Exercises

Introduction and practical details

Ilaria Luise - Sofia Vallecorsa | SCS 17th October 2024

Setup a kaggle account

https://www.kaggle.com/



Competitions Datasets Models Code

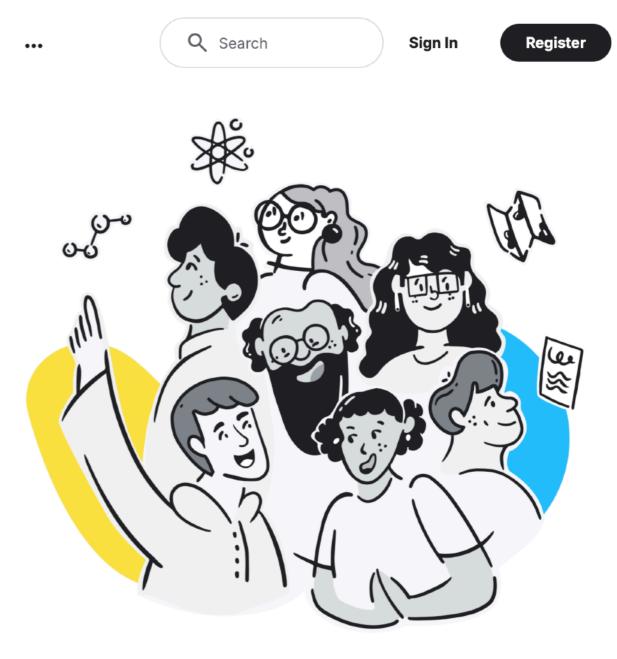
de Discussions Courses

Level up with the largest AI & ML community

Join over 20M+ machine learners to share, stress test, and stay up-to-date on all the latest ML techniques and technologies. Discover a huge repository of community-published models, data & code for your next project.

G Register with Google

Register with Email



Enable internet connection

 \mathbf{T}

- 1) Go to session options
- 2) Verify your phone if you haven't done so
- 3) Enable internet on the node

Exercise 1 - Jet tagging with neural networks

+ Code) (+ Markdown

A first look at training deep neural networks to classify jets in proton-proton collisions.

Learning objectives

- Understand what jet tagging is and how to frame it as a machine learning task
- Understand the main steps needed to train and evaluate a jet tagger
- Learn how to download and process data with the <u>@</u> Datasets library
- Gain an introduction to the fastai library and how to push models to the Hugging Face Hub

References

- Chapter 1 of Deep Learning for Coders with fastai & PyTorch by Jeremy Howard and Sylvain Gugger.
- The Machine Learning Landscape of Top Taggers by G. Kasieczka et al.
- How Much Information is in a Jet? by K. Datta and A. Larkowski.

↓ □	Session options	
	ACCELERATOR	
	None •	
	LANGUAGE	
	Python •	
	PERSISTENCE	
	No persistence	
	ENVIRONMENT	
	Pin to original environment -	
	You won't get new packages, but your code is less likely to break. What is a notebook environment?	
	INTERNET	
	Internet on	
	TAGS	
	Add Tags	

(Optional) Weights and biases

1) Go to: https://wandb.ai/site

2) Login instructions: need to copy the API key when asked

Quickstart: Tracking your first run in Weights & Biases

Weights & Biases' tools make it easy for you to quickly track experiments, visualize results, spot regressions, and more. Simply put, Weights & Biases enables you to build better models faster and easily share findings with colleagues.



1. Set up the wandb library

Install the CLI and Python library for interacting with the Weights and Biases API.

pip install wandb

Next, log in and paste your API key when prompted.

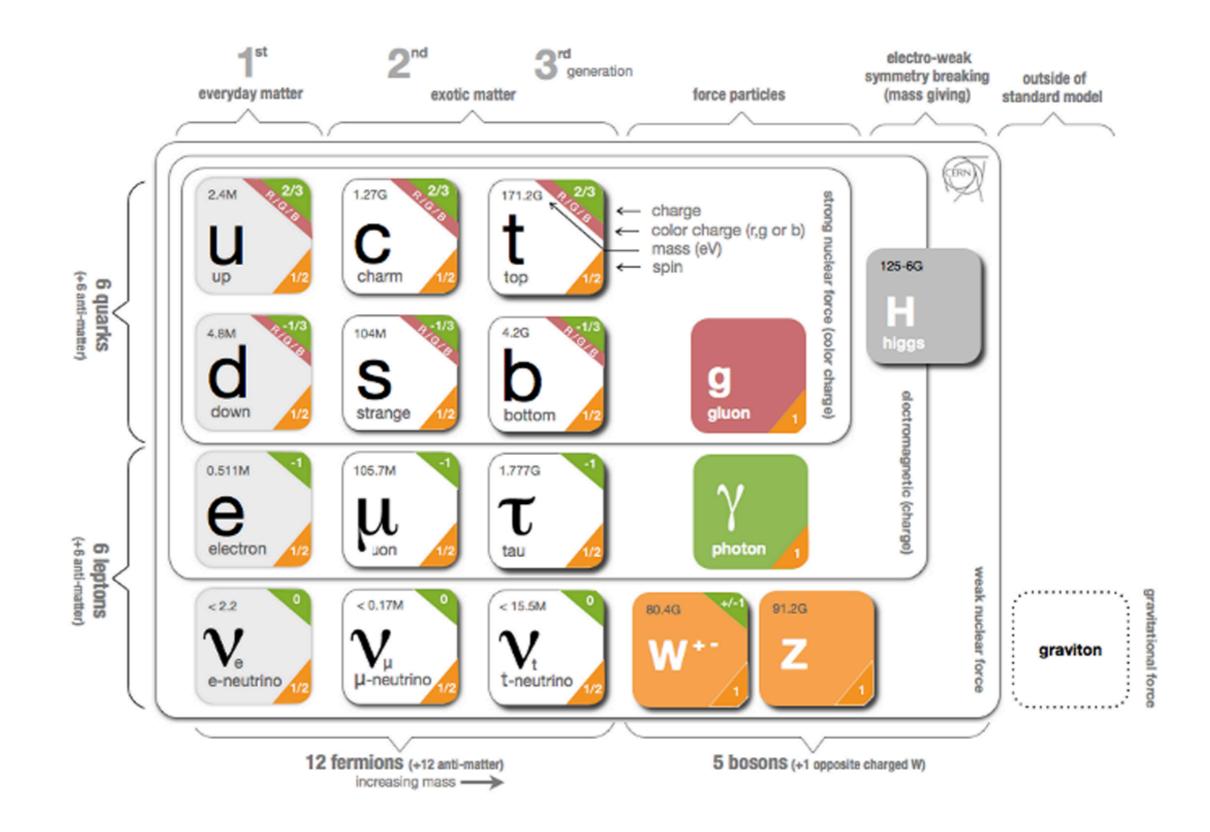
wandb login

Particle Tagging

What is it and why is it important?

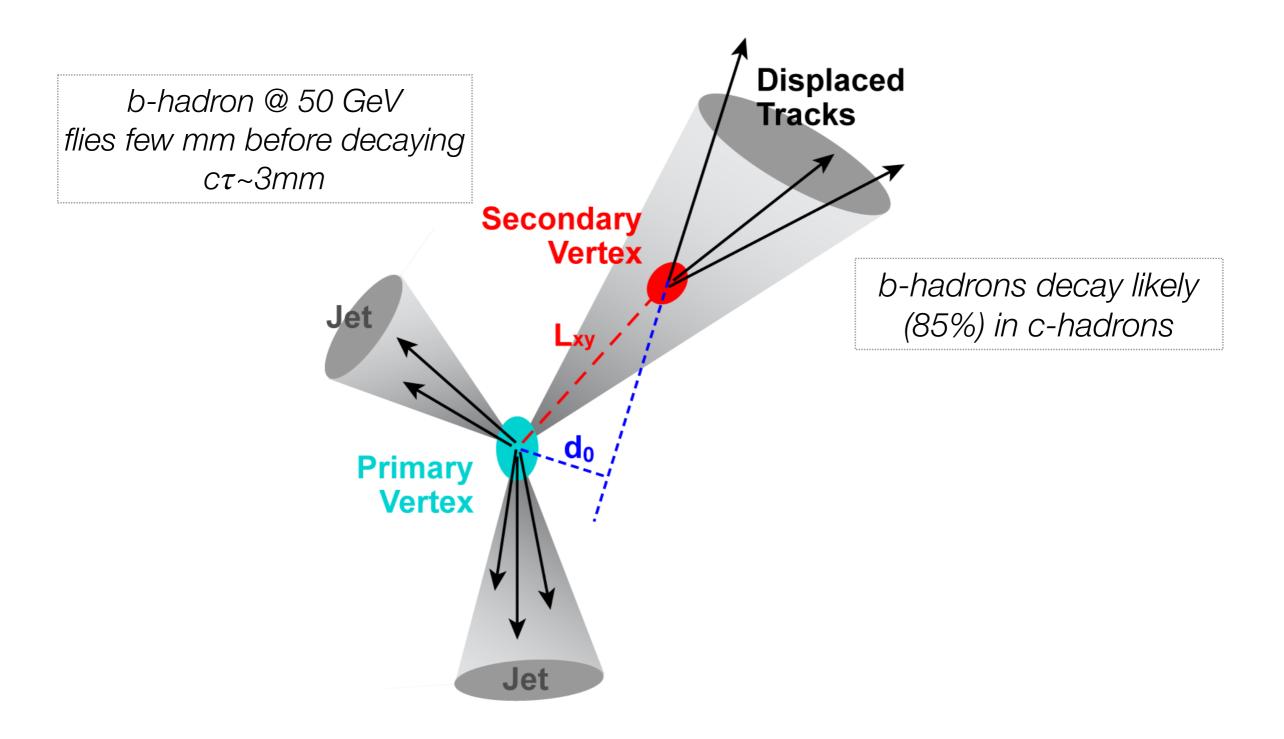
Ilaria Luise - Sofia Vallecorsa | SCS 17th October 2024

The standard model



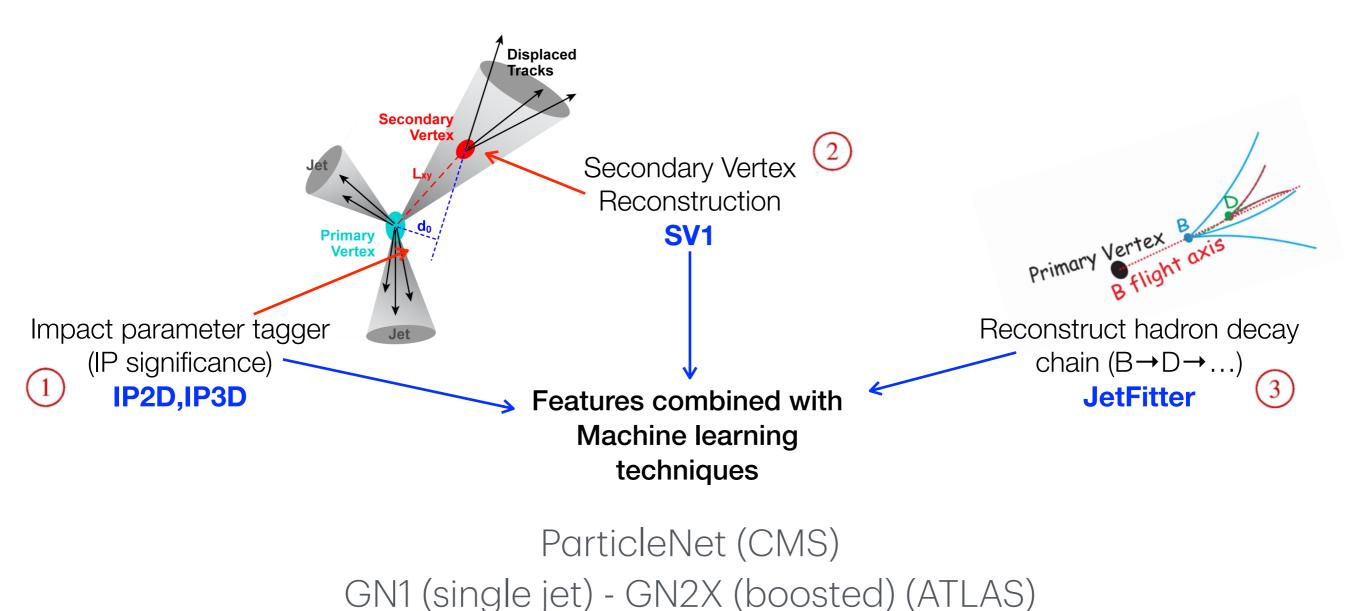
Flavour tagging

b-tagging: Separate b-jets from light (u,d,s,g) and c-jets using specific b-hadron properties



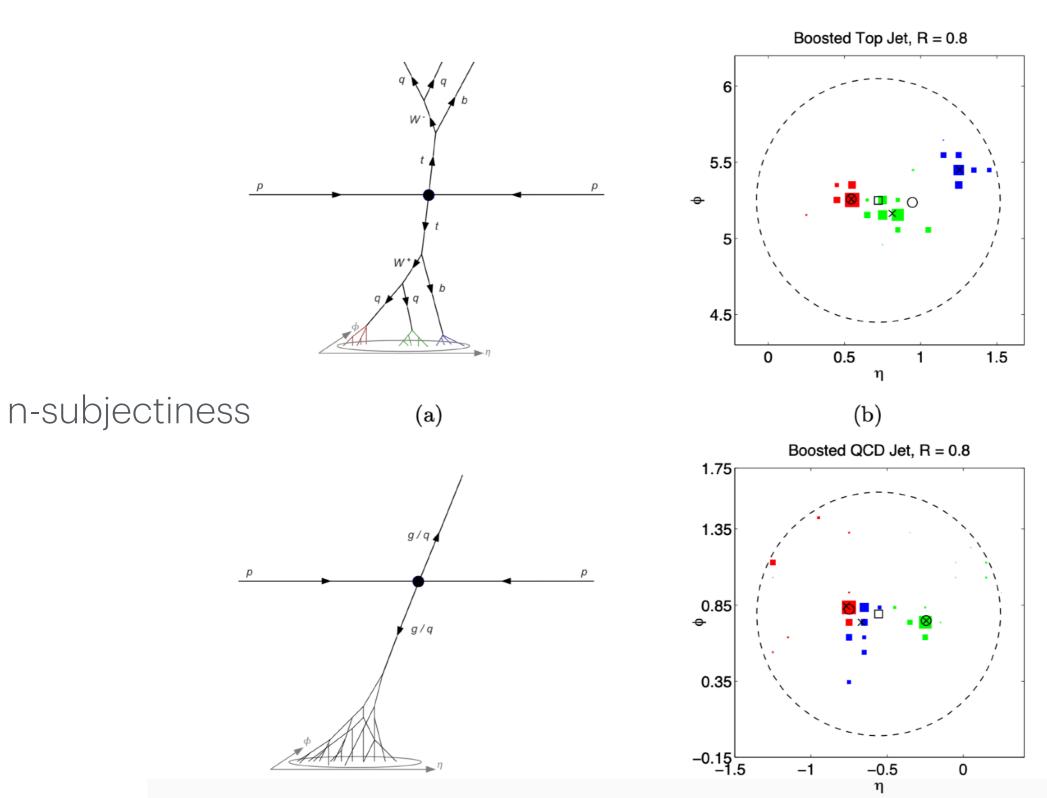
Flavour tagging

b-tagging: Separate b-jets from light (u,d,s,g) and c-jets using specific b-hadron properties



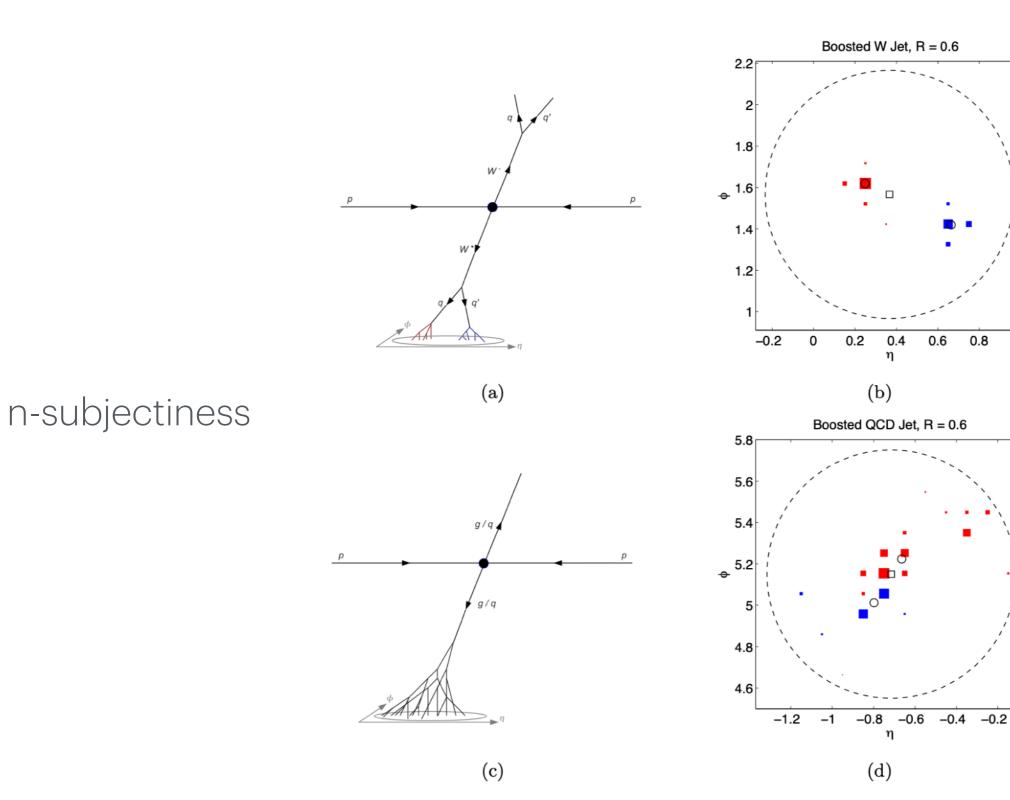
Top tagging

top-tagging: identify boosted top-jets topologies



Top tagging

Other backgrounds



1

ATLAS: top taggers

Tagger	Number of parameters	Inference time		
hlDNN	133,381	3 ms		
DNN	876,641	3 ms		
EFN	959,251	4 ms		
PFN	754,501	3 ms		
ResNet 50	1,499,585	20 ms		
ParticleNet	764,887	143 ms		

Accuracies

Tagger	AUC	ACC	ε_{bkg}^{-1} @ $\varepsilon_{sig} = 0.5$	ε_{bkg}^{-1} @ $\varepsilon_{sig} = 0.8$
ResNet 50	0.872 ± 0.006	0.787 ± 0.006	18.4 ± 1.1	4.63 ± 0.2
EFN	0.894 ± 0.001	0.810 ± 0.001	23.8 ± 0.5	5.74 ± 0.07
hlDNN	0.9374 ± 0.0001	0.8628 ± 0.0002	47.2 ± 0.4	10.36 ± 0.03
DNN	0.9447 ± 0.0004	0.8715 ± 0.0008	73.0 ± 1.3	12.5 ± 0.1
PFN	0.9502 ± 0.0004	0.878 ± 0.001	92.7 ± 1.8	14.6 ± 0.2
ParticleNet	0.9614 ± 0.0005	0.895 ± 0.001	155.8 ± 3.8	20.6 ± 0.4

Performance

	AUC	Acc	1 single	$/\epsilon_B \ (\epsilon_S = 0.5)$	3) median	#Param
			single	mean	meutan	
CNN [16]	0.981	0.930	$914{\pm}14$	$995{\pm}15$	$975{\pm}18$	610k
ResNeXt [31]	0.984	0.936	1122 ± 47	1270 ± 28	1286 ± 31	1.46M
TopoDNN [18]	0.972	0.916	$295{\pm}5$	$382\pm$ 5	378 ± 8	59k
Multi-body N -subjettiness 6 [24]	0.979	0.922	792 ± 18	$798{\pm}12$	$808{\pm}13$	57k
Multi-body N -subjettiness 8 [24]	0.981	0.929	867 ± 15	$918{\pm}20$	$926{\pm}18$	58k
TreeNiN [43]	0.982	0.933	$1025{\pm}11$	$1202{\pm}23$	$1188{\pm}24$	34k
P-CNN	0.980	0.930	732 ± 24	$845{\pm}13$	$834{\pm}14$	348k
ParticleNet [47]	0.985	0.938	1298 ± 46	$1412{\pm}45$	$1393{\pm}41$	498k
LBN [19]	0.981	0.931	836 ± 17	$859{\pm}67$	$966{\pm}20$	705k
LoLa [22]	0.980	0.929	722 ± 17	$768{\pm}11$	765 ± 11	127k
LDA [54]	0.955	0.892	$151{\pm}0.4$	$151.5{\pm}0.5$	$151.7{\pm}0.4$	184k
Energy Flow Polynomials [21]	0.980	0.932	384			1k
Energy Flow Network [23]	0.979	0.927	633 ± 31	$729{\pm}13$	$726{\pm}11$	82k
Particle Flow Network [23]	0.982	0.932	891±18	$1063{\pm}21$	$1052{\pm}29$	82k
GoaT	0.985	0.939	$ 1368 \pm 140$		$1549{\pm}208$	35k

You are going to train your own CNN based tagger: How does it compare to these ones?

Let's get started:

https://iluise.github.io/dl4phys/intro.html