Bayesian model averaging: an overview

Ethan T. Neil (Colorado) PDFLattice 2024 @ JLab 11/18/24



arXiv:2008.01069 (with Will Jay) arXiv:2208.14983 (with Jake Sitison) arXiv:2305.19417 (with Jake Sitison)

 $10^{10}\,a_\mu^{ll,\rm{W}}(\rm{conn.})$ 

 $\circ$ 

(Fermilab/HPQCD/MILC collaborations, arXiv:**2301.0874**)





- 
- •Above example has **2160** model variations discretization, finite volume, mass corrections… model average gives a final combined estimate  $+$  error bar for continuum  $a<sub>µ</sub>$ <sup>||</sup>,<sup>||</sup>,<sup>||</sup>,

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(EN and W. Jay, arXiv:**2008.01069**)



- Bayesian model averaging: key formula is that any expectation value is a weighted average over model space {**Mμ**}, given data set **D**:
- Usually, models are parametric: we have some parameter vector **a**, taken to be common to all models (model Mμ can have extra **am**, marginalized over.) Expectation values are functions of parameters:

$$
\langle f(\mathbf{a}) \rangle = \sum_{\mu} f(\mathbf{a}_{\mu}^{*}) \mathrm{pr}(M_{\mu}|\{y\}),
$$
  
\n
$$
\sigma_{f(\mathbf{a})}^{2} = \langle f(\mathbf{a})^{2} \rangle - \langle f(\mathbf{a}) \rangle^{2}
$$
  
\n
$$
= \sum_{\mu} \sigma_{f(\mathbf{a}_{\mu})}^{2} \mathrm{pr}(M_{\mu}|\{y\}) + \sum_{\mu} f(\mathbf{a}_{\mu}^{*})^{2} \mathrm{pr}(M_{\mu}|\{y\}) - \left(\sum_{\mu} f(\mathbf{a}_{\mu}^{*}) \mathrm{pr}(M_{\mu}|\{y\})\right)^{2},
$$

### average stat. error model-variation systematic

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$$
\langle f(\mathbf{a}) \rangle = \sum_{\mu} \langle f(\mathbf{a}) \rangle_{\mu} \mathrm{pr}(M_{\mu}|D)
$$



 $\mathcal{L}=\mathcal{L}^{\mathcal{L}}\left(\mathcal{L}^{\mathcal{L}}\right)$  . The contract of the contract of  $\mathcal{L}^{\mathcal{L}}$ 

• Briefly: sample best-fit **a\*** is an unbiased estimator for true parameter  $a_T$ . But fluctuations of  $a^*$  above and below  $a<sub>T</sub>$  both overestimate likelihood (underestimate  $\chi^2$ .) Correction of +2 (per dimension of **a**)  $\rightarrow$  +2k.

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- Asymptotically correct model weights pr(M|D) from the (Bayesian) Akaike information criterion (AIC): (note,  $\hat{\chi}^2$  is only data chi-squared, no explicit priors!)
- $-2 \log pr(M_\mu|D) = -2 \log pr(M_\mu) + \text{BAIC}$  $BAIC = \hat{\chi}^2(a^*) + 2k$
- pr(M) is *model prior probability*; if you don't know this, ignore it (take as flat prior  $pr(M) = 1/$  $Nm.$
- <u>"Occam's razor" penalty term</u> +2k appears, where  $k = #$  of model parameters.
- Penalty *emerges naturally* from theoretical considerations as asymptotic bias correction.

(EN and W. Jay, arXiv:**2008.01069**) (EN and J. Sitison, arXiv:**2208.14983**)

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 $\blacksquare$ 

**agrees well with** 









### Model averaging and functions

1.9

1.8

 $1.7$ 

 $1.5$ 

 $1.4$ 

 $\Omega$ 

 $\frac{2}{5}$  1.6

- This is a PDF workshop, so the expectation values of interest are *functions* and not just single values.
- Easy to extend the formalism to functions of independent variables:

$$
f_{\text{avg}}(x) = \sum_{\mu} f_{\mu}(a_{\mu}^{\star}, x) \text{pr}(M_{\mu}|D)
$$

$$
\sigma_{\text{avg}}^2(x) = \sum_{\mu} \sigma_{\mu}^2(a_{\mu}^{\star}, x) \text{pr}(M_{\mu}|D)
$$

$$
+ \sum_{\mu} f_{\mu}(a_{\mu}^{\star}, x)^2 \text{pr}(M_{\mu}|D) - f_{\text{avg}}(x)^2
$$

• (Important: don't omit model-space systematic error! Small here, but not always…)

# Improved information criteria

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(EN and J. Sitison, arXiv:**2208.14983**)

### Using the Kullback-Leibler divergence

 $KL(M_\mu) = E_z[\log pr_M]$ 

- Second term proportional to -log[pr(M|D)]. This is **non-parametric,** good data should
- Three options are natural and give interesting ICs:

**• KL divergence** ("relative entropy") gives a path to Bayesian information criteria\*. Basic definition:

$$
E_{\rm T}(z)] - E_z[\log \text{pr}_{M_\mu}(z)]
$$

determine parameters. But there are multiple ways to obtain the above from a parametric model!





(S. Zhou, *Bayesian model selection in terms of Kullback-Leibler discrepancy,* PhD thesis, Columbia, 2011) (S. Zhou, arXiv:**2009.09248**)

$$
E_z[\log \mathrm{pr}_{M_\mu}(z)] \sim E_z[\log \mathrm{pr}_{M_\mu}(z|\mathbf{a}^*)]]
$$
  

$$
E_z[\log \mathrm{pr}_{M_\mu}(z)] \sim E_z[E_{\mathbf{a}|\{y\}}[\log \mathrm{pr}_{M_\mu}(z)]
$$

 $E_z[log \operatorname{pr}_{M_\mu}(z)] \sim E_z[log E_{\mathbf{a}|\{y\}}[\operatorname{pr}_{M_\mu}(z|\mathbf{a})]]$ 

(EN and J. Sitison, arXiv:**2208.14983**)

• Various g, H, T, Σ are all *tensors of derivatives of chi-squared functions* - see our paper **2208.14983**, sec.

• The above formulas are *approximate*, NLO in large-N expansion (N = data sample size.) PPIC subset

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**6 Intips://gitt  
Model Complexity Data Truncation  
BAIC = 
$$
\hat{\chi}^2(\mathbf{a}^*)
$$
  
 $\hat{\chi}^2(\mathbf{a}^*)$   
 $\hat{\chi}^2(\mathbf{a}^*)$   
<**

- IV. Numerical code available in Python + JAX (gradients/JIT compilation), although the code is *not polished* - just companion code for our paper.
- penalty is approximately  $+2d<sub>C</sub>$  plus 1/N corrections. BPIC has larger bias from posterior avg.
- We advocate use of **optimal truncation**, which replaces NLO —> LO when NLO terms are too large. (Fixes a potential numerical problem with log(…) in PPIC.)

### te formulas https://www.itison/improved\_model\_avg\_paper\_mub.com/jwsitison/improved\_model\_avg\_paper

 $\binom{*}{2}abcd$ 

 $\sum \log \left[1+\frac{1}{2}\left(\frac{1}{4}(g_{i})_{b}(g_{i})_{a}-\frac{1}{2}(H_{i})_{ba}\right)(\Sigma^{*})_{ab}+\frac{1}{4}(g_{i})_{d}T_{cba}(\Sigma^{*}_{2})_{abcd}\right]$ 

# Numerical results: fixed data

- Quadratic model truth, extract constant term  $a_0$ .
- **Left:** fits to polynomials of degree μ. Extra parameters are penalized, moreso for BPIC.



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- **Right:** MA vs. sample size log(N). BPIC does slightly better in general, similar to fixed quadratic model.
- (This is sort of a special case since the "true model" is nested within the more complex μ>2 models…)

## Numerical results: data selection



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• BPIC cuts aggressively often overly so (biasvariance tradeoff!) But it does fairly well when fitting the true model or with lots of data.

- PPIC is more robust against noise, otherwise performing similarly to BAIC (no excessive bias)
- BAIC is reliable and simplest to compute; we advocate PPIC generally, but nothing wrong with AIC!

## Numerical results: data selection (2)

- Scaling results vs. N, similar conclusions to previous slide: we prefer PPIC, robust results and tends to give smaller error than BAIC, particularly w/noise
- BPIC has smallest error but can be too aggressive, particularly for subset selection.
- See paper for many more numerical results, including tests on real LQCD nucleon data (courtesy of JLab/W&M/ MIT/LANL)



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# Summary

• Model averaging is a powerful and simple technique for dealing with analysis choices and associated systematic errors. Easy to "plug in" to existing analysis chains where

• Thoughts for PDFs: For methods that aren't chi-squared fits, need to understand *right bias correction* for however you evaluate likelihood of your model being correct… K-L



- chi-squared fits are done.
- Bayesian + KL divergence perspective suggests two new ICs:
	- PPIC is more robust against noise and performs well in all tests.
	- BPIC uses Occam's Razor more aggressively, smaller error at the price of larger bias.
	- All (N ->  $\infty$ ) roads lead to the (B)AIC, which is simple and effective.
- divergence approach? Other issues?

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Backup slides



### The Kullback-Leibler divergence

 $KL(M_\mu) = E_z[log \text{pr}_{M_T}(z)] - E_z[log \text{pr}_{M_\mu}(z)]$ 

• KL divergence: "relative entropy" between PDFs, true model M<sub>T</sub> vs. candidate model M<sub>μ</sub>.

$$
\equiv \int dz ~ \Big[ {\rm pr}_{M_{\rm T}}(z) \log {\rm pr}_{M_{\rm T}}(z) - {\rm pr}_{M_{\rm T}}(z) \log {\rm pr}_{M_{\mu}}(z)
$$

- KL = 0 if the PDFs are equal, positive definite otherwise. Find the "closest" distribution to pr<sub>MT</sub> by **maximizing** the magnitude of the second term!
- Introduce model parameters **a**, and this leads to familiar results:

$$
E_z[\log \mathrm{pr}(z|\mathbf{a}, M_\mu)] \simeq \frac{1}{N} \sum_i \log \mathrm{pr}(y_i|\mathbf{a}, M_\mu) = \frac{1}{N} \log \mathrm{pr}(\{y\}|\mathbf{a}, M_\mu)
$$
  
sample log-likelihood, i.e. -x<sup>2</sup>/2

<u>function gives model probability weights</u>, via Bayes theorem:  $pr(M|D) \sim pr(D|M)$ .

• e.g. finding best-fit point **a\*** = minimization of KL divergence ("max likelihood".) Same likelihood





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Model avg. Individual fits

 $pr(M|D)$ Fit p-value



### Two approaches to subset selection (EN and J. Sitison, arXiv:**2305.19417**) )<br>)

- A common part of lattice analysis is data cutting: "what [tmin, tmax] should I fit my twopoint correlator over?"
- **Partition data into kept and cut** [ $y_K$ ,  $y_C$ ] of size ( $d_K$ ,  $d_C$ ). Compute relative model weights, average!
- <u>"Perfect model method"</u>: Keep all data.  $y_c$  fit to a model with 㸧2=0; *bias correction* gives **+2dC** penalty.
- "Subspace method": Discard data in cut partition. Recompute *total* KL divergence, gives **+d<sub>c</sub>** penalty.

(EN and W. Jay, arXiv:2008.0 (EN and W. Jay, arXiv:**2008.01069**)





cut



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### BAIC (subset)

• Toy numerical example: model truth is linear,

$$
=1.80-0.53\left(1-\frac{t}{16}\right)
$$

- For constant fit, both criteria are similar; x<sup>2</sup> is
- For linear fit ("true model"), both averages are right, but subset *under-penalizes* cutting so has larger error.

(EN and J. Sitison, arXiv:**2305.19417**)



- Below: "grand average" (both models @ all tmin) vs. sample size log(N).
- Both ICs agree well w/ model truth for all N; generically larger errors for BAIC (subset)



• Example by explicit construction in appendix B of paper, but favoring a "bad fit" over a "good fit" in this way requires that a large amount of data are cut for the "good fit". Rewrite AIC<sup>perf</sup> to see explicitly that the difference

- AICperf << 0 (lower AIC is preferred.) Is this a problem?
- is still just data cutting penalty:

$$
\text{AIC}_{\mu,d_K}^{\text{perf}} = N_{\text{dof}}\left(\hat{\chi}_{\text{K}}^2(\mathbf{a}^*)/N_{\text{dof}} - 1\right) + k - d_K.
$$

### χ2, dof, and subset selection (EN and J. Sitison, arXiv:**2305.19417**)

# degrees of freedom, Ndof=dk-k:

$$
\text{AIC}^{\text{sub}}_{\mu,d_K} = N_{\text{dof}} \left( \hat{\chi}_{K}^{2}(\mathbf{a}^*) / N_{\text{dof}} - 1 \right) + k,
$$
  

$$
\text{AIC}^{\text{perf}}_{\mu,d_K} = N_{\text{dof}} \left( \hat{\chi}_{K}^{2}(\mathbf{a}^*) / N_{\text{dof}} - 2 \right).
$$

$$
\text{AIC}^{\text{sub}}_{\mu,d_K} = N_{\text{dof}} \left( \hat{\chi}_{K}^{2}(\mathbf{a}^*) / N_{\text{dof}} - 1 \right) + k,
$$
  
\n
$$
\text{AIC}^{\text{perf}}_{\mu,d_K} = N_{\text{dof}} \left( \hat{\chi}_{K}^{2}(\mathbf{a}^*) / N_{\text{dof}} - 2 \right).
$$

• Rewrite both forms of AIC in terms of usual number of

• For a bad fit with large Ndof and  $1 < x^2 < 2$ , we can have AICsub  $>> 0$  but

• When constructing any statistical estimator, one typically worries about bias, defined as follows: for distribution  $pr_T(z)$ with property  $\xi(z)$ , given a finite sample  $\{y\}$  of size N and estimator  $X({y})$ ,

$$
b_z[X(\{y\})] \equiv E_z[X(\{y\}) - \xi(z)] = E_z[X(\{y\})] - \xi(z)
$$

# Asymptotic bias

 $\cdot$  In other words, when averaged over the true distribution (i.e. over many independent samples), a non-zero bi means the estimator is wrong. We can further define asymptotic bias as:

• Asymptotic bias is often easier to calculate than finitesample bias, and estimators with zero asymptotic bias are at least self-correcting, in the sense that they are correct as  $N \rightarrow \infty$ .

$$
b_z[X(z)] = \lim_{N \to \infty} b_z[X(\{y\})]
$$

• It is *not* obvious that an unbiased model probability gives an unbiased model average. But we prove the bias on the model average is bounded:

$$
|b_z[\langle f(\mathbf{a})\rangle]| \leq \sum_{\mu} \left| \langle f(\mathbf{a})\rangle_{\mu} \right| |b_z[\mathrm{pr}(M_{\mu}|z)]|
$$

assuming that the individual-model estimates <f(a)> are consistent (a slightly stronger version of asymptotically unbiased.) In short: **unbiased model weights give unbiased model averages**.





- *Some history*: we didn't bring model averaging to lattice, we "added the B" (**Bayesian** MA), found new ICs, and tried to clarify statistical derivations/details.
- Several early variations of model averaging/ variation appear in lattice papers: Y. Chen et al. '04, **BMW '08**, **HPQCD '08**, **FNAL/MILC '14**, BMW '14…however, many old papers use *ad hoc* averaging prescriptions.
- First use of AIC for lattice is BMW '15; see also **CalLat '18**, '20, Rinaldi et al. '19. (More refs in our paper, including statistics papers back to the '70s.)
- First use of AIC with data penalty is BMW '21 (although I will argue for a *corrected* version of their formula here.)

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[**BMW '08**]: (BMW collaboration, *Science* 322 (2008), arXiv:**0906.3599**)



[Y. Chen et al '04]: arXiv:**hep-lat/0405001** [BMW '14]: PRD 90 (2014), arXiv:**1310.3626** [BMW '15]: Science 347 (2015), arXiv:**1406.4088** [Rinaldi et al. '19]: PRD 99 (2019), arXiv:**1901.07519** [CalLat '20]: PRD 102 (2020), arXiv:**2005.04795** [BMW '21]: Nature 593 (2021), arXiv:**2002.12347**