almaka



Extending the Alpaka performance portability library with CUDA Cooperative Groups for the CMS pixel reconstruction

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Alpaka

- alpaka library is a header-only C++17 abstraction library for accelerator development.
- Its aim is to provide performance portability across accelerators through the abstraction of the underlying levels of parallelism.
- Alpaka supports both GPU (CUDA, HIP and SYCL) and CPU (OpenMP, std::threads and Intel TBB) accelerators, with ability to recompile your code from one to the other, changing just a few lines of code.

class VectorAddKernel

{ public:

}:

ALPAKA_NO_HOST_ACC_WARNING template<typename TAcc, typename TElem, typename TIdx> ALPAKA_FN_ACC auto operator()(TAcc const& acc, TElem const* const A, TElem const* const B, TELem* const C, TIdx const const -> void

static_assert(

alpaka::Dim<TAcc>::value == 1, "The VectorAddKernel expects 1-dimensional indices!");

TIdx const gridThreadIdx(alpaka::getIdx<alpaka::6rid, alpaka::Threads>(acc)[0u]); TIdx const threadElemExtent(alpaka::getWorkDiv<alpaka::Thread, alpaka::Elems>(acc)[0u]) TIdx const threadFirstElemIdx(gridThreadIdx * threadElemExtent);

if(threadFirstElemIdx < numElements)</pre>

```
// Calculate the number of elements to compute in this thread.
// The result is uniform for all but the last thread.
TIdx const threadLastElemIdx(threadFirstElemIdx + threadElemExtent);
TIdx const threadLastElemIdxClipped((numElements > threadLastElemIdx) ?
threadLastElemIdx : numElements);
```

CUDA cooperative groups

- Traditionally CUDA had only blocklevel (1024 threads) synchronization. This requires usage of dynamic parallelism for a lot of algorithms, which has a large overhead.
- Cooperative groups are a new abstraction that add support for synchronization both on sub-block level and the whole grid level, allowing for more optimization.



Thank you for your attention.