



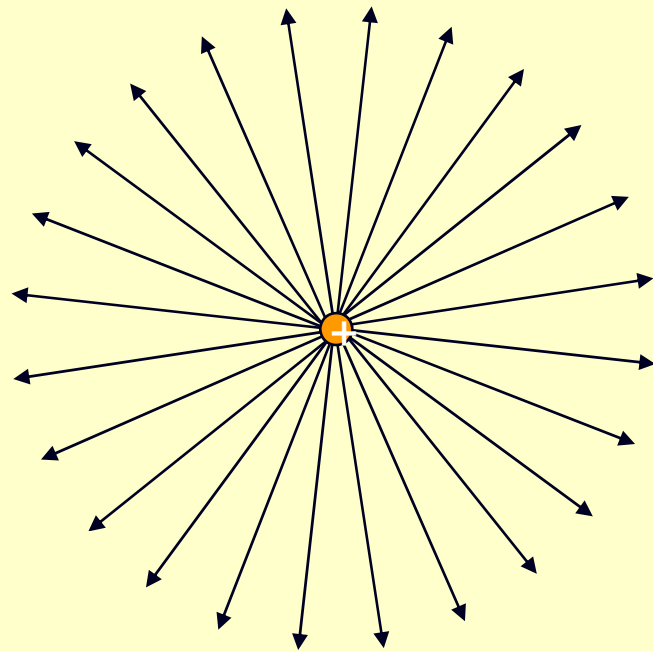
# BPM design

- Introduction
- BPM types
- Bench measurements
- Other requirements
- Conclusion



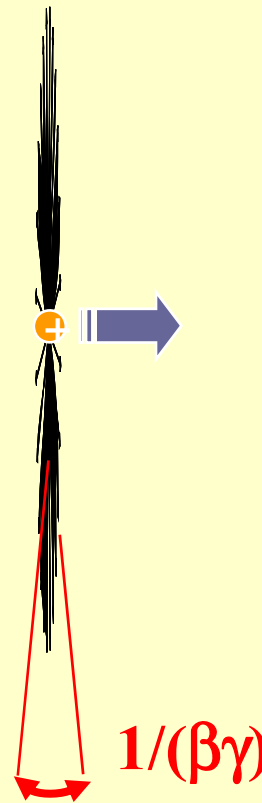
# Introduction

E-Field



Static Point Charge

TEM Wave



Relativistic Point Charge

$$q(r, \phi_w) := \frac{b - r^2}{b + r^2 - 2 \cdot b \cdot r \cdot \cos(\phi_w - \chi)}$$

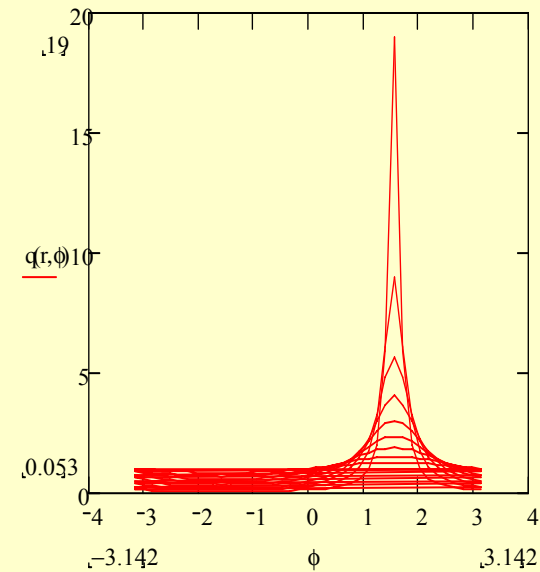


Image current distribution



# Different BPM types

Electrostatic

Button

Electromagnetic coupler

Resistive

Inductive

Cavity

Re-entrant cavity



Image current

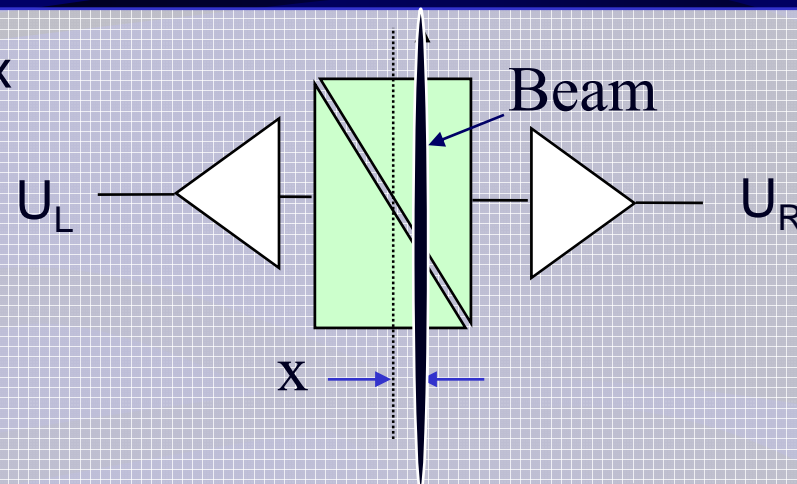
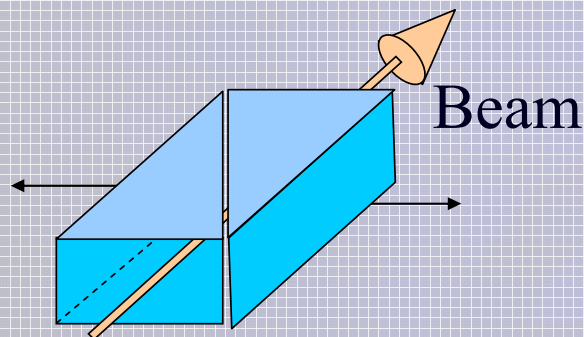
HOM

HF electron beams



# Electrostatic shoebox BPM

Linear cut through a shoebox



Linear Response across  
the aperture

$$X \propto \frac{U_L - U_R}{U_L + U_R} = \frac{\Delta}{\Sigma}$$

Induced charges carried away by low-impedance circuit or sensed on a high impedance as a voltage

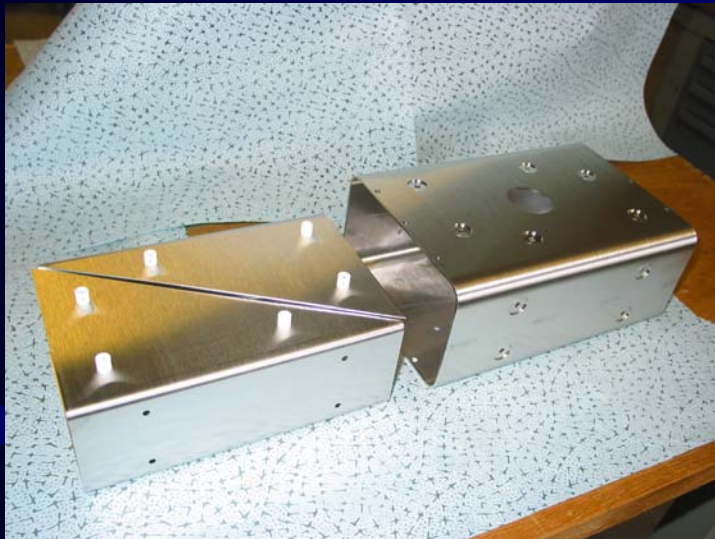
$$V = \frac{\phi_{elec} \cdot I_{elec}}{2 \cdot \pi \cdot C_{elec}} \cdot \frac{I_B(t)}{\beta \cdot c}$$

- ✓ Linear within  $\frac{3}{4}$  of half aperture
- ✓ Low frequency cutoff (kHz) with high RL
- ✗ Sensitive to spray particles
- ✗ Complicated design  $\Rightarrow$  high cost

$$C_{elec} = \frac{\epsilon_0 \cdot \epsilon_r \cdot A}{d}$$



# Electrostatic BPM



Same principle applied to a cylindrical pick-up

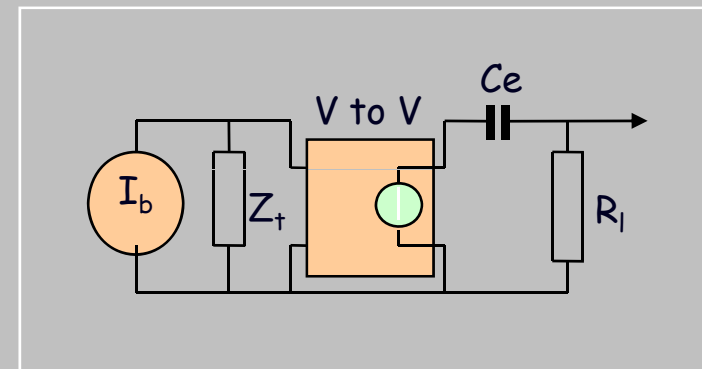
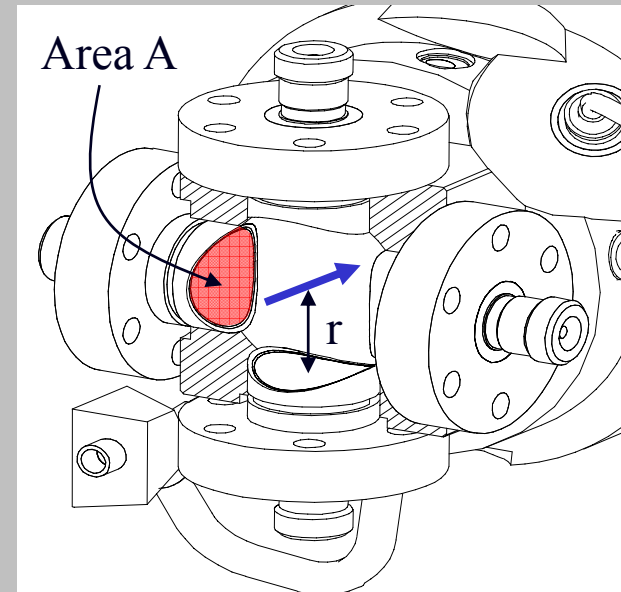
- The cuts can be made by photo-chemical, sand-blasting or other mechanical means.  
→ Here done by photo-chemical process



# Button BPM

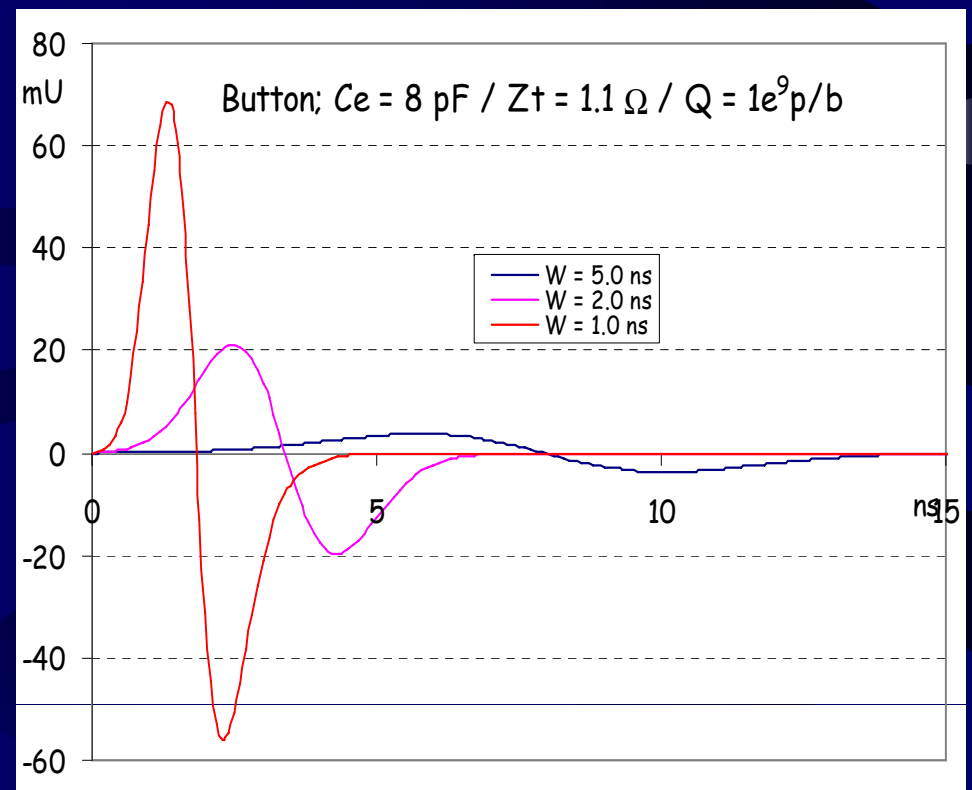
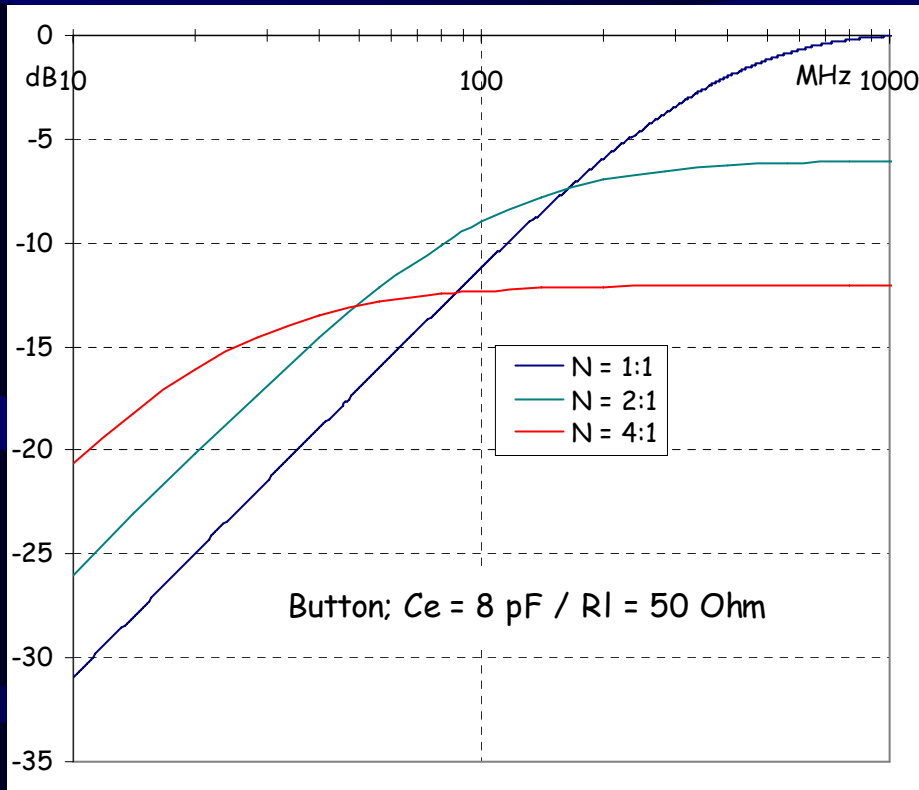
- ✓ Lowest longitudinal impedance
- ✓ Low cost  $\Rightarrow$  most popular
- ✗ Non-linear
  - requires correction algorithm when beam is off-centre
- ✗ Low frequency cut-off
  - $T = R_1 C_e$  (few hundreds MHz)
  - $R_L = 50 \text{ ohm}$ ,  $C$  very small

$$V = \frac{A_{elec} \cdot R_L}{2 \cdot \pi \cdot r \cdot \beta \cdot c} \cdot \frac{dI_B(t)}{dt}$$





# Button Frequency & Time Response



- **Frequency domain:**

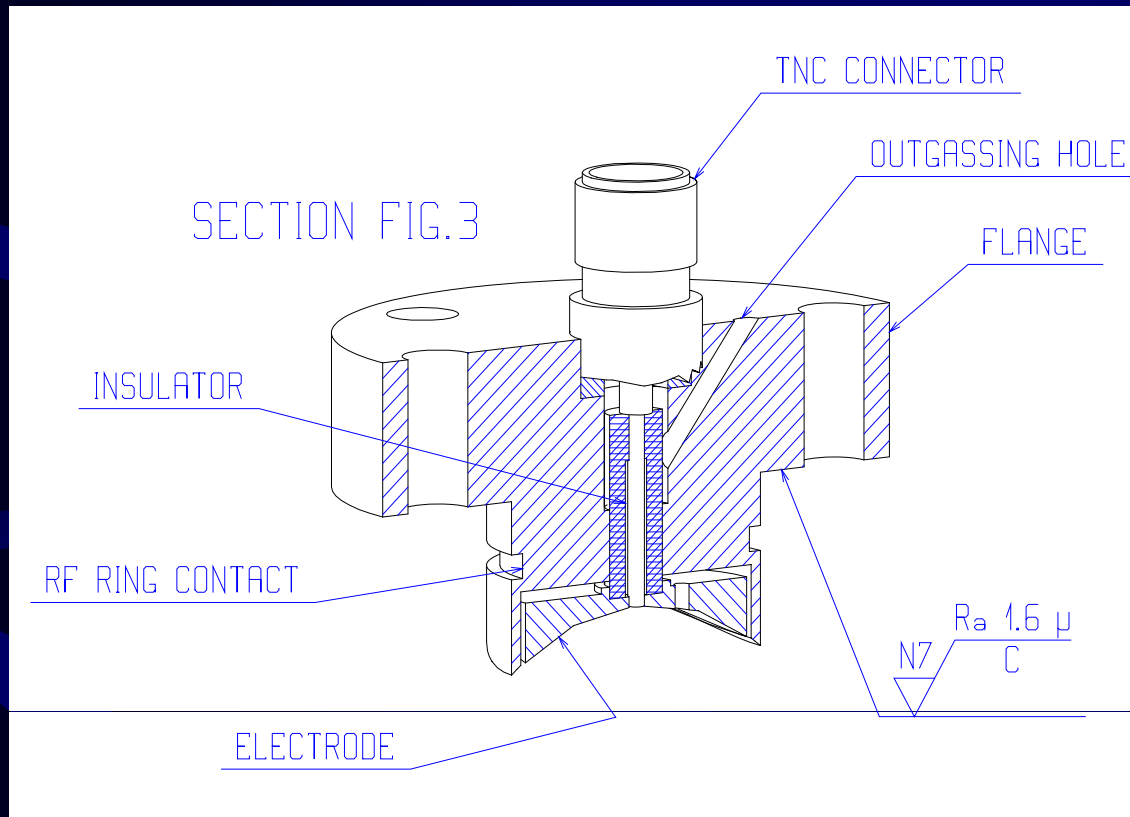
- Impedance transformers improve the low frequency levels at the expense of the high frequency

- **Time domain:**

- Differentiated pulse
- Exponential dependence of amplitude on bunch length



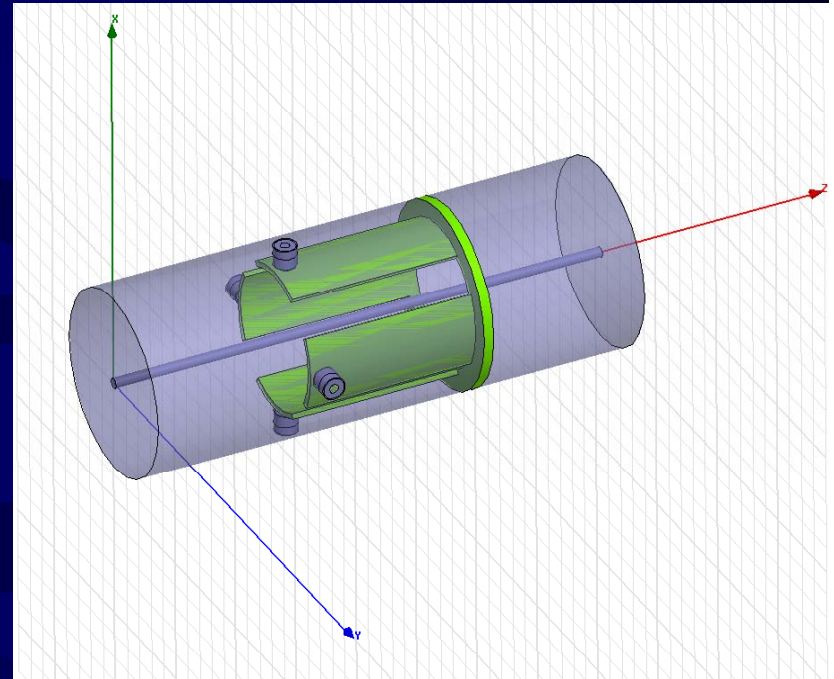
# What does a real (LHC) electrostatic button monitor look like?





# Electromagnetic (Directional) coupler

- Four 50Ω lines.
- Directional if terminated in both ends
- ✓ Linear if optimized ( $\phi_{elec} \approx 60^\circ$ )
- ✗ Higher cost but shorted version is a possible cheaper option.
- ✗ Narrow band device.

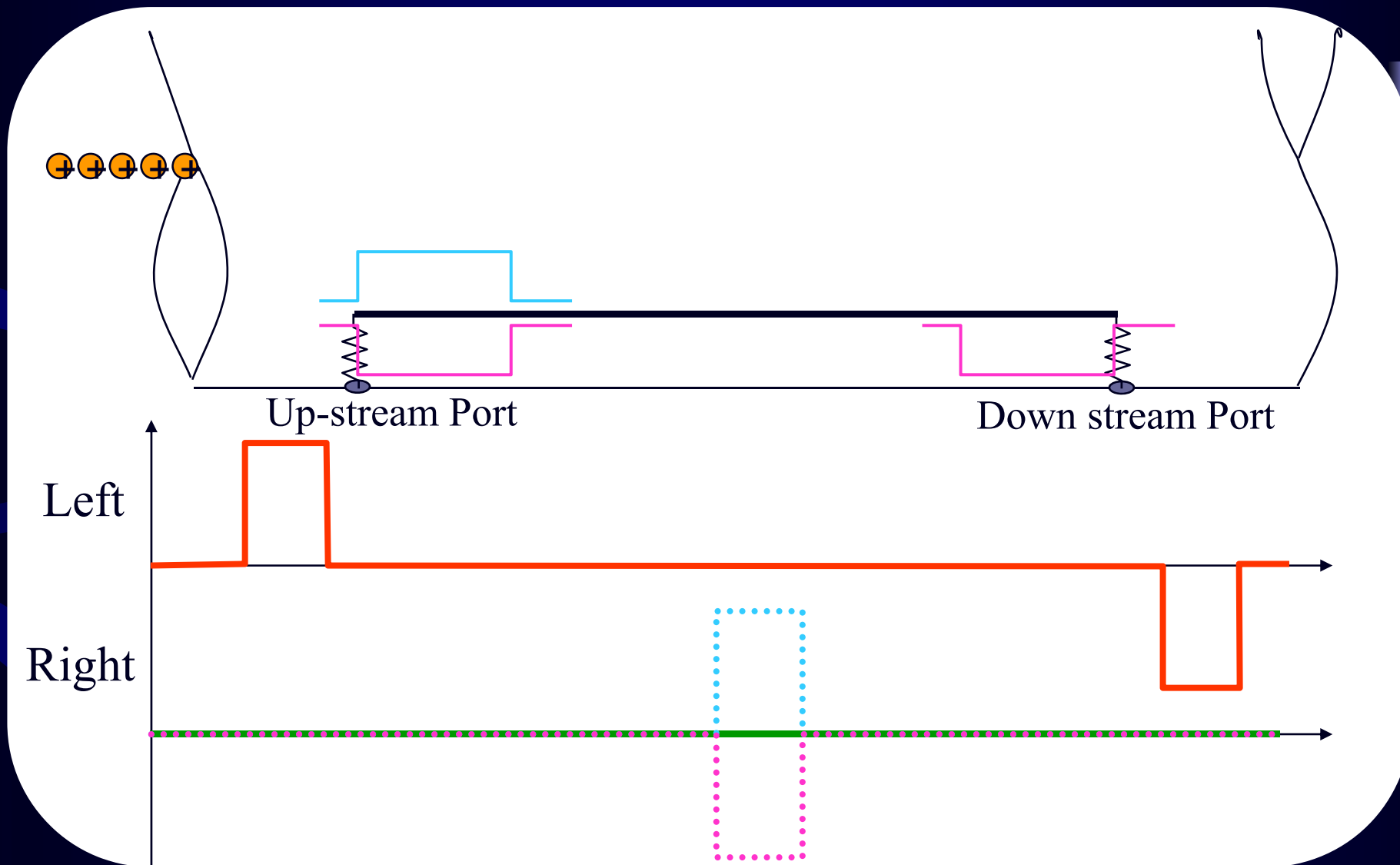


$$V_U = \frac{\phi_{elec} \cdot Z_0}{4 \cdot \pi} \cdot \left[ I_B(t) - I_B\left(t - \frac{l}{\beta_b \cdot c} - \frac{l}{\beta_s \cdot c}\right) \right]$$

$$V_U = \frac{\phi_{elec} \cdot Z_0}{4 \cdot \pi} \cdot \left[ I_B(t) - I_B\left(t - \frac{2 \cdot l}{c}\right) \right]$$



# EM Stripline Coupler – right travelling beam



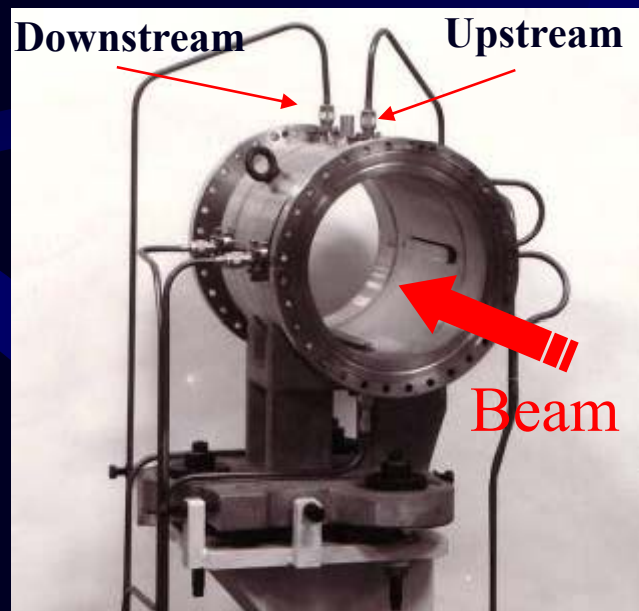
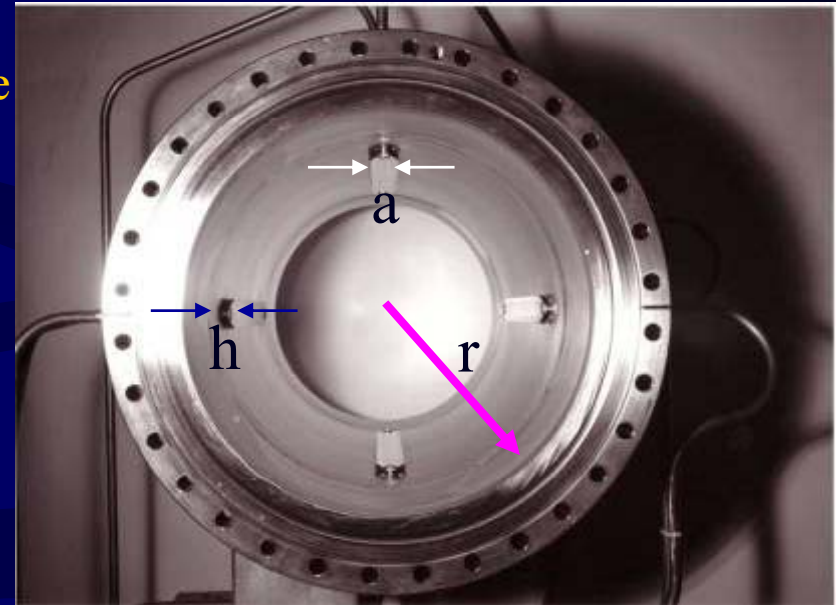


# Electromagnetic (Directional) coupler

- Is a transmission line (strip line) which couples to the transverse electromagnetic (TEM) beam field

$$Z_{t\infty} = 60 \ln[(r+h)/r] \equiv Z_0 * [a/2\pi(r+h)]$$

- $Z_0$  is the characteristic impedance
- $a, r, h, l$  are the mechanical dimensions
- $t = l/c$  is the propagation time in the coupler

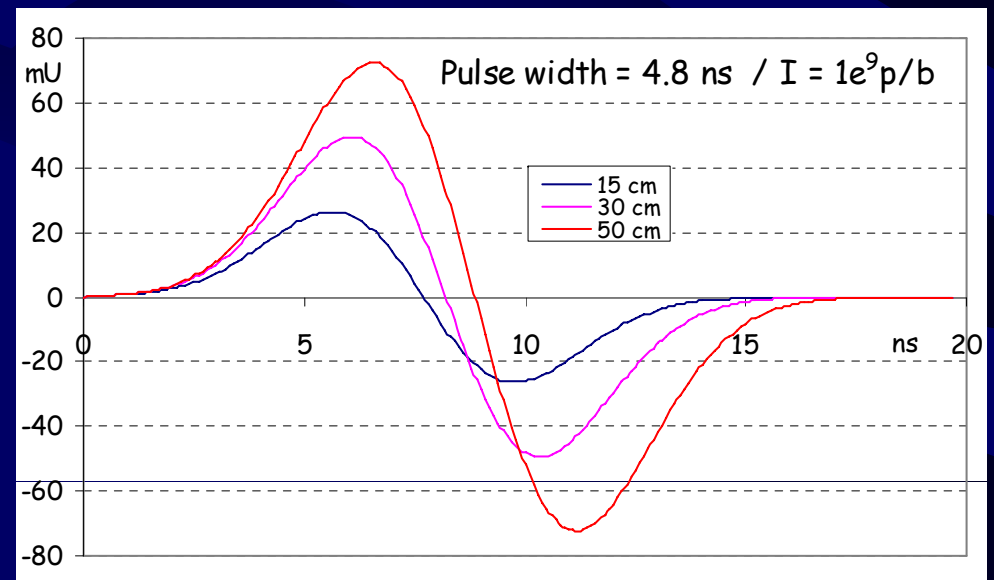
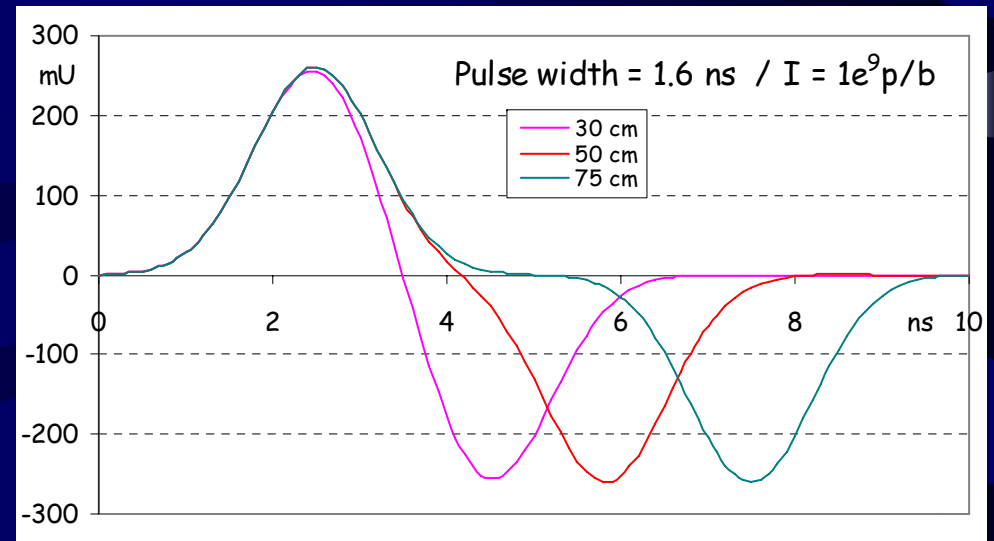
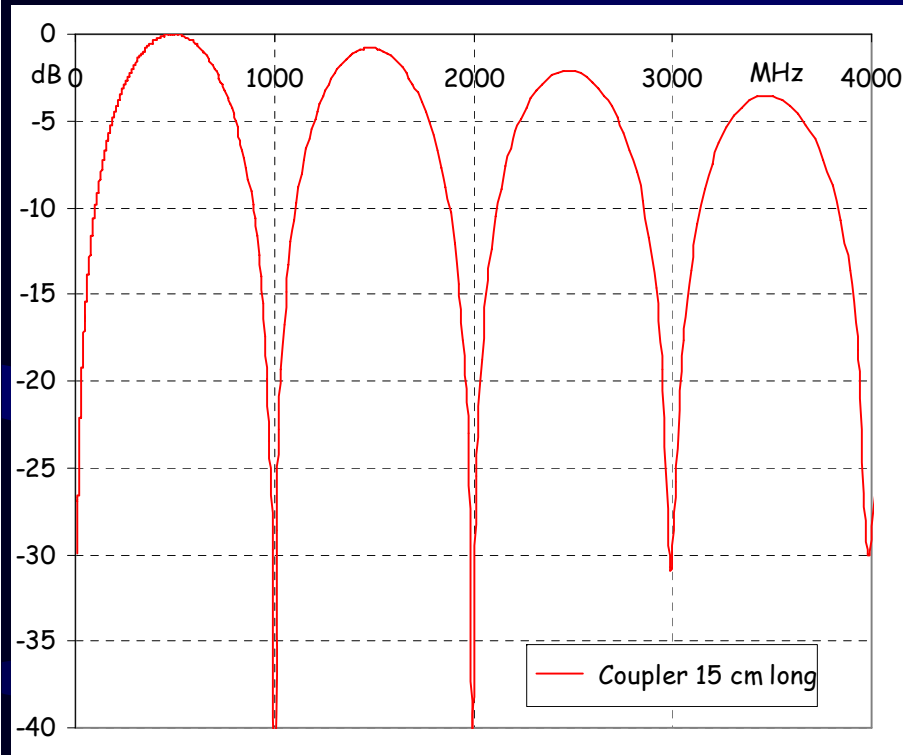


- **Two termination ports**
  - Upstream: usually used to acquire signal.
    - Same signal seen whether Downstream port is open, shorted or terminated by  $Z_0$
  - Downstream: 2 cases
    - Upstream terminated by  $Z_0 \Rightarrow$  no signal
    - Upstream short circuit  $\Rightarrow$  delayed & inverted signal

**Directivity!**



# Coupler frequency & time response



- Sinusoidal amplitude response

- Maximum signal for  $f = 1/4 * t$

- Zero signal for  $f = 1/2 * t$

- Time domain:

- Bipolar pulse

19/04-2007



# Resistive BPM (WCM)

$$q(r, \phi) := \frac{1 - r^2}{1 + r^2 - 2 \cdot r \cdot \cos(\phi - \chi)}$$
$$X \propto \frac{U_L - U_R}{U_L + U_R} = \frac{\Delta}{\Sigma}$$

- A voltage proportional to the beam current and the beam position develops on the **RESISTORS** in the beam pipe gap
- The gap must be closed by a box to avoid floating sections of the beam pipe
- The box is filled with the **FERRITE** to force the image current to go over the resistors



# A Beam Position Sensitive WCM



- A position sensitive WCM is still used in the CERN PS.
- It contains 96 resistors of  $10\ \Omega$  in 32 groups of 3 in series),  $V_{\Sigma}/I_B \approx 1\ \Omega$ .
- Position measurement bandwidth is 9 MHz – 1.5 GHz (2.2 decade)
- Current measurement bandwidth is 3 MHz – 1.5 GHz (2.7 decade)

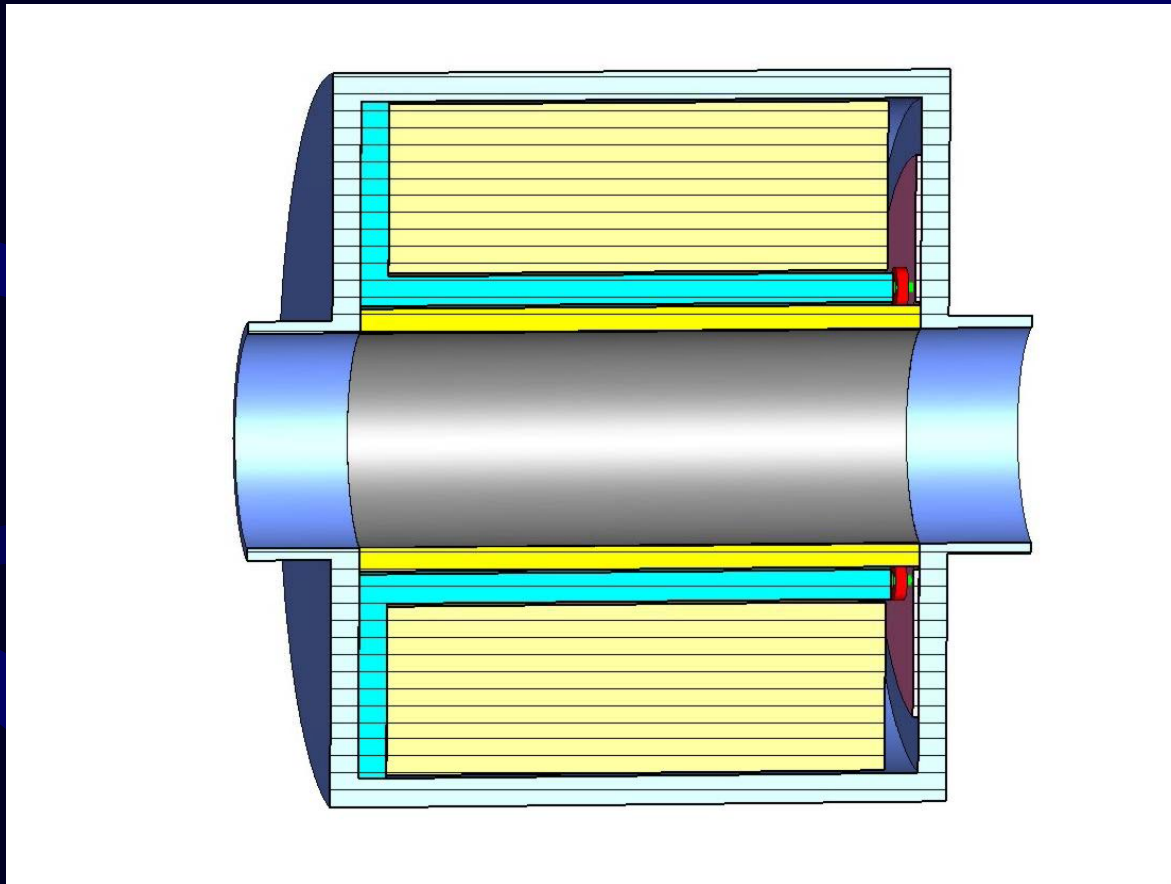
*G.C. Schneider, A 1.5 GHz Wide-Band Beam Position and Intensity Monitor for the Electron-Positron Accumulator (EPA), CERN/PS 87-9 (BT), 1987*



# Inductive Pick-Up

**MORE INDUCTANCE**

**LESS RESISTANCE**



- Four or eight electrodes, which covers up to 75 % of the circumference. **No feed-thru's**
- The small electrode diameter step is occupied by a titanium coated ceramic tube. **Low longitudinal impedance**
- Small current transformers guides the image currents to an external load.
- The current transformers (mounted on a PCB) are as small as possible to gain high frequency cut-off with many turns
- The connection between the electrodes and the cover is made by screws.

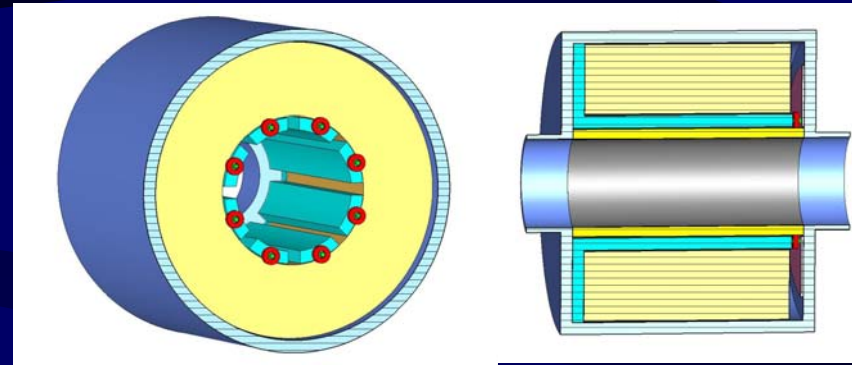
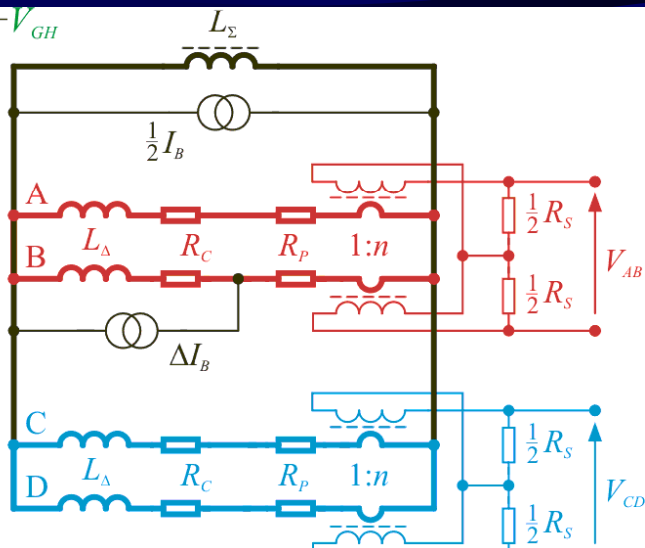
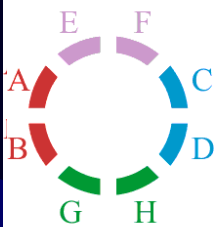


# IPU – A Low Frequency Model

$$V_{\Sigma} = V_{AB} + V_{CD} + V_{EF} + V_{GH}$$

$$V_{\Delta H} = V_{AB} - V_{CD}$$

$$V_{\Delta V} = V_{EF} - V_{GH}$$



$$R_P = \frac{R_S}{2n^2}$$

- Electrodes are combined in pairs so that each transformer sees half of the load
- Frequency low cut-offs are limited by connection parasitic resistances
- Each transformer has one calibration turn (not shown)

$$R_T = \frac{V_{\Sigma}}{I_B} = \frac{R_S}{2n}$$

$n=30$ ,  $R_S \cong 7 \Omega$  giving  $R_T \cong 0.1 \Omega$  and  $R_P \cong 4 \text{ m}\Omega$

$f_{L\Sigma} \cong 150 \text{ Hz}$  ( $R_P$  with  $L_{\Sigma} \cong 5 \mu\text{H}$ )

$f_{L\Delta} \cong 10 \text{ kHz}$  ( $R_P$  with  $L_{\Delta} \cong 70 \text{ nH}$ )

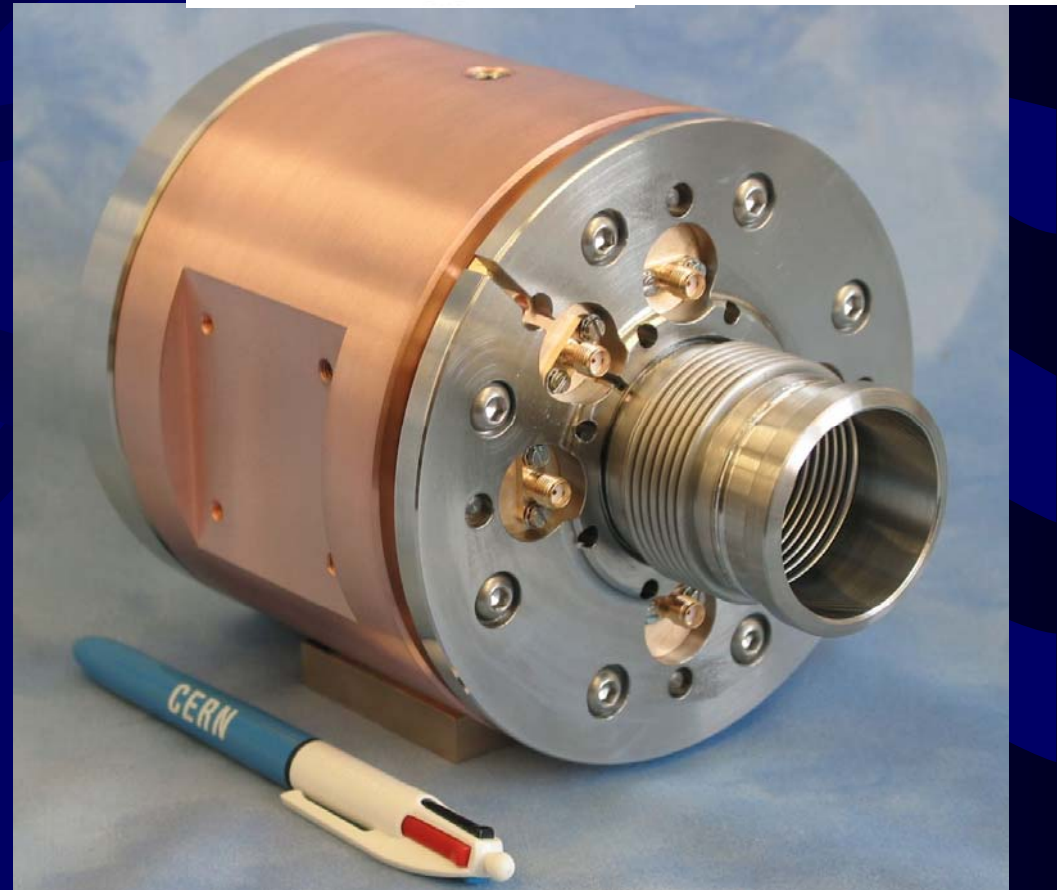
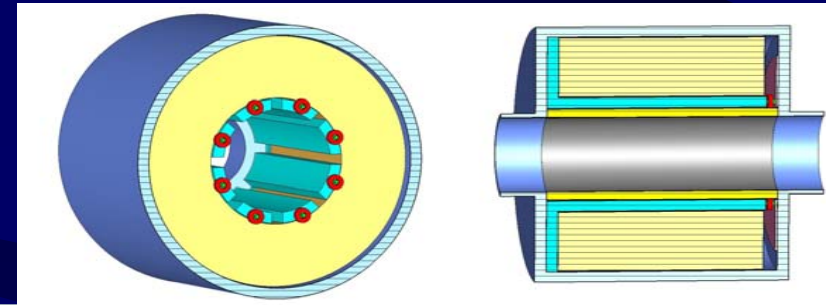
The electrode signal high cut-off frequency is beyond 300 MHz

$$f_{L\Sigma} = \frac{1}{2\pi L_{\Sigma}} \left( \frac{R_S}{2n^2} + R_C \right)$$

$$f_{L\Delta} = \frac{1}{2\pi L_{\Delta}} \left( \frac{R_S}{2n^2} + R_C \right)$$



# Inductive Pick



- The ceramic tube is coated with low resistance titanium layer, resistance: end-to-end  $\approx 10 \Omega$ , i.e.  $\approx 15 \Omega/\text{square}$
- Primary circuit has to have small parasitic resistances (Cu pieces, CuBe screws, gold plating)
- Tight design, potential cavities damped with the ferrite



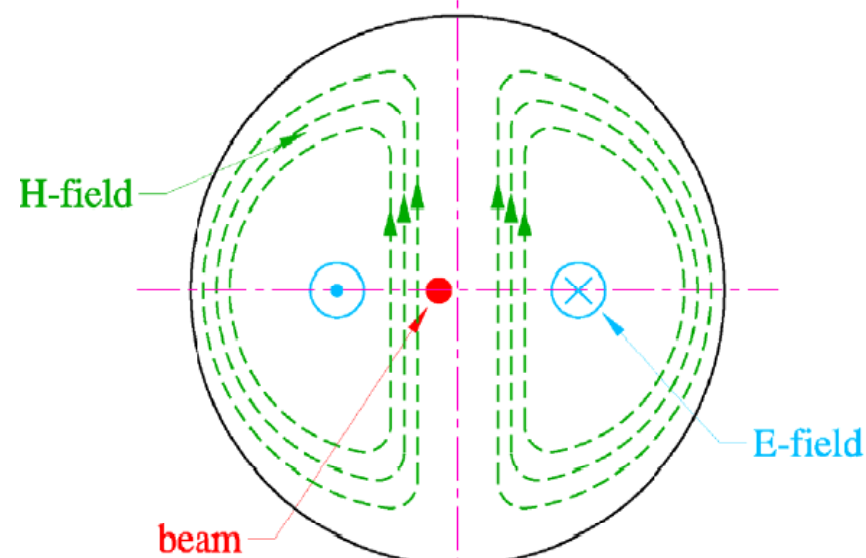
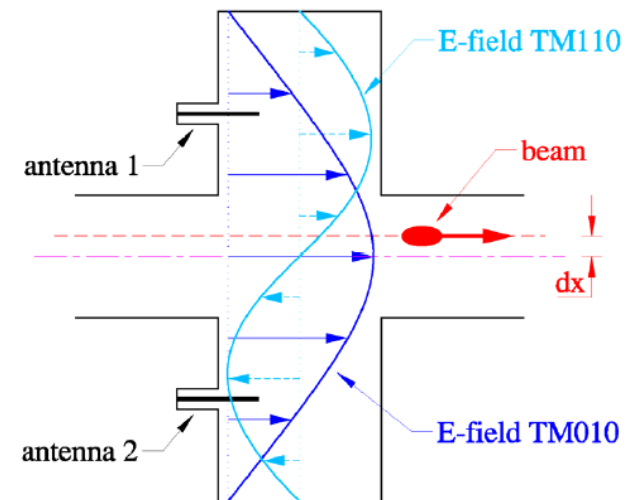
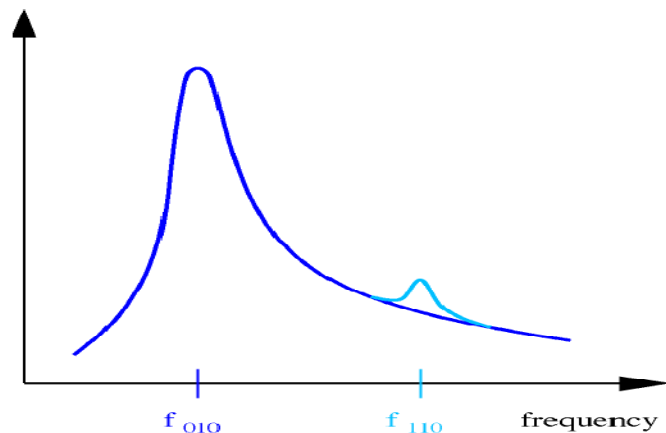
# Cavity BPM

- ✚ Difference of large numbers problem reduced to rejection of the primary fundamental peak. Frequency domain.
- ✚ Damping time quite high due to intrinsic high Q.

$$\tau = \frac{Q_{ld}}{\pi * f_{Dip}}$$

→ Poor time resolution (~100ns)

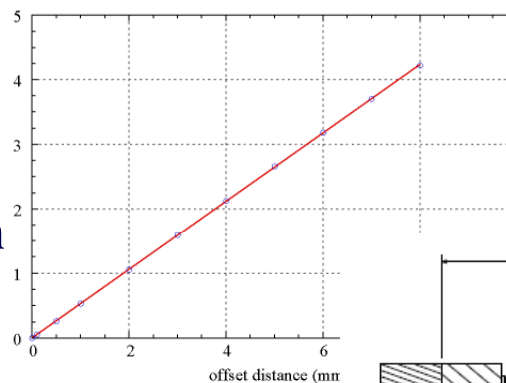
- ✚ Need of extra cavities for orthogonal plane and normalization.
- ✚ Sub-micron resolution.



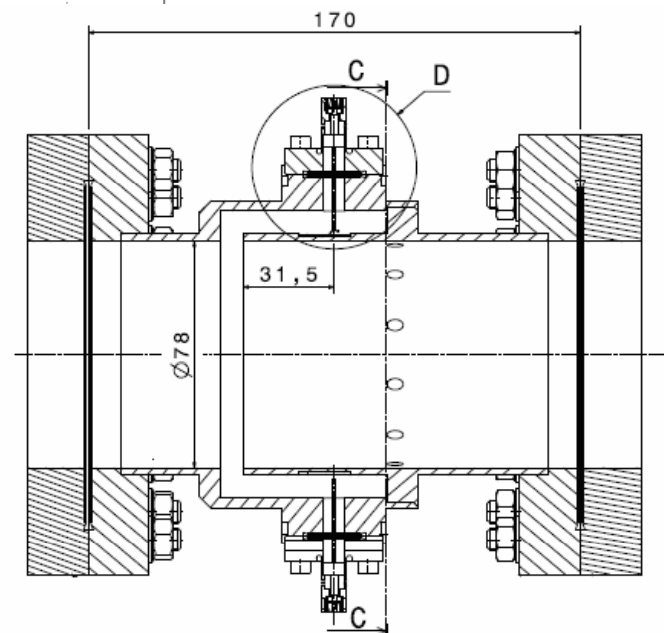


# Re-entrant cavity BPM

- ✚ Re-entrant geometry for a higher frequency separation between the monopole and dipole modes. → [Better CMRR](#)
- ✚ Resolution: CARE ~ 1 $\mu$ m (CALIFES ~5 $\mu$ m)
- ✚ Dynamic range: 5mm
- ✚  $Q_{ld} = 50 \rightarrow$   
Time resolution ~ 10ns
- ✚ ID 78mm; Length ~170mm

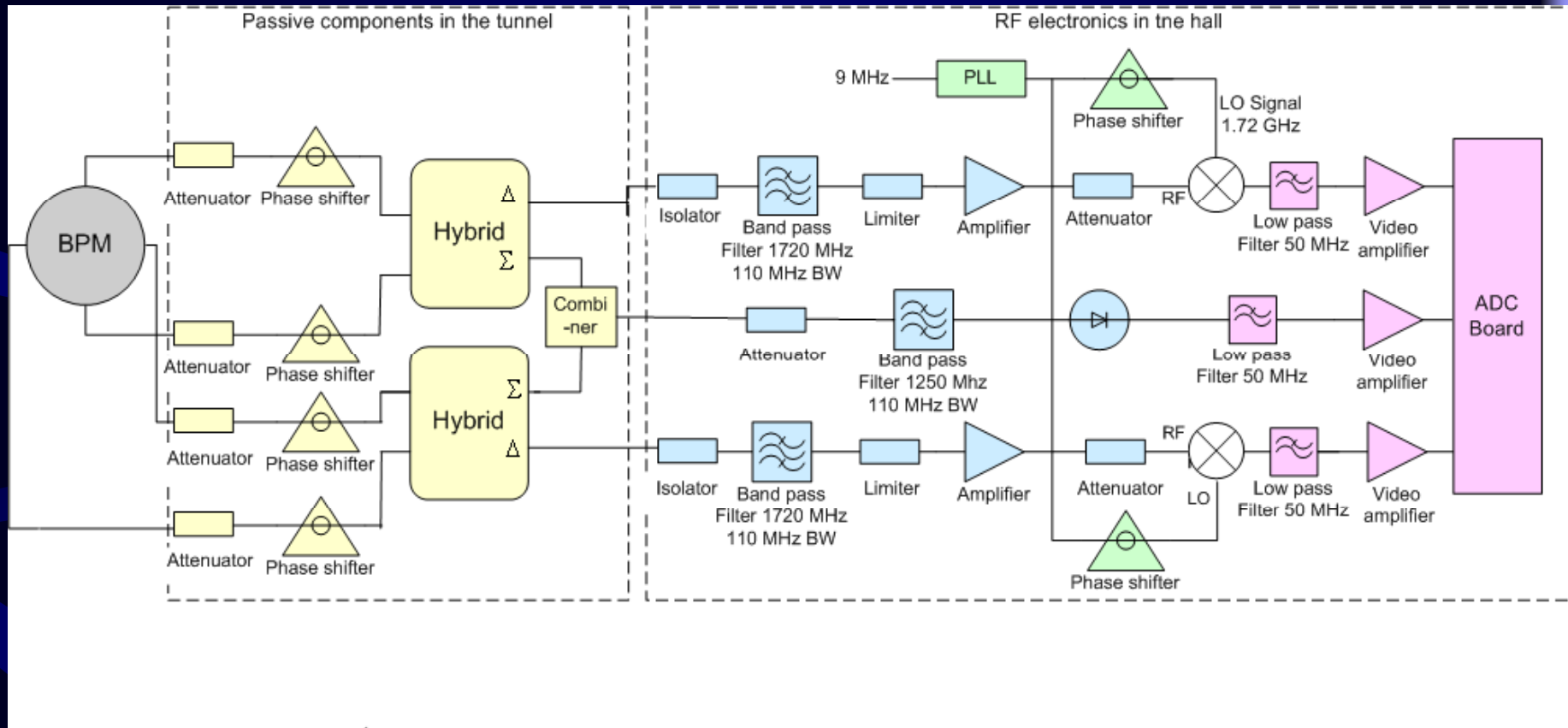


Eigen modes	F (MHz)			Q <sub>1</sub>			(R/Q) <sub>1</sub> ( $\Omega$ ) at 5 mm	(R/Q) <sub>1</sub> ( $\Omega$ ) at 10 mm
	HFSS	Meas. in lab.	Meas. in tunnel	HFSS	Meas. in lab.	Meas. in tunnel	Calc.	Calc.
Monop. mode	1250	1254	1255	22.95	22.74	23.8	12.9	12.9
Dipole mode	1719	1725	1724	50.96	48.13	59	0.27	1.15





# Re-entrant cavity BPM electronics





# Bench tests

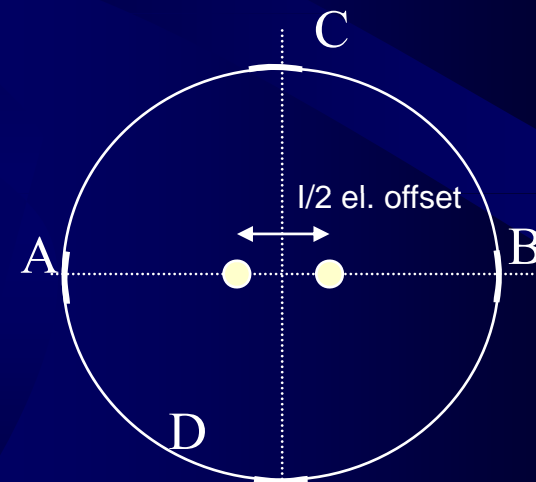
$$\text{Position} = K_{x,y} \times (A-B)/(A+B) + \text{offset} = K_{x,y} * \Delta_{x,y} / S + \text{offset}$$

■  $K_{x,y}$  = BPM sensitivity estimated from simulations or measured. Linear or polynomial fits can be used.

■ Offset = Difference between mechanical center and electrical center. For high precision this must be measured using metrology and a stretched wire.

■ To find the offset with micron precision (**with respect to an external reference**) move the wire to the electrical center, rotate the BPM 180°, and move the wire the new electrical center.

■ The difference between the two RELATIVE measurements is equal to two times the electrical offset



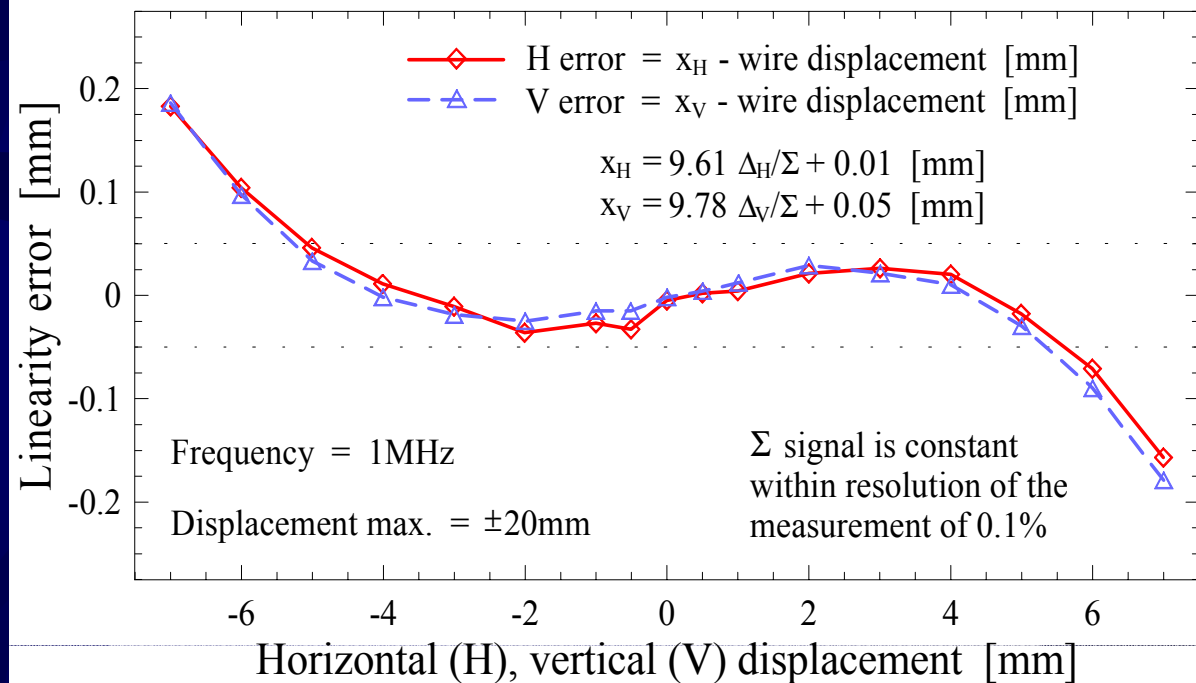


# IPU Bench test



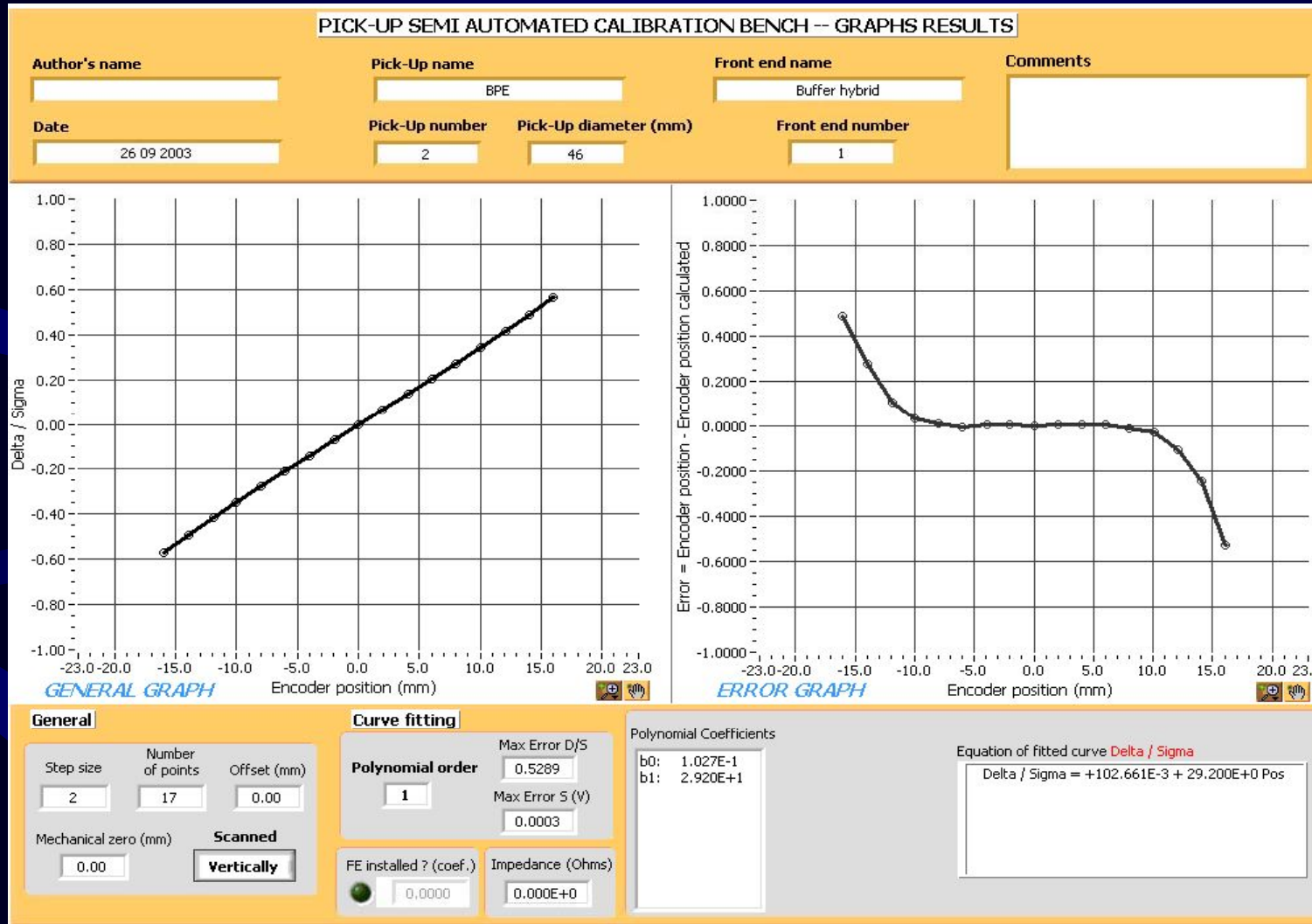
A thin wire forming a coaxial line was displaced diagonally across the pick-up aperture. The measurement was done with a network analyzer: signal was applied to the wire and hybrid signals were observed.

$$\text{horizontal position} = 9.61 \frac{\Delta_H}{\Sigma} + 0.01 \text{ [mm]}$$
$$\text{vertical position} = 9.78 \frac{\Delta_V}{\Sigma} + 0.05 \text{ [mm]}$$





# Electrostatic BPM bench measurement



$\Delta = \Sigma = 29.2 \text{ mm}$   
Offset = 0.1 mm



# Other requirements

- Must be vacuum tight down to  $10^{-9}$  Torr.
- Must be bake able to  $150^{\circ}$  C. Watch out for stresses due to different thermal expansions, i.e ceramic and metal.
- External reference directly connected to the detector or via WPS-system.
- Minimize front-end electronics due to radiation.



# BPM overview

	Electrostatic	Button	Strip line	WCM	Inductive	Cavity	Re-entr. Cavity
Linearity	Very good	Bad	Good	Good	Good	Good	Good
Sensitivity	Good	Good	Good	Good	Good	Very good	Very good
Load imp.	High	50Ω	50Ω	50Ω	50Ω	50Ω	50Ω
FE close?	Yes	No	No	No	No	No	No
Feed-thru's	Yes	Yes	Yes	Yes	No	Yes	yes
Long. Imp	Bad	Very good	Good	Good	Good	Bad	Good
Cost	Expensive	Cheap	Medium	Medium	Medium	Medium	Medium



# Conclusion

- To be filled in later.....