Computational costs**
 - A complete 3D magnet simulation does not allow for fast predictions
- **Tough requirements for machine operation**
 - Field stability at 1 unit in 100 000
 - Field quality at 1 unit in 10 000



→ **Measurement data** needs to be **integrated** in the numerical model to enable **accurate predictions**

→ **The digital twin is a hybrid model**



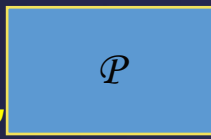
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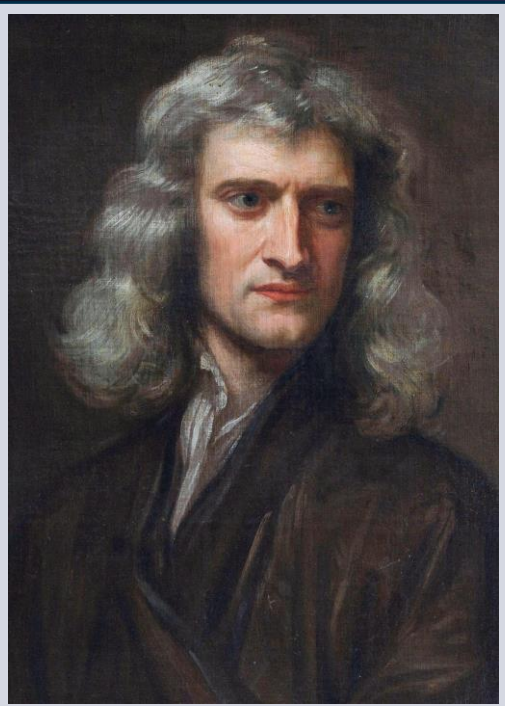
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Hybrid modeling [2]

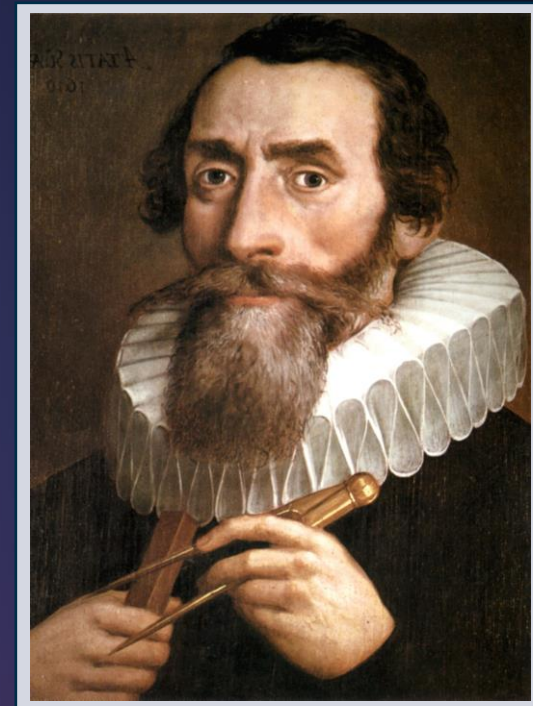
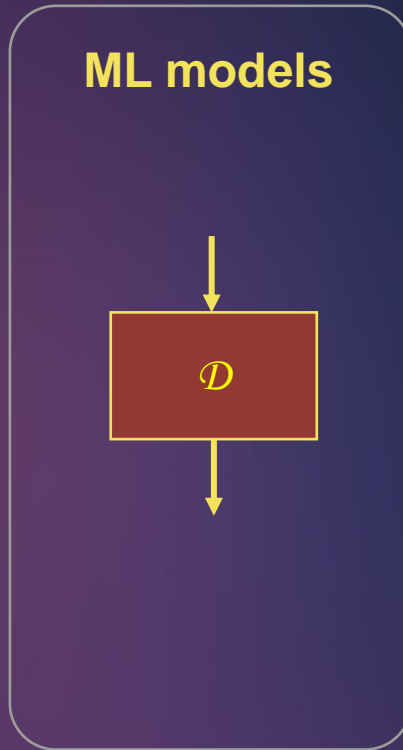
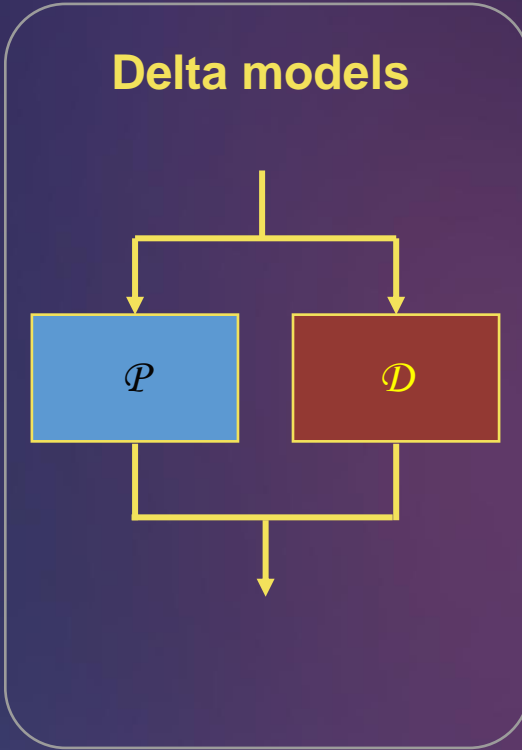
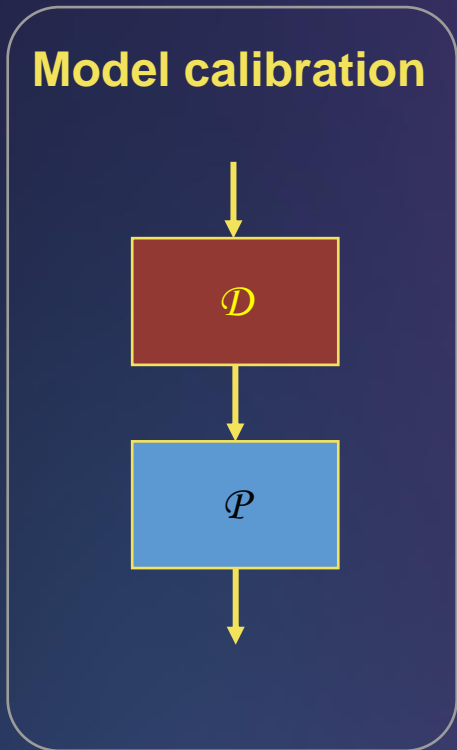
1st principle modeling
“Newtonian paradigm”



Machine learning (ML)
“Keplerian paradigm”

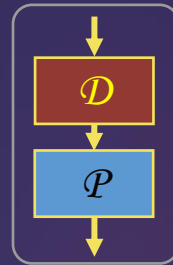


https://commons.wikimedia.org/wiki/File:Sir_Isaac_Newton_by_Sir_Godfrey_Kneller,_Bt.jpg



https://de.wikipedia.org/wiki/Johannes_Kepler#/media/Datei:Portrait_Confused_With_Johannes_Kepler_1610.jpg

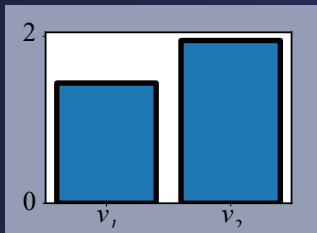
Model calibration [3]



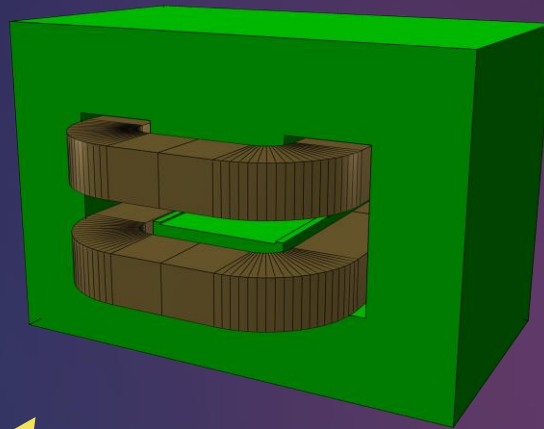
Calibration test campaign



Resulting parameters

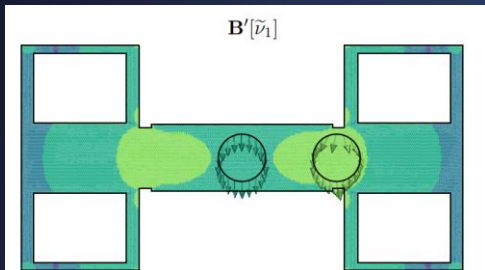


Digital twin



Design of a test campaign

Design of experiment (DOE)
 optimal sensor placement

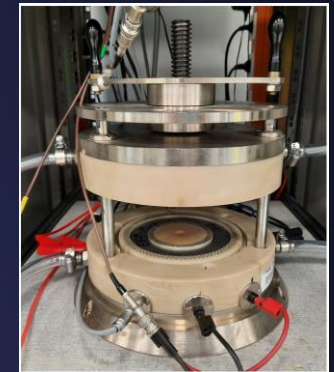


Magnet manufacturing QA

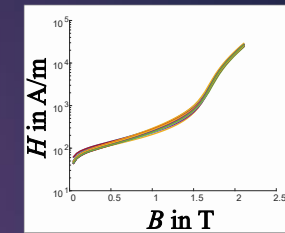
Material Specimen



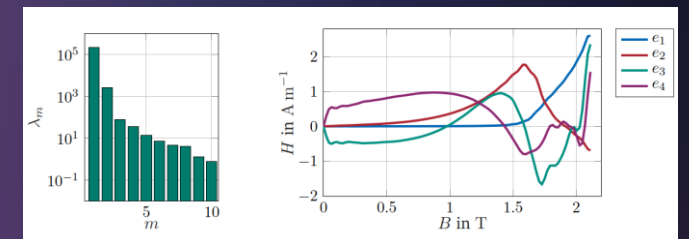
Permeameter



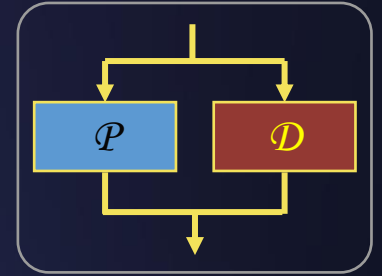
H(B)-curve



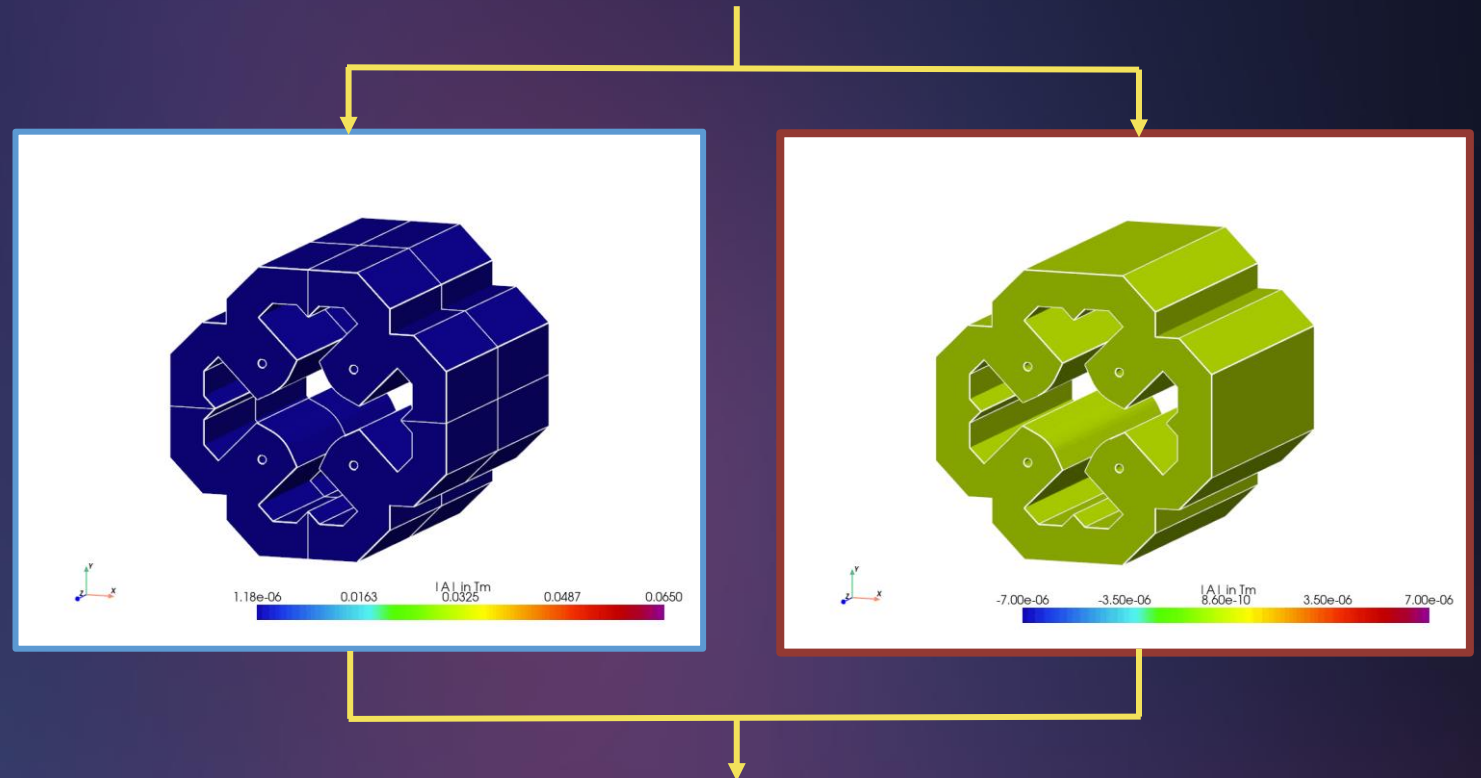
↓ Pattern recognition (KLE)



Delta models – Example



- **Discrepancy** between measurement and simulation **may not vanish** after magnet calibration
- **Discrepancy** drives the delta model
- Delta model **implies Maxwell's equations** in the vacuum domain
 $\text{curl } \mathbf{H} = \mathbf{0}, \text{div } \mathbf{B} = 0$
- **Boundary element** or **volume integral methods** have been used



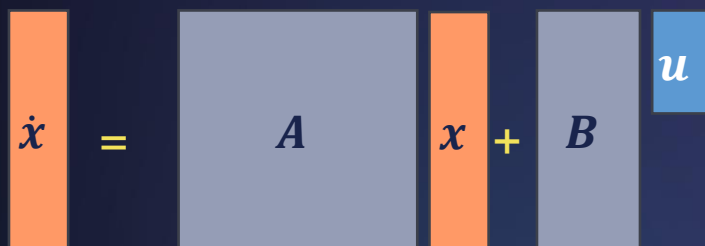
Magnet operation

Requires rapid information exchange

Model order reduction (MOR) [5]

$$\dot{x}(t) = A x(t) + B u(t)$$

High fidelity model



Reduced order model (ROM)

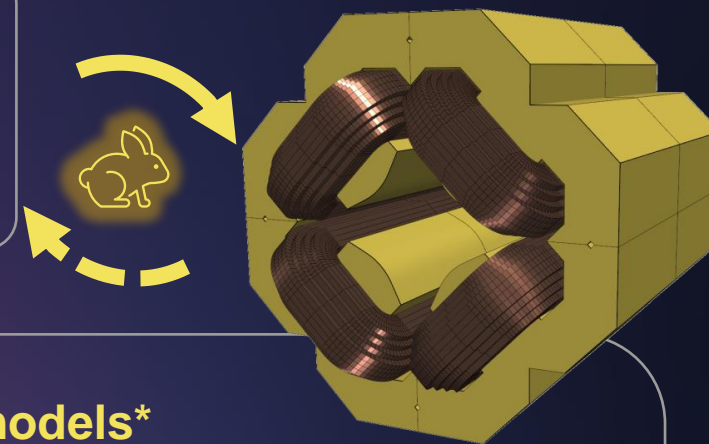


x : State vector, u : Input vector, \hat{x} : ROM state

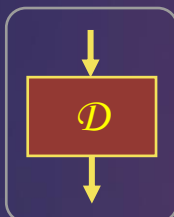
Magnet operation

- **State observation**
- **Prediction**
- Maintenance

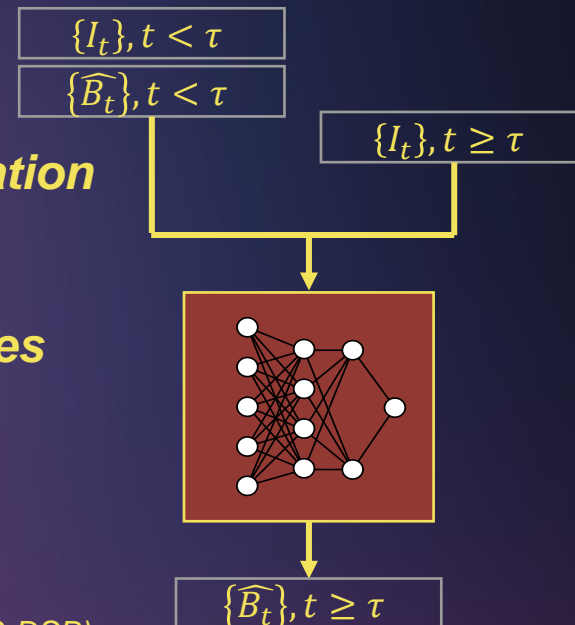
Digital twin



Machine learning models*



- Example: **Hysteresis compensation** for SPS dipole magnets
- Neural network-based **Time series modeling $B(I)$**
- Currently developed with **SPS training data**



*Example provided by A. Lu (PhD, BE-CSS-DSB)



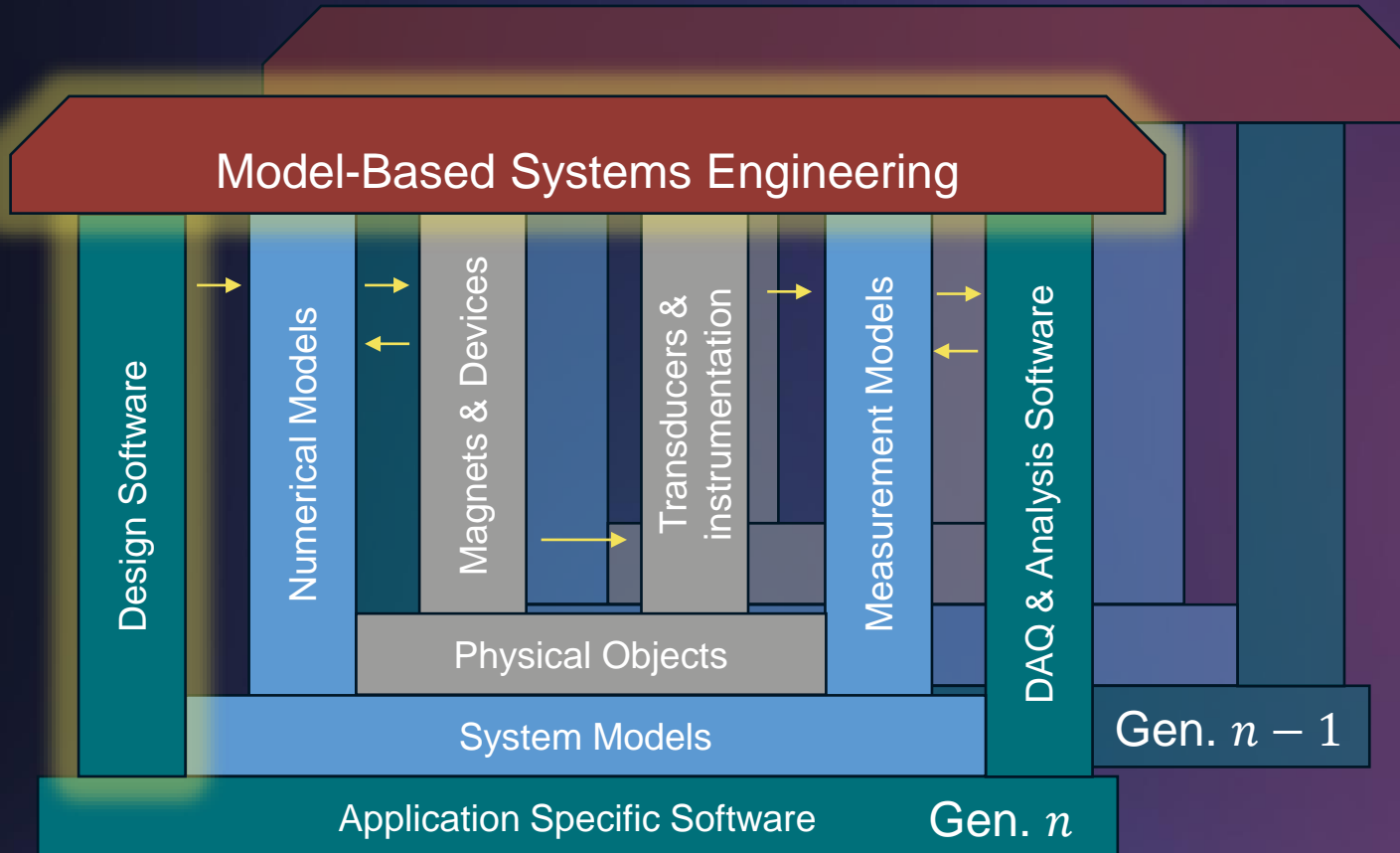
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Integration

Integrating the digital twin with **Model Based Systems Engineering**



ROXIE API* for integration in MBSE

Example gallery

Below is a gallery of examples for using this package

Output parsing and plotting

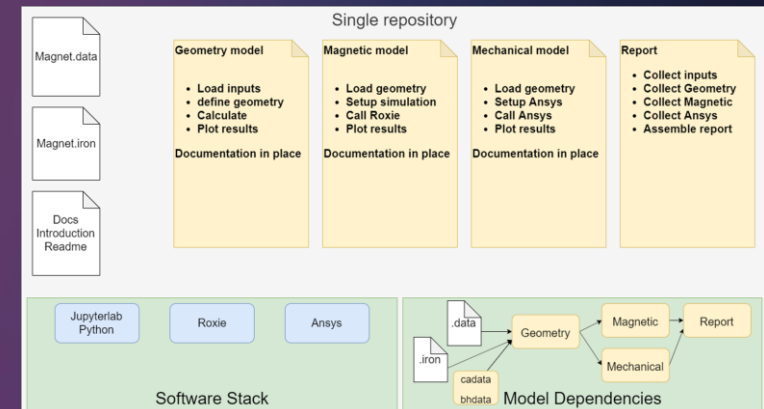
Examples using the output parsing and plotting functionality

Plot a Full run report	2D Crosssection plots	2D Forces plots	Field quality plots
Plotting of 3D wedges	Show Objectives and Design variables	3D plots	Graph plots
Custom 3D plots	Custom plots in 2D		



code available

pyMBSE: self-contained multi model execution



*Developed by M. Bonora (TE-MS-C-TM)



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Conclusion

Developing the digital twin of the accelerator magnet

- Numerical models and simulation data ***need to be integrated*** in the ***development and product lifecycle management***
- We must use ***hybrid modeling*** to design application specific digital twins
- In doing so we must follow the principles of ***model-based systems engineering***
→ ***Traceability, platform independence, versioning***
- A ***collaborative effort in the ATS sector*** will make the digital twin possible!



We need to build up the bridges together