# From Model-Agnostic Searches to Unfolding: Deep Learning in Particle Physics

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## Outline

- Model Agnostic New Physics search
- Detector Simulation Framework
- Unfolding

## New Physics?

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- Copious amounts of data are generated at the LHC, making the discovery potential for new physics enormous.
- Despite thousands of searches for new physics at the LHC, all we have are limits and null results.

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What if new physics is hiding in the data but we haven't looked in the right places yet? 

J. Kim, K. Kong, B. Nachman, D. Whiteson, 1907.06659



## Model-Agnostic Searches

Can we search for new physics more model-independently and fill all the gaps in our coverage?



(a) Signal sensitivity

Nachman and Shih, 2001.04990

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**Direct Density** estimation, Sideband

signal model independence

## Autoencoders (AEs) as Anomaly Detectors

Autoencoders work by learning compression to a latent space which preserves the original information.





- The reconstruction fidelity gives an anomaly score.
- Variational AE has encoder, decoder architecture like AE. Encoder of VAE attempts to generate parameters of the parametric probability distribution in latent space. Typically, distribution is chosen to be gaussian.



https://towardsdatascience.com/

## Unsupervised Anomaly Detection

Events



- Not relying on specific signal hypothesis model independent search.
- Unsupervised anomaly detection trained on data — no MC modelling dependence



ATLAS-CONF-2023-022

## CWoLA Bump Hunt – Weak Supervision

- Trained on two data samples with different signal fractions.
- Classifier is also optimal for distinguishing signal vs background because optimal classifier is the likelihood ratio.



## CWoLA Bump Hunt – Weak Supervision

- Trained on two data samples with different signal fractions.
- Classifier is also optimal for distinguishing signal vs background because optimal classifier is the likelihood ratio.
- Can also be used for a weakly supervised bump hunt:
  - Train a classifier between signal region and side bands
  - Apply a threshold cut on the classifier output and perform a bump hunt





(S)

**(B)** 

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### CWoLa hunting in the dijet final state [Collins et al: 1902.02634]

## LHC Run3

Annual CPU Consumption [MHS06years]

- At the end of LHC Run3, the computational needs will exceed the available budget.
- A large fraction goes into simulation.





CERN-LHCC-2020-015; LHCC-G-178

### Wall clock consumption per workflow

Figure 1: ATLAS CPU hours used by various activities in 2018

## LHC Run3

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Figure 1: ATLAS CPU hours used by various activities in 2018 CERN-LHCC-2020-015; LHCC-G-178

will be fast and faithful

### Wall clock consumption per workflow

# Calls for Detector Simulation which

### Deep Generative Models

Learns the distribution of data and generates new data from the distribution.

### Sampling from Noise



## Deep Generative Models

Learns the distribution of data and generates new data from the distribution.

- Generative Adversarial Networks (GANs) are a way to make a generative model by having two neural networks compete with each other
- Generator: generates fake samples, tries to fool the Discriminator
- Discriminator: tries to distinguish between real and fake samples
- Train them against each other
- Repeat this and we get better Generator and Discriminator



### Sampling from Noise



### - Goodfellow et. al., "Generative Adversarial Networks" (2014)

### GANs



https://research.nvidia.com/publication/2018-04\_progressivegrowing-gans-improved-quality-stability-and-variation

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GANs have been demonstrated to be capable of reproducing Geant4 calorimeter images with reasonable accuracy (both at the individual image level and at the distributional level), while gaining up to 5 orders of magnitude in computational speed.





Plot from Claudius Krause's slide

## Normalizing Flows

A transformation of a simple probability distribution into a more complex distribution by a sequence of invertible and differentiable mappings.



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**Probability Transformation in NFs** 

Learn f(x) to transform  $p_X(x)$  to  $p_Z(z)$ 

$$p_{\mathbf{X}}(\mathbf{x}) \qquad \qquad p_{\mathbf{Z}}(\mathbf{z})$$

https://mbrubake.github.io/cvpr2021-nf in cv-tutorial/Introduction%20-%20CVPR2021.pdf

## Volume correction $p_X(x) = p_Z(f(x)) |\det J(f(x))|$ Invertible, differentiable function

## Building Flows by Composition

- Invertible, differentiable functions are closed under composition.



### CALOFLOW

### Flow I

• learns  $p_1(E_0, E_1, E_2 | E_{tot})$ 

### Flow II

learns  $p_2(\vec{\mathfrak{T}}|E_0, E_1, E_2, E_{tot})$  of normalized showers Claudius Krause and David Shih, 2106.05285



### CaloGAN: [1705.02355; 1712.10321]

### CALOFLOW

### Flow I

learns  $p_1(E_0, E_1, E_2 | E_{tot})$ 

### Flow II

- learns  $p_2(\vec{\mathfrak{T}}|E_0, E_1, E_2, E_{tot})$  of normalized showers
- in CALOFLOW v1:
  - Slow in sampling ( $\approx$  500× slower than CALOGAN) •
  - Impressive quality! ullet





### Claudius Krause and David Shih, 2106.05285



Average shower shapes for  $e^+$ . Columns are calorimeter layers 0 to 2 Claudius Krause and David Shih, 2106.05285



Claudius Krause and David Shih, 2106.05285

## Unfolding at the LHC



Classifier based approach 

OmniFold [1911.09107], Profiled Unfolding [2302.05390]

Density based approach 

FCGAN [1912.00477], cINN [2006.06685], IcINN [2212.08674], OTUS [2101.08944]

## Unfolding Setup

Measurements are affected by detector effects of finite resolution and limited acceptance.

3. Goal of unfolding is to learn a generative particle-level model that reproduces the data



1. Learn detector response from trustable simulation

Andreassen, Komiske, Metodiev, Nachman, Thaler, 1911.09107

2. Truth-level measurements can be compared across experiments and to theoretical calculations

## Unfolding Setup



Andreassen, Komiske, Metodiev, Nachman, Thaler, 1911.09107

### Weights w(x) = q(x)/p(x) so that when dataset A is weighted by w, it is statistically identical to dataset B.

## Unfolding Setup

• What if we don't (and can't easily) know q(x) and p(x)?



Andreassen, Komiske, Metodiev, Nachman, Thaler, 1911.09107

### Weights w(x) =q(x)/p(x) so that when dataset A is weighted by w, it is statistically identical to dataset B.

### What if we don't (and can't easily) know q(x) and p(x)? **Detector-level** Particle-level Data Truth Natural Dataset A with points sampled from p(x)ATLAS, CMS **GEANT, DELPHES** PYTHIA, HERWIG, SHERPA Synthetic Simulation Generation Dataset B with points sampled from q(x)

Andreassen, Nachman, PRD RC 101 (2020) 091901

## Unfolding Setup

Use classification to train a neural network to distinguish the two datasets, NN learn to approximate the likelihood ratio q(x)/p(x)

> Weights  $\mathbf{w}(\mathbf{x}) =$ q(x)/p(x) so that when dataset A is weighted by *w*, it is statistically identical to dataset B.

## **OmniFold Equations**

### Inputs

(t, m) – pairs of Gen and Sim events  $v_0(t)$  – initial particle-level weights for Gen – Data

 $v_n(t)$  – particle-level weights for Gen, n<sup>th</sup> iteration  $\omega_n(m)$  – detector-level weights for Sim, n<sup>th</sup> iteration

 $\omega_n^{pull}(t) = \omega_n(m) - \text{pulling } \omega_n \text{ back to particle-level}$  $\nu_n^{push}(m) = \nu_n(t) - \text{pushing } \nu_n \text{ to detector-level}$ 

### **OmniFold**

Step 1 - 
$$\omega_n(m) = \nu_{n-1}^{\text{push}}(m) \times L\left[(1, \text{Data}), \left(\nu_{n-1}^{\text{push}}, \text{Sim}\right)\right](m)$$
  
Step 2 -  $\nu_n(t) = \nu_{n-1}(t) \times L\left[\left(\omega_n^{\text{pull}}, \text{Gen}\right), \left(\nu_{n-1}, \text{Gen}\right)\right](t)$ 



Andreassen, Komiske 1911.09107

Unfold any observable  $p_{Gen}(t)$  using universal weights  $v_n(t)$ 

 $p_{\text{unfolded}}^{(n)}(t) = v_n(t) \times p_{\text{Gen}}(t)$ 

Andreassen, Komiske, Metodiev, Nachman, Thaler,

### **OmniFolding Jet Substructure Observables**



Andreassen, Komiske, Metodiev, Nachman, Thaler, 1911.09107

## Summary/Outlook

There is a substantial ongoing work in model agnostic searches, and its exciting to see it starting to be used in experimental results.

[ATLAS: 2005.02983, ATLAS-CONF-2022-045, ATLAS-CONF-2023-022, CMS-DP-2022-021, CMS-DP-2022-043....]

- Techniques, like generative models, are paving the way for more efficient and realistic simulations, reducing computational costs and expanding the scope of theoretical investigations.
- Density estimation-based models like normalizing flows/diffusion models (that can efficiently map a simple distribution to a target one) are being used for detector simulation.

### Training Discriminator



### update discriminator weights

## OmniFold - Schematic

OmniFold weights particle-level Gen to be consistent with Data once passed through the detector



Training Generator



# weights

## Real time Anomaly Detection

![](_page_36_Picture_1.jpeg)

An event selected by an autoencoder-based anomaly detection hardware triggering algorithm in the CMS Experiment, [https://cds.cern.ch/record/2876546]

### CWoLa in action: tt+bb

![](_page_37_Figure_1.jpeg)

Multijet background is hard to model – learn a classifier directly from data using jet substructure to make two samples and use jet kinematics to train the CWoLa classifier

Phys. Lett. B 803 (2020) 135285

### Other Unsupervised Bump Hunts

- **ANODE**: interpolates probability densities from sidebands to the signal-region & constructs likelihood ratio [Nachman, Shih: 2001.04990]
- **CATHODE**: samples from the background model in signal region after interpolating and estimates likelihood ratio with classifier [Hallin et al: 2109.00546]
- SALAD: Reweight simulation to match sidebands, then interpolate into the signal region and use a second classifier to get the likelihood ratio [Andreassen et al: 2001.05001]
- **CURTAINS**: Train an invertible neural network conditioned on mass to map between sidebands [Raine et al: 2203.09470]
- **FETA**: Map simulation to data in sidebands, then compare to SR data [Golling et al: 2212.11285]