A Julia interface to the ROOT framework

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- Need for integration of the ROOT framework and more generally legacy C++ libraries had been identified in Potential of the Julia Programming Language for High Energy Physics Computing ☑, Jonas Eschle et al. (2023).
- WRAPIT! C was developed to automate generation of Julia-binding for C++ libraries.
 - Was presented at Erlangen's JuliaHEP workshop I.
 - CXXWRAP C used for the C++-Julia interface.
- $\operatorname{ROOT.JL}$ has been rewritten from scratch using $\operatorname{WRAPIT!}$.

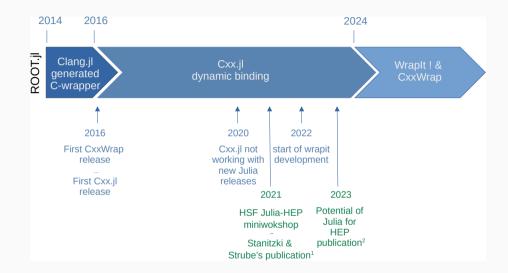
• Transparent for the Julia user:

say_hello("World") to call void say_hello(const char*)
a = A() to instantiate class A

@ccall "./libHello.so".say_hello("World"::Cstring)::Cvoid @cxx cxx_say_hello(pointer("World"))

- Support for large libraries with 1000+ classes and methods.
- Minimal effort to add the bindings to an existing C++ library and update them when the library code evolves.
 - $\Rightarrow\,$ Automatic discovery of the types and methods to bind.
 - \Rightarrow Requiring a compilation step is not a problem.

$\operatorname{ROOT.JL}$ history



Original developer: Joseep Pata; Oliver Schulz joined in 2017; Philippe Gras main developer of the CXXWRAP version, with several contributions from Pere Mato. Few other developers contributed along the ROOT.jl history.

¹ doi:10.1007/s41781-021-00053-3 🗹 ² doi:10.1007/s41781-023-00104-x 🗹

- Second ROOT.JL revolution: first was the migration to CXX.JL and dynamic binding (ala CPPYY).
- No more limited to Julia 1.3.x ! 😀
- Static binding
 - $\rightarrow\,$ Limited to ROOT classes included in the build. \thickapprox
 - ightarrow But can be relatively easily extended to more classes. \red{eq}
- C++ ROOT libraries are installed automatically.
 - Can also use an already existing installation, with constraints on the ROOT version.
- Package in the General Julia registry
 - \rightarrow Easy installation: julia>]add ROOT

Release v0.3.2

TSystem, TROOT, TInterpreter, \rightarrow System classesTH1x, TH2x, TProfile, TGraph, TAxis, TCanvas, TPad, \rightarrow Histogram, graph and plottingTF1, TF1Parameters, TFormula, TFitResults, \rightarrow Functions and fittingTRandom, \rightarrow Random number generationTFile, TDirectoryFile, TTree, TBranch, \rightarrow ROOT I/O including TTreesTTreeReader, TTreeReaderValue, TTreeReaderArray, \rightarrow Reading TTreesTObject, TClass, TNamed, TVectorD, TVectorF, TSeqCollection, TList \rightarrow Base and collection classes

Release v0.3.3-moreclasses

add https://github.com/JuliaHEP/ROOT.jl#v0.3.3-moreclasses

All classes from v0.3.2

The full Histogram package apart from TMutiGraph class

```
The full Geometry package
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Adding new classes is relatively easy

- For the easiest cases: adding the name of the class header file in the configuration file of the code generator will be enough.
- For less-easy cases, some method or types, causing issue but unneeded, will need to be added in the veto configuration file.
- For worst cases, extra development of $\operatorname{WRAPIT}!$ needed.

Templates

Most difficult cases are templated class, which have limited support in WRAPIT! (linked to libclang limitations)

Hackatron!

Working group to prioritize the classes to add, and possibly start adding them.

Click here for the demo \square

Altenative link (view from web) 🗷

Providing TFile write support using native ROOT libraries had been identified as a priority at the last JuliaHEP workshop.

- Reading/Writing histograms and any ROOT class other than TTree and RNtuple is straightfoward.
- Reading TTree is easy thanks to TTreeReader.
- Writing TTree is difficult because of "SetAddress" mechanism of ROOT.

The $\rm ROOTIO.JL$ package built on top of $\rm ROOT.JL$ will provide a higher-level interface. See next talk from Yash Solanki.

Handling of ROOT dependencies

Current system

- Since release 0.3.0 ROOT library and its dependencies downloaded from conda-forge if the expected ROOT release not found in the user environment.
- Compilation of the C++ part of the wrapper done at the $\mathrm{ROOT.JL}$ package installation time.

Pros of the current system

- Does not duplicate ROOT installation, if expected release is already installed in the user environment.
- Automatic installation of dependencies if it is not available.

Cons of the current system

- A non-standard way of managing binary dependencies of a Julia package.
- Large volume of software (4.9 GB) downloaded by Conda, which won't be shared with other Julia packages.
- Long package installation, due to Conda package installation and the compilation of the C++ part of the wrapper. ⇒ Limited number of ROOT classes in the default release.

Use of the Julia BinaryProvider, aka __JLL packages

- First discussions on a $\mathrm{ROOT_JLL}$ dates from Jan. 2019 C
- Several challenges
 - $\checkmark\,$ Both $\rm Julia$ and $\rm ROOT$ use $\rm LLVM$, but of different releases. Solved.
 - X Need to cross-compile root on Alpine (light container-oriented Linux distribution using musl as c library instead of the more common glicc). Lot of progress performed but not solved yet.
 - **✗** ROOT library must be "dlopen'ed": causes recently discovered and not-yet-understood issues.
 - \mathbf{X} Handling of compiler/libc/stdc++ version dependency.
- Will solve the package installation long time issue, by allowing to precompile the wrapper.

Hackatron

A good challenge for the Hackatron!

Several usage example shipped with the package

 $https://github.com/JuliaHEP/ROOT.jl/tree/master/examples \ \cap{2.1}$

- Histogramming, plotting, writting histogram to disk
- Fitting Histograms and Graphs
- Reading and writing TTrees

Nowadays

Users need to consult the ROOT reference manual.

Future

Help (docstring) pages generated from the ROOT doxygen-based reference manual.

Hackatron!

Development of a doxygen \rightarrow Julia help page convertor in Julia is an easy project.

Will be useful for several other projects.

Starting code already available.

- A new Julia interface to ROOT.
- Includes already many ROOT classes.
- Provides TFile writing. See next talk for a higher-level interface for TTree writing.
- Next development priority: speeding up package installation by distributing compiled c++ library as a _jll package.
- Several topics identified for the Hackatron: class prioritisation, cross-compiling challenge, doxygen-to-julia-docstring converter.