



# The *Time-of-Flight* system of the PAMELA experiment: in-flight performances.

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# The PAMELA experiment

- Search for antimatter
- Search for dark matter
- Study of cosmic-ray propagation
- Study solar physics and solar modulation
- Study of electron spectrum
- Study terrestrial magnetosphere

- First switch-on on June 21th 2007
- Continuous data taking mode since 11th July 2006
- Detectors are performing nominally
- Analysis is in progress



Launched on June 15th 2006 !

# PAMELA apparatus

7 detectors combined for high-sensitivity particle identification and precise momentum measure

## Time-Of-Flight

**plastic scintillator strips + PMT:**

- ⇒ trigger, albedo rejection;
- ⇒ mass identification up to  $E \sim 1$  GeV;
- ⇒ charge identification from  $dE/dX$ .

## **Magnetic spectrometer**

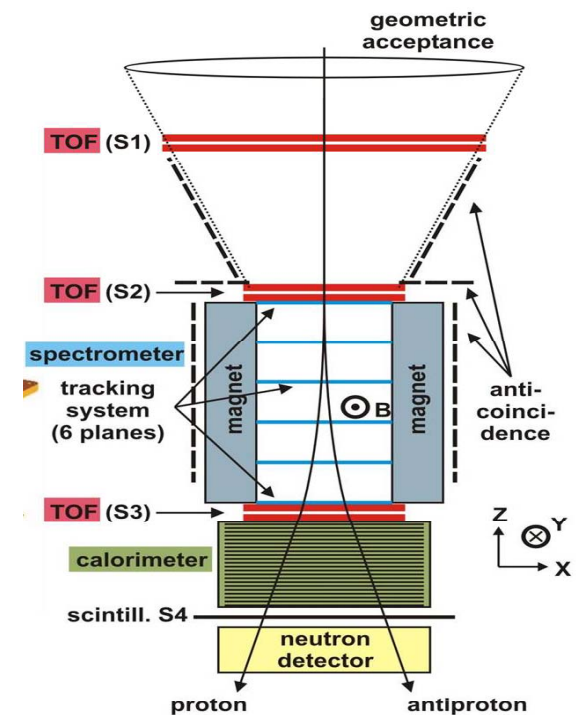
**with microstrip Si tracker:**

- ⇒ charge sign and momentum from the curvature;
- ⇒ charge identification from  $dE/dX$ .

## **Electromagnetic calorimeter**

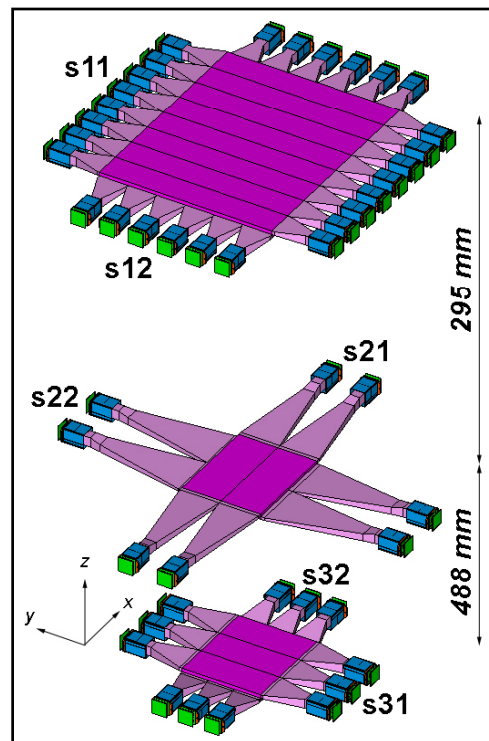
**W/Si sampling;  $16.3 X_0$ :**

- ⇒ discrimination  $e^+ / p$ ,  $e^- /$  from shower topology;
- ⇒ direct  $E$  measurement for  $e^-$ .



# The *Time-of-Flight* system

- 6 layers (3 planes, double view)
- Several paddles (scintillator + 2 PMTs) for each layer



- provide a fast signal for triggering data acquisition in the whole instrument
- measure the flight time of particles crossing its planes; once this information is integrated with the measurement of the trajectory length through the instrument, their velocity can be derived. This feature enable also the rejection of albedo particles
- determine the absolute value of charge  $z$  of incident particles through the multiple measurement of the specic energy loss  $dE=dx$  in the scintillator counters



# Monitoring *ToF* in orbit

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Main items to control:

- **Gain stability**

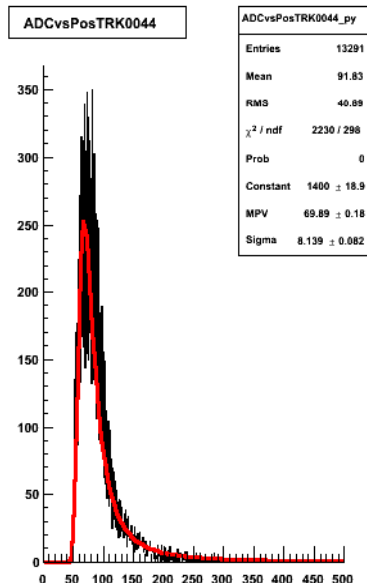
variation of gain as function of time changes the conditions for all measurement operations and has to be taken into account in the calibration software

- **Time resolution**

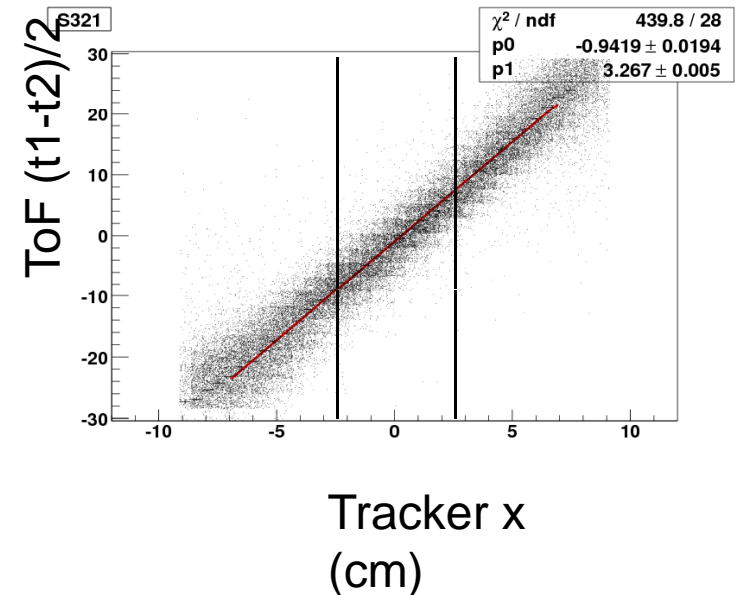
a good time resolution means, first of all, a good  $\beta$  measurement!

# Gain measurements

Select a clean sample of protons as reconstructed by the magnetic spectrometer with rigidity > 5 GV and  $\beta > 0.7$  which hit ToF paddles in a window of  $\pm 2.5$  cm from the centre of the paddle itself

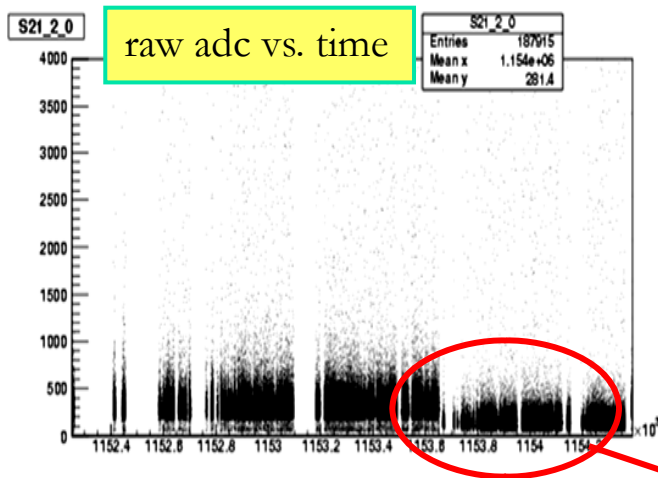


For this sample we can plot and fit the Landau distribution of the raw ADC signal: its peak value is the parameter we have to control

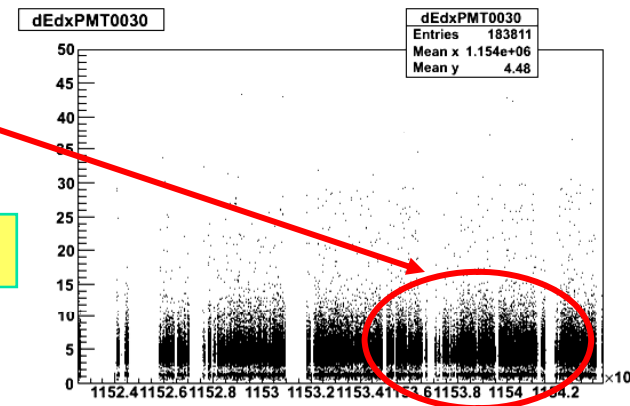


# Gain stability

For the periods during which there is a loss of gain for some PMTs we use "ad hoc" calibration parameters to normalize the situation



dEdx in m.i.p. in the same time interval

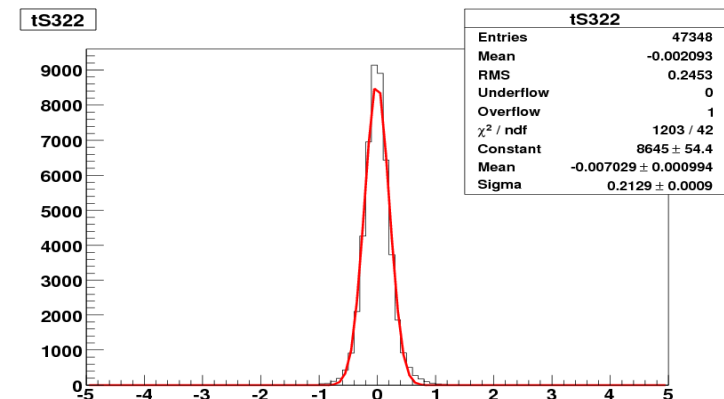
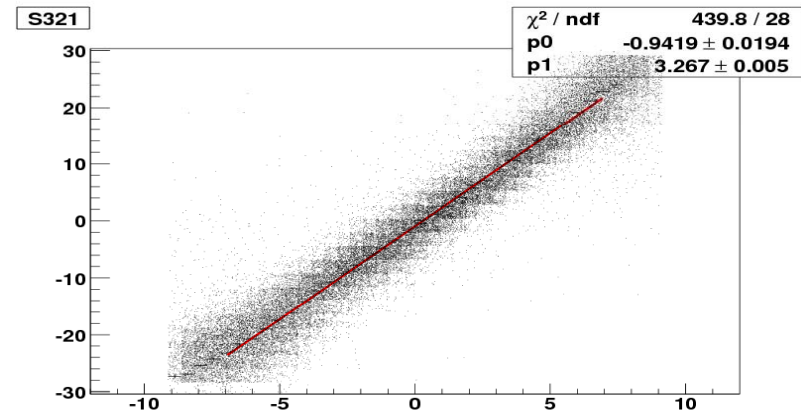


# Single paddle time resolution

The position of the hit point on a paddle as reconstructed by the ToF is proportional to the difference of the time measurements operated at both ends for that event

$$x = \frac{v_{eff}(t_1 - t_2)}{2} + cost$$

Plotting this TOF position vs. the position as reconstructed by the Tracker (assuming negligible the uncertainty in the projected position), the  $\sigma$  of the distribution of residuals gives us the single paddle time resolution.







# Single paddle time resolution

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- At this moment the measured time resolution is  $\sim 200$  ps for S1 and S3 paddles and  $\sim 150$  ps for S2 paddles for  $Z=1$  particles
- For higher  $Z$  the time resolution improves: preliminary result for  $Z=2$  is  $\sim 105$  ps
- This results are in agreement with some results from a beam test of February 2006 (in this case time resolution reached a value of 48 ps for Carbon ions)
- We expect improvement for  $Z \leq 3$  from *Time-Walk effect* correction (work in progress)



# $\beta$ resolution

The resolution on measurements of time of flight within two paddles of two different planes is the composition of the single paddle time resolution:

$$\Delta t_{ij} = \sqrt{(\delta t_i)^2 + (\delta t_j)^2}$$

Remembering that time of flight and  $\beta$  are related by:

$$T_{tof} = K_1 + K_2 \frac{1}{\beta}$$

We can easily derive  $\beta$  resolution according to:

$$\Delta T_{tof} = \frac{d \cdot \sigma_{\beta}}{c\beta^2}$$

Preliminary  $\beta$  resolution:  $\sim 14\%$  for  $Z=1$  (single measurement)

Also this result improves for higher  $Z$  and can be improved considering multiple measurements for the same event (6 layers allow several 2 paddles combinations...)



# Conclusions

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- The system is working well!
- Preliminary results are encouraging
- Several improvements are possible
- Work is in progress!



# $\beta$ measurement with *ToF*

$$t_1 = C_1 + \frac{x_1}{v_{eff}}$$

$$t_2 = C_2 + \frac{x_2}{v_{eff}}$$

$$t_3 = C_3 + \frac{x_3}{v_{eff}} + \frac{L}{c\beta}$$

$$t_4 = C_4 + \frac{x_3}{v_{eff}} + \frac{L}{c\beta}$$



$$t_{S1} = (t_1 + t_2) / 2$$

$$t_{S2} = (t_3 + t_4) / 2$$



$$\Delta T = t_{S2} - t_{S1} = a + b/\beta$$

Calibration constants

