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Cooling studies for FCC-ee vertex detector

MAPS detectors technologies for the FCC-ee vertex detector

CERN, 1 - 2 July 2024

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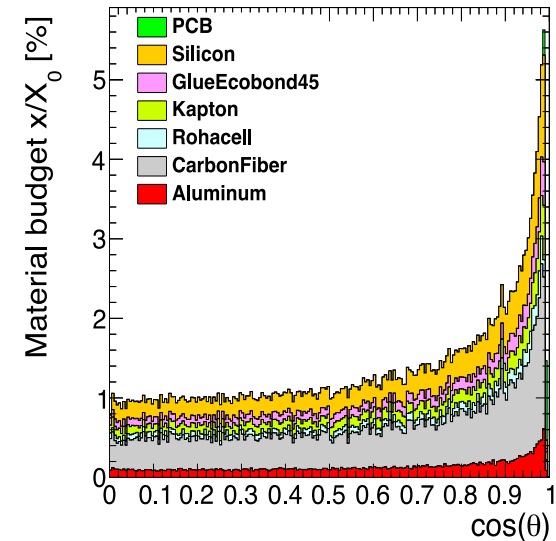
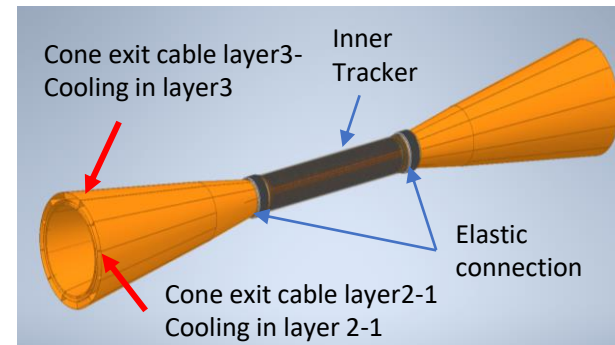
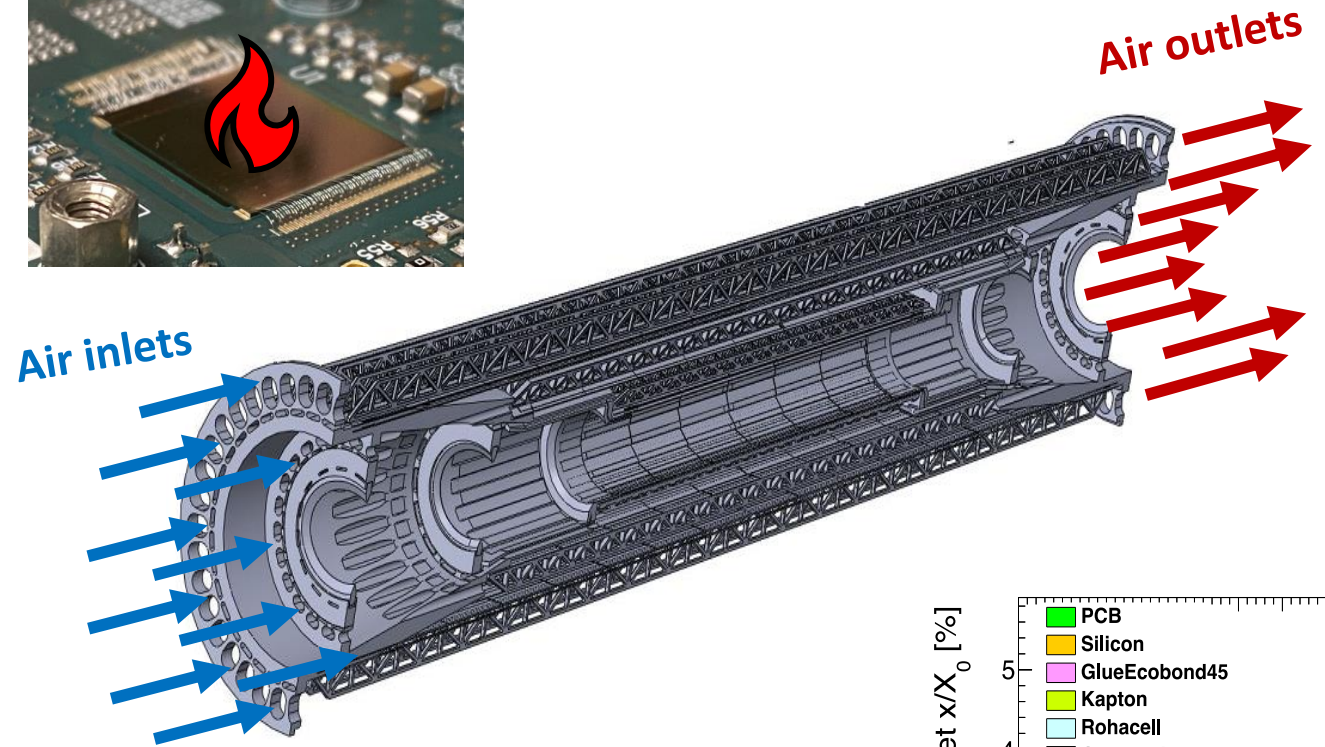
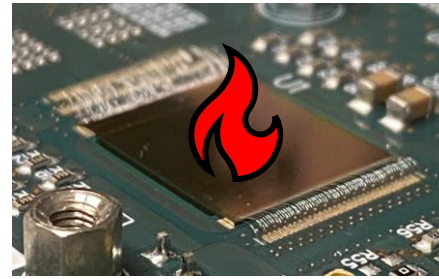
(1) *Università degli Studi di Perugia*

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AN AIR COOLING SYSTEM FOR THE VERTEX DETECTOR

- A cooling system is necessary for removing the heat dissipated by **sensors** and **electronics** inside the vertex detector volume.
- A system based on the **forced convection of a gas** inside the detector seems particularly promising.
- This would substantially reduce **material budget**.
 - No pipes needed inside the vertex volume, just the gas flow.
 - Services concentrated in the two endcaps.
- Air is the easiest fluid to use on this purpose.



HOW TO EVALUATE THE THERMAL PERFORMANCE ?

- Two different ways to proceed:

NUMERICAL SIMULATIONS

The first approach

EXPERIMENTAL TEST

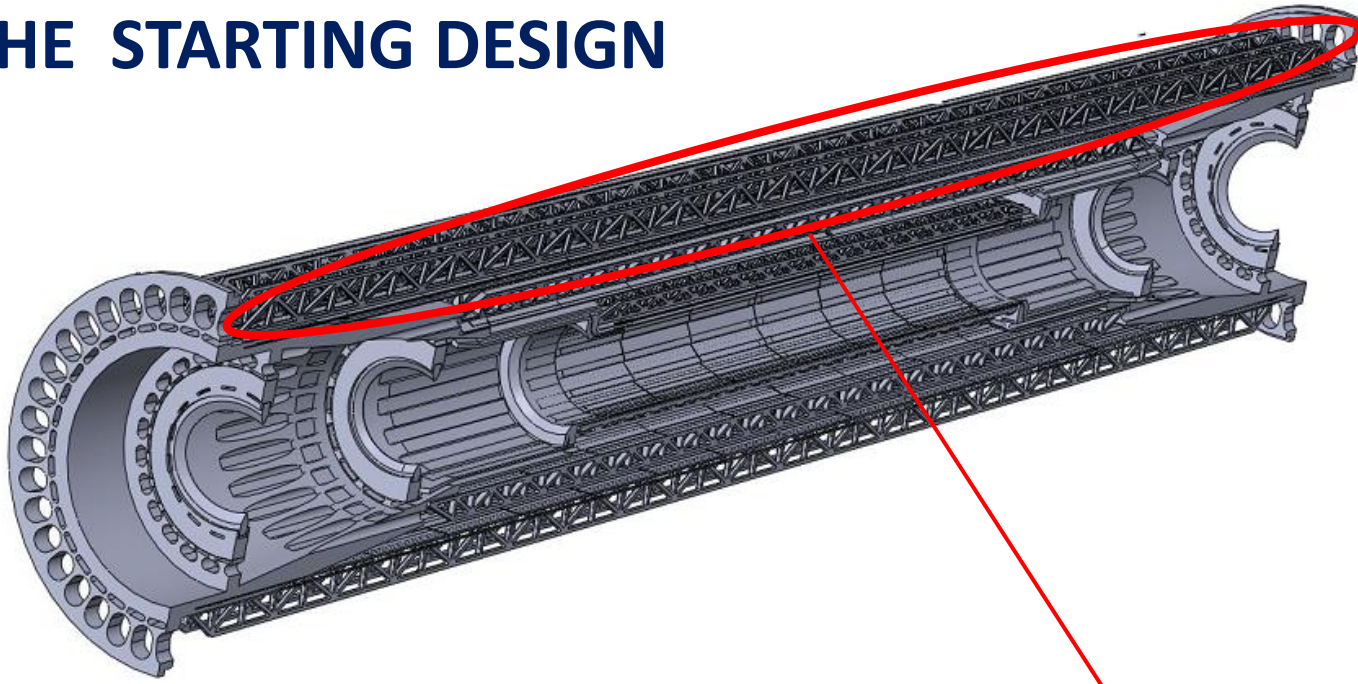
- Faster to have results.
- Easier to compare different design choices.
- Generally less expensive.

- Plenty of software are available, both Licensed and Open Source.

- We used the Ansys suite, mainly because of the greater experience of our team working with it.



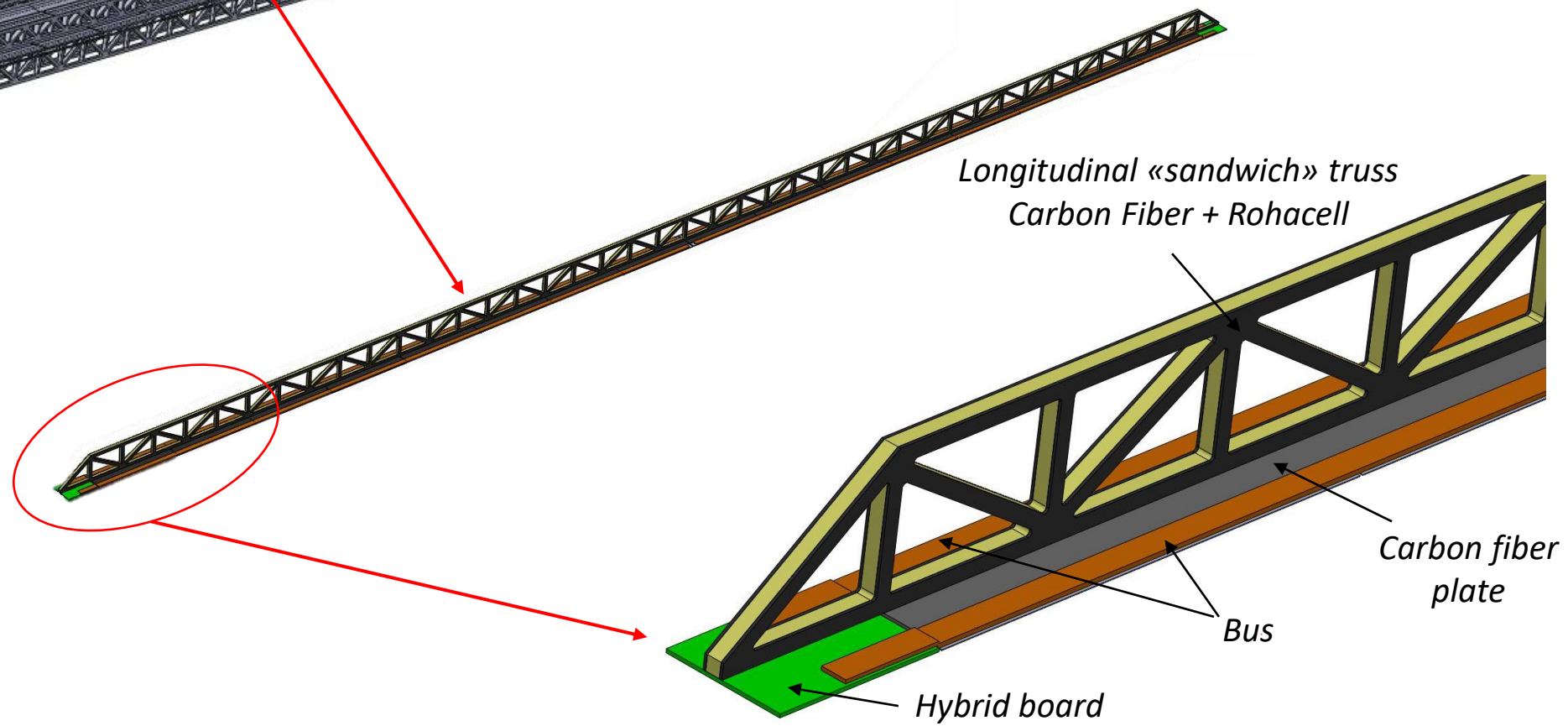
THE STARTING DESIGN



- The detector is made of lightweight longitudinal elements (“staves”) supported by endcaps at the ends:

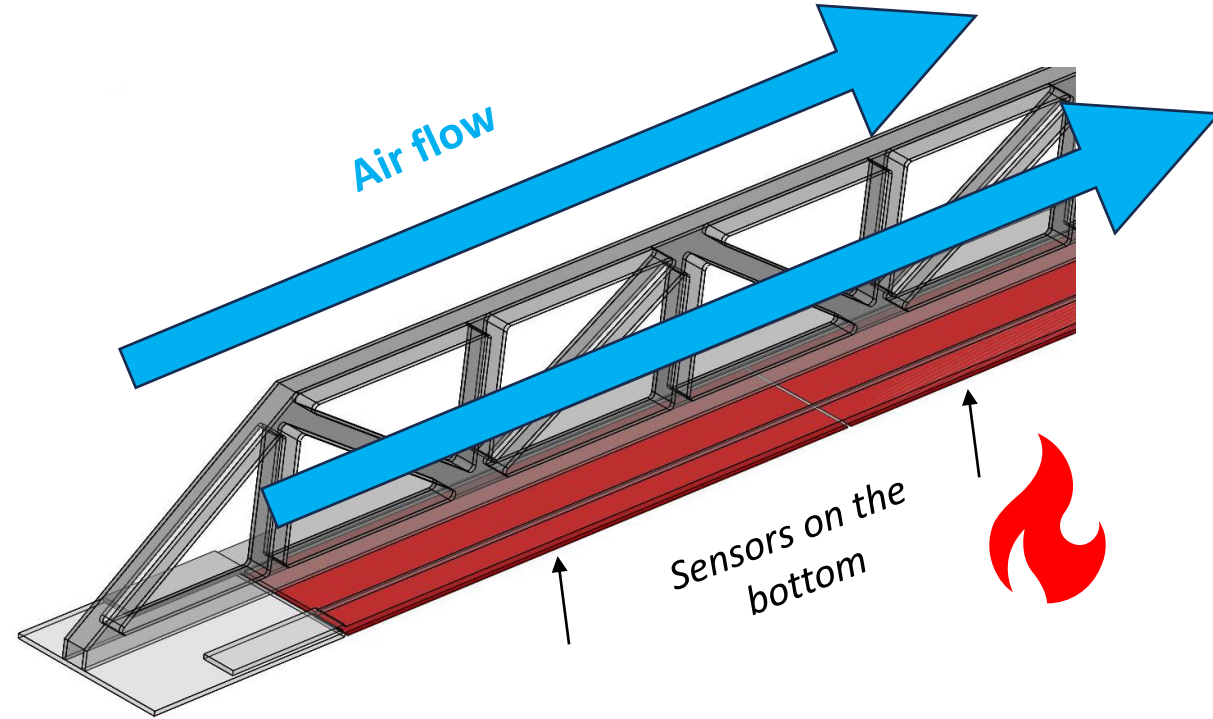
- 36 staves in **layer 3**, 16 Modules each, L = 540mm
- 24 staves in **layer 2**, 10 Modules each, L = 340mm
- 15 staves in **layer 1**, 6 Modules each, L = 220mm

- Reticular lightweight support to provide stiffness.
- Thin carbon fiber walls interleaved with Rohacell.
- 2 buses (data and power).
- 1.8 mm wide and 250 μm thick (50 μm Al, 200 μm kapton) per side.
- Inspired to low mass hybrid R&D.
- Sensors facing interaction point w/o any other material in front.
- Readout chips either sides.



INPUTS FOR THE MODEL

- Sensors are on the bottom face of each stave.
- Current estimation for sensors power dissipation:
 - Layer 3: $\dot{Q} \sim 77 \text{ W}$ (total)
 - Layer 2: $\dot{Q} \sim 32 \text{ W}$ (total)
 - Layer 1: $\dot{Q} \sim 12 \text{ W}$ (total)
- Modeled as constant volumetric heat source inside the volume of sensors.
- For the moment, only the bulk of the electronics boards is represented.
- Air flow has the same direction for all the layers (co-current flow)
- Input for simulations:
 - Temperature of air at inlet: $T_{\text{air}} = 15^\circ\text{C}$
 - Velocity of air at inlet: we tried different scenarios, with respectively: $v_{\text{in}_1} = 10 \text{ m/s}$, $v_{\text{in}_2} = 20 \text{ m/s}$, $v_{\text{in}_3} = 30 \text{ m/s}$



NUMERICAL ANALYSIS OF THE VERTEX

- *Some points to have in mind:*

- Different heat exchange modes are present :

- Conduction - through the mechanical parts
 - Convection - with the coolant, by definition
 - Radiation - Probably negligible, but worth evaluating



«Conjugate heat transfer problem»
Need to include in the model both the **solid** and the **fluid** domain, and make a mesh for both.

- Large difference in scale between the various components.

- Sensor thickness: order of 50 μm
 - Staves size: order of 500 mm



The smallest significant detail in the domain defines the minimum cell size for the mesh.

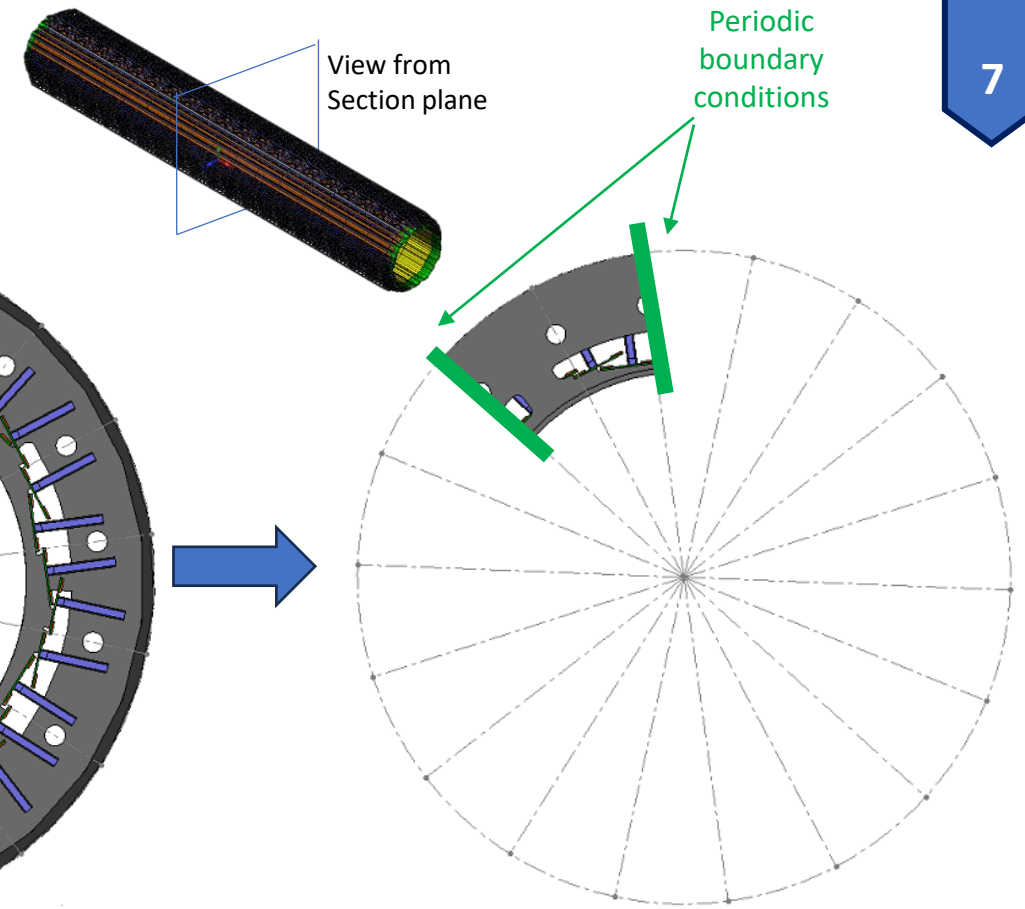


Then, overall scale of the domain defines the maximum number of cells which are needed.

➤ **The number of cells needed to discretize the domain quickly becomes enormous !**

SIMPLIFICATIONS OF GEOMETRY

- Simplification of the geometry is needed. THE FIRST approach:



Starting from the full geometry

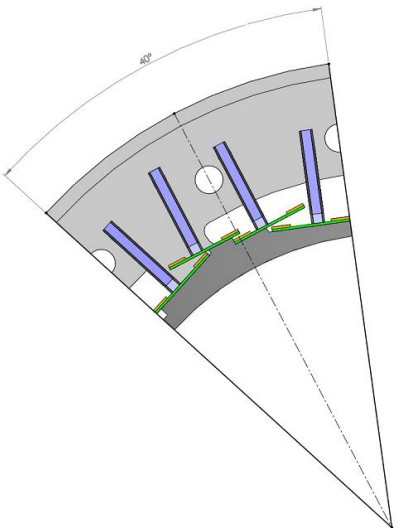
Removing layer 1 and 2

*Focus on one sector of Layer 3
(40° circular symmetry)*

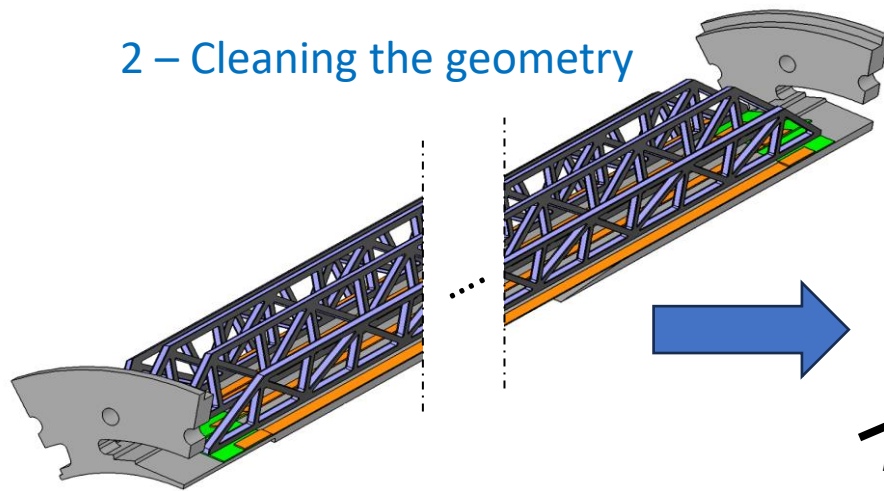
- A model for a 40° sector of layer 3 is manageable with a medium-performance desktop workstation.
- Next target is to include also layer 2 and 1 (the layers are not airtight, air moves between layers)
- For simulating bigger domains, exploring higher performance machines or HPC capabilities.

STEPS FOR THERMAL SIMULATIONS

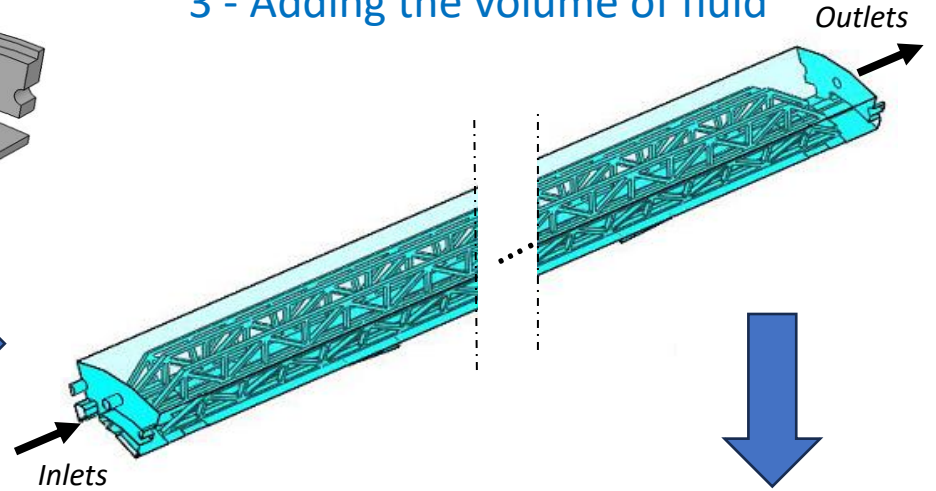
1 - Definition of the domain



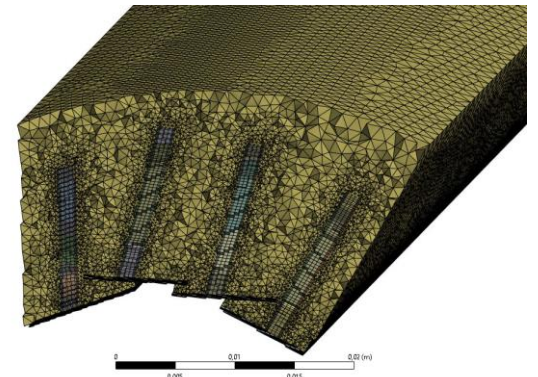
2 - Cleaning the geometry



3 - Adding the volume of fluid



4 - Creating the grid



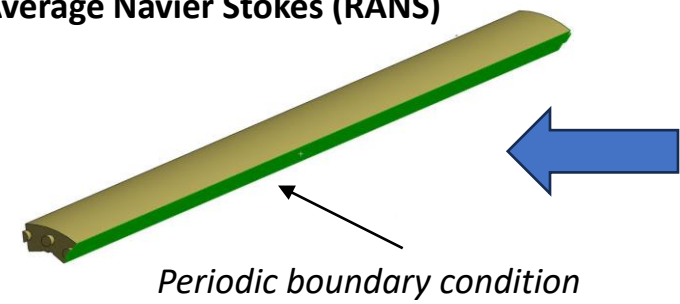
6 - Run calculations



We used: i9-10900X CPU, 20 threads, RAM 128 GB, 2 TB SSD

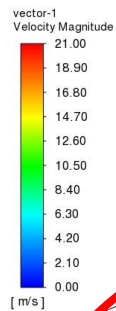
5 - Setting up the model

- ✓ Steady state conditions
- ✓ **Turbulent flow: Reynolds Average Navier Stokes (RANS)**
- ✓ Viscous model k- ω SST
- ✓ Pressure based solver
- ✓ No radiation heat exchange
- ✓ Volumetric constant power source on sensors volume

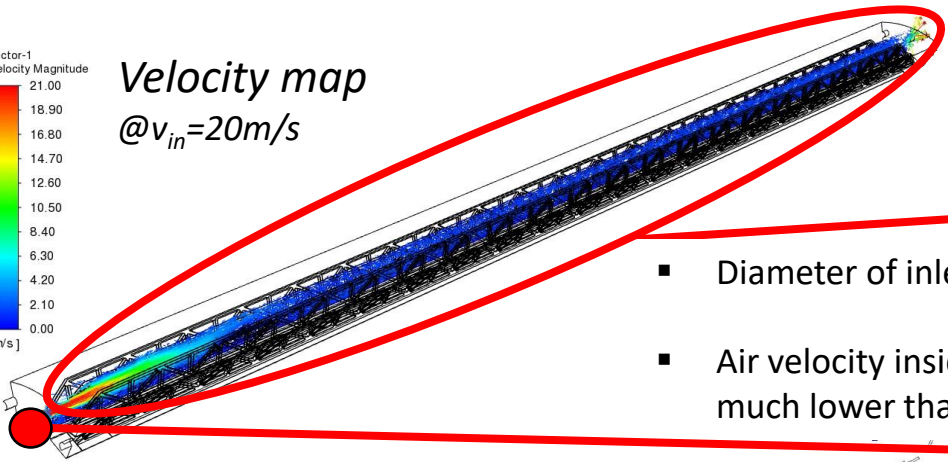


- Both the solid and fluid domains are simulated at the same time
 - 10'500'000 Elements
 - 17'000'000 Nodes

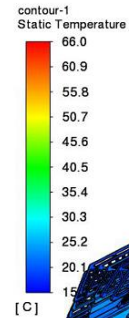
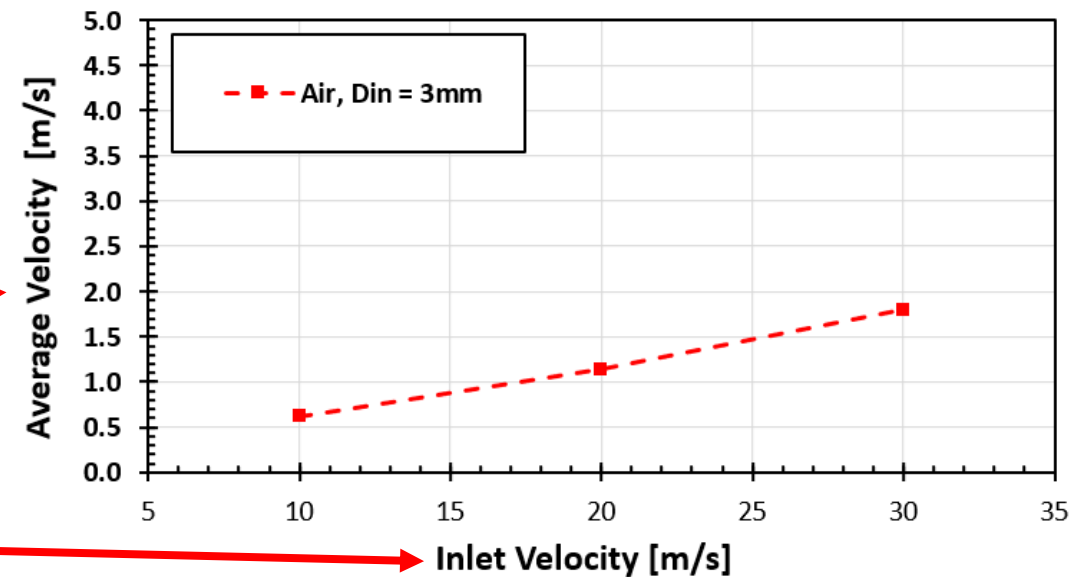
ANALYSIS OF RESULTS



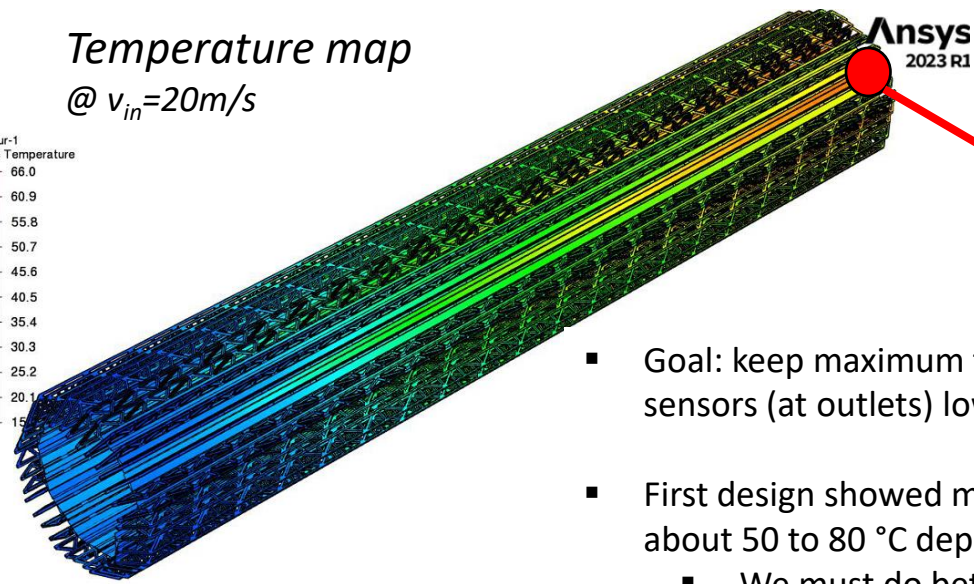
Velocity map
@ $v_{in}=20\text{m/s}$



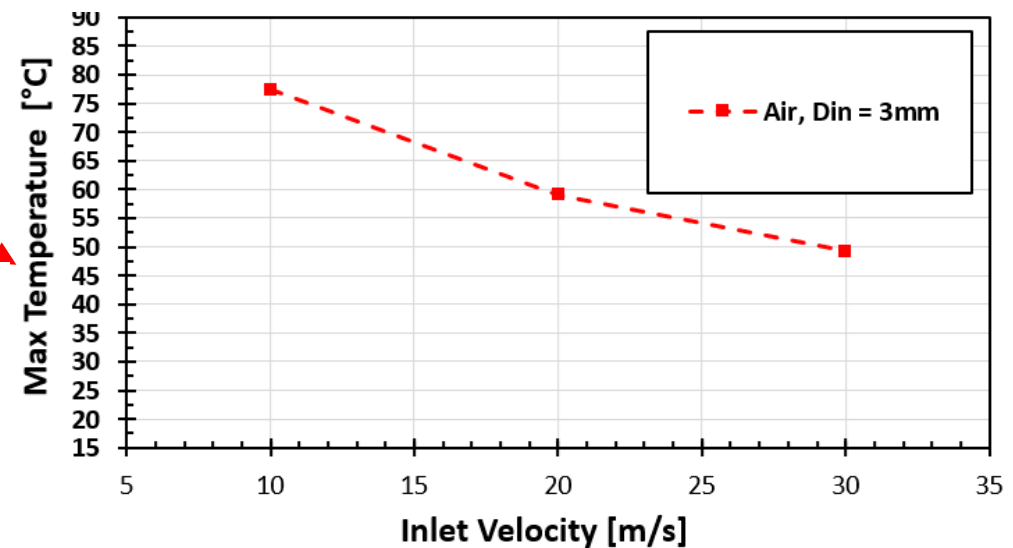
- Diameter of inlet holes $D_{in} = 3\text{mm}$
- Air velocity inside the cylinder much lower than inlets.



Temperature map
@ $v_{in}=20\text{m/s}$

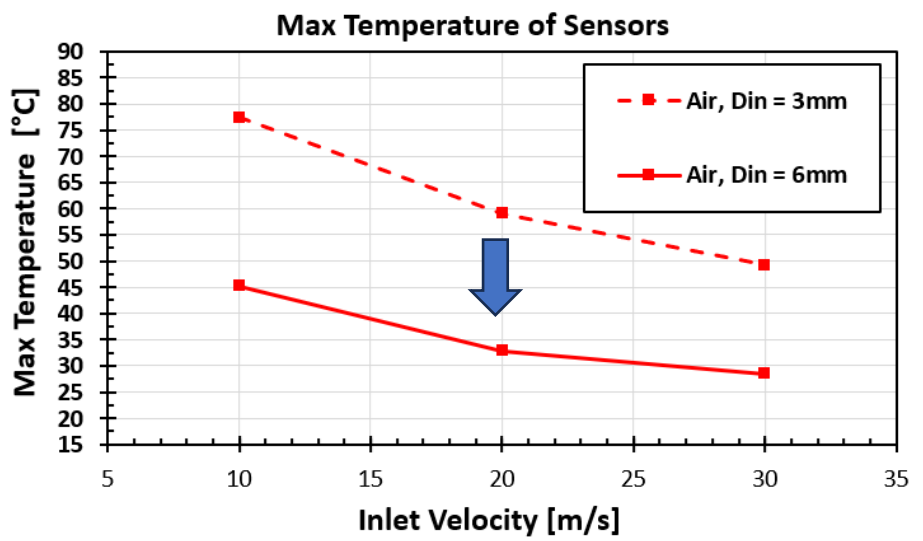
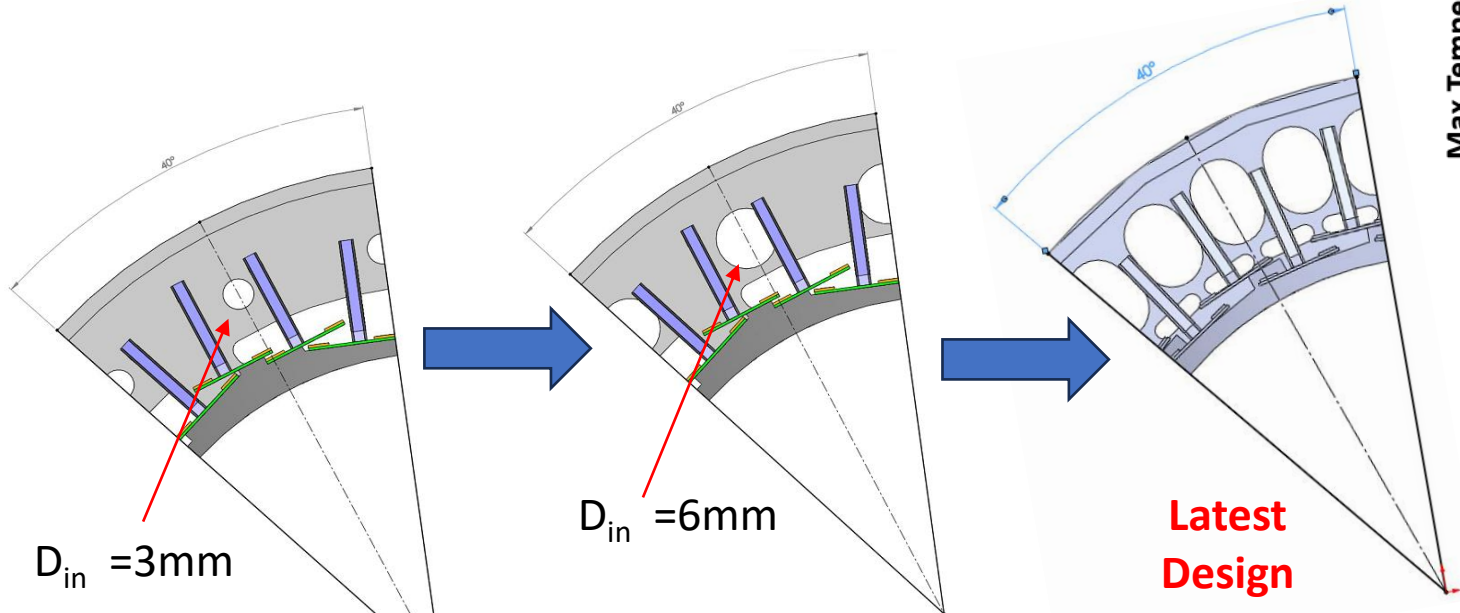


- Goal: keep maximum temperature of sensors (at outlets) low.
- First design showed max temperature about 50 to 80 °C depending on air flow.
 - We must do better!

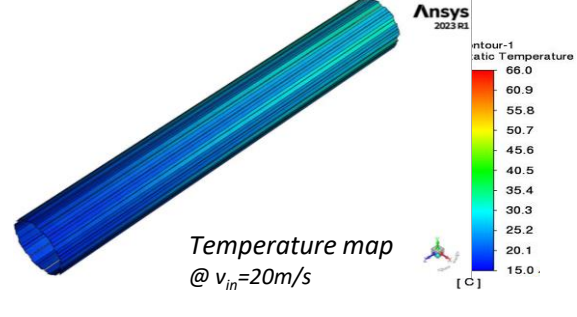
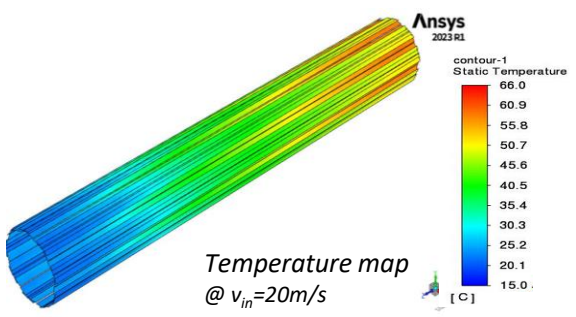


DESIGN OPTIMIZATION

- Big improvement just increasing the diameter for inlets holes.
 - Mass flow rate increase as well (for same v_{in}).

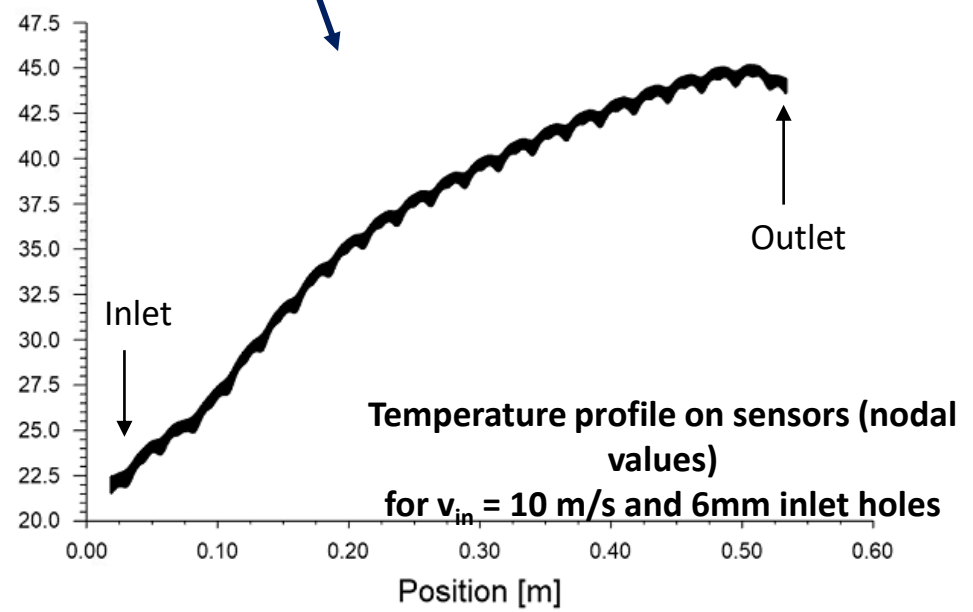
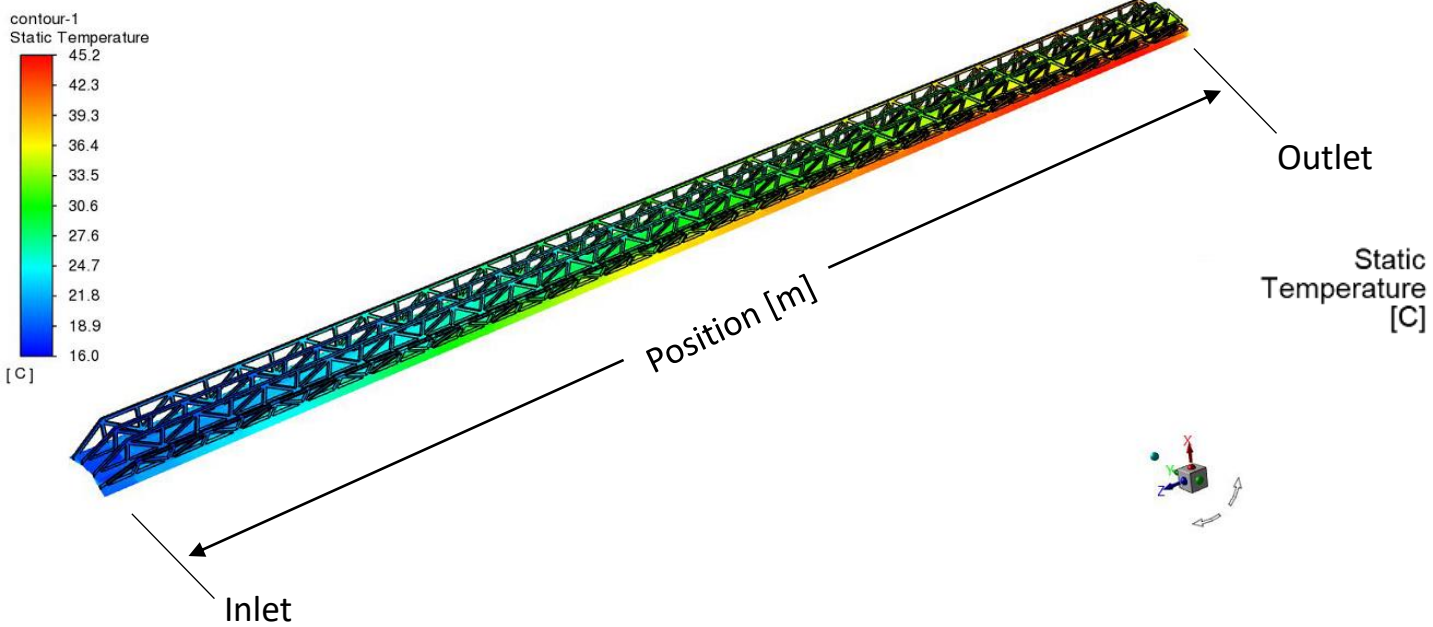
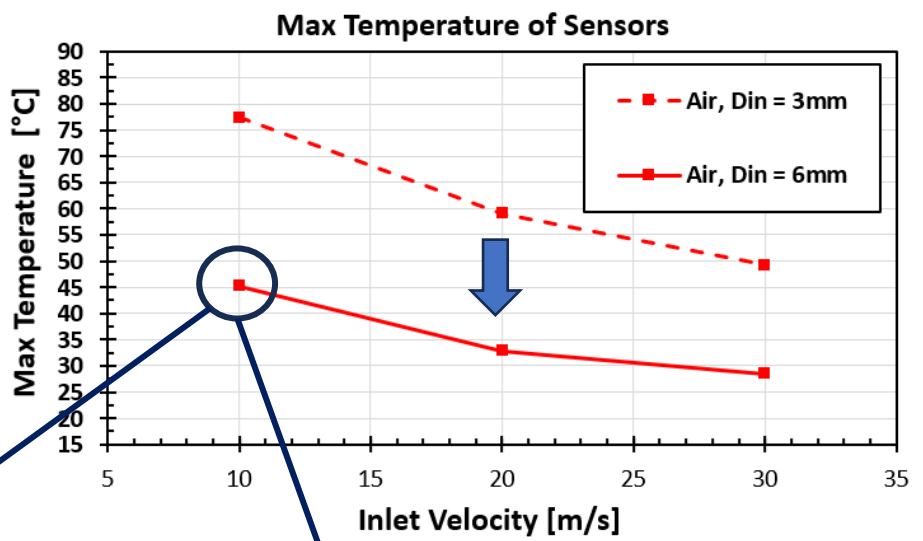


- Obtained max sensor ΔT wrt inlet air temp. about **15 to 30°C**. (Function of air velocity)



DESIGN OPTIMIZATION

- Big improvement just increasing the diameter for inlets holes.
 - Mass flow rate increase as well (for same v_{in}).
- Check also the max temperature gradient allowed by sensors along the stave:
 - Now worst case about **22°C** for $V_{in} = 10\text{m/s}$
 - Margin for improvements
 - Already better values for higher velocities

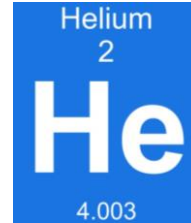


ANOTHER POSSIBILITY: CHANGING THE FLUID PROPERTIES

- The use of helium as a fluid instead of air was investigated.

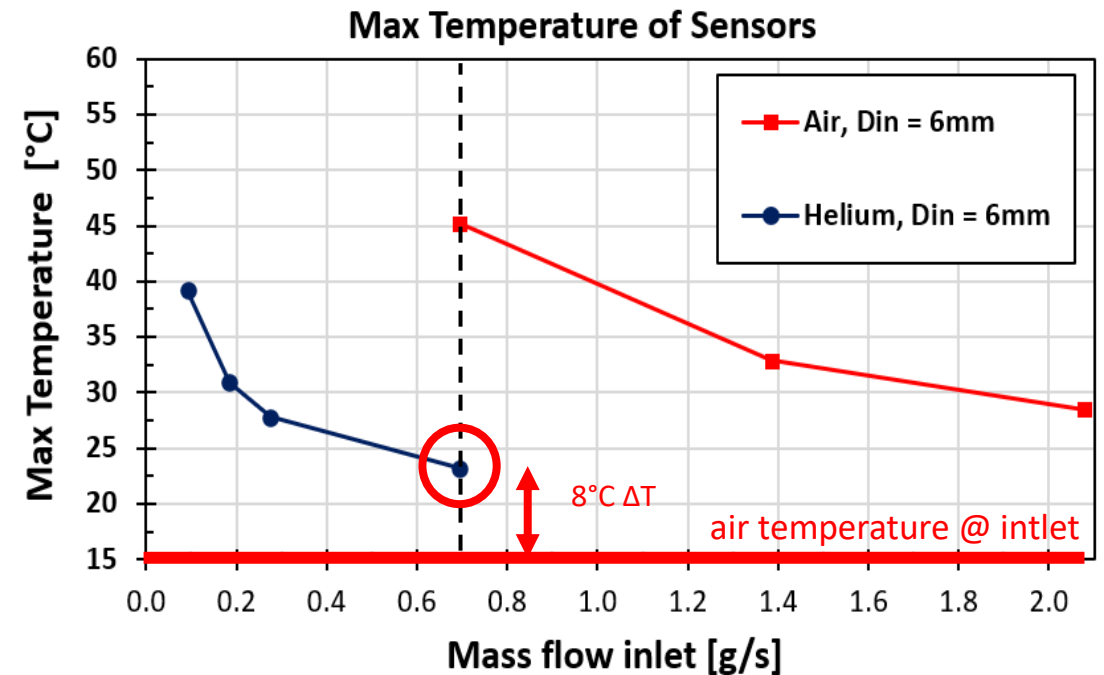
- Properties of helium taken from Ansys libraries:

- Lower density than air.
- Higher thermal conductivity than air.



$$\dot{m} = \rho \cdot v \cdot A$$

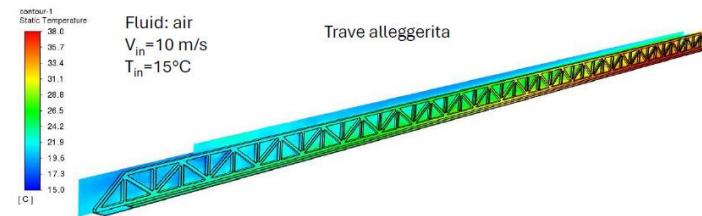
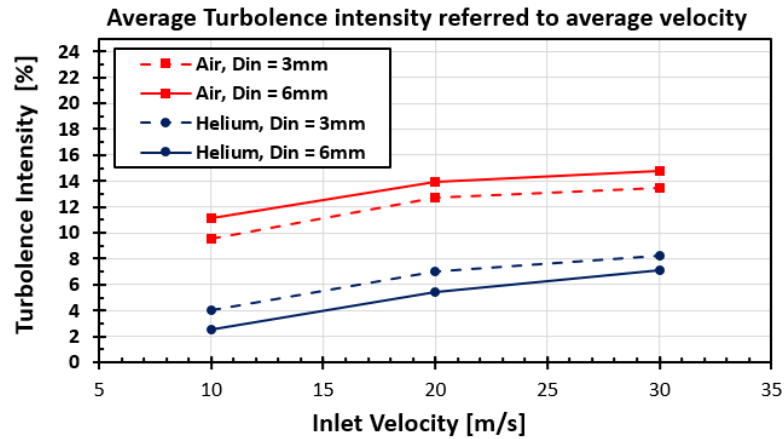
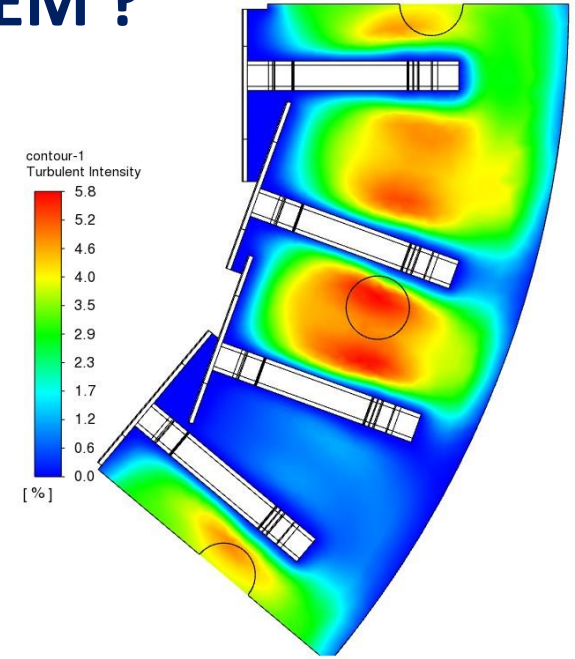
	Air	Helium
Density [kg/m ³]	1.225	0.1625
Specific Heat [J/(kg K)]	1006	5193
Thermal Conductivity [W/(m K)]	0.024	0.152
Viscosity [kg/(m s)]	1.79e-05	1.99e-05



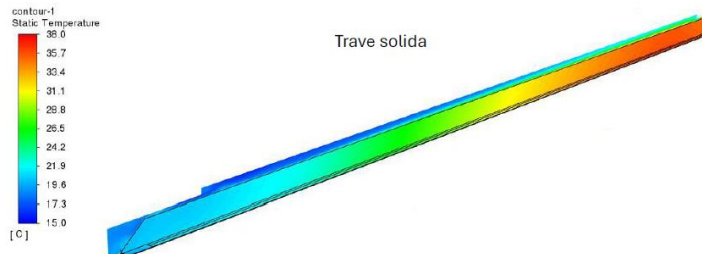
- Comparison is interesting considering the same mass flow rate instead of same inlet velocity.
- Helium offers much better cooling than air for the same mass flow rate.

WHAT IS MAXIMUM AIRFLOW TOLERATED BY THE SYSTEM ?

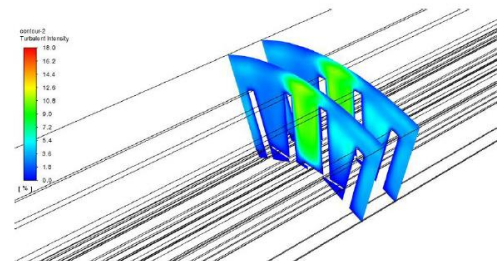
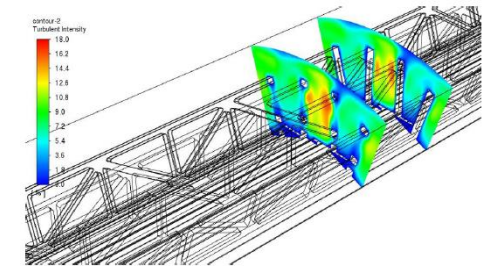
- The **turbulence** generates a mixing of air which favors heat exchange.
- But also induces vibrations on the lightweight structure.
- Turbulence is generated by the air moving through the stave holes, but also depends on the air injection system (the compressor for example).
 - **Turbulence at the inlet is another input for the model**
(Current Hypothesis 5 to 10%)
- Need to study the **fluid-induced-vibrations to the structure**



$V_{media_aria}=1.5$ m/s
Turbulent Intensity=12.6%
 $T_{max_sensor}=37.9^{\circ}\text{C}$
Mass_flow=0.17 g/s

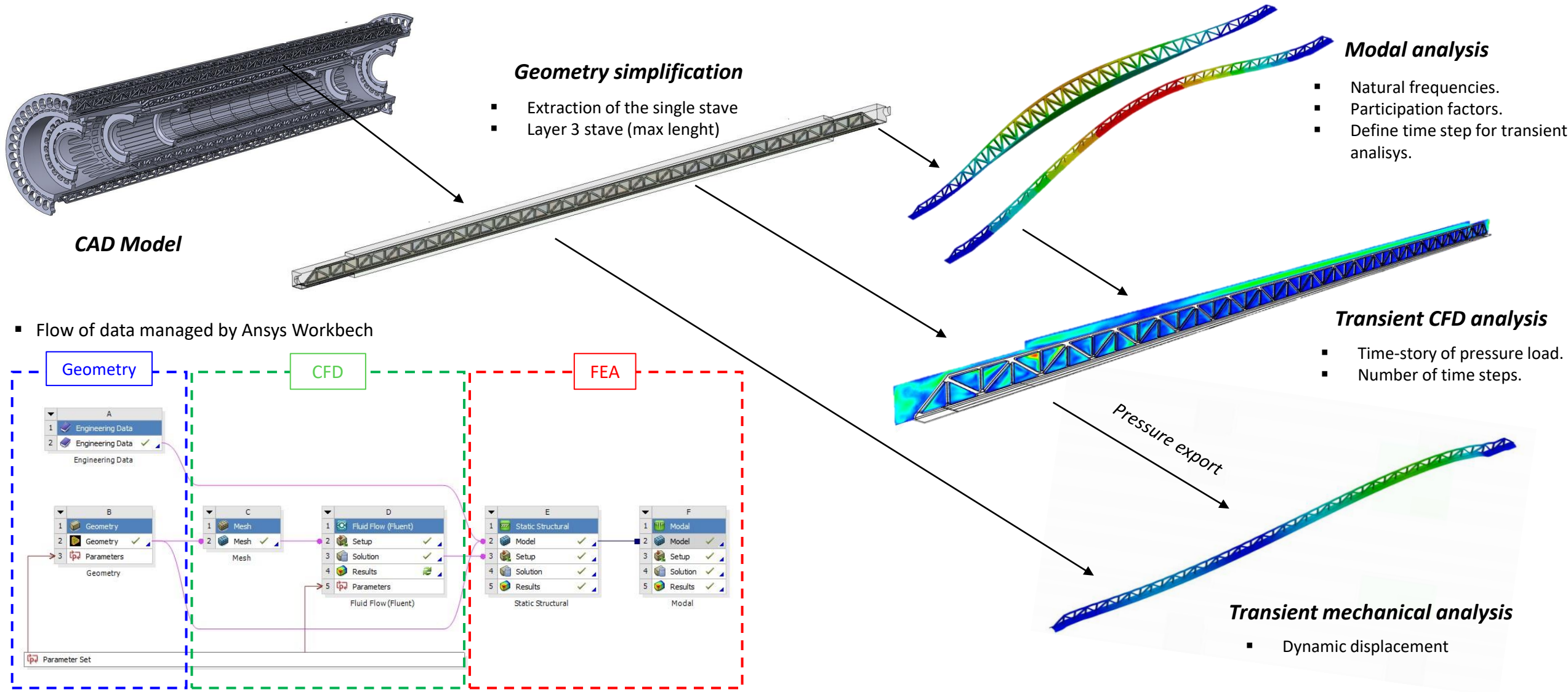


$V_{media_aria}=1.5$ m/s
Turbulent Intensity=10.5%
 $T_{max_sensor}=36.2^{\circ}\text{C}$
Mass_flow=0.17 g/s

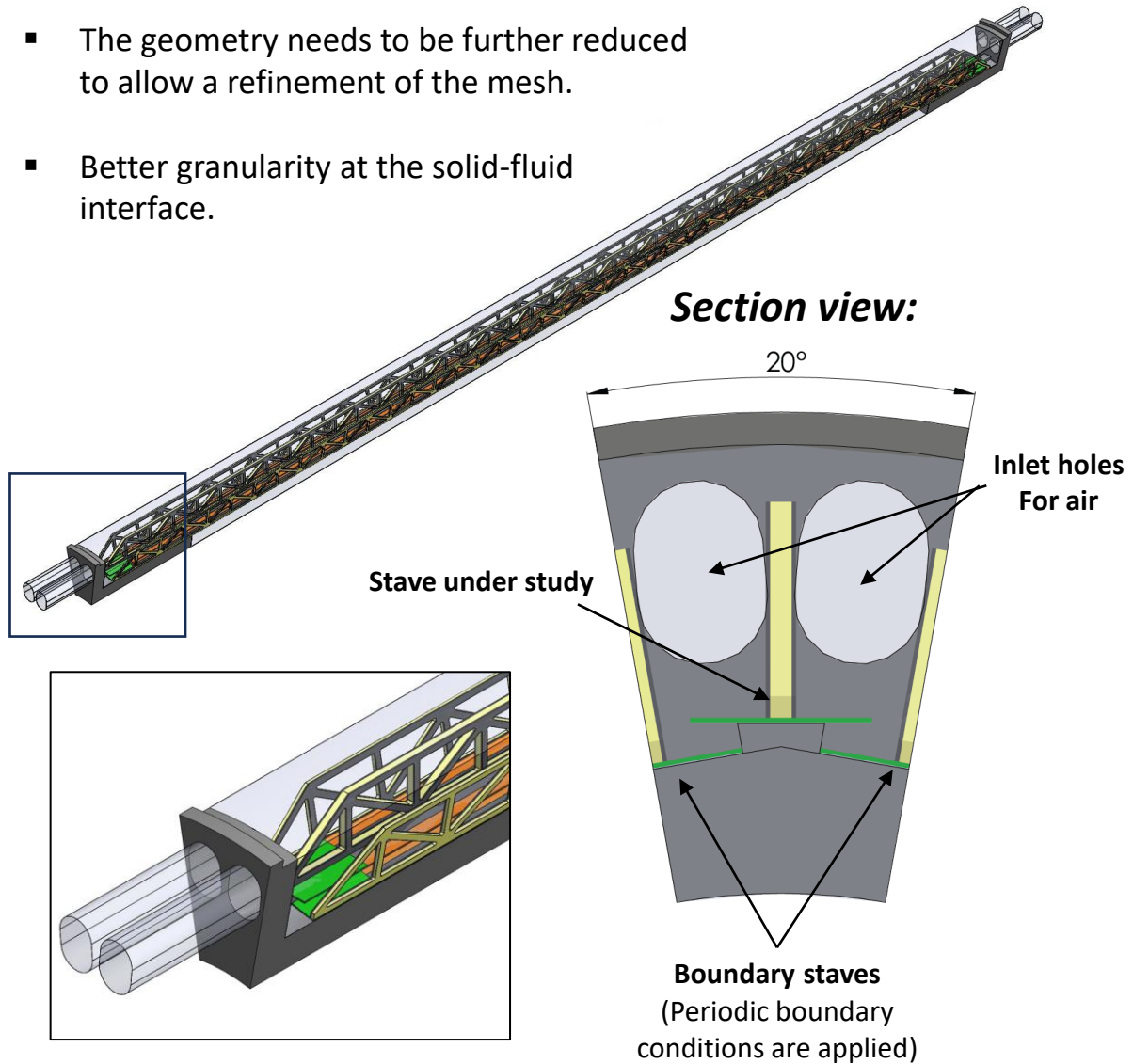


A MULTIPHYSICS MODEL FOR THE EVALUATION OF MECHANICAL STRESS

- Define a tool to evaluate whether the air flow necessary to remove the heat generates excessive vibrations on the stave.

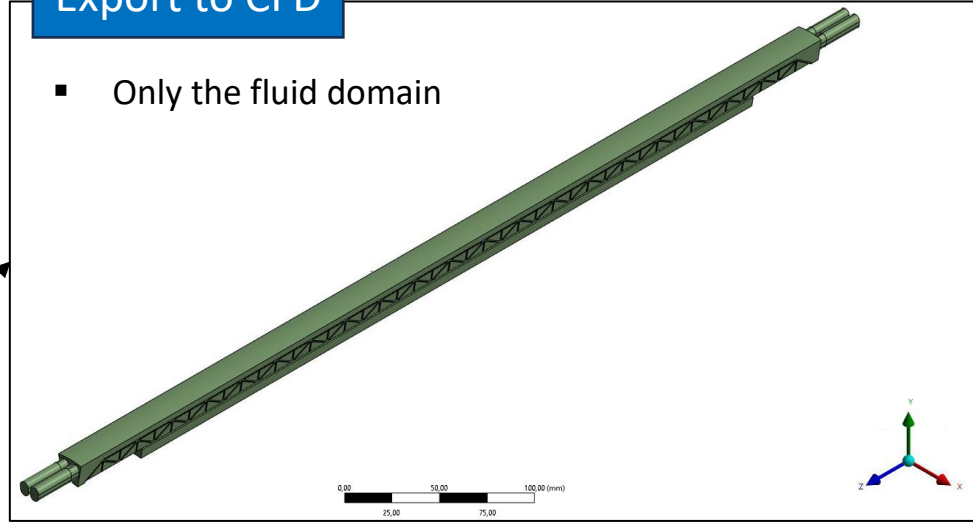


- The geometry needs to be further reduced to allow a refinement of the mesh.
- Better granularity at the solid-fluid interface.



Export to CFD

- Only the fluid domain



Export to FEA

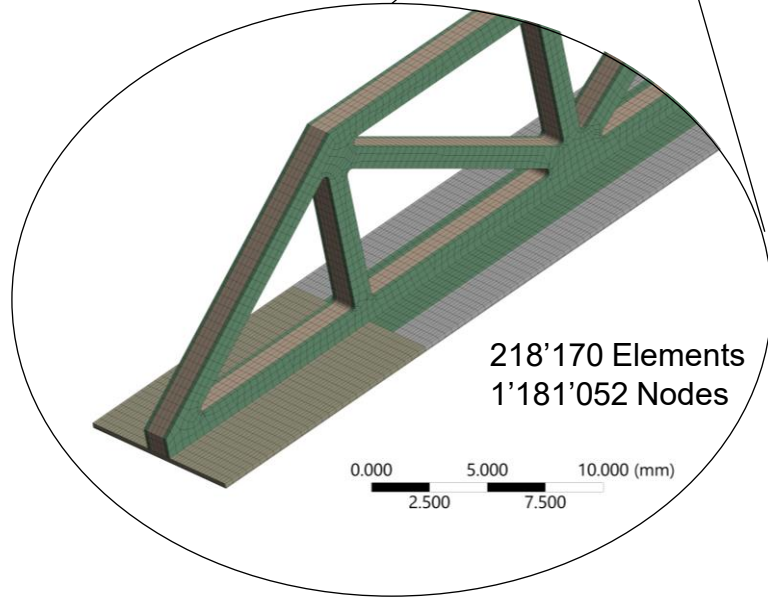
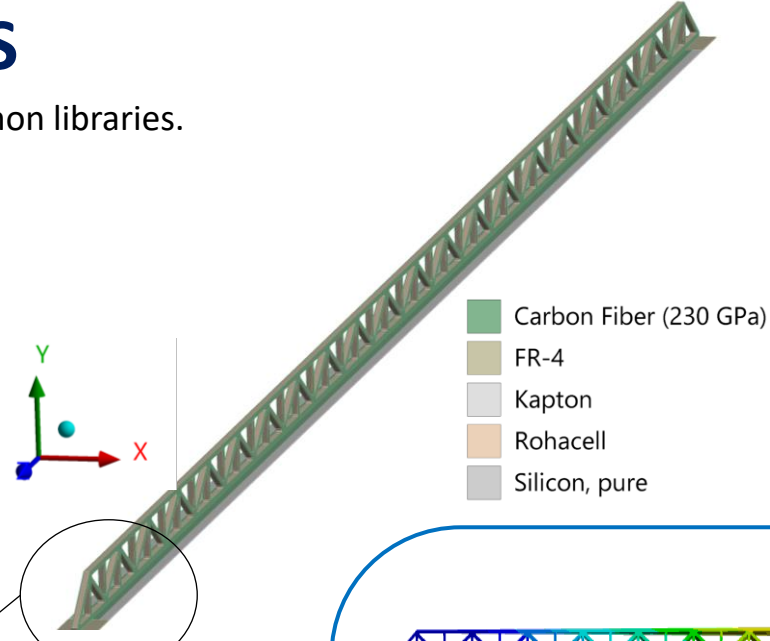
- Only the central stave



MODAL ANALYSIS

- Material data taken from common libraries.
- Frequencies > 100 Hz
- 1° Mode torsional
- Natural frequencies are used to define the time step for next transient analysis:

$$\Delta t < \frac{1}{f_{max} \cdot 10}$$



Constraints

- Hypothesis: support cone (anchoring of each stave) not deforming with time.

Lateral View

Bottom View

Results

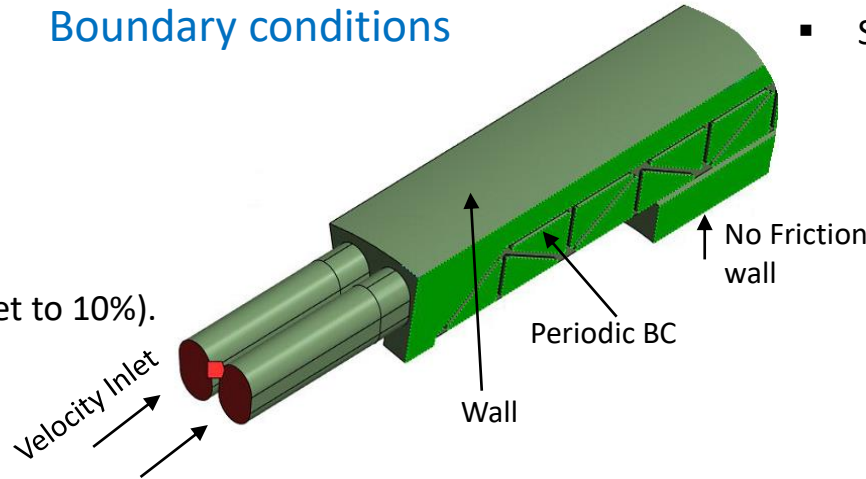
Mode	Frequency [Hz]
1	118.8
2	147.1
4	292.1
5	394.4

CFD TRANSIENT ANALYSIS

- $Re > 4'000$ – Turbulent flow $Re = \frac{F_{inertia}}{F_{viscous}} = \frac{\rho V D_H}{\mu}$
- Viscous model: Large Eddy Simulation (LES) Model
- Average velocity at inlet: $V_{in_avg} = 10$ m/s
- Turbulence generator at inlet (turbulence intensity set to 10%).
 - Spectral Synthesizer Algorithm [

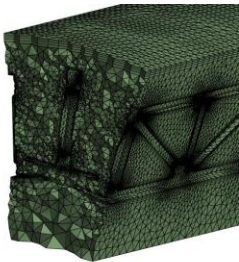
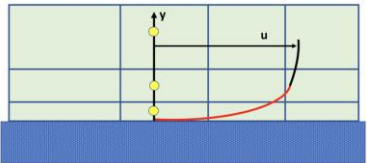
$$\mathbf{u}(\mathbf{r}, t) = 2K_t \sum_{i=1}^N \sqrt{q_i} [\sigma_i \cos(k_i \mathbf{d}^i \cdot \mathbf{r} + \phi_i + s_i \frac{t}{T})]$$

Boundary conditions

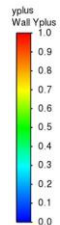


- Solver parameters:
 - Time step = $6.8e-4$ s
 - N° of time steps (Total simulated time) defined by the time a flow particle takes to cross the entire beam, given the RMS velocity of the flow along the axis.
 - NOTE: this involve long calculation time !

Mesh



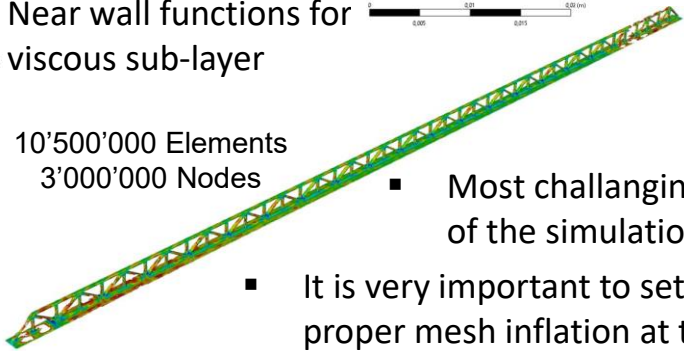
- Near wall functions for viscous sub-layer



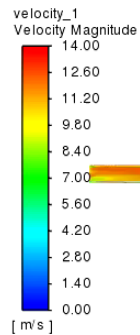
10'500'000 Elements
3'000'000 Nodes

- Most challenging part of the simulation.

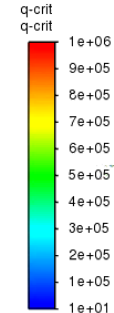
- It is very important to set a proper mesh inflation at the boundary layers.



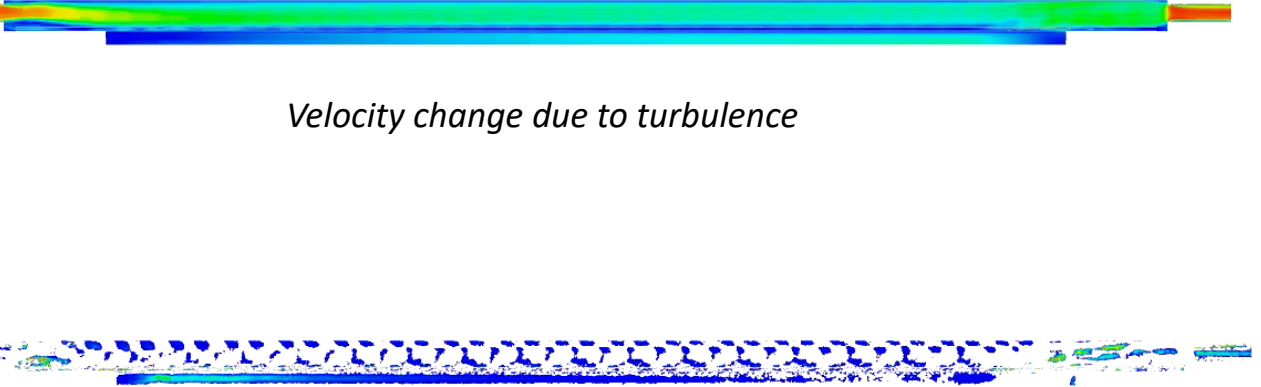
Results



Velocity change due to turbulence



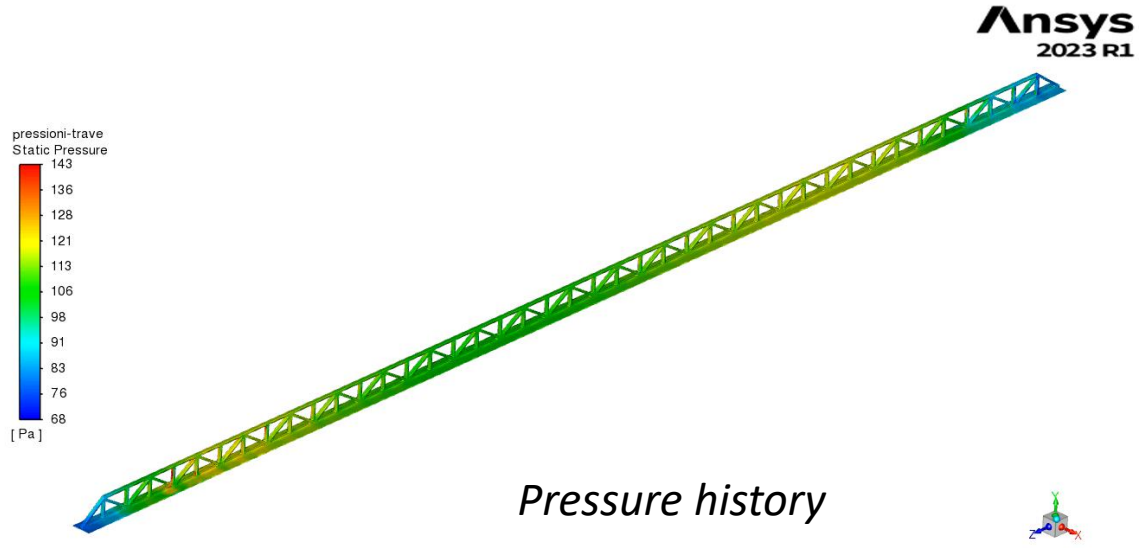
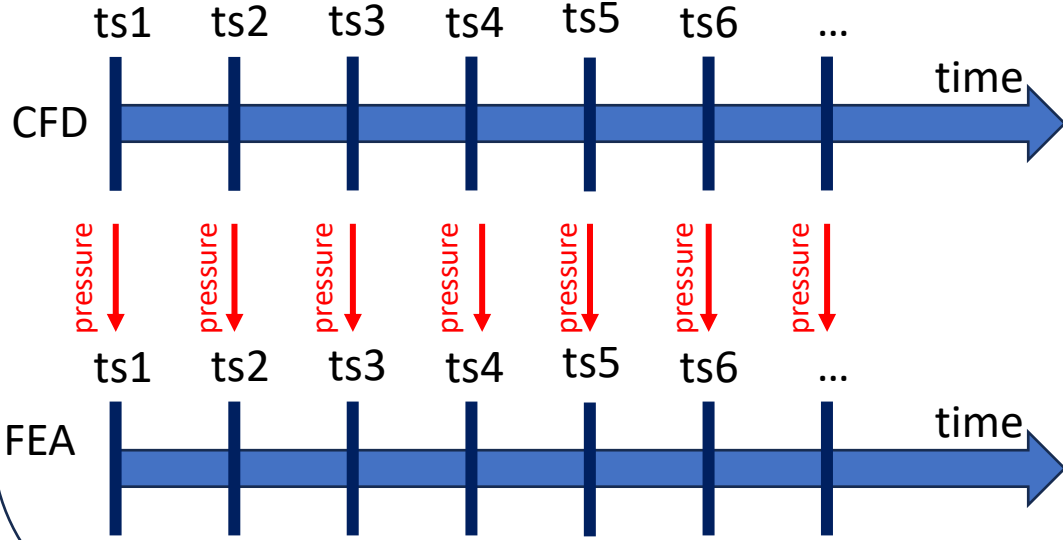
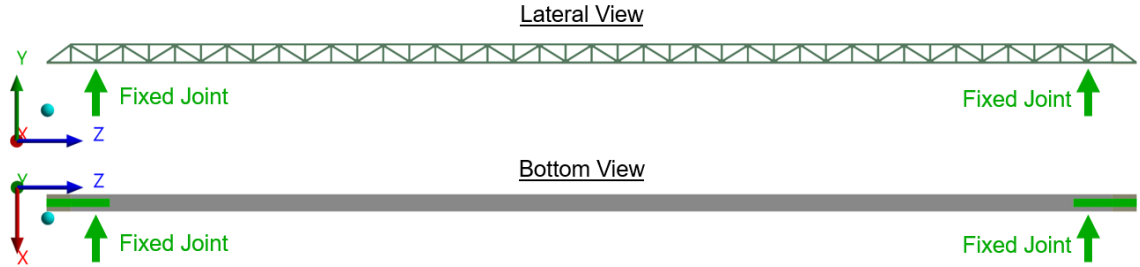
Q-criterion can be used for vortex visualization



SETTING THE MECHANICAL TRANSIENT ANALYSIS

Boundary conditions

- Same constraints and materials used for Modal analysis.
- Pressure history is imported from CFD as external load on all the boundary surfaces of the beam.
- Set time step (ts) for FEA simulations the same as for CFD (pressure load is updated each time step).



RESULTS

D: Transient Structural

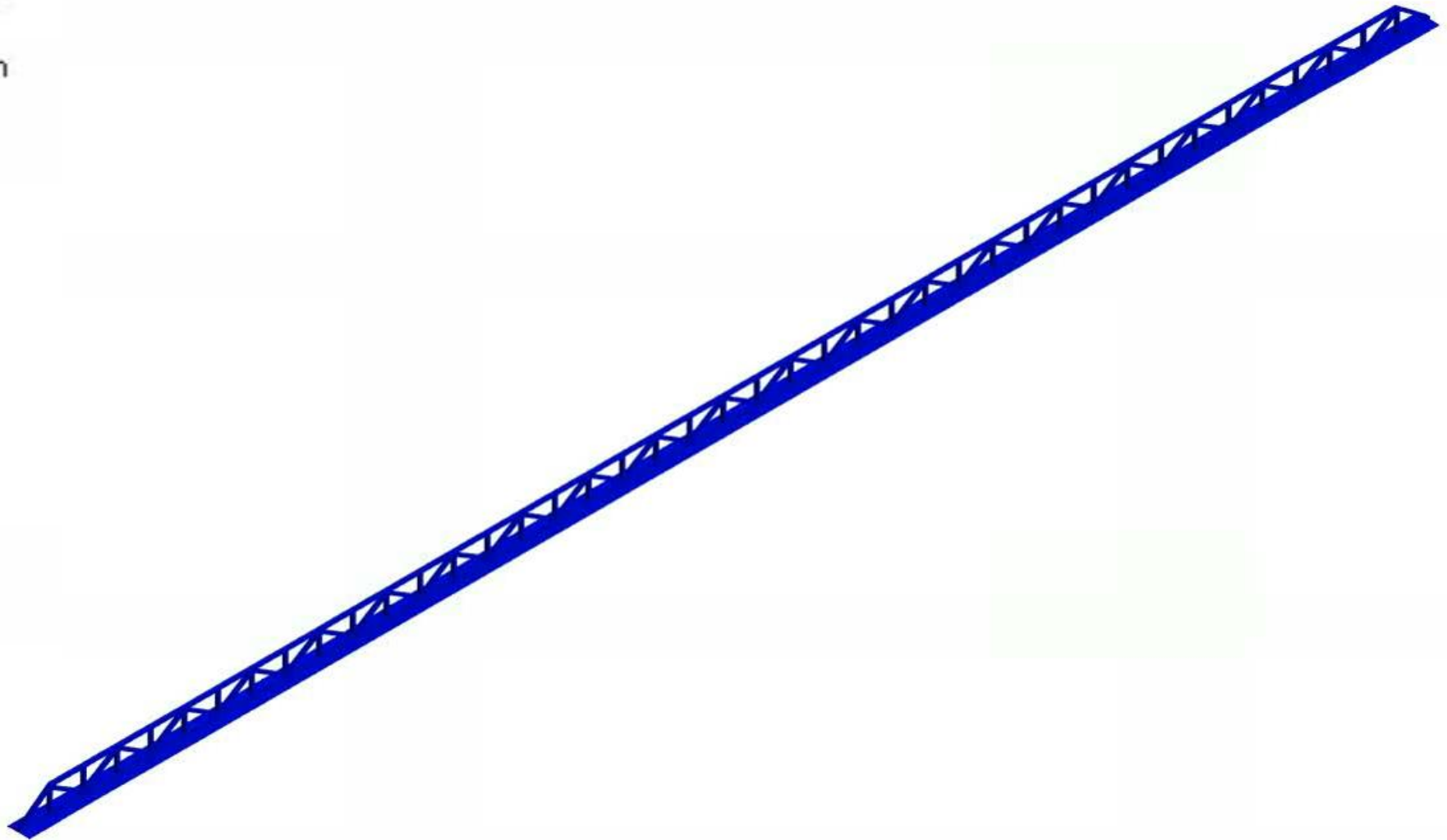
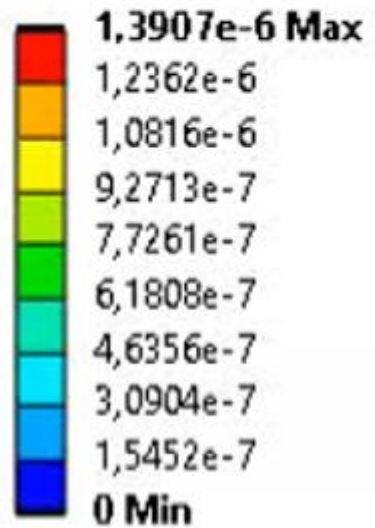
Total Deformation

Type: Total Deformation

Unit: m

Time: 2,e-003 s

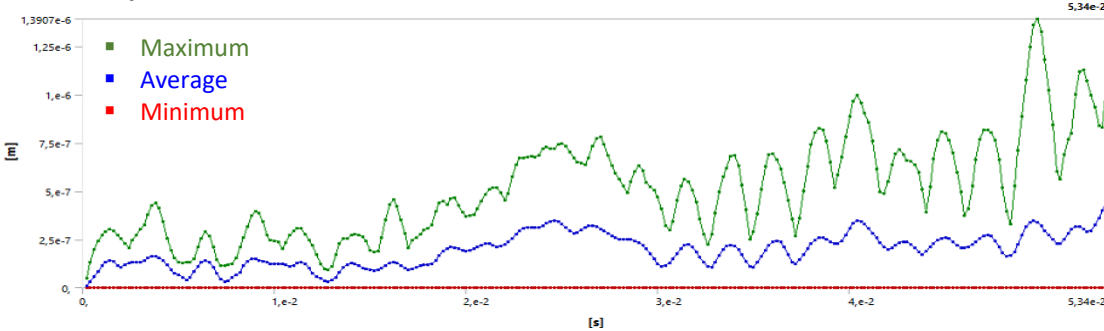
25/05/2024 01:07



RESULTS

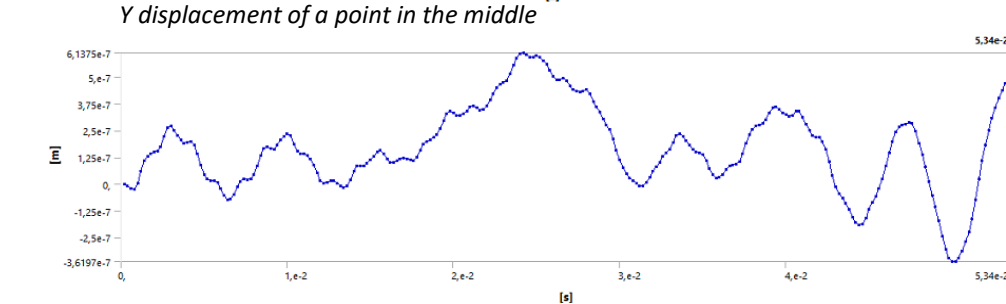
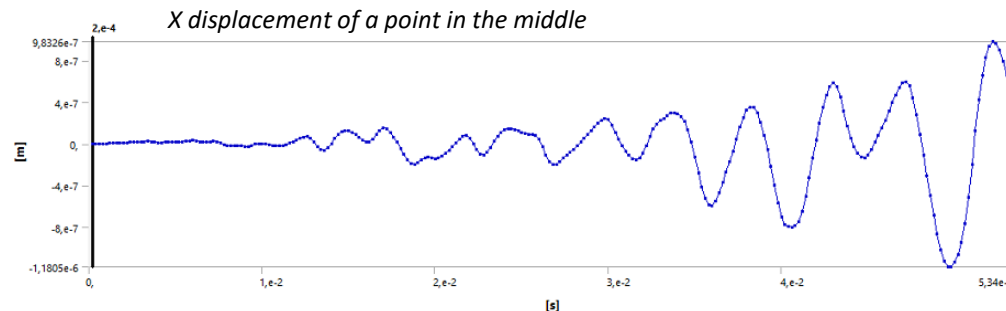
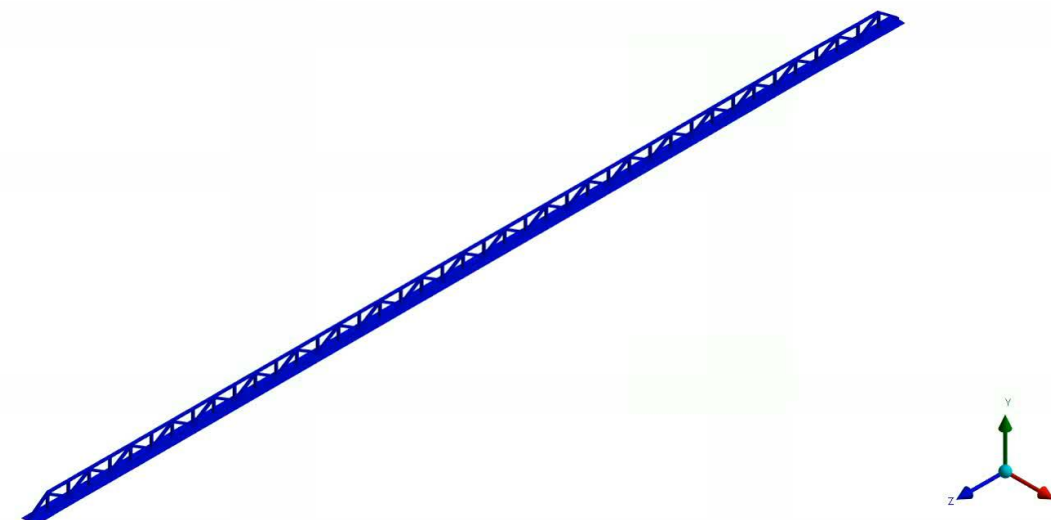
- Simulation takes some time steps before first modes are fully developed.
- First two natural frequencies are clearly triggered.

Global deformation:

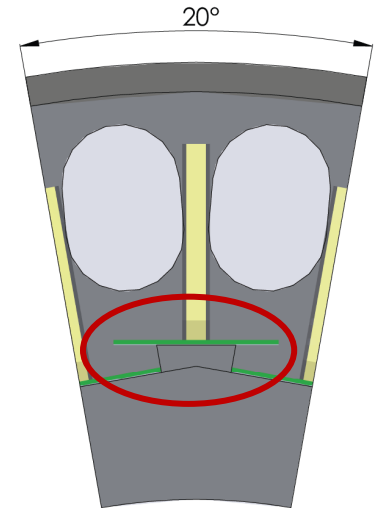


D: Transient Structural
Total Deformation
Type: Total Deformation
Unit: m
Time: 2.e-003 s
25/05/2024 01:07

1.3907e-6 Max
1.2362e-6
1.0816e-6
9.2713e-7
7.7261e-7
6.1808e-7
4.6356e-7
3.0904e-7
1.5452e-7
0 Min

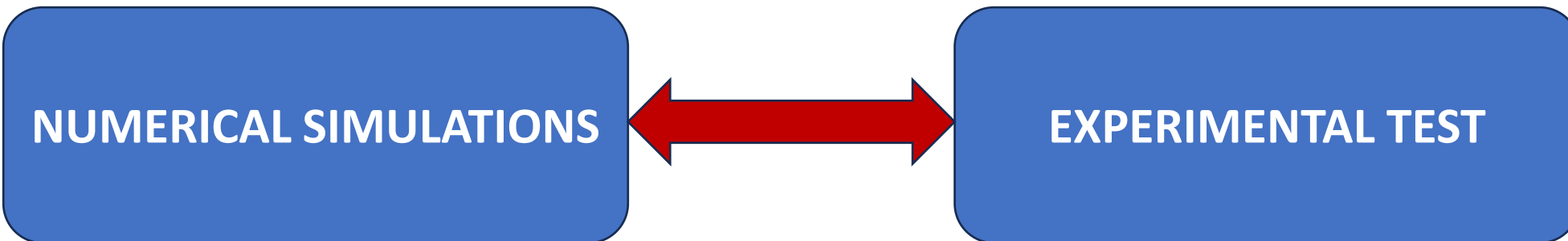
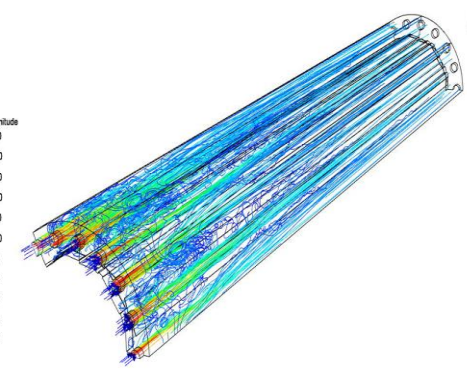
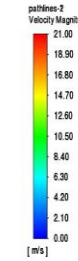


- Maximum displacement magnitude about $1.5 \mu\text{m}$ @ $v_{in} = 10\text{m/s}$
 - Mainly due to first-mode
 - This give hint to improve stiffness in the fixation region to the support cone.
- Model must be tuned with experimental data.
 - Look for suitable displacement sensors for the micron scale!



SUMMARY & FINAL REMARKS

- Numerical simulations are a valid tool for guiding the design of the vertex detector.
- A **FVM model** is useful for predicting the maximum temperature of the sensors.
 - Promising results on the simulated geometry with staves, still margin for improvements.
- A **Multiphysics** model joining CFD and FEA can be used to analyze the fluid-induced-vibrations on the structure.
 - For an air velocity of 10 m/s, simulated oscillations came in the micron scale in the simulated geometry.
- The proposed modeling workflow can be applied to any geometry of the vertex.
- **An experimental validation is crucial to tune the model ! Simulation work needs to go hand by hand with tests.**



- This is particularly true for the study of the dynamic response, since the turbulence model to be used really depends on the application.

Thanks for your attention

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