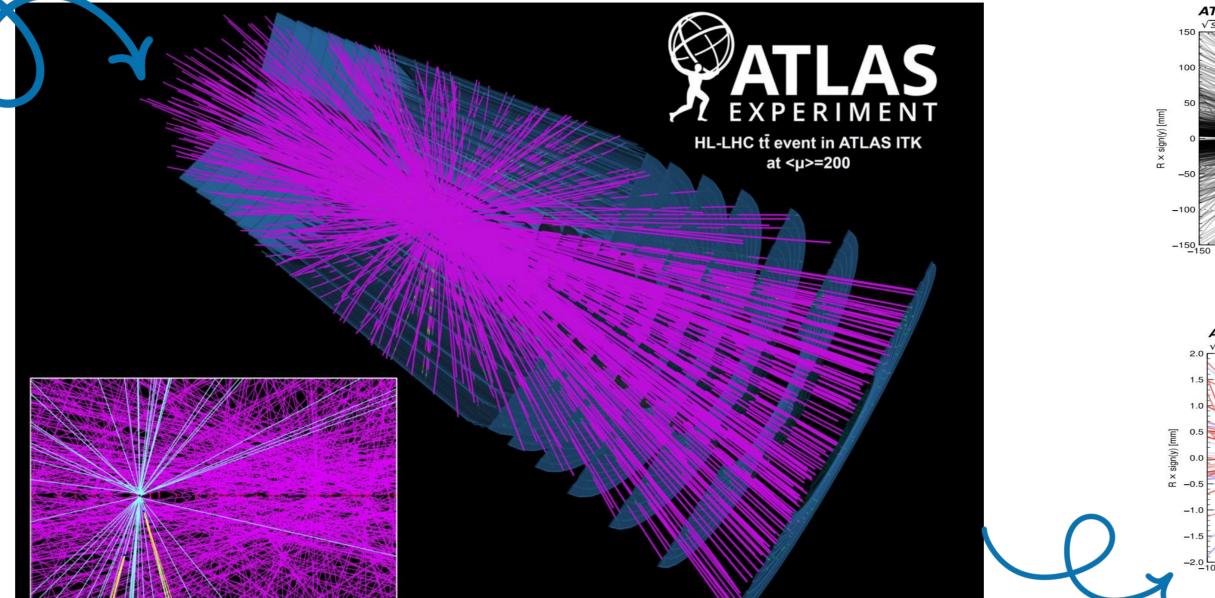
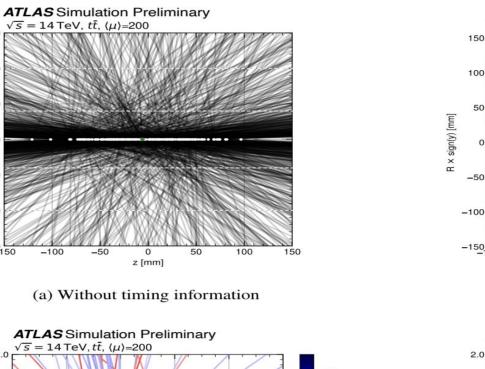
Time will tell ATLAS Vertex seeding at high pile-up

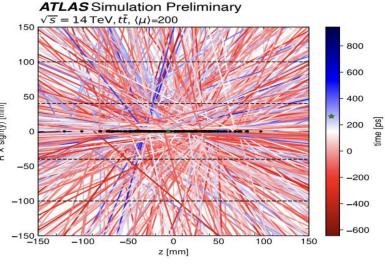
Cléo Nicollin with the support of Andreas Stefl, Paul Gessinger-Befurt, Valentina Cairo, Pierfrancesco Butti

Motivations

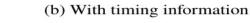
- \star One of the challenges in high-pile-up scenarios at the HL-LHC is the increased difficulty in reconstructing the locations of proton-proton interactions (**vertexing**).
- We will look at how hit-time **information** can be used to improve

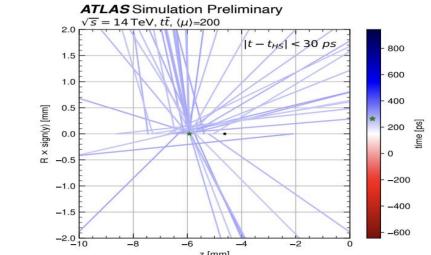






aits,





the vertex-finding algorithms.

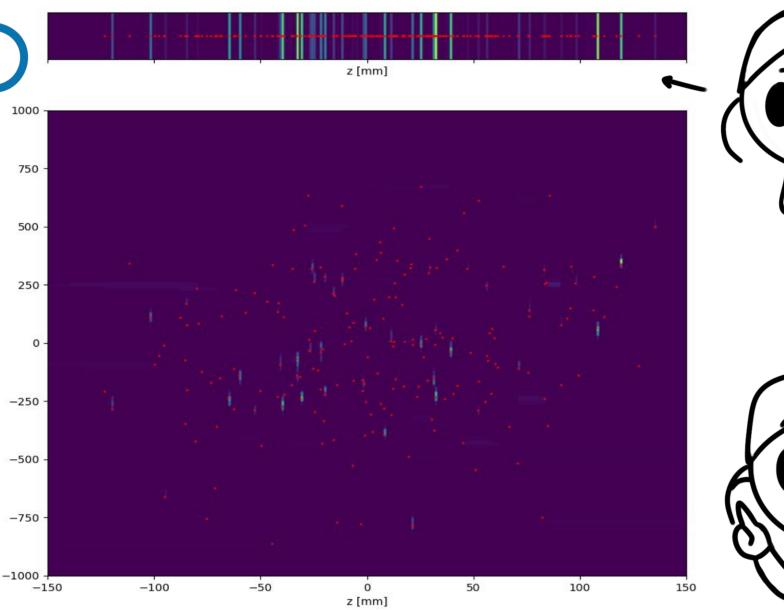
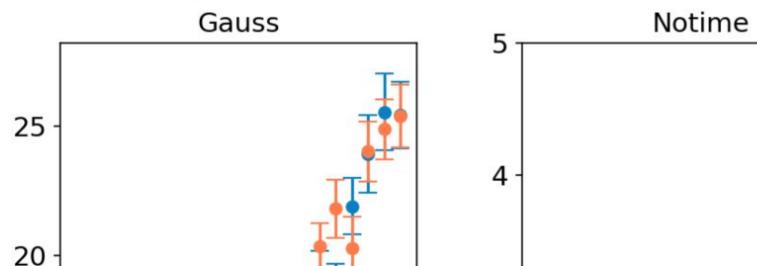


Fig 3: Seeder grid visualization in 2D (top) and 3D (bottom) to illustrate improvement of visibility of

points.



Space (um): 45, Time (mm): 22 Space (um): 15, Time (mm): 19



Overlapping

Vertices in 2D

Time

Fig 1:HL-LHC tt- event at <u>=200 showing charged particles in purple

(d) With timing information, spatial zoom and time cut (c) With timing information, spatial zoom Fig 2: Longitudinal view of a simulated $t\bar{t}$ event with high $\mu =$ 200 with (1(a)) no track-timing compared to (1(b),1(c),1(d)) with track-timing information. Figure from ATLAS paper [1].



"Time" and "no time" algorithms use a track density grid to avoid recomputing Gaussians, while vertex finding Clear map of vertices in 3D! algorithms use a **binned search** over high track density regions to reduce CPU time compared to the analytical Gaussian method computations.

200

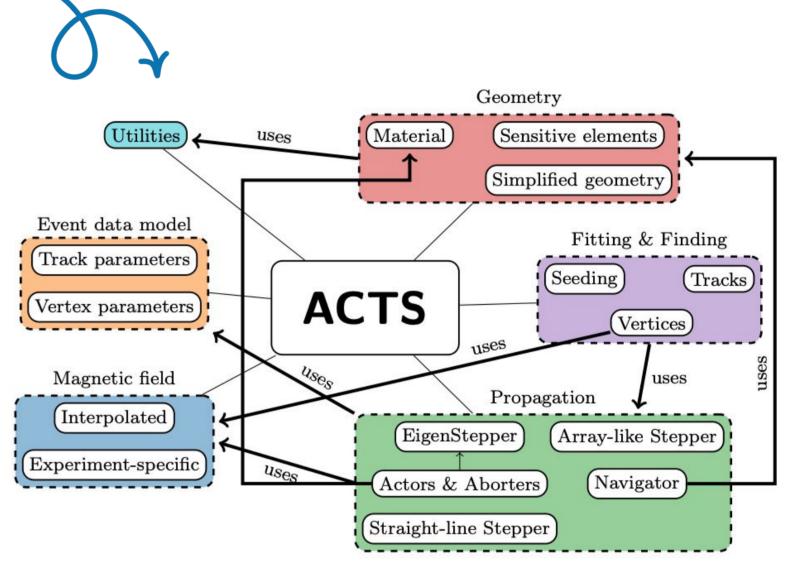
3_{ps}

Tfinding

110

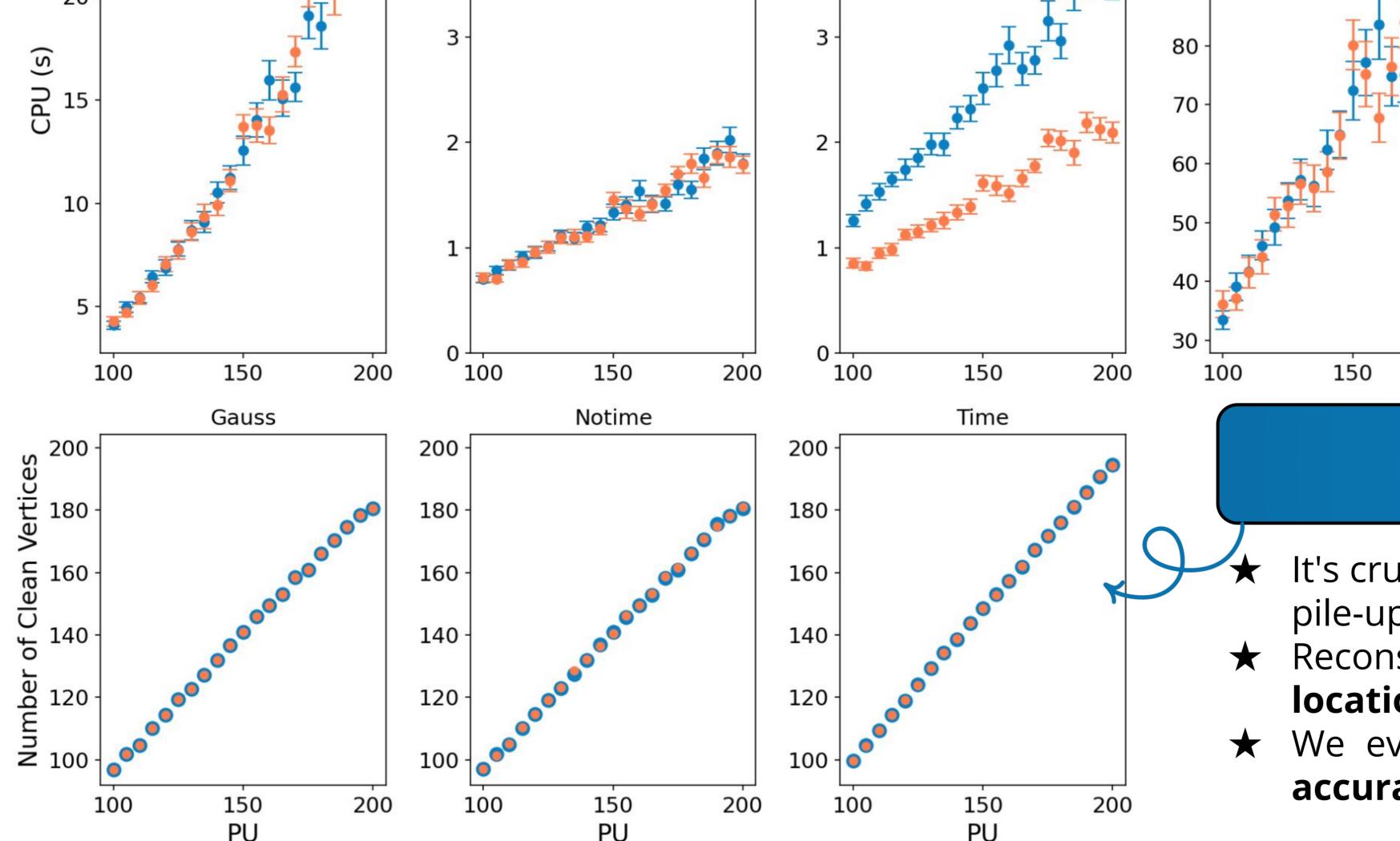
100

90



S Project Components and their relations. Arrows show inter-module "use" relationships e.g. Steppers connect to the magnetic field module for information retrieval.





- We investigated the effect of usage of time information on such search algorithms as well as the impact of their configuration parameters on CPU usage and physics performance
- Most of the **improvement** comes from changes \star to the space parameter, though the time parameter also contributes significantly.



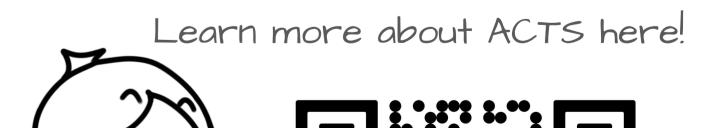
- It's crucial to identify the **hard scatter vertex** and keep it free from pile-up contamination.
- Reconstruction algorithms must accurately determine vertex **locations** and correctly associate **tracks**.

\ / /

(T)

We evaluated how different vertex finding configurations affect accurate vertex reconstruction.

Fig 5: Performance metrics of various algorithms for multiple muon events with <100 pile-up options. Each event includes Y muons per vertex and up to X vertices per event. We studied reconstruction algorithms using the Open Data Detector (ODD) and ACTS Fatras simulation (refer to [2] de Moraes et al.; [3] Gonçalo et al.). Results show muon events, with blue lines for default parameters and orange



lines for optimized parameters reducing CPU usage while maintaining clean vertices.



- \star Understanding the algorithms and their configurations
- \star Automating data collection process for the comparisons
- \star Investigating memory consumption



- ★ Extended parameter search for "AdaptiveGridDensityVertexFinder"
- ★ Implementation of "GaussianTrackDensityVertexFinder" with time information
- \star Looking into alternative algorithms

Acknowledgements and Sources

I sincerely appreciate the invaluable support and contributions from the ATLAS/ ACTS contributors, the Summer Program, and my dedicated supervisors.

[1] ATLAS Collaboration. "Performance of the ATLAS Track Reconstruction Algorithms in Dense Environments." ATLAS Public Note, 2023, CERN

[2] de Moraes, A., et al. "Simulating the Response of a Particle Detector with FATRAS." *Journal of Physics: Conference Series*, vol. 2438, no. 1, 2023, p. 012110, IOP Publishing, doi:10.1088/1742-6596/2438/1/012110.

[3] Gonçalo, R., et al. "Performance Evaluation of the Open Data Detector with ACTS." Presented at CTD Workshop, 11 Oct. 2023