# From Model-Agnostic Searches to Unfolding: Deep Learning in Particle Physics

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# Outline

- Model Agnostic New Physics search
- ▶ Detector Simulation Framework
- Unfolding

# New Physics?

- Copious amounts of data are generated at the LHC, making the discovery potential for new physics enormous .
- Despite thousands of searches for new physics at the LHC, all we have are limits and null results.

J. Kim, K. Kong, B. Nachman, D. Whiteson, 1907.06659





■ What if new physics is hiding in the data but we haven't looked in the right places yet?

# Model-Agnostic Searches

Nachman and Shih, 2001.04990

■ Can we search for new physics more model-independently and fill all the gaps in our coverage?



(a) Signal sensitivity

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# Model-Agnostic Searches

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**Direct Density** estimation, Sideband

signal model independence

 Can we search for new physics more model-independently and fill all the gaps in our coverage?



# Autoencoders (AEs) as Anomaly Detectors

 Autoencoders work by learning compression to a latent space which preserves the original information.



- The reconstruction fidelity gives an anomaly score.
- Variational AE has encoder, decoder architecture like AE. Encoder of VAE attempts to generate parameters of the parametric probability distribution in latent space. Typically, distribution is chosen to be gaussian.





# Unsupervised Anomaly Detection

Events

ATLAS-CONF-2023-022

- Not relying on specific signal hypothesis  $10^{-1}$ model independent search.
- Unsupervised anomaly detection trained on





# CWOLA Bump Hunt – Weak Supervision  $\frac{Mixed\ Sumber$   $\frac{Mixed\ Samp}{}$   $\frac{Mixed\ Samp}{}$   $\frac{Mixed\ Samp}{}$   $\frac{Mixed\ Sap}{}$

- Trained on two data samples with different signal fractions.
- Classifier is also optimal for distinguishing signal vs background because optimal classifier is the likelihood ratio.  $\int$



# CWoLA Bump Hunt – Weak Supervision

- Trained on two data samples with different signal fractions.
- Classifier is also optimal for distinguishing signal vs background because optimal classifier is the likelihood ratio.  $\int$  s
- Can also be used for a weakly supervised bump hunt:
	- Train a classifier between signal region and side bands
	- Apply a threshold cut on the classifier output and perform a bump hunt





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## [Collins et al: 1902.02634]

# LHC Run3

Annual CPU Consumption [MHS06years]

- At the end of LHC Run3, the computational needs will exceed the available budget.
- A large fraction goes into simulation.



CERN-LHCC-2020-015; LHCC-G-178

Figure 1: ATLAS CPU hours used by various activities in 2018



## Wall clock consumption per workflow

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Figure 1: ATLAS CPU hours used by various activities in 2018 CERN-LHCC-2020-015; LHCC-G-178





# Calls for Detector Simulation which

will be fast and faithful

## Wall clock consumption per workflow

# Deep Generative Models

## Sampling from Noise

Source distribution

Target distribution



Learns the distribution of data and generates new data from the distribution.

# Deep Generative Models

- Generative Adversarial Networks (GANs) are a way to make Sampling from Noise a generative model by having two neural networks compete with each other
- Generator: generates fake samples, tries to fool the Discriminator
- **Discriminator:** tries to distinguish between real and fake samples
- Train them against each other
- Repeat this and we get better Generator and Discriminator

Learns the distribution of data and generates new data from the distribution.





## GANs



https://research.nvidia.com/publication/2018-04\_progressivegrowing-gans-improved-quality-stability-and-variation

## GANs

https://research.nvidia.com/publication/2018-04\_progressivegrowing-gans-improved-quality-stability-and-variation and  $\frac{a}{\frac{a}{\xi}}$ ,





## GANs



https://research.nvidia.com/publication/2018-04 progressivegrowing-gans-improved-quality-stability-and-variation and a set of  $\frac{a}{\frac{a}{8}}$ .



 GANs have been demonstrated to be capable of reproducing Geant4 calorimeter images with reasonable accuracy (both at the individual image level and at the distributional level), while gaining up to 5 orders of magnitude in computational speed.

Plot from Claudius Krause's slide



# Normalizing Flows

 A transformation of a simple probability distribution into a more complex distribution by a sequence of invertible and differentiable mappings.



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**Probability Transformation in NFs** Learn  $f(x)$  to transform  $p_x(x)$  to  $p_z(z)$ 



https://mbrubake.github.io/cvpr2021-nf in cv-tutorial/Introduction%20-%20CVPR2021.pdf

# Volume correction  $p_X(x) = p_Z(f(x)) |\text{det}[(f(x))|$ Invertible, differentiable function

# Building Flows by Composition

- Invertible, differentiable functions are closed under composition.
- 



## CALOFLOW

## Flow I

earns  $p_1(E_0, E_1, E_2|E_{tot})$ 

## Flow II

learns  $p_2(\vec{x}|E_0, E_1, E_2, E_{tot})$  of normalized showers Claudius Krause and David Shih, 2106.05285



## CaloGAN: [1705.02355; 1712.10321]

## CALOFLOW

## Flow I

learns  $p_1(E_0, E_1, E_2|E_{tot})$ 

## Flow II

- **learns**  $p_2(\overrightarrow{\mathfrak{X}}|E_0,E_1,E_2,E_{tot})$  **of normalized showers**  $p_2(\overrightarrow{\mathfrak{X}}|E_0,E_1,E_2,E_{tot})$  **of normalized showers**  $p_2(\overrightarrow{\mathfrak{X}}|E_0,E_1,E_2,E_{tot})$ **PERIMENT ASSAURE 1.**  $E_1, E_2 | E_{tot}$ <br> **11**<br> **11**<br> **12**<br> **13**<br> **14**<br> **14**
- $\blacksquare$  in CALOFLOW v1:
	-
	- Impressive quality!



## CaloGAN: [1705.02355; 1712.10321]

## Claudius Krause and David Shih, 2106.05285





Average shower shapes for  $e^+$ . Columns are calorimeter layers 0 to 2<br>Claudius Krause and David Shih, 2106.05285



Claudius Krause and David Shih, 2106.05285

# Unfolding at the LHC



■ Classifier based approach

**• Density based approach** 

■ Classifier based approach<br>OmniFold [1911.09107], Profiled Unfolding [2302.05390]<br>■ Density based approach<br>FCGAN [1912.00477], cINN [2006.06685], IcINN [2212.08674], OTUS [2101.08944]

Measurements are affected by detector effects of finite resolution and limited acceptance.

1. Learn detector response from trustable simulation



3. Goal of unfolding is to  $\begin{bmatrix} \overline{a} \\ \overline{b} \\ \overline{c} \end{bmatrix}$ learn a generative particle-level model that reproduces the data

2. Truth-level measurements can be compared across experiments and to theoretical calculations

Andreassen, Komiske, Metodiev, Nachman, Thaler, 1911.09107

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## Weights  $w(x) =$  $q(x)/p(x)$  so that when dataset A is weighted by  $w$ , it is statistically identical to dataset B.



What if we don't (and can't easily) know  $q(x)$  and  $p(x)$ ?

Andreassen, Komiske, Metodiev, Nachman, Thaler, 1911.09107

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# What if we don't (and can't easily) know  $q(x)$  and  $p(x)$ ?  $q(x)/p(x)$ Detector-level<br>
Particle-level<br>
Truth<br>
CEANT, DELPHES PYTHIA, HERWIG, SHERPA<br>
GEANT, DELPHES PYTHIA, HERWIG, SHERPA<br>
Simulation<br>
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Ceneratio Dataset A with points<br>sampled from  $p(x)$   $\frac{1}{z}$ sampled from  $p(x)$ ATLAS, CMS Dataset B with points<br>sampled from  $q(x)$ sampled from  $q(x)$

Andreassen, Nachman, PRD RC 101 (2020) 091901

Weights  $w(x) =$  $q(x)/p(x)$  so that when dataset A is weighted by  $w$ , it is statistically identical to dataset B.

Use classification to train a neural network to distinguish the two datasets, NN learn to approximate the likelihood ratio

# OmniFold Equations

## Inputs

niFold Equations<br>
Inputs<br>
— pairs of Gen and Sim events<br>
— initial particle-level weights for Gen — Data  $\begin{array}{ccc}\n\text{min} \\
\text{limits} \\
\text{- pairs of Gen and Sim events} \\
\text{- initial particle-level weights for Gen-Data}\n\end{array}\n\qquad\n\begin{array}{ccc}\n\text{Dett} \\
\text{partial} \\
\$ 

1 million and Sim events<br>
1 million and Sim events<br>
1 million particle-level weights for Gen – Data<br>
1 million particle-level weights for Gen, n<sup>th</sup> iteration<br>
1 million particle-level weights for Sim, n<sup>th</sup> iteration<br>
1  $n$  lnputs<br>
– pairs of Gen and Sim events<br>
initial particle-level weights for Gen – Data<br>
particle-level weights for Gen, n<sup>th</sup> iteration<br>
– detector-level weights for Sim, n<sup>th</sup> iteration<br>
–  $\omega_n(m)$  – pulling  $\omega_n$  back

**Inputs**<br>
and Sim events<br>
e-level weights for Gen – Data<br>
I weights for Gen, n<sup>th</sup> iteration<br>
wel weights for Sim, n<sup>th</sup> iteration<br>
– pulling  $\omega_n$  back to particle-level<br>
- pushing  $\nu_n$  to detector-level **Inputs**<br>
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– pulling  $\omega_n$  back to particle-level<br>
– pushing  $\nu_n$  to detector-level<br> **OmniFo** 

 $n(M)=v_{n-1}$  (*III*)  $\times$  L (1, Data) push  $(m) \vee$   $\lceil$  (1 Dota)  $\lceil$  $n-1$ <sup>,  $\frac{\sin\left(\frac{\pi}{2}\right)}{\pi}$ </sup> push  $\lim_{m \to \infty}$   $\int$   $\lim_{m \to \infty}$  $\mathbf{v}_n(t) = \mathbf{v}_{n-1}(t) \times \mathbf{L}[\mathbf{w}_n]$ , Gen), ( $\mathbf{v}_{n-1}$ , Gen pull  $C_{\alpha n}$  (  $_{n-1}$ , Gen)]( $\iota$ )

Synthetic Simulation

1911.09107

Unfold any observable  $p_{Gen}(t)$  using universal weights  $v_n(t)$ 

unfolded  $\mathcal{V} = \mathcal{V}_n(\mathcal{V}) \wedge \mathcal{V}$ Gen $\mathcal{V}$ n)  $(t) = u(t) v_3$  $n(t) \times p_{Gen}(t)$ 



## OmniFold Andreassen, Komiske, Metodiev, Nachman, Thaler,



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Andreassen, Komiske, Metodiev, Nachman, Thaler, 1911.09107

# Summary/Outlook

■ There is a substantial ongoing work in model agnostic searches, and its exciting to see it starting to be used in experimental results.

[ATLAS: 2005.02983, ATLAS-CONF-2022-045, ATLAS-CONF-2023-022, CMS-DP-2022-021, CMS-DP-2022-043….]

- Techniques, like generative models, are paving the way for more efficient and realistic simulations, reducing computational costs and expanding the scope of theoretical investigations.
- Density estimation-based models like normalizing flows/diffusion models (that can efficiently map a simple distribution to a target one) are being used for detector simulation.

# Training Discriminator



## update discriminator weights

OmniFold - Schematic<br>• OmniFold weights particle-level Gen to be consistent with Data once passed through the OmniFold - Schematic<br>• OmniFold weights particle-level Gen to be consistent with Data once passed through the<br>Detector Detector-level Particle-level detector



Training Generator



# weights

# Real time Anomaly Detection



An event selected by an autoencoder-based anomaly detection hardware triggering algorithm in the CMS Experiment, [https://cds.cern.ch/record/2876546]



 $\triangleright$  Multijet background is hard to model – learn<br>a classifier directly from data using jet<br>substructure to make two samples and use iet a classifier directly from data using jet substructure to make two samples and use jet Multijet background is hard to model – learn<br>a classifier directly from data using jet<br>substructure to make two samples and use jet<br>kinematics to train the CWoLa classifier

Phys. Lett. B 803 (2020) 135285

# Other Unsupervised Bump Hunts

- ANODE: interpolates probability densities from sidebands to the signal-region & constructs likelihood ratio [Nachman, Shih: 2001.04990] Jther Unsupervised Bump Hunts<br>ANODE: interpolates probability densities from sidebands to the signal-re<br>likelihood ratio [Nachman, Shih: 2001.04990]<br>CATHODE: samples from the background model in signal region after inte<br>es
- CATHODE: samples from the background model in signal region after interpolating and likelihood ratio [Nachman, Shih: 2001.04990]<br>
CATHODE: samples from the background model in signal region after interpolating and<br>
estimates likelihood ratio with classifier [Hallin et al: 2109.00546]<br>
SALAD: Reweight simu
- SALAD: Reweight simulation to match sidebands, then interpolate into the signal region and
- **CURTAINS:** Train an invertible neural network conditioned on mass to map between sidebands [Raine et al: 2203.09470] FETA: Reweight simulation to match sidebands, then interpolate into the signal region and<br>use a second classifier to get the likelihood ratio [Andreassen et al: 2001.05001]<br>FETA: Train an invertible neural network conditio
- 2212.11285]