

Dissertation Defense

Riley Xu

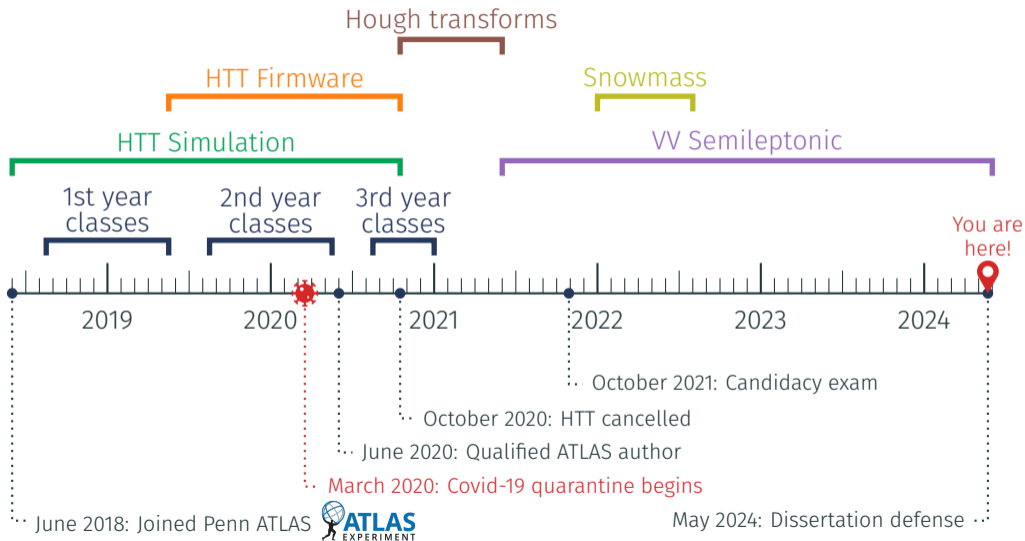
Advisor: Elliot Lipeles

May 21, 2024



- I. Introduction
- II. Hough Transforms
- III. VV Semileptonic

A Timeline



Tracking in the Trigger

- **HTT Simulation**
 - Software framework development
 - Functional simulation of hardware
 - Generating and optimizing patterns
- **HTT Firmware**
 - Sensor drivers
 - Power-up handshakes and protocols
 - Gigabit transceivers
 - Booting Linux on SoCs
- **Hough Transforms**
 - Converting HTTSim and maintenance
 - Implementing Hough algorithms
 - Algorithm optimizations

Analysis

- **Snowmass 2021**
 - Estimating future collider reaches
 - Summary plots for SUSY particles
- **VV Semileptonic**
 - Unfolding studies
 - Fiducial region definition
 - Fit validation
 - Sensitivity studies
 - ANN W/Z tagger mass window
 - $t\bar{t}$ background rejection
 - EFT interference resurrection
 - V+jets background modeling
 - Functional fits
 - Gaussian process regression

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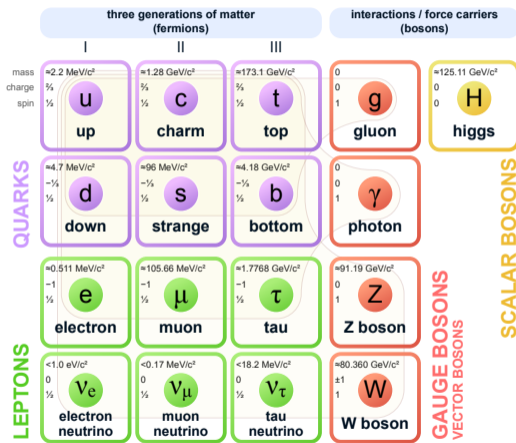
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The Standard Model

- The Standard Model (SM):
 - Current model of the fundamental universe
 - Elementary particles and 3/4 forces
 - Well tested and accepted
- But incomplete! Missing:
 - Gravity
 - Neutrino masses / oscillations
 - Dark matter
- And some looming experimental discrepancies:
 - CDF W mass measurement
 - Muon $g - 2$

Standard Model of Elementary Particles



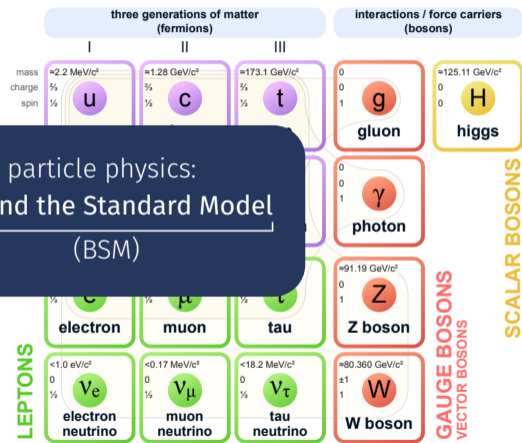
Wikimedia

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Goal of modern particle physics:
Discover physics beyond the Standard Model
(BSM)

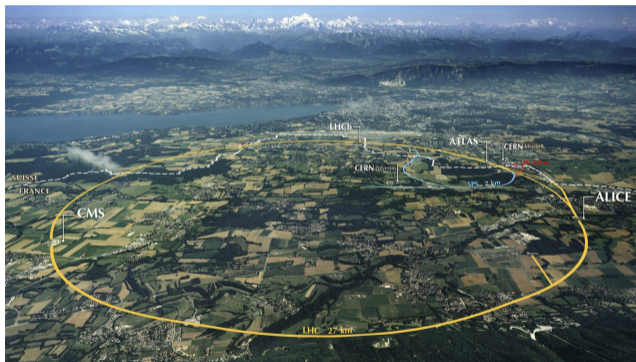
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Wikimedia

Searching for BSM Physics: Large Hadron Collider

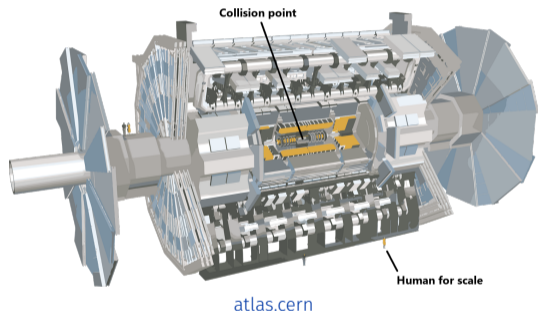
- What does BSM physics look like?
 - We don't know...but many theories
 - Usually postulate new, massive particles
 - Need to probe high energies
- Large Hadron Collider (LHC):
 - 27km underground ring by Geneva
 - Accelerates protons to 99.9999991% speed of light
 - Collided head-on to create massive particles
 - Detectors monitor collision products



Maximilien Brice

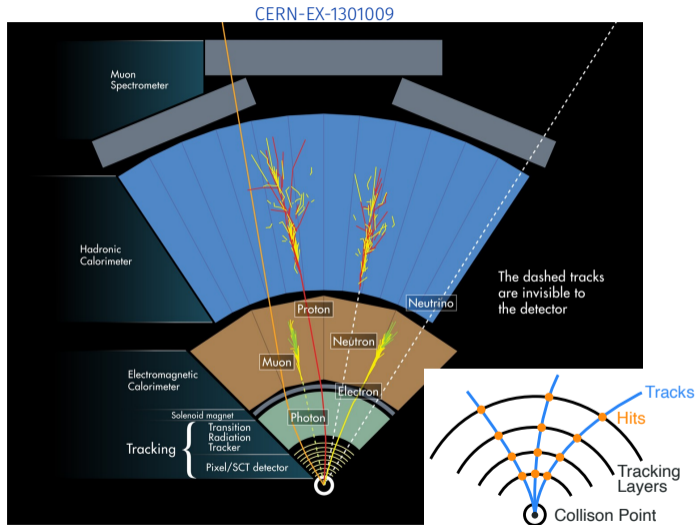
The ATLAS Detector

- General purpose detector on LHC ring
 - Monitors proton-proton collision products
 - Several layered systems to identify variety of particles
- A 7000 tonne machine
 - Approved in 1995, finished in 2008
 - 46 meters long, 25 meters diameter
- Collaboration of >6000 people from 47 countries



Particle Reconstruction

- Particles fly through detector and leave **hits**
- Reconstruction: hits \rightarrow particles
 - “Connect-the-dots” \rightarrow **tracks** (particle momentum)
 - Calorimeter showers \rightarrow **jets** (particle energy)
 - Where hits occur \rightarrow particle type



Tracking in the Trigger: Hough Transforms

- BSM physics is rare...
 - LHC collides **lots** of protons, once every 25ns
 - ATLAS generates 120 TB of data every second
 - Impossible to save everything
- Trigger:
 - Filter out “boring” (low-energy) data on the fly
 - Must filter down by a factor of $\approx 40,000$
 - Must be **efficient**: don't throw out interesting events on accident
- Need tracking in the trigger!
 - Currently using software tracking in CPUs
 - Very power intensive, unscalable after current run (ending circa 2025)

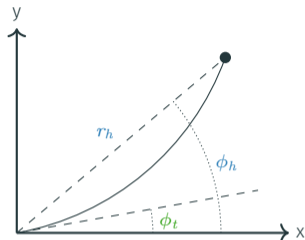
Hough Transform

- Efficient tracking method run on FPGAs
 - Cheaper and less power hungry than CPUs
- Track parameters are related to hit coordinates:

$$\phi_t = \frac{B r_h}{2} \frac{q}{p_T} + \phi_h$$

- Measure: hit coordinates ϕ_h, r_h
- Want: track parameters $\phi_t, q/p_T$

Beam at origin, into page



Hough Transform

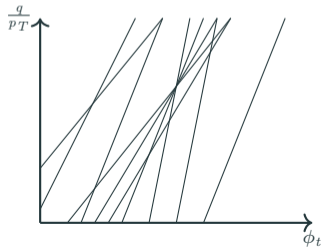
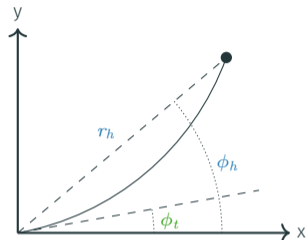
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$$y = m x + b$$

- Measure: hit coordinates ϕ_h, r_h
- Want: track parameters $\phi_t, q/p_T$
- For each hit: line of valid track parameters

Beam at origin, into page



Hough Transform

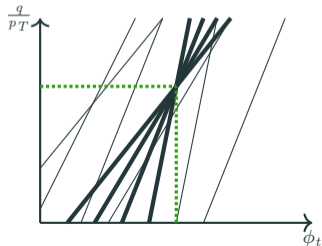
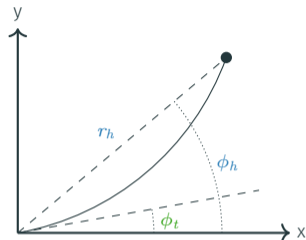
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 - For each hit: line of valid track parameters
 - Hits from same track intersect at true parameters
- Algorithm:
 1. Plot the lines for each hit in the detector
 2. Points where multiple lines intersect == tracks!

Beam at origin, into page



Hough Transform

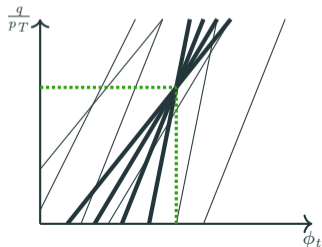
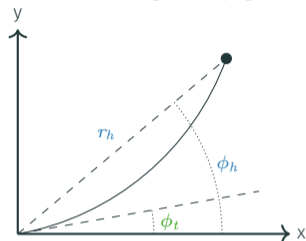
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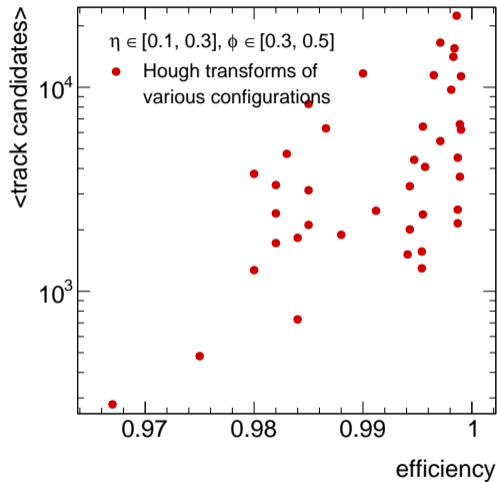
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- Algorithm:
 1. Plot the lines for each hit in the detector
 2. Points where multiple lines intersect == tracks!
 - Relies on many simplifying assumptions
 - Major assumption: constant B field in tracker

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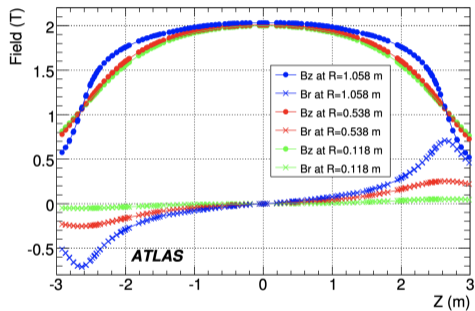
Hough Transform Tests

- Let's test!
 - Lots of tunable parameters
 - Corrections for detector inefficiencies
 - Corrections for Hough assumptions
 - And many more
 - Also try Elliot's alternative version
- Metrics:
 - Efficiency: % of tracks found
 - Fake rate: # of fake tracks per event
- Summary:
 - Great efficiency
 - Fake rate a bit high, but filtered downstream
 - Many suitable working points to choose from



Magnetic Field

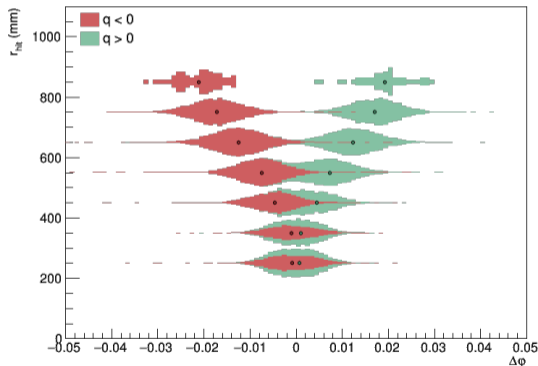
- Problems arise:
 - Previous results were for small slice in center of detector
 - Endcap has much lower efficiency: 99%
→ 87%
- Hypothesis:
 - Hough equation assumes constant magnetic field
 - Actual field in ATLAS decays near endcaps



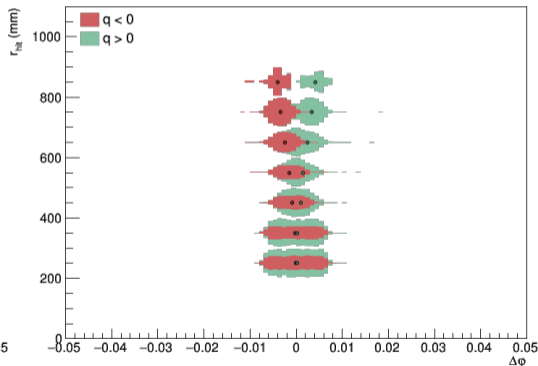
J. Phys.: Conf. Ser. 110 (2008) 092018

Magnetic Field Errors

- Verify: in simulation we know truth track parameters
- Calculate expected ϕ_h from Hough equation, compare vs true ϕ_h
- Big deviation at large r and low p_T , with sign dependent on charge



$p_T = 2$ GeV



$p_T = 10$ GeV

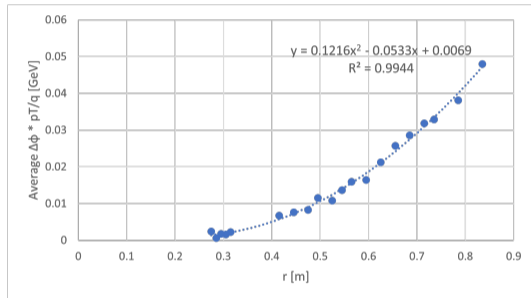
Magnetic Field Correction

- How to fix? Empirical correction!
- Approximate deviation with form

$$\Delta\phi = f(r_h) \frac{q}{p_T}$$

- Empirically fit a quadratic $f(r_h)$
- Add the correction to the Hough equation

$$\phi_t = \left(\frac{Br_h}{2} + f(r_h) \right) \frac{q}{p_T} + \phi_h$$



Plotting $\Delta\phi / \frac{q}{p_T} = f(r_h)$

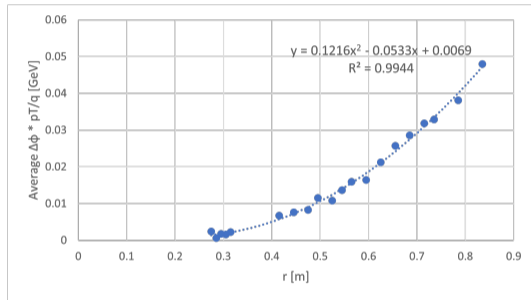
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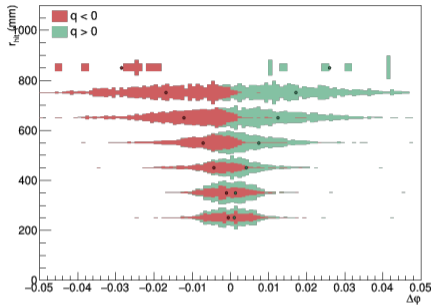
- Empirically fit a quadratic $f(r_h)$
- Add the correction to the Hough equation

$$\phi_t = \left(\frac{Br_h}{2} + f(r_h) \right) \frac{q}{p_T} + \phi_h$$
$$y = \quad m \quad x + b$$

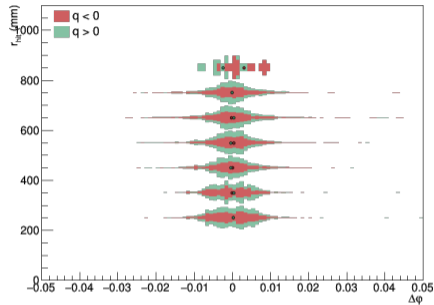


Plotting $\Delta\phi / \frac{q}{p_T} = f(r_h)$

Correction Test



Before correction



After correction

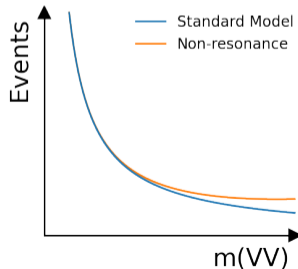
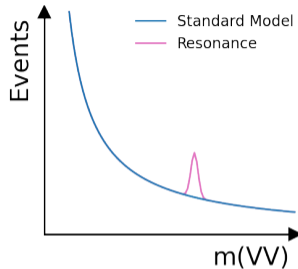
Config	Eff % in p_T bins (GeV)			Fake Tracks ($\mu = 200$)
	[1-2]	[2-4]	[4+]	
No correction	87.0	98.0	99.5	13k
With correction	97.3	98.9	99.5	10k

VV Semileptonic: Gaussian Process Regression

Two Approaches

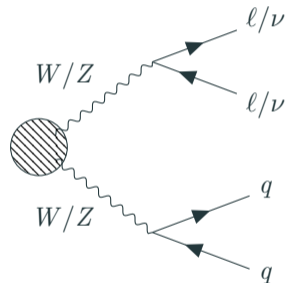
- Look for BSM physics in two major ways:
 - Direct search: assume a model and look for predicted signatures (often **resonance**)
 - Indirect measurement: look for shape deviations from SM (**non-resonance**)
- Indirect requires precise measurement of distributions
 - Need accurate background modeling!

this analysis



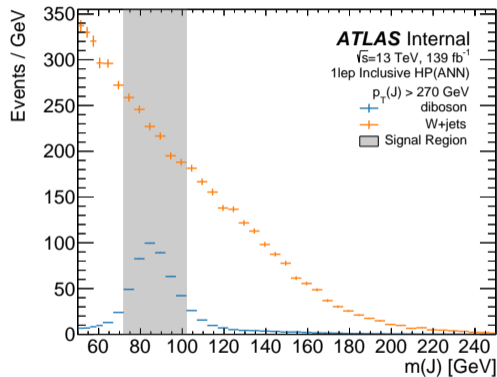
Analysis Overview

- VV Semileptonic: Pair of vector bosons ($V = W, Z$)
 - One decays to leptons: three channels $0l, 1l, 2l$
 - Other decays to quarks: single jet
- Why?
 - Dibosons are specially sensitive to certain BSM effects (EFT c_W operator)
 - ATLAS has only measured fully leptonic dibosons
 - Semileptonic
 - ⇒ Higher branching ratios
 - ⇒ More data at higher energies
 - ⇒ Better sensitivity to BSM effects
- But: much messier backgrounds



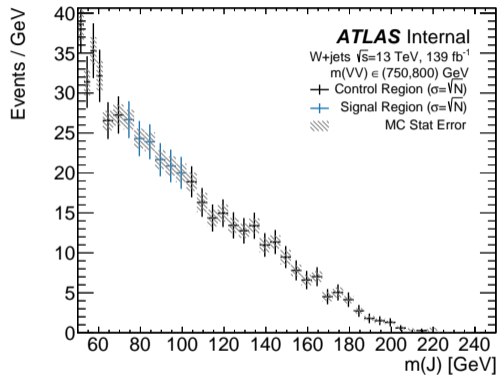
V+jets Background

- Main background is V+jets
 - Real leptonic boson
 - Extraneous jet mimics the hadronic boson
- Want data-driven approach
 - MC has large systematic errors
- Method: Sideband interpolation
 - Real bosons have a mass peak: signal region $m(J) \in [72, 102]$ GeV
 - V+jets is smooth distribution
 - Interpolate V+jets contribution from sidebands



First Attempts

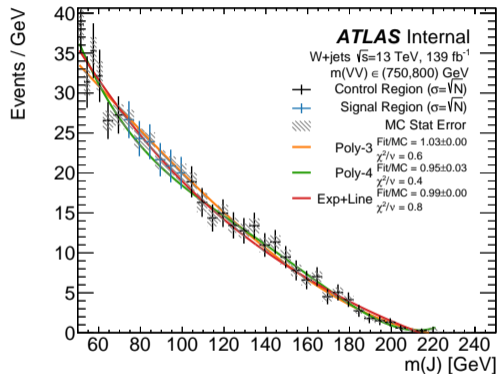
- Common method: functional fits



$m(VV) \in [750, 800] \text{ GeV}$

First Attempts

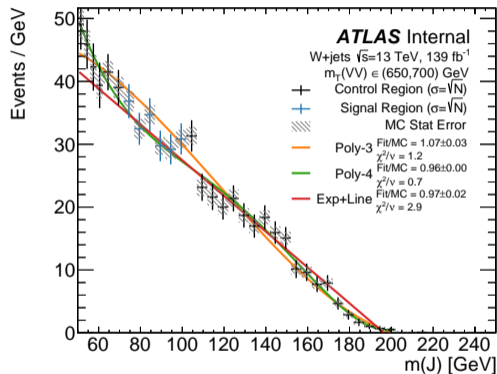
- Common method: functional fits
 1. 3rd order polynomial
 2. 4th order polynomial
 3. Exponential + linear
- Many problems:
 - Arbitrary choice of function leads to bias!
 - In this example, 8% difference between poly-3 and poly-4



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First Attempts

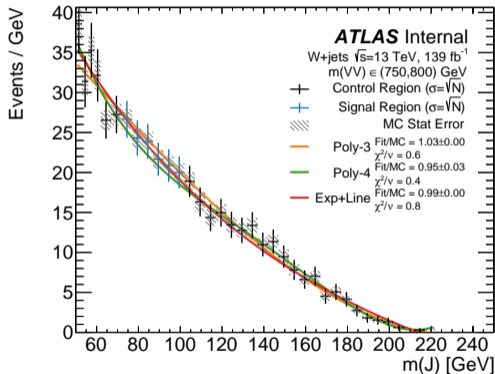
- Common method: functional fits
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 3. Exponential + linear
- Many problems:
 - Arbitrary choice of function leads to bias!
 - In this example, 8% difference between poly-3 and poly-4
 - Functional form can drastically change between bins



$$m_T(VV) \in [650, 700] \text{ GeV}$$

An Alternative Approach

- No one function is the best
 - What if we average over these 3?
 - Biases may average out to 0
 - But why these 3 and not others?
- Average over **every possible** fit function
- But how to do that?
 - Can't fit an infinite number of functions
 - Prioritize “good-fitting” functions
 - Prioritize “smooth”/simple functions



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 - Can't fit an infinite number of functions ←
 - Prioritize “good-fitting” functions →
 - Prioritize “smooth”/simple functions →

- Use Bayesian statistics!

$$\underbrace{p(f|\mathbf{y})}_{\text{posterior}} = \underbrace{p(\mathbf{y}|f)}_{\text{likelihood}} \underbrace{p(f)}_{\text{prior}} / \underbrace{p(\mathbf{y})}_{\text{marginal likelihood}}$$

- f = function, \mathbf{y} = data

$$\underbrace{p(f|\mathbf{y})}_{\text{posterior}} = \underbrace{p(\mathbf{y}|f)}_{\text{likelihood}} \underbrace{p(f)}_{\text{prior}} / \underbrace{p(\mathbf{y})}_{\text{marginal likelihood}}$$

- Hard part: defining the **prior**
 - How to define probabilities over functions?
 - How to prioritize “smooth” functions?
- Use formalism called Gaussian process
 - Generalization of multivariate Gaussian to ∞ dimensions

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- Use formalism called Gaussian process
 - Generalization of multivariate Gaussian to ∞ dimensions
- Can use to define probabilities over functions
 - Approximate functions as ∞ -dimensional vectors
 - ∞ -dimensional Gaussian \equiv PDF over functions
- Like normal Gaussians, fully defined by its mean and covariance
 - Covariance is called a **kernel**, controls the smoothness

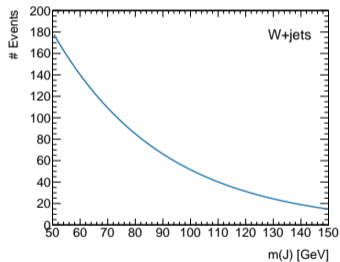
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- Hard part: defining the **prior**
 - How to define probabilities over functions?
 - How to pick a prior over functions?
 - Use formalism called Gaussian process
 - Generalization of multivariate Gaussian to ∞ dimensions
 - Can use to define probabilities over functions
 - ∞ -dimensional PDF over functions
 - Like normal Gaussians, fully defined by its mean and covariance
 - Covariance is called a **kernel**, controls the smoothness
- Choosing a prior \implies Choosing a kernel

Understanding the Kernel

$$\underbrace{p(f|\mathbf{y})}_{\text{posterior}} = \underbrace{p(\mathbf{y}|f)}_{\text{likelihood}} \underbrace{p(f)}_{\text{prior}} / \underbrace{p(\mathbf{y})}_{\text{marginal likelihood}}$$

- What is the kernel?
 - Arbitrary function $k(x_1, x_2)$
 - Covariance between $f(x_1)$ and $f(x_2)$
- How correlated should neighboring points be?

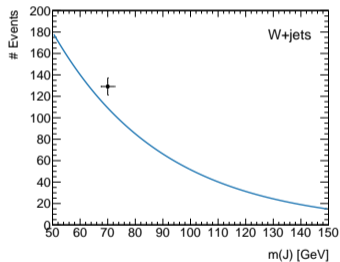


Prior
(no data)

Understanding the Kernel

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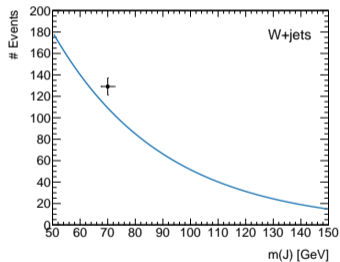


Prior
+ datapoint

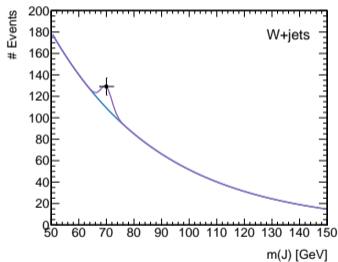
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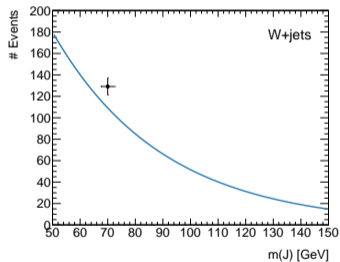


Posterior
small correlations
e.g. $k(70, 80) = 0$

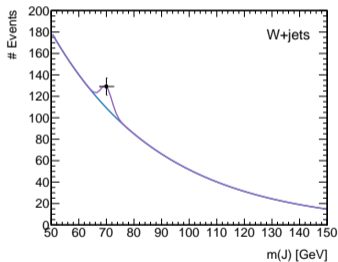
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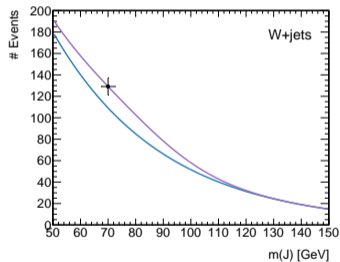
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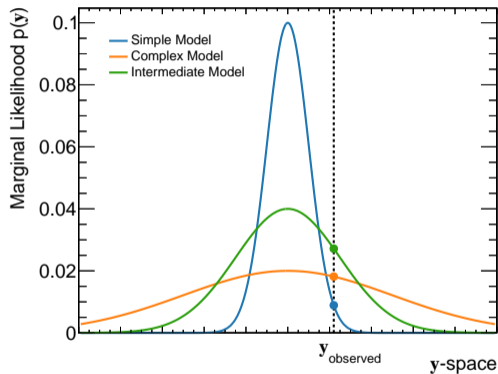


Posterior
large correlations
e.g. $k(70, 80) > 0$

Choosing a Kernel

$$p(f|\mathbf{y}) = \underbrace{p(\mathbf{y}|f)}_{\text{likelihood}} \underbrace{p(f)}_{\text{prior}} / \underbrace{p(\mathbf{y})}_{\text{marginal likelihood}}$$

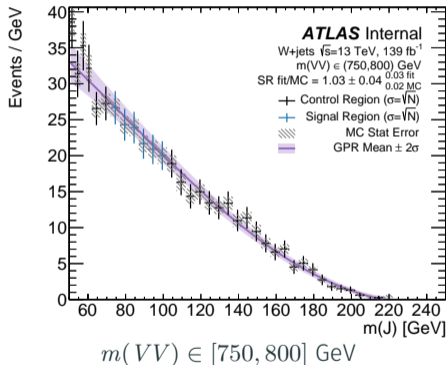
- How to choose the kernel?
 - Maximize the marginal likelihood $p(\mathbf{y} | \text{kernel})$
 - Pick the one that best matches the sideband data
- Automatic trade-off between complexity and accuracy
 - **Simple model** can't model data correctly
 - **Complex model** adapts readily, but has small max probability
 - **Intermediate model** achieves best balance



Adapted from [Rasmussen and Williams](#)

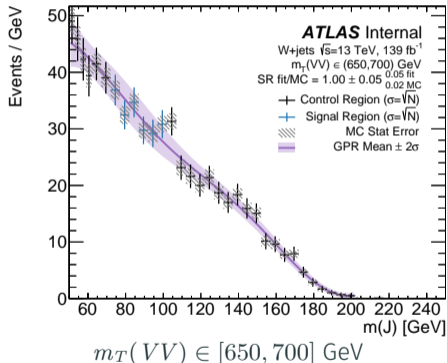
$$\underbrace{p(f|y)}_{\text{posterior}} = \underbrace{p(y|f)}_{\text{likelihood}} \underbrace{p(f)}_{\text{prior}} / \underbrace{p(y)}_{\text{marginal likelihood}}$$

- With kernel chosen, we now have a **prior**!
- Plug and chug Bayes' rule to get **posterior**
 - Remember, output is a probability distribution for EVERY possible fit function
 - Use $\max p(f)$ as predicted value (solid line)
 - Use 1σ CI as uncertainty (shaded band)
- Works great!
 - Smaller errors than functional fits
 - Manifest errors from PDF
 - No arbitrary choice of function anymore
 - No headaches from non-convergence



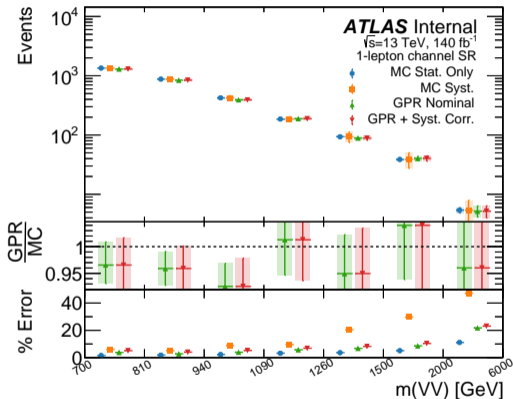
$$\underbrace{p(f|y)}_{\text{posterior}} = \underbrace{p(y|f)}_{\text{likelihood}} \underbrace{p(f)}_{\text{prior}} / \underbrace{p(y)}_{\text{marginal likelihood}}$$

- With kernel chosen, we now have a **prior**!
- Plug and chug Bayes' rule to get **posterior**
 - Remember, output is a probability distribution for EVERY possible fit function
 - Use $\max p(f)$ as predicted value (solid line)
 - Use 1σ CI as uncertainty (shaded band)
- Works great!
 - Smaller errors than functional fits
 - Manifest errors from PDF
 - No arbitrary choice of function anymore
 - No headaches from non-convergence
 - Adapts readily to changing shapes bin-to-bin



Closure Tests

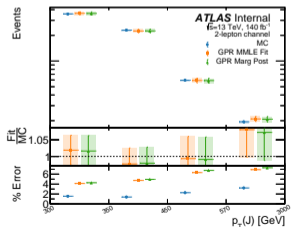
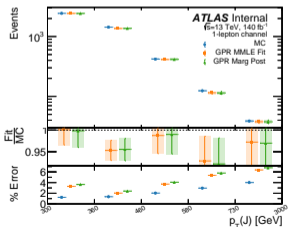
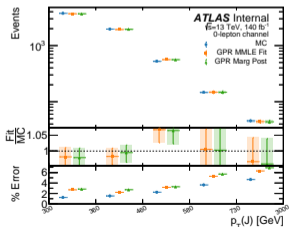
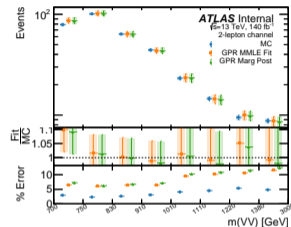
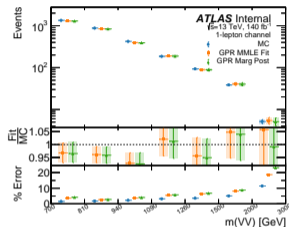
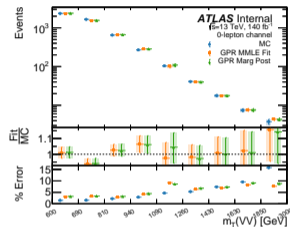
- Repeat for every bin in $m(VV)$
 - Closures within uncertainties
 - Much lower errors compared to Monte Carlo simulations
- Some subtleties not addressed:
 - Uncertainties on kernel choice
 - Dealing with signal contamination and other backgrounds in control region
 - Tests on 2D fits



Compare GPR (red) with MC (orange)

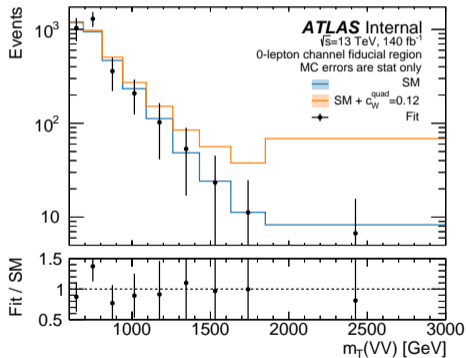
Many Closure Tests

Repeat for bins of $p_T(J)$, and repeat for every lepton channel...

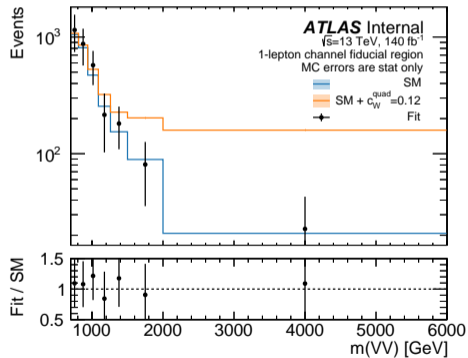


Final Results?

- Money plots: measured diboson distributions (unfolded)
- But first: tests of full procedure on asimov data (fake data == expected events from SM)
- Good closure with SM, large sensitivity to BSM effect (c_W set to 2σ global limit)



0-lepton channel



1-lepton channel

Final Results!

- Still blinded...awaiting EB request!



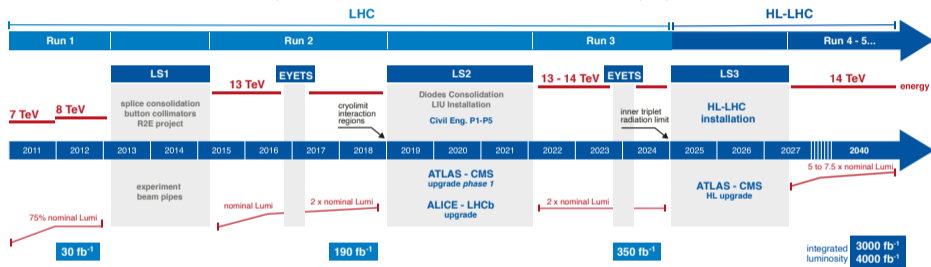
Conclusion

- Optimized Hough transforms for tracking in the trigger
- Introduced Gaussian process regression for background modeling in the WW Semileptonic analysis
- Results pending!

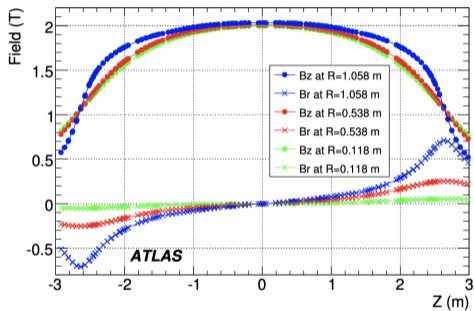
Thank you for your attention!

Backup

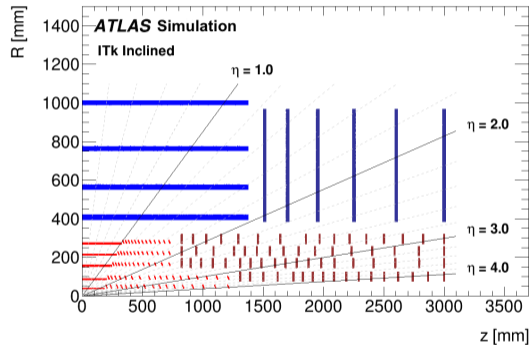
<https://hilumilhc.web.cern.ch/content/hl-lhc-project>



- In 2027 the LHC will be upgraded to the High Luminosity LHC
- Average inelastic collisions per bunch up to $\langle \mu \rangle \sim 200$
- ATLAS will need upgrades to handle this extra pileup, to be installed 2025-2027



J. Phys.: Conf. Ser. 110 (2008) 092018



<https://cds.cern.ch/record/2257755>

Hough Setup and Configuration Variables

Layer choice Which detector layers to input. Default 8 layers: Pixel 4, Strip 0 inner side, Strip 1-3 both sides.

Threshold Minimum number of hit layers to create a track candidate.

Bin sizes Width of ϕ_t and q/p_T bins. Finer bins = less fake tracks but also lower efficiency.

Padding Add extra bins to nominal region of interest account for boundary effects.

z -slicing See next slide.

Smearing Fill extra phi bins on each side to account for resolution effects and d_0 .

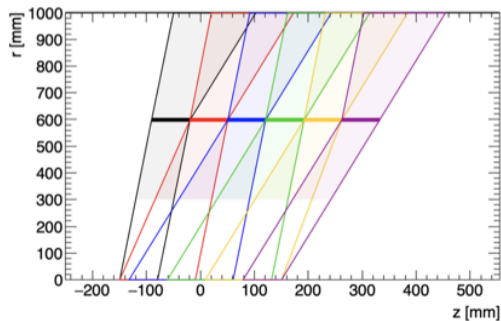
Duplicate removal Many algorithms. Window algorithm: for each bin, look at $n \times n$ neighbors. If any neighbor

1. Has more hit layers
2. Has equal hit layers, but more hits
3. Has equal hit layers and hits, but is in a lower-left bin

do not create road from this bin.

Key-layer Slicing

- Define slices by splitting a **key layer** along z , on module boundaries
 - For each slice, select tracks that go through the respective modules on the key layer
 - Add all other modules these tracks hit to the slice
- Best key layer appears to be the outer short strip layer (for current layer choice)



(Elliot)

<clusters> per slice:

Layer	6 Slice	18 Slice
0	102	70
1	86	51
2	45	13
3	66	35
4	71	43
5	72	44
6	224	85
7	278	98
Ave	118	55

Single muons flat in:

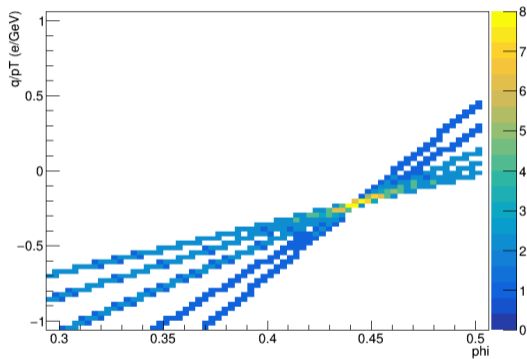
$$\phi \in [0.3, 0.5]$$

$$d_0 \in [-2, 2] \text{ mm}$$

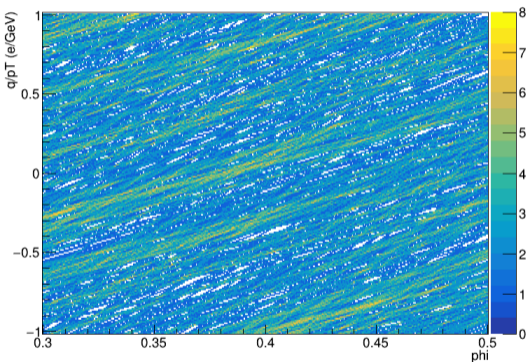
$$z_0 \in [-150, 150] \text{ mm}$$

$$1/p_T \in [-1, 1] \text{ GeV}$$

Sample Images

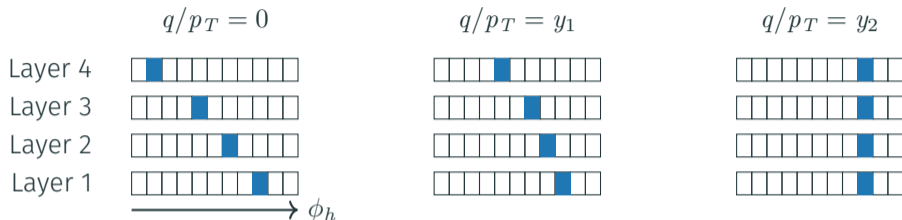


Single track with no background hits



Single track with $\mu = 200$ background hits

1D Hough Transform



- Instead of binning in q/p_T and ϕ_t , bin in ϕ_h (per layer)
- Assume hits from same layer all have the same r
- Iterate different $q/p_T \implies$ bitshift the ϕ_h bins to ϕ_t

$$\phi_t - \phi_h = \frac{r_i B}{2} \cdot \frac{q}{p_T}$$

- Multiple layers have hit at same bin \implies intersection at common ϕ_t for the given $q/p_T \implies$ track!

Task Force Decision

- Task forces created December 2020 to evaluate new EF baseline
- Reports submitted June 2021, reviewed by a trigger committee
- Committee concluded to not pursue custom hardware, but keep investigating commodity solutions
- TDR amendment published: [ATLAS-TDR-029-ADD-1](#)

TF	Algorithm	Hardware	Pros	Cons
Custom	Pattern matching	AM chip	Low power	Costly and difficult
Hetero	Hough transform	FPGA	Cheap, ok power	Lots of fakes
Software	ITk fast tracking	CPU	Best at tracking	Power intensive

Comparison - Cost, Power, and Effort

Architecture	Cost (MCHF)	Effort (FTE)	Power (MW)
Custom	4.55	140	0.59
Heterogeneous commodity	2.0	80 ¹	0.91
Software-only	3.28	14 ¹	1.82

- HTT cost is 17.45 MCHF, the EF farm is 3.4 MCHF, and the Run-3 farm is 2.85 MCHF
- $1 \text{ MW} \times \text{duty cycle} = 3 \text{ GWh/year} \approx 200 \text{ homes}$
- Point-1 expected limit of 2.5 MW

¹Review committee notes that these seem underestimated

W/Z Branching Ratios

Mode	Branching Ratio (%)
$e\nu$	10.71 ± 0.16
$\mu\nu$	10.63 ± 0.15
$\tau\nu$	11.38 ± 0.21
hadrons	67.41 ± 0.27

W boson

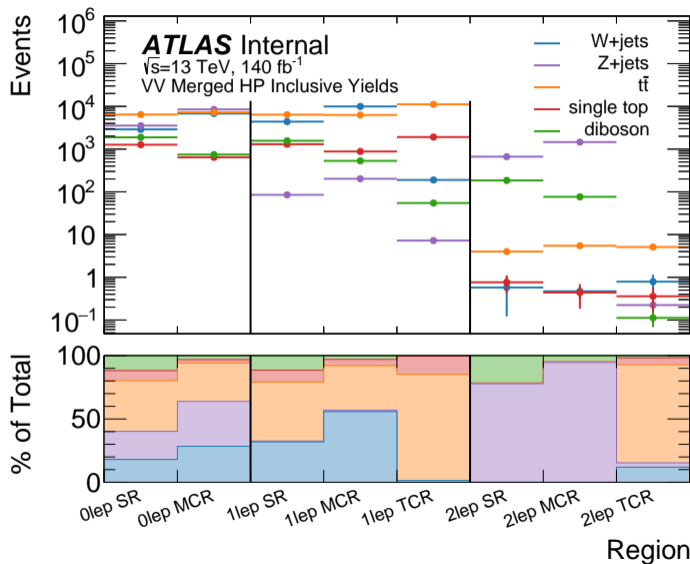
Mode	Branching Ratio (%)
e^+e^-	3.3632 ± 0.0042
$\mu^+\mu^-$	3.3662 ± 0.0066
$\tau^+\tau^-$	3.3696 ± 0.0083
invisible	20.000 ± 0.055
hadrons	69.911 ± 0.056

Z boson

Event Selection

0-lepton	1-lepton	2-lepton
Lepton Selection		
0 "Loose" leptons	1 "Tight" lepton and 0 "Loose" leptons	2 opp.-sign same-flavor "Loose" leptons
$E_T^{\text{miss}} > 200 \text{ GeV}$ $E_T^{\text{miss}} \text{ sig.} > 10$	$p_T(\ell) > 30 \text{ GeV}$ $E_T^{\text{miss}} > 100 \text{ GeV}$ $p_T(W) > 200 \text{ GeV}$	Leading ℓ $p_T > 27 \text{ GeV}$ Subleading ℓ $p_T > 25 \text{ GeV}$ $83 < m_{ee} < 99 \text{ GeV}$ $m_{\mu\mu} > 85.6 - 0.0117p_T(\ell\ell) \text{ GeV}$ $m_{\mu\mu} < 94.0 + 0.0185p_T(\ell\ell) \text{ GeV}$
Jet Selection		
Leading large- R jet		
$p_T(J) > 300 \text{ GeV}$ $72 \text{ GeV} < m(J) < 102 \text{ GeV}$ Pass W/Z substructure tagger		
Topology Requirements		
$\Delta\phi(\text{jets}, E_T^{\text{miss}}) > \frac{\pi}{9}$	$E_T^{\text{miss}}/p_T(W) > 0.2$ (electron-only)	-
-	No additional b -jets	-
-	$p_T(V)/m(VV) > 0.35$	

Channel Yields



Recent ATLAS/CMS Diboson Results

	Process	Note	\mathcal{L} [fb^{-1}]	Ref.	ATLAS?
ATLAS	$pp \rightarrow 4\ell$	SF+OS x2	139	↗	
	$WZ \rightarrow 3\ell$	Polarizations, no EFT fit	139	↗	
	$WW \rightarrow e\mu$	No EFT fit	140	↗	
	$WW + j \rightarrow e\mu$	Interference enhanced	139	↗	
	$Z + 2j \rightarrow 2\ell$	VBF	139	↗	
	$Z + \gamma\gamma \rightarrow 2\ell$	Dim-8 aQGC limits	139	↗	
	$ZZ + 2j \rightarrow 4\ell$	Dim-8 aQGC limits, VBS	139	↗	
	$W^\pm W^\pm + 2j \rightarrow 2\ell$	Dim-8 aQGC limits, VBS	139	↗	
	$W\gamma + 2j \rightarrow \ell$	Dim-8 aQGC limits, VBS	139	↗	
	$VV + 2j \rightarrow \ell\ell jj$	Dim-8 aQGC limits, VBS	139	↗	
CMS	$WW \rightarrow 2\ell$		36	↗	✓
	$WZ \rightarrow 3\ell$	Polarization angles	138	↗	✓
	$W\gamma \rightarrow \ell$	Interference resurrection	138	↗	7 TeV ; Run-2 in progress?
	$Z\gamma + 2j \rightarrow 2\ell$	Dim-8 aQGC limits, VBS	36	↗	No EFT limits
	$W\gamma + 2j \rightarrow \ell$	Dim-8 aQGC limits, VBS	138	↗	✓
	$W^\pm W^\pm + 2j \rightarrow 2\ell$	Dim-8 aQGC limits, VBS	137	↗	✓
	$WZ + 2j \rightarrow 3\ell$	Dim-8 aQGC limits, VBS	137	↗	
	$ZZ + 2j \rightarrow 4\ell$	Dim-8 aQGC limits, VBS	137	↗	✓
	$VV + 2j \rightarrow \ell\ell jj$	Dim-8 aQGC limits, VBS	36	↗	✓

Disclaimer: This list is probably far from comprehensive.

Effective Field Theory

- Framework to organize indirect measurements
- No assumptions about new particles or decay modes! Only major assumption:

$$\underbrace{\text{Energy BSM physics}}_{\Lambda} \gg \underbrace{\text{Energy SM physics}}_E$$

- Effectively, Taylor expansion around SM in terms of $1/\Lambda$

$$\text{Taylor: } f(x) = e^x \approx 1 + x + \frac{1}{2!}x^2 + \dots$$

$$\text{EFT: } \mathcal{L}_{\text{BSM}} \approx \mathcal{L}_{\text{SM}} + \frac{1}{\Lambda^2} \sum_i c_i \mathcal{O}_i^{(6)} + \frac{1}{\Lambda^4} \sum_i c_i \mathcal{O}_i^{(8)} + \dots$$

- 59 operators $\mathcal{O}_i^{(6)}$ at leading order
- Experiments fit the coefficients c_i/Λ^2

Effective Field Theory

- Framework to organize indirect measurements
- No assumptions about new particles or decay modes! Only major assumption:

Energy BSM physics \gg Energy SM physics

Targets of indirect measurements:

1. Unfolded cross section
2. EFT coefficient limits

- Effectively, Taylor

$$\text{Taylor: } f(x) = f(0) + f'(0)x + \frac{1}{2!}f''(0)x^2 + \dots$$

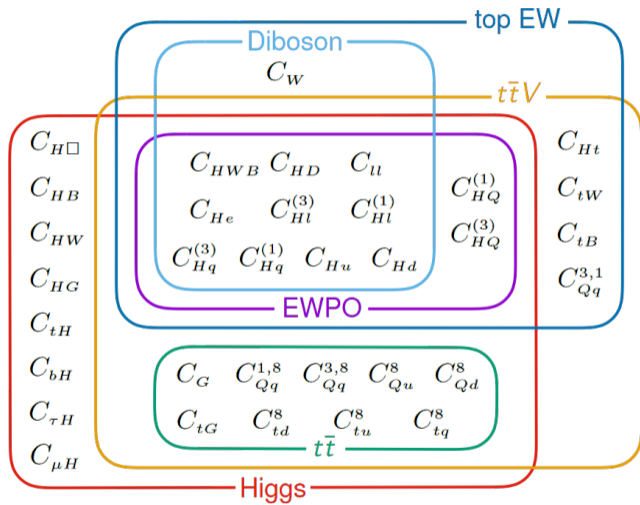
$$\text{EFT: } \mathcal{L}_{\text{BSM}} \approx \mathcal{L}_{\text{SM}} + \frac{1}{\Lambda^2} \sum_i c_i \mathcal{O}_i^{(6)} + \frac{1}{\Lambda^4} \sum_i c_i \mathcal{O}_i^{(8)} + \dots$$

- 59 operators $\mathcal{O}_i^{(6)}$ at leading order
- Experiments fit the coefficients c_i/Λ^2

$$\sigma \propto |\mathcal{M}_{\text{SMEFT}}|^2 = |\mathcal{M}_{\text{SM}}|^2 + \underbrace{\frac{1}{\Lambda^2} \mathcal{M}_{\text{SM}}^* \mathcal{M}_{\text{EFT}}^{(6)}}_{\text{linear term}} + \underbrace{\frac{1}{\Lambda^4} |\mathcal{M}_{\text{EFT}}^{(6)}|^2}_{\text{quadratic term}} + \underbrace{\frac{1}{\Lambda^4} \mathcal{M}_{\text{SM}}^* \mathcal{M}_{\text{EFT}}^{(8)}}_{\mathcal{O}(8) \text{ interference}}$$

- First order operators are dimension 6
 - Odd-dimension terms violate lepton/baryon number
 - 59 operators
- **Linear** interference term is first order effect (Λ^{-2})
- **Quadratic** term is second order effect (Λ^{-4})
 - Same order as un-modeled **dim-8 interference**
 - Taken as an uncertainty
- Two fits: just **linear**, and **linear** + **quadratic**

SMEFT Sensitive Operators



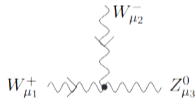
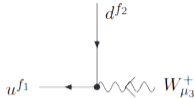
x2012.02779

SMEFT Operators: other than 4 fermion

X^3		φ^6 and $\varphi^4 D^2$		$\psi^2 \varphi^3$	
Q_G	$f^{ABC} G_\mu^{A\nu} G_\nu^{B\rho} G_\rho^{C\mu}$	Q_φ	$(\varphi^\dagger \varphi)^3$	$Q_{e\varphi}$	$(\varphi^\dagger \varphi)(\bar{l}_p e_r \varphi)$
$Q_{\tilde{G}}$	$f^{ABC} \tilde{G}_\mu^{A\nu} G_\nu^{B\rho} G_\rho^{C\mu}$	$Q_{\varphi\Box}$	$(\varphi^\dagger \varphi)\Box(\varphi^\dagger \varphi)$	$Q_{u\varphi}$	$(\varphi^\dagger \varphi)(\bar{q}_p u_r \tilde{\varphi})$
Q_W	$\varepsilon^{IJK} W_\mu^{I\nu} W_\nu^{J\rho} W_\rho^{K\mu}$	$Q_{\varphi D}$	$(\varphi^\dagger D^\mu \varphi)^* (\varphi^\dagger D_\mu \varphi)$	$Q_{d\varphi}$	$(\varphi^\dagger \varphi)(\bar{q}_p d_r \varphi)$
$Q_{\tilde{W}}$	$\varepsilon^{IJK} \tilde{W}_\mu^{I\nu} W_\nu^{J\rho} W_\rho^{K\mu}$				
$X^2 \varphi^2$		$\psi^2 X \varphi$		$\psi^2 \varphi^2 D$	
$Q_{\varphi G}$	$\varphi^\dagger \varphi G_{\mu\nu}^A G^{A\mu\nu}$	Q_{eW}	$(\bar{l}_p \sigma^{\mu\nu} e_r) \tau^I \varphi W_{\mu\nu}^I$	$Q_{\varphi l}^{(1)}$	$(\varphi^\dagger i \overleftrightarrow{D}_\mu \varphi)(\bar{l}_p \gamma^\mu l_r)$
$Q_{\varphi \tilde{G}}$	$\varphi^\dagger \varphi \tilde{G}_{\mu\nu}^A G^{A\mu\nu}$	Q_{eB}	$(\bar{l}_p \sigma^{\mu\nu} e_r) \varphi B_{\mu\nu}$	$Q_{\varphi l}^{(3)}$	$(\varphi^\dagger i \overleftrightarrow{D}_\mu^I \varphi)(\bar{l}_p \tau^I \gamma^\mu l_r)$
$Q_{\varphi W}$	$\varphi^\dagger \varphi W_{\mu\nu}^I W^{I\mu\nu}$	Q_{uG}	$(\bar{q}_p \sigma^{\mu\nu} T^A u_r) \tilde{\varphi} G_{\mu\nu}^A$	$Q_{\varphi e}$	$(\varphi^\dagger i \overleftrightarrow{D}_\mu \varphi)(\bar{e}_p \gamma^\mu e_r)$
$Q_{\varphi \tilde{W}}$	$\varphi^\dagger \varphi \tilde{W}_{\mu\nu}^I W^{I\mu\nu}$	Q_{uW}	$(\bar{q}_p \sigma^{\mu\nu} u_r) \tau^I \tilde{\varphi} W_{\mu\nu}^I$	$Q_{\varphi q}^{(1)}$	$(\varphi^\dagger i \overleftrightarrow{D}_\mu \varphi)(\bar{q}_p \gamma^\mu q_r)$
$Q_{\varphi B}$	$\varphi^\dagger \varphi B_{\mu\nu} B^{\mu\nu}$	Q_{uB}	$(\bar{q}_p \sigma^{\mu\nu} u_r) \tilde{\varphi} B_{\mu\nu}$	$Q_{\varphi q}^{(3)}$	$(\varphi^\dagger i \overleftrightarrow{D}_\mu^I \varphi)(\bar{q}_p \tau^I \gamma^\mu q_r)$
$Q_{\varphi \tilde{B}}$	$\varphi^\dagger \varphi \tilde{B}_{\mu\nu} B^{\mu\nu}$	Q_{dG}	$(\bar{q}_p \sigma^{\mu\nu} T^A d_r) \varphi G_{\mu\nu}^A$	$Q_{\varphi u}$	$(\varphi^\dagger i \overleftrightarrow{D}_\mu \varphi)(\bar{u}_p \gamma^\mu u_r)$
$Q_{\varphi WB}$	$\varphi^\dagger \tau^I \varphi W_{\mu\nu}^I B^{\mu\nu}$	Q_{dW}	$(\bar{q}_p \sigma^{\mu\nu} d_r) \tau^I \varphi W_{\mu\nu}^I$	$Q_{\varphi d}$	$(\varphi^\dagger i \overleftrightarrow{D}_\mu \varphi)(\bar{d}_p \gamma^\mu d_r)$
$Q_{\varphi \tilde{W}B}$	$\varphi^\dagger \tau^I \varphi \tilde{W}_{\mu\nu}^I B^{\mu\nu}$	Q_{dB}	$(\bar{q}_p \sigma^{\mu\nu} d_r) \varphi B_{\mu\nu}$	$Q_{\varphi ud}$	$i(\tilde{\varphi}^\dagger D_\mu \varphi)(\bar{u}_p \gamma^\mu d_r)$

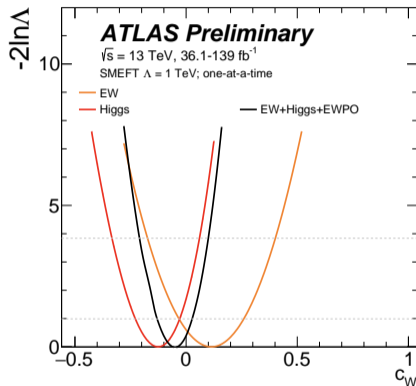
x1008.4884

SMEFT Feynman Rules

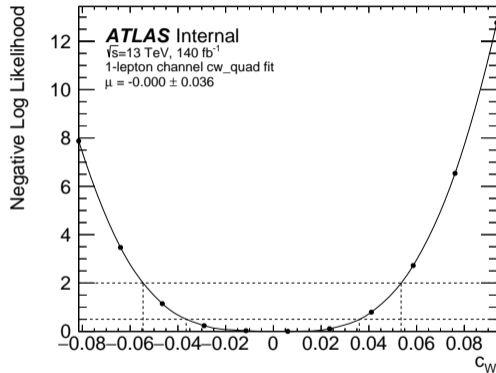


$$\begin{aligned}
 & -\frac{i\bar{g}}{\sqrt{2}} K_{f_1 f_2} \gamma^{\mu_3} P_L - 2v p_3^\nu K_{f_1 g_1} C_{g_1 f_2}^{dW} \sigma^{\mu_3 \nu} P_R - \frac{i\bar{g}v^2}{\sqrt{2}} K_{f_1 g_1} C_{g_1 f_2}^{\varphi q^3} \gamma^{\mu_3} P_L \\
 & - \frac{i\bar{g}v^2}{2\sqrt{2}} C_{f_1 f_2}^{\varphi ud} \gamma^{\mu_3} P_R - 2v p_3^\nu K_{g_1 f_2} \sigma^{\mu_3 \nu} P_L C_{g_1 f_1}^{uW*} \\
 & + \frac{i\bar{g}^2}{\sqrt{\bar{g}^2 + \bar{g}'^2}} (\eta_{\mu_1 \mu_2} (p_1 - p_2)^{\mu_3} + \eta_{\mu_2 \mu_3} (p_2 - p_3)^{\mu_1} + \eta_{\mu_3 \mu_1} (p_3 - p_1)^{\mu_2}) \\
 & - \frac{6i\bar{g}}{\sqrt{\bar{g}^2 + \bar{g}'^2}} C^W (p_3^{\mu_1} p_1^{\mu_2} p_2^{\mu_3} - p_2^{\mu_1} p_3^{\mu_2} p_1^{\mu_3} + \eta_{\mu_1 \mu_2} (p_1^{\mu_3} p_2 \cdot p_3 - p_2^{\mu_3} p_1 \cdot p_3) \\
 & + \eta_{\mu_2 \mu_3} (p_2^{\mu_1} p_1 \cdot p_3 - p_3^{\mu_1} p_1 \cdot p_2) + \eta_{\mu_3 \mu_1} (p_3^{\mu_2} p_1 \cdot p_2 - p_1^{\mu_2} p_2 \cdot p_3)) \\
 & + \frac{i\bar{g}\bar{g}'v^2}{(\bar{g}^2 + \bar{g}'^2)^{3/2}} C^{\varphi WB} (\eta_{\mu_1 \mu_2} (\bar{g}'^2 p_1^{\mu_3} - \bar{g}^{\prime 2} p_2^{\mu_3}) + \eta_{\mu_2 \mu_3} (\bar{g}'^2 p_2^{\mu_1} + \bar{g}^2 p_3^{\mu_1}) \\
 & + \eta_{\mu_3 \mu_1} (-\bar{g}^2 p_3^{\mu_2} - \bar{g}'^2 p_1^{\mu_2})) \\
 & - \frac{2i\bar{g}}{\sqrt{\bar{g}^2 + \bar{g}'^2}} C^{\tilde{W}} (\epsilon_{\mu_1 \mu_2 \mu_3 \alpha_1} (p_1^{\alpha_1} p_2 \cdot p_3 + p_2^{\alpha_1} p_1 \cdot p_3 + p_3^{\alpha_1} p_1 \cdot p_2) \\
 & + \epsilon_{\mu_1 \mu_2 \alpha_1 \beta_1} (p_1 - p_2)^{\mu_3} p_1^{\alpha_1} p_2^{\beta_1} + \epsilon_{\mu_2 \mu_3 \alpha_1 \beta_1} (p_2 - p_3)^{\mu_1} p_2^{\alpha_1} p_3^{\beta_1} \\
 & + \epsilon_{\mu_3 \mu_1 \alpha_1 \beta_1} (p_3 - p_1)^{\mu_2} p_3^{\alpha_1} p_1^{\beta_1}) \\
 & - \frac{i\bar{g}\bar{g}'v^2}{\sqrt{\bar{g}^2 + \bar{g}'^2}} C^{\varphi \tilde{W} B} \epsilon_{\mu_1 \mu_2 \mu_3 \alpha_1} p_3^{\alpha_1}
 \end{aligned}$$

<https://arxiv.org/pdf/1704.03888.pdf>



Current ATLAS global limits



Our 1-lep fit (asimov, no systematics)

$$p(\mathbf{y}_* | X, \mathbf{y}, X_*) \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$$

$$\boldsymbol{\mu} = \boldsymbol{\mu}_0(X_*) + K_{X_*X} K^{-1} (\mathbf{y} - \boldsymbol{\mu}_0(X)),$$

$$\Sigma = K_{X_*X_*} - K_{X_*X} K^{-1} K_{XX_*}$$

$$K \equiv K_{XX} + \text{diag}(\boldsymbol{\sigma}^2)$$

X training inputs

\mathbf{y} training targets

$\boldsymbol{\sigma}^2$ noise on \mathbf{y}

$\boldsymbol{\mu}_0$ mean of the prior

X_* test inputs

\mathbf{y}_* predicted values

$K_{XX'}$ covariance of the prior, evaluated between X and X'

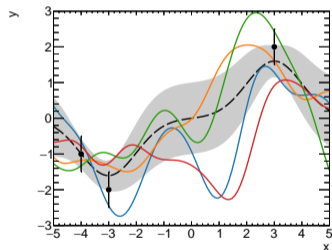
$$p(\mathbf{y}) = \frac{1}{\sqrt{(2\pi)^n |K|}} \exp \left[-\frac{1}{2} \mathbf{y}^T K^{-1} \mathbf{y} \right]$$

Kernel Example

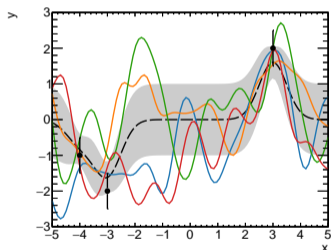
Example with toy data, radial basis function \implies 2 hyperparameters

$$k(x, x') = \gamma^2 \times \exp \left[-\frac{(x - x')^2}{2\ell^2} \right]$$

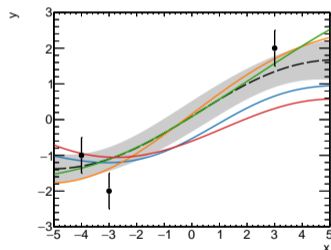
- γ overall variance
- ℓ length scale



$$\ell = 1, \gamma = 1$$



$$\ell = 0.5, \gamma = 1$$



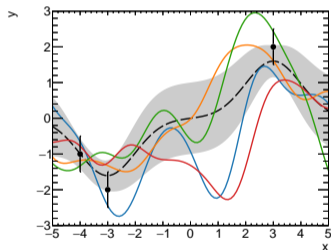
$$\ell = 5, \gamma = 1$$

Kernel Example

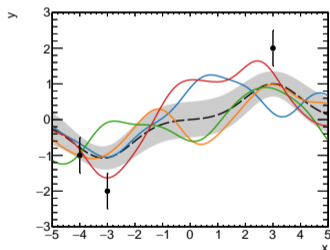
Example with toy data, radial basis function \implies 2 hyperparameters

$$k(x, x') = \gamma^2 \times \exp \left[-\frac{(x - x')^2}{2\ell^2} \right]$$

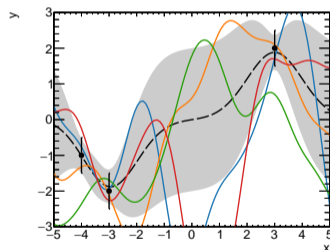
- γ overall variance
- ℓ length scale



$\ell = 1, \gamma = 1$



$\ell = 1, \gamma = 0.5$



$\ell = 1, \gamma = 2$

Alternative Kernels

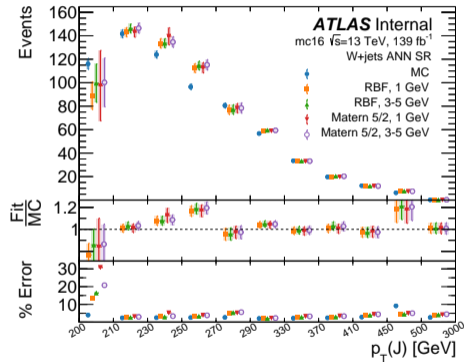
- Isotropic kernels (functions of $r = |\mathbf{x}_1 - \mathbf{x}_2|$) behave very similarly

- RBF:

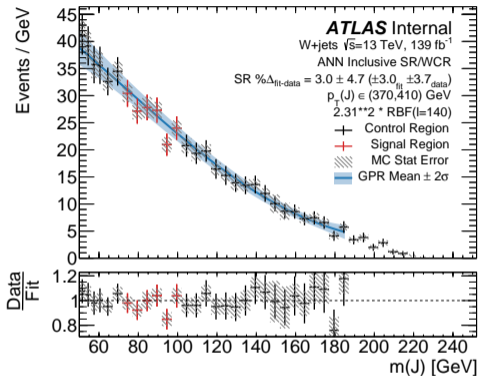
$$k(r) = \gamma^2 \times \exp\left[-\frac{r^2}{2\ell^2}\right]$$

- Matern 5/2:

$$k(r) = \gamma^2 \left(1 + \frac{\sqrt{5}r}{\ell} + \frac{5r^2}{3\ell^2}\right) \exp\left(-\frac{\sqrt{5}r}{\ell}\right)$$

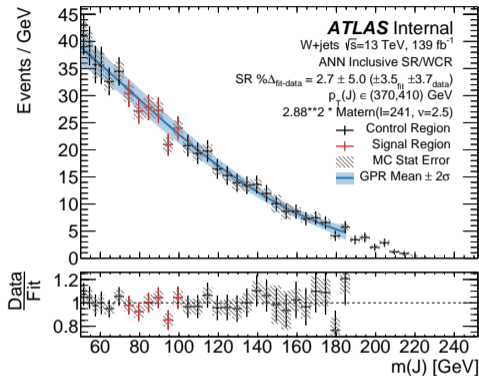


Alternative Kernels



RBF Kernel

$$k(r) = \gamma^2 \times \exp \left[-\frac{r^2}{2\ell^2} \right]$$

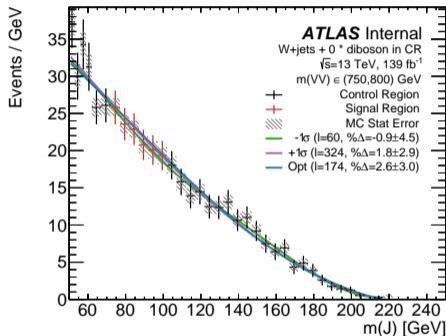


Matern 5/2 Kernel

$$k(r) = \gamma^2 \left(1 + \frac{\sqrt{5}r}{\ell} + \frac{5r^2}{3\ell^2} \right) \exp \left(-\frac{\sqrt{5}r}{\ell} \right)$$

Systematic Errors

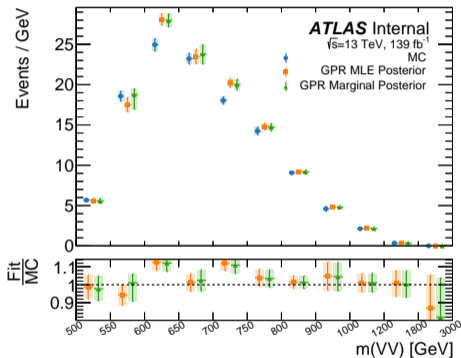
- How dependent is the output on the choice of **kernel**?
 - A little, $\approx 2\%$ in example on right
 - Which to choose? Error on choice?
- A familiar idea:
 - Don't choose a single **kernel**
 - Average over all kernels / hyperparameters
 - Weight by how well each kernel fits the data
- Another round of Bayes' rule!
 - Jargon: marginalizing the kernel choice
 - Net effect: slightly larger errors



Posterior modes with 3 different hyperparameter settings

Systematic Errors

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Summary of yields from multiple $m(VV)$ bins

Marginalize the Posterior

- Bayesian is awesome! Marginalize hyperparameters out from posterior
- $\boldsymbol{\theta} = (\ell, \gamma)$ list of hyperparameters
- Add explicit $\boldsymbol{\theta}$ dependence on previous formulas

$$\underbrace{p(f|\mathbf{y})}_{\text{marginal posterior}} = \int d\boldsymbol{\theta} \underbrace{p(f|\mathbf{y}, \boldsymbol{\theta})}_{\text{original posterior}} \times \underbrace{p(\boldsymbol{\theta}|\mathbf{y})}_{\text{hyperposterior}}$$

$$\underbrace{p(\boldsymbol{\theta}|\mathbf{y})}_{\text{hyperposterior}} = \frac{\overbrace{p(\mathbf{y}|\boldsymbol{\theta})}^{\text{marginal likelihood}} \times \overbrace{p(\boldsymbol{\theta})}^{\text{hyperprior}}}{\underbrace{p(\mathbf{y})}_{\text{normalizing constant}}}$$

Example: Marginal Likelihood

$$p(f|\mathbf{y}) \propto \int d\boldsymbol{\theta} p(f|\mathbf{y}, \boldsymbol{\theta}) p(\mathbf{y}|\boldsymbol{\theta})$$

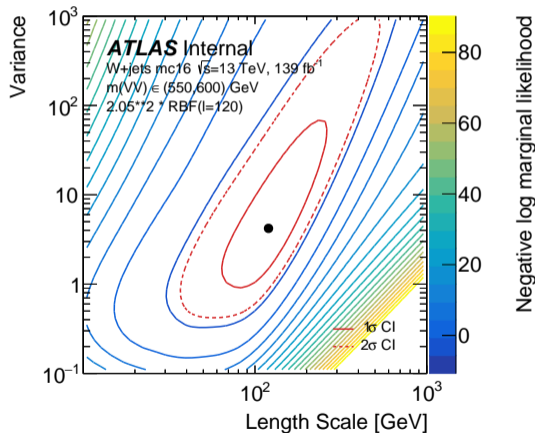
- RBF kernel, so two hyperparameters γ and ℓ

$$k(\mathbf{x}_1, \mathbf{x}_2) = \gamma^2 \cdot \exp \left[-\frac{|\mathbf{x}_1 - \mathbf{x}_2|^2}{2\ell^2} \right]$$

- Black dot is maximum (MMLE)
- Technically, we should be looking at

$$\underbrace{p(\boldsymbol{\theta}|\mathbf{y})}_{\text{hyperposterior}} \propto \underbrace{p(\mathbf{y}|\boldsymbol{\theta})}_{\text{marginal likelihood}} \times \underbrace{p(\boldsymbol{\theta})}_{\text{hyperprior}}$$

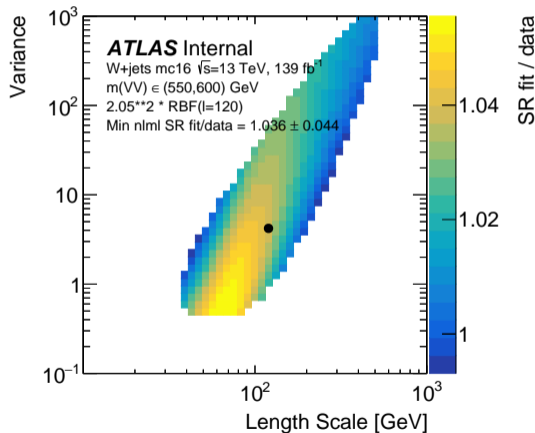
- But assuming $p(\boldsymbol{\theta}) \sim \log\text{-constant}$ in grid, reduces to marginal likelihood



Example: Posterior

$$p(f|\mathbf{y}) \propto \int d\boldsymbol{\theta} p(f|\mathbf{y}, \boldsymbol{\theta}) p(\mathbf{y}|\boldsymbol{\theta})$$

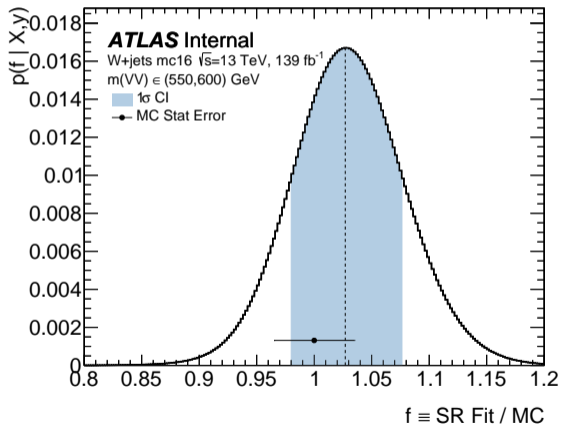
- This is the usual output of GPR, evaluated at each $\boldsymbol{\theta}$
- Keep in mind the output is actually a Gaussian distribution
- Here we show just the mean scaled by MC event count
- For simplicity, only evaluate within 1σ or 2σ CI



Example: Marginal Posterior

$$p(f|\mathbf{y}) \propto \int d\boldsymbol{\theta} p(f|\mathbf{y}, \boldsymbol{\theta}) p(\mathbf{y}|\boldsymbol{\theta})$$

- Evaluate integral at multiple f to get full distribution
- Pick mode and 1σ CI as predicted values
- Repeat in each $m(VV)$ bin



GPR Signal Contamination

- Fit: $N_{W+jets} = N_{data} - N_{top,t\bar{t}} - \mu_{guess} N_{diboson}$
 - Take $\mu_{guess} = 1$
 - But if $\mu_{guess} \neq \mu_{truth}$, signal contamination!

- Test: vary μ_{truth} and fit GPR to

$$N_{W+jets}^{MC} + (\mu_{truth} - 1)N_{diboson}^{MC}$$

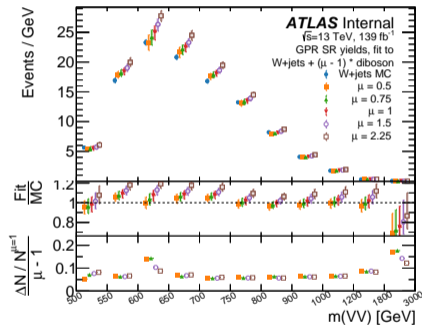
- Idea: keep $\mu_{guess} = 1$ in GPR, correct in likelihood fit
 - Simply subtract out correlation term:

$$N_{no\ contam} = N_{contam}^{fit\ yield} - (\mu - 1)\Delta N$$

- ΔN a “nuisance histogram” determined from right
- As fitter varies μ , automatically corrected

GPR yield \approx linear vs μ_{truth} :

$$N_{GPR}^{\mu} = (\mu - 1)\Delta N + N_{GPR}^{\mu=1}$$



	$\mu_{truth} = 1$	$\mu_{truth} = 1.5$
No correction	$1.00 \pm .10$	$1.40 \pm .10$
With correction	$1.00 \pm .13$	$1.50 \pm .12$

Unfolding

- Unfolding: undo detector-specific effects \rightarrow “truth” distribution
 - Adjust for detector efficiencies and resolutions
 - So people outside of ATLAS can use measurement
- Likelihood-based approach:
 - Assume linear detector response, determine matrix from simulation

$$N_i^{\text{Detector}} = R_{ij} N_j^{\text{Truth}}$$

- Treat each truth bin as separate “signal samples” in likelihood fit
- “Signal strength” == unfolded event counts N_j^{Unfolded}

$$\text{Normal Likelihood: } L(\text{data} \mid \mu) = \prod_i P(\text{data}_i \mid \text{bkg}_i + \mu \cdot \text{signal}_i)$$

$$\text{Unfolding Likelihood: } L(\text{data} \mid \vec{N}^{\text{Unfolded}}) = \prod_i P(\text{data}_i \mid \text{bkg}_i + R_{ij} N_j^{\text{Unfolded}})$$

Response Matrix Components

Response matrix

$$R_{ij} = \frac{\epsilon_j}{\alpha_i} M_{ij}$$

Migration matrix

$$M_{ij} = \frac{N_{ij}^{\text{Reco} \cap \text{Truth}}}{N_j^{\text{Reco} \cap \text{Truth}}}$$

Efficiency

$$\epsilon_j = \frac{N_j^{\text{Reco} \cap \text{Truth}}}{N_j^{\text{Truth}}}$$

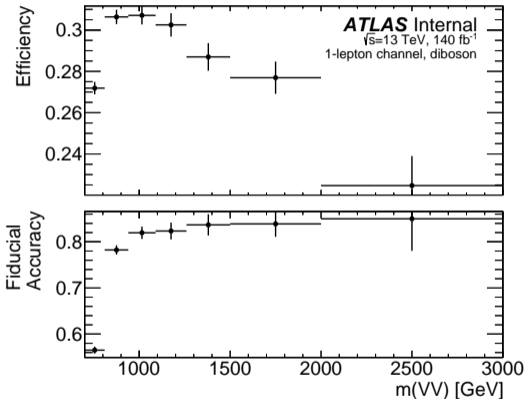
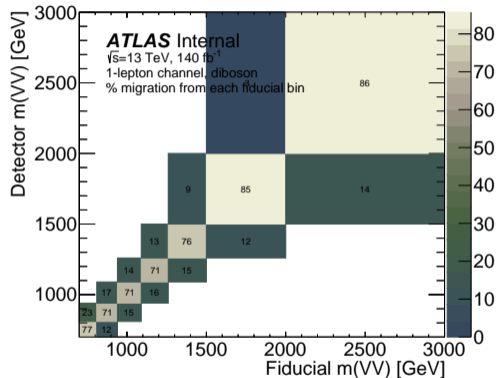
Acceptance

$$\alpha_i = \frac{N_i^{\text{Reco} \cap \text{Truth}}}{N_i^{\text{Reco}}}$$

i : reco bin

j : truth bin

Response Matrix Components



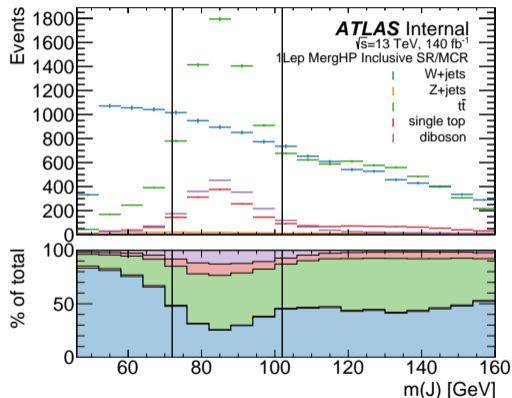
Unfolding Workflow

MCR is not pure V +jets. Method:

1. Fit top and $t\bar{t}$ to TCR (99% pure, use nominal for other samples)
2. Subtract top, $t\bar{t}$, W from MCR

$$N_{V+\text{jets}} = N_{\text{data}} - \mu_{t\bar{t}} N_{t\bar{t}}^{\text{MC}} - \mu_t N_t^{\text{MC}} - \mu_{VV} N_{VV}^{\text{MC}}$$

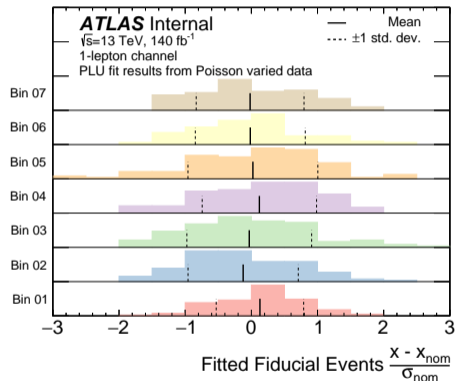
3. Fit GPR to event-subtracted $N_{V+\text{jets}}$ to get SR yield
4. Repeat steps 2-3 for various μ_{VV} - determine signal contamination correction ([slides from before](#))
5. Repeat steps 1-3 for $\pm 1\sigma$ of all systematics and $\mu_{t\bar{t}}, \mu_t$
6. Repeat for all bins in $m(VV)$ / other variable



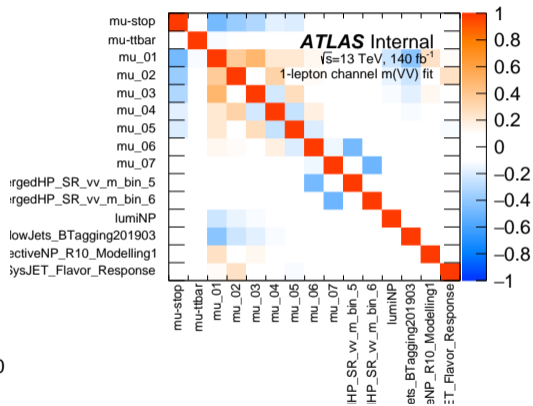
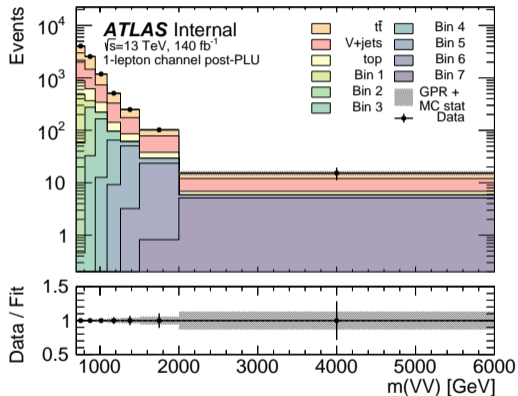
End result: GPR yield histograms in $m(VV)$ for each $\pm 1\sigma$ systematic and $\pm 1\sigma$ on $\mu_{t\bar{t}}, \mu_t$

PLU Toy Test

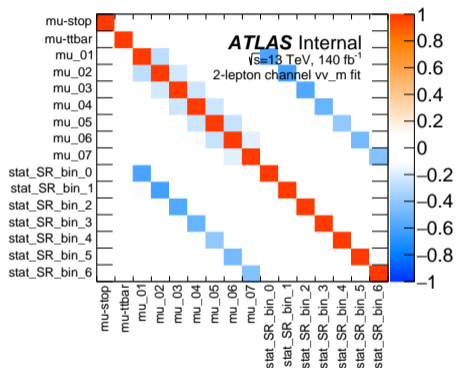
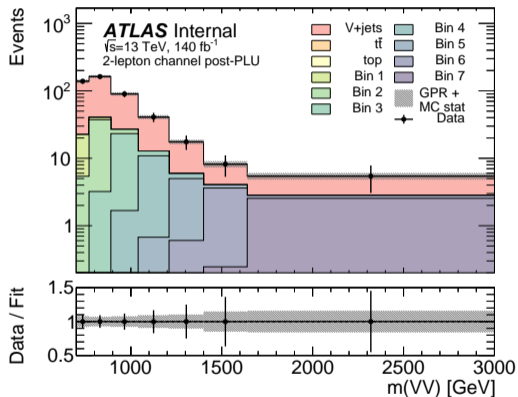
- Vary the data in each bin by Poisson statistics
- Do PLU fit, repeat 100 times
- Plot difference against original yields
- Confirms no bias, accurate uncertainties



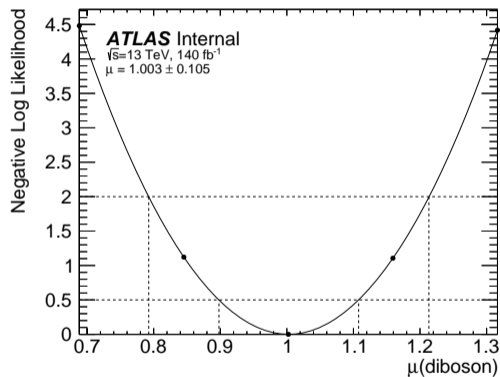
PLU Fit Correlations (1-lep)



PLU Fit Correlations (2-lep)



SM Diboson Cross Section



Systs.	Channels	μ	σ
✘	0+1+2	0.999 ± 0.105	9.5
	0	1.004 ± 0.132	7.6
	1	1.064 ± 0.156	6.8
	2	1.001 ± 0.212	4.7
✔	1+2	1.038 ± 0.164	6.3
	1	1.058 ± 0.217	4.9
	2	1.012 ± 0.218	4.6